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Факультет: «Информационные технологии и прикладная математика»

Кафедра: 806 «Вычислительная математика и программирование»

Дисциплина: «Объектно-ориентированное программирование»

Лабораторная работа № 7

Тема: Проектирование структуры классов.

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1. Постановка задачи

Спроектировать простейший графический векторный редактор, который поддерживает:

- Создание нового документа
- Импорт документа из файла
- Импорт документа в файл
- Создание графического примитива
- Удаление графического примитива
- Отображение документа на экране
- Реализация операции undo, отменяющей последнее действие

2. Репозиторий github

https://github.com/StormStudioAndroid2/oop_exercise_07

3. Описание программы

Реализован класс Figure с общим функционалом фигур, у него наследники – Circle, Trapeze, Rectangle, Rhombus, Polyline, Polyfigure. У каждого есть свой FigureBuilder. В классе Factory в зависимости от того, пустой builder или нет, будет производиться создание фигуры. В файле Loader.h хранится метод загрузки из файла. В файле Helper.h вспомогательные методы для определения, принадлежит точка внутренности фигуры или нет.

4. Листинг программы

main.cpp

```
#include<iostream>

#include <array>
#include <fstream>
#include <iostream>
#include <vector>
#include "model/Action.h"
#include "sdl.h"
#include "imgui.h"
#include "model/Rectangle.h"
#include "model/Circle.h"
#include "model/Loader.h"
#include "model/Polyfigure.h"
#include <stack>

#include "Factory.h"
void setBrush(Brush& brush) {

    ImGui::InputInt("Green", &brush.green);
```

```

    ImGui::InputInt("Blue", &brush.blue);

    ImGui::InputInt("Red", &brush.red);
    if (brush.green > 255) {
        brush.green = 255;
    }
    if (brush.blue > 255) {
        brush.blue = 255;
    }
    if (brush.red > 255) {
        brush.red = 255;
    }
}

int main() {
    Brush brush;
    Factory factory;
    std::stack<std::unique_ptr<Action>> history;

    sdl::renderer renderer("Editor");
    bool quit = false;
    std::unique_ptr<Action> action;
    std::vector<std::unique_ptr<Figure>> figures;
    std::unique_ptr<Builder> active_builder = nullptr;
    const int32_t file_name_length = 128;
    char file_name[file_name_length] = "";
    int32_t remove_id = 0;
    while(!quit){
        renderer.set_color(0,100,0);
        renderer.draw_line(20-1, 20, 20, 20+1);
        renderer.set_color(0, 0, 0);
        renderer.clear();
        sdl::event event;

        while(sdl::event::poll(event)){
            sdl::quit_event quit_event;
            sdl::mouse_button_event mouse_button_event;
            if(event.extract(quit_event)){
                quit = true;
                break;
            } else if(event.extract(mouse_button_event)) {
                if (factory.isBuilding()) {
                    std::unique_ptr<Figure> figure = factory.buildingFigure(mouse_button_event);
                    if (figure) {
                        figures.emplace_back(std::move(figure));
                        action = std::make_unique<CreateAction>();
                        history.push(std::move(action));
                        active_builder = nullptr;
                    }
                }
            } else {
                if (mouse_button_event.button() ==
sdl::mouse_button_event::right && mouse_button_event.type() ==
sdl::mouse_button_event::down) {
                    for (int i = 0; i < figures.size(); ++i) {
                        if (figures[i]->isInside(vertex{
mouse_button_event.x(), mouse_button_event.y() }))) {
                            figures.erase(figures.begin() + i);
                            break;
                        }
                    }
                }
            }
        }
    }
}

```

```

        }
    }
}

for(const std::unique_ptr<Figure>& figure: figures){
    figure->render(renderer);
}

ImGui::Begin("Menu");
if(ImGui::Button("New canvas")){
    figures.clear();
}
ImGui::InputText("File name", file_name, file_name_length - 1);
if(ImGui::Button("Save")){
    std::ofstream os(file_name);
    if(os){
        for(const std::unique_ptr<Figure>& figure: figures){
            figure->save(os);
        }
    }
}
ImGui::SameLine();
if(ImGui::Button("Load")){
    std::ifstream is(file_name);
    if(is){
        loader loader;
        figures = loader.load(is);
    }
}
if(ImGui::Button("Rectangle")){
    factory.startBuildRectangle(brush);
}
ImGui::SameLine();

if (ImGui::Button("Trapeze")) {
    factory.startBuildTrapeze(brush);
}
ImGui::SameLine();

if (ImGui::Button("Rhombus")) {
    factory.startBuildRhombus(brush);
}
ImGui::SameLine();

if (ImGui::Button("Polyline")) {
    factory.startPolyBuildLine(brush);
}
ImGui::SameLine();

if (ImGui::Button("Polyfigure")) {
    factory.startPolyBuildFigure(brush);
}
ImGui::SameLine();

if (ImGui::Button("Circle")) {
    factory.startBuildCircle(brush);
}

if (ImGui::Button("undo")) {
    if (!history.empty()) {
        action = std::move(history.top());
    }
}

```

```

        history.pop();
        action->undoAction(figures);
        action = nullptr;
    }
}
setBrush(brush);
ImGui::InputInt("Remove_Id", &remove_id);

if(ImGui::Button("Remove")) {
    if (figures.size() > remove_id) {
        std::unique_ptr<Figure> figure = std::move(figures[remove_id]);
        action = std::make_unique<DeleteAction>(std::move(figure), remove_id);
        history.push(std::move(action));
        figures.erase(figures.begin()+remove_id);
    }
}
// Undo
ImGui::End();

renderer.present();
}

}
Figure.h

```

```

#pragma once

#include "Builder.h"
struct vertex {
    int32_t x, y;
};

struct Brush {
    int green;
    int red;
    int blue;
    Brush() {
        red = 0;
        green = 0;
        blue = 0;
    }
};

struct Figure {
public:
    virtual void render(const sdl::renderer& renderer) = 0;
    virtual void addBrush(Brush& brush) = 0;
    virtual bool isInside(vertex& v) = 0;
    virtual void save(std::ostream& os) const = 0;
    virtual ~Figure() = default;
};

struct Builder {
public:
    virtual std::unique_ptr<Figure> add_vertex(const vertex& v) = 0;
    virtual ~Builder() = default;
};

struct Action

```

```

{
public:
    virtual void undoAction(std::vector<std::unique_ptr<Figure>>& figures) = 0;
    virtual ~Action() = default;

};

struct CreateAction : Action
{
public:
    void undoAction(std::vector<std::unique_ptr<Figure>>& figures) override {
        figures.erase(figures.end() - 1);
    }
    CreateAction() {}
    ~CreateAction() {}
};

struct DeleteAction : Action
{
public:
    void undoAction(std::vector<std::unique_ptr<Figure>>& figures) override {
        figures.insert(figures.begin() + index, std::move(figure));
    }
    DeleteAction(std::unique_ptr<Figure> figure, size_t index) {
        this->figure = (std::move(figure));
        this->index = index;
    }
    ~DeleteAction() {}
private:
    std::unique_ptr<Figure> figure;
    size_t index;
};

Loader.h
#ifndef D_LOADER_H
#define D_LOADER_H

#include<vector>
#include<memory>

#include "Figure.h"
#include "Rhombus.h"
#include "Rectangle.h"
#include "Trapeze.h"
#include "Polyline.h"
#include "Polyfigure.h"

struct loader {
    std::vector<std::unique_ptr<Figure>> load(std::ifstream& is) {
        std::string figure_name;
        std::vector<std::unique_ptr<Figure>> figures;
        while (is >> figure_name) {
            vertex v;

            if (figure_name == std::string("rhombus")) {
                std::array<vertex, 4> vertices;
                for (int32_t i = 0; i < 4; ++i) {
                    is >> v.x >> v.y;
                    vertices[i] = v;
                }
                Brush load_clr {};
                is >> load_clr.red >> load_clr.green >> load_clr.blue;
                figures.emplace_back(std::make_unique<Rhombus>(vertices));
                (*figures[figures.size() - 1]).addBrush(load_clr);
            }
        }
    }
};

```

```

else if (figure_name == std::string("rectangle")) {
    std::array<vertex, 4> vertices;
    for (int32_t i = 0; i < 4; ++i) {
        is >> v.x >> v.y;
        vertices[i] = v;
    }
    Brush load_clr {};
    is >> load_clr.red >> load_clr.green >> load_clr.blue;
    fig-
ures.emplace_back(std::make_unique<Rectangle>(vertices));
    (*figures[figures.size() - 1]).addBrush(load_clr);
}
else if (figure_name == std::string("trapeze")) {
    std::array<vertex, 4> vertices;
    for (int32_t i = 0; i < 4; ++i) {
        is >> v.x >> v.y;
        vertices[i] = v;
    }
    Brush load_clr {};
    is >> load_clr.red >> load_clr.green >> load_clr.blue;
    figures.emplace_back(std::make_unique<Trapeze>(vertices));
    (*figures[figures.size() - 1]).addBrush(load_clr);
}
else if (figure_name == std::string("circle")) {
    std::array<vertex, 2> vertices;
    for (int i = 0; i < 2; ++i) {
        is >> v.x >> v.y;
        vertices[i] = v;
    }
    Brush load_clr {};
    is >> load_clr.red >> load_clr.green >> load_clr.blue;
    figures.emplace_back(std::make_unique<Circle>(vertices));
    (*figures[figures.size() - 1]).addBrush(load_clr);
}
else if (figure_name == std::string("polyline")) {
    std::vector<vertex> vertices;
    int count_v;
    is >> count_v;
    for (int i = 0; i < count_v; ++i) {
        is >> v.x >> v.y;
        vertices.push_back(v);
    }
    Brush load_clr {};
    is >> load_clr.red >> load_clr.green >> load_clr.blue;
    fig-
ures.emplace_back(std::make_unique<Polyline>(vertices));
    (*figures[figures.size() - 1]).addBrush(load_clr);
}
else if (figure_name == std::string("polyfigure")) {
    std::vector<vertex> vertices;
    int count_v;
    is >> count_v;
    for (int i = 0; i < count_v; ++i) {
        is >> v.x >> v.y;
        vertices.push_back(v);
    }
    Brush load_clr {};
    is >> load_clr.red >> load_clr.green >> load_clr.blue;
    fig-
ures.emplace_back(std::make_unique<Polyfigure>(vertices));
    (*figures[figures.size() - 1]).addBrush(load_clr);
}

```

```

        }
        return figures;
    }
    ~loader() = default;
};

#endif //D_LOADER_H

Trapeze.h
#pragma once
#include "Figure.h"

#include "Helper.h"

struct Trapeze : Figure {
public:

    Trapeze(const std::array<vertex, 4>& vertices) : vertices_(vertices) {}

    void render(const sdl::renderer& renderer) override {
        renderer.set_color(brush.red, brush.green, brush.blue);
        for (int32_t i = 0; i < 4; ++i) {
            renderer.draw_line(vertices_[i].x, vertices_[i].y,
                               vertices_[(i + 1) % 4].x, vertices_[(i + 1) % 4].y);
        }
        renderer.set_color(0, 0, 0);
    }
    void addBrush(Brush& brush) override {
        this->brush.blue = brush.blue;
        this->brush.red = brush.red;
        this->brush.green = brush.green;
    }
    void save(std::ostream& os) const override {
        os << "trapeze\n";
        for (int32_t i = 0; i < 4; ++i) {
            os << vertices_[i].x << ' ' << vertices_[i].y << '\n';
        }
        os << brush.red << ' ' << brush.green << ' ' << brush.blue << '\n';
    }
    bool isInside(vertex& v) override {
        return isInside1(vertices_, v);
    }
    ~Trapeze() { }

private:
    std::array<vertex, 4> vertices_;
    Brush brush;
};

struct TrapezeBuilder : Builder {
public:
    std::unique_ptr<Figure> add_vertex(const vertex& v) {
        vertices_[n_] = v;
        n_ += 1;
        if (n_ != 4) {
            return nullptr;
        }
    }
};

```



```

        std::unique_ptr<Figure> figure = std::make_unique<Trapeze>(vertices_);
        figure->addBrush(brush);
        return std::move(figure);
    }
    TrapezoidBuilder(Brush& brush) {
        this->brush.blue = brush.blue;
        this->brush.red = brush.red;
        this->brush.green = brush.green;
    }
private:
    int32_t n_ = 0;
    std::array<vertex, 4> vertices_;
    Brush brush;
};

Circle.h
#pragma once
#include "Figure.h"
#include "math.h"
#include "sdl.h"

struct Circle : Figure {
public:
    Circle(const std::array<vertex, 2>& vertices) : vertices_(vertices) {}

    void render(const sdl::renderer& renderer) override {
        renderer.set_color(brush.red, brush.green, brush.blue);
        ;
        DrawCircle(renderer, vertices_[0].x, vertices_[0].y, this->
        >getLength(vertices_[0], vertices_[1]));
        renderer.set_color(0, 0, 0);
    }
    void addBrush(Brush& brush) override {
        this->brush.blue = brush.blue;
        this->brush.red = brush.red;
        this->brush.green = brush.green;
    }
    void save(std::ostream& os) const override {
        os << "circle\n";
        for (int32_t i = 0; i < 2; ++i) {
            os << vertices_[i].x << ' ' << vertices_[i].y << '\n';
        }
        os << brush.red << ' ' << brush.green << ' ' << brush.blue << '\n';
    }

    bool isInside(vertex& v) override {
        int32_t radius = (vertices_[0].x - vertices_[1].x)*(vertices_[0].x -
        vertices_[1].x) + (vertices_[0].y - vertices_[1].y)*(vertices_[0].y - vertices_[1].y);
        return ((vertices_[0].x - v.x)*(vertices_[0].x - v.x) + (vertices_[0].y
        - v.y)*(vertices_[0].y - v.y) < radius);
    }
    ~Circle() { }

private:
    void DrawCircle(const sdl::renderer&renderer, int32_t centreX, int32_t centreY,
    int32_t radius)
    {
        const int32_t diameter = (radius * 2);

        int32_t x = (radius - 1);
        int32_t y = 0;
        int32_t tx = 1;

```

```

        int32_t ty = 1;
        int32_t error = (tx - diameter);

        while (x >= y)
        {
            // Each of the following renders an octant of the circle
            renderer.draw_line(centreX + x, centreY - y, centreX + x + 1,
centreY - y + 1);
            renderer.draw_line(centreX + x, centreY + y, centreX + x + 1,
centreY + y + 1);
            renderer.draw_line(centreX - x, centreY - y, centreX - x + 1,
centreY - y + 1);
            renderer.draw_line(centreX - x, centreY + y, centreX - x + 1,
centreY + y + 1);
            renderer.draw_line(centreX + y, centreY - x, centreX + y + 1,
centreY - x + 1);
            renderer.draw_line(centreX + y, centreY + x, centreX + y + 1,
centreY + x + 1);
            renderer.draw_line(centreX - y, centreY - x, centreX - y + 1,
centreY - x + 1);
            renderer.draw_line(centreX - y, centreY + x, centreX - y + 1,
centreY + x + 1);

            if (error <= 0)
            {
                ++y;
                error += ty;
                ty += 2;
            }

            if (error > 0)
            {
                --x;
                tx += 2;
                error += (tx - diameter);
            }
        }
    }
    int32_t getLength(const vertex& v1, const vertex& v2) {
        return (int32_t)sqrt((v1.x - v2.x)*(v1.x - v2.x) + (v1.y - v2.y)*(v1.y -
v2.y));
    }
    std::array<vertex, 2> vertices_;
    Brush brush;

};

```

```

struct CircleBuilder : Builder {
public:
    std::unique_ptr<Figure> add_vertex(const vertex& v) {
        vertices_[n_] = v;
        n_ += 1;
        if (n_ != 2) {
            return nullptr;
        }
        std::unique_ptr<Figure> figure = std::make_unique<Circle>(vertices_);
        figure->addBrush(brush);
        return std::move(figure);
    }
    CircleBuilder(Brush& brush) {

```

```

        this->brush.blue = brush.blue;
        this->brush.red = brush.red;
        this->brush.green = brush.green;
    }
private:
    int32_t n_ = 0;
    std::array<vertex, 2> vertices_;
    Brush brush;
};
Factory.h
#pragma once
#include "sdl.h"
#include "model/Rectangle.h"
#include "model/Rhombus.h"
#include "model/Trapeze.h"
#include "model/Circle.h"
#include "model/Polyline.h"
#include "model/Polyfigure.h"

struct Factory {
private:
    std::unique_ptr<Builder> builder;
    std::unique_ptr<Builder> polyBuilder;

public:
    std::unique_ptr<Figure> buildingFigure(sdl::mouse_button_event
mouse_button_event) {
        if (builder && mouse_button_event.button() ==
sdl::mouse_button_event::left && mouse_button_event.type() ==
sdl::mouse_button_event::down) {
            std::unique_ptr<Figure> figure = builder-
>add_vertex(vertex{ mouse_button_event.x(), mouse_button_event.y() });
            if (figure) {
                this->builder = nullptr;
                return std::move(figure);
            }
        }
        if (polyBuilder && mouse_button_event.button() ==
sdl::mouse_button_event::left && mouse_button_event.type() ==
sdl::mouse_button_event::down) {
            std::unique_ptr<Figure> figure = polyBuilder-
>add_vertex(vertex{ mouse_button_event.x(), mouse_button_event.y() });
            figure = nullptr;
            return nullptr;
        }
        if (polyBuilder && mouse_button_event.button() ==
sdl::mouse_button_event::right && mouse_button_event.type() ==
sdl::mouse_button_event::down) {
            std::unique_ptr<Figure> figure = polyBuilder-
>add_vertex(vertex{ mouse_button_event.x(), mouse_button_event.y() });
            polyBuilder = nullptr;
            return std::move(figure);
        }
        return nullptr;
    }
    void startBuildFigure() {}
    void startBuildTrapeze(Brush& brush) {
        builder = std::make_unique<RectangleBuilder>(brush);
    }
}

```

```

        void startBuildRectangle(Brush& brush) {
            builder = std::make_unique<TrapezeBuilder>(brush);

        }
        void startBuildRhombus(Brush& brush) {
            builder = std::make_unique<RhombusBuilder>(brush);

        }
        void startBuildCircle(Brush& brush) {
            builder = std::make_unique<CircleBuilder>(brush);

        }
        void startPolyBuildLine(Brush& brush) {
            polyBuilder = std::make_unique<PolylineBuilder>(brush);

        }
        void startPolyBuildFigure(Brush& brush) {
            polyBuilder = std::make_unique<PolyfigureBuilder>(brush);

        }
        bool isBuilding() {
            return builder != nullptr || polyBuilder!=nullptr;
        }
};
Helper.h
#pragma once
#include "Figure.h"
#define INF 1000000;

int32_t max(int32_t a, int32_t b) {
    if (a > b) {
        return a;
    }
    return b;
}
int32_t min(int32_t a, int32_t b) {
    if (a < b) {
        return a;
    }
    return b;
}
bool onSegment(vertex p, vertex q, vertex r)
{
    if (q.x <= max(p.x, r.x) && q.x >= min(p.x, r.x) &&
        q.y <= max(p.y, r.y) && q.y >= min(p.y, r.y))
        return true;
    return false;
}

// To find orientation of ordered triplet (p, q, r).
// The function returns following values
// 0 --> p, q and r are colinear
// 1 --> Clockwise
// 2 --> Counterclockwise
int orientation(vertex p, vertex q, vertex r)
{

```

```

    int val = (q.y - p.y) * (r.x - q.x) -
              (q.x - p.x) * (r.y - q.y);

    if (val == 0) return 0; // colinear
    return (val > 0) ? 1 : 2; // clock or counterclock wise
}

// The function that returns true if line segment 'p1q1'
// and 'p2q2' intersect.
bool doIntersect(vertex p1, vertex q1, vertex p2, vertex q2)
{
    // Find the four orientations needed for general and
    // special cases
    int o1 = orientation(p1, q1, p2);
    int o2 = orientation(p1, q1, q2);
    int o3 = orientation(p2, q2, p1);
    int o4 = orientation(p2, q2, q1);

    // General case
    if (o1 != o2 && o3 != o4)
        return true;

    // Special Cases
    // p1, q1 and p2 are colinear and p2 lies on segment p1q1
    if (o1 == 0 && onSegment(p1, p2, q1)) return true;

    // p1, q1 and p2 are colinear and q2 lies on segment p1q1
    if (o2 == 0 && onSegment(p1, q2, q1)) return true;

    // p2, q2 and p1 are colinear and p1 lies on segment p2q2
    if (o3 == 0 && onSegment(p2, p1, q2)) return true;

    // p2, q2 and q1 are colinear and q1 lies on segment p2q2
    if (o4 == 0 && onSegment(p2, q1, q2)) return true;

    return false; // Doesn't fall in any of the above cases
}

// Returns true if the vertex p lies inside the polygon[] with n vertices
template<std::size_t SIZE>

bool isInside1(std::array<vertex, SIZE> polygon, vertex p)
{
    // There must be at least 3 vertices in polygon[]
    int n = polygon.size();
    if (n < 3) return false;

    // Create a vertex for line segment from p to infinite
    vertex extreme;
    extreme.x = INF;
    extreme.y = p.y;

    // Count intersections of the above line with sides of polygon
    int count = 0, i = 0;
    do {
        int next = (i + 1) % n;

        // Check if the line segment from 'p' to 'extreme' intersects
        // with the line segment from 'polygon[i]' to 'polygon[next]'
        if (doIntersect(polygon[i], polygon[next], p, extreme))
        {
            // If the vertex 'p' is colinear with line segment 'i-next',

```

```

        // then check if it lies on segment. If it lies, return true,
        // otherwise false
        if (orientation(polygon[i], p, polygon[next]) == 0)
            return onSegment(polygon[i], p, polygon[next]);

        count++;
    }
    i = next;
} while (i != 0);

// Return true if count is odd, false otherwise
return count & 1; // Same as (count%2 == 1)
}

bool isInside1(std::vector<vertex>& polygon, vertex p)
{
    // There must be at least 3 vertices in polygon[]
    int n = polygon.size();
    if (n < 3) return false;

    // Create a vertex for line segment from p to infinite
    vertex extreme;
    extreme.x = INF;
    extreme.y = p.y;

    // Count intersections of the above line with sides of polygon
    int count = 0, i = 0;
    do {
        int next = (i + 1) % n;

        // Check if the line segment from 'p' to 'extreme' intersects
        // with the line segment from 'polygon[i]' to 'polygon[next]'
        if (doIntersect(polygon[i], polygon[next], p, extreme))
        {
            // If the vertex 'p' is colinear with line segment 'i-next',
            // then check if it lies on segment. If it lies, return true,
            // otherwise false
            if (orientation(polygon[i], p, polygon[next]) == 0)
                return onSegment(polygon[i], p, polygon[next]);

            count++;
        }
        i = next;
    } while (i != 0);

    // Return true if count is odd, false otherwise
    return count & 1; // Same as (count%2 == 1)
}

```

Вывод

Я изучил создание проектов со сложной архитектурой, также создал Gui с помощью библиотеки и использовал принципы ООП для построения проекта

Список литературы

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