Functions of **Right** hand:

1. Control three **forward** directions of the car
2. Control the robotic **arm**
3. Activate the **distance calculation** module.

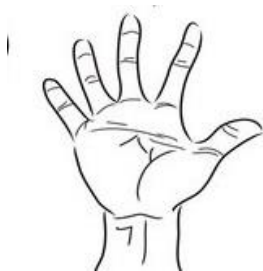**Definitions of each gesture of the right hand**:

Gesture '1': Forward   **Gesture '2': Forward Left**   **Gesture '3': Forward Right**

Gesture 'open the plam': Hand open   **Gesture 'close the plam': Hand close**

Gesture 'Thump up': Arm up   **Gesture 'Thump down': Arm down**

Gesture ' √ ': Activate the distance calculation module

Functions of **Left** hand:

1. Control three **backward** directions of the car
2. Change the **speed** mode of the car
3. Activate the **distance calculation** module.

Definitions of each gesture of the left hand:

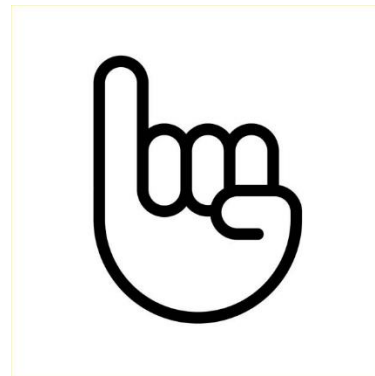**Gesture '1': Backward**   **Gesture '2': Backward Left**   **Gesture '3': Backward Right**

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Gesture 'Thump only': Fast mode   **Gesture 'Little finger only':Slow mode**

Gesture ' √ ': Activate the distance calculation module