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### CONSTRUCTION MACHINE, ANTENNA ATTACHMENT METHOD, AND ANTENNA ATTACHMENT STRUCTURE

#### Abstract

A construction machine includes a lower traveling body and an upper revolving body. The upper revolving body is revolvably supported by the lower traveling body. The upper revolving body includes an operator seat, a roof above the operator seat, a pair of rear support columns extending upward from a rear section of the upper revolving body and supporting the roof, and a first GNSS antenna support post. The first GNSS antenna support post is to be attached to a first GNSS antenna at a top end of the first GNSS antenna support post, is connected to the first rear support column, extends upward, and located outside of the roof and between the rear section and a front section. In a plan view, the roof is positioned off center of the upper revolving body towards one end that is an opposite end where the first GNSS support post is located.

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## Background/Summary

[0001] This application is a Continuation under 35 U.S.C. § 120 of U.S. patent application Ser. No. 17/623,097, filed Dec. 27, 2021, which was a national phase entry under 35 U.S.C. § 371 of PCT Patent Application No. PCT/JP2020/021706, filed on Jun. 2, 2020, which claims priority under 35 U.S.C. § 119 to Japanese Patent Application No. 2019-0140402, filed Jul. 31, 2019, the entireties of which are incorporated by reference.

### TECHNICAL FIELD

[0002] The present invention mainly relates to a construction machine to which a pair of global navigation satellite system (GNSS) antennas are attached.

### BACKGROUND ART

[0003] Patent Literature 1 discloses a work vehicle to which a global positioning system (GPS) antenna is attached. The work vehicle is equipped with a fixed member which is rod-shaped and extending vertically. The GPS antenna is attached to the fixed member.

[0004] Patent Literature 2 discloses a construction machine including a lower traveling body and an upper revolving body which is revolvably supported with respect to the lower traveling body. The construction machine is equipped with a GPS antenna. Specifically, a hydraulic oil tank is disposed in the upper revolving body, and the GPS antenna is attached to the hydraulic oil tank. Since the hydraulic oil tank is covered by a tank cover, the GPS antenna is also covered by the tank cover, so that the antenna can be protected.

### CITATION LIST

Patent Literature

[0005] Patent Literature 1: Japanese Unexamined Patent Publication No. 2006-56280 [0006] Patent Literature 2: Japanese Unexamined Patent Publication No. 2003-112579

### DISCLOSURE OF INVENTION

Problems to be Solved by the Invention

[0007] In a construction machine having a lower traveling body and an upper revolving body as in Patent Literature 2, when a GNSS antenna is attached to the upper revolving body, the position of the GNSS antenna changes according to the revolving angle of the upper revolving body.

Therefore, it is necessary to install, for example, two GNSS antennas in order to obtain the position of the construction machine with high accuracy. In a case where the GNSS antenna is covered by another member, radio waves may not properly be received from the GNSS satellite.

[0008] The present invention has been made in view of the above circumstances, and it is a main object of the present invention to provide a structure for properly arranging a pair of GNSS antennas in a construction machine including a lower traveling body and an upper revolving body.

Means for Solving the Problems

Effect of the Invention

[0009] The problem to be solved by the present invention is as described above, and the means for

solving the problem and effects thereof will be described below.

[0010] According to a first aspect of the present invention, there is provided a construction machine having the following configuration. That is, the construction machine includes a lower traveling body and an upper revolving body. The upper revolving body is supported revolvably by the lower traveling body. The upper revolving body includes a prime mover, an operator seat, a roof, rear support columns, a base body, antenna support posts, and GNSS antennas. The prime mover is disposed at the rear section of the upper revolving body and drives at least the lower traveling body. The operator seat is disposed above the prime mover and the operator is seated on the operator seat. The roof is disposed above the operator seat. The rear support columns are provided as a pair and extend upward from the rear section of the upper revolving body to support the roof. The base body is attached to the pair of rear support columns to connect them together. The antenna support posts are provided as a pair and extend upward from the base body at positions not overlapping the roof in plan view. The GNSS antennas are provided as a pair, and each GNSS antenna is attached to each of the pair of antenna support posts.

[0011] This facilitates the GNSS setting, because the relative position of the pair of GNSS antennas is fixed and known as the GNSS antennas are connected to the same base body via the antenna support posts. By attaching the GNSS antennas using the rear support columns in the positional relationship described above, the GNSS antennas can be disposed at positions where the radio waves from the GNSS satellite are hardly blocked by the roof or the like.

[0012] In the construction machine described above, the base body preferably includes a pair of attaching members, each attached detachably to each of the pair of rear support columns.

[0013] This enables reduction in size of the construction machine in a situation where the GNSS antennas are not necessary (for example, during transportation of the construction machine). If the attaching height of the base body is changeable because, for example, the placement distance between the rear support columns is fixed, the attaching height of the GNSS antennas can be changed.

[0014] In the construction machine described above, the base body preferably includes a first adjustment mechanism capable of changing the placement distance between the pair of attaching members.

[0015] This allows the base body to be attached to various types of construction machines having different placement distances between the rear support columns. In addition, the attaching height of the base body can also be adjusted for the construction machine in which the placement distance between the rear support columns changes with height.

[0016] In the above-described construction machine, the base body, the antenna support posts, and the GNSS antennas are located, in plan view, inside a revolving area having an outer edge defined by the trajectory of an outer edge of a counterweight, which is disposed at the rear end of the upper revolving body, when the counterweight revolves with the upper revolving body.

[0017] This prevents enlargement of the revolving area due to the attaching members used to attach the GNSS antennas.

[0018] In the construction machine described above, the revolving area is preferably within the vehicle width of the lower traveling body.

[0019] Thus, the present invention is applicable to relatively small construction machines in which a major part of the upper revolving body does not extend outside the lower traveling body even during revolving of the upper revolving body.

[0020] The construction machine described above preferably has the following configuration. That is, the left ends of the base body, the antenna support posts, and the GNSS antennas are located, in plan view, inside the left end of the lower traveling body in the right-left direction. The right ends of the base body, the antenna support post column, and the GNSS antenna are located, in plan view, inside the right end of the lower traveling body in the right-left direction.

[0021] Since the members for attaching the GNSS antennas do not protrude from the lower

traveling body in the right-left direction, the GNSS antennas or the like are unlikely to collide with obstacles, for example, in a situation where the construction machine is located in a narrow space. [0022] In the construction machine described above, the base body preferably includes a second adjustment mechanism capable of changing the placement distance between the pair of antenna support posts.

[0023] Since the minimum placement distance between the pair of GNSS antennas is fixed according to the specifications of the GNSS antennas, the provision of the second adjustment mechanism makes it possible to support the GNSS antennas of various specifications.

[0024] According to a second aspect of the present invention, an antenna attachment method described below is provided. That is, the antenna attachment method is a method of attaching GNSS antennas to a construction machine including a lower traveling body and an upper revolving body. The upper revolving body is revolvably supported by the lower traveling body and includes a pair of rear support columns extending upward from the rear section of the upper revolving body and a roof disposed above the operator seat and supported by the rear support columns. The antenna attachment method includes attaching a base body and attaching antennas. In attaching the base body, the base body is attached to the pair of rear support columns to connect them together. In attaching the antennas, a pair of GNSS antennas is attached to a pair of antenna support posts extending upward from the base body at positions not overlapping the roof in plan view.

[0025] According to a third aspect of the present invention, an antenna attachment structure having a configuration described below is provided. That is, the antenna attachment structure attaches the GNSS antennas to a construction machine including a lower traveling body and an upper revolving body. The upper revolving body is revolvably supported by the lower traveling body and includes a pair of rear support columns extending upward from the rear section of the upper revolving body and a roof disposed above the operator seat and supported by the rear support columns. The antenna attachment structure includes a base body, antenna support posts, and GNSS antennas. The base body can be attached to the pair of rear support columns to connect them together. The antenna support posts are provided as a pair and extend from the base body. The GNSS antennas are provided as a pair, and each GNSS antenna is attached to each of the pair of antenna support posts.

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## Description

### BRIEF DESCRIPTION OF DRAWINGS

[0026] FIG. 1 is a side view illustrating an overall configuration of a revolving work vehicle according to an embodiment of the present invention.

[0027] FIG. 2 is a plan view of the revolving work vehicle.

[0028] FIG. 3 is a schematic view illustrating a rear section of an upper revolving body.

[0029] FIG. 4 is an exploded schematic view of an antenna attachment structure.

[0030] FIG. 5 is a schematic view of the antenna attachment structure included in the revolving work vehicle according to a first modification.

[0031] FIG. 6 is a plan view of the revolving work vehicle according to the first modification.

[0032] FIG. 7 is a schematic view of an antenna attachment structure provided in a revolving work vehicle according to a second modification.

[0033] FIG. 8 is a schematic diagram of an antenna attachment structure provided in a revolving work vehicle according to a third modification.

[0034] FIG. 9 is a schematic view illustrating a comparative example in which a pair of antennas is attached separately.

### DESCRIPTION OF EMBODIMENTS

[0035] An embodiment of the present invention will be described below with reference to the

accompanying drawings. FIG. 1 is a side view illustrating an overall configuration of a revolving work vehicle 1 according to an embodiment of the present invention.

[0036] A revolving work vehicle (construction machine, hydraulic shovel) 1 illustrated in FIG. 1 includes a lower traveling body 11 and an upper revolving body 12.

[0037] The lower traveling body 11 includes a crawler travel device 21 and a hydraulic motor 22. The crawler travel device 21 and the hydraulic motor 22 are provided as a pair and disposed on both right and left sides.

[0038] Each crawler travel device 21 includes an endless crawler made of, for example, rubber. The crawler is wound around a sprocket, and the sprocket is coupled to an output shaft of the hydraulic motor 22 disposed on the same side as the crawler travel device 21.

[0039] Each hydraulic motor 22 is configured to rotate forward and backward to allow the revolving work vehicle 1 to move forward and backward. The hydraulic motors 22 are configured to be operable separately on the right and left sides to allow the revolving work vehicle 1 to move linearly or to change the direction of the revolving work vehicle 1 (lower traveling body 11).

[0040] The upper revolving body 12 includes a revolving frame 31, a vehicle body 32, a revolving motor 33, an engine (prime mover) 34, a hydraulic pump unit 35, a operation unit 36, an operator seat 37, a GNSS antenna 64, work equipment 13, and a counterweight 38.

[0041] The revolving frame 31 is disposed above the lower traveling body 11, and supported by the lower traveling body 11 to revolve about an axis extending in the vertical direction. The vehicle body 32 is fixed to the revolving frame 31 to rotate integrally with the revolving frame 31. The vehicle body 32 is nearly circular in plan view (specifically, the front portion is shaped linearly) to constitute a part of the side face of the upper revolving body 12. Space is formed inside the vehicle body 32, in which and the revolving motor 33, the engine 34, the hydraulic pump unit 35, and so on are disposed.

[0042] The revolving motor 33 generates a driving force to rotate the revolving frame 31 and the vehicle body 32 with respect to the lower traveling body 11. The engine 34 is disposed in the rear section of the upper revolving body 12. The rear section indicates, for example, the section located behind the center in the front-back direction. The engine 34 is configured as, for example, a diesel engine. The engine 34 may be a gasoline engine. An electric motor may also be provided in addition to or instead of the engine 34. The hydraulic pump unit 35 is driven by the engine 34 to generate the oil pressure necessary for traveling and working of the revolving work vehicle 1.

[0043] The operation unit 36 includes various control members. For example, the control members include a travel control lever 36a and a work control lever 36b provided as a pair and disposed on the right and left. The operator seat 37 is disposed above the engine 34 and near the operation unit 36. The operator is seated on the operator seat 37 and operates the above-described control members to provide various instructions to the revolving work vehicle 1. The GNSS antenna 64 is disposed behind the operator seat 37. The details of the mounting method of the GNSS antenna 64 will be described later.

[0044] The work equipment 13 includes a boom 41, an arm 42, a bucket 43, and a blade (soil removal plate) 47. The work equipment 13 also includes, as actuators, a boom cylinder 44, an arm cylinder 45, a bucket cylinder 46, and a blade cylinder 48.

[0045] The boom 41 is configured as an elongated member with its base end being rotatably supported on the front of the vehicle body 32. The boom cylinder 44 is attached to the boom 41, allowing the boom cylinder 44 to expand and contract to rotate the boom 41.

[0046] The arm 42 is configured as an elongated member with its base end being rotatably supported by the distal end of the boom 41. The arm cylinder 45 is attached to the arm 42, allowing the arm cylinder 45 to expand and contract to rotate the arm 42.

[0047] The bucket 43 is configured as a container-shaped member with its base end being rotatably supported by the distal end of the arm 42. The bucket cylinder 46 is attached to the bucket 43, allowing the bucket cylinder 46 to expand and contract to rotate the bucket 43 and perform a

scooping operation or a dumping operation.

[0048] The blade **47** is provided to extend in a direction of a width of the vehicle body (right-left direction). The blade **47** is disposed in front of the lower traveling body **11**. The blade **47** is rotatably supported relative to the lower traveling body **11** about an axis extending in the right-left direction. The blade cylinder **48** is attached to the blade **47**, allowing the blade cylinder **48** to extend and contract to move the blade **47** up and down.

[0049] In the present embodiment, the boom cylinder **44**, the arm cylinder **45**, the bucket cylinder **46**, and the blade cylinder **48** are all formed by hydraulic cylinders. These hydraulic cylinders expand and contract by the hydraulic power generated by the hydraulic pump unit **35**.

[0050] The counterweight **38** is a weight for stabilizing the revolving work vehicle **1** equipped with the work equipment **13**, which is a heavy object, on the front. For this purpose, the counterweight **38** is located at the rear end of the upper revolving body **12**. In plan view, the outer edge (peripheral surface) of the counterweight **38** is arc-shaped.

[0051] Next, a method of attaching the GNSS antenna **64** will be described in detail with reference to FIGS. **2** to **4**.

[0052] When the upper revolving body **12** revolves with respect to the lower traveling body **11**, the front and rear of the lower traveling body **11** and the front and rear of the upper revolving body **12** do not match. For the purpose of describing the configuration of the upper revolving body **12**, the front and rear of the upper revolving body **12** will simply be referred to as front and rear below.

[0053] As illustrated in FIGS. **3** and **4**, for example, two GNSS antennas **64** are attached to the revolving work vehicle **1**. This is because the position information of the work equipment **13** of the revolving work vehicle **1** needs to be acquired in implementing the information-based construction according to, for example, machine control technology or machine guidance technology. In particular, to detect the position information of the work equipment **13** in the revolving work vehicle **1**, even when the upper revolving body **12** revolves with respect to the lower traveling body **11**, the position of the revolving work vehicle **1** and the information of a revolving angle of the upper revolving body **12** are needed. To obtain these values, the detection results of the two GNSS antennas **64** are needed. The relative position of the two GNSS antennas **64** relative to the revolving work vehicle **1** is also needed to obtain these values. To obtain these values with high accuracy, the placement distance between the two GNSS antennas **64** needs to be equal to or greater than a specified value (minimum placement distance).

[0054] As illustrated in FIG. **3**, the revolving work vehicle **1** includes roof support units **51** and a roof **55**, and the GNSS antennas **64** are attached to the roof support units **51**. The roof support units **51** are provided as a pair and disposed on the right and left, and the GNSS antennas **64** are attached at two positions corresponding to the two roof support units **51**. As illustrated in FIG. **2**, the right and left roof support units **51** are different in shape, but have the same function, so that the description is given below as the same units. The right and left roof support units **51** may be in the same shape or provided symmetrically.

[0055] As illustrated in FIG. **3**, the roof support units **51** each include a rear support column **52**, a roof attaching unit **53**, and a front support column **54**. The roof support unit **51** may be formed by curving a member (pipe material) or coupling a plurality of members by welding or with bolts.

[0056] The rear support column **52** is a member (with its longitudinal direction being parallel with the vertical direction) extending upward from the rear section of the upper revolving body **12**. The rear section of the upper revolving body **12** corresponds to a section behind the center of the upper revolving body **12** in the front-back direction (more particularly, the rearmost section of the upper revolving body **12** when it is divided into four equal parts in the front-back direction). In another perspective, the rear support column **52** extends upward from behind the mounting position of the operator seat **37**. The rear support column **52** is fixed to the vehicle body **32** with bolts or the like. The rear support column **52** may extend diagonally upward.

[0057] The roof attaching unit **53** is connected to the upper end of the rear support column **52**. The

roof attaching unit **53** extends front to back. The roof **55** is disposed so as to connect the pair of right and left roof attaching units **53**. The roof **55** is disposed to cover the upper side of the operation unit **36** and the operator seat **37**.

[0058] The front support column **54** is a member extending upward from the front section of the upper revolving body **12**. The front section is defined corresponding to the definition of the rear section. The front end of the roof attaching unit **53** is coupled to the upper end of the front support column **54**.

[0059] Thus, the revolving work vehicle **1** of the present embodiment is so-called a canopy-type revolving work vehicle having the roof disposed on the columns. In other words, the revolving work vehicle **1** of the present embodiment is not a cabin-type revolving work vehicle, so that the operation space in which the operation unit **36** and the operator seat **37** are disposed is not partitioned from the outside. The revolving work vehicle **1** of the present embodiment is so-called a four-column canopy-type revolving work vehicle, as it has two columns each at the front and the rear. The revolving work vehicle **1** may be a two-column canopy-type revolving work vehicle by omitting the front support columns **54**.

[0060] Next, the antenna attachment structure **60** is described. The antenna attachment structure **60** is a structure for attaching the GNSS antennas **64** to the revolving work vehicle **1**. As illustrated in FIGS. **3** and **4**, the antenna attachment structure **60** includes a base body **61**, antenna support posts **63**, and the GNSS antennas **64**.

[0061] The base body **61** is a member extending to the right and left. As illustrated in FIG. **3**, the base body **61** is disposed behind the pair of right and left rear support columns **52** to connect them together. Specifically, a pair of right and left attaching members **62** is attached to the front side of the base body **61** to attach the base body **61** to the rear support columns **52**.

[0062] The attaching members **62** are clamping members attached to the rear support columns **52** by tightening bolts while gripping the rear support columns **52**. A placement distance between the attaching members **62** in the right-left direction is the same as a placement distance between the rear support columns **52** in the right-left direction. Accordingly, the pair of right and left attaching members **62** is attached to the pair of right and left rear support columns **52**. A stretchable member, such as rubber, may be disposed between the attaching members **62** and the rear support columns **52**. The attaching members **62** are detachable from the rear support columns **52** when the gripping is released by loosening the bolts.

[0063] By providing such detachable attaching members **62**, the GNSS antenna **64** can easily be added to an existing revolving work vehicle **1**. For example, when the revolving work vehicle **1** is loaded onto a truck or the like for transportation, the size of the revolving work vehicle **1** can be reduced by removing the antenna attachment structure **60**, so as not to exceed, for example, the maximum loading size of the truck. When the placement distance between the rear support columns **52** is fixed, the attaching height of the antenna attachment structure **60** can easily be adjusted.

[0064] The antenna support posts **63** are vertically extending members attached to the upper surface of the base body **61** on the right and left as a pair. As illustrated in FIG. **4**, the upper part of the antenna support post **63** has a protruding portion with a threaded groove formed around it. As described above, it is desirable to keep the two GNSS antennas **64** as far apart as possible. In the present embodiment, therefore, the placement distance between the antenna support posts **63** is larger than the placement distance between the attaching members **62** (placement distance between the rear support columns **52**). However, both placement distances may be the same, or the placement distance between the antenna support posts **63** may be smaller.

[0065] The GNSS antennas **64** are provided as a pair, one on the left and one on the right, and are attached to the top of the pair of antenna support posts **63**. Specifically, a screw hole is formed on the underside of each GNSS antenna **64** to attach the GNSS antenna **64** to the antenna support post **63** by aligning the screw hole of the GNSS antenna **64** with the protruding portion of the antenna

support post **63** and rotating the GNSS antenna **64**. Rotating the GNSS antenna **64** reversely, it can be removed from the antenna support post **63**. By making the GNSS antennas **64** to be detachable, the GNSS antennas **64** can be removed when not in use to prevent theft.

[0066] The GNSS antennas **64** receive signals from the GNSS satellite that constitutes a satellite positioning system like GPS. A positioning signal received by the GNSS antennas **64** is input to a receiving unit not shown to perform positioning operation. By performing the positioning operation, the position information of the revolving work vehicle **1** (in particular, the position information of the GNSS antennas **64**) is calculated to obtain, for example, latitude and longitude information. Simultaneously, the revolving angle of the upper revolving body **12** is also calculated.

[0067] The antenna attachment structure **60** is attached behind the rear support columns **52**.

Accordingly, in the plan view of the revolving work vehicle **1** (FIG. **2**), the antenna support posts **63** and the GNSS antennas **64** are arranged at positions not overlapping the roof **55**. Thus, the positioning signals from the GNSS satellite can hardly be blocked by the roof **55**. As illustrated in FIG. **1**, the upper ends of the GNSS antennas **64** are at the same height as or slightly lower than the upper ends of the roof attaching unit **53** (or roof **55**). This decreases the possibility of objects falling from above to directly hit the GNSS antenna **64**. Since the boundary between the rear support column **52** and the roof attaching unit **53** is gently curved instead of being bent at a right angle, the placement distance between the roof support unit **51** and the GNSS antenna **64** can be increased. This facilitates reception of the positioning signals from the GNSS satellite. The GNSS antennas **64** may be attached at positions higher than the roof attaching units **53** to further facilitate the reception of the positioning signals from the GNSS satellite.

[0068] In performing the antenna attachment method to attach the GNSS antennas **64** to the revolving work vehicle **1**, the base body **61** is first attached to both of the pair of rear support columns **52** so as to connect them together (attaching the base body). Next, the pair of GNSS antennas **64** is attached to the pair of antenna support posts **63** extending upward from the base body **61** (attaching the antennas). The order of the above steps is an example and may be different. That is, the base body **61** may be attached to the rear support columns **52** after the GNSS antennas **64** are attached to the antenna support posts **63**.

[0069] Next, with reference to FIG. **2**, the position of the antenna attachment structure **60** relative to a revolving area **100** of the revolving work vehicle **1** is described. In the following description, the revolving area **100** is an area, in plan view, having an outer edge defined by the trajectory (circle or arc) of an outer edge of the counterweight **38** when it revolves with the upper revolving body **12** (an area inside the outer edge of the trajectory). From another perspective, the revolving area **100** may be regarded as an area where the vehicle body **32** of the upper revolving body **12** revolves in plan view, an area where a portion of the upper revolving body **12** excluding the work equipment **13** and the antenna attachment structure **60** revolves in plan view, or an area where the rear section of the upper revolving body **12** (the section behind the center in the front-back direction and excluding the antenna attachment structure **60**) revolves.

[0070] In the revolving work vehicle **1** of the present embodiment, the revolving area **100** is located inside the lower traveling body **11** in the right-left direction (in other words, the revolving area **100** is located within the vehicle width of the lower traveling body **11**). Specifically, the revolving center corresponds to the center of the revolving work vehicle **1** in the right-left direction. The diameter of the revolving area **100** is smaller than a right-left width of the lower traveling body **11** (specifically, a length from the left end of the left lower traveling body **11** to the right end of the right lower traveling body **11**). In other words, the upper revolving body **12** is not positioned outside the lower traveling body **11** even during revolving of the upper revolving body **12**. The diameter of the revolving area **100** may be larger than the right-left width of the lower traveling body **11**. Even in this case, it is preferable that the diameter of the revolving area **100** is smaller than 1.2 times the right-left width of the lower traveling body **11**.

[0071] The antenna attachment structure **60** of the present embodiment is smaller than the right-left



width of the lower traveling body **11** and does not protrude from the lower traveling body **11** in the right-left direction. In other words, the right and left ends of the antenna attachment structure **60** are located inside the ends of the lower traveling body **11** in the right-left direction. Basically, therefore, when the lower traveling body **11** has a sufficient width for travel, the antenna attachment structure **60** does not collide with obstacles.

[0072] The antenna attachment structure **60** of the present embodiment is entirely located inside the revolving area **100**, except for a portion of the left end. Since the protruding amount of the antenna attachment structure **60** from the revolving area **100** is very small, the antenna attachment structure **60** is unlikely to collide with obstacles during revolving of the upper revolving body **12**.

Alternatively, as illustrated in a first modification below, the entire antenna attachment structure **60** may be positioned inside the revolving area **100**.

[0073] Next, a first modification is described with reference to FIGS. **5** and **6**. In the following description, the constituent components identical to or similar to those of the above-described embodiment are marked with the same signs in the drawings and may be omitted from the description.

[0074] The revolving work vehicle **1** of the first modification includes the antenna attachment structure **60** capable of positioning the antenna attachment structure **60** inside the revolving area **100**, while keeping the placement distance between the GNSS antennas **64** to be not excessively small. The first modification mainly differs from the embodiment described above in the structure of the base body **61**. Specifically, the base body **61** of the first modification is L-shaped in plan view. In other words, the base body **61** includes a first portion **61a** and a second portion **61b**.

[0075] Like the base body **61** of the embodiment described above, the first portion **61a** extends to the right and left to connect the pair of right and left rear support columns **52** together. The two attaching members **62** are both attached to the first portion **61a**. The antenna support post **63** is disposed on the first portion **61a** at a position near the end (specifically, at a short distance away from the end) on the side opposite to the boundary with the second portion **61b**.

[0076] The attaching member **62** is attached to the end of the base body **61**, and the antenna support post **63** is disposed at a short distance away from the end of the base body **61** (for example, at a position where the attaching member **62** and the GNSS antenna **64** do not overlap in plan view). This allows the GNSS antennas **64** to be positioned inside the revolving area **100**, as illustrated in FIG. **6**. In addition, the left end of the first portion **61a** (where the attaching member **62** is attached) has its rear corner dropped (chamfered). This allows the base body **61** to be positioned inside the revolving area **100**, as illustrated in FIG. **6**.

[0077] The second portion **61b** is a portion that extends forward from the boundary with the first portion **61a**. Accordingly, the longitudinal direction of the first portion **61a** intersects (is orthogonal to) the longitudinal direction of the second portion **61b**. In the second portion **61b**, the antenna support post **63** is disposed near the end on the side opposite to the boundary with the first portion **61a**. The corner of the right end of the first portion **61a** (the rear end of the second portion **61b**) is not dropped, but may be dropped.

[0078] By positioning the antenna attachment structure **60** inside the revolving area **100**, the antenna attachment structure **60** is not positioned outside the revolving area **100** even during revolving of the upper revolving body **12**. Further, as in the embodiment described above, since the revolving area **100** is positioned inside the lower traveling body **11** in the right-left direction, the antenna attachment structure **60** is not positioned outside the lower traveling body **11** even during revolving of the upper revolving body **12**. This decreases the possibility of the antenna attachment structure **60** colliding with obstacles.

[0079] By providing the second portion **61b** and disposing the GNSS antenna **64** on the second portion **61b**, the placement distance between the GNSS antennas **64** can be increased compared to the configuration in which the GNSS antennas **64** are mounted on the linear-shaped base body **61**.

[0080] Next, a second modification is described with reference to FIG. **7**. The second modification

differs from the embodiment described above in that the base body **61** includes a first adjustment mechanism **70**. The first adjustment mechanism **70** is a mechanism for adjusting the placement distance between the pair of right and left attaching members **62**.

[0081] As illustrated in FIG. 7, the first adjustment mechanism **70** includes an inner member **71** which is slidably inserted into the base body **61**. The attaching member **62** is attached to the inner member **71**. The inner member **71** has a plurality of inner holes **72** formed for positioning. Correspondingly, the base body **61** also has an outer hole **73** for formed for positioning. After aligning the inner hole **72**, which corresponds to a desired placement distance between the attaching members **62**, with the outer hole **73**, the inner member **71** is attached to the base body **61** by fastening a bolt **74**.

[0082] If the placement distance between the attaching members **62** and the placement distance between the rear support column **52** do not match, the antenna attachment structure **60** cannot be attached to the rear support columns **52**. In this respect, the placement distance between the attaching members **62** can be adjusted in the second modification, allowing the antenna attachment structure **60** to be attached to various revolving work vehicles **1**. The antenna attachment structure **60** can also be attached at a desired height even in the revolving work vehicle **1** in which the placement distance between the rear support columns **52** changes as they move upward.

[0083] The configuration for adjusting the placement distance between the attaching members **62** is not limited to the above structure. For example, the attaching members **62** may be detachable from the base body **61**, and a plurality of holes or the like for attaching the attaching members **62** may be formed in the base body **61**.

[0084] Next, a third modification is described with reference to FIG. 8. The third modification differs from the above embodiment in that the base body **61** includes a second adjustment mechanism **80**. The second adjustment mechanism **80** is a mechanism for adjusting the placement distance between the pair of right and left antenna support posts **63**.

[0085] As illustrated in FIG. 8, the second adjustment mechanism **80** includes an inner member **81** which is slidably inserted into the base body **61**. The antenna support post **63** is attached to the inner member **81**. The inner member **81** has a plurality of inner holes **82** formed for positioning. Correspondingly, the base body **61** has an outer hole **83** formed for positioning. After aligning the inner hole **82**, which corresponds to a desired placement distance between the GNSS antennas **64**, with the outer hole **83**, the inner member **81** is attached to the base body **61** by fastening a bolt **84**.

[0086] As described above, a larger placement distance between the two GNSS antennas **64** is preferred. Specifically, in order to properly detect the position or the like of the revolving work vehicle **1**, the placement distance between the GNSS antennas **64** needs to be larger than the minimum placement distance. The minimum placement distance varies depending on the types of the GNSS antennas **64**. In this respect, the placement distance between the antenna support posts **63** (GNSS antennas **64**) can be adjusted in the second modification, allowing the GNSS antennas **64** to be attached to satisfy the condition of the minimum placement distance according to the type of the GNSS antennas **64**.

[0087] The configuration for adjusting the placement distance between the antenna support posts **63** is not limited to the above configuration. For example, the antenna support posts **63** may be detachable from the base body **61**, with a plurality of holes or the like formed in the base body **61** for attaching the antenna support posts **63**.

[0088] In the configuration of the above-described embodiment and modifications, the two GNSS antennas **64** are connected to the same base body **61**. Accordingly, the relative position of the GNSS antennas **64** is fixed and known. This allows the process of registering the relative position of the two GNSS antennas **64** with respect to the revolving work vehicle **1** to be performed easily and accurately, compared to the configuration in which the base body **61** is split as illustrated in FIG. 9.

[0089] The antenna attachment structure **60** may be disposed to connect the pair of right and left

front support columns **54** together. However, since the space in front of the front support columns **54** is narrow due to the work equipment **13** and the like, it is preferable to attach the antenna attachment structure **60** as illustrated in the above embodiment. The antenna attachment structure **60** may also be disposed to connect the rear support columns **52** and the front support columns **54**, which are arranged front to back, together. However, since the space between the rear support columns **52** and the front support columns **54** is the space used for the ride of the operator, it is preferable to attach the antenna attachment structure **60** as in the above embodiment.

[0090] As described above, the revolving work vehicle **1** according to the embodiment described above includes the lower traveling body **11** and the upper revolving body **12**. The upper revolving body **12** is supported revolvably by the lower traveling body **11**. The upper revolving body **12** includes the engine **34**, the operator seat **37**, the roof **55**, the rear support columns **52**, the base body **61**, the antenna support posts **63**, and the GNSS antennas **64**. The engine **34** is disposed at the rear section of the upper revolving body **12** and drives (by driving the hydraulic pump unit **35**) at least the lower traveling body **11**. The operator seat **37** is disposed above the engine **34** and the operator is seated on the operator seat **37**. The roof **55** is disposed above the operator seat **37**. The rear support columns **52** are provided as a pair and extend upward from the rear section of the upper revolving body **12** to support the roof **55**. The base body **61** is attached to both of the pair of rear support columns **52** so as to connect them together. The antenna support posts **63** are provided as a pair and extend upward from the base body **61** at positions not overlapping the roof **55** in plan view. The GNSS antennas **64** are provided as a pair, and each GNSS antenna **64** is attached to each of the pair of antenna support posts **63**.

[0091] This facilitates the GNSS setting, because the relative position of the pair of GNSS antennas **64** is fixed and known as the GNSS antennas **64** are connected to the same base body **61** via the antenna support posts **63**. By attaching the GNSS antennas **64** using the rear support columns **52** in the positional relationship described above, the GNSS antennas **64** can be disposed at positions where the radio waves from the GNSS satellite are hardly blocked by the roof **55** or the like.

[0092] In the revolving work vehicle **1** of the above embodiment, the base body **61** includes the pair of attaching members **62**, each attached detachably to each of the pair of rear support columns **52**.

[0093] This enables reduction in size of the revolving work vehicle **1** in a situation where the GNSS antennas **64** are not necessary (for example, during transportation of the revolving work vehicle **1**). If the attaching height of the base body **61** is changeable because, for example, the placement distance between the rear support columns **52** is fixed, the attaching height of the GNSS antennas **64** can be changed.

[0094] In the revolving work vehicle **1** of the second modification, the base body **61** includes the first adjustment mechanism **70** capable of changing the placement distance between the pair of attaching members **62**.

[0095] This allows the base body **61** to be attached to various types of revolving work vehicles **1** having different placement distances between the rear support columns **52**. In addition, the attaching height of the base body **61** can also be adjusted for the revolving work vehicle **1** in which the placement distance between the rear support columns **52** changes with height.

[0096] In the revolving work vehicle **1** of the first modification, the base body **61**, the antenna support posts **63**, and the GNSS antennas **64** are located, in plan view, inside a revolving area **100** having an outer edge defined by the trajectory of the outer edge of a counterweight **38**, which is disposed at the rear end of the upper revolving body **12**, when the counterweight revolves with the upper revolving body **12**.

[0097] This prevents enlargement of the revolving area **100** due to the attaching members used to attach the GNSS antennas **64**.

[0098] In the revolving work vehicle **1** of the above embodiment, the revolving area **100** is within the vehicle width of the lower traveling body **11**.

[0099] Thus, the present invention is applicable to relatively small construction machines in which a major part of the upper revolving body **12** does not extend outside the lower traveling body **11** even during revolving of the upper revolving body **12**.

[0100] In the revolving work vehicle **1** of the above embodiment, the right and left ends of the base body **61**, the antenna support posts **63**, and the GNSS antennas **64** are located, in plan view, inside the ends of the lower traveling body **11** in the right-left direction.

[0101] Since the members for attaching the GNSS antennas **64** do not protrude from the lower traveling body **11** in the right-left direction, the GNSS antennas **64** or the like are unlikely to collide with obstacles, for example, in a situation where the revolving work vehicle **1** is located in a narrow space.

[0102] In the revolving work vehicle **1** of the third modification, the base body **61** includes the second adjustment mechanism **80** capable of changing the placement distance between the pair of antenna support posts **63**.

[0103] Since the minimum placement distance between the pair of GNSS antennas **64** is fixed according to the specifications of the GNSS antennas **64**, the provision of the second adjustment mechanism **80** makes it possible to support the GNSS antennas **64** of various specifications.

[0104] Although the preferred embodiment and modifications of the present invention have been described above, those configurations may change, for example, as described below.

[0105] The configurations of the above-described modifications can be combined as appropriate. For example, the L-shaped base body **61** of the first modification may be applied to the second or third modification. The first adjustment mechanism **70** of the second modification may be applied to the first or third modification. The second adjustment mechanism **80** of the third modification may be applied to the first or second modification.

[0106] The shapes of the constituent components of the antenna attachment structure **60** are illustrated as examples and can be changed, as necessary. For example, the base body **61** or the antenna support posts **63** may not be provided linearly and may include curved portions. The attaching members **62** are not limited to the clamping members, but may be configured to be attached to screw holes or the like formed in the rear support columns **52**. Furthermore, the structure described as detachable in the above embodiment may be non-detachable.

#### DESCRIPTION OF REFERENCE NUMERALS

[0107] **1** Revolving work vehicle (Construction machine) [0108] **11** Lower traveling body [0109] **12** Upper revolving body [0110] **13** Work equipment [0111] **51** Roof support unit [0112] **52** Rear support column [0113] **53** Roof attaching unit [0114] **54** Front support column [0115] **55** Roof [0116] **60** Antenna attachment structure [0117] **61** Base body [0118] **62** Attaching member [0119] **63** Antenna support post [0120] **64** GNSS antenna

#### Claims

1. A construction machine, comprising: a lower traveling body; and an upper revolving body revolvably supported by a lower traveling body, wherein the upper revolving body includes an operator seat, a roof disposed above the operator seat, a pair of rear support columns, extending upward from a rear section of the upper revolving body, and supporting the roof, a first GNSS antenna support post which is to be attached to a first GNSS antenna at a top end of the first GNSS antenna support post, is connected to the first rear support column, extends upward, and located outside of the roof and between the rear section and a front section which is located at an opposite side from the rear section, and wherein, in a plan view, the roof is positioned off center of the upper revolving body towards one end, the one end being an opposite end where the first GNSS support post is located.

2. The construction machine according to claim 1, wherein the upper revolving body further includes a second GNSS antenna support post which is to be attached to a second GNSS antenna at

a top end of the second GNSS antenna support post, is connected to the second rear support column, extends upward, and located outside, wherein the top end of the second GNSS antenna support post is positioned closer to the roof than the top end of the first GNSS antenna support post is.

**3.** The construction machine according to claim 1, wherein at least a part of the first GNSS antenna support post is parallel to the pair of rear support columns.

**4.** The construction machine according to claim 2, wherein at least a part of the second GNSS antenna support post is parallel to the pair of rear support columns.

**5.** The construction machine according to claim 1, wherein the first GNSS antenna support post is located at a right side of the roof which is a side between the rear section and the front section.

**6.** The construction machine according to claim 2, wherein the first GNSS antenna support post and the second GNSS antenna support post are configured as a pair.

**7.** The construction machine according to claim 1, wherein the first GNSS antenna support post is connected to a first rear support column via a base body.

**8.** The construction machine according to claim 2, wherein the second GNSS antenna support post is connected to a second rear support column via a base body.

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