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### X-RAY FLUORESCENCE SPECTROMETER

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#### Abstract

Provided is an X-ray fluorescence spectrometer that achieves a uniform state on a back side of a thin sheet-shaped sample so as to prevent a difference in a measurement condition depending on a measurement position. The X-ray fluorescence spectrometer includes: a sample stage; a background correction cover, which is arranged adjacent to an outer side of the sample stage so that a surface of the background correction cover is substantially flush with a surface of the sample stage; and a moving mechanism. The moving mechanism moves the background correction cover based on movement of the sample stage and, when the sample stage is absent on a back side of the sample at a measurement position, moves the background correction cover so that the background correction cover is located on the back side of the sample at the measurement position.

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## Background/Summary

### TECHNICAL FIELD

[0001] The present invention relates to an X-ray fluorescence spectrometer that measures a thin sheet-shaped sample at a freely-selected measurement position on the sample.

### BACKGROUND ART

[0002] There has been known an X-ray fluorescence spectrometer as an apparatus for measuring an element contained in a sample or a concentration of the element. For X-ray fluorescence analysis, a sample is arranged on a sample stage, and a position of the sample stage is controlled so that primary X-rays are radiated to a desired measurement position. Then, the X-ray fluorescence spectrometer analyzes, for example, an element contained in the sample based on an intensity of fluorescent X-rays that are emitted when the sample is irradiated with the primary X-rays.

[0003] When the sample is a thin sheet-shaped sample, for example, a silicon wafer, the primary X-rays that have been radiated may be transmitted through the sample. There is a fear of the fluorescent X-rays or scattered rays that are emitted from the sample stage becoming background for the fluorescent X-ray intensity to be measured, affecting a result of analysis. Further, the fluorescent X-rays or the scattered rays, which may become background, have different influences at a measurement position where the sample stage is present on a lower side of the sample and a measurement position where the sample stage is absent on the lower side of the sample. Thus, a measurement condition may be different depending on the measurement position. For example, in Patent Literature 1 listed below, there is described a simultaneous multi-element X-ray fluorescence spectrometer. According to Patent Literature 1, even when the sample stage has a cutout portion, a background correction is performed in accordance with a measurement position so that a difference in the measurement condition depending on the measurement position is reduced.

### CITATION LIST

Patent Literature

[0004] [PTL 1] JP 2017-161276 A

### SUMMARY OF INVENTION

#### Technical Problem

[0005] In Patent Literature 1, a background intensity is measured in advance at each measurement position, and a corresponding background intensity is subtracted from the measured intensity given at each of the measurement positions in actual analysis, to thereby reduce a difference in the measurement condition depending on the measurement position. However, it is inevitable that the measured intensity will be affected depending on whether the sample stage is present a back side of the sample at the measurement position.

[0006] Further, a diameter of a semiconductor substrate such as a silicon wafer has been increased. However, in view of, for example, securing of a movable range within a limited space inside the apparatus and costs, it is desired that the sample stage be downsized as much as possible. However, when the sample is larger than the sample stage on which the sample is placed, it will result in a region where the sample stage is present on a back side of the sample and a region where the sample stage is absent on the back side of the sample.

[0007] The present disclosure has been made to solve the problems described above, and has an object to provide an X-ray fluorescence spectrometer that achieves a uniform state on a back side of a thin sheet-shaped sample so as to prevent a difference in a measurement condition depending

on a measurement position.

#### Solution to Problem

[0008] (1) An X-ray fluorescence spectrometer according to one aspect of the present disclosure includes: an X-ray source configured to radiate primary X-rays to a surface of a sheet-shaped sample; a detector configured to measure an intensity of fluorescent X-rays emitted from the sample irradiated with the primary X-rays; a sample stage on which the sample is to be placed; an analysis unit configured to perform an analysis based on the intensity of the fluorescent X-rays, which has been measured by the detector, at a plurality of measurement positions on the surface of the sample; at least one background correction cover, which has an outer edge portion with a shape extending along a part of an outer edge of the sample stage, and is arranged adjacent to an outer side of the sample stage so that a surface of the background correction cover is substantially flush with a surface of the sample stage; and a moving mechanism configured to move the sample stage so that the primary X-rays are radiated to a freely-selected measurement position on the surface of the sample. The moving mechanism moves the background correction cover based on movement of the sample stage and, when the sample stage is absent on a back side of the sample at a measurement position, moves the background correction cover so that the background correction cover is located on the back side of the sample at the measurement position.

[0009] (2) In the above-mentioned aspect of the present disclosure, the background correction cover is made of the same material as a material of the sample stage.

[0010] (3) In the above-mentioned aspect of the present disclosure, the sample stage has a holding portion with a protruding shape to be brought into abutment against a part of the sample.

[0011] (4) In the above-mentioned aspect of the present disclosure, the moving mechanism includes: a triple sun shaft to be rotationally driven; a sun arm fixed to the triple sun shaft; a double planetary shaft being rotatably supported at a rotating end portion of the sun arm; a planetary arm fixed to the double planetary shaft; and a sample shaft being rotatably supported at a rotating end portion of the planetary arm. The sample stage is fixed to the sample shaft. The background correction cover is fixed to the planetary arm.

[0012] (5) In the above-mentioned aspect of the present disclosure, the moving mechanism includes: an XY stage configured to move the sample stage in an XY plane, being parallel to the surface of the sample stage and the surface of the background correction cover, to such a position that the primary X-rays are radiated to the measurement position; and a rotary mechanism configured to rotate the background correction cover about a center of the sample stage.

[0013] (6) In the above-mentioned aspect of the present disclosure, a distance from a center to the outer edge of the sample stage is smaller than a distance from a center to an outer edge of the sample, and a distance from the center of the sample stage to an end portion of the background correction cover is larger than the distance from the center to the outer edge of the sample.

[0014] (7) In the above-mentioned aspect of the present disclosure, the analysis unit includes a correction unit configured to perform a correction by subtracting a background intensity from the measured intensity measured by the detector.

[0015] (8) In the above-mentioned aspect of the present disclosure, the sample stage has a circular shape, and the outer edge portion of the background correction cover, which has a shape extending along the part of the outer edge of the sample stage, has an arc-like shape extending along the outer edge of the sample stage having the circular shape.

[0016] (9) In the above-mentioned aspect of the present disclosure, the X-ray fluorescence spectrometer further includes a sample detecting unit configured to detect, when the sample has a circular shape with a cutout portion, a position of the cutout portion of the sample, which is arranged on an outer side of the outer edge of the sample stage.

#### Advantageous Effects of Invention

[0017] According to the present disclosure, the X-ray fluorescence spectrometer that achieves a

uniform state on the back side of the sample so as to prevent the measurement condition from differing depending on the measurement position can be provided.

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## Description

### BRIEF DESCRIPTION OF DRAWINGS

[0018] FIG. 1 is a schematic view for illustrating an example of an X-ray fluorescence spectrometer.

[0019] FIG. 2 is a top view and a side view for illustrating a state in which a sample that is a circular substrate is arranged on a sample stage.

[0020] FIG. 3 is an explanatory view for illustrating a moving mechanism according to a first embodiment.

[0021] FIG. 4A is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and background correction covers when a measurement position is at (0 mm, 0 degrees).

[0022] FIG. 4B is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (75 mm, 0 degrees).

[0023] FIG. 4C is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (100 mm, 0 degrees).

[0024] FIG. 4D is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (150 mm, 0 degrees).

[0025] FIG. 5A is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (0 mm, 60 degrees).

[0026] FIG. 5B is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (75 mm, 60 degrees).

[0027] FIG. 5C is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (100 mm, 60 degrees).

[0028] FIG. 5D is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (150 mm, 60 degrees).

[0029] FIG. 6A is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (0 mm, -60 degrees).

[0030] FIG. 6B is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (75 mm, -60 degrees).

[0031] FIG. 6C is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (100 mm, -60 degrees).

[0032] FIG. 6D is a view for illustrating a positional relationship among the moving mechanism, the sample stage, and the background correction covers when the measurement position is at (150 mm, -60 degrees).

[0033] FIG. 7 is an explanatory view for illustrating a moving mechanism according to a second

embodiment.

[0034] FIG. 8 is a view for illustrating a modification example of the sample stage and the background correction cover.

## DESCRIPTION OF EMBODIMENTS

### First Embodiment

[0035] Now, a preferred embodiment for carrying out the present disclosure (hereinafter referred to as “embodiment”) will be described. FIG. 1 is a schematic view illustrating an example of an X-ray fluorescence spectrometer **100**. As illustrated in FIG. 1, the X-ray fluorescence spectrometer **100** includes an X-ray source **102**, a sample stage **104**, background correction covers **108**, a moving mechanism **110**, a spectroscopic device **112**, a detector **114**, a goniometer **116**, a counter **118**, an information processing unit **120**, and a sample detecting unit.

[0036] The X-ray source **102** irradiates a surface of a sample **128** with primary X-rays **130** to cause fluorescent X-rays to be emitted from the sample **128**. In this case, some of the primary X-rays **130** are transmitted through the sample **128** and reach the sample stage **104** or the background correction cover **108**, which is present at a back side of the sample **128**, to cause fluorescent X-rays or scattered rays to be emitted. Then, the fluorescent X-rays or the scattered rays are transmitted through the sample **128** again and are measured together with the fluorescent X-rays emitted from the sample **128** as background.

[0037] The X-ray source **102** radiates the primary X-rays **130** to a predetermined position in a sample chamber (not shown) in which the sample stage **104** and other components are arranged. The X-ray source **102** may be configured so as to be capable of changing an irradiation position. In the first embodiment, however, description is given of a case in which a position of the X-ray source **102** is fixed and in which the X-ray source **102** is configured so as to be capable of radiating the primary X-rays **130** only to a position (origin O described later) of a triple sun shaft **206** (see, for example, FIG. 2).

[0038] The sample stage **104** has the sample **128** placed thereon, and moves the sample **128** using the moving mechanism **110** so that the primary X-rays **130** are radiated to a freely-selected measurement position on a surface of the sample **128**. More specifically, for example, the sample stage **104** has holding portions **106**. The holding portions **106** each have a circular shape, protrude in a vertical direction from a surface of the sample stage **104**, and hold the sample **128** parallel to the surface of the sample stage **104** at a distance of, for example, **10** mm from the surface of the sample stage **104**. The holding portions **106** hold the sample **128** at at least three positions. The sample stage **104** may have two or more holding portions **106** each having a linear shape, a circular shape, or an arc-like shape when viewed from above and having a shape such as a projecting shape when viewed from its side. Details of the sample stage **104** will be described later.

[0039] The background correction covers **108** can be arranged adjacent to the sample stage **104** on an outer side, and each have an outer edge portion with a shape extending along a part of an outer edge of the sample stage **104**. More specifically, for example, the outer edge portion of the background correction cover **108** with a shape extending along a part of the outer edge of the sample stage **104** is an arc-like portion extending along the outer edge of the sample stage **104** having a circular shape. In this embodiment, two background correction covers **108** are provided. The two background correction covers **108** are arranged by the moving mechanism **110** so that their outer edge portions each having the arc-like shape extend along the outer edge portion of the sample stage **104** having a circular shape. In this embodiment, the moving mechanism **110** that moves the background correction covers **108** and the sample stage **104** is described as one mechanism. However, the background correction covers **108** and the sample stage **104** may be moved by different mechanisms.

[0040] Further, the sample stage **104** and the background correction covers **108** are arranged so that the surface of the sample stage **104** and surfaces of the background correction covers **108** are substantially flush with each other. Thus, an influence of the fluorescent X-rays or scattered rays

resulting from the primary X-rays **130** that have been transmitted through the sample **128** can be made substantially the same in a region in which the sample **128** and the sample stage **104** overlap with each other in plan view, and a region in which the sample **128** and the background correction covers **108** overlap with each other in plan view.

[0041] The term “substantially flush” means that the surfaces are located at the same height to such a degree that an influence of, for example, the scattered rays on the surface of the sample stage **104** and an influence of, for example, the scattered rays on the surfaces of the background correction covers **108** become equal to each other in terms of influences on accuracy of X-ray fluorescence analysis. Thus, when a difference in height between the surface of the sample stage **104** and the surfaces of the background correction covers **108** is small enough not to affect the accuracy of the X-ray fluorescence analysis, the surface of the sample stage **104** and the surfaces of the background correction covers **108** can be regarded as being substantially flush with each other. In order to equalize the influence of the fluorescent X-rays or the scattered rays, it is desired that the background correction covers **108** be made of the same material as a material of the sample stage **104**.

[0042] The moving mechanism **110** moves an irradiation position of the primary X-rays from the X-ray source **102** or the sample stage **104** so that the primary X-rays are radiated to a freely-selected measurement position on the surface of the sample **128**. Further, the moving mechanism **110** moves the background correction covers **108** based on the movement of the sample stage **104**. When the sample stage **104** is absent on the back side of the sample **128** at the measurement position, the background correction covers **108** are moved so as to be located on the back side of the sample **128** at the measurement position. Details of the moving mechanism **110** will be described later.

[0043] The spectroscopic device **112** spectrally disperses fluorescent X-rays. Specifically, for example, the spectroscopic device **112** spectrally disperses fluorescent X-rays having a specific wavelength that satisfies Bragg's conditional expression among fluorescent X-rays having a plurality of wavelengths, which have been emitted from the sample **128**.

[0044] The detector **114** measures an intensity of the fluorescent X-rays that have been spectrally dispersed by the spectroscopic device **112**. More specifically, the detector **114** is, for example, a scintillation counter. The detector **114** measures an intensity of the fluorescent X-rays and outputs a pulse signal having a pulse height corresponding to measured energy of the fluorescent X-rays.

[0045] The spectroscopic device **112** and the detector **114** are pivoted by the goniometer **116** while maintaining a fixed angular relationship therebetween. More specifically, the spectroscopic device **112** is pivoted by the goniometer **116** so that an incident angle  $\theta$  of the fluorescent X-rays with respect to a surface of the spectroscopic device **112** is varied within a predetermined range. The incident angle  $\theta$  is an angle formed by a direction in which the fluorescent X-rays emitted from the sample **128** travel and the surface of the spectroscopic device **112**. The fluorescent X-rays are diffracted by the spectroscopic device **112**, and fluorescent X-rays that satisfy the Bragg's conditional expression (specifically, fluorescent X-rays emitted at an emission angle  $\theta$ ) are emitted. The detector **114** is moved by the goniometer **116** to a position at which the fluorescent X-rays emitted from the spectroscopic device **112** at the emission angle  $\theta$  are incident thereon.

[0046] The counter **118** counts the pulse signals output from the detector **114** based on a pulse height. More specifically, for example, the counter **118** counts the pulse signals, which are output as intensities measured by the detector **114**, based on a pulse height, and outputs the pulse signals as X-ray intensities to the information processing unit **120**.

[0047] The sample detecting unit detects a direction in which the sample **128** is arranged. More specifically, when the sample **128** has a cutout portion **204** and has a circular shape larger than the sample stage **104**, a sample detecting unit detects a position of the cutout portion **204** of the sample **128** arranged on the sample stage **104**. For example, the sample detecting unit is a transmission-type sensor such as a beam sensor, and includes a light source **126** and a light-receiving portion

**127**. The cutout portion **204** is, for example, a notch formed in an outer periphery of a substrate having a circular shape. The light source **126** radiates a light beam such as a laser beam **132** from above or below the sample stage **104** all along the outer edge of the sample **128**. When the light beam is received by the light-receiving portion **127** that is opposed to the light source **126** across the sample **128**, the position of the cutout portion **204** of the sample **128** that is arranged on the sample stage **104** is detected. In this manner, the sample detecting unit can detect the direction of the sample **128** arranged on the sample stage **104**. In FIG. **1**, there is illustrated an example in which the light source **126** and the light-receiving portion **127** of the sample detecting unit are arranged above and below the substrate. However, the sample detecting unit may be arranged on a side of the substrate and may be a sensor other than a beam sensor as long as the position of the cutout portion **204** can be detected.

[0048] The information processing unit **120** controls operations of the parts of the X-ray fluorescence spectrometer **100** and also analyzes the sample **128**. More specifically, for example, the information processing unit **120** is a computer, and controls operations of the moving mechanism **110**, the goniometer **116**, and the sample detecting unit. Further, the information processing unit **120** includes an analysis unit **122**. The analysis unit **122** acquires a fluorescent X-ray spectrum based on the outputs from the counter **118**. Further, the analysis unit **122** analyzes elements contained in the sample **128** based on the fluorescent X-ray spectrum. In this case, the analysis unit **122** analyzes the sample **128** by using a known method such as a calibration curve method or a fundamental parameter method.

[0049] As illustrated in FIG. **1**, the analysis unit **122** may include a correction unit **124**. The correction unit **124** performs a correction of subtracting a background intensity from the measured intensity measured by the detector **114**. More specifically, first, for example, a blank sample, which does not contain an element being a target to be analyzed, is arranged on the sample stage **104**. Then, the blank sample is irradiated with the primary X-rays **130**, and a measured intensity of energy generated from analyzed elements is measured. The correction unit **124** stores the measured intensity. Next, a sample to be analyzed, which contains an element being a target to be analyzed, is arranged on the sample stage **104**. Then, the sample to be analyzed is irradiated with the primary X-rays **130**, and a measured intensity of energy generated from analyzed elements is measured. The correction unit **124** performs a correction by subtracting the prestored measured intensity from the measured intensity described above. The correction unit **124** may perform a background correction by using other known methods.

[0050] According to the present disclosure, as will be described later, the sample stage **104** or the background correction covers **108** can be arranged on the back side of the measurement position regardless of a position of the measurement on the sample **128**. Thus, after a background intensity measured at one measurement position on the blank sample is stored, the background correction can be performed at all measurement positions on the sample to be analyzed.

[0051] The wavelength-dispersive X-ray fluorescence spectrometer **100** illustrated in FIG. **1** is of a scanning type that pivots the spectroscopic device **112** and the detector **114**. However, the X-ray fluorescence spectrometer **100** may also be a single-element spectrometer or a simultaneous multi-element spectrometer, in which the goniometer **116** is not used and the spectroscopic device **112** and the detector **114** are fixed. Further, the X-ray fluorescence spectrometer **100** may be of an energy-dispersive type. When the X-ray fluorescence spectrometer **100** is of an energy-dispersive type, the spectroscopic device **112** and the goniometer **116** are not included, and a semiconductor detector such as a silicon drift detector (SDD) is used as the detector **114**.

[0052] Next, details of the moving mechanism **110**, the sample stage **104**, the background correction covers **108**, and a conveying arm **202** in the first embodiment will be described with reference to FIG. **2** and FIG. **3**. FIG. **2** is a top view and a side view for illustrating a state in which the sample **128**, being a circular substrate, is arranged on the sample stage **104** by the conveying arm **202**. FIG. **3** is a sectional view taken along the line III-III of FIG. **2** (the conveying arm **202**

and the sample **128** are not shown) for detail. The background correction covers **108** are not visible on the cross section taken along the line III-III. However, for better understanding of their positional relationship with respect to the sample stage **104**, the background correction covers **108** are indicated by broken lines in FIG. 3.

[0053] The moving mechanism **110** includes the triple sun shaft **206**, a sun arm **208**, a double planetary shaft **210**, a planetary arm **212**, and a sample shaft **214**. The triple sun shaft **206** is rotationally driven. The sun arm **208** is fixed to the triple sun shaft **206**. The double planetary shaft **210** is rotatably supported at a rotating end portion of the sun arm **208**. The planetary arm **212** is fixed to the double planetary shaft **210**. The sample shaft **214** is rotatably supported at a rotating end portion of the planetary arm **212**.

[0054] More specifically, the triple sun shaft **206** is a triple shaft including a first sun shaft **302**, a second sun shaft **304**, and a third sun shaft **306**, which are rotationally driven independently of each other by drive motors (not shown).

[0055] Hereinafter, a position of the triple sun shaft **206** in an XY plane (in the top view of FIG. 2, a left and right direction corresponds to an X-axis direction and a up and down direction corresponds to a Y-axis direction) that contains the surface of the sample stage **104** is set as a measurement position and also as the origin O. The sun arm **208** is a box-shaped arm that is fixed to the third sun shaft **306**. The double planetary shaft **210** is a double shaft including a first planetary shaft **308** and a second planetary shaft **310**. The first planetary shaft **308** is rotatably supported at the rotating end portion of the sun arm **208**. The second planetary shaft **310** is provided rotatably with respect to the first planetary shaft **308**. Hereinafter, a position of the double planetary shaft **210** in the XY-plane is represented by A. A first sun gear **312**, a first idler gear **314**, a first planetary gear **316**, a second sun gear **318**, a second idler gear **320**, and a second planetary gear **322** are arranged inside the sun arm **208**. More specifically, the first sun gear **312** is fixed to the second sun shaft **304**. The first planetary gear **316** is fixed to the first planetary shaft **308** and is rotated in association with the first sun gear **312** through intermediation of the first idler gear **314**. The second sun gear **318** is fixed to the first sun shaft **302**. The second planetary gear **322** is fixed to the second planetary shaft **310** and is rotated in association with the second sun gear **318** through intermediation of the second idler gear **320**.

[0056] The planetary arm **212** is a box-shaped arm that is fixed to the second planetary shaft **310**. A third planetary gear **324**, a third idler gear **326**, and a sample gear **328** are arranged inside the planetary arm **212**. More specifically, the third planetary gear **324** is fixed to the first planetary shaft **308**. The sample gear **328** is fixed to the sample shaft **214** and is rotated in association with the third planetary gear **324** through intermediation of the third idler gear **326**. The sample shaft **214** is rotatably supported at the rotating end portion of the planetary arm **212**. Hereinafter, a position of the sample shaft **214** in the XY-plane is represented by B. Further, the first idler gear **314** and the second idler gear **320** are fixed to a first idler shaft **315** and a second idler shaft **321** that are rotatably supported by the sun arm **208**, respectively.

[0057] The third idler gear **326** is fixed to a third idler shaft **327** that is rotatably supported by the planetary arm **212**. The sample stage **104** is fixed to the sample shaft **214**, and the background correction covers **108** are fixed to the planetary arm **212**.

[0058] The triple sun shaft **206** is rotatably supported on a bottom surface of the sample chamber through intermediation of a bearing **330** while maintaining airtightness of the sample chamber. Similarly, the first planetary shaft **308**, the second planetary shaft **310**, the first idler shaft **315**, and the second idler shaft **321** are rotatably supported through intermediation of bearings **331** to **334** while maintaining airtightness of the sun arm **208** having a box shape. Similarly, the third idler shaft **327** and the sample shaft **214** are rotatably supported through intermediation of **335** to **337** bearings while maintaining airtightness of the planetary arm **212** having a box shape.

[0059] The sun arm **208**, the double planetary shaft **210**, the planetary arm **212**, the sample shaft **214**, and the sample stage **104** are arranged together with the sample **128** inside the sample



chamber. The sample **128** is placed on the sample stage **104** so that a center of the sample **128** having a circular shape and a center of the sample stage **104** match each other. The moving mechanism **110** is supported only by the triple sun shaft **206**, and the third shaft is rotatably supported through sun **306** intermediation of the bearing **330**. Further, concentric shafts of the triple sun shaft **206**, which is a triple shaft, and concentric shafts of the double planetary shaft **210**, which is a double shaft, are rotatably supported while airtightness is maintained therebetween by bearings (not shown).

[0060] In the moving mechanism **110** according to the first embodiment, a distance from the triple sun shaft **206** to the double planetary shaft **210** and a distance from the double planetary shaft **210** to the sample shaft **214** are set equal to each other. Further, a gear ratio between the first sun gear **312** and the first planetary gear **316** is set to 1:1. A gear ratio between the second sun gear **318** and the second planetary gear **322** is set to 2:1. A gear ratio between the third planetary gear **324** and the sample gear **328** is set to 1:1.

[0061] The sample stage **104** has a circular shape and has six holding portions **106**. More specifically, for example, the sample stage **104** has a circular shape with a radius of 100 mm and has six holding portions **106** in the vicinity of the outer edge of the sample stage **104** having a circular shape. The six holding portions **106** are arranged equally at intervals of 60 degrees. Each of the holding portions **106** has a protruding shape extending in the vertical direction from the surface of the sample stage **104**. Tops of the holding portions **106** are brought into abutment against a back surface of the sample **128**, to thereby hold the sample **128**. Further, an electrostatic chuck may be provided in a center portion of the sample stage **104** so as to attract and hold the sample **128**.

[0062] The background correction covers **108** may be arranged adjacent to the sample stage **104** on the outer side. The background correction covers **108** each have an outer edge portion with a shape extending along a part of the outer edge of the sample stage **104**. More specifically, each of the background correction covers **108** has a substantially semilunar shape and has an arc-shaped outer edge portion (inner-side outer edge portion adjacent to the sample stage **104**) extending along a part of the outer edge of the sample stage **104** having a circular shape and an arc-shaped outer edge portion (outer-side outer edge portion) on the opposite side. In this embodiment, the background correction covers **108** include a background correction cover **108A** and a background correction cover **108B**. Hereinafter, a center portion of the inner-side outer edge portion of the background correction cover **108A**, which is adjacent to the sample stage **104**, is represented by C, and a center portion of the outer-side outer edge portion thereof is represented by D.

[0063] The background correction cover **108A** is fixed to the planetary arm **212** so that a position of a line segment BC corresponds to a position of a line segment AB rotated counterclockwise by 45 degrees about the position B. The line segment AB is a center line of the planetary arm **212** in its longitudinal direction, and the line segment BC is a line that connects the center portion C of the inner-side outer edge portion of the background correction cover **108A** and the position B of the sample shaft **214** to each other (center line of the background correction cover **108A**). The background correction cover **108B** is fixed to the planetary arm **212** so that its position is symmetric to a position of the background correction cover **108A** with respect to the line segment AB serving as a line of symmetry. Specifically, the background correction cover **108B** is fixed at a position of the background correction cover **108A** rotated clockwise by 90 degrees about the position B. Further, the background correction covers **108** are fixed to the planetary arm **212** so that a distance between the center portion C of the inner-side outer edge portion of the background correction cover **108A** and the position B of the sample shaft **214** becomes substantially equal to the radius of the sample stage **104**. Further, a distance between the center portion C of the inner-side outer edge portion and the center portion D of the outer-side outer edge portion of the background correction cover **108A** is set so as to be larger than a difference between a radius of the sample **128** and the radius of the sample stage **104**. Further, the background correction cover **108A** and the background correction cover **108B** have the same shape.

[0064] With the background correction covers **108** described above, even when a distance from the center of the sample stage **104** to its outer edge is smaller than a distance from the center of the sample **128** to its outer edge, a measurement can be performed under an environment in which the state of the back side of the sample **128** immediately below the measurement position of the sample **128** is uniform regardless of the measurement position as long as a difference between the above-mentioned distances is smaller than a length of a line segment CD. Specifically, a uniform environment can be achieved on the back side of the sample **128** by setting the distance from the position B of the sample shaft **214** (the center of the sample stage **104**) to the center portion D of the outer-side outer edge portion of the background correction cover **108A** larger than the distance from the center of the sample **128** to its outer edge (radius of the sample **128**). For example, even for the sample **128** that is larger than the sample stage **104**, when the radius of the sample stage **104** is set to 100 mm and the distance CD is set to 80 mm, the present disclosure can be applied to the sample **128** having a circular shape and a radius up to 180 mm.

[0065] The conveying arm **202** conveys the sample **128**. More specifically, for example, the conveying arm **202** conveys the sample **128** between a load lock (not shown) and the sample chamber (not shown) in which the sample stage **104** is arranged. When the sample **128** is to be conveyed onto the sample stage **104**, the conveying arm **202** moves the sample **128** from the right side toward the left side in FIG. 2 while carrying the sample **128** thereon so that the center of the sample **128** having a circular shape and the center of the sample stage **104** are aligned with each other when viewed from above. During this movement, the conveying arm **202** moves above (in a Z-axis direction) the surface of the sample stage **104** having a circular shape. After moving the sample **128** so that the center of the sample **128** having a circular shape and the center of the sample stage **104** are aligned with each other, the conveying arm **202** is moved downward in the vertical direction ( $-Z$ -axis direction) to allow the sample **128** to be held by the holding portions **106**. Further, the conveying arm **202** is moved through a gap defined by the holding portions **106** (space between the back surface of the sample **128** and the surface of the sample stage **104**) from the left side toward the right side in FIG. 2. Through the above-mentioned procedure, the sample **128** is conveyed from the load lock onto the sample stage **104**. When the sample **128** is to be conveyed from the sample stage **104** into the load lock, a reverse procedure to the above-mentioned procedure is carried out.

[0066] As described above, the gap defined by the holding portions **106** enables the conveying arm **202** to convey the sample **128** between the load lock and the sample chamber in a non-contact manner with the surface of the sample **128**. A conveying method is not limited to the above-mentioned one and may be other methods. For example, the conveying arm **202** may attract the surface of the sample **128** so as to convey the sample **128** between the load lock and the sample chamber. With this configuration, the holding portions **106** provided to the sample stage **104** can be omitted.

[0067] Next, an operation of the moving mechanism **110** will be described. First, consideration is given to a case in which rotation of the second sun gear **318** with respect to a coordinate system X-Y is fixed by fixing rotation of the drive motor (not shown) that rotationally drives the first sun shaft **302** while the drive motor that rotationally drives the third sun shaft **306** is rotated. In this case, the distance from the triple sun shaft **206** to the double planetary shaft **210** and the distance from the double planetary shaft **210** to the sample shaft **214** are set equal to each other. Thus, the center of the sample stage **104** can be moved from an X-coordinate  $2d$  to  $-2d$  on an X axis (first principle). A value  $2d$  is a sum of a distance OA from the triple sun shaft **206** to the double planetary shaft **210** and a distance AB from the double planetary shaft **210** to the sample shaft **214**.

[0068] Next, consideration is given to a case in which the first sun shaft **302** and the third sun shaft **306** are rotationally driven in the same direction by the same angle, specifically, the second sun gear **318** and the sun arm **208** are rotated integrally. In this case, the sample stage **104** revolves about the origin O while the angle defined by the sun arm **208** and the planetary arm **212** is

maintained, specifically, a revolution radius of the sample stage **104** is maintained (second principle). Based on the first and second principles, the center of the sample stage **104** can be located at an appropriate position inside a circle that has the origin as a center and a radius of  $2d$ . [0069] Next, consideration is given to a case in which rotation of the first sun gear **312** with respect to the coordinate system X-Y is fixed by fixing rotation of the drive motor that rotationally drives the second sun shaft **304** while the sun arm **208** and the planetary arm **212** are rotated integrally based on the second principle. In this case, the first sun gear **312** and the first planetary gear **316** have the gear ratio of 1:1. Thus, directions of the first planetary gear **316** and the third planetary gear **324** in the coordinate system X-Y are maintained.

[0070] Similarly, a direction of the sample gear **328**, which is operated in association with the third planetary gear **324** through intermediation of the third idler gear **326**, and a direction of the sample stage **104** are also maintained in the coordinate system X-Y. This means that the fixing of the second sun shaft **304** allows the direction of the sample stage **104** in the coordinate system X-Y to be maintained even when the sample stage **104** is caused to revolve about the origin based on the second principle. Specifically, the direction of the sample stage **104** can be determined appropriately regardless of the position of the sample stage **104** in the coordinate system X-Y while the position of the sample stage **104** is maintained (third principle).

[0071] According to the first to third principles, when the sample **128** has a radius of  $2d$  or less, the sample **128** can be moved so that a freely-selected measurement position on the sample matches the irradiation position of the primary X-rays **130**.

[0072] Next, with reference to FIG. 4A to FIG. 6D, a positional relationship among the moving mechanism **110**, the sample stage **104**, and the background correction covers **108** for each measurement position will be described. In the following description, a measurement position (“ $r$ ” mm,  $\theta$  degrees) is a position that is “ $r$ ” mm away from the center of the sample **128** and rotated clockwise by  $\theta$  degrees from 0 degrees set in a rightward direction in FIG. 4A to FIG. 6D.

Specifically, a position ( $r$  mm,  $\theta$  degrees) is a relative position with respect to the center of the sample **128** that is moved together with the sample stage **104**. Meanwhile, the origin O is an absolute fixed position (specifically, a fixed position inside the sample chamber (not shown) in which the sample stage **104** and other components are arranged) and is a measurement position to which the primary X-rays are radiated. Thus, all the positions O in FIG. 4A to FIG. 6D are the same position inside the sample chamber. Further, a state illustrated in FIG. 2 is referred to as an initial state. Specifically, in the initial state, a center line OA of the sun arm **208** and a center line AB of the planetary arm **212** in its longitudinal direction are located on the X axis, a position of the triple sun shaft **206** is represented by coordinates  $(-2d, 0)$  on the XY plane, and a center line CD of the background correction cover **108A** is located at a position rotated counterclockwise by 45 degrees from the X axis. Further, it is assumed that the sample **128** is arranged so that the cutout portion **204** is located in the Y-axis direction under the initial state.

[0073] FIG. 4A to FIG. 4D are views for illustrating the positional relationship among the moving mechanism **110**, the sample stage **104**, and the background correction covers **108** when  $\theta$  is fixed to 0 degrees and “ $r$ ” is changed to 0 mm, 75 mm, 100 mm, and 150 mm, respectively. As illustrated in FIG. 4A, when a measurement position is at (0 mm, 0 degrees) (specifically, at the center of the sample **128**), the moving mechanism **110** moves the sample **128** so that the center of the sample **128** is located at the origin O to which the primary X-rays **130** are radiated. Thus, the moving mechanism **110** moves the sample **128** so that the position B of the sample shaft **214** matches the origin O. In this state, the center line OA of the sun arm **208** and the center line AB of the planetary arm **212** in its longitudinal direction are located on a Y axis. Further, the background correction cover **108A** and the background correction cover **108B** are fixed to the planetary arm **212** so as to have the above-mentioned positional relationship. Thus, the background correction cover **108A** is arranged (on a lower right side of the position B in FIG. 4A) so that the position of the line segment BC corresponds to a position of the line segment AB rotated counterclockwise by 45 degrees about

the position B. Further, the background correction cover **108B** is arranged (on a lower left side of the position B in FIG. 4A) at a position to which the background correction cover **108A** is rotated clockwise by 90 degrees about the position B. In a state illustrated in FIG. 4A, the sample stage **104** is present on the back side of the sample **128** at the measurement position (0 mm, 0 degrees). [0074] As illustrated in FIG. 4B to FIG. 4D, when the measurement position (position O) is located at (75 mm, 0 degrees), (100 mm, 0 degrees), and (150 mm, 0 degrees), the moving mechanism **110** moves the sample **128** so that the measurement position on the sample **128** is located at the origin O to which the first X-rays **130** are radiated. Specifically, the sun arm **208** is rotated clockwise from a state illustrated in FIG. 4A, and the planetary arm **212** is rotated counterclockwise from the state illustrated in FIG. 4A. As a result, the sample stage **104** is moved to the positions at which the distance between O and B becomes equal to 75 mm, 100 mm, and 150 mm. As described above, the position O is a fixed position inside the sample chamber (not shown). Thus, the sample stage **104** illustrated in FIG. 4B to FIG. 4D is moved from the position of the sample stage **104** illustrated in FIG. 4A to the left side (in a -X-axis direction) in FIG. 4B to FIG. 4D. Further, the background correction cover **108A** and the background correction cover **108B** are fixed to the planetary arm **212** as described above, and thus are moved while maintaining a positional relationship with respect to the planetary arm **212**.

[0075] In states illustrated in FIG. 4B and FIG. 4C, the sample stage **104** is present on the back side of the sample **128** at the position (75 mm, 0 degrees) and at the position (100 mm, 0 degrees). Meanwhile, in a state illustrated in FIG. 4D, the background correction cover **108A** is present on the back side of the sample **128** at the measurement position (150 mm, 0 degrees). FIG. 5A to FIG. 5D are views illustrating the positional relationship among the moving mechanism **110**, the sample stage **104**, and the background correction covers **108** when  $\theta$  is fixed to 60 degrees and "r" is changed to 0 mm, 75 mm, 100 mm, and 150 mm, respectively. As illustrated in FIG. 5A, when a measurement position is at (0 mm, 60 degrees) (specifically, at the center of the sample **128**), the moving mechanism **110** moves the sample **128** so that the center of the sample **128** is located at the origin

[0076] O to which the primary X-rays **130** are radiated. Thus, the moving mechanism **110** moves the sample **128** so that the position B of the sample shaft **214** matches the origin O. In this state, the center line OA of the sun arm **208** and the center line AB of the planetary arm **212** in its longitudinal direction are located at a position rotated clockwise from the Y axis by 60 degrees about the position O. Further, the background correction cover **108A** is arranged so that a position of the line segment BC corresponds to a position of the line segment AB rotated counterclockwise by 45 degrees about the position B. The background correction cover **108B** is arranged so that its position corresponds to a position of the background correction cover **108A** rotated by 90 degrees about the position B. In a state illustrated in FIG. 5A, the sample stage **104** is present on the back side of the sample **128** at the measurement position (0 mm, 60 degrees).

[0077] As illustrated in FIG. 5B to FIG. 5D, when the measurement position is located at (75 mm, 60 degrees), (100 mm, 60 degrees), and (150 mm, 60 degrees), the moving mechanism **110** moves the sample **128** so that the measurement position on the sample **128** is located at the origin O to which the first X-rays **130** are radiated. Specifically, the sun arm **208** is rotated clockwise from a state illustrated in FIG. 5A, and the planetary arm **212** is rotated counterclockwise from the state illustrated in FIG. 5A. As a result, the sample stage **104** is moved to the positions at which the distance between O and B becomes equal to 75 mm, 100 mm, and 150 mm. As described above, the position O is a fixed position inside the sample chamber (not shown). Thus, the sample stage **104** illustrated in FIG. 5B to FIG. 5D is moved from the position of the sample stage **104** illustrated in FIG. 5A to the upper left side (in a-X-axis direction and Y-axis direction) in FIG. 5B to FIG. 5D. Further, the background correction cover **108A** and the background correction cover **108B** are fixed to the planetary arm **212** as described above, and thus are moved while maintaining a positional relationship with respect to the planetary arm **212**. In states illustrated in FIG. 5B and FIG. 5C, the

sample stage **104** is present on the back side of the sample **128** at the position (75 mm, 60 degrees) and at the position (100 mm, 60 degrees). Meanwhile, in a state illustrated in FIG. 5D, the background correction cover **108A** is present on the back side of the sample **128** at the measurement position (150mm, 60 degrees).

[0078] FIG. 6A to FIG. 6D are views illustrating the positional relationship among the moving mechanism **110**, the sample stage **104**, and the background correction covers **108** when  $\theta$  is fixed to  $-60$  degrees and “r” is changed to 0 mm, 75 mm, 100 mm, and 150 mm, respectively. As illustrated in FIG. 6A, when a measurement position is at (0 mm,  $-60$  degrees) (specifically, at the center of the sample **128**), the moving mechanism **110** moves the sample **128** so that the center of the sample **128** is located at the origin O to which the primary X-rays **130** are radiated. Thus, the moving mechanism **110** moves the sample **128** so that the position B of the sample shaft **214** matches the origin O. In this state, the center line OA of the sun arm **208** and the center line AB of the planetary arm **212** in its longitudinal direction are located at a position rotated counterclockwise from the Y axis by 60 degrees about the position O. Further, the background correction cover **108A** is arranged so that a position of the line segment BC corresponds to a position of the line segment AB rotated counterclockwise by 45 degrees about the position B. The background correction cover **108B** is arranged so that its position corresponds to a position of the background correction cover **108A** rotated by 90 degrees about the position B. In a state illustrated in FIG. 6A, the sample stage **104** is present on the back side of the sample **128** at the measurement position (0 mm,  $-60$  degrees).

[0079] As illustrated in FIG. 6B to FIG. 6D, when the measurement position is located at (75 mm,  $-60$  degrees), (100 mm,  $-60$  degrees), and (150 mm,  $-60$  degrees), the moving mechanism **110** moves the sample **128** so that the measurement position on the sample **128** is located at the origin O to which the first X-rays **130** are radiated. Specifically, the sun arm **208** is rotated counterclockwise from a state illustrated in FIG. 6A, and the planetary arm **212** is rotated clockwise from the state illustrated in FIG. 6A. As a result, the sample stage **104** is moved to the positions at which the distance between O and B becomes equal to 75 mm, 100 mm, and 150 mm. As described above, the position O is a fixed position inside the sample chamber (not shown). Thus, the sample stage **104** illustrated in FIG. 6B to FIG. 6D is moved from the position of the sample stage **104** illustrated in FIG. 6A to the lower left side (in a-X-axis direction and-Y-axis direction) in FIG. 6B to FIG. 6D. Further, the background correction cover **108A** and the background correction cover **108B** are fixed to the planetary arm **212** as described above, and thus are moved while maintaining a positional relationship with respect to the planetary arm **212**. In states illustrated in FIG. 6B and FIG. 6C, the sample stage **104** is present on the back side of the sample **128** at the position (75 mm, 60 degrees) and at the position (100 mm, 60 degrees). Meanwhile, in a state illustrated in FIG. 6D, the background correction cover **108B** is present on the back side of the sample **128** at the measurement position (150 mm, 60 degrees).

[0080] As described above, when two background correction covers **108** are fixed to the planetary arm **212**, the background correction covers **108** can be moved and arranged at predetermined positions with small movement of the arms.

[0081] As described above, any one of the sample stage **104**, the background correction cover **108A**, and the background correction cover **108B** is arranged on the back side of the measurement position illustrated in FIG. 4A to FIG. 6D. Further, even when a position other than the measurement position illustrated in FIG. 4A to FIG. 6D is set as a measurement position, the sample **128** can be moved so that a freely-selected measurement position on the sample **128** is located at the position of the triple sun shaft **206** to which the primary X-rays **130** are radiated, and the sample stage **104** or the background correction covers **108** can be arranged on the back side of the measurement position based on the first to third principles described above. Accordingly, a uniform environment is achieved on the back side of the sample **128** immediately below the measurement position, and thus the measurement condition can be prevented from differing depending on where the measurement position is set.

[0082] Description has been given for the embodiment in which two background correction covers **108** are provided. However, one background correction cover **108** may be provided as long as any one of the sample stage **104** and the background correction cover **108** is present on the back side of the measurement position.

## Second Embodiment

[0083] Next, a second embodiment will be described. The second embodiment is different from the first embodiment only in a configuration of a moving mechanism **110**. Other configurations of the second embodiment are the same as those of the first embodiment, and thus description thereof is omitted.

[0084] As illustrated in FIG. 7, the moving mechanism **110** according to the second embodiment includes a first XY stage **702** and a second XY stage **704**. The first XY stage **702** moves a sample stage **104** to such a position in the XY plane being parallel to a surface of the sample stage **104** and a surface of a background correction cover **108** that primary X-rays **130** are radiated to a measurement position.

[0085] More specifically, the first XY stage **702** includes two first X drive shafts **706**, a first Y drive shaft **708**, and a first vertically moving device **710**. Each of the two first X drive shafts **706** has an elongated shape. The two first X drive shafts **706** are fixed at the same height (at the same position in the Z-axis direction) with their longitudinal direction aligned with the X axis inside a sample chamber. Further, the two first X drive shafts **706** each have a rail for guiding the first Y drive shaft **708**. The rails are provided on sides facing each other.

[0086] The first Y drive shaft **708** has an elongated shape. One end portion of the first Y drive shaft **708** is fitted into the rail of one of the first X drive shafts **706**, and another end portion thereof is fitted into the rail of another one of the first X drive shafts **706**. The first Y drive shaft **708** is moved in the X-axis direction by an actuator (not shown) while being guided by the two first X drive shafts **706**. Further, the first Y drive shaft **708** has a rail for guiding the first vertically moving device **710** on its upper surface.

[0087] The first vertically moving device **710** is fitted into the rail of the first Y drive shaft **708**, and is moved in the Y-axis direction by an actuator (not shown) while being guided by the first Y drive shaft **708**. Further, the first vertically moving device **710** has an upper surface on which the sample stage **104** is arranged and has a configuration that is expandable and contractible in the Z-axis direction. With this configuration, the first vertically moving device **710** appropriately moves the sample stage **104** in the Z-axis direction. Further, the first vertically moving device **710** has a configuration that can rotate the sample stage **104** in the XY plane as desired.

[0088] The second XY stage **704** includes two second X drive shafts **712**, a second Y drive shaft **714**, and a second vertically moving device **716**. Each of the two second X drive shafts **712** has an elongated shape. The two second X drive shafts **712** are fixed at the same height (at the same position in the Z-axis direction) with their longitudinal direction aligned with the X axis inside a sample chamber. Further, the two second X drive shafts **712** each have a rail for guiding the second Y drive shaft **714**. The rails are provided on sides facing each other.

[0089] The second Y drive shaft **714** has an elongated shape. One end portion of the second Y drive shaft **714** is fitted into the rail of one of the second X drive shafts **712**, and another end portion thereof is fitted into the rail of another one of the second X drive shafts **712**. The second Y drive shaft **714** is moved in the X-axis direction by an actuator (not shown) while being guided by the two second X drive shafts **712**. Further, the second Y drive shaft **714** has a rail for guiding the second vertically moving device **716** on its upper surface.

[0090] The second vertically moving device **716** is fitted into the rail of the second Y drive shaft **714**, and is moved in the Y-axis direction by an actuator (not shown) while being guided by the first Y drive shaft **708**. Further, the second vertically moving device **716** has an upper surface on which the background correction cover **108** is arranged and has a configuration that is expandable and contractible in the Z-axis direction. With this configuration, the second vertically moving device

**716** appropriately moves the background correction cover **108** in the Z-axis direction. Further, the second vertically moving device **716** has a configuration that can rotate the background correction cover **108** in the XY plane as desired.

[0091] The first XY stage **702** and the second XY stage **704** are arranged so as not to interfere with each other in operation.

[0092] With the above-mentioned configuration of the moving mechanism **110**, the sample stage **104** and the background correction cover **108** can be arranged at freely-selected positions within a range in which the first XY stage **702** and the second XY stage **704** can be driven. Thus, after a sample **128** is arranged on the sample stage **104** by a method similar to that used in the first embodiment, the sample **128** can be moved so that primary X-rays **130** are radiated to a freely-selected measurement position on the sample **128**. Further, when the sample stage **104** is absent on the back side of the measurement position, the background correction cover **108** can be moved to the back side of the measurement position. Accordingly, also in the second embodiment, a uniform environment is achieved on the back side of the sample **128** immediately below the measurement position, and thus the measurement condition can be prevented from differing depending on the measurement position.

[0093] In the present disclosure, the sample stage **104** or the background correction cover **108** is only required to be arranged so as to be arranged on the back side of the measurement position. However, the configuration of the moving mechanism **110** is not limited to those described in the first embodiment and the second embodiment, and may be other configurations.

[0094] For example, the moving mechanism **110** may have a mechanism for rotating the sample stage **104**. For example, when the moving mechanism **110** has a mechanism for rotating the sample stage **104** by an appropriate angle, by 90 degrees, or by 180 degrees for each rotation, a measurement can be conducted on the entire surface of the sample **128** by using the first XY stage **702**, which has a small size and a small movement range, without an increase in size of the sample chamber.

[0095] Further, the moving mechanism **110** may have a rotary mechanism in place of the second XY stage **704**. More specifically, the moving mechanism **110** may include, for example, the first XY stage **702** described above and a rotary mechanism for rotating the background correction cover **108** about a center of the first XY stage **702**. When the sample stage **104** has a circular shape and has the holding portions **106**, the background correction cover **108** has a shape similar to that of the background correction cover in the first embodiment. The background correction cover **108** is rotated around the sample stage **104** by the rotary mechanism so as to be arranged on the back side of the measurement position. In this case, the second XY stage **704**, the first vertically moving device **710**, and the second vertically moving device **716** are not used. Thus, the background correction cover **108** can be moved to the measurement position with only the simple rotary mechanism.

[0096] Further, for example, the shape of the sample stage **104** is not limited to a circular shape, and may be an octagonal shape as illustrated in FIG. 8, a square shape, a rectangular shape, or other polygonal shapes. Further, the shape of the background correction cover **108** is not limited to a semilunar shape, and may be a rectangular shape as illustrated in FIG. 8. Even in a configuration illustrated in FIG. 8, the background correction cover **108** having a rectangular shape may be arranged adjacent to one side of the sample stage **104** having an octagonal shape, and has an outer edge portion extending along a part of the outer edge of the sample stage **104**. Thus, the sample stage **104** or the background correction cover **108** can be arranged on the back side of a freely-selected measurement position of the sample **128**.

[0097] Further, the moving mechanism **110** may move the irradiation position of the primary X-rays from the X-ray source **102** and the background correction cover **108** without moving the sample stage **104**. More specifically, the moving mechanism **110** may include an irradiation-position control unit and a rotary mechanism. The irradiation-position control unit controls the

irradiation position of the primary X-rays from the X-ray source so that primary X-rays are radiated to a freely-selected measurement position on the surface of the sample **128**. The rotary mechanism rotates the background correction cover **108** about the center of the sample stage **104**. For example, the irradiation-position control unit moves the X-ray source **102** in the XY plane so that the primary X-rays are radiated to a freely-selected measurement position on the sample **128**. Further, for example, the moving mechanism **110** may change a direction in which the X-ray source **102** faces, specifically, a direction in which the primary X-rays are radiated, so that the primary X-rays are radiated to a freely-selected measurement position on the sample **128**. When the sample stage **104** is not located on the back side of the sample **128** at the measurement position, the rotary mechanism moves the background correction cover **108** to the measurement position. For example, when the sample stage **104** and the background correction cover **108** have shapes similar to those described in the first embodiment, the moving mechanism **110** rotates the background correction cover **108** around the sample stage **104**. With the configuration described above, effects similar to those obtained in the embodiments described above can be achieved and the components for moving the sample stage **104** can be omitted.

[0098] Further, for example, a robot arm capable of moving the background correction cover **108** to a freely-selected position may be provided to the configuration in which the position of the sample stage **104** is fixed and the X-ray source **102** can radiate the primary X-rays **130** to a freely-selected position on the sample **128**. The robot arm has, for example, four degrees of freedom including three degrees of freedom for moving the background correction cover **108** to a freely-selected position in an XYZ space inside the sample chamber and one degree of freedom for rotating the background correction cover **108** by any appropriate angle in the XY plane.

[0099] The present disclosure can be variously modified without being limited to the above-mentioned examples. The configuration of the e above-mentioned X-ray fluorescence spectrometer **100** is described as one example, and the present disclosure is not limited thereto. The configurations described in the above-mentioned examples may be replaced by configurations that are substantially the same as the configurations described in the above-mentioned examples, configurations that exhibit the same action and effect as those of the configurations described in the above-mentioned examples, or configurations that achieve the same object as that of the configurations described in the above-mentioned examples.

#### REFERENCE SIGNS LIST

[0100] **100** X-ray fluorescence spectrometer, **102** X-ray source, **104** sample stage, **106** holding portion, **108**, **108A**, **108B** background correction cover, **110** moving mechanism, **112** spectroscopic device, **114** detector, **116** goniometer, **118** counter, **120** information processing unit, **122** analysis unit, **124** correction unit, **126** light source, **127** light-receiving portion, **128** sample, **130** primary X-rays, **132** laser, **202** conveying arm, **204** cutout portion, **206** triple sun shaft, **208** sun arm, **210** double planetary shaft, **212** planetary arm, **214** sample shaft, **302** first sun shaft, **304** second sun shaft, **306** third sun shaft, **308** first planetary shaft, **310** second planetary shaft, **312** first sun gear, **314** first idler gear, **315** first idler shaft, **316** first planetary gear, **318** second sun gear, **320** second idler gear, **321** second idler shaft, **322** second planetary gear, **324** third planetary gear, **326** third idler gear, **327** third idler shaft, **328** sample gear, **330** to **337** bearing, **702** first XY stage, **704** second XY stage, **706** first X drive shaft, **708** first Y drive shaft, **710** first vertically moving device, **712** second X drive shaft, **714** second Y drive shaft, **716** second vertically moving device

#### Claims

1. An X-ray fluorescence spectrometer, comprising: an X-ray source configured to radiate primary X-rays to a surface of a sheet-shaped sample; a detector configured to measure an intensity of fluorescent X-rays emitted from the sample irradiated with the primary X-rays; a sample stage on which the sample is to be placed; an analysis unit configured to perform an analysis based on the



intensity of the fluorescent X-rays, which has been measured by the detector, at a plurality of measurement positions on the surface of the sample; at least one background correction cover, which has an outer edge portion with a shape extending along a part of an outer edge of the sample stage, and is arranged adjacent to an outer side of the sample stage so that a surface of the background correction cover is substantially flush with a surface of the sample stage; and a moving mechanism configured to move the sample stage so that the primary X-rays are radiated to a freely-selected measurement position on the surface of the sample, wherein the moving mechanism moves the background correction cover based on movement of the sample stage and, when the sample stage is absent on a back side of the sample at a measurement position, moves the background correction cover so that the background correction cover is located on the back side of the sample at the measurement position.

2. The X-ray fluorescence spectrometer according to claim 1, wherein the background correction cover is made of the same material as a material of the sample stage.

3. The X-ray fluorescence spectrometer according to claim 1, wherein the sample stage has a holding portion with a protruding shape to be brought into abutment against a part of the sample.

4. The X-ray fluorescence spectrometer according to claim 1, wherein the moving mechanism includes: a triple sun shaft to be rotationally driven; a sun arm fixed to the triple sun shaft; a double planetary shaft being rotatably supported at a rotating end portion of the sun arm; a planetary arm fixed to the double planetary shaft; and a sample shaft being rotatably supported at a rotating end portion of the planetary arm, wherein the sample stage is fixed to the sample shaft, and wherein the background correction cover is fixed to the planetary arm.

5. The X-ray fluorescence spectrometer according to claim 1, wherein the moving mechanism includes: an XY stage configured to move the sample stage in an XY plane being parallel to the surface of the sample stage and the surface of the background correction cover to such a position that the primary X-rays are radiated to the measurement position; and a rotary mechanism configured to rotate the background correction cover about a center of the sample stage.

6. The X-ray fluorescence spectrometer according to claim 1, wherein a distance from a center to the outer edge of the sample stage is smaller than a distance from a center to an outer edge of the sample, and wherein a distance from the center of the sample stage to an end portion of the background correction cover is larger than the distance from the center to the outer edge of the sample.

7. The X-ray fluorescence spectrometer according to claim 1, wherein the analysis unit includes a correction unit configured to perform a correction by subtracting a background intensity from the measured intensity measured by the detector.

8. The X-ray fluorescence spectrometer according to claim 1, wherein the sample stage has a circular shape, and wherein the outer edge portion of the background correction cover, which has a shape extending along the part of the outer edge of the sample stage, has an arc-like shape extending along the outer edge of the sample stage having the circular shape.

9. The X-ray fluorescence spectrometer according to claim 1, further comprising a sample detecting unit configured to detect, when the sample has a circular shape with a cutout portion, a position of the cutout portion of the sample, which is arranged on an outer side of the outer edge of the sample stage.

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