Führ:

$$(w-y) \cdot kg = y$$
 $y = kgw - kgy 1:y$
 $1 = kg \cdot \frac{w}{y} - kg$ $1 + kg$

$$\frac{1+g\alpha}{g} = \frac{g}{y} - \frac{g}{d}$$

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$$\frac{1+g\alpha}{d} = \frac{g}{1+g\alpha}$$

a) P-regler, PD-regler, PT&

grenzstabil, leine osz anteil da kein j.

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$$\frac{y}{w} = \frac{kg}{1+kg} = \frac{1}{s \cdot (s+1)} = \frac{1}{s \cdot (s+1)}$$

$$\frac{1}{s \cdot (s+1)} = \frac{1}{s \cdot (s+1)}$$

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$$\frac{y}{w} = \frac{k_{g}}{1 + k_{g}} = \frac{(k + M_{s})}{s \cdot (s + 1)} = \frac{(k + M_{s})}{s \cdot (s + 1)}$$

$$\frac{1}{1 + \frac{k + M_{s}}{s \cdot (s + 1)}} = \frac{(k + M_{s})}{s \cdot (s + 1)}$$

$$\frac{1}{1 + \frac{k_{g}}{s \cdot (s + 1)}} = \frac{(k + M_{s})}{s \cdot (s + 1)}$$

$$\frac{1}{1} = \frac{1}{1} = \frac{1}$$

$$\frac{3}{d} = \frac{9}{1+gh} = \frac{5(s+1)}{1+gh} = \frac{5(s+1)}{1+gh}$$

$$= \frac{1}{1+gh} = \frac{1}{1+$$

$$\frac{y}{d} = \frac{(1)}{(5(5+1))} = \frac{1}{(5(5+1))}$$

$$\frac{y}{d} = \frac{(5(5+1))}{(5(5+1))} = \frac{1}{(5(5+1))}$$

1) c)
$$E_{w}(s) = \frac{1 - G_{w}(s)}{S}$$
 $\lim_{t \to \infty} E_{w}(t) = \lim_{S \to \infty} s \cdot E_{w}(s)$
 $\lim_{t \to \infty} \frac{1 - K}{S^{2} + s + K} = 1 - \frac{K}{K} = 1 - \frac{1}{K} = 1 - \frac{1}{K}$
 $\lim_{S \to \infty} 1 - \frac{K}{S^{2} + s + K} = 1 - \frac{K}{K} = 1 - \frac{1}{K} = \frac{1}{K} = 1 - \frac{1}{K} = \frac$