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COMP 4107 Assignment Two: O Find ox if: q) $f = X_1 + X_2 + X_3$, $X = (X_1, X_2, X_3)$: Since f is a scaler 4×18 a vector, we use Scalar-by-vector Conversion: $\frac{\partial f}{\partial x} = \begin{bmatrix} \partial f & \partial f & \partial f \\ \partial x_1 & \partial x_2 & \partial x_3 \end{bmatrix} = \begin{bmatrix} \partial (X_1 + X_2 + X_3) & \frac{\partial}{\partial X_3} (X_1 + X_2 + X_3) \\ \partial x_2 & \frac{\partial}{\partial x_3} & \frac{$ $b)f = (x_1 + x_2, x_3x_2, x_1 - x_3^2, x_2 - 8), X = (x_{11}x_{21}x_3);$ Since f is a vector g x is a vector, use vector-by-vector conversion: $\frac{\partial f}{\partial x} = \begin{bmatrix} \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_2} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3} \\ \frac{\partial f}{\partial x_3} & \frac{\partial f}{\partial x_3}$ 213 () f = (X, 2x3, - Cos 2x +14): Since f is a vector & x is a scaler, use vector-by-scalor: d) f = [9x 3x 2] = C / Hint: 3x4 = 2Cx+b: (05(xh), 3(xh) HS AS == C & 3xx = 2Cx+b we Note: $= \begin{bmatrix} 9 & 3C \\ 0 & \cos(xx)(3Cx+b) \end{bmatrix} =$ (26x+b) COS(X4) thus!

(2Cx+b) Cos(xy

e)
$$f = \begin{bmatrix} 3P & 27 \\ P24 & 7 \end{bmatrix}$$
, $P = X_1 - 2X_2$, $P = X_2X_3$, $X = (X_1/X_2/X_3)$
 $f = \begin{bmatrix} 3(x_1 - 2x_2) & 2(X_2X_3) \\ (X_1 - 2X_2) - (X_2X_3) & 7 \end{bmatrix} = \begin{bmatrix} 3X_1 - 6X_2 & 2X_2X_3 \\ (X_1 - 2X_2) - (X_2X_3) & 7 \end{bmatrix}$

Since f is a matrix & x is a vector, use a matrix-by-vector conversion: thus, derive f by each Xi to get three matracies for a tensor

$$A_{1} = \frac{\partial}{\partial x_{1}} \frac{3x_{1} - 6x_{2}}{x_{1} - 2x_{2} - 2x_{3}} = \frac{3}{1} \frac{0}{0}$$

$$A_{2} = \frac{\partial}{\partial x_{2}} \frac{3x_{1} - 6x_{2}}{x_{1} - 2x_{2} - 2x_{3}} \frac{3x_{2} - 6x_{3}}{x_{1} - 2x_{2} - 2x_{3}} = \frac{-6}{2} \frac{3x_{3}}{x_{1} - 6x_{2}} \frac{3x_{1} - 6x_{2}}{2x_{2} - 2x_{3}} = \frac{0}{2} \frac{3x_{2}}{x_{2} - 2x_{3}} = \frac{0}{2} \frac{3x_{2} - 6x_{2}}{2x_{2} - 2x_{3}} = \frac{0}{2} \frac{3x_{2}}{x_{2} - 2x_{3}} =$$

So, the resulting tensor is:

$$\frac{\partial \mathcal{L}}{\partial x} = \left\{A_{1/A_{2/A_{3}}}\right\}$$

(2) For a Perception model with the current weight vector W= (-0.3, 2.1,1) & the current bigs term Wo=-0.2, the input/output pair (X14) = ((1,1,0),-1) is given. If our learning Constant 9=0.2 & C=0, find the updated weights & the bigs of the neuron after training for 3. iterations on this data point: We know the training Rule: $W_i \leftarrow W_i + \Delta W_i$ where $\Delta W_i = h(t-0)X_i$ Since C=0: (Use bipolar mode) 0=output= | if Sum W; *X; >0 As a=0.2 & n=a, n=0.2 We are targeting a Value of -1, thus t=+1 thus, we have: t=-1,0=output, 11=0.2 & Wi*xi = Wixi+Waxa+WaXa+Wo iteration one: W=(-0.3)(1)+(2.1)(1)+(7/4)-0.2=1.6>0 -D 0=1 Our output is 1, yet y=-1, so reweight $\Delta W_i = 0.2(-1-1)(|_{1}|_{1}0) = -0.4(|_{1}|_{1}0) = (-0.4, -0.4, 0)$ $W_i \leftarrow (-0.3, 2.1, 1) + (-0.4, -0.4, 0) = (-0.7, 1.7, 1)$ iteration Two: £=-1,0=output, n=0.2, W=1.6

Treation Three: $\begin{aligned}
& \ell = -1, 0 = \text{output}, \, n = 0.2, \, w_i = 1.6 \\
& W_a = (-0.7)(1) + (1.7)(1) + (1)(0) + 1.6 = 2.6 > 0 \\
& U_b = 1 \quad \text{yet} \quad \text{y} = -1, \text{ so re weight} \\
& \Delta w_i = 0.2(-1-1)(1,1,0) = 0.2(-2)(1,1,0) = (-0.4,-0.4,0) \\
& W_i \leftarrow (-0.7,1.7,1) + (-0.4,-0.4,0) = (-1.1,1.3,1)
\end{aligned}$ Iteration Three:

t = -1, 0 = 0 utput, n = 0.2, Wa = 2.6 $W_3 = (-1.1)(1) + (1.3)(1) + (1.0) + 2.6 = 2.8 > 0$ $L_{0} = 1 \text{ yet } y = -1, \text{ so rewrite}$ $\Delta W_1 = 0.2(-1-1)(1,1,0) = (-0.4,-0.4,0)$ $W_1 \leftarrow (-1.1,1.3,1) + (-0.4,-0.4,0) = (-1.5,0.9,1)$ Thus, after three iterations we see that $(W = (-1.5,0.9,1) \text{ & } W_3 = 2.8)$

3 For each image, Pick the best number of layers for a hypothetical neural network classifier. Cite the reason; a) A Single layer neural network would work best. Reasoning:

The region in diagram A is a half-Plane bounded by a Hyperplane, Since it 18 a region seperable by a single line. For example: Note: Single layer the 0's 2 . 's are Seperable by a Single line. Also, outliers exist, but can't easily be included using more layers as this world disript the main relationship. b) A double layer neural network would work hest: The region in diagram B is a Convex region since it is a region seperable by 9 double line - V: for example: Note the V Seperates the is & o's outliers are mostly scattered & can't be included by a higher-order c) A Single layer neural network would work, & a Jouble can to: The region in diagram C is a half-Plane bounded by a Hyperplane, Since it is a region seperated by a single line. for example Single-Rayer Single or Two - the dashed line represents the Second lager (two is layer which is optional. The second layer More accurate) can be used to segment out the extra--empty white Space to make higher double-laye resolution results. - The Single layer model excludes the dashed Single-layers faster line, whereas the double layer model forms Dodouble-layer's more accurate a V-shape of the vertex & excludes the top half of the solid line (it forms a convex

region

A Three layer neural network would work since their are multiple disconnected clusters of points. This indicates a high-complexity model should be used:

Regsoning:

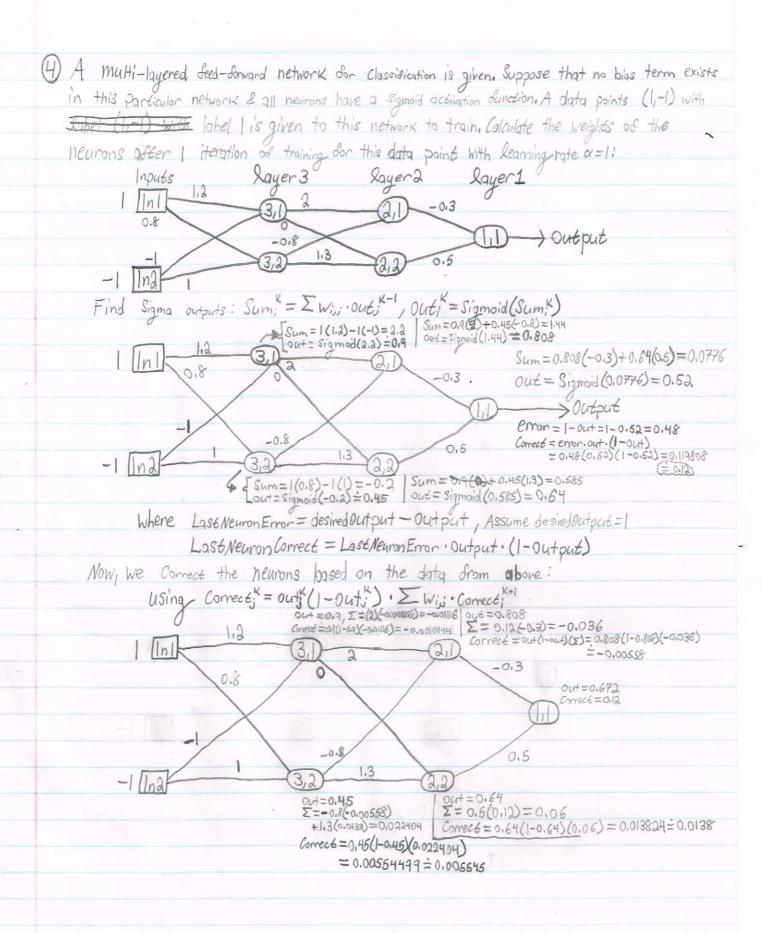
Three layer

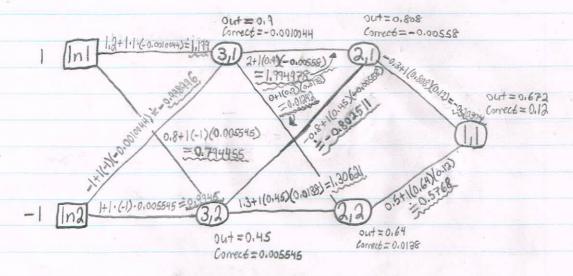
Note:

this lets us separate the 's from

the 0's, Since we can skirt around

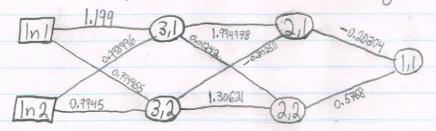
the meshed regions between the 's & 0's.





Find the new weights using: Wis = Wisi + h. Out's · Correcti given h= == 1

So, we have the Sollowing Ketwork after I iteration of training:



(5) We have trained a neural network on a dataset that Consists of a train see & a test set. We decide to split the train set into lo folds & do lo-fold Cross-validation on the training before sinding the sinal test accuracy by retraining the best network. We get (in terms of cross validation accuracy) on the whole training set & then sind the testing accuracy. After Joing So, we have got these results:

Training accuracy: 81%

10-fold Cross-Validation accuracy 78%

Test accuracy; 59%

Explain why the test accuracy is lower than training or validation accuracy. What so you think happened here? Which of these resules is the correct result? What do you think should be done in this situation (or maybe this is not a problem in the first flace)?

Why the test accuracy is lower in the testing accuracy is lower one to overditting.

the testing accuracy is lower due to oversitting. When the training accuracy is greater then the testing, the model was oversitted. This is akin to having memorized an exact pattern in the dataset without retaining the underlieing trend in the dataset. Thus, we end up making an overly elaborate model that sits the training set resectly but doesn't retain the trend (or pattern) behind the data. Therefore, when testing the data on the testing set, we sind the accuracy is low since we havn't accurally learned the underlying rules behind the data. This is an error due to variance.

The Correct result is ultimately the testing accuracy Although the training data is closely modeled by the program, it didn't Pickup on the true trend, meaning it "memorized" the dataset but didn't "learn" anything, which defeats the point of the task.

I think that the overlitting can be resulved by reducing the variance in the Sampling data, resulting in higher precision estimators in the dataset. This would reduce the rate of false treatments in the data I also present dalse variables from being in the model. We can also change the regularization paralmeters to increase neight decay (X), which will Smooth out the models learning rate to somm a solid (rather then Squigly) Curve to model the datas underlying trend with Laotly, We can validate the dataset better. We currently are using a simple 10-Sold cross-validation model (1 of 10 datasets used validate), but we can vamp up the validation by using a 3-Sold or leave-one-out model (uses 1/3 & 1/2 to validate). This would slow the Program Since we would be wasting \$\frac{1}{2}\$ or \$\frac{1}{2}\$ data for validation, but it would greatly help to Prevent overditting like we have in the current model.