Operating systems – Assignment 3 I/O Scheduling

Lennart Jern CS: ens16ljn

Teacher Ahmed Aley

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1 Introduction

Disk access is significantly slower than any CPU operation and is often a bottle neck when it comes to performance. In this report I compare the performance of three I/O schedulers: "cfq", "noop" and "deadline". Additionally, all tests are done on two different types of disks: a USB flash drive and a hard disk drive (also connected via USB).

The benchmark used consists of a search for files in a hierarchy of directories. In other words, this report is focused on seek times since nothing is written to disk and just meta data (such as file name and directory content) is read.

2 Method

The benchmark consists of a program (mfind, see listing 1) that searches for files in a hierarchy of directories and prints out the time taken for each call to readdir. A script (timer.sh, see listing 2) is used to run mfind in four parallel processes, ten times for each of the three schedulers, and collects all timing data in log files. The partition is unmounted between each run to make sure that no files are cached.

Processing of the data is done by stats.py (see listing 3) in order to obtain some statistical properties. The python library Pandas¹ proved very helpful in this regard.

Remark 1. The program mfind was originally made for another assignment and was here simplified and modified to measure the time required for each I/O request. In addition to mfind.c the program also consists of a parser (parser.c and parser.h in listings 4 and 5) and the linked list that keeps track of what directories to search (list.c and list.h in listings 6 and 7). The complete program can be compiled using the make file in listing 8.

A script was also used to create the tree of searched directories in order to make the benchmark easier to reproduce. This script can be found in listing 9.

All tests were run on my personal computer with the specifications seen in table 1. The drives used was a Kingston DataTraveler 1 GB and a Verbatim 500 GB portable 2.5" HDD. Both drives were connected to a USB 2.0

¹http://pandas.pydata.org/

port.

Component	Specification
OS:	Fedora 25
Kernel:	Linux 4.8.13-300.fc25.x86_64
CPU:	Intel Core i5-2500K CPU @ 3.7GHz
RAM:	7965MiB
GCC:	6.2.1
Bash:	4.3.43
Python:	3.5.2
Pandas:	0.18.1
Matplotlib:	1.5.3

Table 1: Test system specification.

3 Results

The calculated statistical properties of the timing data can be seen in tables 2 and 3. Only slight differences can be seen between the schedulers for the flash drive. Most noticeably, the maximum time required is considerably greater for cfq than for the other schedulers. This also reflects on a greater standard deviation.

	cfq	deadline	noop
count	$1.709\cdot 10^5$	$1.709\cdot 10^5$	$1.709 \cdot 10^5$
mean	$4.546 \cdot 10^{-4}$	$4.478 \cdot 10^{-4}$	$4.399 \cdot 10^{-4}$
std	$1.465 \cdot 10^{-3}$	$1.396 \cdot 10^{-3}$	$1.395 \cdot 10^{-3}$
\min	$2.600 \cdot 10^{-8}$	$2.600 \cdot 10^{-8}$	$2.100 \cdot 10^{-8}$
25%	$8.400 \cdot 10^{-8}$	$8.500 \cdot 10^{-8}$	$8.400 \cdot 10^{-8}$
50%	$2.160 \cdot 10^{-7}$	$2.140 \cdot 10^{-7}$	$2.150 \cdot 10^{-7}$
75%	$1.914 \cdot 10^{-5}$	$1.888 \cdot 10^{-5}$	$1.845 \cdot 10^{-5}$
max	$6.358 \cdot 10^{-2}$	$3.325 \cdot 10^{-2}$	$4.208 \cdot 10^{-2}$

Table 2: Statistical properties for the Kingston flash drive. The time values are measured in seconds.

Looking at the means and medians (50 % quantile), we see that noop has the lowest mean, but is beaten by deadline when it comes to the median. Noop also has the lowest minimum time required.

The picture is quite different when looking at table 3. This is for a traditional spinning hard drive, so the cfq scheduler get to shine. The cfq scheduler has the best mean, minimum, median and 75 % quantile. All this comes at a cost, of course, the maximum time is far greater than for the other schedulers. Despite this, however, the cfq still manages to have the lowest standard deviation among the three.

	cfq	deadline	noop
count	$1.709\cdot 10^5$	$1.709 \cdot 10^{5}$	$1.709\cdot 10^5$
mean	$2.892 \cdot 10^{-4}$	$4.626 \cdot 10^{-4}$	$4.413 \cdot 10^{-4}$
std	$2.018 \cdot 10^{-3}$	$3.082 \cdot 10^{-3}$	$3.030 \cdot 10^{-3}$
\min	$2.300 \cdot 10^{-8}$	$2.600 \cdot 10^{-8}$	$2.400 \cdot 10^{-8}$
25%	$1.170 \cdot 10^{-7}$	$1.210 \cdot 10^{-7}$	$1.230 \cdot 10^{-7}$
50%	$2.490 \cdot 10^{-7}$	$2.610 \cdot 10^{-7}$	$2.590 \cdot 10^{-7}$
75%	$2.036 \cdot 10^{-6}$	$2.320 \cdot 10^{-6}$	$2.366 \cdot 10^{-6}$
max	$1.259 \cdot 10^{-1}$	$8.426 \cdot 10^{-2}$	$8.346 \cdot 10^{-2}$

Table 3: Statistical properties for the Verbatim HDD. The time values are measured in seconds.

A comparison of the two drives reveals that the scheduler should be chosen depending on the type of drive for best performance. On a traditional spinning drive, there is more to win by ordering the requests in an efficient way. However, the ordering does not matter much on a solid state drive, since there is no physical movement required. In that case is is better not to spend time finding the "perfect order" and thus delay some requests.

In order to improve the noop scheduler on traditional HDDs we would have to allow a higher maximum time. This would give the scheduler a better possibility to control the ordering of the requests.

Similarly, the cfq scheduler would probably be faster on flash drives if it just sent all requests in the order they came in, instead of reordering them. The deadline scheduler is similar in performance to the noop scheduler on both drives and could probably improve it's performance on HDDs in the same way. My guess is that the deadline and noop schedulers would show greater differences if the requests were longer.

4 Final thoughts and lessons learned

Caching of data gave some problems at first, but this could easily be solve by unmounting the drive between each run. However, the unmounting was quite problematic for the HDD since it would sometimes remain busy even after a sync call. To solve this, a one second sleep was added to the script.

The problem with sync and umount made me quite suspicious of the data gathered. I am uncertain about what really should be timed and how to make sure that the I/O requests are actually done on the disk and not just in some cache. Perhaps more fine tuned control would be needed to solve these problems, with calls to syncfs periodically. But that makes it hard to determine the actual time taken for individual requests.

One thing is clear: the I/O scheduler can definitely have a great impact on performance and it can be quite tricky to accurately measure the performance of these schedulers. Some theoretical background would have been interesting and helpful if time would have allowed for that during the lectures.

A Code listings

Listing 1: mfind.c

```
1 /**
    * File: mfind.c
     * Author: Lennart Jern - ens16ljn@cs.umu.se
    * Usage: ./mfind [-t \{d|f|1\}] [-p nrthr] start1 [start2 ...] name
    * mfind can search after files, links and directories from given start paths.
    * The search can be done with more than one thread by specifying the flag
     * '-p#', where # is the number of threads to use.
9
10
11
    #define _GNU_SOURCE
12
    #include <stdio.h>
14
15
    #include <stdlib.h>
    #include <errno.h>
    #include <string.h>
17
18
   #include <dirent.h>
   #include <sys/stat.h>
19
                                // timing
   #include <time.h>
20
21
    #include "parser.h"
                                // Includes list.h
22
   #define ONE_OVER_BILLION 1E-9
23
24
   void *find_file(void *s_data);
25
26
   int search_path(SearchData *data, char *path);
    int search_directory(SearchData *search_data, DIR *dir, char *path);
27
   int get_dirent(struct dirent *priv_dirent, DIR *dir);
28
29
   void process_file(char *file_path, char *name,
                     struct stat f_stat, SearchData *data);
30
   int add_dir(LinkedList *list, char *dir_path);
31
    void check_starting_dirs(SearchData *search_data);
    void print_path(void *path);
33
34
    void delete_path(void *path);
    void SearchData_delete(SearchData *s_data);
35
36
37
    * main - parse arguments, do the search and then clean up.
38
39
    * Oparam argc -- number of arguments
    * Oparam argv -- array of arguments
40
                  O if everything went well, a positive int otherwise
    * @return
41
42
43
    int main(int argc, char *argv[]) {
44
        int ret = 0;
45
        SearchData *search_data = parse_arguments(argc, argv);
46
47
        check_starting_dirs(search_data);
      #ifdef DEBUG
49
        50
        printf("#_\Threads:_\%d\n", search_data->num_threads);
51
        printf("#_Type:_%c\n", search_data->type);
52
53
        printf("\#_{\sqcup}Needle:_{\sqcup}\%s\n", search_data->needle);
        List_print(search_data->directories, print_path);
54
        printf("=======\n\n");
55
      #endif
```

```
58
         search_data->num_searchers = 0;
59
60
         find_file(search_data);
61
62
         // Check for errors
         ret = search_data->error;
63
64
         // Free allocated memory
65
         SearchData_delete(search_data);
66
         return ret;
    }
67
68
69
70
     * find_file - search for files and directories
71
     * @param s_data -- search data, containing needle to look for and list of
                         directories to look in
72
73
    void *find_file(void *search_data) {
74
75
         unsigned int reads = 0;
         SearchData *data = search_data;
76
         char *path = NULL;
77
78
         int error = 0;
79
         // Keep searching while there are dirs in the list.
80
81
         while((path = (char *)List_get(data->directories)) != NULL) {
82
83
             data->num_searchers++;
84
             reads++:
85
             if (search_path(data, path) != 0) {
86
                perror(path);
87
                 // We don't consider permission denied or missing dir as errors
88
89
                 // error = 1;
90
91
92
             delete_path(path);
93
             data->num_searchers--;
94
         } // End while. No more dirs to search and all threads done.
95
           // Make sure caller knows if there were errors.
         data->error = error;
96
97
         98
         return NULL;
   }
99
100
101
102
     * search_path - open and search the directory given by path
     * Oparam data -- SearchData (what to search for)
103
     * @param path -- path to directory to search
104
105
     * @return
                   0 on successful search, -1 if there were errors
106
107
    int search_path(SearchData *data, char *path) {
         // Open the directory. If it fails, clean up and continue with the next one.
108
         DIR *dir = opendir(path);
109
         int ret = 0;
110
111
         if (dir == NULL) {
112
113
             ret = -1;
             return ret;
114
115
116
         // Check for matches in the dir
117
         if (search_directory(data, dir, path) != 0) {
118
            ret = -1;
119
```

```
120
121
122
         if (closedir(dir) != 0) {
            perror("closedir");
123
124
125
        return ret:
    }
126
127
128
129
     * add folders to the list.
130
     * @param search_data -- data regarding the search
131
132
     * Oparam dir
                          -- dir to look in
      * @param path
133
                           -- path to the dir (used for printing)
134
     * @return
                            O if everything went well, a poitive int otherwise.
135
    int search_directory(SearchData *search_data, DIR *dir, char *path) {
136
137
         struct dirent *priv_dirent;
         struct stat f_stat;
138
        char *file_path = NULL;
139
140
         int at_end = 0;
        int ret = 0;
141
142
143
         while (at_end != 1) {
            priv_dirent = malloc(sizeof(struct dirent));
144
145
             if (priv_dirent == NULL) {
                 perror("malloc");
146
                 exit(EXIT_FAILURE);
147
148
149
150
            at_end = get_dirent(priv_dirent, dir);
151
             if (at_end != 0) {
152
                 // Either error or end of dir
153
                 if (at_end == -1) {
154
                    ret++;
155
156
                 free(priv_dirent);
157
                 continue;
            }
158
159
             // Build file path string
160
             if (asprintf(&file_path, "%s/%s", path, priv_dirent->d_name) == -1) {
161
                 fprintf(stderr, "Error: \_asprintf \_failed. \_Unable \_to \_set \_file\_path. \n");
162
                 free(priv_dirent);
163
164
                 ret++;
                 continue;
165
            }
166
167
             // Get stats (file type)
            if (lstat(file_path, &f_stat) != 0) {
168
169
                 perror(file_path);
170
                 free(priv_dirent);
                 free(file_path);
171
172
                 ret++;
                 continue;
173
            }
174
175
             // Print matches.
176
177
            process_file(file_path, priv_dirent->d_name, f_stat, search_data);
178
             // Add directories to the list (not . and ..)
179
180
             if (S_ISDIR(f_stat.st_mode)
                 && strcmp(priv_dirent->d_name, ".") != 0
181
```

```
182
                  && strcmp(priv_dirent->d_name, "..") != 0) {
183
184
                  if (add_dir(search_data->directories, file_path) != 1) {
                      fprintf(stderr, "Failed_{\sqcup}to_{\sqcup}add_{\sqcup}directory_{\sqcup}to_{\sqcup}list.\n");
185
186
                      return -1;
187
             }
188
189
             free(file_path);
190
191
             file_path = NULL;
              free(priv_dirent);
192
             priv_dirent = NULL;
193
194
195
         return ret:
     }
196
197
198
199
     * get_dirent - copy the next dirent in dir to priv_dirent in a thread safe way.
      * This private dirent is safe to use in a multi thread environment.
200
      * @param priv_dirent -- pointer to dirent where the dirent will be saved.
201
202
      * @param dir
                             -- dir to read from
203
      * @return
                             -1 on error, 1 when the last element was read and
                                 0 otherwise
204
205
     int get_dirent(struct dirent *priv_dirent, DIR *dir) {
206
207
         struct dirent *dirent;
         errno = 0;
208
209
         // Starting time
210
211
         struct timespec start;
         // Time when finished
212
213
         struct timespec end;
         clock_gettime(CLOCK_REALTIME, &start);
214
215
216
         dirent = readdir(dir);
217
218
         // Get the time when finished
         clock_gettime(CLOCK_REALTIME, &end);
219
         // Calculate time it took
220
221
         double time_taken = (end.tv_sec - start.tv_sec)
                              + (end.tv_nsec - start.tv_nsec)
222
                              * ONE_OVER_BILLION;
223
         printf("%.12lf\n", time_taken);
224
225
         if (errno != 0) {
226
             perror("readdir");
227
228
             return -1;
         } else if (dirent == NULL) {
229
             // No more files to read
230
231
             return 1;
232
         // Copy dirent to private memory
233
         memcpy(priv_dirent, dirent, sizeof(struct dirent));
234
235
         return 0;
236 }
237
238
239
      * process_file - print out matching file.
      * @param file_path -- the path to the file
                      -- name of the file
-- file stats
      * Oparam name
241
242
      * Oparam f_stat
243 * @param data -- SearchData (what type and name are we looking for?)
```

```
244 */
245
    void process_file(char *file_path, char *name,
246
                      struct stat f_stat, SearchData *data) {
         int match = 0;
247
248
         char type = data->type;
         // Is the name matching?
249
         if (strcmp(name, data->needle) == 0) {
250
251
             match = 1;
252
253
         // Check type, print if we have a match
254
         if (S_ISDIR(f_stat.st_mode)) {
255
             if (match == 1 && (type == 'd' || type == '\0') ) {
256
                 printf("%s\n", file_path);
257
258
259
         } else if (S_ISREG(f_stat.st_mode)) {
             if (match == 1 && (type == 'f' || type == '\0') ) {
260
261
                 printf("%s\n", file_path);
262
         } else if (S_ISLNK(f_stat.st_mode)) {
263
             if (match == 1 && (type == '1' || type == '\0') ) {
264
265
                 printf("%s\n", file_path);
266
267
    }
268
269
270 /**
     * add_dir - add a directory to the list in a thread safe manner
271
272
     * @param list -- list to add to
      * @param dir_path -- path to the directory
273
                       1 if the dir was added, 0 if addition failed.
274
     * @return
275
276
    int add_dir(LinkedList *list, char *dir_path) {
277
         char *new_dir = malloc(strlen(dir_path)+1);
278
         if (new_dir == NULL) {
             perror("malloc");
279
280
             exit(EXIT_FAILURE);
281
         strcpy(new_dir, dir_path);
282
283
         if (List_append(list, (void *)new_dir) != 1) {
284
285
            return 0;
286
287
         return 1;
288 }
289
290 /**
291
     st check_starting_dirs - check if the starting dirs match the search criterias
     * Cparam search_data -- data egarding the search
292
293
294
     void check_starting_dirs(SearchData *search_data) {
295
         char *path;
296
         struct stat f_stat;
         LinkedList *checked_dirs = List_init();
297
298
299
         // Check all starting dirs for matches
         while((path = (char *)List_get(search_data->directories)) != NULL) {
300
             if (lstat(path, &f_stat) != 0) {
301
                 perror(path);
                 continue;
303
304
           // Print if there is a match
305
```

```
306
             process_file(path, basename(path), f_stat, search_data);
307
308
              // Add the checked dir to the new list
              char *new_dir = malloc(strlen(path)+1);
309
              if (new_dir == NULL) {
310
                  perror("malloc");
311
                  exit(EXIT_FAILURE);
312
             strcpy(new_dir, path);
314
315
              if (List_append(checked_dirs, (void *)new_dir) == 0) {
316
                  fprintf(stderr, "Could_{\sqcup}not_{\sqcup}add_{\sqcup}path_{\sqcup}to_{\sqcup}list. \backslash n");
317
318
                  search_data->error++;
319
320
             free(path);
321
         // Delete the old list
322
323
         List_delete(search_data->directories, delete_path);
324
         // Add the checked dirs
         search_data->directories = checked_dirs;
325
326 }
327
328
329
      * print_path - print out a path
     * Oparam path -- a void pointer to a path string
330
331
     void print_path(void *path) {
332
         char *str = (char *)path;
333
         printf("%s\n", str);
334
335
336
337
338
     * delete_path - delete and free any memory occupied by path
339
     * Oparam path -- path to be freed
340
     void delete_path(void *path) {
341
342
         free(path);
343
344
345
     * SearchData_delete - free all memory allocated for s_data
346
347
     * @param s_data -- SearchData to free
348
     void SearchData_delete(SearchData *s_data) {
349
350
         free(s_data->needle);
351
         List_delete(s_data->directories, delete_path);
352
         free(s_data);
353 }
```

Listing 2: timer.sh

```
#!/bin/bash

# timer.sh

# #

# A timer script to measure the differences between i/o schedulers

# # Author: Lennart Jern (ens16ljn@cs.umu.se)

# Clean up old results

m ../data/*.log
```

```
11
    {\tt SCHEDULERS="cfq\_noop\_deadline"}
12
13
    DEVICE="/sys/block/sdc/queue/scheduler"
14 # Starting directory and expression to search for
# START="/run/media/lennart/KINGSTON/test_files expression"
    {\tt START="/run/media/lennart/Verbatim/test\_files\_expression"}
16
    # MNT="/run/media/lennart/KINGSTON"
17
    MNT="/run/media/lennart/Verbatim"
19
    for S in $SCHEDULERS
20
21
        echo $S | sudo tee $DEVICE
22
        echo "Scheduler: _ 'cat _ $DEVICE'"
23
        # LINE=""
24
        # Time the commands 10 times
25
26
        for i in $(seq 1 10)
27
        do
28
            # Unmount and mount to clear all cache
29
            sync
30
            sleep 1
31
            sudo umount -f $MNT
32
            sudo rm -d $MNT
            sudo mkdir $MNT
33
34
            sudo mount /dev/sdc1 $MNT
35
36
            \mbox{\#} We use 4 parallel1 comands that store their respective times in
             # separate log files
37
            {\tt COMMAND1="./mfind} \bot {\tt START} \bot >_{\sqcup} ... / {\tt data} / {\tt S-1.log}"
38
            COMMAND2="./mfind_$START_>>_../data/$S-2.log"
39
            40
            COMMAND4="./mfind_$START_>>_../data/$S-4.log"
41
42
            eval $COMMAND1 &
43
            eval $COMMAND2 &
44
45
            eval $COMMAND3 &
            eval $COMMAND4 &
46
47
            # Wait for all commands to finish
48
49
50
            # A little progress report
51
            echo "Run⊔$i⊔done."
52
        done
53
54
    done
55
    # Restore cfq scheduler
56
   echo "cfq" | sudo tee $DEVICE
```

Listing 3: stats.py

```
1 """
2 stats.py
3
4 Process the data produced by timer.sh by calculating the medians, max values and min values for each scheduler.
6
7 Author: Lennart Jern (ens16ljn@cs.umu.se)
8 """
9
10 import pandas as pd
11 import re
```

```
12
13
    def produce_stats():
14
        Read the data from files, calculate statistical values and make a plot.
15
16
17
        base = "../data/"
        ext = ".csv"
18
19
        header=("cfq", "deadline", "noop")
20
        # Get individual read times as a DataFrame
21
        df = get_read_times()
22
23
        stats = df.describe()
24
25
        # Escape per cent chars
        idx = ['count', 'mean', 'std', 'min', '25\%', '50\%', '75\%', 'max']
26
27
        stats = stats.set_index([idx])
28
29
        # Save stats as csv
        stats.to_csv(base+"stats.csv", header=header, float_format="%.3e")
30
31
32
33
    def collect_read_times(file_name):
         ""Read thread times from a file."""
34
35
        f = open(file_name)
        times = []
36
        # Regular expression to find floats
37
        time = re.compile("(\d+\.\d+)")
38
39
        for line in f:
40
            match = time.match(line)
41
42
43
            if (match):
                 t = float(match.group(1))
44
45
                 times.append(t)
46
        return times
47
48
49
    def get_read_times():
          ""Collect timing information about all schedulers in a DataFrame."""
50
51
        schedulers = ["cfq", "deadline", "noop"]
        base = "../data/"
ext = ".log"
52
53
        header=("cfq", "deadline", "noop")
54
55
        # Collect all times in one file
56
        times = {key: [] for key in schedulers}
57
        for s in schedulers:
58
59
            # We have 4 parallell log files for each scheduler
            for i in [1,2,3,4]:
60
                f = base+s+"-"+str(i)+ext
61
62
                 times[s].extend(collect_read_times(f))
        # Return a DataFrame with all timing data
63
        df = pd.DataFrame(times)
64
        return df
65
66
67
    # Collect statistical data
   produce_stats()
```

Listing 4: parser.c

1 /**

```
2 * File: parser.c
     * Author: Lennart Jern - ens16ljn@cs.umu.se
 4
     * This parser extracts search data from command line arguments.
5
 6
7
    #include <stdio.h>
    #include <stdlib.h>
10
    #include <getopt.h>
11
    #include <errno.h>
12
    #include <string.h>
#include "parser.h"
13
14
15
16
17
     * parse_arguments - parse command line arguments into SearchData.
     * The SearchData should be freed by calling SearchData_delete when
18
19
     * you are done.
     * Cparam argc -- number of arguments
* Cparam argv -- array of arguments
20
21
                     SearchData containing: dirs to look in, needle to look
22
     * @return
23
                              for, file type and number of threads.
24
25
    SearchData *parse_arguments(int argc, char *argv[]) {
         SearchData *s_data;
26
27
         \label{eq:char_susage} \textbf{char} \ *usage = \ "Usage:$_{\sqcup}./mfind$_{\sqcup}[-t$_{\sqcup}\{d|f|1\}]$_{\sqcup}[-p$_{\sqcup}nrthr]$_{\sqcup}start1$_{\sqcup}[start2$_{\sqcup}...]$_{\sqcup}name";
28
         // No point to continue if there are less than 3 args
29
30
         if (argc < 3) {
             fprintf(stderr, "%s\n", usage);
31
             exit(EXIT_FAILURE);
32
33
34
35
         s_data = malloc(sizeof(SearchData));
36
         if (s_data == NULL) {
             perror("malloc");
37
38
              exit(EXIT_FAILURE);
39
40
41
         // Set num_threads and type from given arguments
         if (set_flags(s_data, argc, argv) != 0) {
   fprintf(stderr, "%s\n", usage);
42
43
              exit(EXIT_FAILURE);
44
45
         // Make sure the flags are safe
46
47
         check_flags(s_data);
48
49
         // Check that there is at least one dir to look in and a name to look for.
         if (optind >= argc -1) {
50
51
             fprintf(stderr, "%s\n", usage);
52
              free(s_data);
              exit(EXIT_FAILURE);
53
54
55
         add_dirs_and_needle(s_data, argv, optind, argc-1);
56
57
         return s_data;
58
    }
59
60
61
     * set_flags - parse the arguments and add corresponding search data
62
* @param s_data -- SearchData to add info to
```

```
* Oparam argc -- number of arguments
     * Oparam argv -- array of arguments
66
     * @return
                         O if everything went well, -1 otherwise.
67
68
    int set_flags(SearchData *s_data, int argc, char *argv[]) {
69
         char *optstr = "t:p:";
70
         int opt;
71
         char type = '\0';
72
         int num_threads = 1;
73
74
         // Parse flags
         while ((opt = getopt(argc, argv, optstr)) != -1) {
75
76
             char *end;
             switch (opt) {
77
             case 't':
78
79
                  type = *optarg;
                 break;
80
81
             case 'p':
82
                  errno = 0;
                  num_threads = strtol(optarg, &end, 10);
83
                  if (errno != 0) {
84
85
                     perror("strtol");
86
87
                  break;
             default:
88
89
                  return -1;
90
         }
91
92
         s_data->num_threads = num_threads;
93
94
         s_data->type = type;
95
         return 0;
96
    }
97
98
     * check_flags - make sure the flags (num_threads and type) are correct and safe
99
100
     * @param s_data -- SearchData to check.
101
     void check_flags(SearchData *s_data) {
102
103
         int num_threads = s_data->num_threads;
         char type = s_data->type;
104
105
         if (num_threads < 1) {</pre>
106
             fprintf(stderr, "Number \_ of \_ threads \_ must \_ be \_ more \_ than \_ 0! \n");
107
108
             exit(EXIT_FAILURE);
         } else if (num_threads > MAXTHREADS) {
109
             fprintf(stderr, \ "Too_{\sqcup}many_{\sqcup}threads!_{\sqcup}Resetting_{\sqcup}to_{\sqcup}1. \ \ \ ");
110
111
             num_threads = 1;
112
113
         if (type != 'd' && type != 'f' && type != 'l' && type != '\0') {
             fprintf(stderr, "Type_must_be_d|f|1.\n");
114
             exit(EXIT_FAILURE);
115
116
117
         s_data->num_threads = num_threads;
118
119
         s_data->type = type;
120 }
121
     * add_dirs_and_needle - parse starting dirs and needle from arguments and
123
124
     * add them to the search data.
* Oparam s_data -- search data to add to
```

```
126
   * Oparam argv -- array of arguments
127
      * @param first \operatorname{\mathsf{--}} index of first directory in argv
128
      * @param last -- index of last element in argv. This should be the needle.
129
     void add_dirs_and_needle(SearchData *s_data, char *argv[], int first, int last) {
130
         LinkedList *dirs = List_init();
131
132
         char *needle;
         int num_dirs = last - first;
133
134
         \ensuremath{//} Add all starting directories to the list of dirs.
135
         for (int i = 0; i < num_dirs; i++) {</pre>
136
              char *new_dir = malloc(strlen(argv[first+i])+1);
if (new_dir == NULL) {
137
138
                  perror("malloc");
139
                  exit(EXIT_FAILURE);
140
141
              strcpy(new_dir, argv[first+i]);
142
143
              if (List_append(dirs, (void *)new_dir) == 0) {
144
                  fprintf(stderr, "Could_not_add_path_to_list.\n");
145
146
                  s_data->error++;
147
         }
148
149
         // The last arg is the needle/name to search for
150
151
         needle = argv[last];
         s_data->needle = malloc(strlen(needle)+1);
152
         if (s_data->needle == NULL) {
153
              perror("malloc");
154
              exit(EXIT_FAILURE);
155
156
157
158
         // Add everything to s_data.
159
         strcpy(s_data->needle, needle);
160
         s_data->directories = dirs;
161 }
```

Listing 5: parser.h

```
* File: parser.h
3
    * Author: Lennart Jern - ens16ljn@cs.umu.se
     * This is a header file for a parser that extracts search data from command
5
 6
    * line arguments.
 7
8
    #include "list.h"
10
11
12
    #define MAXTHREADS (1)
13
14
    typedef struct search_data SearchData;
15
16
    struct search_data {
17
            char *needle;
            LinkedList *directories;
18
19
            int num_threads;
20
            char type;
            int num_searchers;
21
            unsigned int error;
```

```
23 };
24
25 SearchData *parse_arguments(int argc, char *argv[]);
26 int set_flags(SearchData *s_data, int argc, char *argv[]);
27 void check_flags(SearchData *s_data);
28 void add_dirs_and_needle(SearchData *s_data, char *argv[], int first, int last);
```

Listing 6: list.c

```
/**
 1
     * File: list.c
     * Author: Lennart Jern - ens16ljn@cs.umu.se
5
     * A simple implementation of a linked list.
6
8
    #include <stdio.h>
9
    #include <stdlib.h>
    #include <string.h>
#include "list.h"
11
12
13
14
15
    * List_init
    * Create and initialize a LinkedList.
16
^{17}
18
    * @return pointer to list
19
20
    LinkedList *List_init(void) {
        LinkedList *lst = calloc(1, sizeof(LinkedList));
21
        if (lst == NULL) {
22
             fprintf(stderr, "Allocation uof umemory ufor ulinked ulist ufailed \n");
             exit(EXIT_FAILURE);
24
25
26
        return lst;
27 }
28
29 /**
    * Appends an element with the specified value to the list
30
31
     * Oparam 1: List to append to
     * Oparam value: Pointer to value to be added
32
33
    * @return
                     1 on success, otherwise 0.
34
    int List_append(LinkedList *1, void *value) {
35
36
37
         Node *new_node = calloc(1, sizeof(Node));
        if (new_node == NULL) {
38
39
             fprintf(stderr, "Failed_{\sqcup}to_{\sqcup}allocate_{\sqcup}memory_{\sqcup}for_{\sqcup}new_{\sqcup}node. \n");
             return 0;
40
41
42
        new_node->value = value;
        new_node->next = NULL;
43
44
         if (1->first == NULL) {
45
            1->first = new_node;
46
47
             return 1;
48
        Node *node_ptr = 1->first;
49
50
        while (node_ptr->next != NULL) {
51
           node_ptr = node_ptr->next;
```

```
53
54
         node_ptr->next = new_node;
55
         return 1;
    }
56
57
58
     * List_get - get the value of the first node in the list and delete the node
59
     * from the list.
     * @param l -- the list
61
     * @return -- pointer to value, remember to free it later.
62
63
     void *List_get(LinkedList *1) {
64
65
         if (1->first == NULL) {
66
             return NULL;
67
68
         Node *node = 1->first;
         1->first = 1->first->next;
69
70
         void *value = node->value;
         free(node);
71
         node = NULL;
72
73
         return value;
74
    }
75
76
77
     * List_sort
78
     \boldsymbol{\ast} Sort the list 1st by selection sort, using the comparison function comp.
      * Oparam lst: LinkedList to sort
79
     \boldsymbol{\ast} Oparam comp: function used to compare the values of two nodes to determine
80
81
                     what order they should be placed in.
82
83
     void List_sort(LinkedList *lst, int (*comp)(void *value1, void *value2)) {
84
         if (lst->first == NULL) {
85
             // Empty list, nothing to do
86
             return;
87
         Node *boundary = lst->first; // ordered nodes before this
88
89
         Node *smallest = lst->first; // should be placed next in order
         Node *last_sorted = NULL; // add smallest after this one
90
         Node *current = lst->first;
91
92
         Node *prev = NULL;
         Node *before_smallest = NULL;
93
94
         // run untill the whole list is sorted
         while (boundary->next != NULL) {
96
97
             smallest = boundary;
             current = boundary;
98
             prev = NULL;
99
100
             before_smallest = NULL;
             // loop through the unordered part of the list and pick out the node
101
102
             // with the "smallest" value
103
             while (current->next != NULL) {
                 prev = current;
104
105
                 current = current->next;
106
                 if (comp(smallest->value, current->value) < 0) {</pre>
                      smallest = current;
107
108
                      before_smallest = prev;
109
             }
110
111
             // Do we have to move smallest?
112
             if (before_smallest != NULL) {
113
                // cut out smallest
114
```

```
115
                 before_smallest->next = smallest->next;
116
                 if (last_sorted == NULL) {
117
                      // place it first
                      smallest->next = lst->first;
118
119
                     lst->first = smallest;
                 } else {
120
                      // place it after last_sorted
121
122
                      smallest->next = last_sorted->next;
                     last_sorted->next = smallest;
123
124
125
             // update last_sorted and boundary
126
127
             last_sorted = smallest;
             boundary = smallest->next;
128
129
130
    }
131
132
133
     * List_remove
      * Removes an element from the bottom of the list and frees the allocated memory
134
135
      * by calling delete_value(value).
136
      * Oparam lst: the list to remove from
137
138
     * Oreturn 1 on successful removal, 0 if no node was removed.
139
140
     int List_remove(LinkedList *lst, void (*delete_value)(void *value)) {
         Node *node = lst->first;
141
         Node *prev = node;
if (node == NULL) {
142
143
             return 0;
144
145
         if (node->next == NULL) { // Only one element in list
146
147
             delete_value(node->value);
148
             free(node);
149
             lst->first = NULL;
             return 1;
150
151
152
         while (node->next != NULL) {
153
             prev = node;
154
             node = node->next;
155
156
         prev->next = NULL;
         delete_value(node->value);
157
         free(node);
158
159
         return 1;
160
161
162
     * List_delete
163
164
     * Frees all memory allocated by the nodes in the LinkedList
      * using delete_value(value) and frees the list itself after that.
165
166
      * Oparam 1st:
167
                             LinkedList to free.
      * Cparam delete_value: function used to free the memory allocated by the value
168
                              of a node.
169
170
171
     void List_delete(LinkedList *lst, void (*delete_value)(void *value)) {
172
         if (lst) {
             while(List_remove(lst, delete_value)) ;
173
             free(lst);
174
175
176 }
```

```
177
178
179
     * List_print
     * Prints the LinkedList using the function provided.
180
181
     * @param lst: LinkedList to print.
182
     * Oparam print: function used to print the node values.
183
184
    void List_print(LinkedList *lst, void (*print)(void *value)) {
185
186
         Node *current = lst->first;
187
         while (current != NULL) {
188
             print(current->value);
189
             current = current->next;
190
191
192 }
```

Listing 7: list.h

```
1 /**
 2
    * File: list.h
    * Author: Lennart Jern - ens16ljn@cs.umu.se
 4
    * This is a header file for my own implementation of a liked list.
 6
    */
 8
    typedef struct linked_list LinkedList;
9
10
    typedef struct node Node;
11
    struct node {
12
           void *value;
13
           struct node *next;
14
15 };
16
17 struct linked_list {
18
           Node *first;
   };
19
20
21
    struct user_info {
           unsigned int uid;
22
23
           char *uname;
24
    };
25
26 /**
27
    * List_init
    * Create and initialize a LinkedList.
28
    * @return pointer to list
30
31
32 LinkedList * List_init(void);
33
34
    * Appends an element with the specified value to the list
35
    * @param 1: List to append to
36
37
    * Oparam value: Pointer to value to be added
    * @return
                  1 on success, otherwise 0.
38
39
   int List_append(LinkedList *1, void *value);
40
41
42 /**
```

```
43 * List_get - get the first element from the list. The element is removed
    * from the list so remember to free it when you are done.
    * Operam 1 -- the list

* Oreturn -- a pointer to the first value in the list
45
46
47
   void *List_get(LinkedList *1);
48
49
50 /**
    * List_sort
51
52
    * Sort the list 1st by selection sort, using the comparison function comp.
    * @param lst: LinkedList to sort
53
    * Oparam comp: function used to compare the values of two nodes to determine
54
55
                    what order they should be placed in.
56
57 void List_sort(LinkedList *lst, int (*comp)(void *value1, void *value2));
58
59 /**
60
    * List_remove
    * Removes an element from the bottom of the list and frees the allocated memory
61
    * by calling delete_value(value).
62
63
64
    * @param lst: the list to remove from
    * @return 1 on successful removal, 0 if no node was removed.
65
int List_remove(LinkedList *lst, void (*delete_value)(void *value));
68
69 /**
    * List_delete
70
    * Frees all memory allocated by the nodes in the LinkedList
71
    * using delete_value(value) and frees the list itself after that.
72
73
74
    * Oparam lst:
                           LinkedList to free.
75
    * @param delete_value: function used to free the memory allocated by the value
76
                            of a node.
77
   void List_delete(LinkedList *lst, void (*delete_value)(void *value));
78
79
80
    * List_print
81
    * Prints the LinkedList using the function provided.
82
83
84
    * Oparam lst: LinkedList to print.
    * Oparam print: function used to print the node values.
85
86
87  void List_print(LinkedList *lst, void (*print)(void *value));
```

Listing 8: Makefile

```
SOURCE=mfind.c list.c

DBJECTS=mfind.o list.o parser.o

FLAGS=-std=c11 -Wall -pedantic -Werror -pthread

all: $(OBJECTS)

gcc $(OBJECTS) -pthread -o mfind

gcc $(FLAGS) crazy_search.c -o crazy_search

mfind.o: mfind.c

gcc $(FLAGS) -c mfind.c

list.o: list.c list.h

gcc $(FLAGS) -c list.c
```

```
14
   parser.o: parser.c parser.h list.h
15
16
           gcc $(FLAGS) -c parser.c
17
18 debug: FLAGS+=-DDEBUG -g
    debug: all
19
20
21
    test: all
22
            ./mfind -td -p2 . .. fail mfind
23
24 time: FLAGS+=-DTIME
25 time: all
26
27
    memtest: all
           valgrind ./mfind -td -p2 . .. mfind
28
29
30 clean:
           rm -f mfind *.o
```

Listing 9: generate_test_files.sh

```
1 #!/bin/bash
   # File: generate_test_files.sh
4 # Author: Lennart Jern - ens16ljn@cs.umu.se
5 #
   # Generate a file tree to do tests on.
   # Starting directory
9
    # START=/run/media/lennart/KINGSTON
10
    START=/run/media/lennart/Verbatim
11
# Move to correct directory/device
13 cd $START
15 # Remove tree if existent
16
    rm -r test_files
17
18 # Create directory to hold all test files
19
    mkdir test_files
20 cd test_files
^{21}
22
   # Split up the files between a few directories
   for DIR in a b c d e; do
23
24
        mkdir $DIR
25
        cd $DIR
        # Create empy files
26
27
       for F in $(seq 1 20); do
            touch $F
28
        done
29
        for D in f g h i j; do
    mkdir $D
31
32
            cd $D
33
        done
34
35
        cd "$START/test_files"
36
    done
37
38
39 # Big files
40 mkdir bigs
```

```
41 cd bigs
42
43 # Generate files with lots of zeros...
44 for F in $(seq 1 5); do
45 head -c 50M < /dev/zero > "file$F"
46 done
47
48 cd "$START/test_files"
49 # Generate deep folders
50 for i in $(seq 1 10); do
51 mkdir "deep$i"
         cd "deep$i"
52
         for D in $(seq 1 100); do
    mkdir "dir$D"
53
54
              cd "dir$D"
55
          done
56
57
         cd "$START/test_files"
58 done
```