

# MS Advanced Camera Controller

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'MS Advanced Camera Controller' is a camera controller, which has several camera options to suit the most diverse situations. The cameras included in the code are:

- **LookAt The Player:** A camera that stands still, but always rotates toward the object containing the script. Automatic and manual gears system for the vehicle.
- **FirstPerson:** A first-person camera that allows 360-degree rotation without moving the player. Ideal for FPS.
- **FollowPlayer:** A camera that follows the object that contains the script smoothly, and avoids obstacles, getting in front of them. This type of camera also makes a smooth rotation towards the object containing the code.
- **Orbital:** A simple orbital camera with configurable zoom, distance and motion speed options, and also contains a function that avoids obstacles and detects collisions.
- **Stop:** A totally dead camera with no action at all.
- **StraightStop:** A camera that stands still in its position, but keeps the horizon always straight.
- **OrbitalThatFollow:** A junction of the 'FollowPlayer' and 'Orbital' cameras.
- **ETS StyleCamera:** A 'FirstPerson' camera, with an additional sliding option when the player looks to the left, allowing the camera to move slightly, and come back in case the player looks to the right.

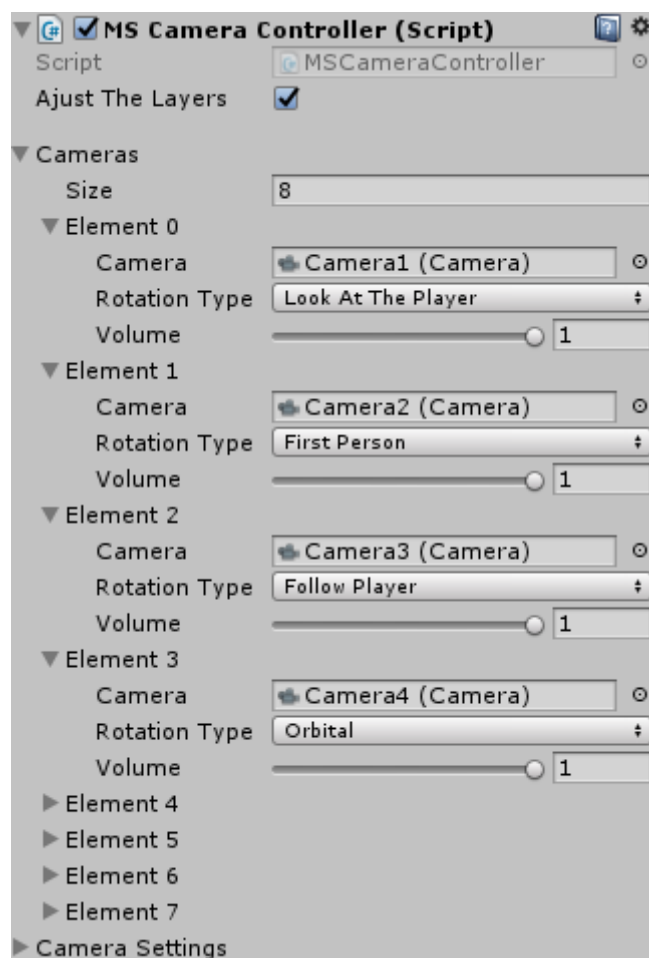
'MS Advanced Camera Controller' also includes a demo scene, with all kinds of cameras listed above, to demonstrate the operation.

## How to use:

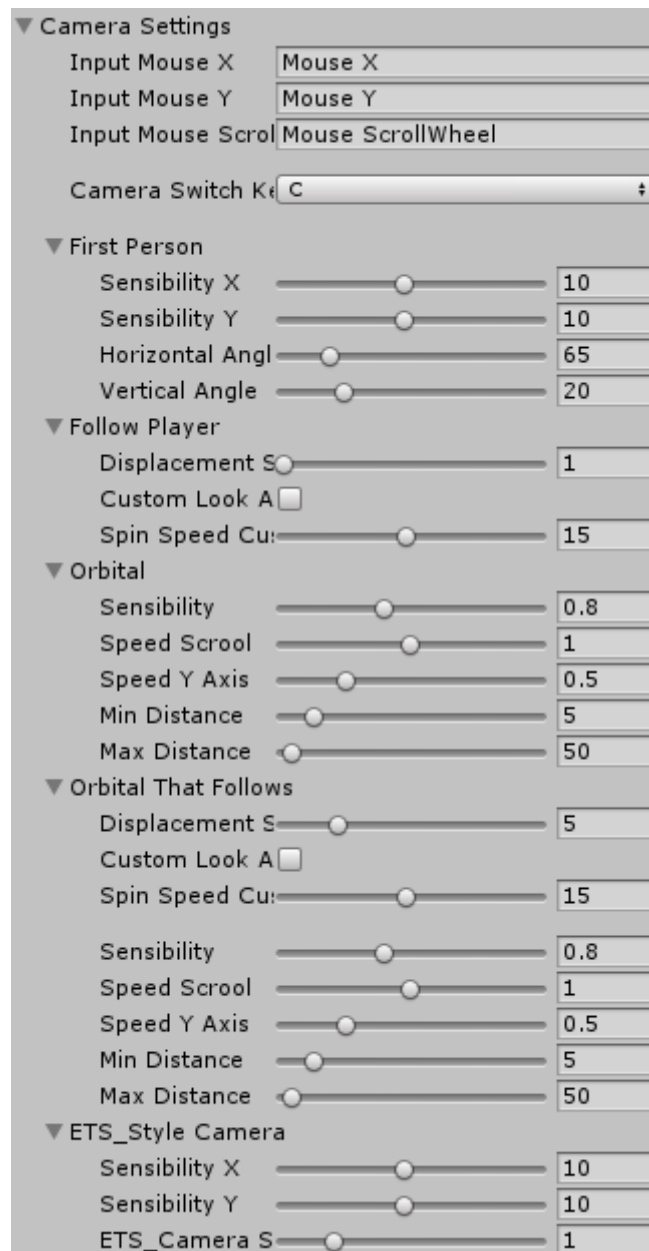
To use the asset, simply associate the 'MSCameraController' script with your player's main object, associate the cameras with the variables and configure everything.

In the 'Cameras' array, you must define the number of cameras you have and press the 'Enter' key to initialize the array of cameras.

Once you've done that, simply associate each camera with an index and set the type of rotation or movement that each camera should have, as the image below illustrates.



You can configure each type of Camera as well, by setting the limits of movement, speeds, rotations, among other things, as the image below demonstrates.



The entire system has 'Tooltips' in the variables, making the system easy to implement, and helping to avoid errors. These Tooltips provide warnings that help the user to implement the system. To see the warnings, just rest your mouse over some variable, and the warning will appear.