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// ELEC402 PRJ1 SystemVerilog FSM Project
// Project Name: Food Food Dispenser
// Name: Xingwei Su
// File: Food Dispenser FSM
// Description: Design's main logical FSM
module food dispenser fsm (
                                    //High when reset
    input reset,
    input clk,
                                    //Base clk input (fast)
    input timesup,
                                    //High when count time is up
    input [6:0] food_weight,
                                    //Foot weight measure under plate
    input [6:0] set_food_weight,
                                    //Initialized target food weight (set on UI interface
module)
    input refill detector,
                                    //High when need refill
    input cap detector,
                                    //High when cap open
    input play function pedal,
                                    //High when one full press cycle (press+release) is done
    input initialize flag,
                                    //High when UI interface module finish initialize
                                    //Posedge when new day
    input newday,
    output logic food gate,
                                    //High when gate open
    output logic warning,
                                    //High when warning
    output logic play_function_flag,
                                                //High when doing play function
    output logic play function fail flag
                                                //Posedge when fail
);
//Logic parameter setting
logic [3:0]
                                                                                 //15 states
state;
Max
logic [3:0] play function counter;
                                                                //Counter counts to 15, daily
play function limit 15 times
//State Parameters
parameter [3:0]
                    initialize state
                                                    = 4'd0;
parameter [3:0]
                    initialize wait for finish
                                                    = 4'd1;
parameter [3:0]
                    idle
                                                    = 4'd2;
parameter [3:0]
                    before_open_gate
                                                    = 4'd3;
parameter [3:0]
                    add food
                                                    = 4'd4;
parameter [3:0]
                    weight detect
                                                    = 4'd5;
parameter [3:0]
                    add food complete
                                                    = 4'd6;
parameter [3:0]
                    wait_for_refill
                                                    = 4'd7;
parameter [3:0]
                    play_function_detected
                                                    = 4'd8;
parameter [3:0]
                    play function fail
                                                    = 4'd9;
parameter [3:0]
                    play function complete
                                                    = 4'd10;
parameter [3:0]
                    newday reset
                                                    = 4'd11;
```

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//Value parameter
parameter [6:0]
                     play_function_1g_food
                                                 = 7'd1;
//FSM flip-flop
// always_ff @(posedge clk) begin
//
       if (reset) state <= 3'd0;</pre>
       else begin
//
//
           state <= nextstate;</pre>
//
           play_function_counter <= next_play_function_counter;</pre>
//
       end
// end
//FSM
always ff @(posedge clk or posedge reset) begin
    if (reset)
        state <= initialize_state;</pre>
    else begin
        case (state)
            //Output values preset
            initialize_state: begin
                 food gate <= 1'b0;
                 warning <= 1'b0;</pre>
                 play function flag <= 1'b0;
                 play_function_fail_flag <= 1'b0;</pre>
                 play_function_counter <= 1'b0;</pre>
                 state <= initialize wait for finish;</pre>
            end
            //Wait for UI initialization
            initialize_wait_for_finish:
                 state <= initialize_flag ? idle : initialize_wait_for_finish;</pre>
            //Idle stage (detect flags)
            idle:
                 state <= newday ? newday_reset :</pre>
                              (refill_detector ? wait_for_refill :
                              (timesup ? before_open_gate :
                              (play_function_pedal ? play_function_detected : idle)));
            //Detect if there is still food left on plate
            //Warning if more than 1/3 target food weight is left
            before_open_gate: begin
                 warning <= (food weight > (set food weight / 2'd3)) ? 1'b1 : 1'b0;
                 state <= add_food;</pre>
            end
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//Gate open
             add food: begin
                 food_gate <= 1'b1;</pre>
                 state <= weight_detect;</pre>
             end
             //Detect the weight of the food
             //If on Play mode, only 1g of food will be send to plate
             //If equal close gate
             weight_detect:
                 if (play_function_flag)
                     state <= (play function 1g food == food weight) ? add food complete :</pre>
weight_detect;
                 else
                     state <= (set_food_weight == food_weight) ? add_food_complete :</pre>
weight_detect;
             //Gate close
             add food complete: begin
                 food gate <= 1'b0;
                 state <= play_function_flag ? play_function_complete : idle;</pre>
             end
             //Refill food in bank
             //Wait for cap to be closed to continue
             wait for refill:
                                      state <= refill_detector ? wait_for_refill :</pre>
                                                    (cap_detector ? wait_for_refill : idle);
             //Pedal trigered
             //Open function
             play_function_detected: begin
                 play_function_fail_flag <= 1'b0;</pre>
                 if (play_function_counter == 4'd15)
                     state <= play function fail;</pre>
                 else begin
                     play_function_flag <= 1'b1;</pre>
                     state <= add_food;</pre>
                 end
             end
             //More than 15 times daily
                                      {state, play_function_fail_flag} <= {idle, 1'b1};
             play_function_fail:
                 //blink LED (in module LED) <- test for posedge fail flag
             //Count up daily play times counter
             // Close function
             play_function_complete: begin
                 play_function_counter <= play_function_counter + 1'b1;</pre>
                 play_function_flag <= 1'b0;</pre>
```