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Hard disk drive disk media curvature mitigation

Abstract

A hard disk drive includes multiple disk media mounted on a spindle, where the outer diameter of each disk medium is offset from the inner diameter of the disk medium in a same direction along an axis of rotation of the spindle, and a load/unload ramp positioned, based on the offset, to align in correspondence with the outer diameters of the disk media. Thus, the curvature of irregular disk media, such as that associated with thinner and thinner disks, is mitigated by grouping similarly-characterized irregular disks together on a given spindle and compensating the ramp accordingly.

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Background/Summary

FIELD OF EMBODIMENTS

(1) Embodiments of the invention may relate generally to hard disk drives and particularly to approaches to mitigating disk media curvature in a hard disk drive.

BACKGROUND

(2) A hard disk drive (HDD) is a non-volatile storage device that is housed in a protective enclosure and stores digitally encoded data on one or more circular disks having magnetic surfaces. When an HDD is in operation, each magnetic-recording disk is rapidly rotated by a spindle system. Data is read from and written to a magnetic-recording disk using a read-write head (or “transducer”) housed in a slider that is positioned over a specific location of a disk by an actuator. A read-write head makes use of magnetic fields to write data to and read data from the surface of a magnetic-recording disk. A write head works by using the current flowing through its coil to produce a magnetic field. Electrical pulses are sent to the write head, with different patterns of positive and negative currents. The current in the coil of the write head produces a localized magnetic field across the gap between the head and the magnetic-recording disk, which in turn magnetizes a small area on the recording medium.

(3) Increasing the storage capacity of hard disk drives (HDDs) is one of the on-going goals of HDD technology evolution. In one form, this goal manifests in increasing the number of disks implemented in a given HDD. However, oftentimes maintaining a standard form factor is required, as characterized in part by the z-height of an HDD, which inherently provides challenges with respect to fitting more disks into a given HDD. More particularly, customer specifications and/or common design and operational constraints include load/unload requirements and operational shock (or “op-shock”) requirements, which generally relate to an HDD's operational tolerance of a mechanical shock event. It remains a challenge to increase the number of disks while maintaining a standard form factor, while also reliably meeting load/unload and op-shock requirements.

(4) Any approaches that may be described in this section are approaches that could be pursued, but not necessarily approaches that have been previously conceived or pursued. Therefore, unless otherwise indicated, it should not be assumed that any of the approaches described in this section qualify as prior art merely by virtue of their inclusion in this section.

Description

BRIEF DESCRIPTION OF THE DRAWINGS

(1) Embodiments are illustrated by way of example, and not by way of limitation, in the figures of the accompanying drawings and in which like reference numerals refer to similar elements and in which:

(2) FIG. 1 is a plan view illustrating a hard disk drive, according to an embodiment;

(3) FIG. 2 is a cross-sectional side view illustrating a disk stack and corresponding load/unload ramp;

(4) FIG. 3A is a cross-sectional side view illustrating a curvature-mitigated disk stack and corresponding load/unload ramp, according to an embodiment;

(5) FIG. 3B is a cross-sectional side view illustrating a curvature-mitigated disk stack and corresponding load/unload ramp, according to an embodiment; and

(6) FIG. 4 is a flow diagram illustrating a method for assembling a hard disk drive, according to an embodiment.

DETAILED DESCRIPTION

(7) Generally, approaches to mitigating disk media curvature in a hard disk drive (HDD) are described. In the following description, for the purposes of explanation, numerous specific details are set forth in order to provide a thorough understanding of the embodiments of the invention described herein. It will be apparent, however, that the embodiments of the invention described

herein may be practiced without these specific details. In other instances, well-known structures and devices may be shown in block diagram form in order to avoid unnecessarily obscuring the embodiments of the invention described herein.

INTRODUCTION

Terminology

(8) References herein to “an embodiment”, “one embodiment”, and the like, are intended to mean that the particular feature, structure, or characteristic being described is included in at least one embodiment of the invention. However, instances of such phrases do not necessarily all refer to the same embodiment,

(9) The term “substantially” will be understood to describe a feature that is largely or nearly structured, configured, dimensioned, etc., but with which manufacturing tolerances and the like may in practice result in a situation in which the structure, configuration, dimension, etc. is not always or necessarily precisely as stated. For example, describing a structure as “substantially vertical” would assign that term its plain meaning, such that the sidewall is vertical for all practical purposes but may not be precisely at 90 degrees throughout.

(10) While terms such as “optimal”, “optimize”, “minimal”, “minimize”, “maximal”, “maximize”, and the like may not have certain values associated therewith, if such terms are used herein the intent is that one of ordinary skill in the art would understand such terms to include affecting a value, parameter, metric, and the like in a beneficial direction consistent with the totality of this disclosure. For example, describing a value of something as “minimal” does not require that the value actually be equal to some theoretical minimum (e.g., zero), but should be understood in a practical sense in that a corresponding goal would be to move the value in a beneficial direction toward a theoretical minimum.

(11) Context

(12) Recall that the number of disks in a given form factor may be increased to increase storage capacity. Consequently, implementation of thinner recording disks (or simply “disks”) may be considered. However, generally, the thinner the disks the poorer the flatness control of the disks, which is simply a fundamental result of the substrate and media manufacturing processes (such as due to stresses to the substrate caused by inconsistent magnetic plating deposited on each side of the disk). Non-flat (also “non-planar” or “irregular” or “warped”) disks typically take one of various main forms, such as those referred to as bowl (e.g., concave), umbrella (e.g., convex), and saddle (e.g., shaped in the form of a horse's saddle, as in bent down at the sides so as to give the upper part a rounded form).

(13) FIG. 2 is a cross-sectional side view illustrating a disk stack and corresponding load/unload ramp. Disk stack **200** comprises a plurality of recording disks **202a-202n** (or “hard disks” or simply “disks”), such as magnetic-recording disks, where n represents an arbitrary number of disks (here, ten) that may vary from implementation to implementation. Disks **202a-202n** are mounted on a spindle **204** for rotation. Typically adjacent to or even somewhat overlapping with the disks **202a-202n** is one or more load/unload (LUL) ramp **206** structure(s). LUL ramp technology involves a mechanism that moves the head stack assembly (HSA), including the read-write head sliders (see, e.g., slider **110b** that includes a magnetic read-write head **110a** of FIG. 1), away from and off the disks **202a-202n** and safely positions them onto a cam-like structure. The cam typically includes for each slider a shallow ramp portion on the side closest to the disk, which merges with a typically horizontal “parking” area that may have a detent feature to hold the corresponding slider in place. During a power-on sequence, for example, the read-write heads (e.g., read-write head **110a**) are loaded by moving the sliders (e.g., sliders **110b**) off the LUL ramp **206** and over the disk **202a-202n** surfaces when the disks reach the appropriate rotational speed. Thus, the terminology used is that the sliders or HSA are “loaded” to or over the disk (i.e., off the ramp) into an operational position, and “unloaded” from the disk (i.e., onto the ramp) such as in an idle position.

(14) However, in view of irregular disks **202a-202n** having poor flatness control, such as with

thinner disks (for a non-limiting example, 0.45 millimeters (mm) thick), the disk stack **200** of FIG. 2 illustrates (in exaggerated format) that random incorporation of irregular disks **202a-202n** onto spindle **204** may very well cause a mismatch or misalignment with the corresponding LUL ramp **206**, which is operationally problematic. Thus, challenges remain with increasing the number of disks in a given form factor in view of HDD load/unload and op-shock requirements, such as due to disk stack tolerance stack-up, and poor disk flatness in particular.

(15) Curvature-Mitigated Disk Stack

(16) According to an embodiment, hard disk drive (HDD) disk stack tolerance stack-up and op-shock performance, for example, can be improved if known-shaped disks are placed in certain, controlled positions in the disk stack. Likewise, the LUL ramp can be designed to align ramp tips with the expected disk height at the outer diameter (OD) of each of the disks.

(17) FIG. 3A is a cross-sectional side view illustrating a curvature-mitigated disk stack and corresponding load/unload ramp, according to an embodiment. Disk stack **300** comprises a plurality of recording disks **302a-302n** (or simply “disks”), such as magnetic-recording disks, where *n* represents an arbitrary number of disks (here, ten) that may vary from implementation to implementation. Disks **302a-302n** are rotatably mounted on a spindle **304**. Adjacent to or somewhat overlapping with the disks **302a-302n** is one or more load/unload (LUL) ramp **306** structure(s), operating or functioning the same as or similarly to as described in reference to ramp **206** (FIG. 2). Here, rather than randomly incorporating irregular disks onto spindle **304**, disks **302a-302n** are sorted (e.g., before or during assembly of the disks onto the spindle) by their irregularity characteristic, and similarly-characterized irregular disks **302a-302n** are mounted together on the same spindle **304**. For example, bowl disks are assembled together on the same spindle, and/or umbrella disks are respectively assembled together on the same spindle, and/or saddle disks are respectively assembled together on the same spindle. Here, all the disks **302a-302n** are depicted as umbrella-shaped (in exaggerated format), for purposes of example, while noting that each of the other irregular-shaped disk forms may be similarly grouped and mounted on a respective spindle.

(18) The point being that disks **302a-302n** having a similar irregular shape are assembled together, to avoid random misalignments between disks **302a-302n** and corresponding ramp(s) **306** (e.g., where the ramp tip end closest to the disk may be used as frame of reference relative to alignment), such as illustrated and described in reference to disk stack **200** of FIG. 2. As such, one way to characterize this approach to implementation of irregular or non-planar disks is to describe the disk media as having an outer diameter (OD) that is offset from its inner diameter (ID), thus describing an irregular or non-planar or warped set of disks such as those referred to as bowl, umbrella, saddle, or otherwise. In the embodiment illustrated in FIG. 3A the plurality of disks **302a-302n** mounted on the spindle **304**, whose ODs are offset from their IDs in a same direction (e.g., along an axis of rotation **304r** of the spindle), consists of all of the disk media mounted on the spindle **304**.

(19) Not only are similarly-characterized irregular disks **302a-302n** (e.g., characterized based on form and/or amount of ID-OD offset) mounted together on the same spindle **304**, furthermore and according to an embodiment the LUL ramp(s) **306** is positioned to align in correspondence with (or in alignment with) the OD of the disk media, i.e., disks **302a-302n**. As mentioned, one approach to aligning the LUL ramp(s) **306** with the group of similarly-characterized irregular disks **302a-302n** is to align the ramp tips **306t** (e.g., the primary sloped portion of the ramp **306**, typically closest to the disk media) with the expected disk height at the outer diameter (OD) of each of the disks. Note that such alignment may vary from implementation to implementation, where other portions or points of ramp **306** may serve as the point of reference for alignment with the disks **302a-302n**, in the broader context of LUL ramp technology generally and the corresponding desired load and unload procedures for a given HDD design. That is to say that aligning the ramp **306** with the disks **302a-302n** does not necessarily require that the corresponding components are precisely aligned,

such as end point of ramp tip **306t** to disk **302a-302n** OD point, but that other considerations of load/unload technology may be considered in the context of aligning the corresponding components.

(20) Note that slider load/unload processes are not simple or trivial. For example, the physical configuration of a ramp can affect the amount that the sliders are lifted as well as the speed at which they are loaded and unloaded. At unloading, the slider moves up and away from the disk first, and then typically moves back down toward the disk, a phenomenon referred to herein as slider “rebound”. More particularly, the slider is lifted gradually by way of a lift tab extending from the end of the suspension load beam mechanically interacting with and thereby being lifted on the ramp slope, while the gramload on the slider is decreasing gradually. Here, the term “gramload” generally refers to the spring load of the entire suspension and slider assembly. However, the slider air bearing surface (ABS) forces include not only a positive lift force for flying over the disk but also a negative suction force. Therefore, even while the gramload is decreasing the slider is still being pulled close to the disk for some duration (due to the suction) until the ABS breaks from or overcomes the suction force. Once enough lifting is achieved to overcome the ABS forces, the slider typically moves upward rapidly. Because the suspension (including the flexure) acts as a spring, once the slider moves high it then returns to low (i.e., closer to the disk), and then continues the high-low loop (e.g., slider oscillation) with damping, until the slider oscillation finally ends. The point here reinforces the notion that properly aligning the ramp **306** with the OD of the disks **302a-302n** may be more complex than and entail more considerations than simply physically and linearly aligning certain portions of the structure of the corresponding components.

(21) Furthermore, there are a number of ways in which ramp **306** may be aligned in correspondence with the disk media. For manufacturing simplicity, according to one embodiment the ramp **306** position and its alignment with the disks **302a-302n** is not adaptive from HDD to HDD, rather a common disk-ramp interface is designed to be static based, for example, on a mean or average disk irregularity (e.g., curvature or ID-OD offset). For example, if disk non-planarity over a significant number of samples is found to have a certain offset, then a static ramp design and/or vertical positioning within corresponding HDDs can be implemented accordingly. For example, the ramp seating surface of its corresponding structural base (see, e.g., HDD housing **168** of FIG. 1) may be machined more or less from the nominal, to effectively lower or raise the ramp from nominal, for HDDs for which this curvature mitigation approach is implemented. It may also be that a different ramp **306** is used for each of the respective characteristic forms of the corresponding irregular disks **302a-302n**, according to an embodiment. Alternatively, it may be that the bottom interface/attachment of the ramp **306** with its corresponding structural base may be implemented to be variable, such that the ramp **306** is able to be assembled with the base at a variable height (such as using something akin to a set screw, for a non-limiting example), such as based on the specific characteristic form of the corresponding irregular disks **302a-302n** mounted on spindle **304**, according to an embodiment.

(22) While assembling together a set of umbrella-shaped irregular disks **302a-302n** such as illustrated in FIG. 3A may be preferred, e.g., to limit the risk of ramp-cover interference due to the disk stack tolerance stack-up that reaches its maximum at the top disk **302a**, other irregular disk stack configurations are considered. FIG. 3B is a cross-sectional side view illustrating a curvature-mitigated disk stack and corresponding load/unload ramp, according to an embodiment. Here also, rather than randomly incorporating irregular disks onto spindle **354**, the disks are sorted by their irregularity characteristic, and similarly-characterized irregular disks are mounted together on the same spindle **354**.

(23) Here, the plurality of disk media comprises a first group of disk media, disks **352-1a** through **352-1m** where m represents an arbitrary number of disks (here, five) that may vary from implementation to implementation, and a second group of disk media, disks **352-2a** through **352-2n** where n represents an arbitrary number of disks (here, five) that may vary from implementation to

implementation. As depicted, each of the first group of disks **352-1a** through **352-1m** is rotatably mounted on a spindle **354** with an outer diameter offset from an inner diameter in a same first direction along the axis of rotation **354r** of the spindle **354**, and each of the second group of disks **352-2a** through **352-2n** is rotatably mounted on the spindle **354** with an outer diameter offset from an inner diameter in a same opposing second direction along the axis of rotation **354r** of the spindle **354**. As depicted for purposes of example, disks **352-1a** through **352-1m** are all bowl-shaped (in exaggerated format) and disks **352-2a** through **352-2n** are all umbrella-shaped (in exaggerated format).

(24) Likewise, the LUL ramp comprises a first ramp portion **356-1** and a second ramp portion **356-2**, where the first ramp portion **356-1** (e.g., corresponding ramp tips **356t**) is positioned to align in correspondence with the outer diameters of the first disks **352-1a** through **352-1m**, and the second ramp portion **356-2** (e.g., corresponding ramp tips **356t**) is positioned to align in correspondence with the outer diameters of the second disks **352-2a** through **352-2n**. For example, the top ramp portion **356-1** may be shifted up 20 μm (micrometers, or microns) from the nominal while the bottom ramp portion **356-2** is shifted down 20 μm from the nominal, both to align with their corresponding disk sub-stack **352-1a** through **352-1m** and **352-2a** through **352-2n**, respectively. Furthermore and according to an embodiment, the top disks **352-1a** through **352-1m** may be grouped together based on their similar mean irregularity (ID-OD offset of 10 micron) while the bottom disks **352-2a** through **352-2n** are grouped together based on their similar mean irregularity (ID-OD offset of 25 micron) that is different from the top disks **352-1a** through **352-1m**. Therefore, the top ramp portion **356-1** would be shifted up around 10 μm from the nominal while the bottom ramp portion **356-2** would be shifted down around 25 μm from the nominal, both to align with their corresponding disk sub-stack **352-1a** through **352-1m** and **352-2a** through **352-2n**, respectively.

(25) Method for Assembling a Hard Disk Drive

(26) FIG. 4 is a flow diagram illustrating a method for assembling a hard disk drive, according to an embodiment. For example, the method of FIG. 4 can be used to build embodiments of disk stacks illustrated and described in reference to FIGS. 3A-3B.

(27) At block **402**, determine the flatness of each disk medium of a plurality of disk media. For example, any of a number of conventional measuring tools, machines, operations, etc. may be used to measure the flatness, or lack thereof, of a group of disk media such as disks **302a-302n** (FIG. 3A), **352-1a** through **352-1m** (FIG. 3B), **352-2a** through **352-2n** (FIG. 3B). According to an embodiment, disks **302a-302n**, **352-1a** through **352-1m**, **352-2a** through **352-2n** are then sorted based on the determined flatness, and oriented into corresponding disk cassettes based on similar flatness and with their outer diameters offset from their inner diameters in the same direction within each corresponding disk cassette, for readily positioning the disk media from each disk cassette onto a spindle with their outer diameters offset from their inner diameters in the same direction. Such pre-orienting of the disk media in corresponding disk cassettes may be performed as part of media manufacturing/testing process, or as part of HDD manufacturing/testing process, for example. Regardless, once similarly-characterized disks are oriented in cassettes, they can be installed/assembled onto the spindle serially per usual manufacturing procedure.

(28) At block **404**, position the disk media onto a spindle such that an outer diameter of each disk medium is offset from an inner diameter of the disk medium in a same direction along an axis of rotation of the spindle. For example, disks **302a-302n**, **352-1a** through **352-1m**, **352-2a** through **352-2n** are positioned onto respective spindle **304** (FIG. 3A), **354** (FIG. 3B) such that the OD of each disk is offset from the ID of the disk in the same direction along an axis of rotation **304r**, **354r** of the spindle **304**, **354**. In the case of disk stack **300** of FIG. 3A, disks **302a-302n** are all positioned as umbrella-shaped with their ODs offset lower than their IDs. In the case of disk stack **350** of FIG. 3B, disks **352-1a** through **352-1m** are all positioned as bowl-shaped with their ODs offset higher than their IDs and disks **352-2a** through **352-2n** are all positioned as umbrella-shaped with their ODs offset lower than their IDs.

(29) According to an embodiment, after determining flatness (block **402**) and prior to positioning onto the spindle (block **404**), each disk medium is marked as to whether the disk medium should be positioned onto the spindle as a first group of disk media with their outer diameters offset from their inner diameters in a same first direction along the axis of rotation of the spindle or the disk medium should be positioned as a second group of disk media with their outer diameters offset from their inner diameters in a same opposing second direction along the axis of rotation of the spindle. For example, disks **302a-302n** and **352-2a** through **352-2n** may all be similarly marked (e.g., with a bar code), along with other similarly shaped disks, to indicate that these disks are to be assembled onto the respective spindle **304**, **354** as umbrella-shaped disks (OD lower than ID), while disks **352-1a** through **352-1m** may all be similarly marked (e.g., with a bar code), along with other similarly shaped disks, to indicate that these disks are to be assembled onto the respective spindle **354** as bowl-shaped disks (OD higher than ID). Thus, each disk marking can be read at assembly time (e.g., by a robotic machine) to determine how such disks **302a-302n**, **352-1a** through **352-1m**, **352-2a** through **352-2n** should be oriented and assembled onto the corresponding spindle **304**, **354**. Alternatively to reading at assembly time, the marked disks **302a-302n**, **352-1a** through **352-1m**, **352-2a** through **352-2n** may be sorted based on their respective marking and oriented into corresponding disk cassettes based on their marking, with their outer diameters offset from their inner diameters in the same direction within each corresponding disk cassette, for readily positioning the disk media from each disk cassette onto a spindle with their outer diameters offset from their inner diameters in the same direction.

(30) According to an embodiment, disks **302a-302n**, **352-1a** through **352-1m**, **352-2a** through **352-2n** may be sorted based on the determined flatness, packaged into corresponding disk cassettes based on the type or form or characterization, and the disk cassettes assigned to corresponding disk installation stations based on the type.

(31) At block **406**, position a load/unload (LUL) ramp relative to the outer diameters of the disk media. For example, ramp **306** (FIG. 3A), **356-1** and **356-2** (FIG. 3B) is positioned in alignment with or relative to the ODs of the respective disks **302a-302n**, **352-1a** through **352-1m**, **352-2a** through **352-2n**, as described in more detail elsewhere herein. Hence the error in alignment between disks and ramps is minimized, improving load/unload tolerances and op-shock performance, and enabling more disks to be added to the same standard HDD form factor.

(32) Physical Description of an Illustrative Operating Context

(33) Embodiments may be used in the context of a digital data storage device (DSD) such as a hard disk drive (HDD). Thus, in accordance with an embodiment, a plan view illustrating a conventional HDD **100** is shown in FIG. 1 to aid in describing how a conventional HDD typically operates.

(34) FIG. 1 illustrates the functional arrangement of components of the HDD **100** including a slider **110b** that includes a magnetic read-write head **110a**. Collectively, slider **110b** and head **110a** may be referred to as a head slider. The HDD **100** includes at least one head gimbal assembly (HGA) **110** including the head slider, a lead suspension **110c** attached to the head slider typically via a flexure, and a load beam **110d** attached to the lead suspension **110c**. The HDD **100** also includes at least one recording medium **120** rotatably mounted on a spindle **124** and a drive motor (not visible) attached to the spindle **124** for rotating the medium **120**. The read-write head **110a**, which may also be referred to as a transducer, includes a write element and a read element for respectively writing and reading information stored on the medium **120** of the HDD **100**. The medium **120** or a plurality of disk media may be affixed to the spindle **124** with a disk clamp **128**.

(35) The HDD **100** further includes an arm **132** attached to the HGA **110**, a carriage **134**, a voice-coil motor (VCM) that includes an armature **136** including a voice coil **140** attached to the carriage **134** and a stator **144** including a voice-coil magnet (not visible). The armature **136** of the VCM is attached to the carriage **134** and is configured to move the arm **132** and the HGA **110** to access portions of the medium **120**, all collectively mounted on a pivot shaft **148** with an interposed pivot bearing assembly **152**. In the case of an HDD having multiple disks, the carriage **134** may be

referred to as an “E-block,” or comb, because the carriage is arranged to carry a ganged array of arms that gives it the appearance of a comb.

(36) An assembly comprising a head gimbal assembly (e.g., HGA **110**) including a flexure to which the head slider is coupled, an actuator arm (e.g., arm **132**) and/or load beam to which the flexure is coupled, and an actuator (e.g., the VCM) to which the actuator arm is coupled, may be collectively referred to as a head-stack assembly (HSA). An HSA may, however, include more or fewer components than those described. For example, an HSA may refer to an assembly that further includes electrical interconnection components. Generally, an HSA is the assembly configured to move the head slider to access portions of the medium **120** for read and write operations.

(37) With further reference to FIG. **1**, electrical signals (e.g., current to the voice coil **140** of the VCM) comprising a write signal to and a read signal from the head **110a**, are transmitted by a flexible cable assembly (FCA) **156** (or “flex cable”, or “flexible printed circuit” (FPC)).

Interconnection between the flex cable **156** and the head **110a** may include an arm-electronics (AE) module **160**, which may have an on-board pre-amplifier for the read signal, as well as other read-channel and write-channel electronic components. The AE module **160** may be attached to the carriage **134** as shown. The flex cable **156** may be coupled to an electrical-connector block **164**, which provides electrical communication, in some configurations, through an electrical feed-through provided by an HDD housing **168**. The HDD housing **168** (or “enclosure base” or “baseplate” or simply “base”), in conjunction with an HDD cover, provides a semi-sealed (or hermetically sealed, in some configurations) protective enclosure for the information storage components of the HDD **100**.

(38) Other electronic components, including a disk controller and servo electronics including a digital-signal processor (DSP), provide electrical signals to the drive motor, the voice coil **140** of the VCM and the head **110a** of the HGA **110**. The electrical signal provided to the drive motor enables the drive motor to spin providing a torque to the spindle **124** which is in turn transmitted to the medium **120** that is affixed to the spindle **124**. As a result, the medium **120** spins in a direction **172**. The spinning medium **120** creates a cushion of air that acts as an air-bearing on which the air-bearing surface (ABS) of the slider **110b** rides so that the slider **110b** flies above the surface of the medium **120** without making contact with a thin magnetic-recording layer in which information is recorded. Similarly in an HDD in which a lighter-than-air gas is utilized, such as helium for a non-limiting example, the spinning medium **120** creates a cushion of gas that acts as a gas or fluid bearing on which the slider **110b** rides.

(39) The electrical signal provided to the voice coil **140** of the VCM enables the head **110a** of the HGA **110** to access a track **176** on which information is recorded. Thus, the armature **136** of the VCM swings through an arc **180**, which enables the head **110a** of the HGA **110** to access various tracks on the medium **120**. Information is stored on the medium **120** in a plurality of radially nested tracks arranged in sectors on the medium **120**, such as sector **184**. Correspondingly, each track is composed of a plurality of sectorized track portions (or “track sector”) such as sectorized track portion **188**. Each sectorized track portion **188** may include recorded information, and a header containing error correction code information and a servo-burst-signal pattern, such as an ABCD-servo-burst-signal pattern, which is information that identifies the track **176**. In accessing the track **176**, the read element of the head **110a** of the HGA **110** reads the servo-burst-signal pattern, which provides a position-error-signal (PES) to the servo electronics, which controls the electrical signal provided to the voice coil **140** of the VCM, thereby enabling the head **110a** to follow the track **176**. Upon finding the track **176** and identifying a particular sectorized track portion **188**, the head **110a** either reads information from the track **176** or writes information to the track **176** depending on instructions received by the disk controller from an external agent, for example, a microprocessor of a computer system.

(40) An HDD's electronic architecture comprises numerous electronic components for performing their respective functions for operation of an HDD, such as a hard disk controller (“HDC”), an

interface controller, an arm electronics module, a data channel, a motor driver, a servo processor, buffer memory, etc. Two or more of such components may be combined on a single integrated circuit board referred to as a “system on a chip” (“SOC”). Several, if not all, of such electronic components are typically arranged on a printed circuit board that is coupled to the bottom side of an HDD, such as to HDD housing **168**.

(41) References herein to a hard disk drive, such as HDD **100** illustrated and described in reference to FIG. **1**, may encompass an information storage device that is at times referred to as a “hybrid drive”. A hybrid drive refers generally to a storage device having functionality of both a traditional HDD (see, e.g., HDD **100**) combined with solid-state storage device (SSD) using non-volatile memory, such as flash or other solid-state (e.g., integrated circuits) memory, which is electrically erasable and programmable. As operation, management and control of the different types of storage media typically differ, the solid-state portion of a hybrid drive may include its own corresponding controller functionality, which may be integrated into a single controller along with the HDD functionality. A hybrid drive may be architected and configured to operate and to utilize the solid-state portion in a number of ways, such as, for non-limiting examples, by using the solid-state memory as cache memory, for storing frequently-accessed data, for storing I/O intensive data, and the like. Further, a hybrid drive may be architected and configured essentially as two storage devices in a single enclosure, i.e., a traditional HDD and an SSD, with either one or multiple interfaces for host connection.

(42) Extensions and Alternatives

(43) In the foregoing description, embodiments of the invention have been described with reference to numerous specific details that may vary from implementation to implementation. Therefore, various modifications and changes may be made thereto without departing from the broader spirit and scope of the embodiments. Thus, the sole and exclusive indicator of what is the invention, and is intended by the applicants to be the invention, is the set of claims that issue from this application, in the specific form in which such claims issue, including any subsequent correction. Any definitions expressly set forth herein for terms contained in such claims shall govern the meaning of such terms as used in the claims. Hence, no limitation, element, property, feature, advantage or attribute that is not expressly recited in a claim should limit the scope of such claim in any way. The specification and drawings are, accordingly, to be regarded in an illustrative rather than a restrictive sense.

(44) In addition, in this description certain process steps may be set forth in a particular order, and alphabetic and alphanumeric labels may be used to identify certain steps. Unless specifically stated in the description, embodiments are not necessarily limited to any particular order of carrying out such steps. In particular, the labels are used merely for convenient identification of steps, and are not intended to specify or require a particular order of carrying out such steps.

Claims

1. A hard disk drive (HDD) comprising: a plurality of disk media rotatably mounted on a spindle, wherein in an undisturbed state an outer diameter of each disk medium is offset from an inner diameter of the disk medium in a same direction along an axis of rotation of the spindle; and a load/unload (LUL) ramp positioned, based on the offset, to align in correspondence with the outer diameters of the disk media; wherein: the plurality of disk media comprises a first group of disk media; the HDD further comprises a second group of disk media; the LUL ramp comprises a first ramp portion and a second ramp portion; each disk medium of the first group of disk media is rotatably mounted on the spindle with an outer diameter offset from an inner diameter in a same first direction along the axis of rotation of the spindle; the first ramp portion is positioned, based on the offset in the first direction, to align in correspondence with the outer diameters of the first group of disk media; each disk medium of the second group of disk media is rotatably mounted on the

spindle with an outer diameter offset from an inner diameter in a same opposing second direction along the axis of rotation of the spindle; and the second ramp portion is positioned, based on the offset in the second direction, to align in correspondence with the outer diameters of the second group of disk media.

2. The HDD of claim 1, wherein the plurality of disk media consists of all of the disk media mounted on the spindle.

3. The HDD of claim 1, wherein: the first group of disk media consists of a top half of the disk media mounted on the spindle; and the second group of disk media consists of a bottom half of the disk media mounted on the spindle.

4. The HDD of claim 1, wherein each disk medium of the plurality of disk media is substantially equal to or less than 0.5 millimeters (mm) thick.

5. The HDD of claim 1, further comprising: a plurality of head sliders, each head slider housing a read-write transducer configured to read from and to write to a respective disk medium of the plurality of disk media; and an actuator configured for moving the plurality of head sliders to access portions of the disk media.

6. The HDD of claim 1, further comprising: an enclosure base; wherein the LUL ramp is configured to be variably positioned relative to the enclosure base.

7. The HDD of claim 1, wherein: the first ramp portion is positioned based on a first offset distance in the first direction; and the second ramp portion is positioned based on a second offset distance in the second direction that is different from the first offset distance.

8. A method for assembling a hard disk drive (HDD), the method comprising: determining flatness of each disk medium of a plurality of disk media; based on the determined flatness, positioning at least some of the plurality of disk media onto a spindle of the HDD such that an outer diameter of each disk medium is offset from an inner diameter of the disk medium in a same direction along an axis of rotation of the spindle; and positioning a load/unload (LUL) ramp within the HDD, based on the offset, relative to the outer diameters of the at least some disk media; wherein: the plurality of disk media comprises a first group of disk media; the LUL ramp comprises a first ramp portion and a second ramp portion; positioning the at least some disk media includes: positioning each disk medium of the first group of disk media with its outer diameter offset from its inner diameter in a same first direction along the axis of rotation of the spindle, and positioning each disk medium of a second group of disk media with its outer diameter offset from its inner diameter in a same opposing second direction along the axis of rotation of the spindle; and positioning the LUL ramp includes: positioning the first ramp portion, based on the offset in the first direction, to align in correspondence with the outer diameters of the first group of disk media, and positioning the second ramp portion, based on the offset in the second direction, to align in correspondence with the outer diameters of the second group of disk media.

9. The method of claim 8, wherein positioning the at least some disk media includes positioning all of the disk media with their outer diameters offset from their inner diameters in the same direction.

10. The method of claim 8, wherein: positioning the first group of disk media includes positioning the first group as a top half of the disk media; and positioning the second group of disk media includes positioning the second group as a bottom half of the disk media.

11. The method of claim 8, further comprising: sorting the plurality of disk media based on the determined flatness; and orienting the sorted disk media into corresponding disk cassettes based on similar flatness and with their outer diameters offset from their inner diameters in the same direction within each corresponding disk cassette, for positioning the disk media from each disk cassette onto the spindle with their outer diameters offset from their inner diameters in the same direction.

12. The method of claim 8, further comprising: after determining flatness and prior to positioning onto the spindle, marking each disk medium as to whether the disk medium should be positioned onto the spindle as a first group of disk media with their outer diameters offset from their inner

diameters in a same first direction along the axis of rotation of the spindle or the disk medium should be positioned as a second group of disk media with their outer diameters offset from their inner diameters in a same opposing second direction along the axis of rotation of the spindle.

13. The method of claim 12, further comprising: sorting the plurality of disk media based on their marking; and orienting the sorted disk media into corresponding disk cassettes based on their marking and with their outer diameters offset from their inner diameters in the same direction within each corresponding disk cassette.

14. The method of claim 8, further comprising: sorting the plurality of disk media based on type based on the determined flatness; packaging the disk media into corresponding disk cassettes based on the type; and assigning the disk cassettes to corresponding disk installation stations based on the type.

15. A hard disk drive (HDD) comprising: a disk stack comprising a plurality of disk media rotatably mounted on a spindle, wherein in an undisturbed state an outer diameter of each disk medium is offset from an inner diameter of the disk medium in a same direction along an axis of rotation of the spindle; a plurality of head sliders each housing a read-write transducer configured to read from and to write to a respective disk medium of the disk stack; means for moving the plurality of head sliders to access portions of the plurality of disk media; and means for supporting loading the plurality of head sliders onto the disk stack and for supporting unloading the plurality of head sliders from the disk stack, the means for supporting positioned, based on the offsets of the plurality of disk media, to align in correspondence with the outer diameters of the plurality of disk media; wherein: the plurality of disk media comprises a first group of disk media; the HDD further comprises a second group of disk media; the LUL ramp comprises a first ramp portion and a second ramp portion; each disk medium of the first group of disk media is rotatably mounted on the spindle with an outer diameter offset from an inner diameter in a same first direction along the axis of rotation of the spindle; the first ramp portion is positioned to align, based on the offset in the first direction, in correspondence with the outer diameters of the first group of disk media; each disk medium of the second group of disk media is rotatably mounted on the spindle with an outer diameter offset from an inner diameter in a same opposing second direction along the axis of rotation of the spindle; and the second ramp portion is positioned to align, based on the offset in the second direction, in correspondence with the outer diameters of the second group of disk media.

16. The HDD of claim 15, wherein the plurality of disk media consists of all of the disk media mounted on the spindle.

17. The HDD of claim 15, wherein: the first group of disk media consists of a top half of the disk media mounted on the spindle; and the second group of disk media consists of a bottom half of the disk media mounted on the spindle.
