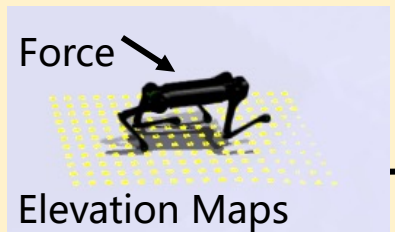


## Proprioception



## External



## Hybrid Internal Optimization

Target  
Encoder

$\mathbf{l}_t^T$

Contrastive  
Learning

Hybrid Internal Model

## Policy

Source  
Encoder

$\mathbf{l}_t^S$

Hybrid Internal  
Embedding

Policy  
Network

$\hat{\mathbf{v}}_t$

$\mathbf{o}_t^a$

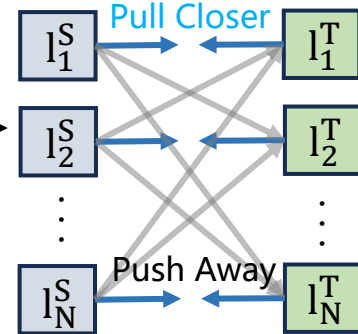
Critic  
Network

$V_t$

Policy  
Gradient

$\mathbf{a}_t$

## Proximal Policy Optimization



## Comparisons

