Creating a point cloud:

```
gWgmfDxsmYOsvfBr8gQj,243.019,-676.931,950.56
6EdibLGB8HmPPuyVhzPP,76.9982,819.208,-409.772
FK7B8odYlbcyHKLx9I32,-377.056,-779.229,-888.18
1kIWxLfAyqQAuBQagKvg,459.639,-117.771,258.4
2WfLYnLVUnyHXJTx5IGr,-804.498,69.7958,-903.256
fhg4VFaF51JpaZF59dCh,-71.2607,-184.484,-995.178
rGMxwyofivwPzMtWP9t4,742.302,-841.609,-982.36

Finished, waiting for key press.
PS C:\Users\Andi\Source\Repos\PCCP3\Release> .\mmDistPt.exe -g 1000,1000,1000,1000 > test2.txt
PS C:\Users\Andi\Source\Repos\PCCP3\Release>
```

Calculating minimum and maximum distance:

```
Minimum distance of 8.1403 between point: IgxIX4a2dREbbSqWy6yh and point: jSAjBQjgnZSCe8nPQHnp!

Maximum distance of 143.523 between point: ZYFYZ5B6kzMCk8R6BEuZ and point: aPHWfUTjlTOSj3iH7JTR!
Time taken (high resolution time): 0.381s

Finished, waiting for key press.
```