

# The DickeyFuller Test for Stationarity

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# 1. What is Stationarity?

- A time series  $\{y_t\}$  is **strictly stationary** if its statistical properties (like mean, variance, autocorrelation) do not change over time.
- **Weak (covariance) stationarity:**
  1.  $E[y_t] = \mu$  (constant mean)
  2.  $\text{Var}(y_t) = \sigma^2$  (constant variance)
  3.  $\text{Cov}(y_t, y_{t+k})$  depends only on lag  $k$ , not on  $t$ .

## 2. What is a Unit Root?

- Consider the AR(1) model:  $y_t = \phi y_{t-1} + \varepsilon_t$ , where  $\varepsilon_t \sim \text{IID}(0, \sigma^2)$ .
- If  $|\phi| < 1$ , the process is stationary.
- If  $\phi = 1$ , there is a **unit root**, and  $y_t = y_{t-1} + \varepsilon_t$  is a **random walk**  $\rightarrow$  nonstationary.

## What does IID mean?

- IID stands for independent and identically distributed
  - Each  $\varepsilon_t$  is drawn from the same distribution (e.g., Normal with mean 0, variance  $\sigma^2$ )
  - No dependence across time: each error term is independent of the others

### 3. Rewriting Using Differences

- Define the first difference:  $\Delta y_t = y_t - y_{t-1}$ .
- Then:
  - $\Delta y_t = (\phi - 1) y_{t-1} + \varepsilon_t = \delta y_{t-1} + \varepsilon_t$ ,  
where  $\delta = \phi - 1$ .
- Hypotheses:
  - $H_0: \delta = 0$  (i.e.,  $\phi = 1$ , nonstationary).
  - $H_1: \delta < 0$  (i.e.,  $|\phi| < 1$ , stationary).

## 4. DickeyFuller Test Statistic

- Estimate regression:  $\Delta y_t = \delta y_{t-1} + \varepsilon_t$ .
- Compute tstatistic:  $t_\delta = \hat{\delta}/\text{SE}(\hat{\delta})$ .
- Compare  $t_\delta$  to nonstandard critical values (e.g., from MacKinnon tables).

## 5. Augmented DickeyFuller (ADF)

- Add intercept and trend if needed:

$$\Delta y_t = \alpha + \beta t + \delta y_{t-1} + \sum_{i=1}^p \gamma_i \Delta y_{t-i} + \varepsilon_t$$

.

- The additional lag terms control for higherorder correlation in residuals.