

This week's homework <https://mycourses.aalto.fi/mod/assign/view.php?id=361337> is due no later than **Thursday 27.09.2018 23:55**.

### Exercise 1.1 Extreme points of a univariate function

Characterize the stationary points of the function  $f(x) = 2x^4 - 5x^3 - x^2$ . Plot the function to verify your analysis.

### Exercise 1.2 Extreme points of a bivariate function

Characterize the stationary points of the function  $f(x, y) = (y - x^2)^2 - x^2$ . Plot the surface and contour plots of the function to verify your analysis.

### Exercise 1.3 Newton's method for a univariate problem

Consider the following unconstrained optimization problem where  $f(x)$  is a univariate function.

$$\text{minimize } f(x) \quad (1)$$

Solve the problem (1) with different functions  $f(x)$  using Newton's method. In the univariate case, Newton's method starts with an initial starting point  $x_0 \in \mathbb{R}$  and updates the solution as follows:

$$x_{n+1} = x_n - f''(x_n)^{-1} f'(x_n)$$

Try different starting points and observe if the method converges to a stationary point or diverges without producing a solution. Plot the functions  $f(x)$  and show the path taken by Newton's method. You can try, for example, the following functions and starting points:

$f(x) = x^4 - x^3 - 8x^2$	try different values for $x_0$
$f(x) = -x^2$	$x_0 = 1$
$f(x) = \arctan(x)$	$x_0 = 1$
$f(x) = (1/4)x^4 - x^2 + 2x$	$x_0 = 0$

### Exercise 1.4 Newton's method for a bivariate problem

Consider the following unconstrained optimization problem

$$\text{minimize } (x_1 - 2)^4 + (x_1 - 2x_2)^2 \quad (2)$$

Let  $f(x) = (x_1 - 2)^4 + (x_1 - 2x_2)^2$  denote the objective function. Solve the problem (2) using Newton's method. Newton's method starts with an initial starting point  $x_0 \in \mathbb{R}^2$  and updates the solution as follows:

$$x_{n+1} = x_n - \nabla^2 f(x_n)^{-1} \nabla f(x_n)$$

Try different starting points and observe if the method converges to a stationary point or diverges without producing a solution. Plot the contour of  $f(x)$  in  $(x_1, x_2)$  plane and show the path taken by Newton's method.

### Exercise 1.5 Pooling Problem

Consider the following simplified example of a pooling problem presented in Figure 1. This problem arises, for example, in gas transportation and oil refinery blending problems.

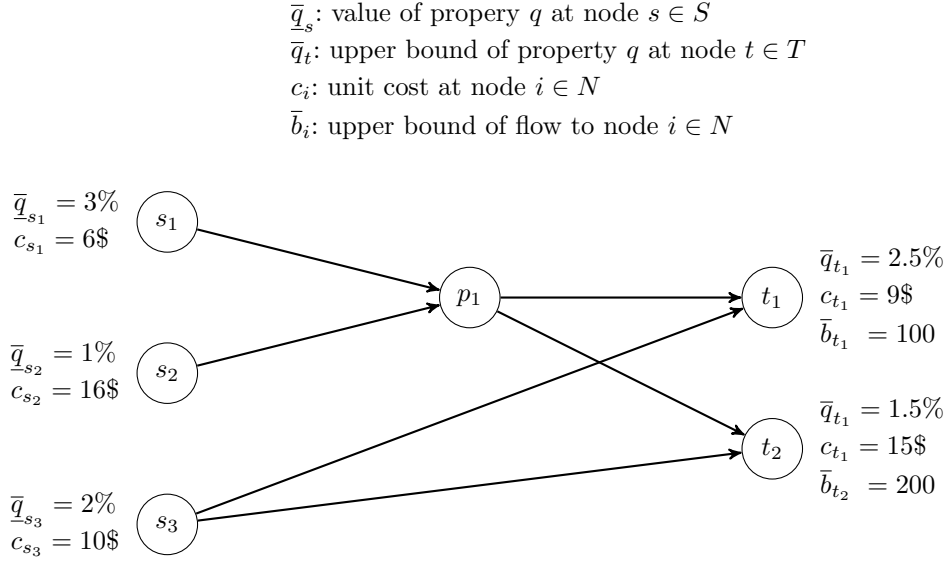


Figure 1: Pooling problem network.

The problem considered here is defined on a directed graph  $G = (N, A)$  as follows. We have a set of source nodes  $S = \{s_1, s_2, s_3\}$ , a set of intermediate pool nodes  $P = \{p_1\}$ , and a set of target nodes  $T = \{t_1, t_2\}$ . The node set is thus

$$N = S \cup P \cup T$$

Each source  $s \in S$  has a unit cost  $c_s$  to transport oil and each target  $t \in T$  has a unit cost  $c_t$  which represents profit of receiving oil. Each node  $i \in N$  has a property value  $q_i$  which corresponds to oil sulfur content in this example. The property values at sources  $s \in S$  are constants  $q_s = \bar{q}_s$  and the values at targets  $t \in T$  have upper bounds  $q_t \leq \bar{q}_t$ . The property values  $q_p$  at pool nodes  $p \in P$  and  $q_t$  at target nodes  $t \in T$  are unknown.

The arcs  $A$  represent pipes transporting oil between the nodes. From each source  $s \in S$ , crude oil with a property value  $q_s$  flows to target nodes  $t \in T$  either directly or via pool nodes  $p \in P$ . When two or more oil streams with different properties flow to a pool node  $p \in P$  or a target node  $t \in T$ , the properties  $q_p$  or  $q_t$  of the oil at that node change due to blending.

The objective is to maximize profit by sending oil from sources  $s \in S$  to targets  $t \in T$ . We can use the following variables to formulate the problem:

$$\begin{aligned}
 x_{ij} &\geq 0 && \text{amount of oil flowing through each arc } (i, j) \in A \\
 q_i &\geq 0 && \text{property (sulfur content) at each node } i \in N
 \end{aligned}$$

Let us further define

$$N_i^- = \{j \in N : (j, i) \in A\} \quad \text{and} \quad N_i^+ = \{j \in N : (i, j) \in A\}$$

The problem can be formulated as follows.

$$\text{maximize}_{x,q} \sum_{t \in T} c_t \sum_{j \in N_t^-} x_{jt} - \sum_{s \in S} c_s \sum_{j \in N_s^+} x_{sj} \quad (3)$$

$$\text{subject to} \quad \sum_{j \in N_p^-} x_{jp} = \sum_{j \in N_p^+} x_{pj}, \quad \forall p \in P \quad (4)$$

$$\sum_{j \in N_t^-} x_{jt} \leq \bar{b}_t, \quad \forall t \in T \quad (5)$$

$$\sum_{j \in N_p^-} q_j x_{jp} = q_p \sum_{j \in N_p^+} x_{pj}, \quad \forall p \in P \quad (6)$$

$$\sum_{j \in N_t^-} q_j x_{jt} = q_t \sum_{j \in N_t^+} x_{jt}, \quad \forall t \in T \quad (7)$$

$$q_t \leq \bar{q}_t, \quad \forall t \in T \quad (8)$$

$$q_s = \bar{q}_s, \quad \forall s \in S \quad (9)$$

$$q_i \geq 0, \quad \forall i \in P \cup T \quad (10)$$

$$x_{ij} \geq 0, \quad \forall (i, j) \in A \quad (11)$$

The objective (3) maximizes profit - cost. (4) maintains flow balance, and (5) defines upper bound of flow to target nodes. (6) and (7) determine the property values at pool nodes and target nodes, respectively. (8) imposes upper bounds for property values at target nodes and (9) sets the initial property values at source nodes.

The problem is non-convex due to the constraints (6) and (7) which are called *bilinear*. Typically, there are more pools and more than one property  $q_i$  for each node  $i$ . This can be modeled by introducing a set  $K$  of different properties so that  $q_i^k$  denotes the value of property  $k$  at node  $i$ .

One strategy to obtain a solution is to first fix the values of unknown property values  $q_i, i \in P \cup T$  and solve the remaining Linear Programming problem. You can find different solutions by trying different value combinations. Another option is to set the smallest lower bounds on  $q_i, i \in P \cup T$  and try to solve the problem with a non-linear programming solver.

Model and solve the problem (3) – (11) with Julia using JuMP using the data shown in Figure 1.