Lucas Doyle

Senior Machine Learning Engineer | San Francisco, CA



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Sounds cliché, but making code do something in the real world is what excites me. My superpowers are zero-to-one problem-solving, prototypes and last second demos that seem impossible. I've shipped at-scale across firmware, mobile, backend, frontend and ML infrastructure.

Experience

Samsara - Senior Machine Learning Engineer II

San Francisco, CA | 2018 - Present

Python, Golang, Typescript (React, Redux, React Native), Android (Java, Kotlin)

ML Infrastructure

Led edge infrastructure / end-to-end implementation and deployment of video pipelines for Samsara's video-based safety products. These run on 2M+ of Samsara's Al dashcams, improving driver safety, engagement, and trust at scale.

- Developed and deployed pipelines (e.g. tailgating, rolling stop sign detection, lane departure), including device farm QA automation, shadow testing, and firmware infrastructure / feature development.
- Built internal tools for debugging, evaluation, and telemetry replay; enabled scalable model iteration and observability across firmware and cloud.
- Spearheaded offline evaluation pipelines for quantized models and integrated support for multimodal data (e.g. video, IMU, GPS, hardware emulation).
- Mentored interns and collaborated cross-functionally with product, firmware, science and data teams to streamline ML deployment and validation processes.

Mobile

- Led performance and infrastructure efforts for mobile applications with 500k+ DAU, driving major improvements in responsiveness, reliability, and developer velocity.
- Helped bootstrap new apps, products and the company's first native Android systems and mobile device management (MDM) stack.

Airware - Senior Software Engineer

San Francisco, CA | 2014 - 2018

Javascript (React, Redux, Leaflet, React Native), Python, Swift, PHP, Golang

Developed core technologies for a drone platform to capture, upload and process largescale imagery into survey-grade data for insurance and mining industries.

- Created a desktop app for flashing and configuring fixed-wing and multirotor drone avionics hardware.
- Built cloud workflows for large-scale survey processing and analysis with a GIS/geospatial-focused UI.
- Developed a mobile app for drone operators using React Native and iOS, enabling geofence editing and on-device photogrammetry processing.
- Led feature development, large-scale refactors, product mergers / acquisitions; contributed to hiring, planning, and mentoring engineers.

MUJIN Inc. (株式会社MUJIN) - Software Engineer

Tokyo, Japan | 2012 - 2014

Python (django, OpenRAVE), Javascript (Backbone/Marionette, WebGL)

Fourth employee at a Japanese industrial robotics startup:

- Designed and implemented the web interface for the MUJIN Controller, a robotic arm workcell planning system used by Canon, Honda, and other system integrators.
- Developed customer-facing UIs featuring a real-time WebSocket-based WebGL viewer for a bin-picking system.
- Collaborated with an international team while living in Japan for two years.

Education

Rensselaer Polytechnic Institute

B.S. Computer and Systems Engineering | 2008 - 2012

Boeing Robotic Wingbox

Simulated intra-wing robot for aircraft inspection. (project link)

DaBuzz Market Sentiment Analyzer

Web crawler for financial news sentiment analysis. (project link)

Patents

Lane departure monitoring (US12165393B1)

Context based action menu (US12150007B1)

Unmanned aerial vehicle privacy controls (US20220392353A1)