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April 28, 2016

Bijan Karimi, Ph.D., Professor  
Electrical & Computer Engineering and Computer Science  
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Dear Dr. Karimi,

Attached is the report entitled "Mobile Motion Tracking Robot Arm". This report explains in detail the work completed at University of New Haven, by the UNH students in Electrical & Computer Engineering during the fall of 2015 and spring of 2016, for the Senior Design courses required by the school.

We would much appreciate it if you read our report carefully where our report focuses on the design and construction of the robot arm, mobile platform, and programming of the Arduino and Microsoft Kinect. This is the final submitted copy of the report. Should you have any questions or comments about the report, feel free to contact us via email any time.

Sincerely,   
Jeffery Ruocco Jeffrey Falberg Getro Jean-Bapiste

**Mobile Motion Tracking Robot Arm**

**Senior Design Project Report**

From: Jeffrey Falberg, Getro Jean-Baptiste, Jeffery Ruocco

To: Professor Bijan Karimi

April 28th, 2016

**Executive Summary**

**Acknowledgments**

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