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Systems and Methods for Live Culture Incubation and Monitoring

Abstract

In some examples, a system for cell incubation and imaging includes a first housing around a chamber. The chamber receives a culture. The first housing includes a light-transmissive first imaging access port. The system includes a chamber environment interface that controls a property of an environment within the chamber to maintain the property within a predetermined range (for incubation of the culture). The system includes a chamber environment sensor that measures the property to verify that the property is maintained within the predetermined range. The system includes a sensor within a second housing. The second housing includes a light-transmissive second imaging access port. The sensor captures a representation of the culture through the two imaging access ports while the first housing is detachably coupled to the second housing and while the property of the environment within the chamber is maintained within the predetermined range.

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Background/Summary

CROSS-REFERENCE TO RELATED APPLICATIONS [0001] This application claims the benefit of U.S. Provisional Application No. 63/553,126, filed Feb. 13, 2024, and titled “Systems and Methods for Live Culture Incubation and Imaging,” which is hereby incorporated by reference in its entirety and for all purposes.

BACKGROUND

Field of the Invention

[0002] The present disclosure generally pertains to live culture incubation, perfusion, and/or imaging systems. More specifically, the present disclosure pertains to culture systems that control properties of an environment in a chamber that includes a cell culture to maintain the property within a predetermined range associated with incubation of the cell culture, as well as imaging systems that capture image data of the cell culture over time as the culture systems continue to incubate the cell culture.

Background

[0003] Cells are the fundamental units of life. Cells make up tissues, which then make up organs and organisms. Therefore, observing cells, tissues (e.g., including 3D organoids and/or 3D spheroids) and organs have allowed researchers make significant scientific and economic relevant discoveries in the fields of biology, agriculture, ecology, healthcare, environmental sciences, geology, to name a few. While cells and tissues can be observed in living or ‘fixed’ non-living formats, observing living cells and tissue cultures (mammalian and non-mammalian) have become an essential platform utilized in fundamental cell & tissue biological research, clinical research, drug discovery, disease research, virology, regenerative medicine and/or all domains where a scientist needs to study live cellular and tissue moieties outside the animal organism.

SUMMARY

[0004] Systems and methods are described for cell incubation and/or imaging. In some examples, a system includes a first housing around a chamber. The chamber receives a culture. The first housing includes a first imaging access port that is light-transmissive. The system includes at least one chamber environment interface that controls a property of an environment within the chamber to maintain the property within a predetermined range. Therein the predetermined range is associated with incubation of the culture. The system includes at least one chamber environment sensor that measures the property of the environment within the chamber to verify that the property is maintained within the predetermined range. The system includes at least one sensor within a second housing. The second housing includes a second imaging access port that is light-transmissive. The at least one sensor captures a representation of the culture within the chamber through the first imaging access port and the second imaging access port while the first housing is detachably coupled to the second housing and while the property of the environment within the chamber is maintained within the predetermined range.

[0005] In some aspects, the techniques described herein relate to a system for culture processing. The system includes a first housing around a chamber. The chamber receives a culture. The first housing includes a first imaging access port that is light-transmissive. The system includes at least one chamber environment interface that controls a property of an environment within the chamber to maintain the property within a predetermined range. The predetermined range is associated with incubation of the culture. The system includes at least one chamber environment sensor that measures the property of the environment within the chamber to verify that the property is maintained within the predetermined range. The system includes at least one sensor within a

second housing. The second housing includes a second imaging access port that is light-transmissive. The at least one sensor captures a representation of the culture within the chamber through the first imaging access port and the second imaging access port while the first housing is detachably coupled to the second housing and while the property of the environment within the chamber is maintained within the predetermined range.

[0006] In some aspects, the techniques described herein relate to a method of culture processing. The method includes receiving a culture into a chamber within a first housing. The first housing includes a first imaging access port that is light-transmissive. The method includes controlling a property of an environment within the chamber using at least one chamber environment interface to maintain the property within a predetermined range. The predetermined range is associated with incubation of the culture. The method includes measuring the property of the environment within the chamber using at least one chamber environment sensor to verify that the property is maintained within the predetermined range. The method includes capturing a representation of the culture within the chamber using at least one sensor through the first imaging access port and a second imaging access port while the first housing is detachably coupled to a second housing and while the property of the environment within the chamber is maintained within the predetermined range. The second housing includes the at least one sensor and the second imaging access port that is light-transmissive.

[0007] In some aspects, the techniques described herein relate to a non-transitory computer readable storage medium having embodied thereon a program, wherein the program is executable by a processor to perform a method of culture processing. The method includes receiving a culture into a chamber within a first housing. The first housing includes a first imaging access port that is light-transmissive. The method includes controlling a property of an environment within the chamber using at least one chamber environment interface to maintain the property within a predetermined range. The predetermined range is associated with incubation of the culture. The method includes measuring the property of the environment within the chamber using at least one chamber environment sensor to verify that the property is maintained within the predetermined range. The method includes capturing a representation of the culture within the chamber using at least one sensor through the first imaging access port and a second imaging access port while the first housing is detachably coupled to a second housing and while the property of the environment within the chamber is maintained within the predetermined range. The second housing includes the at least one sensor and the second imaging access port that is light-transmissive.

[0008] In some aspects, the techniques described herein relate to a system for culture processing. The system includes means for receiving a culture into a chamber within a first housing. The first housing includes a first imaging access port that is light-transmissive. The system includes means for controlling a property of an environment within the chamber using at least one chamber environment interface to maintain the property within a predetermined range. The predetermined range is associated with incubation of the culture. The system includes means for measuring the property of the environment within the chamber using at least one chamber environment sensor to verify that the property is maintained within the predetermined range. The system includes means for capturing a representation of the culture within the chamber using at least one sensor through the first imaging access port and a second imaging access port while the first housing is detachably coupled to a second housing and while the property of the environment within the chamber is maintained within the predetermined range. The second housing includes the at least one sensor and the second imaging access port that is light-transmissive.

[0009] This summary is not intended to identify key or essential features of the claimed subject matter, nor is it intended to be used in isolation to determine the scope of the claimed subject matter. The subject matter should be understood by reference to appropriate portions of the entire specification of this patent, any or all drawings, and each claim.

Description

BRIEF DESCRIPTION OF THE DRAWINGS

[0010] Illustrative embodiments of the present application are described in detail below with reference to the following figures:

[0011] FIG. 1 is a cutaway architecture diagram illustrating an incubator system, according to some examples;

[0012] FIG. 2 is a cutaway architecture diagram illustrating an imaging system, according to some examples;

[0013] FIG. 3 is a cutaway architecture diagram illustrating the incubator system and the imaging system combined to form an incubation and imaging system, according to some examples;

[0014] FIG. 4 is a flow diagram illustrating an exemplary process for performing long-term cell or tissue culture incubation using the incubator system, according to some examples;

[0015] FIG. 5 is a flow diagram illustrating an exemplary process for performing long-term cell or tissue culture imaging using the incubation and imaging system, according to some examples;

[0016] FIG. 6 includes exploded perspective views of the incubation and imaging system, according to some examples;

[0017] FIG. 7 is a perspective view of the bottom module of the incubator system, according to some examples;

[0018] FIG. 8 is a cutaway architecture diagram illustrating the incubation and imaging system, according to some examples;

[0019] FIG. 9 includes a front view of the incubation and imaging system, a perspective view of the incubation and imaging system, and a side view diagram of a gas cartridge, according to some examples;

[0020] FIG. 10 includes internal views of internal components of the incubation and imaging system, according to some examples;

[0021] FIG. 11 includes internal views of internal components of the incubation and imaging system, according to some examples;

[0022] FIG. 12 is a user interface diagram illustrating a dashboard interface for visualizing data from an incubation and imaging system, according to some examples;

[0023] FIG. 13 includes block diagrams illustrating two approaches to regulate and inject controlled quantities of gas into the incubated chamber, according to some examples;

[0024] FIG. 14 is a perspective view of an incubation and imaging system in which the imaging system is on top of the incubator system, and various internal components are visible, according to some examples;

[0025] FIG. 15 is a perspective view of a cell culture setup to perform in-vitro neuronal recordings on microelectrode arrays, according to some examples;

[0026] FIG. 16 is a conceptual diagram illustrating various features of the incubation and imaging system, according to some examples;

[0027] FIG. 17 is an example of a phase contrast image (modified to be viewable in black and white) of MCF10A wild type cells successfully cultured in the incubator system and imaged, according to some examples;

[0028] FIG. 18 is a conceptual illustration of an incubation and imaging system performing multimodal neuronal stimulation and microscopy, according to some examples;

[0029] FIG. 19 is a perspective diagram illustrating an imaging system, according to some examples;

[0030] FIG. 20 is a cross-section diagram illustrating an imaging system, according to some examples;

[0031] FIG. 21 is a perspective diagram illustrating an incubation and imaging system, according

to some examples;

[0032] FIG. **22** is a block diagram illustrating an example of a machine learning system for training, use of, and/or updating of one or more machine learning model(s) that are used to generate analysis and/or recommendation(s), in accordance with some examples;

[0033] FIG. **23** is a flow diagram illustrating a process for cell incubation and imaging, in accordance with some examples.

[0034] FIG. **24** is a block diagram of an exemplary computing device that may be used to implement some aspects of the technology.

DETAILED DESCRIPTION

[0035] It is to be understood that the disclosed subject matter is not limited in its application to the details of construction and to the arrangements of the components set forth in the following description or illustrated in the drawings. The disclosed subject matter is capable of other embodiments and of being practiced and carried out in various ways. Also, it is to be understood that the phraseology and terminology employed herein are for the purpose of description and should not be regarded as limiting. As such, those skilled in the art will appreciate that the conception, upon which this disclosure is based, may readily be utilized as a basis for the designing of other structures, methods, and systems for carrying out the several purposes of the disclosed subject matter. Therefore, the claims should be regarded as including such equivalent constructions insofar as they do not depart from the spirit and scope of the disclosed subject matter. Although the disclosed subject matter has been described and illustrated in the foregoing exemplary embodiments, it is understood that the present disclosure has been made only by way of example, and that numerous changes in the details of implementation of the disclosed subject matter may be made without departing from the spirit and scope of the disclosed subject matter.

[0036] Systems and methods are disclosed for cell culture incubation, imaging, and management. In some examples, a system for live cell and tissue culture imaging includes of an incubation subsystem and an imaging subsystem. The incubation subsystem allows for long-term live cell or tissue culture incubation at controlled environmental conditions, for instance including temperature, relative humidity, and gas concentrations. The imaging subsystem allows for long-term live culture imaging and subsequent analysis using on-system computing and online cloud-based computing modalities. The subsystems are battery-powered and light-weight, allowing for portability of live cultures between user locations. The user loads live cultures into the incubator subsystem and can physically, optically and electrically integrate it with the imaging subsystem to commence live culture analysis. The imaging subsystem, which is anti-vibration stabilized, performs rough and fine auto-focusing, while initiating time-lapse camera-based data acquisition. On-board analysis of raw camera data is performed on high-speed computing subsystems, allowing for high frame-rate analysis. Online cloud-connectivity pipelines provide for remote analytics of incubation and imaging functions.

[0037] Sustaining, manipulating and analyzing live cells and tissues, allows the researcher to gain rich insights over longer time-frames and make discoveries. In accordance with some embodiments of the present disclosure, a modular cell and tissue incubator subsystem is disclosed herein that utilizes minimal bench-space and is cost-effective, such that individual researcher can have ‘personal’ units on their respective lab bench, thereby reducing potential for contamination between researchers. Integration of simple and safe miniature gas supply sources (cartridges) inside the incubator subsystems itself thereby relieves the researchers from having to coordinate large gas tank hookups to walls with facilities support, also increasing general lab safety. In some embodiments, the incubator subsystem is battery powered and operable at low DC voltages. Chamber volumes are minimized to satisfy culture dish sizes and lowering gas supply cost. In some examples, an imaging system is integrated with the incubator system, so that the cell cultures can be imaged as the incubator continues to incubate the cell cultures.

[0038] Visualizing cells and tissues with high-magnification time-lapse video is especially valuable

in dynamic studies such as, but not limited to, drug-effects on mitigating cancer progression, neuronal degeneration, metabolic syndromes, viral progression and immunological responses. Along with rapid advancements in areas such as gene editing, stem-cell and tissue engineering, cell and gene therapy, laboratories are in need to efficiently sustain, monitor and analyze precious cells and tissues. In some examples, systems and methods described herein may use image analysis pipelines (e.g., CellProfiler, ImageJ). In some examples, systems and methods described herein may use ultra-fast parallel computing on graphical processing units (GPUs), image analysis using machine learning and/or artificial intelligence, and/or other techniques, for rich information gathering and analysis from biological image-based data.

[0039] In some evolving healthcare scenarios (such as Advanced Therapy Medicinal Products ATMP), cell and tissue cultures need also to be transported from the patient sites and/or bio-repositories, to local and global collaborator sites. Alternatively, laboratories working jointly on unique problems, can want to share their cell lines and tissues of interest within departments, universities, divisions and/or organizations located in different states and perhaps even countries. However, transportation of cells and/or tissues between labs (and especially when distances are greater than a few miles), is traditionally conducted cryogenically in liquid nitrogen and/or on dry ice, both of which are logistically challenging and can hamper the viability of the cells and/or tissues, given the nature of the freeze-thaw cycle.

[0040] In some examples, an exemplary researcher workflow for a scientific lab can include extracting cells or tissues from a diseased organism, a normal organism (e.g., non-diseased), a biological repository, another laboratory, or a combination thereof. The workflow can include placing the cells or tissues in one or more petri dishes (in any of a set of different physical formats), with an appropriate amount of cell culture media (comprising of nutrients, serum, pH indicators and buffers) and in some cases with experimental reagents of interest. The workflow can include placing the petri-dish in an incubation environment, which maintains control of temperature (e.g., within a range around 37 degrees C. for mammalian cells, but can vary), relative humidity (e.g., >60%) and gas composition (e.g., a specified distribution of Carbon dioxide, Nitrogen, and/or Oxygen at respective concentration percentages) to specified control points. The workflow can include observing the cells or tissues over time via a modality such as microscopy and/or, in some cases, biochemical or neural recording. These observations can last a few seconds to several weeks or months (in case of some cell types such as primary neurons and stem cells). The workflow can include analyzing every recorded data (images and/or other biochemical, molecular and/or physiological signals). The workflow can include testing scientific hypothesis and/or making discoveries relevant to the experimentation.

[0041] There are several challenges in scientific lab research workflows. The challenges in research workflows include that cell and/or tissue culture incubators tend to be shared by multiple researchers, given their limited availability due to high price and space constraints. This can lead to microbial contamination between researchers (e.g., between experiments), potentially ruining valuable experimentation. The challenges in research workflows include that traditional cell and tissue culture incubators are bulky (e.g., often the size of small refrigerator or larger), therefore not portable, often operated at high 110/220 AC voltage. Generally, if a researcher wants to transport their cell and/or tissue cultures, the researcher has to remove the cultures from the incubator and quickly move the cultures to the destination. Cells and/or tissues can be very sensitive to environmental conditions, and if transportation is prolonged, can lead to loss of experimentation and/or false results. Sharing of cells and tissues in liquid nitrogen and/or on dry ice is logistically challenging. The researcher has to have access to liquid nitrogen and/or dry ice to transport cultures safely, which is not readily available in many countries. They will always need to disrupt the cells and tissues native environment (such as breaking them away from their adherent surface and/or replacing the culture media with additional cryo-protectants). At the destination site too, there are requirements for the receiving party to handle the shipment safely, thaw the cells and tissues to

culture the cells and tissues back, all of which can lead to loss of viable cells.

[0042] Furthermore, given a requirement to control gas composition and percentages at specified levels, cell and tissue incubators typically depend on an external tank(s) of gas, which can cause additional challenges in research workflow. This supply line is piped into the incubator and attached via pneumatic couplers. Given the large chamber volumes of incubator (e.g., >1 cubic ft), these supply tanks are typically large (e.g., greater than 5 pounds, in some examples 50 pounds) and are securely affixed to the walls next to the incubator with chains. This severely limits the portability of cells and tissues in a controlled environment, it also requires regular facilities support to install and monitor any safety concerns. Additionally, given the large volumes of the incubation chamber, gas requirements increase usage costs.

[0043] Another challenge in research workflows is that traditional cell and tissue incubators are not equipped with imaging components (e.g., microscopy components). Thus, a researcher using a traditional incubator has to remove their cells and tissue cultures from the incubator and quickly load the cells onto a nearby microscope to take images and/or videos, before rapidly bringing the cells back into the incubated environment. This severely limits how, and for how long, the researcher can do long-term microscopy without disturbing the cell and tissue environment. For instance, in some cases, the researcher is limited to imaging the cells for a few hours or (on rare occasions) days, but cannot image the cells for longer periods of time (e.g., weeks or months) without disturbing the cell and tissue environment, potentially damaging or even killing the cells. In some examples, a microscope may be encased in a 'case' incubator positioned around a microscope, a 'stage' incubator may be placed on a microscope, and/or the microscope itself may be placed within a large incubator. However, without further integrations (such as those discussed herein), such combinations can limit compatible devices, limit available resources, and do not provide systematic integrations between the incubator and the microscope to control the culture conditions and microscopy conditions, leading to inefficient workflows. In some examples, for instance, image focus losses can be caused by spatial temporal temperature shifts between the culture and optical system environments, in some cases requiring special objective lens heaters to compensate for the z-focus drifts. Such combinations can also remain dependent on large fixed gas tanks and/or bulky equipment that is not portable.

[0044] Even if a researcher is able to perform long-term cell and/or tissue microscopy and acquire digital assets, traditional instruments (e.g., microscopes) are not able to, by themselves, process the images and/or videos (e.g., high-resolution images at high frame rates) that they capture, and thus, a user may have to store raw data files on isolated hard-disks-another challenge of research workflows. Even if the financial issue of storage costs is overcome, a major hurdle of analyzing massive data volumes and transfer to off-system compute environment remains. For example, at 25 fps and a moderate 5M pixel resolution, with low 8-bit image depth, a single day of imaging can yield >10 TB of raw data. These storage amounts climb exponentially with higher number of experimental days, higher camera resolutions, richer and more color depth, and/or greater frame rates (e.g., which may be required to capture certain cellular events that happen in a millisecond or less). Thus, storage and/or analysis of data can quickly become a bottleneck in experimentation, can greatly reduce throughput of an experiment, speed of analysis, and/or flexibility of research hardware. In some cases, this issue can push a researcher to reduce image resolution and/or frame rate below what they would like to use, which may cause the researcher to fail to capture important events.

[0045] In some cases, research workflows involve a need to interface with the cell cultures while the cell cultures are under incubation. These interfaces can include, but are not limited to, the need to perfuse the cell and tissue culture media regularly, add or remove manipulation reagents for controlled experimental perturbation and/or for creating specific imaging conditions, perform neuronal recordings using micro-electrode arrays embedded within the culture dishes. These interfaces are therefore fluidic, electrical, optical and/or pneumatics based. In some examples, the

interfaces are co-located next to the incubators, but not integrated, which further restricts portability. In some examples, interface lines can be awkwardly positioned, restricting access into the incubator and/or creating sealing issues. All of these can be issues with traditional research workflows.

[0046] As noted above, in some examples, challenges in research workflows can include sharing cell and tissue culture incubators and imaging systems, which can lead to contaminated cell cultures. Challenges can include the fact that traditional incubators, gas tanks, and/or microscopes are large and bulky and are generally not compatible with one another, and thus each take up precious lab space and need facilities support (e.g., for large gas tank delivery and high voltage AC power hook-up), limiting what experiments users can run and increasing utility costs. Challenges in research workflows can include traditional incubators, gas tanks, and/or microscopes not being compatible with one another and not being portable, meaning that cells generally must be moved frequently between devices and sometimes between buildings or longer distances (e.g., to a different country). Cell and tissue cultures often get destroyed during inter-lab transfer to core microscopy facilities. Inter-lab cell and tissue culture sharing, particularly across geographic regions, is a logistical problem, with freezing, thawing, and/or other travel-related disturbances leading to loss of viability of cells. Challenges in research workflows can include that traditional solutions for long-term live cell culture microscopy are not integrated with traditional incubator solutions, generally requiring a user to remove cells from the incubator to allow the cells to be imaged. Challenges in research workflows can include that traditional microscopes do not perform real-time in-system image analysis, instead requiring enormous amounts of data to be stored and/or analyzed on a different device, leading to large data bottlenecks. Challenges in research workflows can include that traditional systems can limit external world interactions and/or manipulations of cell and tissue cultures via fluidic, optical, mechanical and electrical stimuli, for instance requiring cells to be removed from an incubator for any interactions and/or manipulations.

[0047] Systems and methods described herein overcome these challenges to empower the usage of long-term live cell and tissue culture incubation and analysis into high-impact areas such as research efforts in academia, government, industry and within service-based CRO units, and in science education in school, college and university settings. The systems and methods described herein augment research and discovery efforts, and empower the strengthening of education domestically and internationally. For instance, the systems and methods described herein allow for cell and tissue cultures to be readily analyzed within laboratories, and for cell and tissue cultures to be shared in their native environment across geographical borders (e.g., maintained in an incubation environment during travel), allowing for greater outreach and collaboration.

[0048] The systems and methods described herein further provide for reduced opening and closing of incubator doors, which change environmental conditions impacting cell cultures within minutes and cause variability of scientific results. For instance, integration of an imaging system with an incubator means that cell cultures can remain in the incubator while the imaging module captures images, videos, and/or other sensor data from the cell cultures. Real-time monitoring of the cell cultures further provides enhanced reliability and flexibility, allowing the system to capture images and/or videos (and/or other representations) of rare occurrences (e.g., by allowing for longer-term imaging), allowing the system to continue incubating the cell culture (e.g., keeping the cell culture alive) and monitoring the cell culture even without any human interaction (e.g., allowing users to perform other tasks or take a break, for instance for a holiday) or with minimal human interaction (e.g., to change a setting remotely using user device coupling to the incubator and/or imaging system over a network and/or via a cloud service).

[0049] Systems and methods are described for cell incubation and/or imaging. In some examples, a system includes a first housing around a chamber. The chamber receives a culture (e.g., a cell culture). The first housing includes a first imaging access port that is light-transmissive (e.g., is transparent, translucent, and/or includes a hole or aperture in the first housing). The system

includes at least one chamber environment interface that controls a property (e.g., temperature, humidity, pressure, pH, fluidic flow rate, orientation, level of illumination, gas concentration, liquid concentration, reagent concentration, etc.) of an environment within the chamber to maintain the property within a predetermined range. Therein the predetermined range is associated with incubation of the culture. The system includes at least one chamber environment sensor that measures the property of the environment within the chamber to verify that the property is maintained within the predetermined range. The system includes at least one sensor within a second housing. The second housing includes a second imaging access port that is light-transmissive (e.g., is transparent, translucent, and/or includes a hole or aperture in the second housing). The at least one sensor captures a representation of the culture within the chamber through the first imaging access port and the second imaging access port while the first housing is detachably coupled to the second housing (e.g., via latches, magnets, pins into recesses, screws, clips, slide rails, elastic, seals, hook and loop fasteners, stud fasteners, other types of fasteners, or combinations thereof) and while the property of the environment within the chamber is maintained within the predetermined range (e.g., by the chamber environment interface).

[0050] Cell incubation and/or imaging systems can include various improvements, various limitations, or combinations thereof. In a first illustrative example, a small incubation unit (e.g., 22×22×22 cm, weighing 3.6 kg) can be placed inside a microscopy unit. However, in some cases, such a system can still require large CO₂-fillable tanks, can be operated at high AC voltage of 220V (not battery powered), can lack on-board sensors and real-time sensor connectivity to track and monitor incubation performance, can lack incorporation of on-system live frame computing, and/or can lack a way to add additional interfaces (electrical, perfusion, optical and pneumatic). In a second illustrative example, a small live cell culture incubator device (e.g., the size of a travel suitcase) can allow for improved travel, but can still be limited by lacking any imaging modality and/or lacking means to actively supply gas (e.g., depending on an initial equilibration of carbon dioxide CO₂ using a larger incubator), reducing transport time capability given environmental degradation of the desired gas composition. A small incubator device, on its own, still lacks integration of incubation with imaging modalities and/or image-based data analytic capabilities while the cells are in an incubated environment. In a third illustrative example, a small incubator device can control for gases (e.g., carbon dioxide (CO₂) and/or nitrogen (N₂)) (e.g., for air composition), with CO₂ and N₂ gases still supplied from externally placed tanks and not integrated within the system, limiting portability and effective travel range. In some examples, an incubator may rely on dry ice, which can sublime over time and further limit portability and effective travel range. In a fourth illustrative example, a microscope can be placed in a large incubator (e.g., with large wall-mounted gas tanks), however such a combination is not portable.

[0051] Systems and methods described herein provide advanced solution(s) for cell & tissue culture incubation, imaging, analysis and inter-lab sharing of cultures in their native environment (e.g., in an incubation environment). Systems and methods described herein allow for easy-to-use, inexpensive, portable, lab-bench compatible, modular, cloud-connected for real-time and longitudinal analytics and on-board rich computing resources coupled to high-magnification and/or high-frame rate imaging modalities.

[0052] FIG. 1 is a cutaway architecture diagram illustrating an incubator system **100**. The incubator system **100** can be referred to as a portable cell and tissue incubator system, or an incubation subsystem. In some examples, the incubator system **100** can be referred to as an incubator subsystem or an incubation subsystem, for instance when the incubator system **100** is used as a subsystem of a combined incubation and imaging system (e.g., incubation and imaging system **300** of FIG. 3).

[0053] FIG. 1 shows an embodiment of the major subsystems, components and interfaces of the incubator system **100**. In the presented embodiment, the incubator system **100** includes a top module **101** and a bottom module **102**, which can come together to close or be separated to open

the incubated chamber **139**. The top module **101** and bottom module **102** are physically separated by a surface **138** and a chamber seal **118** (e.g., with a reversible sealing mechanism), both of which can reside within the top module **101** (but can also reside with the bottom module **102**). The separation surface **138** allows for physical interfaces to occur between the top module **101** and bottom modules **102**. The separation surface **138**, via the aid of the chamber seal **118** (e.g., the reversible sealing mechanism), allows for the user to open and close the incubator system **100** to gain access to the incubated chamber **139**, using handle features **116** provided on the top module **101**. A proximity sensor **141** allows for monitoring the separated or closed state of the top module **101** from the bottom module **102**. In some examples, the incubator system **100** includes anti-vibration legs **136**, which reduce external vibrations from entering the subsystem and improving the performance and operational reliability of the subsystem. In some examples, the incubator system **100** includes alignment features **137**, such that the subsystem can be physically docked with other subsystems of varying type (such as the imaging system **200**). Such alignment features can be readily implemented using pin and socket mechanical features and can also be magnetic in nature for increased hold. In some examples, alignment and/or docking can be implemented with snap-and-release mechanisms or with electronic activated latches.

[0054] In some examples, the bottom module includes an imaging access port **129** (e.g., microscopy access port), to allow for a transparent path for microscopy of the cell and tissue culture dish **128**, when the incubator system **100** is docked on top of an imaging system **200**. The imaging access port **129** can be referred to as a microscopy access port. In this embodiment, there is a provision to maintain a chamber seal **140** (using but not limited to sealing gaskets, silicone o-rings or sealing gels) between the culture dish **128** and the incubated environment in the incubated chamber **139**, such that only the bottom of the culture dish is exposed to the outside environment when the imaging access port **129** is opened. In some examples, the imaging access port **129** is not provided (e.g., missing), for instance when applications do not require microscopy or if the microscope is provided inside the incubated chamber **139** (as described in FIG. **14**). The entirety of the incubator system **100** is portable and handle features **119** provided on the bottom module **102**, further aid in doing so. In some examples, a handle strap may be included on the top module **101** and/or bottom module **102**, with a mechanical locking feature to keep both these subsystems together while transportation. To thermally isolate the incubated chamber **139**, all chamber exposed surfaces of the top module **101** and bottom module **102**, are lined with an insulating material **122**. The insulated material can be made of, but not limited to, materials such as fiberglass, foam and ceramic fillings or with specially designed 3D printed materials with insulation properties, or combinations thereof. While shown in FIG. **1** is an embodiment where the top module **101** is placed on top of the bottom module **102**, alternative embodiments may have the subsystems placed side by side or in reverse order. Alternatively, also the incubated chamber may have a separate and reversibly sealed access door to load and unload the culture dish **128**, without having to separate the top and bottom modules. Such an additional access door may provide further reduction of environmental changes during culture dish exchanges.

[0055] The culture dish **128** may include a cell culture, which can include, in some examples, one or more cells, tissues, organoids (e.g., 3D organoids), spheroids (e.g., 3D spheroids, organs, portions of any of the previously-listed materials, or combinations thereof. In some examples, the culture dish **128** may include media that the cell culture is grown within and/or perfused into.

[0056] In some examples, the physical interfaces between the top module **101** and bottom module **102** include an electrical interface subsystem **131**, a fluidic interface subsystem **127** and a pneumatic interface subsystem **117**, all of which reside on the separation surface **138**. In some examples, the fluidic interface subsystem **127** may not be necessary; if no fluid exchange is needed for the incubator subsystem application. The interfaces are air-tight sealed best possible using off-the-shelf gaskets, adhesives and/or washers (not shown) through the separation surface **138**, to ensure that the incubated chamber **139** remains isolated from the external environment.

[0057] In some examples, the electrical interface subsystem **131**, the pneumatic interface subsystem **117**, and/or the fluidic interface subsystem **127** can reside entirely on (and/or in) the bottom module **102**, and can directly provide access to the incubated chamber **139**. In such examples, external systems can interface with the incubator system **100** via reversible fluidic, electrical and/or pneumatic connectors.

[0058] In some examples, the separation surface **138** includes a check valve **130** and/or a relief valve **142**. In some examples, the incubator system **100** can use the check valve **130** and/or the relief valve **142** to release gas(es) (e.g., air) from the interior of the incubated chamber **139** in the bottom module **102** (e.g., to the top module **101**, to the exterior of the incubator system **100**, and/or otherwise to the exterior of the incubated chamber **139**). In some examples, the check valve **130** and/or the relief valve **142** allow for air-escape when the top module **101** and bottom module **102** are closed together and sealed via the chamber seal **118** (e.g., the reversible sealing mechanism). The check valve **130** and/or the relief valve **142** allow for balancing the positive or negative pressure in the incubated chamber **139** (e.g., to be within a threshold range of atmospheric pressure), caused by either injection or removal of material into or out of the incubated chamber **139**. The electrical interface subsystem **131** includes electrical connectors for digital, analog and power signals to and from the thermal control subsystem **132**, chamber sensor subsystem **133**, optical subsystem **134** and a head stage interface **135**, that are present within the incubated chamber **139**. In some examples, the fluidic interface subsystem **127** includes fluidic ports to and from the culture dish **128** and the humidity wick **126** (or humidity stick). The humidity wick **126** is made of water retaining material which allows for evaporation and increasing the humidity inside the incubated chamber, such as but not limited to, a porous wick, sponge or towel and positioned at a designated humidity wick holder **123** (or humidity stick holder).

[0059] In some examples, a fluidic port may be used to inject mist into the chamber **139** to increase humidity, which can be accomplished by pressurizing water through fine nozzles. In some instances, instead of a humidity wick, water can be dropped onto a small ultrasonic element that in turn then creates mist inside the chamber.

[0060] In some examples, the fluidic interface subsystem **127** may be present in the incubator system **100**. In some examples, the fluidic interface subsystem **127** may be missing in the incubator system **100**, for instance if the application does not require reagent exchanges, and/or if humidity control is achieved by simply wetting the humidity stick, prior to closing the chamber, without active delivery of water to the stick. The pneumatic interface subsystem **117** includes through-panel mechanical ports for gas input or sampling out of the incubated chamber **139**. In some examples, the pneumatic interface subsystem **117** include additional ports to allow for calibrated gas to be purged into the incubated chamber **139** for gas sensor calibration. While a single electrical interface, fluidic interface and pneumatic interface is depicted in FIG. **1**, the interfaces themselves may be partitioned and spatially distributed across the separating surface **138** to aid for compact design.

[0061] In some examples, the thermal control subsystem **132** is placed within the incubated chamber **139** includes a heating element, cooling element and a circulating effector such as a convective fan or blower. In some examples, a cooling element may not be necessary to arrive at temperature set-points and only a heating element is provided. Heating and cooling elements may be implemented using a wide variety of electronic components, including but not limited to, peltier-based thermoelectric heater-cooling, resistive heaters and ceramic heating. There may be one or several heating elements, cooling elements and/or convective elements placed inside the incubated chamber to accomplish uniform heat distribution. In some examples, the thermal control subsystem may be placed outside the incubated chamber **139** and in the top module **101**, to reduce electronics within the incubated chamber. In such an arrangement, a blower may push heated or cooled air into the chamber to arrive at the temperature set-point.

[0062] In some examples, the chamber sensor subsystem **133** is placed within the incubated

chamber **139** includes gas sensors, temperature sensors and humidity sensors. In some examples, a Carbon dioxide and/or an Oxygen gas sensor is/are configured. In some examples, both a Carbon dioxide and an Oxygen gas sensor are configured. In some examples, additional gas sensors (such as gas sensor(s) for Nitrogen and/or other gases) may also be included. In some examples, single temperature and relative humidity sensors are configured. In some examples, multiple temperature and relative humidity sensors are implemented to sense these parameters at different spatial points of the incubated chamber **139**. As shown in FIG. **1**, an illustrative example is for the chamber sensor subsystem **133** to be placed within the incubated environment as to sense these environmental parameters directly. However, in some examples, the chamber sensor subsystem **133** entirely or some of its component may be placed outside the incubated chamber **139** and in the top module **101**. In such an arrangement, a sample of environmental air can be pulled outside using a sampling pump and onto the sensors.

[0063] In some examples, the optical subsystem **134** is placed with the incubated chamber **139**, and comprising of an illumination source for microscopy that is positioned above the culture dish **128**. Such an illumination source can be implemented using, but not limited to, an array of light-emitting diodes in a rectangular or ring orientation, and operated in a continuous ON mode and/or in a pulsed-mode. When activated, the illumination sourcing (e.g., illumination source **204**), which may be coupled to additional optical elements such as condenser lenses and filters, floods the culture samples for bright-field imaging, dark-field imaging, fluorescence imaging, and/or phase-contrast imaging (e.g., in conjunction with an imaging system **200**). In some examples, the optical subsystem may include both the illumination source and optical lenses to confer upright microscopy of the culture samples placed in the culture dish **128**.

[0064] In some examples, a culture dish holder **125** or a plurality of such holders stacked onto each other, can be placed inside the incubated chamber **139**. Each culture dish holder **125** can have designated locations to hold one or a plurality of culture dishes **128**. In an illustrative example, both the culture dish holder **125** and the culture dish **128** can be easily unloaded by the user outside the incubated chamber **139**. However, alternative embodiments may fix the culture dish holder **125** within the incubated chamber, with the user having to load and unload the culture dish into the holder. In some examples, the culture dish holder **125** may also carry the humidity wick holder **123**, which can hold a humidity wick **126**. In some examples, the bottom module **102** (e.g., the incubated chamber **139**) can include other water storing components that allow for passive or active (such as the ultrasonic mist generation component described above) release and/or increase of humidity in the incubated chamber **139**, such as humidifiers with water tanks or reservoirs. In some examples, the bottom module **102** (e.g., the incubated chamber **139**) can include a dehumidifier to absorb or otherwise reduce humidity in the incubated chamber **139**. The culture dish holder can be placed on an anti-vibration component (e.g., anti-vibration legs **136**), to prevent the culture dish from experiencing external vibrations and movement impacts when the incubator system **100** is transported around by the user.

[0065] In some examples, the culture dish is a standard round petri-dish. In some examples, the culture dish **128** can take different formats used in laboratories such as well-plates (with multiple culture wells), tissue culture flasks, perfusion cassettes, culture dishes with thin cover-glass at bottom for high-magnification imaging, microelectrode array dishes or microfluidic chips. If the application calls for fluidic exchange, the culture dish **128** may have input and output fluidic ports with fluidic lines coupled to the fluidic interface subsystem **127**, via plastic tubing, silicone tubing, and/or metal tubing. The culture dish **128** includes cells or tissues of the user's choice and with the added media, suited for the application.

[0066] In some examples, the head stage interface **135** (which may be referred to as an additional electrical interface) allows for expanding the functionality provided by the incubator system **100**. One such functionality is the ability to perform neuronal activity recordings using micro-electrode arrays (MEA). In such a scheme, the head stage interface **135** can connect to the MEA-based

culture dish and provide the electrical recording connectivity to the electrical interface subsystem **131**. Other such schemes can include monitoring ion-channel signals using pH electrode arrays embedded within the culture dish **128**. In another embodiment, the additional electronic interface may connect to a specially designed culture dish holder that has an array of ultraviolet lights that are used to illuminate the incubated chamber and provide a means for contamination control. In yet another embodiment, the head stage interface **135** may connect to a special culture dish holder that has a micro-bacterial reagent mister to provide the means for contamination control. In yet another embodiment, the head stage interface **135** may connect to a special culture dish holder that has additional heating elements to induce a high-temperature sterilization cycle. In yet other embodiments, the head stage interface **135** may connect to a special culture dish holder that has additional sensors to expand the functionality of the chamber sensor subsystem **133**.

[0067] In some examples, the top module **101** includes a DC power input **104**, a battery module **105**, a user interface subsystem **103**, a Controller subsystem, a System sensor subsystem **108**, a fluidic subsystem **109** and a Gas subsystem **112**. In some examples, a fluidic subsystem **109** may not be included in the incubator system **100**, for instance if an application (for which the incubator system **100** is to be used) does not required active reagent exchanges.

[0068] In some examples, the DC power input **104** allows for plugging into an external supply to power the incubator system **100** and charge the battery module **105**. When the DC power input is unplugged, the incubator system **100** continues to be powered by the battery module **105**. The battery subsystem can be made of rechargeable material, such as but not limited to, Lithium-ion, Lithium-poly, Nickel-Metal Hydride or Nickel-Cadmium. In some examples, the unit may be powered by a single-use battery. In some examples, the battery module **105** powers the controller subsystem **106**, which then distributes power to the remaining subsystems in the top module **101** and electronic components in the incubated chamber **139**, via the Electrical interface subsystem **131**. In some examples, the battery subsystem may be connected to a power-distribution subsystem (not illustrated in FIG. 1), which in turn distributes the power.

[0069] In some examples, the controller subsystem **106** includes a micro-processor or micro-controller board that is pre-loaded with a firmware program. The firmware program comprises a command and data interface routine for communicating with the external world via the communication interface **107**. This routine accepts commands, such as but not limited to, set-points, calibration curves and configuration parameters to allow the user to control the incubator system **100**. The routine also transmits sensor data, events, warnings and logs to the user for monitoring incubator system **100** performances, functionality and reliability. The communication interface **107** provides a wireless (via protocols such as but not limited to Wifi, Bluetooth, Cellular) and/or wired (via protocols such as but not limited to USB, Ethernet, serial port, I2C, MOSI). The controller subsystem **106** also includes a core controller routine, which accepts the set-point information provided by the user, and along with chamber sensor subsystem **133** data, performs a close-loop feedback control to achieve environmental conditions inside the incubated chamber **139**. The controller subsystem **106** also includes an Alarm and event coordinator routine, to read sensor information from the system sensor subsystem **108** and warn the user of the state of the incubator subsystem. In some examples, the controller subsystem **106** may also include additional routines, such as adaptive machine learning for better control accuracy and/or storage capacity to allow temporary data storage in case of lost communications.

[0070] In some examples, a machine learning algorithm and/or model can monitor incubated chamber **139** temperature and change heating parameters in order to reduce the time it takes to arrive stably within a specified set-point. Inputs into the machine learning algorithm and/or model can include external environment temperature, past chamber open-close event history, heater component and fan life, relative humidity conditions, chamber gas concentration conditions, additional user provided information such as culture dish **128** type, size and/or count, current state and/or history of fluid exchanges via the fluid interface subsystem **127**, optical subsystem **134**

current state (e.g., image(s), video(s), and/or current capture settings) and/or history (e.g., previously captured image(s), video(s), and/or previous capture settings), current state and/or history of gas exchanges via the pneumatic interface subsystem **117**, current state and/or history of any addition electrical interfaces **135** present in the chamber. In some examples, a machine learning algorithm and/or model can predict the timing of empty/full state of the gas cartridge **114** and/or the reagent & waste cartridge **110**, by utilizing current and/or history of valve operation described in the gas subsystem **112**, pressure conditions recorded by the system sensor subsystem **108**, current state and/or history of fluid exchanges via the fluid interface subsystem **127** and/or chamber opening/closing event history. In some examples, a machine learning algorithm and/or model can predict battery module **105** charge capacities, the implementation of which would further aid the user to assess and/or plan available culture transport time without DC power input **104**. In some examples, the machine learning algorithm and/or model may utilize, as inputs, in-service battery life and performance history, external room environmental conditions, internal incubated environment chamber conditions, recent user behavior such as chamber opening/closing events, current state and/or history of power utilizations across the various subsystems within the incubated system **100**, current state and/or history of the thermal control subsystem **132**, current state and/or history of fluid exchanges via the fluid interface subsystem **127**, optical subsystem **134** current state and/or history, current state and/or history of gas exchanges via the pneumatic interface subsystem **117**, current state and/or history of any addition electrical interfaces **135** present in the chamber.

[0071] In some examples, the user interface subsystem **103** includes a display screen (such as but not limited to provide by an OLED array) and touch interface, providing the user the ability to observe limited, but key information about the incubated chamber **139** environment (such as, but not limited to, Temperature, Relative Humidity) on an ongoing basis. Using the touch interface, the user is also able to access a user configuration menu and interact with the incubator system **100** to address alarms, events and warnings provided by the controller subsystem **106**. In some examples, additional status lights, knobs, buttons and switches are provided to allow the user to quickly review status and set important parameters. In yet another embodiment, the user interface subsystem **103** provides neither display screen nor touchscreen, with most interactions conducted by a device-linked software application, via the communication interface **107**.

[0072] In some examples, the fluidic subsystem **109** includes a coupling interface to temporarily accept a reagent and waste cartridge **110**. The reagent and waste cartridge is user-loaded and comprising of label and handling feature to aid user to load cartridge correctly. The reagent side of the cartridge is coupled to its respective reservoir and connected via a set of pump and valve to deliver reagents to the fluidic interface subsystem **127**, and thereby into the culture dish **128**. Similarly the waste side of the cartridge is coupled to its respective reservoir and connected via a set of pump and valve to extract reagents from the fluidic interface subsystem **127**, and thereby from the culture dish **128**. In some examples, multiple reagent and waste cartridges are accepted to deliver different reagents into the culture dish **128**, via a plurality of fluidic pathways. In some embodiments, the reagent may be water to allow for active delivery of water droplets into the incubated chamber onto humidity stick **124** and/or onto an ultrasonic mister (not shown) added inside the chamber. In other embodiments, the reagent may be, but not limited to, a synthetic or biological drug, genetic manipulating agent, media, additional cells or staining chemicals. In some examples, the reagent and waste cartridges may be separated to compact the size by utilizing a single waste cartridge.

[0073] In some examples, the system sensor subsystem **108** includes (a) cartridge presence sensors used to detect the presence or absence of the reagent & waste cartridge **110** and the gas cartridge **114**, (b) gas pressure and/or flow sensors used to detect the remaining capacity of the gas cartridge **114**, (c) chamber state sensors used to detect the state of the chamber, such as but not limited to, incubated chamber open or close via the proximity sensor **141**, (d) tilt sensors used to detect

incubator system **100** orientations during placement on a surface or during transportation, and (e) external gas sensors, in the configuration when chamber gas is sampled and sensed outside the incubated chamber **139**. In addition to these sensors, additional identification sensors (not shown) can be implemented to confirm the authenticity of the cartridges and to prevent the system from faulty use conditions. In some examples, a plurality of these sensors can be implemented to match the plurality of cartridges.

[0074] In some examples, the gas subsystem **112** includes (a) a coupling interface **113** (e.g., coupling port) receiving a user-loadable gas cartridge **114**, and interfaced to a pressure regulator that has input pressure capacity of >1200 psi (and/or other gas tank pressures used for gas tank(s)). In some examples, the gas subsystem **112** can receive more than one gas cartridge **114**, for instance receiving different gas cartridges **114** with different gases in them. In an illustrative example, the gas subsystem **112** can receive a first gas cartridge **114** with carbon dioxide (CO.sub.2) and a second gas cartridge **114** with Nitrogen gas (N.sub.2). The gas subsystem **112** includes (b) a pressure regulator provides a stepped down pressure supply (e.g., a range of 0-20 psi). The gas subsystem **112** includes (c) a valve interfaced to the pressure regulator that opens or closes for a brief duration of time (e.g., a range of 0-5 seconds) and interfaces with a constricted pneumatic line. The valve outputs the gas towards the downstream constrictor, however, also includes a path to vent the pressurized gas to the atmosphere via a port **115**, if so chosen by the user. Such a need may arise if the user wishes to replace a cartridge prior to it being fully empty or if an incorrect cartridge was loaded. The gas subsystem **112** includes (d) a constricted pneumatic line implemented by, for instance, a miniature orifice or small ID tube, further controls the amount of gas supplied to the incubated chamber **139** via the pneumatic interface subsystem **117**. Control of gas injections ensures gas percentages do not overshoot the set-point. An alternative embodiment can incorporate a sampler pump in the gas subsystem **112** that allows for sampling the gas environment of the incubated chamber **139** and flooding external (outside incubated chamber **139**) gas sensors, while removing the need for maintaining gas sensors within the incubated chamber **139**. An alternative embodiment includes a plurality of gas cartridges either as a backup for the primary cartridge and/or comprised of different gases. Such an embodiment will require multiple regulators, however, may utilize a valve with multiple selectable input pathways and two outputs (one that is directed towards the constrictor and the other to the vent port **115**). In some examples, the incubator system **100** can include an ultra-fast valve (open and close times of <100 msec) that can eliminate the need for a downstream constrictor. In some examples, the gas subsystem **112** can include additional air purge pumps to purge the incubated chamber environment with atmospheric air and/or regulate the gas concentration in case of overshooting from set-point values. In some examples, the gas subsystem **112** can include controlled replenishment of atmospheric oxygen into the chamber, given that cell cultures consume oxygen which may get depleted in the environmental chamber **139**.

[0075] In some examples the gas cartridge **114** includes a male thread and frangible seal, which couples to a female thread and piercing port within the coupling interface **113**. The gas cartridge includes human-interface finger contoured features to aid twisting the cartridges into the coupling interface **113** and ensuring a secure seal. The gas cartridge also contains physical features that can be detected by the cartridge presence sensor on successful loading. In alternate embodiments, the gas cartridge also contains identification features (such as but not limited to optical barcodes, RFID, NFC tags) to further authenticate the cartridge and with accompanying sensors in the system sensor subsystem **108**. In an alternative embodiment, the gas cartridge **114** and coupling interface **113** may interface via quick-disconnecting using spring-based sealing and opening mechanisms that are commonly used in pressurized air hose plug-and-socket adapters.

[0076] FIG. 2 is a cutaway architecture diagram illustrating an imaging system **200**. In some examples, the imaging system **200** can be referred to as an imaging subsystem, for instance when the imaging system **200** is used as a subsystem of a combined incubation and imaging system (e.g.,

incubation and imaging system **300** of FIG. 3).

[0077] Various subsystems, components, and interfaces of the imaging system **200** are illustrated in FIG. 2. In some examples, the imaging system **200** includes, or encompasses, an imaging environment **220**, which is insulated from the external world by an insulation layer **221**. The insulation layer **221** (which can be made from, for instance, fiber glass, foam, and/or ceramic composites) reduces thermal exchanges from the external world into or out of the imaging environment, to better control the temperature of the imaging system **200** and/or the incubator system **100** from fluctuations. In some examples, such an insulation feature may not be a separate layer, however, the functionality offered by the chassis material (such as but not limited to bent sheet metal, injection molded plastics, 3D printed materials and ceramics) of the imaging system **200**.

[0078] The imaging system **200** includes an alignment feature **201** that is used to align with an incubator system **100**, which ensures that both subsystems are spatially oriented as needed for the functionality of the integrated unit. The imaging subsystem includes imaging access port **206** (e.g., microscopy access port) which allowing the optics subsystem **205** access to the culture dish **128** in the incubator system **100**. In some embodiments, the imaging access port **206** may already be open and not requiring removal and in other embodiments, it can be mechanically linked to self-open and close when integrating with an incubator subsystem. Additionally, a proximity sensor **209** is provided on the imaging subsystem to allow for detection of the physical integration. In some examples, such a proximity sensor (such as, but not limited to using a reed-switch and adjoining magnet) may be housed in the incubator subsystem, to accomplish the same functionality. The imaging subsystem includes handle features **211** that allow the users to transport the subsystem easily and includes anti-vibration dampening legs **213** to reduce bench noise from entering the imaging environment. In some examples, the handle features **211** may be designed within the outer chassis of the imaging subsystem. In some examples, the handle features **211** may be accomplished using belts and/or externally added handles.

[0079] In some examples, the DC power input **222** allows for plugging into an external supply to power the imaging system **200** and charge the battery subsystem **202**. When the DC power input is unplugged, the imaging system **200** continues to be powered by the battery subsystem **202**. The battery subsystem can be made of rechargeable material, such as but not limited to, Lithium-ion, Lithium-poly, Nickel-Metal Hydride or Nickel-Cadmium. In some examples, the unit may be powered by a single-use battery. In some examples, the battery subsystem **202** powers the video & image processor **219**, which then distributes power to the remaining subsystems in the imaging system **200**. In some examples, the battery subsystem may be connected to a power-distribution subsystem (not illustrated in FIG. 2), which in turn distributes the power.

[0080] In some examples, the video & image processor **219** includes a micro-processor or micro-controller board that is pre-loaded with a firmware program, with all computing occurring on a single processing core. In some examples, the computing occurs on a micro-processor or micro-controller board with additional parallel graphic processing unit (GPU) co-processors. The firmware program running on the subsystem, comprises a command and data interface routine for communicating with the external world via the communication interface **218**. This routine accepts commands, such as but not limited to, set-points, calibration curves, illumination control, image and video acquisition and configuration parameters to allow the user to control the imaging system **200**. The command and data interface routine also transmits sensor data, video & image data (raw or processed), events, warnings and logs to the user for monitoring the performance, functionality, and reliability of the imaging system **200**. The communication interface **218** provides a wireless (via protocols such as but not limited to WiFi, Bluetooth, Cellular) and/or wired (via protocols such as but not limited to USB, Ethernet, serial port, I2C, MOSI).

[0081] In some examples, the video & image processor **219** includes a core controller routine, which accepts the control information provided by the user, and along with feedback from the

system sensor subsystem **210** data, controls the various subsystems and components in the imaging environment **220**, including but not limited to the thermal control subsystem **208**, the optics subsystem **205**, the Illumination source **204**, Data storage **217**, motion controller subsystem **212**, Focus detection subsystem **207** and user interface subsystem **203**. The core controller routine includes an alarm and event coordinator sub-routine, to read sensor information from the system sensor subsystem **210** and warn the user of the state of the imaging subsystem. In some examples, the core controller routine may also include additional sub-routines, such as long-term adaptive machine learning for better control accuracy and/or predictions of system performance. For instance, a machine learning algorithm and/or model can monitor the temperature of the incubated chamber **139** and change heating parameters in order to reduce the time it takes to arrive stably within a specified set-point. Inputs into the learning algorithm and/or model can include external environment temperature, integration event history with the incubator system **100**, heater component and fan life, current state and/or history of the optical subsystem **205**, current state and/or history of the illumination source **204**, current state and/or history of the motion controller subsystem **212**, current state and/or history of the video & image processor **219**. In some examples, a machine learning algorithm and/or model can predict battery subsystem **202** charge capacities, the implementation of which would further aid the user to assess and/or plan available culture imaging time without DC power input **104**. In this instance, the machine learning algorithm and/or model may utilize, as inputs, in-service battery life and performance history, external room environmental conditions, image(s) and/or video(s) captured by the optical subsystem **205**, image capture settings (e.g., focus, exposure time, aperture size, zoom, white balance, analog gain, digital gain, level of illumination) used by the optical subsystem **205** to capture image(s) and/or video(s), image processing settings (e.g., brightness, contrast, color saturation, tone mapping, noise reduction, sharpening) used by the video & image processor **219** to process image(s) and/or video(s) captured using the optical subsystem **205**, internal imaging environment chamber system sensor subsystem **210** conditions, recent user behavior such as incubator system **100** integration events, current state and/or history of power utilizations across the various subsystems within the imaging system **200**, current state and/or history of the thermal control subsystem **208**, current state and/or history of the motion controller subsystem **212**, current state and/or history of the optical subsystem **205**, current state and/or history of the illumination source **204**, current state and/or history of usage of the data storage **217**, current state and/or history of the thermal control subsystem **132** in the integrated incubator system **100**, current state and/or history of the system sensor subsystem **108** in the integrated incubator system **100**. In some examples, the machine learning algorithm and/or model can enhance the ability and speed to achieve and/or maintain focus, inputs to which may include video and/or stacks of image frame data acquired and processed by the video & image processor **219**, current state and/or history of the focus detection subsystem **207**, current state and/or history of the sensors of the system sensor subsystem **210** (including in addition to described in FIG. 2, a vibration sensor), current state and/or history of the thermal control subsystem **208**, current state and/or history of the motion controller subsystem **212**, additional user provided information such as culture dish **128** type, size and/or count. Outputs of such a machine learning algorithm and/or model can modulate the current state and/or future state of the thermal control subsystem **208**, current state and/or future state of the motion controller subsystem **212**, current state and/or future state of the focus detection subsystem **207**, current state and/or future state of the video & image processor **219**, and/or current state and/or future state of the optics subsystem **205**. In some examples, a machine learning algorithm and/or model can detect and/or predict occurrence of a specified condition(s) and/or event(s) associated with the culture, such as at least a specified amount of a particular set of one or more cell(s) or tissue(s) dying, a particular set of one or more cell(s) or tissue(s) growing beyond a threshold amount, at least a specified amount of a particular set of one or more cell(s) or tissue(s) undergoing a specified modification, fluorescence of a specified amount of a particular set of one or more cell(s) or

tissue(s) in a specific color or light frequency range (e.g., based on a biomarker), or a combination thereof. In some examples, the machine learning algorithm can apply computer vision techniques to image(s) and/or video(s) captured using the optical subsystem **205**, such as feature extraction, feature detection, feature recognition, feature tracking, object detection, object recognition, object tracking, image classification, object classification, semantic segmentation, or combinations thereof. In some examples, a machine learning algorithm and/or model can determine image capture setting(s) (e.g., focus, exposure time, aperture size, zoom, white balance, analog gain, digital gain, level of illumination) for the optical subsystem **205** to use for further capture of image(s) and/or video(s) based on previous image capture setting(s), previous image processing setting(s), previous image(s) and/or video(s), predicted changes to the culture (e.g., predicted increased brightness due to bioluminescent biomarkers), or combinations thereof. In some examples, a machine learning algorithm and/or model can determine image processing setting(s) (e.g., brightness, contrast, color saturation, tone mapping, noise reduction, sharpening) used by the video & image processor **219** to process image(s) and/or video(s) captured using the optical subsystem **205** based on previous image capture setting(s), previous image processing setting(s), previous image(s) and/or video(s), predicted changes to the culture (e.g., predicted increased brightness due to bioluminescent biomarkers), or combinations thereof.

[0082] In some examples, the user interface subsystem **203** includes a display screen (such as but not limited to provide by an OLED array) and touch interface, providing the user the ability to observe limited, but key information about the imaging environment (such as, but not limited to Temperature, Video and Image data) on an ongoing basis. Using the touch interface, the user is also able to access a user configuration menu and interact with the imaging system **200** to address alarms, events and warnings provided by the video & image processor **219**. In some examples, additional status lights, knobs, buttons and switches are provided to allow the user to quickly review status and set important parameters. In yet another embodiment, the user interface subsystem **203** provides neither display screen nor touchscreen, with most interactions conducted by a device-linked software application via the communication interface **218**.

[0083] In some examples the motion controller subsystem **212** is housed on top of an additional anti-vibration component, to further reduce external and internal vibrational disturbances while the optics subsystem **205** (installed on the motion controller subsystem **212**) is performing an imaging operation. The motion controller subsystem **212** controls the position of an XY stage and Z-stage to enable positioning the optical subsystem at various spatial locations to perform microscopy on the culture dish **128**. The XY and Z stages can be made using an assembly of linear actuators using various mechanical mechanisms, including but not limited to being belt-driven, lead screw-driven, voice-coil or piezo-based actuation. The Z-stage is coupled with the optical subsystem **205** and aids in focusing of lenses for imaging purposes. In an alternative embodiment, a plurality of XY and Z stages are used with one or a plurality of motion control subsystems, to enable the use of a plurality of optical subsystems **205**. Such an embodiment would allow for simultaneous imaging of multiple culture dish locations and/or allow for reducing the spatial travel required of the stages. In an alternative embodiment, components of the optical subsystem can be placed on an additional stage (such as but not limited to a rotating stage), to present various objective lens and thereby microscopy magnifications for imaging purposes, which is also controlled by the motion controller subsystem **212**.

[0084] In some examples, the optics subsystem **205** includes a microscopic objective lens, and excitation & emission filter set and an imaging camera, and is coupled to an Illumination source **204**. The illumination source **204** provides light at known wavelengths (utilizing sources such as but not limited to light-emitting diodes LEDs, lasers or filament-based), to enable illuminating the samples in the culture dish **128**, via an inverted microscopy mode (whereby the excitation light travels through the objective lens to the sample and the emitted or reflected light follows a similar path back to the camera). In an alternative embodiment, the illumination source **204** can be

included within the optics subsystem **205** for further compactness. In some examples, the excitation and emission filter set allows for epi-fluorescent microscopy, and designed to match the illumination source and fluorescence wavelengths of the samples in the culture dish **128**. In an alternative embodiment, the excitation and emission filter set may not be present if the application does not require filtering of specified wavelengths, such as but not limited to bright-field microscopy, dark-field microscopy, differential interference contrast or phase-contrast microscopy. In an alternative embodiment, the illumination source **204** may not be present, when utilizing the optical subsystem **134** light source present in the incubator system **100**, in the case of performing trans-illumination microscopy.

[0085] In some examples, image or video data acquired by the camera in the optic subsystem **205** are transmitted to the video & image processor **219**. Such data transmission can utilize communication protocols such as, but not limited to, Camera-link, CoaXpress, USB, Camera Serial Interface or Ethernet. The image or video data can be transmitted in raw uncompressed format or compressed format, depending on the user settings and camera capture needs. The video & image processor **219** allows for real-time frame-by-frame computing and analysis of the incoming data. Computing and analysis algorithms can include, but not limited to, image processing pipelines starting with raw image adjustments, feature segmentation, identification, counting, tracking and quantitation. In some examples, GPU parallel processing routings in the video & image processor **219** can implement machine learning algorithms to train a predictive model. In an alternative embodiment, the image or video data may also be transmitted to a data storage **217** (using but not limited to storage technologies such flash memory, solid-state drive or disc-drives), that can be later retrieved by the video & image processor **219**. For instance, cellular and/or tissue related features extracted by the machine-learning algorithm on processing of video and/or image frames, can be used to predict outcomes in various use cases such as but not limited to healthy vs. disease states for purposes of diagnosis, phenotype of interest vs. non-phenotype of interest for biological research, contamination vs. not contaminated for quality control, drug-sensitive vs. not drug-sensitive for drug discovery, infectious vs non-infectious for virology. In such instances, the machine-learning model itself can be trained on culture sets encompassing sub-sets of both and/or multiple known outcomes. In some instances, alternative artificial intelligence methods such as Deep Learning may be applied directly to large known outcome culture sets and/or to longitudinal imaging sets on a single culture (in which case the outcome at various time-points is known and/or controlled by the user per the application), to inherently train the learning model using video data. Once trained, the model may then be used to predict culture outcomes on unknown culture sets and/or longitudinal time-points. In some examples, the learning models using the ML and/or Deep Learning approaches may be generated ‘on-board’ the integrated system. In other examples, the raw and/or processed videos and images may be uploaded ‘off-board’ the integrated system to take advantage of high-performance computing environments offered in the cloud. The learning models generated ‘off-board’, may then be downloaded ‘on-board’ once the training is partially and/or fully completed.

[0086] In some examples, the thermal control subsystem **208** is placed within the imaging environment **220** includes a heating element, cooling element and a circulating effector such as a convective fan or blower. In some examples a cooling element may not be necessary to arrive at temperature set-points and only a heating element is provided. Heating and cooling elements may be implemented using a wide variety of available electronic components, including but not limited to, peltier-based thermoelectric heater-cooling, resistive heaters and ceramic heating. There may be one or several heating elements, cooling elements and/or convective elements placed inside the imaging chamber to accomplish uniform heat distribution. In some examples, the thermal control subsystem **208**, the core-controller routing in the video & image processor **219** and a temperature sensor (or a plurality of sensors) in the system sensor subsystem **210**, include components in a feed-back system, used to maintain the temperature of the optics subsystem **205** within set

tolerances (+/-5 degrees Celsius or less) of the temperature measured in the incubated chamber **139**. The utility of doing so is to prevent focus drifts caused due to temperature differences at the objective lens in the optics subsystem **205**, at the microscope access port **206** interface.

[0087] In some examples, camera focusing is achieved by acquiring a series of images “image stack” by moving the z-stage in step increments and then analyzing the images in the video & image processor **219**, to arrive at the z-stage position for best focus. Auto-focusing algorithms can implement, but not limited to, contrast-based, phase-based or image file size-based methods, either of which can be user selected. In an alternative embodiment, a focus detection subsystem **207** can be included, comprising of an optical method to locate the z-height of the surface that the sample resides on in the culture dish **128**. Such a focus detection subsystem **207** can include a compact off-axis laser light coupled into the objective lens in the optic subsystem **205**. Given the off-axis nature of the laser light, the light is reflected from the sample surface is captured at different XY locations across the camera sensor plane, which can then be calibrated to ascertain focus z-height. In some examples, the focus detection subsystem **207** can directly direct a tiny light spot at the sample surface and capture reflected light onto an internal camera subsystem, utilizing geometric changes and/or time-of-flight methods to determine focus offsets.

[0088] In some examples, the system sensor subsystem **210** includes (A) a sensor used to detect the state of the chamber, such as but not limited to, incubator subsystem presence or absence via a proximity sensor (e.g., proximity sensor **209**), (B) a sensor used to detect the temperature at the optic subsystem **205**, (C) tilt sensors used to detect imaging system **200** orientations during placement on a surface or during transportation, and/or (D) XYZ position sensors, to monitor spatial position of the XY and Z stages.

[0089] FIG. **3** is a cutaway architecture diagram illustrating the incubator system **100** and the imaging system **200** combined to form an incubation and imaging system **300**. Several aspects of an ‘integration event’ ensure that both the subsystems are spatial, electrically and optically coupled with each other. To ensure desired spatial orientation of both subsystems, FIG. **3**, depicts a scheme where the alignment features **137** on the incubator system **100** mate with the alignment features **201** of the imaging system **200**. Retaining the alignment can occur simply due to the forces of gravity. In some examples, additional magnets and mechanical latches can be implemented to further constrain the spatial mating of the subsystems. To ensure optical coupling of the subsystems, the imaging access port **129** of the incubator system **100** and the microscopy access port **206** of the imaging system **200** can be manually removed by the user and/or automatically moved via mechanical linkages at the successful completion of the alignment. A proximity sensor **209** on the imaging subsystem confirms successful physical integration of the two subsystems. For electrical coupling the communication interface **107** of the incubator system **100** can be connected to the communication interface **218** of the imaging system **200**, using external wires such as, but not limited, to a USB cable, a Ethernet cable, a Serial interface cable, ribbon cables with I2C or MOSI channels. In an alternative embodiment, an internal electrical connection can be made from the top module **101**, to the bottom module **102** of the incubator subsystem and finally into the imaging system **200** using an additional electrical interface port, implemented using a series of spring-loaded pogo-pin connectors. In an alternative embodiment, the incubator system **100** and imaging system **200**, communicate information using wireless protocols (e.g., cellular networks, WLAN, WiFi and/or Bluetooth) and/or cloud-based network protocols.

[0090] FIG. **4** is a flow diagram illustrating an exemplary process **400** for performing long-term cell or tissue culture incubation using the incubation system. The process **400** may include workflow operations for users operating the incubator system **100** and/or the incubation and imaging system **300**, as well as system operations of the incubator system **100** and/or the incubation and imaging system **300**.

[0091] The process **400**, at operation **405**, involves the user powering up the incubator system **100**, then at operation **410** and/or operation **415**, selecting (e.g., via user interface subsystem **103**)

whether the incubator subsystem performs in online mode or offline mode. When operating in online mode, at operation **425**, the communication interface **107** establishes a connection (wired or wireless) to a dedicated secure cloud service (e.g., cloud-based database). At operation **430**, the communication interface **107** sends conditions and additional alerts (associated with the incubated chamber **139**) received from the controller subsystem **106** to the cloud service (e.g., the cloud-based database). At operation **435**, the cloud-based service (e.g., cloud-base database) provides the user (e.g., through a cloud user interface or through user interface subsystem **103**) with the ability to visualize subsystem performance and/or, at operation **440** control (e.g., set and/or modify) environmental parameters (e.g., remotely and/or locally). The database also stores long-term data and is analyzed (e.g., by ML model(s) **2225**) for hardware reliability improvements. These can include, but not limited to, assessing control loop performance and predicting component failures in case conditions do not meet quality criteria.

[0092] If, at operation **415**, the incubation and imaging system **300** is operating in offline mode (e.g., user selects offline mode), the environmental parameters are set via the user interface subsystem **103**, itself (e.g., based on inputs received by the user interface subsystem **103**).

[0093] At operation **445**, whether the incubation and imaging system **300** is in the online mode or offline mode, the user then accesses the incubated chamber **139** and loads a culture dish **128** housed within a culture dish holder **125**. At operation **450**, the user closes the incubator chamber by loading the top module **101** back onto the bottom module **102**.

[0094] At operation **460**, incubator subsystem controller feedback is activated to help the controller subsystem **106** arrives at the environmental set points within acceptable limits (e.g., within threshold limits and/or ranges). If, at operation **465**, the environmental set points are within the acceptable limits (e.g., within threshold limits and/or ranges), then the feedback can continue back to operation **460**, optionally with a delay before checking again (at operation **465**), to ensure that the environmental set points are maintained within the acceptable limits (e.g., within threshold limits and/or ranges) over time.

[0095] If, at operation **465**, the environmental set points are not within the acceptable limits (e.g., not within threshold limits and/or ranges), then the incubator system **100** and/or the incubation and imaging system **300** can perform various checks, and alert the user if needed. At operation **470**, if the system detects (e.g., based on measurements from sensors such as the proximity sensor **141**) that the incubation chamber is still open, the system can go to operation **485** and alert the user (e.g., via the user interface subsystem **103**) to take action to close the incubation chamber. At operation **475**, if the system detects (e.g., based on measurements from sensors, such as the cartridge presence sensors) that a gas cartridge **114** is empty or missing, the system can go to operation **485** and alert the user (e.g., via the user interface subsystem **103**) to take action to refill or replace the gas cartridge **114**. At operation **480**, if the system detects (e.g., based on measurements from sensors, such as the cartridge presence sensors) that a reagent cartridge (e.g., reagent & waste cartridge **110**) is empty or missing, the system can go to operation **485** and alert the user (e.g., via the user interface subsystem **103**) to take action to refill or replace the reagent cartridge.

[0096] For instance, in some examples, if the system sensor subsystem **108** reports the chamber open, gas cartridge missing or a reagent cartridge missing, it will enter an alert loop, until the situation is remedied by the user. In some examples, the user may connect additional electrical interfaces **135** to the culture dish **128** prior to loading it into the incubator subsystem and reversibly disconnect it when unloading. Data from the additional electrical interface **135** can also communicated to the cloud-database. In some examples, perfusion fluidic lines may be coupled between the fluidic interface subsystem **127** to the culture dish **128**, during the loading steps and de-coupled during the unload steps.

[0097] If none of the checks (operations **470** through **480**) identify an issue, then at operation **490**, the incubator system **100** and/or incubation and imaging system **300** delays before collecting further sensor readings and/or status readings, and before returning to operation **460**.

[0098] FIG. 5 is a flow diagram illustrating an exemplary process 500 for performing long-term cell or tissue culture imaging using the incubation and imaging system 300. The process 500 may include workflow operations for users operating the imaging system 200 and/or the incubation and imaging system 300, as well as system operations of the imaging system 200 and/or the incubation and imaging system 300.

[0099] In some examples, the process 500 includes the operations of the process 400, for instance to load culture dishes 128 into the incubator system 100, such as any of operations 405 through 455, or combinations thereof. At operation 502, the cultures are successfully loaded into the incubator system 100 (e.g., or incubator subsystem of the incubation and imaging system 300).

[0100] When an imaging session is desired, at operation 504, the user (and/or the system itself) power ups the imaging system 200. At operations 506 and 508, the user (and/or the system itself) removes the cover(s) from the imaging access port 129 of the incubator subsystem (e.g., incubator system 100) and/or from the imaging access port 206 of the imaging subsystem (e.g., imaging system 200), allowing for optical access between the subsystems of the incubation and imaging system 300. At operation 510, the two subsystems are loaded together and/or spatially aligned using the alignment features 137 and the alignment features 201 present on the subsystems. At operation 512, the user (and/or the system itself) couples (e.g., connects) the communication interface 107 and the communication interface 218 between the subsystems (e.g., using wired cables or wireless interfaces). In some examples, the communication interfaces connect as a result of aligning the two subsystems and bringing them together (via the use of, but not limited to, pogo-pin like electrical connectors) and the user does not have to perform this extra step manually. In some examples, at operation 514, the user interface subsystem 103 provides real-time updates as to the status of the incubator subsystem, imaging subsystem, or both.

[0101] At operation 516, the user (and/or the system) selects whether the imaging subsystem performs in online mode or offline mode via the user interface subsystem 203.

[0102] When operating in online mode, at operation 528, the communication interface 218 establishes connection (wired or wireless) to a dedicated cloud service (with a cloud-based database), where, at operation 530, the communication interface 218 sends conditions of the imaging environment 220, sensor status, imaging data, and/or additional alerts received from the video & image processor 219. At operation 532, the cloud-based database provides the user with the ability to remotely visualize subsystem performance, and, at operation 534, control (e.g., set and/or modify) imaging parameters via an interface (e.g., cloud interface, the user interface subsystem 103, and/or user interface subsystem 203). At operation 536, the database can also store long-term data that is analyzed for hardware reliability improvements, image algorithm improvements and machine learning. These can include, but not limited to, assessing performance of the imaging system 200 and predicting component failures in case conditions do not meet quality criteria.

[0103] If, at operation 516, the system is in offline mode (e.g., as selected by the user and/or the system), then at operation 518, the imaging parameters are set via the user interface subsystem 203 (and/or the user interface subsystem 103).

[0104] At operation 520, whether the system is in online mode or offline mode, the user and/or system creates a target imaging map where imaging is expected to occur. At operation 522, the system initiates a focusing routine at all target points, for instance performing auto-focusing procedures, for instance looping through (at operation 524) until data for all focus points is collected. At operation 526, the system initiates video acquisition.

[0105] At operation 538 and operation 540, the motion controller subsystem 212 commanding the XY stage 214 and Z-stage 216 to the various target map positions (e.g., for instance moving to a first or next XY target location at operation 538, and/or moving to a stored z-focus position at operation 540), and performing auto-focusing procedures. Once an initial focus map is obtained, the imaging subsystem loops through to the target map positions performing additional fine-

focusing (at operation **542**) and acquiring raw video or image frames by the optics subsystem **205**. At operation **544**, the raw data can be sent to the video & image processor **219** for real-time image processing (e.g., GPU-based) (at operation **548**) and/or sent to storage **217** (at operation **544** and/or operation **554**). The video & image processor **219** can extract image features according to the needs of the particular application (e.g., experiment) being run on the incubation and imaging system **300** (at operation **550**). At operation **554**, the extracted image features can be further sent to storage for later retrieval. If, at operation **556**, all target points and time points are complete, then at operation **558**, the process **500** is complete, and ends. If at operation **556**, all target points and time points are not complete, the process **500** can return to operation **538**.

[0106] In the case of online mode configurations (e.g., via operation **546** and/or operation **552**), then raw data frames and/or extracted image features can be sent to the cloud-database for real-time remote access (e.g., at operation **530**). In some examples, the user may have additional steps to change out or replace optical subsystem add-ons (like excitation/emission filters, sources) prior to initiating the imaging routine (e.g., the process **500**). In some examples, these steps are conducted for long durations of times exceeding a threshold amount of time (e.g., for one or more minute(s), hour(s), day(s), week(s), month(s), and/or year(s)), all the while the system recording raw videos and/or processed videos of the cultures that are maintained in the incubated chamber **139**. The system may provide the user physical alerts and/or notifications via electronic messaging if any of the imaging subsystem's sensors in the system sensor subsystem **210**, system sensors in the system sensor subsystem **108** and/or an adaptive machine learning algorithm in either the video & image processor **219** or control subsystem **106** or both, find incubation and/or imaging environment parameters outside of previously set bounds and/or if the system is detected to be in an error state, or detect a specific condition or event in the culture (e.g., an amount of cells or tissues has died, grown by at least a growth amount, multiplied by at least a multiplication amount, fluoresced in a color and/or frequency range associated with a biomarker, and/or been modified in a specified way), thereby allowing the user to take appropriate action (e.g., correct the error state, advance the experiment to a next stage, and the like). In some examples, processing of the video and/or image data itself may lead to these alerts and notifications, such as for instance when the imaging subsystem cannot find focus for more than a set amount of time, frame brightness-levels or contrast or background noise are outside acceptable thresholds, frame drift is detected signifying unacceptable movement of culture plate or imaging XYZ stages, non-uniform illumination and/or de-focus across the field of camera view. In some examples, the alerts and/or notifications are caused by processing of culture and tissue related parameters, such as for instance cellular morphology characteristics, cellular growth characteristics, cellular movement dynamics, internal sub-cellular features, external cellular derived features, molecular properties within the cellular environment, inter-cellular features, cellular organization within a tissue, tissue organization within an organoid or organ, internal cellular and/or tissue biochemical parameters and/or biochemical parameters in the culture dish, presence of unwanted microbes and/or microorganisms indicative of possible contamination, physio-chemical properties of the culture media. This system of notifications and alerts can improve flexibility of the system and efficiency of a laboratory as a whole, allowing the system to continue incubating and monitoring a culture without user input or intervention, allowing a user to perform other tasks with the knowledge that the system will notify or alert the user if and when user input or intervention is needed.

[0107] FIG. **6** includes exploded perspective views **600A-600C** of the incubation and imaging system **300**. In a first exploded perspective view **600A**, two culture dishes **128** are placed into the incubated chamber **139** in the bottom module **102** (which is insulated), on a culture dish holder **125** with a culture dish **128** with humidity sticks on vibration stabilizers. The top module **101** is also visible, with an ergonomic handle **650** (e.g., an example of the handle features **116**), chamber seal **118**, and proximity sensor **141** all visible.

[0108] In a second exploded perspective view **600B**, the top module **101** is illustrated with the user

interface subsystem **103**, the communication interface **107**, and the separation surface **138** visible and marked. The communication interface **107** can include WiFi and/or Bluetooth communication interface(s) with predictive reliability analytics and/or cloud services. Several components are illustrated between the top module **101** and the bottom module **102**. These components can be part of the top module **101**, the bottom module **102**, or both. These components can include a temperature and humidity sensors **605**, uniform thermal control **610** (e.g., with a heating element and/or a convective fan), a gas sensor **630**, and/or other components. In some examples, the temperature and humidity sensors **605** may be part of the chamber sensor subsystem **133**. In some examples, the uniform thermal control **610** can be part of the thermal control subsystem **132**. In some examples, the gas sensor **630** can be part of the system sensor subsystem **108** and/or the chamber sensor subsystem **133**.

[0109] In a third exploded perspective view **600C**, the top module **101** is illustrated in an exploded fashion, with several components being visible. These components include the battery module **105**, the controller subsystem **106**, the gas cartridge **114**, a regulator valve and constrictor assembly **615** (e.g., which may be, or may be part of, the gas subsystem **112**), a chamber vent **620** (e.g., gas subsystem **112**, pneumatic interface subsystem **117**, check valve **130**, relief valve **142**), a gas cartridge pressure sensor **625** (e.g., part of the system sensor subsystem **108** and/or the gas subsystem **112** that sensors pressure of the gas cartridge **114**), and top and bottom module handles **640** (e.g., handle features **116**, handle features **119**).

[0110] FIG. 7 is a perspective view **700** of the bottom module **102** (e.g., insulated) of the incubator system **100**. Components visible through the top of the bottom module **102** in the perspective view **700** include the pneumatic interface subsystem **117**, the electrical interface subsystem **131**, the separation surface **138**, the fluidic interface subsystem **127**, and a mounting bracket **705** supporting the thermal control subsystem **132** and the sensors of the chamber sensor subsystem **133**.

[0111] FIG. 8 is a cutaway architecture diagram **800** illustrating the incubation and imaging system **300**. Some of the components of the incubation and imaging system **300** that are visible in the cutaway architecture diagram **800** include the top module **101**, the bottom module **102**, the battery module **105**, the controller subsystem **106**, the pneumatic interface subsystem **117**, the chamber seal **118**, the electrical interface subsystem **131**, the anti-vibration legs **136**, the separation surface **138**, the temperature and humidity sensors **605**, the uniform thermal control **610**, the constrictor assembly **615**, the gas cartridge pressure sensor **625**, the gas sensor **630**, a space **810** for additional optics and/or imaging subsystems (e.g., imaging system **200**), and an incubation environment **815** (e.g., incubated chamber **139**).

[0112] FIG. 9 includes a front view **910** of the incubation and imaging system **300**, a perspective view **920** of the incubation and imaging system **300**, and a side view diagram **930** of a gas cartridge **114**. In the front view **910** and the perspective view **920**, certain components of the incubation and imaging system **300** are visible, including the top module **101**, the bottom module **102**, and the user interface subsystem **103**. In the side view diagram **930**, the gas cartridge **114** is illustrated in the palm of a user's hand, showing how small the gas cartridge **114** can be. In the perspective view **920**, the incubation and imaging system **300** is illustrated held in a user's hand, also showing how small the incubation and imaging system **300** can be. In the view **910**, the incubation and imaging system **300** is powered off and at rest. In the view **920**, the incubation and imaging system **300** is powered on and held single-handedly, showcasing the portability of the incubation and imaging system **300**.

[0113] FIG. 10 includes internal views (view **1010**, view **1040**) of internal components of the incubation and imaging system **300**. In view **1010**, several components of the incubation and imaging system **300** are visible, including the DC power input **104**, the battery module **105**, the controller subsystem **106**, the check valve **130**, a solenoid valve **1015** with a constrictor (e.g., which may be the valve and constrictor of the gas subsystem **112**), a fluid pump **1020** (e.g., of the fluidic subsystem **109**), a pressure sensor **1025** (e.g., of the system sensor subsystem **108**), a pressure regulator **1030** (e.g., of the regulators of the gas subsystem **112**), and a reservoir **1035**

(e.g., of the fluidic subsystem **109**). In some examples, the components visible in the view **1010** may be in the top module **101**.

[0114] In view **1040**, several components of the incubation and imaging system **300** are visible, including the chamber seal **118**, the separation surface **138**, the temperature and humidity sensors **605**, a carbon dioxide sensor **1045** (e.g., of the chamber sensor subsystem **133**), three temperature sensors **1050A-1050C** (e.g., of the chamber sensor subsystem **133** and/or system sensor subsystem **210**), and a heating element **1055** (e.g., of the thermal control subsystem **132** and/or thermal control subsystem **208**). The view **1040** may represent an example layout of the chamber sensor subsystem **133**, the incubated chamber **139**, the thermal control subsystem **132**, the chamber seal **118**, and/or separating surface **138**.

[0115] FIG. **11** includes internal views (e.g., view **1110**, view **1120**) of internal components of the incubation and imaging system **300**. In view **1110**, several components of the incubation and imaging system **300** are visible, including an access interface for the pneumatic interface subsystem **117**, an access interface for the fluidic interface subsystem **127**, the electrical interface subsystem **131**, the illumination source **204** (e.g., a light emitting diode (LED) ring add-on), and a base **1115** (e.g., printed circuit board (PCB) or other circuit board) for mounting electronics in the incubated chamber (e.g., incubated chamber **139**, incubation environment **815**, incubated environment **1125**). The view **1110** can represent an example of an added-on optical subsystem (with a ring LED illumination source **204**) and an example layout of the fluidic interface subsystem **127** access, the electrical interface subsystem **131** access, and the pneumatic interface subsystem **117** access.

[0116] In view **1120**, several components of the incubation and imaging system **300** are visible, including the bottom module **102**, the space **810** for additional optics and/or imaging module(s), the incubated environment **1125** (e.g., incubated chamber **139**, incubation environment **815**), and insulation **1130** (e.g., insulating material **122**) around the incubated environment **1125**. The view **1120** can represent an example design of the bottom module **102**, with insulation **1130** (e.g., insulating material **122**) and the incubated environment **1125** (e.g., incubated chamber **139**). In alternate embodiments, the imaging access port **129** and/or a plurality of such ports is fabricated at the bottom of the incubated environment **1125** (not shown in the view **1120**) to allow for optical access to the culture dish **128** received by/in the incubated environment **1125**.

[0117] FIG. **12** is a user interface diagram illustrating a dashboard interface **1200** for visualizing data from an incubation and imaging system **300**. In the dashboard interface **1200** illustrated in FIG. **12**, real-time data from two independently operating incubator subsystems (“SN0001” and “SN0002”) communicated wirelessly (via WIFI) into an on-line cloud database. The database was then polled regularly (at 5 sec intervals), to provide the remote visualization dashboard for the past 1 day. User interface section **1201** and user interface section **1207** shows the individual temperature sensor readings and average temperature reading in the incubated chamber **139**, in both test units simultaneously. User interface section **1202** and user interface section **1203** shows the relative humidity and CO.sub.2 gas readings, respectively.

[0118] The dashboard interface **1200** provides information to the user, for instance to allow the user to react accordingly to prevent loss of culture growth conditions. In the example illustrated in FIG. **12**, the dashboard interface **1200** shows that SN0002 is reporting temperature levels close to the set-point 37 degrees Celsius, however, the humidity and CO.sub.2 levels are compromised. The cloud-service can notify the user of such a scenario via email, text or other forms of information exchange. The user interface section **1204** and the user interface section **1205** provide the user with information regarding the number of times components of the thermal control subsystem **132** were operated. Such information gathered over long-periods of time can be used to predict component failures, such as but not limited to, lack of incubated environment sealing **118** and insulating material **122**. The user interface section **1207** shows an example of the pressure sensing reading from the gas cartridges loaded onto the respective test units. In this example, a user can observe that test unit SN0001 pressure has dropped and a cartridge replacement is therefore eminent. In

some examples, the layouts for the visualization in the dashboard interface **1200** can display single unit information, additional units and/or provide additional data analysis tools that are configurable by the user.

[0119] FIG. **13** illustrates two examples of systems to regulate and inject controlled quantities of gas by the gas subsystem **112** in the incubator system **100**. In the first diagram **1310**, discrete components are assembled together during manufacturing, including a piercing adapter **1315** (that accepts a sealed gas cartridge **114**, for instance at gas pressures of at least 800 psi, or even of at least 1200 psi), a pressure regulator **1320** (that drops the cartridge pressure, for instance to <20 psi), a valve **1325** to gate the release of gas, and a precision orifice **1330** to further impede, and thereby control, the gas flow (such as, but not limited to, that provided by a Jewel orifice with an orifice diameter <100 micron).

[0120] In the second diagram **1335**, various the components of the gas subsystem **112** are integrated into a single integrated pneumatic manifold **1350**, allowing for additional compactness of this subsystem. The components, as illustrated in the second diagram **1335**, include a carbon dioxide cartridge **1342** (e.g., as an example of the gas cartridge **114**), the piercing adapter **1315** (e.g., which may be a $\frac{3}{8}$ inch female piercing adapter), a release vent **1345** to prematurely drain the carbon dioxide cartridge **1342** if needed (e.g., if the cell culture environment in the chamber already has over a threshold level of carbon dioxide), a multi-stage regulator (e.g., that drops pressure to below 100 pounds per square inch gauge (psig), then drops pressure to below 50 psig, then drops pressure below 5 psig), the piercing adapter **1315**, the pressure regulator **1320** (e.g., with multiple stages), valve **1325**, precision orifice **1330**, and output connector), a barb connector **1355** (e.g., 1/16 inch) to a 5 psi range pressure sensor **1360** (e.g., measuring whether the pressure is within a threshold range of 5 psi), a solenoid valve **1365** (e.g., as an example of the valve **1325**), an orifice **1370** to control flow if needed (e.g., as an example of the precision orifice **1330**), an a barb connector **1375** (e.g., 1/16 inch) as an output interface. In some examples, the pressure at the output interface is between zero and 5 psi. In some examples, the gas subsystem **112** can be in a housing that includes chassis mounting holes with screw threads (e.g., M4 threads).

[0121] FIG. **14** provides a photographic example of an integrated incubator and imaging system as a single subsystem **1400**, without the need for a separate incubator system **100** and imaging system **200**. In this embodiment, the top module **1401** (top module **101**) and bottom module **1402** (bottom module **102**) have subsystems and components as the top module **101** and bottom module **102**, described previously. Not shown in FIG. **14** are the insulation layer (e.g., insulating material **122**, insulation **1130**) and outer chassis.

[0122] An optical microscopy subsystem **1406** (e.g., using the OpenFlexure v7 microscope, another microscope, a custom designed microscope system, or a combination thereof) (e.g., as an optical subsystem **205**) is added to the bottom module **1402**, which includes a camera sensor and an integrated XY stage **1407** (e.g., XY stage **214**) to move a culture dish **1404** (e.g., culture dish **128**) and a Z-stage (e.g., anti-vibration **215**) to move the microscope objective for focusing. The single subsystem **1400** (e.g., and any incubation and imaging system **300**) can include actuators coupled to the optical microscopy subsystem **1406** (e.g., the optical subsystem **205**), to the XY stage **1407** (e.g., XY stage **214**), and/or to the Z-stage (e.g., anti-vibration **215**), to move the culture dish **1404** (e.g., culture dish **128**) relative to the optical microscopy subsystem **1406** (e.g., the optical subsystem **205**) to change focus, to look at different parts of a cell culture, or a combination thereof. Also present in this embodiment is an XYZ stage controller subsystem **1408** (e.g., motion controller subsystem **212**) and a video and graphic processor subsystem **1405** (e.g., video & image processor **219**).

[0123] The various electronic subsystems illustrated in FIG. **14** can be placed inside or outside the bottom module **1402**. If placed inside, these components can be sealed using enclosure case(s) to protect the electronics from the high-humidity environment inside the incubator (e.g., incubated chamber **139**, incubation environment **815**, incubated environment **1125**). If placed outside, the

cables can be routed using sealed panel interfaces.

[0124] In some examples, a system for culture management can include a housing around a chamber (e.g., incubated chamber **139**, chamber with incubation environment **815**, chamber with incubated environment **1125** of FIG. **11**). The chamber receives a culture (e.g., cell and tissue culture dish **128**). The system includes at least one chamber environment interface (e.g., fluidic subsystem **109**, gas subsystem **112**, fluidic interface subsystem **127**, pneumatic interface subsystem **117**, electrical interface subsystem **131**, thermal control subsystem **132**, thermal control subsystem **208**, motion controller subsystem **212**, anti-vibration **215**, chamber vent, gas cartridge, pneumatic interface subsystem, fluidic interface subsystem, regulator, valve, constrictor assembly, heating element, solenoid valve with constrictor, fluid pump, check valve, solenoid valve, CO.sub.2 cartridge) that controls a property of an environment within the chamber to maintain the property within a predetermined range. The predetermined range is associated with incubation of the culture. The system includes at least one chamber environment sensor (e.g., system sensor subsystem **108**, chamber sensor subsystem **133**, system sensor subsystem **210**, proximity sensor, pressure sensor, temperature sensor, humidity sensor, gas sensor, gas cartridge pressure sensor, CO.sub.2 sensor, relative humidity sensor, light sensor) that measures the property of the environment within the chamber to verify that the property is within the predetermined range.

[0125] In some examples, the property of the environment within the chamber includes at least one of a temperature of the environment within the chamber, a humidity of the environment within the chamber, a pressure of the environment within the chamber, a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified fluid in the environment within the chamber, a concentration of a specified mixture of fluids in the environment within the chamber, an orientation of the environment within the chamber, or a level of illumination in the environment within the chamber.

[0126] In some examples, the least one chamber environment interface includes at least one of a heater that heats the environment within the chamber to increase a temperature of the environment, a cooler that cools the environment within the chamber to decrease the temperature of the environment, a humidifier that humidifies the environment within the chamber to increase a humidity of the environment, a dehumidifier that dehumidifies the environment within the chamber to decrease the humidity of the environment, a pump that adjusts at least one of a pressure in the environment within the chamber or a flow rate of a fluid in the environment within the chamber, a valve that adjusts at least one of the pressure in the environment within the chamber or the flow rate of the fluid in the environment within the chamber a pump that adjusts a concentration of a specified gas in the environment within the chamber, a valve that adjusts the concentration of the specified gas in the environment within the chamber, a pump that adjusts a concentration of a specified mixture of gases in the environment within the chamber, a valve that adjusts the concentration of the specified mixture of gases in the environment within the chamber, a pump that adjusts a concentration of a specified fluid in a culture dish in the environment within the chamber, a valve that adjusts the concentration of the specified fluid in the culture dish in the environment within the chamber, a pump that adjusts a concentration of a specified mixture of fluids in the culture dish in the environment within the chamber, a valve that adjusts the concentration of the specified mixture of fluids in the culture dish in the environment within the chamber, at least one gas container that stores one or more specified gases to provide the one or more specified gases into the environment within the chamber, at least one fluid container that stores one or more specified fluids to provide the one or more specified fluids into the environment within the chamber, a fan that facilitates airflow within the chamber, an actuator that adjusts an orientation of the environment within the chamber, a light source that illuminates the environment within the chamber, or a combination thereof.

[0127] In some examples, the least one chamber environment sensor includes at least one of a

temperature sensor, a humidity sensor, a gas pressure sensor, a gas concentration sensor, a fluid concentration sensor, a fluid flow rate sensor, an assay sensor (e.g., biomolecular sensors, biomarker sensors), a bioactivity electrical recording sensor, an orientation sensor, a light sensor, or a combination thereof.

[0128] In some examples, the system includes at least one sensor (e.g., imaging access port **129**, optics subsystem **205**, focus detection subsystem **207**, illumination source **204**) that captures a representation of the culture while the culture is in the chamber. The system includes at least one output interface (e.g., user interface subsystem **103**, communication interface **107**, user interface subsystem **203**, communication interface **218**, display, speakers, buttons, haptic feedback actuator) that outputs a notification based on the representation of the culture captured using the at least one sensor. In some examples, the sensor can be referred to as an image sensor, a media capture sensor (e.g., with “media” in this term referring to images, videos, audio, and/or other forms of media content that can be captured as sensor data).

[0129] In some examples, the at least one sensor includes at least one image sensor of a camera. The at least one image sensor captures the representation of the culture, wherein the representation of the culture includes at least one of an image of the culture or a video of the culture.

[0130] In some examples, the system includes at least one memory storing instructions, and at least one processor (e.g., controller subsystem **106**, video & image processor **219**). Execution of the instructions by the at least one processor causes the at least one processor to analyze the representation of the culture to detect a condition. The notification is indicative of the condition. In some examples, to analyze the representation of the culture, the at least one processor processes the representation of the culture using a trained machine learning model that detects the condition based on the representation of the culture. In some examples, the execution of the instructions by the at least one processor causes the at least one processor to further train the trained machine learning model based on training data to update the trained machine learning model. The training data includes at least one of the representation of the culture, the condition, the notification, feedback to the notification, or a combination thereof.

[0131] In some examples, the at least one output interface includes at least one of a display, a speaker, a haptic feedback actuator, a wired communication interface, or a wireless communication interface.

[0132] FIG. **15** is a perspective view **1500** of a cell culture setup to perform in-vitro neuronal recordings on microelectrode arrays (MEAs). In some examples, performing microelectrode array (MEA) neuronal recording consists of piecing together many devices in an arrangement such as the one illustrated in the perspective view **1500**. These include massive culture incubators (e.g., incubator **1505**, mini-incubator tower **1530**) (e.g., with large external gas tanks **1510**, and powered by AC mains electricity), culture MEA interfaces, MEA pre-amplifiers, data processors (e.g., workstation **1515**) for analysis, and fluidic systems for perfusion. They may also include electrical stimulation modules **1520** and optical stimulation modules **1525**. A complete setup can easily take up an entire 6 ft workbench or multiple racks, with long optical fibers, fluidic and gas tubing, and long cables susceptible to interference. Thus, one challenge with traditional MEA setups is lack of integration and complex equipment setup. An integrated incubation and imaging system, such as the incubation and imaging system **300**, solves issues with disparate non-integrated systems such as these.

[0133] Another challenge with traditional MEA setups is optical, electrical and fluidic stimulation. Traditional systems for optical, electrical or pharmacological stimulation do not allow for multi-modal closed-loop stimulation within the context of traditional incubation setups (e.g., perspective view **1500**), further increasing equipment system complexity. This severely limits application of machine learning models in health science. An integrated incubation and imaging system, such as the incubation and imaging system **300**, solves such issues by allowing for multi-modal closed-loop stimulation, and by allowing use of machine learning models (e.g., ML model(s) **2225**).

[0134] Another challenge with traditional MEA setups is sub-optimal neuronal growth conditions and high-frequency of contamination. The toxic role that abnormally high oxygen concentration in the atmosphere (20%) as compared to physiological levels (<10%) on neuronal cultures has been well-documented. However, the traditional cell culture incubators control only for CO.sub.2 concentration, not oxygen concentration, hampering neuronal network formation and viability. Long-term neuronal cultures need to remain contamination-free for weeks or months to study neurodevelopmental pathways. Sealed neuronal cultures with breathable membranes and hydrophobic barriers can significantly reduce contamination and hyperosmolality stresses caused by incubator door openings. This can cause the death of cultures and expensive experimental losses. An integrated incubation and imaging system, such as the incubation and imaging system **300**, seamlessly integrates of this solution with MEAs dishes at scale, preventing death of cultures and related losses.

[0135] FIG. **16** is a conceptual diagram **1600** illustrating various features of the incubation and imaging system **300**. In some examples, the incubation and imaging system **300** is approximately the size of a shoebox. In some examples, the incubation and imaging system **300** can be used as an MEA culture system. In some examples, the incubation and imaging system **300** is battery powered and can be transported when needed without disturbing neuronal recordings.

[0136] In some examples, the incubation and imaging system **300** includes, as feature **1605**, a hypoxic incubation environment enabled by the use of miniature CO.sub.2 and N.sub.2 gas cartridges (eliminating the need for large gas tanks). The incubation and imaging system **300** can include, as feature **1610**, a single-board computer (SBC) for neural spike recording and real-time analysis, chamber environment control, optical and electrical stimulation control, and wireless cloud-interfacing for transmission of experimental data. The incubation and imaging system **300** can include, as feature **1615**, miniaturized precision fluidic subsystems for culture media replenishment and reagent delivery to the neuronal culture dishes, while simultaneously recording. The incubation and imaging system **300** can include, as feature **1620**, an optical subsystem for optogenetic neuronal stimulation. The incubation and imaging system **300** can include, as feature **1625**, easy to load in-vitro MEA dishes with a custom-designed cap that includes breathable membranes to maintain sterility and prevent hyperosmolality stresses. The incubation and imaging system **300** can include, as feature **1630**, scalable interfacing to compact pre-amplifier boards that perform all analog signal processing, prior to interfacing directly to the single board computer. The incubation and imaging system **300** can include, as feature **1635**, integrated control of temperature, humidity and gas sensing (e.g., CO.sub.2 and O.sub.2). The incubation and imaging system **300** can include, as feature **1640**, a cloud-connected system with a DC-powered battery.

[0137] The incubation and imaging system **300** is designed to allow neuronal cultures (or other types of cell cultures) to be incubated, monitored, and interacted with robustly for long durations, such as weeks, months, or even years.

[0138] The incubation and imaging system **300** greatly improves efficiency and accuracy, prevents cell deaths and damage (e.g., caused by removing cells from incubators to place the cells under microscopes, and doing so for extended periods of time repeatedly), and streamlines the experimental setup for neuroscience researchers. Rather than multiple pieces of equipment to manage, the simplified workflow involves (A) easily loading pre-packaged gas, reagent and media cartridges into the system, (B) opening the system chamber and loading a fresh in-vitro neuronal culture MEA dish with a sealed cap (and in some examples, multiwell MEA plates), (C) closing the chamber, which mechanically and electrically engages the pre-amplifier boards and fluidically engages the culture dish, (D) setting the environmental parameters, stimulation and recording conditions in software, and (E) performing software controlled media replenishment and/or pharmacological treatment without further opening the chamber, while continuously performing long-term recording and analysis using GPU-driven spike sorting with cloud-based remote monitoring. Such a platform will greatly increase the accessibility, standardization, flexibility, and

scalability of in-vitro neuronal MEA based experimentation. Examples of this process are illustrated in FIGS. 4-5.

[0139] Some examples of the incubation and imaging system **300**, or components or subsystems thereof, are illustrated in FIGS. 1, 2, 3, 6, 7, 8, 9, 10, 11, 13, 14, 16, 18, 19, and 21. The incubation and imaging system **300** can be used to control the temperature, humidity and gas levels (e.g., CO.sub.2, O.sub.2, N.sub.2) level inside the incubation environment (e.g., incubated chamber **139**, incubation environment **815**, incubated environment **1125**). The design of the incubation and imaging system **300** includes a top module **101** and a bottom module **102**. In some examples, the top module **101** houses electronics, the controller subsystem **106**, and sub-systems for gas injection (e.g., gas subsystem **112**). Miniature gas cartridges **114**, such as CO.sub.2 cartridges (e.g., **16g**) are all that is needed to supply the requisite gas into the incubation and imaging system **300**. An on-board battery module **105** allows the entire user interface subsystem **103** to be fully portable. The bottom module **102** includes the insulated chamber (e.g., incubated chamber **139**, incubation environment **815**, incubated environment **1125**), sensors (e.g., chamber sensor subsystem **133**), and thermal control components (e.g., thermal control subsystem **132**) that allow for a system to receive culture dishes **128**, such as standard Petri dishes or Society for Biomolecular Screening (SBS)-format well plates, for long-term mammalian cell incubation. In some examples, the incubation and imaging system **300** can be designed to be flexible, for instance to include additional electronic, optical, and/or fluidic interfaces.

[0140] FIG. 17 is an example of a phase contrast image **1700** (modified to be viewable in black and white) of MCF10A wild type cells successfully cultured in the incubator system **100** and imaged. Mammalian MCF (wild type) epithelial cells have been successfully cultured and replicated in the incubation and imaging system **300**, and imaged (as in the phase contrast image **1700** of FIG. 17). The cells remain viable for at least over 72 hrs on a single gas cartridge and 12V DC power supply to the incubation and imaging system **300**. Similar types of images can be captured using the imaging system **200** and/or the incubation and imaging system **300**.

[0141] Referring back to FIG. 1—to generate physiological O.sub.2 concentrations below 20%, the design of the incubation and imaging system **300** can include dual gas control (e.g., CO.sub.2 and N.sub.2) using mini-cartridges (e.g., gas cartridge **114**), precision regulators (e.g., of the gas subsystem **112**), dual solenoid valves (e.g., of the gas subsystem **112**), and dual gas-sensors (e.g., of the system sensor subsystem **108**). In some examples, nitrogen gas is used to drive oxygen out of the incubation environment (e.g., incubated chamber **139**) to reach and maintain physiologically equivalent oxygen levels (<10% O.sub.2). Pressure sensors on each gas channel (e.g., of the system sensor subsystem **108** and/or gas cartridge pressure sensor **625**) can monitor cartridge supply levels. The controller subsystem **106** can include a compute module, such as a single-board computer (e.g., NVidia Jetson Orin), which can be integrated into the incubation and imaging system **300** to maintain user defined environment set-points, including gas, temperature, and humidity. The controller subsystem **106** can transfer real-time data to cloud applications (e.g., InfluxData for time-series storage and/or Grafana for data visualization) via its on-board wifi/BLE network interfaces. All hardware modules can be powered by 12V DC supply and/or an on-board Lithium Ion Battery. A custom designed breathable cap (e.g., using 12.7-micron Dupont Teflon® fluorinated ethylene propylene (FEP) film) can be made using 3D-machining and assembly with rubber o-rings. Using FEP-sealed culture dishes has the added benefit of reducing the Relative Humidity levels in the chamber (e.g., ~65% RH compared to typical >85% RH) due to the membranes' hydrophobic properties. This prevents corrosion, short-circuits and clogs from condensation. To further compact the design, and if needed, to increase space within the chamber, the culture environment can in some examples be sampled using a gas pump and analyzed in the top module **101**, rather than in the bottom module **102**.

[0142] Examples of types of cell cultures that can be incubated and/or imaged using the incubation and imaging system **300** include, by way of example and without limitation, PC12-derived

Neuroscreen™-1 cells, primary rodent cortical neurons, primary rodent hippocampal neurons, and Human iPSC derived Glutamatergic neurons. In some examples, for such cells, use of the incubation and imaging system **300** can improve neurite outgrowth and viability compared to experiments performed using traditional incubation systems and imaging systems that are not integrated with one another.

[0143] In some examples, custom MEAs can be used with the incubation and imaging system **300** to better enhance experimental flexibility. In some examples, a custom pre-amplifier board consisting of 4×32-channel low-noise amplifier and constant-current stimulator chipsets can be used to interface with the MEA dish that will be placed in the chamber of the incubation and imaging system **300**. The custom PCB can use pogo-pins to mechanically and electrically engage with the MEA electrode pads when the user closes the chamber of the incubation and imaging system **300**, forming a sound connection to the MEA with no loose hanging electrical cables with stress points. The amplifier digital interfaces will connect via an electrical interface in the top lid of the chamber to the controller subsystem **106** using a dedicated high-speed SPI bus. The operating system (e.g., Linux, Windows, or Mac) on the controller subsystem **106** will allow for installing software packages (e.g., open source or otherwise) for closed-loop neural recording, stimulation, spike sorting and visualization. In some examples, these software packages are part of the incubation and imaging system **300**, or are associated with the incubation and imaging system **300**.

[0144] FIG. **18** is a conceptual illustration **1800** of an incubation and imaging system **300** performing multimodal neuronal stimulation and microscopy. The incubation and imaging system **300** illustrated in the conceptual illustration **1800** uses a single-board computer (SBC) controller **1805** as its controller subsystem **106**, and also includes a light emitting diode (LED) controller board **1810**. In some examples, to deliver optical stimuli, the LED driver board **1810** controls a blue LED **1815** (e.g., at a first wavelength, such as 470 nm,) and an amber LED **1820** (e.g., at a second wavelength, such as 590 nm), along with a 25 mm fused holographic diffuser. To deliver electrical stimuli, the stimulator chipsets of the incubation and imaging system **300** can be programmatically pulsed via pogo-pin interfaces **1825**. To deliver chemical stimuli, a miniature, pulsation-free, millisecond response time disc pump **1830** can be fluidically coupled to the neuronal culture dish. A bottom chamber seal **1835** allows for an inverted epi-fluorescence microscope **1840** to perform simultaneous live-cell Ca²⁺ imaging. In some examples, the microscope **1840** can be the imaging system **200**, and/or the imaging subsystem of the incubation and imaging system **300**. In some examples, all mechanical, electrical and fluidic interfaces are connected, coupled, activated, and/or actuated automatically in response to the chamber transitioning from an open state to a closed state (see bi-directional arrows with cross-hatched shading in FIG. **18**).

[0145] In an illustrative examples, primary rat cortical neuronal cultures can be transduced with excitatory and inhibitory optogenetic constructs using vectors AAV-CaMKIIa-hChR2 (H134R)-mCherry and AAV-CaMKIIa-eNpHR 3.0-EYFP. Blue and/or yellow light stimulation can be used to confirm optical control of network firing patterns (e.g. via blue LED **1815** and/or amber LED **1820**). Electrical stimulation patterns on the same cultures (e.g., without light) can be tested (e.g., via pogo-pin interfaces **1825**) to confirm electrical control of network firing. The spontaneous spiking and bursting activity of Human iPSC-derived Glutamatergic neurons can be modulated by chemical stimulation (e.g., via millisecond response time disc pump **1830**) and monitored continuously via the MEA electrodes. The SBC controller **1805** can control media exchanges containing Bicuculline (BIC, 30 μM) to block GABA receptors, D-2-Amino-5-phosphonopentanoic acid (D-APV, 60 μM) to block NMDA receptors, or 6-cyano-7-nitroquinoxaline-2,3-dione (CNQX, 30 μM) to block AMPA receptors. The incubation and imaging system **300** can be used to confirm excitatory or inhibitory effects of the chemical modulation. Inverted epi-fluorescence microscopy can be used to image live neural cultures loaded with Fluo-4-AM calcium indicator. Intracellular fluorescence intensity changes due to calcium influx can be correlated against MEA electrical

recordings to confirm Ca²⁺ imaging functionality. Media exchanges can be performed without opening the chamber (of the incubation and imaging system **300**) for cultures for over 1 month. [0146] FIG. **19** is a perspective diagram **1900** illustrating an imaging system **200**.

[0147] FIG. **20** is a cross-section diagram **2000** illustrating an imaging system **200**. Visible within the imaging system **200** of the cross-section diagram **2000** are, for instance, examples of the alignment features **201**, the user interface subsystem **203**, the optical subsystem **205**, the imaging access port **206**, the thermal control subsystem **208**, the motion controller subsystem **212**, the XY stage **214**, and the Z-stage **216**.

[0148] FIG. **21** is a perspective diagram **2100** illustrating an incubation and imaging system **300**. The incubation and imaging system **300** includes an incubator system **100** that is detachable coupled to an imaging system **200**. The top module **101**, the bottom module **102**, the user interface subsystem **103**, and the user interface subsystem **203** are visible from the exterior of the incubation and imaging system **300**. A fluid management system **2110** is also illustrated, as an internal component (or set of components) within the incubator system **100**. The fluid management system **2110** can be used by the incubator system **100** to perfuse media with fluids, gases, cell cultures, and/or reagents.

[0149] In some examples, the culture dish **128**, and/or the culture dish holder **125**, may be, or may include, a bioreactor chip and/or biochip. In some examples, incubator system **100** and/or the fluid management system **2110** use pressurized pumps, valves, and/or filters to input fluids (e.g., liquids and/or gases) into the bioreactor (e.g., the culture dish **128** and/or the culture dish holder **125**) while also extracting spent medium (e.g., waste, including cellular waste and/or depleted nutrients) to perform perfusion cell culture incubation. In some examples, perfusion can be performed using a predetermined pressure (e.g., 2 PSI). In some examples, under perfusion, the incubator system **100** and/or the fluid management system **2110** adds fresh medium to the bioreactor (e.g., the culture dish **128** and/or the culture dish holder **125**) at a specific flow rate, and removes spent medium (e.g., waste) from the bioreactor at the same rate (e.g., within a threshold difference). Filters can ensure that the cells are retained in the bioreactor (e.g., the culture dish **128** and/or the culture dish holder **125**) during perfusion, and not extracted with the spend medium. The fresh medium replenishes fluids (e.g., liquids, gases), nutrients, carbon sources, electrolytes, drugs, pharmaceuticals, other materials, or combinations thereof. In some examples, gases provided to the bioreactor (e.g., the culture dish **128** and/or the culture dish holder **125**) during perfusion can come from the gas cartridge **114** and/or gas cartridge(s) or reservoir(s) of the fluid management system **2110**. In some examples, liquids provided to the bioreactor (e.g., the culture dish **128** and/or the culture dish holder **125**) during perfusion can come from a first set of one or more reservoir(s) of the fluidic subsystem **109** and/or of the fluid management system **2110**. In some examples, spend medium fluids (e.g., liquids and/or gases) extracted from the bioreactor (e.g., the culture dish **128** and/or the culture dish holder **125**) during perfusion can be conveyed to a second set of one or more reservoir(s) of the fluidic subsystem **109** and/or of the gas subsystem **112** and/or the fluid management system **2110**.

[0150] In some examples, perfusion with culture media can improve quality and/or viability of long-term 3D tissue generation. In some examples, for instance, perfusion for a period of time (e.g., 24 hours) can promote increased spheroid cohesion and collective organization. In some examples, perfusion can present benefits to patch quality. Spheroids are integrated into hydrogels to create patches, but these patches can be degraded by cellular metabolites, leading to low hydrogel strength and a decrease in patch quality. In some examples, perfusion for a period of time (e.g., 24 hours) can reduce the size of hole(s) in hydrogel, for instance reducing a ratio of hole size per spheroid. In some examples, the incubator system **100** and/or the fluid management system **2110** can use valve(s) (e.g., of the fluidic subsystem **109**, the gas subsystem **112**, the pneumatic interface subsystem **117**, and/or the fluidic interface subsystem **127**) for fluid line priming, removing bubbles and/or saturating the entire system with media. Because bubbles can impact cell morphology and

protein expression, this reduction in bubbles can improve quality and/or viability of cell cultures. [0151] In some examples, the fluid management system **2110** can be a separate subsystem that is detachably coupled to the incubator system **100** and/or the imaging system **200**, rather than being internal to the incubator system **100**. The subsystems of the incubation and imaging system **300** can be coupled to one another in any order. The imaging system **200** is illustrated as being coupled to the incubator system **100** in an arrangement in which the imaging system **200** is lower (in the direction of gravity) than the incubator system **100**. In some examples, the imaging system **200** is instead coupled to the incubator system **100** in an arrangement in which the incubator system **100** is lower (in the direction of gravity) than the imaging system **200**. For instance, the components of the incubator system **100** and imaging system **200** can be reversed compared to the arrangements illustrated herein (e.g., with the optical subsystem **205** pointing down through the imaging access port **206** at the bottom of the imaging system **200** and the at the imaging access port **129** at the top of the incubator system **100** at the culture dish **128** toward the top of the incubator system **100**). In some examples, an additional subsystem (e.g., the fluid management system **2110**) can be coupled to the incubator system **100** and/or the imaging system **200**. an additional subsystem (e.g., the fluid management system **2110**) can be coupled in between the incubator system **100** and the imaging system **200**, and can have two or more imaging access ports (e.g., similar to the imaging access port **129** and/or the imaging access port **206**) so that light from the culture dish **128** travels through the imaging access port **129** the imaging access port(s) of the additional subsystem, and the imaging access port **206** before reaching the image sensor of the optical subsystem **205**.

[0152] FIG. **22** is a block diagram illustrating an example of a machine learning system **2200** for training, use of, and/or updating of one or more machine learning model(s) **2225** that are used to generate analysis **2235** and/or recommendation(s) **2240**. The machine learning (ML) system **2200** includes an ML engine **2220** that generates, trains, uses, and/or updates one or more ML model(s) **2225**. In some examples, the incubator systems (e.g., incubator system **100**), imaging systems (e.g., imaging system **200**), and/or combined incubation and imaging systems (e.g., incubation and imaging system **300**) discussed herein include, or have access to, the ML system **2200**, the ML system **2200**, the ML engine **2220**, the ML model(s) **2225**, and/or the feedback engine(s) **2250**, or vice versa.

[0153] The ML model(s) **2225** can include, for instance, one or more neural network(s) (NN(s)), one or more convolutional NN(s) (CNN(s)), one or more time delay NN(s) (TDNN(s)), one or more deep network(s) (DN(s)), one or more autoencoder(s) (AE(s)), one or more variational autoencoder(s) (VAE(s)), one or more deep belief net(s) (DBN(s)), one or more recurrent NN(s) (RNN(s)), one or more generative adversarial network(s) (GAN(s)), one or more conditional GAN(s) (cGAN(s)), one or more feed-forward network(s), one or more network(s) having fully connected layers, one or more support vector machine(s) (SVM(s)), one or more random forest(s) (RF), one or more computer vision (CV) system(s), one or more autoregressive (AR) model(s), one or more Sequence-to-Sequence (Seq2Seq) model(s), one or more large language model(s) (LLM(s)), one or more deep learning system(s), one or more classifier(s), one or more transformer(s), or a combination thereof. In examples where the ML model(s) **2225** include LLMs, the LLMs can include, for instance, a Generative Pre-Trained Transformer (GPT) (e.g., GPT-2, GPT-3, GPT-3.5, GPT-4, etc.), DaVinci or a variant thereof, an LLM using Massachusetts Institute of Technology (MIT)® langchain, Pathways Language Model (PaLM), Large Language Model Meta® AI (LLaMA), Language Model for Dialogue Applications (LaMDA), Bidirectional Encoder Representations from Transformers (BERT), Falcon (e.g., 40B, 7B, 1B), Orca, Phi-1, StableLM, Google® Bard®, Google® Gemini®, DeepSeek® R1, Alibaba® Qwen®, ByteDance® Doubao®, variant(s) of any of the previously-listed LLMs, or a combination thereof.

[0154] Within FIG. **22**, a graphic representing the ML model(s) **2225** illustrates a set of circles connected to one another. Each of the circles can represent a node, a neuron, a perceptron, a layer, a portion thereof, or a combination thereof. The circles are arranged in columns. The leftmost column

of white circles represent an input layer. The rightmost column of white circles represent an output layer. Two columns of shaded circles between the leftmost column of white circles and the rightmost column of white circles each represent hidden layers. An ML model can include more or fewer hidden layers than the two illustrated, but includes at least one hidden layer. In some examples, the layers and/or nodes represent interconnected filters, and information associated with the filters is shared among the different layers with each layer retaining information as the information is processed. The lines between nodes can represent node-to-node interconnections along which information is shared. The lines between nodes can also represent weights (e.g., numeric weights) between nodes, which can be tuned, updated, added, and/or removed as the ML model(s) **2225** are trained and/or updated. In some cases, certain nodes (e.g., nodes of a hidden layer) can transform the information of each input node by applying activation functions (e.g., filters) to this information, for instance applying convolutional functions, downscaling, upscaling, data transformation, and/or any other suitable functions.

[0155] In some examples, the ML model(s) **2225** can include a feed-forward network, in which case there are no feedback connections where outputs of the network are fed back into itself. In some cases, the ML model(s) **2225** can include a recurrent neural network, which can have loops that allow information to be carried across nodes while reading in input. In some cases, the network can include a convolutional neural network, which may not link every node in one layer to every other node in the next layer.

[0156] One or more input(s) **2205** can be provided to the ML model(s) **2225**. The ML model(s) **2225** can be trained by the ML engine **2220** (e.g., based on training data **2265**) to generate one or more output(s) **2230**. In some examples, the input(s) **2205** include information **2210**. The information **2210** can include, for instance, information about cultured cells, about the incubator system(s), about the imaging system(s), about fluid(s) and/or reagent(s) and/or gas(es) to be provided to incubated chamber **139**, about waste products received from the incubated chamber **139**, sensor data from one or more sensors (e.g., of the incubator system **100** and/or the imaging system **200**), image data from one or more cameras (e.g., of the imaging system **200**), or a combination thereof. In some examples, the input(s) **2205** can include prompt(s) (e.g., to an LLM). In some examples, the input(s) **2205** can include information retrieved from data store(s) **2270**, for instance via retrieval augmented generation (RAG) (e.g., via RAG query(s) **745**). In some examples, the input(s) **2205** can include prompt(s) that are modified and/or enhanced using information retrieved from data store(s) **2270**, for instance via retrieval augmented generation (RAG) (e.g., via RAG query(s) **745**).

[0157] The output(s) **2230** that ML model(s) **2225** generate by processing the input(s) **2205** (e.g., the information **2210** and/or the previous output(s) **2215**) can include analysis **2235**, recommendation(s) **2240**, and/or RAG query(s) **2245**. The analysis **2235** can include, for instance, analyses of image(s) (e.g., from the imaging system **200**), analyses of sample(s) (e.g., from a sampling fluid port for extraction of samples from the incubated chamber **139**), analyses of sensor data (e.g., from the sensors of the incubator system **100** and/or the imaging system **200**), or a combination thereof. In some examples, the analysis **2235** can include feature extraction, feature detection, feature recognition, feature tracking, object detection, object recognition and/or object tracking analyses (e.g., from images captured by the imaging system **200**), for instance to track how different cells and/or materials (e.g., pharmaceuticals, drugs, infections) (e.g., with or without luminescence via luminescent markers) move throughout the incubated chamber **139**. In some examples, the analysis **2235** can include mass spectrometry analyses.

[0158] The recommendation(s) **2240** can include, for instance, recommendation(s) to modify the fluid(s), the gas(es), the cell(s), the reagent(s) (e.g., pharmaceuticals, drugs, markers), and/or other materials provided to the incubated chamber **139** (e.g., via an input fluid port of the fluidic subsystem **109** and/or gas subsystem **112**), recommendation(s) to adjust a temperature (e.g., via the thermal control subsystem **132**), recommendation(s) to adjust a humidity (e.g., via the humidity

wick **126**), recommendation(s) to adjust a gas level (e.g., of CO.sub.2, O.sub.2, N.sub.2, or another gas) (e.g., via the gas subsystem **112**), recommendation(s) to actuate a valve (e.g., of the fluidic subsystem **109**, the gas subsystem **112**, the pneumatic interface subsystem **117**, the fluidic interface subsystem **127**, the check valve **130**, the relief valve **142**) to switch the valve from one state to another state (e.g., between an open state and a closed state), recommendation(s) to capture image(s) (e.g., using the imaging system **200**), recommendation(s) to adjust lighting (e.g., via the illumination source **204**), to adjust pH (e.g., via the fluidic subsystem **109**, the gas subsystem **112**, the pneumatic interface subsystem **117**, and/or the fluidic interface subsystem **127**), or a combination thereof. In some examples, the recommendation(s) **2240** can be output to a user (e.g., via the user interface subsystem **103** and/or the imaging system **200** and or a cloud-based interface), for instance to allow the user to decide whether to implement the recommended actions, and to allow the user to implement the recommended actions themselves. In some examples, the recommendation(s) **2240** can be output to a system or subsystem (e.g., any of the subsystems and/or components of the incubator system **100**, any of the subsystems and/or components of the imaging system **200**, any of the subsystems and/or components of the incubator system **300**, or a combination thereof) that can automatically implement the recommended actions, for instance by actuating actuators that change the state of a valve, by adjusting an illumination level of the illumination source **204**, by causing a camera (e.g., imaging system **200**) to capture an image and/or video, by adjusting temperature and/or humidity and/or gas composition and/or liquid composition and/or pH and/or another characteristic, or a combination thereof.

[0159] The ML model(s) **2225** can generate the each of the output(s) **2230** based on the information **2210**, information from the data store(s) **2270**, and/or other types of input(s) **2205** (e.g., previous output(s) **2215**).

[0160] In some examples, the ML model(s) **2225** can identify something in the input(s) **2205** about which the data store(s) **2270** include additional information, and can fashion at least one query (e.g., the RAG query(s) **2245**) for the data store(s) **2270** to retrieve the additional information from the data store(s) **2270**. For instance, if the information **2210** references a specific model of device, the RAG query(s) **2245** can include one or more queries of the data store(s) **2270** for additional information about the specific model of device, for instance to retrieve its components, configurations, settings, firmware updates, ranges of optimal operating parameters (e.g., temperature, clock speed, and so forth), or a combination thereof. If the information **2210** references a specific type of cell or drug, the RAG query(s) **2245** can include one or more queries of the data store(s) **2270** for additional information about the specific type of cell or drug, for instance to retrieve its optimal temperatures, humidity levels, acidity levels (e.g., pH), light levels, or a combination thereof. The additional information retrieved from the data store(s) **2270** using the RAG query(s) **2245** can be used as part of the input(s) **2205** (e.g., as part of the information **2210** and/or part of the previous output(s) **2215**) for further passes of data processing by the ML model(s) **2225**.

[0161] In some examples, certain output(s) **2230** (e.g., the analysis **2235**, the recommendation(s) **2240**, the RAG query(s) **2245**) can be used as part of the input(s) **2205** to the ML model(s) **2225** (e.g., as part of previous output(s) **2215**) for identifying other output(s) **2230** (e.g., the analysis **2235**, the recommendation(s) **2240**, the RAG query(s) **2245**). For instance, in an illustrative example, the analysis **2235** can be processed, as previous output(s) **2215**, by the ML model(s) **2225** to generate the recommendation(s) **2240**, the RAG query(s) **2245**, and/or other output(s) **2230**. In some examples, at least some of the previous output(s) **2215** in the input(s) **2205** represent previously-identified instances of some of the output(s) **2230** that are input into the ML model(s) **2225** to generate other types of the output(s) **2230**. In some examples, based on receipt of the input(s) **2205**, the ML model(s) **2225** can select the output(s) **2230** from a list of possible outputs, for instance by ranking the list of possible outputs by likelihood, probability, and/or confidence based on the input(s) **2205**. In some examples, based on receipt of the input(s) **2205**, the ML

model(s) **2225** can identify the output(s) **2230** at least in part using generative artificial intelligence (AI) content generation techniques, for instance using an LLM to generate custom text and/or graphics identifying the output(s) **2230**. In some examples, the LLM-based output(s) **2230** are conversationally responsive to a prompt in the input(s) **2205** (e.g., in the information **2210** and/or in the previous output(s) **2215**).

[0162] In some examples, the ML system repeats the process illustrated in FIG. **22** multiple times to generate the output(s) **2230** in multiple passes, using some of the output(s) **2230** from earlier passes as some of the input(s) **2205** in later passes (e.g., as some of the previous output(s) **2215**). For instance, in a first illustrative example, in a first pass, the ML model(s) **2225** can identify the analysis **2235** based on input of the information **2210** into the ML model(s) **2225**. In a second pass, the ML model(s) **2225** can identify the recommendation(s) **2240** based on input of the information **2210** and the previous output(s) **2215** (that includes the analysis **2235** from the first pass) into the ML model(s) **2225**.

[0163] In some examples, the ML system includes one or more feedback engine(s) **2250** that generate and/or provide feedback **2255** about the output(s) **2230**. In some examples, the feedback **2255** indicates how well the output(s) **2230** align to corresponding expected output(s), how well the output(s) **2230** serve their intended purpose, or a combination thereof. In some examples, the feedback engine(s) **2250** include loss function(s), reward model(s) (e.g., other ML model(s) that are used to score the output(s) **2230**), discriminator(s), error function(s) (e.g., in back-propagation), user interface feedback received via a user interface from a user, or a combination thereof. In some examples, the feedback **2255** can include one or more alignment analysis that score a level of alignment between the output(s) **2230** and the expected output(s) and/or intended purpose.

[0164] The ML engine **2220** of the ML system can update (further train) the ML model(s) **2225** based on the feedback **2255** to perform an update **2260** (e.g., further training) of the ML model(s) **2225** based on the feedback **2255**. In some examples, the feedback **2255** includes positive feedback, for instance indicating that the output(s) **2230** closely align with expected output(s) and/or that the output(s) **2230** serve their intended purpose. In some examples, the feedback **2255** includes negative feedback, for instance indicating a mismatch between the output(s) **2230** and the expected output(s), and/or that the output(s) **2230** do not serve their intended purpose. For instance, high amounts of loss and/or error (e.g., exceeding a threshold) can be interpreted as negative feedback, while low amounts of loss and/or error (e.g., less than a threshold) can be interpreted as positive feedback. Similarly, high amounts of alignment (e.g., exceeding a threshold) can be interpreted as positive feedback, while low amounts of alignment (e.g., less than a threshold) can be interpreted as negative feedback.

[0165] In response to positive feedback in the feedback **2255**, the ML engine **2220** can perform the update **2260** to update the ML model(s) **2225** to strengthen and/or reinforce weights (and/or connections and/or hyperparameters) associated with generation of the output(s) **2230** to encourage the ML engine **2220** to generate similar output(s) **2230** given similar input(s) **2205**. In this way, the update **2260** can improve the ML model(s) **2225** itself by improving the accuracy of the ML model(s) **2225** in generating output(s) **2230** that are similarly accurate given similar input(s) **2205**. In response to negative feedback in the feedback **2255**, the ML engine **2220** can perform the update **2260** to update the ML model(s) **2225** to weaken and/or remove weights (and/or connections and/or hyperparameters) associated with generation of the output(s) **2230** to discourage the ML engine **2220** from generating similar output(s) **2230** given similar input(s) **2205**. In this way, the update **2260** can improve the ML model(s) **2225** itself by improving the accuracy of the ML model(s) **2225** in generating output(s) **2230** are more accurate given similar input(s) **2205**. In some examples, for instance, the update **2260** can improve the accuracy of the ML model(s) **2225** in generating output(s) **2230** by reducing false positive(s) and/or false negative(s) in the output(s) **2230**.

[0166] For instance, here, if the analysis **2235** and/or recommendation(s) **2240** are used in an

experiment, and the experiment is successful, the success of the experiment can be interpreted as feedback **2255** that is positive (e.g., positive feedback). For instance, here, if the analysis **2235** and/or recommendation(s) **2240** are used in an experiment, and the experiment fails or is unsuccessful, the failure or lack of success of the experiment can be interpreted as feedback **2255** that is negative (e.g., negative feedback). Either way, the update **2260** can improve the machine learning system **2200** and the overall system by improving the consistency with which the experiment is successful.

[0167] In some examples, the ML engine **2220** can also perform an initial training of the ML model(s) **2225** before the ML model(s) **2225** are used to generate the output(s) **2230** based on the input(s) **2205**. During the initial training, the ML engine **2220** can train the ML model(s) **2225** based on training data **2265**. In some examples, the training data **2265** includes examples of input(s) (of any input types discussed with respect to the input(s) **2205**), output(s) (of any output types discussed with respect to the output(s) **2230**), and/or feedback (of any feedback types discussed with respect to the feedback **2255**). In some cases, positive feedback in the training data **2265** can be used to perform positive training, to encourage the ML model(s) **2225** to generate output(s) similar to the output(s) in the training data given input of the corresponding input(s) in the training data. In some cases, negative feedback in the training data **2265** can be used to perform negative training, to discourage the ML model(s) **2225** from generate output(s) similar to the output(s) in the training data given input of the corresponding input(s) in the training data. In some examples, the training of the ML model(s) **2225** (e.g., the initial training with the training data **2265**, update(s) **2260** based on the feedback **2255**, and/or other modification(s)) can include fine-tuning of the ML model(s) **2225**, retraining of the ML model(s) **2225**, or a combination thereof.

[0168] In some examples, the ML model(s) **2225** can include an ensemble of multiple ML models, and the ML engine **2220** can curate and manage the ML model(s) **2225** in the ensemble. The ensemble can include ML model(s) **2225** that are different from one another to produce different respective outputs, which the ML engine **2220** can average (e.g., mean, median, and/or mode) to identify the output(s) **2230**. In some examples, the ML engine **2220** can calculate the standard deviation of the respective outputs of the different ML model(s) **2225** in the ensemble to identify a level of confidence in the output(s) **2230**. In some examples, the standard deviation can have an inverse relationship with confidence. For instance, if the respective outputs of the different ML model(s) **2225** are very different from one another (and thus have a high standard deviation above a threshold), the confidence that the output(s) **2230** are accurate may be low (e.g., below a threshold). On the other hand, if the respective outputs of the different ML model(s) **2225** are equal or very similar to one another (and thus have a low standard deviation below a threshold), the confidence that the output(s) **2230** are accurate may be high (e.g., above a threshold). In some examples, different ML models(s) **2225** in the ensemble can include different types of models. For instance, in some examples, an ensemble can include a NN and a SVM that are both trained to process the input(s) **2205** to generate at least a subset of the output(s) **2230**. In some examples, the ensemble may include different ML model(s) **2225** that are trained to process different inputs of the input(s) **2205** and/or to generate different outputs of the output(s) **2230**. For instance, in some examples, a first model (or set of models) can process the input(s) **2205** to generate the analysis **2235**, a second model (or set of models) can process the input(s) **2205** to generate the recommendation(s) **2240**, and a third model (or set of models) can process the input(s) **2205** to generate the RAG query(s) **2245**. In some examples, the ML engine **2220** can choose specific ML model(s) **2225** to be included in the ensemble because the chosen ML model(s) **2225** are effective at accurately processing particular types of input(s) **2205**, are effective at accurately generating particular types of output(s) **2230**, are generally accurate, process input(s) **2205** quickly, generate output(s) **2230** quickly, are computationally efficient, have higher or lower degrees of uncertainty than other models in the ensemble, or a combination thereof.

[0169] In some examples, one or more of the ML model(s) **2225** can be initialized with weights,

connections, and/or hyperparameters that are selected randomly. This can be referred to as random initialization. These weights, connections, and/or hyperparameters are modified over time through training (e.g., initial training with the training data **2265** and/or update(s) **2260** based on the feedback **2255**), but the random initialization can still influence the way the ML model(s) **2225** process data, and thus can still cause different ML model(s) **2225** (with different random initializations) to produce different output(s) **2230**. Thus, in some examples, different ML model(s) **2225** in an ensemble can have different random initializations.

[0170] As an ML model (of the ML model(s) **2225**) is trained (e.g., along the initial training with the training data **2265**, update(s) **2260** based on the feedback **2255**, and/or other modification(s)), different versions of the ML model at different stages of training can be referred to as checkpoints. In some examples, after each new update to a model (e.g., update **2260**) generates a new checkpoint for the model, the ML engine **2220** tests the new checkpoint (e.g., against testing data and/or validation data where the correct output(s) are known) to identify whether the new checkpoint improves over older checkpoints or not, and/or if the new checkpoint introduces new errors (e.g., false positive(s) and/or false negative(s)). This testing can be referred to as checkpoint benchmark scoring. In some examples, in checkpoint benchmark scoring, the ML engine **2220** produces a benchmark score for one or more checkpoint(s) of one or more ML model(s) **2225**, and keeps the checkpoint(s) that have the best (e.g., highest or lowest) benchmark scores in the ensemble. In some examples, if a new checkpoint is worse than an older checkpoint, the ML engine **2220** can revert to the older checkpoint. The benchmark score for a can represent a level of accuracy of the checkpoint and/or number of errors (e.g., false positive or false negative) by the checkpoint during the testing (e.g., against the testing data and/or the validation data). In some examples, an ensemble of the ML model(s) **2225** can include multiple checkpoints of the same ML model.

[0171] In some examples, the ML model(s) **2225** can be modified, either through the initial training (with the training data **2265**), an update **2260** based on the feedback **2255**, or another modification to introduce randomness, variability, and/or uncertainty into an ensemble of the ML model(s) **2225**. In some examples, such modification(s) to the ML model(s) **2225** can include dropout (e.g., Monte Carlo dropout), in which one or more weights or connections are selected at random and removed. In some examples, dropout can also be performed during inference, for instance to modify the output(s) **2230** generated by the ML model(s) **2225**. The term Bayesian Machine Learning (BML) can refer to random dropout, random initialization, and/or other randomization-based modifications to the ML model(s) **2225**. In some examples, the modification(s) to the ML model(s) **2225** can include a hyperparameter search and/or adjustment of hyperparameters. The hyperparameter search can involve training and/or updating different ML models **2225** with different values for hyperparameters and evaluating the relative performance of the ML models **2225** (e.g., against (e.g., against testing data and/or validation data where the correct output(s) are known) to identify which of the ML models **2225** performs best. Hyperparameters can include, for instance, temperature (e.g., influencing level creativity and/or randomness), top P (e.g., influencing level creativity and/or randomness), frequency penalty (e.g., to prevent repetitive language between one of the output(s) **2230** and another), presence penalty (e.g., to encourage the ML model(s) **2225** to introduce new data in the output(s) **2230**), other parameters or settings, or a combination thereof.

[0172] In some examples, the ML engine **2220** can perform retrieval-augmented generation (RAG) using the model(s) **2225**. For instance, in some examples, the ML engine **2220** can pre-process the input(s) **2205** by retrieving additional information from one or more data store(s) **2270** (e.g., any of the databases and/or other data structures discussed herein) and using the additional information to enhance the input(s) **2205** before the input(s) **2205** are processed by the ML model(s) **2225** to generate the output(s) **2230**. For instance, in some examples, the enhanced versions of the input(s) **2205** can include the additional information that the ML engine **2220** retrieved from the from one or more data store(s) **2270**. In some examples, the machine learning system **2200** can retrieve the

additional information from one or more data store(s) **2270** by querying the data store(s) **2270** using RAG query(s) **2245** generated by the ML model(s) **2225** (or extracted from the input(s) **2205** using the ML model(s) **2225**). In some examples, this RAG process provides the ML model(s) **2225** with more relevant information, allowing the ML model(s) **2225** to generate more accurate and/or personalized output(s) **2230**.

[0173] FIG. **23** is a flow diagram illustrating a process **2300** for cell incubation and imaging. The process **2300** is performed by a cell culture processing system. The cell culture processing system may be, and/or may include, the incubator system **100**, the imaging system **200**, the incubation and imaging system **300**, a system that performs the process **400**, a system that performs the process **500**, any of the components illustrated in FIGS. **6-11**, a system that uses the dashboard interface **1200**, any of the components illustrated in FIGS. **13-16**, a system that captures the phase contrast image **1700**, any of the components illustrated in FIG. **18**, the machine learning system **2200**, the ML engine **2220**, the ML model(s) **2225**, the feedback engine(s) **2250**, the computing system **2400**, a processor that executes instructions stored in a memory, a processor that executes instructions stored in a non-transitory computer-readable medium, a system, an apparatus, or a combination thereof.

[0174] At operation **2305**, the cell culture processing system is configured to, and can, receive a culture (e.g., culture dish **128**) into a chamber (e.g., incubated chamber **139**, incubation environment **815**, incubated environment **1125**) within a first housing (e.g., insulating material **122**, housing of the incubator system **100**, housing of the incubation subsystem of the incubation and imaging system **300**). The chamber includes a first imaging access port (e.g., imaging access port **129**) that is light-transmissive (e.g., transparent, translucent). In some examples, the first imaging access port is a lens. In some examples, the first imaging access port is made of glass or plastic (e.g., acrylic). In some examples, the first imaging access port is an orifice, an aperture, and/or a hole within the first housing, with a reversible environmental seal developed between the culture dish and the housing (e.g. chamber seal **140**).

[0175] At operation **2310**, in some examples, the cell culture processing system is configured to, and can, measure a property of an environment within the chamber using at least one chamber environment sensor (e.g., chamber sensor subsystem **133**). At operation **2315**, in some examples, the cell culture processing system is configured to, and can, check if the property is within a predetermined range that is associated with incubation of the culture. If the property is within the predetermined range, operation **2315** is followed by operation **2320**. If the property is outside of the predetermined range, operation **2315** is followed by operation **2325**.

[0176] At operation **2320**, the cell culture processing system is configured to, and can, control the property of the environment within the chamber using at least one chamber environment interface (e.g., fluidic subsystem **109**, gas subsystem **112**, pneumatic interface subsystem **117**, fluidic interface subsystem **127**) to maintain the property within the predetermined range. In some examples, the at least one chamber environment interface provides at least a fluid (e.g., a gas via the gas subsystem **112** and/or the **117**, and/or a liquid via the fluidic subsystem **109** and/or the fluidic interface subsystem **127**) to the chamber to maintain the property within the predetermined range.

[0177] At operation **2325**, in some examples, the cell culture processing system is configured to, and can, control the property of the environment within the chamber using at least one chamber environment interface (e.g., fluidic subsystem **109**, gas subsystem **112**, pneumatic interface subsystem **117**, fluidic interface subsystem **127**) to adjust the property toward or into the predetermined range. In some examples, the at least one chamber environment interface provides at least a fluid (e.g., a gas via the gas subsystem **112** and/or the **117**, and/or a liquid via the fluidic subsystem **109** and/or the fluidic interface subsystem **127**) to the chamber to adjust the property toward or into the predetermined range.

[0178] At operation **2330**, the cell culture processing system is configured to, and can, measure the

property of the environment within the chamber using at least one chamber environment sensor (e.g., chamber sensor subsystem **133**) to verify that the property is maintained within the predetermined range.

[0179] At operation **2335**, the cell culture processing system is configured to, and can, capture a representation (e.g., an image, a video, or another type of sensor data) of the culture within the chamber using at least one sensor through the first imaging access port and a second imaging access port while the first housing is detachably coupled to a second housing and while the property of the environment within the chamber is maintained within the predetermined range. The second housing (e.g., of the imaging system **200** and/or the imaging subsystem of the incubation and imaging system **300**) includes the at least one sensor and the second imaging access port that is light-transmissive (e.g., transparent, translucent). In some examples, the first imaging access port is a lens. In some examples, the first imaging access port is made of glass or plastic (e.g., acrylic). For instance, light from the cell culture is conveyed through both the first imaging access port and the second imaging access port before reaching the at least one sensor. In some examples, at least one of the first imaging access port and/or the second imaging access port may be an orifice, an aperture, and/or a hole within the respective housing.

[0180] In some examples, the first housing is detachably coupled to the second housing using fastener(s) on the first housing and/or the second housing. For instance the fastener(s) can include latches, magnets, pins that go into recesses, screws, clips, slide rails, elastic, seals, hook and loop fasteners, stud fasteners, other types of fasteners, or combinations thereof. In some examples, the alignment features **137** may represent examples of the fasteners on the incubator system **100**. In some examples, the alignment features **201** may represent examples of the fasteners on the imaging system **200**. In some examples, alignment features **137** and the alignment features **201** may be detachably coupled together (e.g., detachably attached, connected, secured, and/or fastened) in the incubation and imaging system **300** as illustrated in FIG. **3**. In some examples, the fastener(s) on the incubator system **100** and/or on the imaging system **200** may include electrical coupling interfaces (e.g., plugs, ports, and/or other types of electrical contacts). In some examples, electrical power can be conveyed across the electrical coupling interfaces of the fasteners while the first housing (e.g., incubator system **100**) is coupled to the second housing (e.g., imaging system **200**). In some examples, data (e.g., sensor data, instructions to the at least one chamber environment interface, instructions to the at least one sensor) can be conveyed across the electrical coupling interfaces of the fasteners while the first housing (e.g., incubator system **100**) is coupled to the second housing (e.g., imaging system **200**). In some examples, a third housing (e.g., of the fluid management system **2110**) is also coupled to the first housing (e.g., incubator system **100**) and/or the second housing (e.g., imaging system **200**) to form the incubation and imaging system **300** (e.g., as illustrated in the perspective diagram **2100**), for instance using any of the types of fasteners (e.g., with or without electrical coupling interfaces) discussed herein. In some examples, the electrical coupling interfaces can also be used to convey power and/or data between the fluid management system **2110** and the incubator system **100**, and/or between the fluid management system **2110** and the imaging system **200**.

[0181] In some examples, the at least one sensor can include an image sensor of a camera (e.g., of the imaging system **200** and/or the incubation and imaging system **300**). In some examples, the at least one sensor can include an electrical sensor that captures electrical recordings (e.g., neuronal recording) of electrical characteristics (e.g., voltage, wattage, current, electrical impedance), which may be important in some cases (e.g., where the cell cultures include neurons or other types of cells that perform electrical activity). In some examples, the at least one sensor can be referred to as a media sensor, for instance where it captures images, videos, audio, and/or other types of media content. In some examples, the at least one sensor can be referred to as a characterization sensor, in that the sensor's data represents a characterization of the status and/or behavior of the cell culture.

[0182] In some examples, the property of the environment within the chamber includes at least one

of a temperature of the environment within the chamber, a humidity of the environment within the chamber, a pressure of the environment within the chamber, a pH of the environment within the chamber, a fluidic flow rate of a fluid within the chamber, an orientation of the environment within the chamber, a level of illumination in the environment within the chamber, a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified liquid in the environment within the chamber, a concentration of a specified mixture of liquids in the environment within the chamber, concentration of a reagent in the environment within the chamber, or a combination thereof. Note that the fluid (of operation **2320** and/or operation **2325**) can be an example of the specified gas, the specified mixture of gases, the specified liquid, the specified mixture of liquids, the reagent, or a combination thereof.

[0183] In some examples, the least one chamber environment interface includes at least one of a heater that heats the environment within the chamber to increase a temperature of the environment, a cooler that cools the environment within the chamber to decrease the temperature of the environment, a humidifier that humidifies the environment within the chamber to increase a humidity of the environment, a dehumidifier that dehumidifies the environment within the chamber to decrease the humidity of the environment, a pump that adjusts a pressure in the environment within the chamber, a valve that adjusts the pressure in the environment within the chamber, a pump that adjusts a concentration of a specified gas in the environment within the chamber, a valve that adjusts the concentration of the specified gas in the environment within the chamber, a pump that adjusts a concentration of a specified mixture of gases in the environment within the chamber, a valve that adjusts the concentration of the specified mixture of gases in the environment within the chamber, a pump that adjusts a concentration of a specified fluid in a culture dish in the environment within the chamber, a valve that adjusts the concentration of the specified fluid in the culture dish in the environment within the chamber, a pump that adjusts a concentration of a specified mixture of fluids in the culture dish in the environment within the chamber, a valve that adjusts the concentration of the specified mixture of fluids in the culture dish in the environment within the chamber, at least one gas container that stores one or more specified gases to provide the one or more specified gases into the environment within the chamber, at least one fluid container that stores one or more specified fluids to provide the one or more specified fluids into the environment within the chamber, at least one gas container that stores one or more specified gases to provide the one or more specified gases into the environment within the chamber, at least one fluid container that stores one or more specified fluids to provide the one or more specified fluids into the environment within the chamber, a fan, an actuator that adjusts an orientation of the environment within the chamber, or a light source that illuminates the environment within the chamber.

[0184] In some examples, the least one chamber environment interface includes at least one of a pump or a valve, and wherein the least one chamber environment interface adjusts at least one of a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified fluid in a culture dish in the environment within the chamber, a concentration of a specified mixture of fluids in the culture dish in the environment within the chamber, a concentration of a specified reagent in the culture dish in the environment within the chamber.

[0185] In some examples, the least one chamber environment sensor includes at least one of a temperature sensor, a humidity sensor, a gas pressure sensor, a gas concentration sensor, a fluid concentration sensor, an assay sensor, a bioactivity electrical recording sensor, an orientation sensor, an image sensor, a light sensor, or a combination thereof.

[0186] In some examples, the cell culture processing system is configured to, and can, outputs a notification based on the representation of the culture using an output interface (e.g., user interface subsystem **103**, communication interface **107**, user interface subsystem **203**, communication

interface **218**). In some examples, the output interface includes at least one of a display, a speaker, a haptic feedback actuator, a wired communication interface, or a wireless communication interface. [0187] In some examples, the representation is an image, and the image is captured using an image sensor. In some examples, the image is a still image. In some examples, the image is a video frame of a video.

[0188] In some examples, the cell culture processing system is configured to, and can, analyze the representation of the culture to detect a condition, and output a notification associated with the condition. In some examples, to analyze the representation of the culture, the at least one processor processes the representation of the culture using a trained machine learning model (e.g., ML model(s) **2225**) that detects the condition based on the representation of the culture (e.g., analysis **2235**, recommendation(s) **2240**). In some examples, the cell culture processing system is configured to, and can, update (e.g., update **2260**) the trained machine learning model based on training data to improve an accuracy of the trained machine learning model. The training data includes at least one of the representation, the condition, the notification, or feedback (e.g., feedback **2255**) associated with the notification.

[0189] In some examples, the property is temperature, and controlling the property (in operation **2320** and/or operation **2325**) includes activating a heater, a fan, a cooling element (e.g., a cooler), or another component of the thermal control subsystem **132**. In some examples, the predetermined range is a range around a predetermined temperature. In some examples, the predetermined temperature is 37 degrees Celsius. In some examples, the predetermined temperature is different from 37 degrees Celsius, for instance because certain types of cells grow best at different temperatures other than 37 degrees Celsius. For instance, in some examples, the predetermined temperature is 20° C., 21° C., 22° C., 23° C., 24° C., 25° C., 26° C., 27° C., 28° C., 29° C., 30° C., 31° C., 32° C., 33° C., 34° C., 35° C., 36° C., 37° C., 38° C., 39° C., 40° C., 41° C., 42° C., 43° C., 44° C., 45° C., 46° C., 47° C., 48° C., 49° C., 50° C., a temperature in between any two of the above-listed temperatures, or another temperature.

[0190] In some examples, the property is a specific concentration of a specific gas, such as CO.sub.2. In some examples, the predetermined range is a range around a predetermined concentration. In some examples, the predetermined concentration is 5% CO.sub.2.

[0191] FIG. **24** illustrates an exemplary computing system **2400** that may be used to implement some aspects of the technology. For example, any of the computing devices, computing systems, network devices, network systems, servers, and/or arrangements of circuitry described herein may include at least one computing system **2400**, or may include at least one component of the computer system **2400** identified in FIG. **24**. The computing system **2400** of FIG. **24** includes one or more processors **2410** and memory **2420**. Each of the processor(s) **2410** may refer to one or more processors, controllers, microcontrollers, central processing units (CPUs), graphics processing units (GPUs), arithmetic logic units (ALUs), accelerated processing units (APUs), digital signal processors (DSPs), application specific integrated circuits (ASICs), field-programmable gate arrays (FPGAs), or combinations thereof. Each of the processor(s) **2410** may include one or more cores, either integrated onto a single chip or spread across multiple chips connected or coupled together. Memory **2420** stores, in part, instructions and data for execution by processor **2410**. Memory **2420** can store the executable code when in operation. The computing system **2400** of FIG. **24** further includes a mass storage device **2430**, portable storage device(s) **2440** (e.g., drive(s) and/or other storage media), output devices **2450**, user input devices **2460**, a display system **2470** (e.g., graphics display), and peripheral device(s) **2480**.

[0192] The components shown in FIG. **24** are depicted as being connected via a single bus **2490**. However, the components may be connected through one or more data transport means. For example, processor **2410** and memory **2420** may be connected via a local microprocessor bus, and the mass storage device **2430**, peripheral device(s) **2480**, portable storage device **2440**, and display system **2470** may be connected via one or more input/output (I/O) buses.

[0193] Mass storage device **2430**, which may be implemented with a magnetic disk drive or an optical disk drive, is a non-volatile storage device for storing data and instructions for use by processor **2410**. Mass storage device **2430** can store the system software for implementing some aspects of the subject technology for purposes of loading that software into memory **2420**.

[0194] Portable storage device **2440** operates in conjunction with a portable non-volatile storage medium, such as a floppy disk, compact disk or Digital video disc, to input and output data and code to and from the computer system **2400** of FIG. **24**. The system software for implementing aspects of the subject technology may be stored on such a portable medium and input to the computer system **2400** via the portable storage device **2440**.

[0195] The memory **2420**, mass storage device **2430**, or portable storage device **2440** may in some cases store sensitive information, such as transaction information, health information, or cryptographic keys, and may in some cases encrypt or decrypt such information with the aid of the processor **2410**. The memory **2420**, mass storage device **2430**, or portable storage device **2440** may in some cases store, at least in part, instructions, executable code, or other data for execution or processing by the processor **2410**.

[0196] Output devices **2450** may include, for example, communication circuitry for outputting data through wired or wireless means, display circuitry for displaying data via a display screen, audio circuitry for outputting audio via headphones or a speaker, printer circuitry for printing data via a printer, or some combination thereof. The display screen may be any type of display discussed with respect to the display system **2470**. The printer may be inkjet, laserjet, thermal, or some combination thereof. In some cases, the output device **2450** (and/or associated circuitry) may allow for transmission of data over an audio jack/plug, a microphone jack/plug, a universal serial bus (USB) port/plug, an Apple® Lightning® port/plug, an Ethernet port/plug, a fiber optic port/plug, a proprietary wired port/plug, a BLUETOOTH® wireless signal transfer, a BLUETOOTH® low energy (BLE) wireless signal transfer, an IBEACON® wireless signal transfer, a radio-frequency identification (RFID) wireless signal transfer, near-field communications (NFC) wireless signal transfer, dedicated short range communication (DSRC) wireless signal transfer, 502.11 Wi-Fi wireless signal transfer, wireless local area network (WLAN) signal transfer, Visible Light Communication (VLC), Worldwide Interoperability for Microwave Access (WiMAX), Infrared (IR) communication wireless signal transfer, Public Switched Telephone Network (PSTN) signal transfer, Integrated Services Digital Network (ISDN) signal transfer, 3G/4G/5G/LTE cellular data network wireless signal transfer, ad-hoc network signal transfer, radio wave signal transfer, microwave signal transfer, infrared signal transfer, visible light signal transfer, ultraviolet light signal transfer, wireless signal transfer along the electromagnetic spectrum, or some combination thereof. Output devices **2450** may include any ports, plugs, antennae, wired or wireless transmitters, wired or wireless transceivers, or any other components necessary for or usable to implement the communication types listed above, such as cellular Subscriber Identity Subsystem (SIM) cards.

[0197] Input devices **2460** may include circuitry providing a portion of a user interface. Input devices **2460** may include an alpha-numeric keypad, such as a keyboard, for inputting alpha-numeric and other information, or a pointing device, such as a mouse, a trackball, stylus, or cursor direction keys. Input devices **2460** may include touch-sensitive surfaces as well, either integrated with a display as in a touchscreen, or separate from a display as in a trackpad. Touch-sensitive surfaces may in some cases detect localized variable pressure or force detection. In some cases, the input device circuitry may allow for receipt of data over an audio jack, a microphone jack, a universal serial bus (USB) port/plug, an Apple® Lightning® port/plug, an Ethernet port/plug, a fiber optic port/plug, a proprietary wired port/plug, a wired local area network (LAN) port/plug, a BLUETOOTH® wireless signal transfer, a BLUETOOTH® low energy (BLE) wireless signal transfer, an IBEACON® wireless signal transfer, a radio-frequency identification (RFID) wireless signal transfer, near-field communications (NFC) wireless signal transfer, dedicated short range

communication (DSRC) wireless signal transfer, 502.11 Wi-Fi wireless signal transfer, wireless local area network (WLAN) signal transfer, Visible Light Communication (VLC), Worldwide Interoperability for Microwave Access (WiMAX), Infrared (IR) communication wireless signal transfer, Public Switched Telephone Network (PSTN) signal transfer, Integrated Services Digital Network (ISDN) signal transfer, 3G/4G/5G/LTE cellular data network wireless signal transfer, personal area network (PAN) signal transfer, wide area network (WAN) signal transfer, ad-hoc network signal transfer, radio wave signal transfer, microwave signal transfer, infrared signal transfer, visible light signal transfer, ultraviolet light signal transfer, wireless signal transfer along the electromagnetic spectrum, or some combination thereof. Input devices **2460** may include any ports, plugs, antennae, wired or wireless receivers, wired or wireless transceivers, or any other components necessary for or usable to implement the communication types listed above, such as cellular SIM cards.

[0198] Input devices **2460** may include receivers or transceivers used for positioning of the computing system **2400** as well. These may include any of the wired or wireless signal receivers or transceivers. For example, a location of the computing system **2400** can be determined based on signal strength of signals as received at the computing system **2400** from three cellular network towers, a process known as cellular triangulation. Fewer than three cellular network towers can also be used—even one can be used—though the location determined from such data will be less precise (e.g., somewhere within a particular circle for one tower, somewhere along a line or within a relatively small area for two towers) than via triangulation. More than three cellular network towers can also be used, further enhancing the location's accuracy. Similar positioning operations can be performed using proximity beacons, which might use short-range wireless signals such as BLUETOOTH® wireless signals, BLUETOOTH® low energy (BLE) wireless signals, IBEACON® wireless signals, personal area network (PAN) signals, microwave signals, radio wave signals, or other signals discussed above. Similar positioning operations can be performed using wired local area networks (LAN) or wireless local area networks (WLAN) where locations are known of one or more network devices in communication with the computing system **2400** such as a router, modem, switch, hub, bridge, gateway, or repeater. These may also include Global Navigation Satellite System (GNSS) receivers or transceivers that are used to determine a location of the computing system **2400** based on receipt of one or more signals from one or more satellites associated with one or more GNSS systems. GNSS systems include, but are not limited to, the US-based Global Positioning System (GPS), the Russia-based Global Navigation Satellite System (GLONASS), the China-based BeiDou Navigation Satellite System (BDS), and the Europe-based Galileo GNSS. Input devices **2460** may include receivers or transceivers corresponding to one or more of these GNSS systems.

[0199] Display system **2470** may include a liquid crystal display (LCD), a plasma display, an organic light-emitting diode (OLED) display, a low-temperature poly-silicon (LTPO) display, an electronic ink or “e-paper” display, a projector-based display, a holographic display, or another suitable display device. Display system **2470** receives textual and graphical information, and processes the information for output to the display device. The display system **2470** may include multiple-touch touchscreen input capabilities, such as capacitive touch detection, resistive touch detection, surface acoustic wave touch detection, or infrared touch detection. Such touchscreen input capabilities may or may not allow for variable pressure or force detection.

[0200] Peripheral device(s) **2480** may include any type of computer support device to add additional functionality to the computer system. For example, peripheral device(s) **2480** may include one or more additional output devices of any of the types discussed with respect to output device **2450**, one or more additional input devices of any of the types discussed with respect to input device **2460**, one or more additional display systems of any of the types discussed with respect to display system **2470**, one or more memories or mass storage devices or portable storage devices of any of the types discussed with respect to memory **2420** or mass storage device **2430** or

portable storage device **2440**, a modem, a router, an antenna, a wired or wireless transceiver, a printer, a bar code scanner, a quick-response (“QR”) code scanner, a magnetic stripe card reader, a integrated circuit chip (ICC) card reader such as a smartcard reader or a EUROPAY®-MASTERCARD®-VISA® (EMV) chip card reader, a near field communication (NFC) reader, a document/image scanner, a visible light camera, a thermal/infrared camera, an ultraviolet-sensitive camera, a night vision camera, a light sensor, a phototransistor, a photoresistor, a thermometer, a thermistor, a battery, a power source, a proximity sensor, a laser rangefinder, a sonar transceiver, a radar transceiver, a lidar transceiver, a network device, a motor, an actuator, a pump, a conveyer belt, a robotic arm, a rotor, a drill, a chemical assay device, or some combination thereof.

[0201] The components contained in the computer system **2400** of FIG. **24** can include those typically found in computer systems that may be suitable for use with some aspects of the subject technology and represent a broad category of such computer components that are well known in the art. That said, the computer system **2400** of FIG. **24** can be customized and specialized for the purposes discussed herein and to carry out the various operations discussed herein, with specialized hardware components, specialized arrangements of hardware components, and/or specialized software. Thus, the computer system **2400** of FIG. **24** can be a personal computer, a hand held computing device, a telephone (“smartphone” or otherwise), a mobile computing device, a workstation, a server (on a server rack or otherwise), a minicomputer, a mainframe computer, a tablet computing device, a wearable device (such as a watch, a ring, a pair of glasses, or another type of jewelry or clothing or accessory), a video game console (portable or otherwise), an e-book reader, a media player device (portable or otherwise), a vehicle-based computer, another type of computing device, or some combination thereof. The computer system **2400** may in some cases be a virtual computer system executed by another computer system. The computer can also include different bus configurations, networked platforms, multi-processor platforms, etc. Various operating systems can be used including Unix®, Linux®, FreeBSD®, FreeNAS®, pfSense®, Windows®, Apple® Macintosh OS® (“MacOS®”), Palm OS®, Google® Android®, Google® Chrome OS®, Chromium® OS®, OPENSTEP®, XNU®, Darwin®, Apple® iOS®, Apple® tvOS®, Apple® watchOS®, Apple® audioOS®, Amazon® Fire OS®, Amazon® Kindle OS®, variants of any of these, other suitable operating systems, or combinations thereof. The computer system **2400** may also use a Basic Input/Output System (BIOS) or Unified Extensible Firmware Interface (UEFI) as a layer upon which the operating system(s) are run.

[0202] In some cases, the computer system **2400** may be part of a multi-computer system that uses multiple computer systems **2400**, each for one or more specific tasks or purposes. For example, the multi-computer system may include multiple computer systems **2400** communicatively coupled together via at least one of a personal area network (PAN), a local area network (LAN), a wireless local area network (WLAN), a municipal area network (MAN), a wide area network (WAN), or some combination thereof. The multi-computer system may further include multiple computer systems **2400** from different networks communicatively coupled together via the internet (also known as a “distributed” system).

[0203] Some aspects of the subject technology may be implemented in an application that may be operable using a variety of devices. Non-transitory computer-readable storage media refer to any medium or media that participate in providing instructions to a central processing unit (CPU) for execution and that may be used in the memory **2420**, the mass storage device **2430**, the portable storage device **2440**, or some combination thereof. Such media can take many forms, including, but not limited to, non-volatile and volatile media such as optical or magnetic disks and dynamic memory, respectively. Some forms of non-transitory computer-readable media include, for example, a floppy disk, a flexible disk, a hard disk, magnetic tape, a magnetic strip/stripe, any other magnetic storage medium, flash memory, memristor memory, any other solid-state memory, a compact disc read only memory (CD-ROM) optical disc, a rewritable compact disc (CD) optical disc, digital video disk (DVD) optical disc, a blu-ray disc (BDD) optical disc, a holographic optical

disk, another optical medium, a secure digital (SD) card, a micro secure digital (microSD) card, a Memory Stick® card, a smartcard chip, a EMV chip, a subscriber identity subsystem (SIM) card, a mini/micro/nano/pico SIM card, another integrated circuit (IC) chip/card, random access memory (RAM), static RAM (SRAM), dynamic RAM (DRAM), read-only memory (ROM), programmable read-only memory (PROM), erasable programmable read-only memory (EPROM), electrically erasable programmable read-only memory (EEPROM), flash EPROM (FLASH-EPROM), cache memory (L1/L2/L3/L4/L5/L7), resistive random-access memory (RRAM/ReRAM), phase change memory (PCM), spin transfer torque RAM (STT-RAM), another memory chip or cartridge, or a combination thereof.

[0204] Various forms of transmission media may be involved in carrying one or more sequences of one or more instructions to a processor **2410** for execution. A bus **2490** carries the data to system RAM or another memory **2420**, from which a processor **2410** retrieves and executes the instructions. The instructions received by system RAM or another memory **2420** can optionally be stored on a fixed disk (mass storage device **2430**/portable storage device **2440**) either before or after execution by processor **2410**. Various forms of storage may likewise be implemented as well as the necessary network interfaces and network topologies to implement the same.

[0205] While various flow diagrams and block diagrams provided and described above may show a particular order of operations performed by some embodiments of the subject technology, it should be understood that such order is exemplary. Alternative embodiments may perform the operations in a different order, combine certain operations, overlap certain operations, or some combination thereof. It should be understood that unless disclosed otherwise, any process illustrated in any flow diagram herein or otherwise illustrated or described herein may be performed by a machine, mechanism, and/or computing system **2400** discussed herein, and may be performed automatically (e.g., in response to one or more triggers/conditions described herein), autonomously, semi-autonomously (e.g., based on received instructions), or a combination thereof. Furthermore, any action described herein as occurring in response to one or more particular triggers/conditions should be understood to optionally occur automatically response to the one or more particular triggers/conditions.

[0206] The foregoing detailed description of the technology has been presented for purposes of illustration and description. It is not intended to be exhaustive or to limit the technology to the precise form disclosed. Many modifications and variations are possible in light of the above teaching. The described embodiments were chosen in order to best explain the principles of the technology, its practical application, and to enable others skilled in the art to utilize the technology in various embodiments and with various modifications as are suited to the particular use contemplated. It is intended that the scope of the technology be defined by the claim.

[0207] Illustrative aspects of the disclosure include: [0208] Aspect 1. A system for culture processing, the system comprising: a first housing around a chamber, wherein the chamber receives a culture, and wherein the first housing includes a first imaging access port that is light-transmissive; at least one chamber environment interface that controls a property of an environment within the chamber to maintain the property within a predetermined range, wherein the predetermined range is associated with incubation of the culture; at least one chamber environment sensor that measures the property of the environment within the chamber to verify that the property is maintained within the predetermined range; and at least one sensor within a second housing, wherein the second housing includes a second imaging access port that is light-transmissive, and wherein the at least one sensor captures a representation of the culture within the chamber through the first imaging access port and the second imaging access port while the first housing is detachably coupled to the second housing and while the property of the environment within the chamber is maintained within the predetermined range. [0209] Aspect 2. The system of Aspect 1, wherein the property of the environment within the chamber includes at least one of a temperature of the environment within the chamber, a humidity of the environment within the chamber, a

pressure of the environment within the chamber, a pH of the environment within the chamber, a fluidic flow rate of a fluid within the chamber, an orientation of the environment within the chamber, or a level of illumination in the environment within the chamber. [0210] Aspect 3. The system of any one of Aspects 1 to 2, wherein the property of the environment within the chamber includes a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified liquid in the environment within the chamber, a concentration of a specified mixture of liquids in the environment within the chamber, or concentration of a reagent in the environment within the chamber. [0211] Aspect 4. The system of any one of Aspects 1 to 3, wherein the least one chamber environment interface includes at least one of a heater that heats the environment within the chamber to increase a temperature of the environment, a cooler that cools the environment within the chamber to decrease the temperature of the environment, a humidifier that humidifies the environment within the chamber to increase a humidity of the environment, a dehumidifier that dehumidifies the environment within the chamber to decrease the humidity of the environment, a pump that adjusts at least one of a pressure in the environment within the chamber or a flow rate of a fluid in the environment within the chamber, a valve that adjusts at least one of the pressure in the environment within the chamber or the flow rate of the fluid in the environment within the chamber, a fan that facilitates airflow within the chamber, an actuator that adjusts an orientation of the environment within the chamber, or a light source that illuminates the environment within the chamber. [0212] Aspect 5. The system of any one of Aspects 1 to 4, wherein the least one chamber environment interface includes at least one of a pump or a valve, and wherein the least one chamber environment interface adjusts at least one of a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified fluid in a culture dish in the environment within the chamber, a concentration of a specified mixture of fluids in the culture dish in the environment within the chamber, a concentration of a specified reagent in the culture dish in the environment within the chamber. [0213] Aspect 6. The system of any one of Aspects 1 to 5, wherein the least one chamber environment sensor includes at least one of a temperature sensor, a humidity sensor, a gas pressure sensor, a gas concentration sensor, a fluid concentration sensor, a fluid flow rate sensor, an assay sensor, a bioactivity electrical recording sensor, an orientation sensor, or a light sensor. [0214] Aspect 7. The system of any one of Aspects 1 to 6, further comprising: at least one output interface that outputs a notification based on the representation of the culture. [0215] Aspect 8. The system of Aspect 7, wherein the at least one output interface includes at least one of a display, a speaker, a haptic feedback actuator, a wired communication interface, or a wireless communication interface. [0216] Aspect 9. The system of any one of Aspects 1 to 8, wherein the at least one sensor includes at least one image sensor, and wherein the representation of the culture includes at least one image of the culture. [0217] Aspect 10. The system of any one of Aspects 1 to 9, further comprising: at least one memory storing instructions; and at least one processor, wherein execution of the instructions by the at least one processor causes the at least one processor to: analyze the representation of the culture to detect a condition; and output a notification that is indicative of the condition. [0218] Aspect 11. The system of Aspect 10, wherein, to analyze the representation of the culture, the at least one processor processes the representation of the culture using a trained machine learning model that detects the condition based on the representation of the culture. [0219] Aspect 12. The system of Aspect 11, wherein the execution of the instructions by the at least one processor causes the at least one processor to: update the trained machine learning model based on training data to improve an accuracy of the trained machine learning model, wherein the training data includes at least one of the representation, the condition, the notification, or feedback associated with the notification. [0220] Aspect 13. A method of culture processing, the method comprising: receiving a culture into a chamber within a first housing, wherein the first housing includes a first imaging access port that

is light-transmissive; controlling a property of an environment within the chamber using at least one chamber environment interface to maintain the property within a predetermined range, wherein the predetermined range is associated with incubation of the culture; measuring the property of the environment within the chamber using at least one chamber environment sensor to verify that the property is maintained within the predetermined range; and capturing a representation of the culture within the chamber using at least one sensor through the first imaging access port and a second imaging access port while the first housing is detachably coupled to a second housing and while the property of the environment within the chamber is maintained within the predetermined range, wherein the second housing includes the at least one sensor and the second imaging access port that is light-transmissive. [0221] Aspect 14. The method of Aspect 13, wherein the property of the environment within the chamber includes at least one of a temperature of the environment within the chamber, a humidity of the environment within the chamber, a pressure of the environment within the chamber, a pH of the environment within the chamber, a fluidic flow rate of a fluid within the chamber, an orientation of the environment within the chamber, or a level of illumination in the environment within the chamber. [0222] Aspect 15. The method of any one of Aspects 13 to 14, wherein the property of the environment within the chamber includes a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified liquid in the environment within the chamber, a concentration of a specified mixture of liquids in the environment within the chamber, or concentration of a reagent in the environment within the chamber. [0223] Aspect 16. The method of any one of Aspects 13 to 15, wherein the least one chamber environment interface includes at least one of a heater that heats the environment within the chamber to increase a temperature of the environment, a cooler that cools the environment within the chamber to decrease the temperature of the environment, a humidifier that humidifies the environment within the chamber to increase a humidity of the environment, a dehumidifier that dehumidifies the environment within the chamber to decrease the humidity of the environment, a pump that adjusts at least one of a pressure in the environment within the chamber or a flow rate of a fluid in the environment within the chamber, a valve that adjusts at least one of the pressure in the environment within the chamber or the flow rate of the fluid in the environment within the chamber, a fan that facilitates airflow within the chamber, an actuator that adjusts an orientation of the environment within the chamber, or a light source that illuminates the environment within the chamber. [0224] Aspect 17. The method of any one of Aspects 13 to 16, wherein the least one chamber environment interface includes at least one of a pump or a valve, and wherein the least one chamber environment interface adjusts at least one of a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified fluid in a culture dish in the environment within the chamber, a concentration of a specified mixture of fluids in the culture dish in the environment within the chamber, a concentration of a specified reagent in the culture dish in the environment within the chamber. [0225] Aspect 18. The method of any one of Aspects 13 to 17, wherein the least one chamber environment sensor includes at least one of a temperature sensor, a humidity sensor, a gas pressure sensor, a gas concentration sensor, a fluid concentration sensor, a fluid flow rate sensor, an assay sensor, a bioactivity electrical recording sensor, an orientation sensor, or a light sensor. [0226] Aspect 19. The method of any one of Aspects 13 to 18, further comprising: outputting, through at least one output interface, a notification based on the representation of the culture. [0227] Aspect 20. The method of Aspect 19, wherein the at least one output interface includes at least one of a display, a speaker, a haptic feedback actuator, a wired communication interface, or a wireless communication interface. [0228] Aspect 21. The method of any one of Aspects 13 to 20, wherein the representation is captured by at least one image sensor, and wherein the representation of the culture includes at least one image of the culture. [0229] Aspect 22. The method of any one of Aspects 13 to 21, further comprising: analyzing the representation of the

culture to detect a condition; and outputting a notification that is indicative of the condition. [0230] Aspect 23. The method of Aspect 22, wherein, analyzing the representation of the culture includes processing the representation of the culture using a trained machine learning model that detects the condition based on the representation of the culture. [0231] Aspect 24. The method of Aspect 23, further comprising: updating the trained machine learning model based on training data to improve an accuracy of the trained machine learning model, wherein the training data includes at least one of the representation, the condition, the notification, or feedback associated with the notification. [0232] Aspect 25. A non-transitory computer-readable medium having stored thereon instructions that, when executed by one or more processors, cause the one or more processors to perform operations according to any of Aspects 1 to 24. [0233] Aspect 26. An apparatus for culture processing, the apparatus comprising one or more means for performing operations according to any of Aspects 1 to 24.

Claims

1. A system for culture processing, the system comprising: a first housing around a chamber, wherein the chamber receives a culture, and wherein the first housing includes a first imaging access port that is light-transmissive; at least one chamber environment interface that controls a property of an environment within the chamber to maintain the property within a predetermined range, wherein the predetermined range is associated with incubation of the culture; at least one chamber environment sensor that measures the property of the environment within the chamber to verify that the property is maintained within the predetermined range; and at least one sensor within a second housing, wherein the second housing includes a second imaging access port that is light-transmissive, and wherein the at least one sensor captures a representation of the culture within the chamber through the first imaging access port and the second imaging access port while the first housing is detachably coupled to the second housing and while the property of the environment within the chamber is maintained within the predetermined range.
2. The system of claim 1, wherein the property of the environment within the chamber includes at least one of a temperature of the environment within the chamber, a humidity of the environment within the chamber, a pressure of the environment within the chamber, a pH of the environment within the chamber, a fluidic flow rate of a fluid within the chamber, an orientation of the environment within the chamber, or a level of illumination in the environment within the chamber.
3. The system of claim 1, wherein the property of the environment within the chamber includes a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified liquid in the environment within the chamber, a concentration of a specified mixture of liquids in the environment within the chamber, or concentration of a reagent in the environment within the chamber.
4. The system of claim 1, wherein the least one chamber environment interface includes at least one of a heater that heats the environment within the chamber to increase a temperature of the environment, a cooler that cools the environment within the chamber to decrease the temperature of the environment, a humidifier that humidifies the environment within the chamber to increase a humidity of the environment, a dehumidifier that dehumidifies the environment within the chamber to decrease the humidity of the environment, a pump that adjusts at least one of a pressure in the environment within the chamber or a flow rate of a fluid in the environment within the chamber, a valve that adjusts at least one of the pressure in the environment within the chamber or the flow rate of the fluid in the environment within the chamber, a fan that facilitates airflow within the chamber, an actuator that adjusts an orientation of the environment within the chamber, or a light source that illuminates the environment within the chamber.
5. The system of claim 1, wherein the least one chamber environment interface includes at least one

of a pump or a valve, and wherein the least one chamber environment interface adjusts at least one of a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified fluid in a culture dish in the environment within the chamber, a concentration of a specified mixture of fluids in the culture dish in the environment within the chamber, a concentration of a specified reagent in the culture dish in the environment within the chamber.

6. The system of claim 1, wherein the least one chamber environment sensor includes at least one of a temperature sensor, a humidity sensor, a gas pressure sensor, a gas concentration sensor, a fluid concentration sensor, a fluid flow rate sensor, an assay sensor, a bioactivity electrical recording sensor, an orientation sensor, or a light sensor.

7. The system of claim 1, further comprising: at least one output interface that outputs a notification based on the representation of the culture.

8. The system of claim 7, wherein the at least one output interface includes at least one of a display, a speaker, a haptic feedback actuator, a wired communication interface, or a wireless communication interface.

9. The system of claim 1, wherein the at least one sensor includes at least one image sensor, and wherein the representation of the culture includes at least one image of the culture.

10. The system of claim 1, further comprising: at least one memory storing instructions; and at least one processor, wherein execution of the instructions by the at least one processor causes the at least one processor to: analyze the representation of the culture to detect a condition; and output a notification that is indicative of the condition.

11. The system of claim 10, wherein, to analyze the representation of the culture, the at least one processor processes the representation of the culture using a trained machine learning model that detects the condition based on the representation of the culture.

12. The system of claim 11, wherein the execution of the instructions by the at least one processor causes the at least one processor to: update the trained machine learning model based on training data to improve an accuracy of the trained machine learning model, wherein the training data includes at least one of the representation, the condition, the notification, or feedback associated with the notification.

13. A method of culture processing, the method comprising: receiving a culture into a chamber within a first housing, wherein the first housing includes a first imaging access port that is light-transmissive; controlling a property of an environment within the chamber using at least one chamber environment interface to maintain the property within a predetermined range, wherein the predetermined range is associated with incubation of the culture; measuring the property of the environment within the chamber using at least one chamber environment sensor to verify that the property is maintained within the predetermined range; and capturing a representation of the culture within the chamber using at least one sensor through the first imaging access port and a second imaging access port while the first housing is detachably coupled to a second housing and while the property of the environment within the chamber is maintained within the predetermined range, wherein the second housing includes the at least one sensor and the second imaging access port that is light-transmissive.

14. The method of claim 13, wherein the property of the environment within the chamber includes at least one of a temperature of the environment within the chamber, a humidity of the environment within the chamber, a pressure of the environment within the chamber, a pH of the environment within the chamber, a fluidic flow rate of a fluid within the chamber, an orientation of the environment within the chamber, or a level of illumination in the environment within the chamber.

15. The method of claim 13, wherein the property of the environment within the chamber includes a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified liquid in the environment within the chamber, a concentration of a specified mixture of liquids in

the environment within the chamber, or concentration of a reagent in the environment within the chamber.

16. The method of claim 13, wherein the least one chamber environment interface includes at least one of a heater that heats the environment within the chamber to increase a temperature of the environment, a cooler that cools the environment within the chamber to decrease the temperature of the environment, a humidifier that humidifies the environment within the chamber to increase a humidity of the environment, a dehumidifier that dehumidifies the environment within the chamber to decrease the humidity of the environment, a pump that adjusts at least one of a pressure in the environment within the chamber or a flow rate of a fluid in the environment within the chamber, a valve that adjusts at least one of the pressure in the environment within the chamber or the flow rate of the fluid in the environment within the chamber, a fan that facilitates airflow within the chamber, an actuator that adjusts an orientation of the environment within the chamber, or a light source that illuminates the environment within the chamber.

17. The method of claim 13, wherein the least one chamber environment interface includes at least one of a pump or a valve, and wherein the least one chamber environment interface adjusts at least one of a concentration of a specified gas in the environment within the chamber, a concentration of a specified mixture of gases in the environment within the chamber, a concentration of a specified fluid in a culture dish in the environment within the chamber, a concentration of a specified mixture of fluids in the culture dish in the environment within the chamber, a concentration of a specified reagent in the culture dish in the environment within the chamber.

18. The method of claim 13, wherein the least one chamber environment sensor includes at least one of a temperature sensor, a humidity sensor, a gas pressure sensor, a gas concentration sensor, a fluid concentration sensor, a fluid flow rate sensor, an assay sensor, a bioactivity electrical recording sensor, an orientation sensor, or a light sensor.

19. The method of claim 13, wherein the representation is captured by at least one image sensor, and wherein the representation of the culture includes at least one image of the culture.

20. The method of claim 13, further comprising: analyzing the representation of the culture to detect a condition; and outputting a notification that is indicative of the condition.
