|  |  |  |  |
| --- | --- | --- | --- |
| **Name** | Jenny Reiman | Jason Laqua | Andrew Kirkham |
| **Hours** | 4 | 8 | 4 |
| **Reading** | <https://developers.google.com/maps/documentation/android/start>  <https://developers.google.com/maps/documentation/android/map>  <http://developer.android.com/guide/topics/location/index.html> | <http://www.appcoda.com/ios-programming-101-drop-a-pin-on-map-with-mapkit-api/>  <http://www.raywenderlich.com/21365/>  <https://github.com/scalessec/Toast>  <http://stackoverflow.com/questions/13515668/rotate-uiimageview-with-same-center-point-using-cgaffinetransformmakerotation>  <http://stackoverflow.com/questions/3925942/cllocation-category-for-calculating-bearing-w-haversine-function>  <https://github.com/robbiehanson/CocoaAsyncSocket> | <https://developers.google.com/maps/documentation/android/start>  <https://developers.google.com/maps/documentation/android/map>  <http://developer.android.com/guide/topics/location/index.html> |
| **Tasks Completed** | Fixing GPS | Fixing GPS | Tilt control of robot  Communication Between Devices Configures Automatically |
| **Tasks for Thursday** | Robot moves to GPS coordinate | Robot moves to GPS coordinate | Robot moves to GPS coordinate |

**Open issues: Robot move to GPS coordinate, accurate GPS**

|  |  |  |  |
| --- | --- | --- | --- |
| **What** | **Who** | **When** | **Done** |
| Iteration one tasks | All | 9-26 | ✓ |
| Iteration two tasks | All | Oct - 31 |  |
| Robot moves in straight line | All | Oct-31 | ✓ |
| Robot moves to GPS coordinate | All | Oct-31 |  |
| Communication Between Devices Configures Automatically | All | Nov-9 | ✓ |
| Android Tilt Control of Robot | Jason | Nov-23 | ✓ |
| Robot Visits all Waypoints | Jenny | Nov-23 |  |
| Robot is able to Return to Android | Jenny | Nov-16 |  |