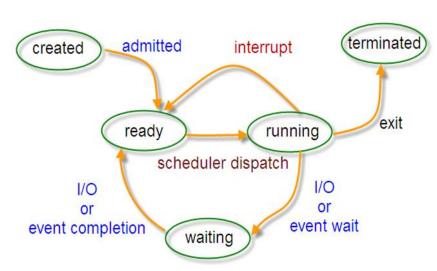
Linux System Programming Part 4 - Processes

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Processes in Linux

- **Processes** are object code in execution: active, alive, running programs.
- Processes consist of data, resources, state, and a virtualized computer.
- Each process is represented by a unique identifier, the process ID (pid).
- The process that the kernel "runs" when there are no other runnable processes is the idle process (pid=0).
- The process that spawns a new process is known as the **parent**; the new process is known as the **child**.
- Each process is owned by a **user** and a **group**.

The process state:



Managing the processes

- ps report a snapshot of the current processes.
- top display Linux processes.
- kill send a signal to a process.
- pgrep, pkill look up or signal processes based on name and other attributes.
- **killall** kill processes by name.
- **Ctrl-C** kill the foreground process.
- **Ctrl-Z** suspend the foreground process.
- **jobs** display status of jobs.
- **fg** returns the suspended process to the foreground.

Process programming in C

- **getpid**() get the pid of the <u>calling</u> process.
- **getppid**() get the pid of the <u>parent</u> process.
- execl(), execlp(), execle(), execv(), execvp(), execvpe() execute a file.
- fork() create a child process.
- exit() cause normal process termination.
- wait(), waitpid(), waitid() wait for process to change state.

Execute a command

```
int execl (const char *path, const char *arg, ...);
int execlp (const char *file, const char *arg, ...);
int execle (const char *path, const char *arg, ..., char * const envp[]);
int execv (const char *path, char *const argv[]);
int execvp (const char *file, char *const argv[]);
int execve (const char *filename, char *const argv[], char *const envp[]);
```

The mnemonics are simple:

- I and \mathbf{v} delineate whether the arguments are provided via a <u>list</u> or an array (<u>vector</u>).
- **p** denotes that the user's full path is searched for the given file. Commands using the p variants can specify just a filename, so long as it is located in the user's path.
- **e** notes that a new environment is also supplied for the new process.

Show own source file

Initialize the variables

Execute 'nano showsrc.c'

If execution failed, write a message and exit

Print unreachable message for demo purposes

```
showsrc.c #include <unistd.h>
            #include <stdio.h>
            #include <stdlib.h>
            int main(int argc, char * argv[])
                int ret;
                ret = execl ("/bin/nano", "nano", "showsrc.c", NULL);
            /* Or we could use this:
                const char *args[] = { "nano", "showsrc.c", NULL };
                ret = execvp ("nano", args); */
                if (ret == -1){
                    printf("Failed to run nano!\n");
                    return EXIT_FAILURE;
                printf("I shouldn't be here!\n");
                return EXIT_SUCCESS;
```

Parent process pid = 15

```
Child process
pid = 16
```

Running a child process

```
#include <sys/types.h>
#include <unistd.h>
pid_t fork (void);
pid_t getpid (void);
pid_t getppid (void);
```

```
pid = fork ( );
if (pid > 0){
    printPIDs("PARENT");
    wait(&child_status);
}
else if (!pid){
    printPIDs("CHILD");
    exit(0);
}
else if (pid == -1) {
    printf("ERROR!");
    return EXIT_FAILURE;
}
```

```
pid = fork ( );
if (pid > 0){
    printPIDs("PARENT");
    wait(&child_status);
}
else if (!pid){
    printPIDs("CHILD");
    exit(0);
}
else if (pid == -1) {
    printf("ERROR!");
    return EXIT_FAILURE;
}
```

- A successful call to **fork**() creates a new process, identical in almost all aspects to the invoking process.
- The parent process gets the pid of the child process and the child process gets 0.
- On error, a child process is not created, **fork()** returns -1, and **errno** is on of:
 - EAGAIN The kernel failed to allocate certain resources, such as a new pid.
 - ENOMEM Insufficient kernel memory was available to complete the request.

```
printpids.c
```

Write sentences into file

Initialize the functions and variables

Fork the process and store the **pid**(s)

If **pid** is positive (parent):

Print parent pid and ppid

If **pid** is zero (child):

Print child pid and ppid

If **pid** is -1 print error and exit

```
void printPIDs(char* process_name)
int main(int argc, char* argv[])
    pid_t pid;
    pid = fork ();
    if (pid > 0) printPIDs("PARENT");
    else if (!pid){
        printPIDs("CHILD");
        exit(0);
    else if (pid == -1) {
        printf("ERROR while forking!");
        return EXIT FAILURE;
    return EXIT SUCCESS;
```

Waiting and Terminating child processes

```
#include <stdlib.h>
void exit (int status);
```

- A call to exit() performs some basic shutdown steps, and then instructs the kernel to terminate the process.
- The status parameter is used to denote the process' exit status.
- When a process terminates, the kernel sends the signal SIGCHLD to the parent.

Parent process pid = 15

```
pid = fork ( );
if (pid > 0){
    printPIDs("PARENT");
    wait(&child_status);
}
else if (!pid){
    printPIDs("CHILD");
    exit(0);
}
else if (pid == -1) {
    printf("ERROR!");
    return EXIT_FAILURE;
}
```

Child process pid = 16

```
pid = fork ( );
if (pid > 0){
    printPIDs("PARENT");
    wait(&child_status);
}
else if (!pid){
    printPIDs("CHILD");
    exit(0);
}
else if (pid == -1) {
    printf("ERROR!");
    return EXIT_FAILURE;
}
```

Waiting and Terminating child processes

```
#include <sys/types.h>
#include <sys/wait.h>
pid t wait (int *status);
int WIFEXITED (status);
int WIFSIGNALED (status);
int WIFSTOPPED (status);
int WIFCONTINUED (status);
int WEXITSTATUS (status);
int WTERMSIG (status);
int WSTOPSIG (status);
int WCOREDUMP (status);
```

- A call to **wait()** returns the *pid* of a terminated child, or *-1* on error.
- If no child has terminated, the call blocks until a child terminates.
- WIFEXITED returns true if the process terminated normally.
- In terminated normally, **WEXITSTATUS** provides the loworder eight bits that were passed to _exit.
- WIFSIGNALED returns true if a signal caused the process' termination.
- In case of signal termination, **WTERMSIG** returns the number of that signal.
- In case of signal termination, WCOREDUMP returns true if the process dumped core in response to receipt of the signal.
- WIFSTOPPED and WIFCONTINUED return true if the process was stopped or continued, respectively.
- If WIFSTOPPED is true, WSTOPSIG provides the number of the signal that stopped the process.

execstat.c

if (argc < 2) {

Execute and print status

Verify we have enough arguments

Fork the process and store the **pid**(s)

The parent waits for the child and exits on error

On success, prints the status of the termination

The child executes the command in the arguments

Exit with success

```
return EXIT_FAILURE;
if (pid == 0) {
  execvp(argv[1], &argv[1]);
  perror("execvp");
  return EXIT_FAILURE; // Never get there normally
else {
  if (wait(&status) == -1) {
    perror("wait");
    return EXIT FAILURE;
  if (WIFEXITED(status))
    printf("Child terminated normally with exit code %i\n",
    WEXITSTATUS(status));
  if (WIFSIGNALED(status))
    printf("Child was terminated by a signal #%i\n",
    WTERMSIG(status));
  if (WCOREDUMP(status))
    printf("Child dumped core\n");
  if (WIFSTOPPED(status))
    printf("Child was stopped by a signal #%i\n", WSTOPSIG
    (status));
```

printf("Usage: %s command, [arg1 [arg2]...]\n", argv[0]);

Zombies and simple signals handling

- When a child dies before its parent, the kernel puts the child into a special process state - the process is then called a **zombie**.
- A process in this state waits for its parent to inquire about its status and only after this the child process cease to exist even as a zombie.
- If the parent never inquires about a child's status then the zombie becomes a ghost - very bad practice.
- If the parent process terminates before its children, then they a reparented to the init process.
- The init process, in turn, periodically waits on all of its children, ensuring that none remain zombies for too long.

```
#include <sys/wait.h>
pid_t waitpid(pid_t pid, int *wstatus, int options);
```

```
#include <signal.h>
int sigaction(int signum, const struct sigaction *act,
                struct sigaction *oldact);
struct sigaction {
    void
             (*sa handler)(int);
    void
             (*sa_sigaction)(int, siginfo_t *, void *);
    sigset t
               sa mask;
    int
               sa_flags;
             (*sa restorer)(void);
    void
};
```

Play with zombies

Define the termination signal handler

Initialize variables to use the signal handler

Set action for SIGCHLD, exit on error

Do 10 times:

Fork the process and store the **pid**(s)

The parent prints the pid of the new child

> The child prints a message and exits

Enter endless loop

```
zombietest.c static void sigchld hdl (int sig)
                      while (waitpid(-1, NULL, WNOHANG) > 0) {}
               act.sa handler = sigchld hdl;
               if (sigaction(SIGCHLD, &act, 0)) {
                  perror ("sigaction");
                  return 1;
              for (i = 0; i < 10; i++) {
                  int pid = fork();
                  if (pid == 0) {
                      printf("I will leave no zombie\n");
                      exit(0);
                  } else {
                       printf("Created a process with the PID %i\n", pid);
              while (1) {
                      sleep(1);
```

Exercise

Program TempFileGenerator:

The <u>parent</u> process should notify after each file is created.

Modify the program or write a new one, in which the processes write only in one file, where the **pid** sequences do not overlap (we have 1000 times **pid_file_1**, then 1000 times **pid_file_2**... then 1000 times **pid_files_cound**).