## SHUYUAN YANG

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#### **EDUCATION**

Case Western Reserve University (CWRU), Cleveland, OH

Aug. 2022 - Present

M.S. in Computer Science, GPA: 3.33/4.0

University of West Florida (UWF), Pensacola, FL

Aug. 2019 - Jul. 2020

International Exchange Program, GPA: 3.7/4.0 Honor: Dean's List for Fall 2019 & Spring 2020

Taiyuan University of Technology (TYUT), Taiyuan, China

Sep. 2016 - Jul. 2020

B.Eng. in Software Engineering, GPA: 3.11/4.0 Honor: Individual Scholarship of TYUT in 2017

### **PUBLICATIONS**

M. H. Le, **S. Yang**, K. R. Golobish, J. C Beaver, and Z. Chua, "Vision-based force estimation for minimally invasive telesurgery through contact detection and local stiffness models", poster presented at Debate: Data vs. Model in Medical Robotics Workshop at the IEEE/RSJ International Conference for Intelligent Robots and Systems, Detroit, USA, Oct. 5–7, 2023. (Awarded 3<sup>rd</sup> Place for Best Poster Competition)

## **THESIS**

# Reconstructing Telesurgical Manipulator Pose via Reinforcement Learning

Aug. 2023 - Present

Supervisor: Prof. Zonghe Chua (CWRU)

A potential approach for estimating a surgical robot's manipulator position is to use reinforcement learning with stereo video data. By achieving alignment between the actual robot and the reinforcement learning agent, the 6 Degrees of Freedom values of the manipulator can be accurately determined.

- > Created a video dataset and prepared the environment for reinforcement learning in a PyBullet simulator
- Took advantage of DeepLabCut to identify key features in images from the stereo video
- Formulated the pose estimation problem as a visual keypoint alignment problem to be solved by a reinforcement learning agent

#### **Application of Microblog Data Mining Based on K-means Algorithm**

Oct. 2019 - May. 2020

Supervisor: Prof. Fan Liu (TYUT)

To mine the real world data, a web crawler was used to collect microblog data. Natural language processing techniques were employed for embedding the raw data for k-means clustering. To enhance the clustering performance, a user feature model was constructed using principal component analysis.

- Conducted a literature review of the k-means algorithm and its application to microblog data mining
- > Implemented a microblog web crawler to create a custom microblog data set for Sina Weibo
- Converted text data into a sparse matrix using natural language processing methods
- Applied k-means clustering on principal component analysis-embedded features to classify users

#### RESEARCH EXPERIENCE

#### **Vision-based Force Estimation for Telesurgical Robotics**

May. 2023 - Present

Supervisor: Prof. Zonghe Chua (CWRU)

In scenarios where access to robot kinematic and camera parameters data is not available, I developed a graph neural network approach to estimating a normalized 3D end-effector position from video data based on extracted keypoints from DeepLabCut. This is combined with a contact detector to create a contact-conditional visual force estimation algorithm for in-the-wild telesurgical data.

- Designed and trained a graph neural network model on a stereo video dataset to estimate the 3D position of the telesurgical end-effector
- Assisted with the training and hyperparameter optimization of a visual contact detection module based on

the EfficientNetB3 architecture

> Tested the generalization of graph neural network position estimator and contact-conditional force estimator from an artificial tissue dataset to a real tissue dataset

## **Chinese Semantic Automatic Grading System**

Oct. 2018 - Jan. 2019

Supervisor: Prof. Zehua Chen (TYUT)

Compared to automatic grading of multiple choice, I focused on employing natural language processing techniques grading of short answer questions. This was achieved through the development of a system capable of analyzing text similarity in Chinese, significantly enhancing the efficiency of educational assessments.

- Segmented Chinese sentences according to part of speech and extracted keywords from them
- Researched a pre-trained word embedding model to calculate the similarity between any two keywords
- > Developed a GUI based on Tkinter and implemented a paragraph similarity comparison system

### **SELECTED PROJECTS**

## Machine Learning Project: Multiple Instance Learning

Aug. 2022 - Dec. 2022

Instructor: Prof. Soumya Ray (CWRU)

- Implemented two Multi-Instance Learning algorithms, miBoosting and miFV, using Python
- ➤ Utilized Numpy objects and methods to significantly optimize the program's runtime
- Proposed an improvement method and hyperparameter optimization instance that greatly enhanced the accuracy of cross-validation

# **Capstone Project: Single Page Web Application Development**

Jan. 2020 - Apr. 2020

Instructor: Dr. Steven P Bitner (UWF)

- > Developed a course schedule planner system to help students manage and preview their course selection
- Utilized Git for coordinating group development activities, including module development and bug fixing
- ➤ Hosted the system on the cloud, collected data using MongoDB Atlas, and regularly deployed the server and the project on the AWS domain

#### **INTERNSHIP**

#### China Telecom Group System Integration Co., Ltd, Taiyuan Branch

Aug. 2021 - Sep. 2021

Intern of the Network Operation Section

- Provided maintenance and solutions for the local network operators
- ➤ Helped users to appropriately allocate IPv6 in fiber optic modems and routers, and add Dynamic DNS
- Undertook telecom wireless network coverage test, analyzed and summarized the test data in matplotlib

#### EXTRACURRICULAR INVOLVEMENT

#### TYUT Robot Team Fighting Robot Project, Team Leader

Dec. 2017 - Aug. 2018

- Designed Robot with SolidWorks, manufactured and assembled the wheel type robot
- ➤ Programmed movement and developed fighting strategies on STM32 series single-chip microcomputers using C, resulting in the creation of two distinct styles of fighting robots
- ➤ Learned MCU programming, employed digital filtering algorithms to address sensor numerical fluctuations, and utilized timer output for high-frequency PWM square wave motor control
- ➤ Won the **First Prize** in the 2018 World Robot Contest Fighting Robot Competition (5%)

## **3D Innovative Design Project,** Team Leader

Sep. 2017 - Dec. 2017

- ➤ Performed various advanced model pre-processing tasks such as model slicing and support material optimization, for 3D printing and scanning
- Won the **Second Prize** in the National 3D Innovative Design Competition

#### **SKILLS**

Programming Languages: Python, Shell Script, C/C++, JavaScript/TypeScript

Utility Tools: SolidWorks, Linux Server, PyTorch/Torchvision, KiCad, OpenWrt