

Simulation

Assignment 3.2 – Importance sampling

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```
In [55]: import numpy as np
```

Classic Monte-Carlo

```
In [122]: def path(c):
           p = 1.0 / (1 + 5/4.0)
           #the length of the que
           state = 1
           while state > 0 and state < c + 1:
               if np.random.random() < p:
                   #if the que length increases we add a person
                   state += 1
               else:
                   #else we subtract a person
                   state -= 1
           #if we hit 0 we return zero, else we return 1
           if state == 0:
               return 0
           else:
               return 1
```

```
In [121]: #different target values
c3 = 3
c5 = 5
c7 = 7
#counters for different target values
counter3 = 0
counter5 = 0
counter7 = 0
iterations = 100000
for i in range(0, iterations):
    #for each iteration calculate one instace of all the different targets
    counter3 += path(c3)
    counter5 += path(c5)
    counter7 += path(c7)

#print the estimated probabilities
print("Probability of queue hitting 3: " + str(counter3 / iterations))
print("Probability of queue hitting 5: " + str(counter5 / iterations))
print("Probability of queue hitting 7: " + str(counter7 / iterations))

Probability of queue hitting 3: 0.17448
Probability of queue hitting 5: 0.08813
Probability of queue hitting 7: 0.05078
```

The algorithm seems to be OK, since the $c = 3$ case gives the given result

Importance sampling

```
In [74]: def IS(c):
           p_star = (5.0 / 4.0) / (1 + 5/4.0)
           p = 1.0 / (1 + 5/4.0)
           state = 1
           arrivals = 0
           completions = 0
           #first simulate the queue and save the arrivals and completions
           while state > 0 and state < c + 1:
               if np.random.random() < p_star:
                   state += 1
                   arrivals += 1
               else:
                   state -= 1
                   completions += 1

           #returns zero or the term inside the summation in the importance sampling formula
           if state == 0:
               return 0
           else:
               return ((p / p_star)**arrivals) * (((1 - p) / (1 - p_star))**completions)
```

```
In [118]: #do the same thing for importance sampling as we did before for Monte-Carlo
c3 = 3
c5 = 5
c7 = 7
counter3 = 0
counter5 = 0
counter7 = 0
iterations = 100000
for i in range(0, iterations):
    counter3 += IS(c3)
    counter5 += IS(c5)
    counter7 += IS(c7)

print("Probability of queue hitting 3: " + str(counter3 / iterations))
print("Probability of queue hitting 5: " + str(counter5 / iterations))
print("Probability of queue hitting 7: " + str(counter7 / iterations))

Probability of queue hitting 3: 0.17389056000005912
Probability of queue hitting 5: 0.08823111680004211
Probability of queue hitting 7: 0.05041343692799139
```

This one also seems to be OK.

Comparing variances

Let's simulate 100 different paths to give us an estimate on the γ and do that 100 times and calculate the variance in both regular Monte-Carlo and importance sampling.

```
In [76]: #functions for estimating the probability of hitting certain queue length for both functions
def estimateMC(c, iterations):
    runs = []
    for i in range(0, iterations):
        runs.append(path(c))
    return np.mean(runs)

def estimateIS(c, iterations):
    runs = []
    for i in range(0, iterations):
        runs.append(IS(c))
    return np.mean(runs)
```

```
In [125]: iterations = 100
estimation_iterations = 100
#make numpy arrays to store the results
moca = np.empty((iterations, 3), dtype = float)
imsa = np.empty((iterations, 3), dtype = float)

#calculate estimates for different queue lengths and save the results
for i in range(0, iterations):
    for j in range(0,3):
        moca[i, j] = estimateMC(3 + 2*j, estimation_iterations)
        imsa[i, j] = estimateIS(3 + 2*j, estimation_iterations)

#calculate the means and standard deviations of estimates from both methods
mc_mean = np.mean(moca, 0)
mc_std = np.std(moca, 0)
is_mean = np.mean(imsa, 0)
is_std = np.std(imsa, 0)
```

```
In [126]: print("{:13}{:9}{:9}{:9}".format("", "c = 3", "c = 5", "c = 7"))
print("{:10}{:9.4f}{:9.4f}{:9.4f}".format("Mean MC:", mc_mean[0], mc_mean[1], mc_mean[2]))
print("{:10}{:9.4f}{:9.4f}{:9.4f}".format("Mean IS:", is_mean[0], is_mean[1], is_mean[2]))
print("{:10}{:9.4f}{:9.4f}{:9.4f}".format("Std MC:", mc_std[0], mc_std[1], mc_std[2]))
print("{:10}{:9.4f}{:9.4f}{:9.4f}".format("Std IS:", is_std[0], is_std[1], is_std[2]))
```

	c = 3	c = 5	c = 7
Mean MC:	0.1706	0.0821	0.0479
Mean IS:	0.1709	0.0899	0.0500
Std MC:	0.0408	0.0281	0.0209
Std IS:	0.0234	0.0166	0.0089

We can see that importance sampling gives us notably smaller standard deviations in all of the cases but the effect is especially clear in the case of $c = 7$ where the occurrence of the event is much lower. There importance sampling has a standard deviation that is over 2 times smaller than the basic Monte-Carlo equivalent.