Discrete Fourier Transformation (DFT)

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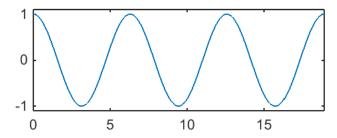
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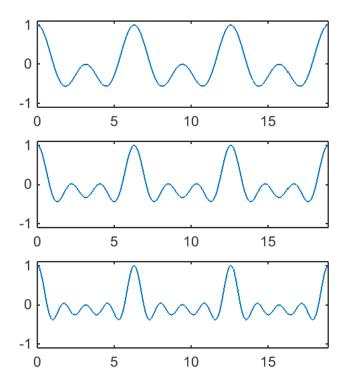
1. Fourier Series

1.1. Delta Dirac Function

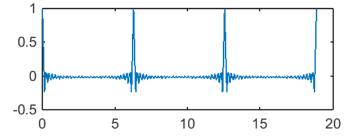
$$\sum_{n=1,2,3,\cdots}\cos(n heta)=\cos heta+\cos2 heta+\cos3 heta+\cdots$$



Out[4]:



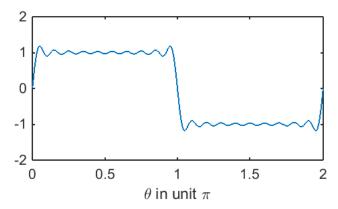
Out[11]:



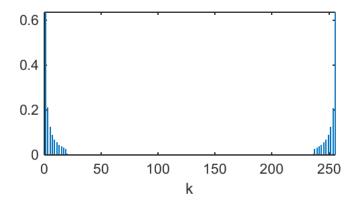
Out[5]:

1.2. Square Wave

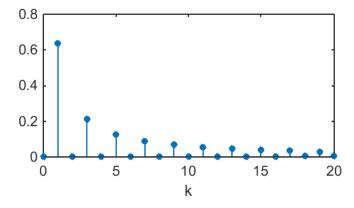
$$\sum_{n=1,3,5,\cdots} \frac{4}{\pi n} \sin(n\theta) = \frac{4}{\pi} \sin \theta + \frac{4}{3\pi} \sin 3\theta + \frac{4}{5\pi} \sin 5\theta + \cdots$$



Out[6]:



Out[11]:

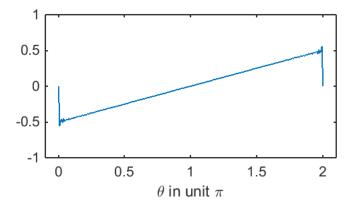


Out[13]:

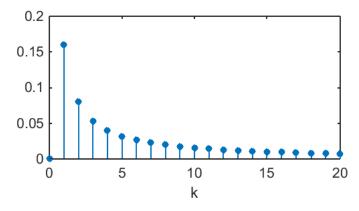
Out[15]:

1.3. Sawtooth wave

$$\frac{1}{2} - \frac{1}{\pi} \sum_{n=1}^{\infty} \frac{1}{n} \mathrm{sin}(\pi \theta)$$



Out[19]:



Out[23]:

2. Eigen-analysis

2.1. Basis

A basis $\{b_k\}$ for a vector space V is a collection of vectors from V that linearly independent and span V

Basis matrix: Stack the basis vectors b_k as columns

$$B = [b_0 | b_1 | b_2 | \cdots | b_{N-1}]$$

Using this matrix, We can now write a linear combination of basis elements as the matrix/vector product

$$x = B \, a = a_0 b_0 + a_1 b_1 + \cdots + a_{N-1} b_{N-1} = \sum_{k=0}^{N-1} a_k b_k = [b_0 \, | \, b_1 \, | \, \cdots \, | \, b_{N-1}] egin{bmatrix} a_0 \ a_1 \ dots \ a_{N-1} \end{bmatrix}$$

An **orthogonal basis** $\{b_k\}_{k=0}^{N-1}$ for a vector space V is a basis whose elements are mutually orthogonal

$$\langle b_k,b_l
angle \,=\,0\,,\quad k\,
eq\, l$$

An **orthonormal basis** $\{b_k\}_{k=0}^{N-1}$ for a vector space V is a basis whose elements are mutually orthogonal and normalized (in the 2-norm)

$$egin{array}{l} \langle b_k,b_l
angle =0\,,\quad k
eq l\ \|b_k\|_2\ =\ 1 \end{array}$$

2.2. Orthogonal Bases

Signal Representation by Orthonormal Basis

$$x=Blpha=\sum_{k=0}^{N-1}lpha_k b_k$$

\$\$ \alpha = B^Hx \qquad \text{or} \qquad \alpha_k = \big \$\$

- **Synthesis**: Build up the signal x as a linear combination of the basis elements b_k weighted by the weights $lpha_k$
- Analysis: Compute the weights α_k such that the synthesis produces x; the weight α_k measures the similarity between x and the basis element b_k

2.3. Eigenvector and eigenvalues

$$Av = \lambda v$$

Using this, we can find this equation

$$AV = V \Lambda \ V = [v_0|v_1|\cdots|v_{N-1}], \, \Lambda = egin{bmatrix} \lambda_0 & & & & \ & \lambda_1 & & \ & & \ddots & \ & & & \lambda_{N-1} \end{bmatrix}$$

We can change to

$$A = V \Lambda V^{-1} \Rightarrow Eigende composition \ V^{-1} A V = \Lambda$$

- Eigenvectors v are input signals that emerge at the system output unchanged (except for a scaling by the eigenvalue \lambda) and so are somehow "fundamental" to the system
- Eigenanalysis of LTI Systems (Finite-Length Signals)
- Goal: Calcuate the eigenvectors and eigenvalues of H
- Fact: The eigenvectors of a circulent matrix (LTI system) are the complex harmonic sinusoids
- Fact: The eigenvalue $\lambda \in C$ corresponding to the sinusoid eigenvector s_k is called the frequency response at frequency k since it measures how the system "responds" to s_k

$$\lambda_k = \sum_{n=0}^{N-1} h[n] e^{-jrac{2\pi}{N}kn} = \left\langle h, s_k
ight
angle = H_u[k]$$

2.4. Eigenvector Matrix of Harmonic Sinusoids $S = \left[s_0|s_1|\cdots|s_{N-1} ight] \\ s_k[n] = \frac{1}{\sqrt{N}}e^{j\frac{2\pi}{N}kn}$

$$S = ig[s_0|s_1|\cdots|s_{N-1}ig] \ s_k[n] = rac{1}{\sqrt{N}}e^{jrac{2\pi}{N}kn}$$

Stack N normalized harmonic sinusoid $\{s_k\}_{k=0}^{N-1}$ as columns into an N imes N complex orthonormal basis matrix

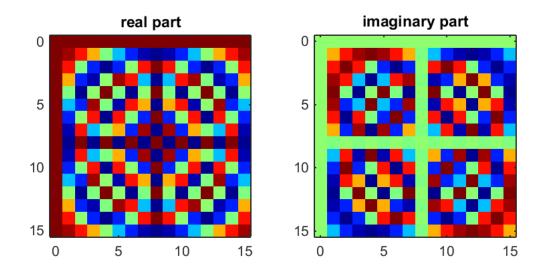
$$s_k \longrightarrow \mathcal{H} \longrightarrow \lambda_k s_k$$

$$\begin{split} s_k[n] * h[n] &= \sum_{m=0}^{N-1} s_k[(n-m)_N] \, h[m] = \sum_{m=0}^{N-1} \frac{e^{j\frac{2\pi}{N}k(n-m)_N}}{\sqrt{N}} \, h[m] \\ &= \sum_{m=0}^{N-1} \frac{e^{j\frac{2\pi}{N}k(n-m)}}{\sqrt{N}} \, h[m] = \sum_{m=0}^{N-1} \frac{e^{j\frac{2\pi}{N}km}}{\sqrt{N}} e^{-j\frac{2\pi}{N}km} \, h[m] \\ &= \left(\sum_{m=0}^{N-1} e^{-j\frac{2\pi}{N}km} \, h[m]\right) \frac{e^{j\frac{2\pi}{N}kn}}{\sqrt{N}} = \lambda_k \, s_k[n] \end{split}$$

2.5. Eigenvalues of LTI Systems

$$\lambda_k \, = \, \sum_{m=0}^{N-1} h[n] \, e^{-jrac{2\pi}{N}kn} \, = \, \langle h, s_k
angle \, = \, H_u[k]$$

 λ_k means the number of s_k in $h[n] \implies$ similarity

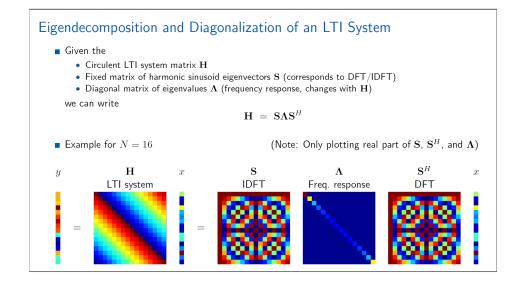


Out[11]:

2.6. Eigendecomposition and Diagonalization of an LTI Systems

- ullet H is LTI System matrix
- ${\cal S}$ is harmonic sinusoid eigenvectors matrix
- Λ is eigenvalue diagonal matrix

$$H=S\Lambda S^H$$



3. Discrete Fourier Transform (DFT)

3.1 Harmonic Sinusoids are an Orthonormal Basis

$$egin{aligned} s_k[n] &= rac{e^{jrac{2\pi}{N}kn}}{\sqrt{N}} \ \langle s_k,s_l
angle &= 0, \quad k
eq l \quad \|s_k\|_2 &= 1 \end{aligned}$$

3.2 DFT & Inverse DFT

• DFT

$$X = S^H x \ X[k] = \langle x, s_k
angle = \sum_{k=0}^{N-1} X[k] \, rac{e^{-jrac{2\pi}{N}kn}}{\sqrt{N}}$$

It is finding how many certain frequncy

• Inverse DFT

$$x=SX \ x[n] = \sum_{k=0}^{N-1} X[k] \, rac{e^{jrac{2\pi}{N}kn}}{\sqrt{N}}$$

It is returing to time domain

Signal Representation by Harmonic Sinusoids

- Given the normalized complex harmonic sinusoids $\{s_k\}_{k=0}^{N-1}$ and the orthonormal basis matrix \mathbf{S} , we define the (normalized) discrete Fourier transform (DFT) for any signal $x \in \mathbb{C}^N$
- Analysis (Forward Normalized DFT)

$$X = \mathbf{S}^{H} x$$

$$X[k] = \langle x, s_k \rangle = \sum_{n=0}^{N-1} x[n] \frac{e^{-j\frac{2\pi}{N}kn}}{\sqrt{N}}$$

■ Synthesis (Inverse Normalized DFT)

$$x = \mathbf{S}X$$

$$x[n] = \sum_{k=0}^{N-1} X[k] \frac{e^{j\frac{2\pi}{N}kn}}{\sqrt{N}}$$

Interpretation: Signal Representation by Harmonic Sinusoids

- Analysis (Forward DFT)
 - \bullet Choose the DFT coefficients X[k] such that the synthesis produces the signal x
 - \bullet The weight X[k] measures the similarity between x and the harmonic sinusoid s_k
 - \bullet Therefore, X[k] measures the "frequency content" of x at frequency k

$$X[k] = \langle x, s_k \rangle = \sum_{n=0}^{N-1} x[n] \frac{e^{-j\frac{2\pi}{N}kn}}{\sqrt{N}}$$

- Synthesis (Inverse DFT)
 - Build up the signal x as a linear combination of harmonic sinusoids s_k weighted by the DFT coefficients X[k]

$$x[n] = \sum_{k=0}^{N-1} X[k] \frac{e^{j\frac{2\pi}{N}kn}}{\sqrt{N}}$$

The Unnormalized DFT

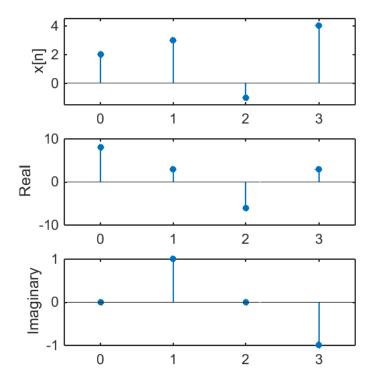
■ Normalized forward and inverse DFT

$$\begin{split} X[k] &=& \sum_{n=0}^{N-1} x[n] \, \frac{e^{-j\frac{2\pi}{N}kn}}{\sqrt{N}} \\ x[n] &=& \sum_{k=0}^{N-1} X[k] \, \frac{e^{j\frac{2\pi}{N}kn}}{\sqrt{N}} \end{split}$$

■ Unnormalized forward and inverse DFT is more popular in practice (we will use both)

$$\begin{array}{rcl} X_u[k] & = & \displaystyle \sum_{n=0}^{N-1} x[n] \, e^{-j \frac{2\pi}{N} k n} \\ \\ x[n] & = & \displaystyle \frac{1}{N} \sum_{k=0}^{N-1} X_u[k] \, e^{j \frac{2\pi}{N} k n} \end{array}$$

2.5. Unnormalized DFT



Out[28]:

FFT algorithms are so commonly employed to compute DFTs that the term 'FFT' is often used to mean 'DFT': DFT refers to a mathematical transformation or function, whereas 'FFT' refers to a specific family of algorithms for computing DFTs.

- use fft command to compute dft
- fft (computationally efficient)

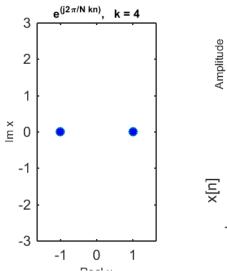
Out[14]: ans =

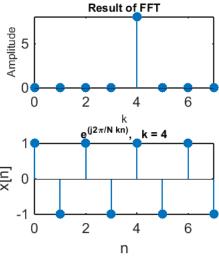
```
8.0000 + 0.0000i 3.0000 + 1.0000i -6.0000 + 0.0000i 3.0000 - 1.0000i
```

- can use dft function defined below, but
- · computationally expensive

```
8.0000 + 0.0000i 3.0000 + 1.0000i -6.0000 - 0.0000i 3.0000 - 1.0000i
```

```
%plot -s 800,400
                                        % index for frequuncy
k = 4;
N = 8;
n = 0:N-1;
                                       % sampling period
x = \exp(1j*2*pi/N*k*n);
                                            % harmonic complex exponential
X = dft(x,N);
subplot(2,2,[1,3]); plot(real(x),imag(x),'o','MarkerFaceColor','b')
axis equal; ylim([-3 3])
xlabel('Real {x}','Fontsize',8)
ylabel('Im {x}','Fontsize',8)
title(['e^{{(j2\pi/N kn)}},  k = ',num2str(k)],'Fontsize',8)
subplot(2,2,2); stem(n,abs(X),'filled'), axis tight
xlabel('k','Fontsize',8)
ylabel('Amplitude','Fontsize',8)
title('Result of FFT','fontsize',8)
subplot(2,2,4), stem(n,real(x),'filled'), axis tight
xlabel('n'), ylabel('x[n]')
title(['e^{(j2\pi/N kn)},  k = ',num2str(k)],'Fontsize',8)
```

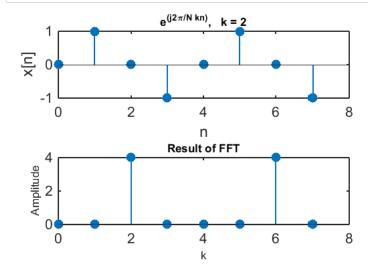




Out[4]:

In [4]:

```
In [30]:
```



Out[30]:

4. DFT Properties

DFT pair

$$x[n] \longleftrightarrow X[k]$$

DFT Frequencies

- X[k] measures the similarity between the time signal x[n] and the harmonic sinusoid $s_k[n]$
- X[k] measures the "frequency content" of x[n] at frequency

$$\omega_k = rac{2\pi}{N} k$$

DFT and Circular Shift

$$x[(n-m)_N] \longleftrightarrow e^{-jrac{2\pi}{N}km}X[k]$$

- · no amplitude changed
- phase changed

DFT and Modulation

$$e^{-jrac{2\pi}{N}r\,n}x[n]\longleftrightarrow X[(k-r)_N]$$

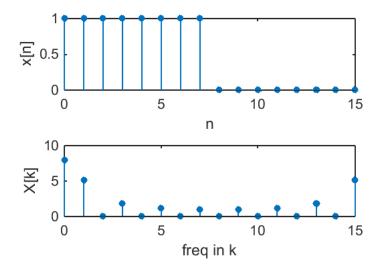
DFT and Circular Convolution

- Circular convolution in the time $\operatorname{domain} = \operatorname{multiplication}$ in the frequency domain

$$Y[k] = H[k]X[k]$$

$$h[n] \star x[n] \longleftrightarrow H[k]X[k]$$

$$y[n] = \mathrm{IDFT}(Y[k])$$



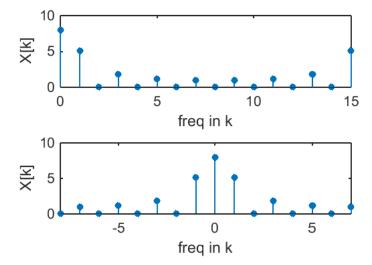
Out[32]:

In [33]:

```
kr = [0:N/2-1 -N/2:-1];
ks = fftshift(kr);

Xs = fftshift(X);

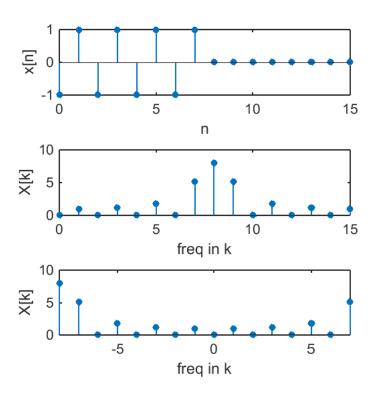
subplot(2,1,1), stem(k,abs(X),'filled','markersize',4), xlabel('freq in k'), ylabel('X[k]')
subplot(2,1,2), stem(ks,abs(Xs),'filled','markersize',4), xlabel('freq in k'), ylabel('X[k]'), xlim([-N/2,N/2-1])
```



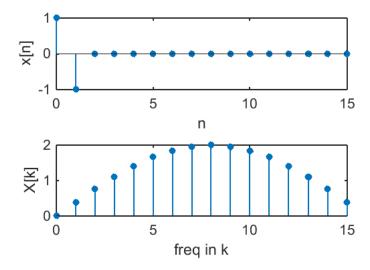
Out[33]:

$$e^{-jrac{2\pi}{N}r\,n}x[n]\longleftrightarrow X[(k-r)_N]$$

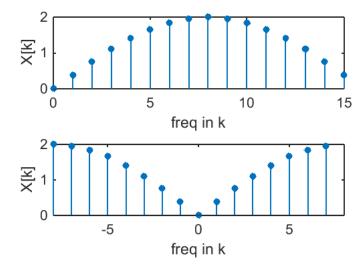
```
In [34]:
               %plot -s 560,600
               N = 16;
               h = zeros(1,N);
               h(1:8) = 1;
               for i = 1:N
                    h(i) = (-1)^i*h(i);
               end
               n = 0:N-1;
               k = n;
               X = dft(h,N);
               kr = [0:N/2-1 -N/2:-1];
               ks = fftshift(kr);
               Xs = fftshift(X);
               subplot(3,1,1), stem(n,h,'filled','markersize',4), xlabel('n'), ylabel('x[n]')
               subplot(3,1,2), stem(k,abs(X),'filled','markersize',4), xlabel('freq in k'), ylabel('X[k]')
subplot(3,1,3), stem(ks,abs(Xs),'filled','markersize',4), xlabel('freq in k'), ylabel('X[k]'), xlim([-N/2,N/2-1])
```



Out[34]:



Out[35]:



Out[36]:

```
In [37]: %plot -s 560,600

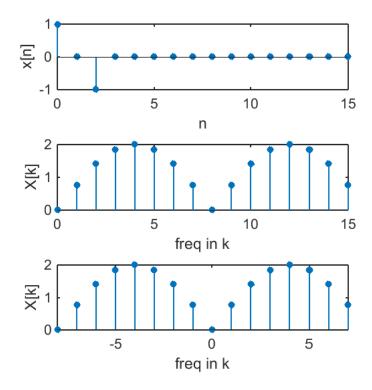
N = 16;
h = zeros(1,N);
h(1) = 1;
h(2) = 0;
h(3) = -1;
n = 0:N-1;
k = n;

X = dft(h,N);

kr = [0:N/2-1 -N/2:-1];
ks = fftshift(kr);

Xs = fftshift(X);

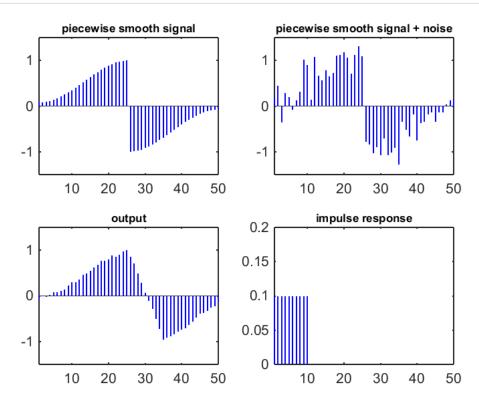
subplot(3,1,1), stem(n,h, 'filled', 'markersize',4), xlabel('n'), ylabel('x[n]')
subplot(3,1,2), stem(k,abs(X), 'filled', 'markersize',4), xlabel('freq in k'), ylabel('X[k]')
subplot(3,1,3), stem(ks,abs(Xs), 'filled', 'markersize',4), xlabel('freq in k'), ylabel('X[k]'), xlim([-N/2,N/2-1])
```



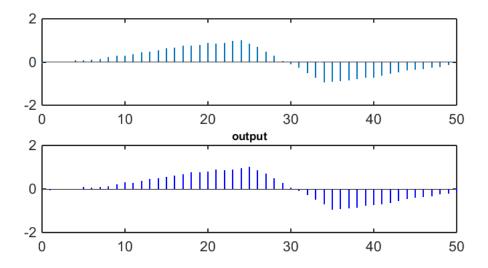
Out[37]:

5. Filtering in Frequency Domain

```
%plot -s 800,600
%---EXAMPLE 2
%---Denoising a piecewise smooth signal
figure('units', 'normalized', 'position',[0 0 1 1.5]);
% piecewise smooth signal
N = 50;
n = 0:N-1;
s = hamming(N) .* [ones(N/2,1); -ones(N/2,1)];
subplot(221)
stem(s,'b','Marker','none','LineWidth',1);
axis([1 N -1.5 1.5])
title('piecewise smooth signal','fontsize',8)
% add noise to the signal
x = s + 0.2*randn(N,1);
subplot(222)
stem(x, 'b', 'Marker', 'none', 'LineWidth',1);
axis([1 N -1.5 1.5])
title('piecewise smooth signal + noise', 'fontsize',8)
\% construct moving average filter impulse response of length \texttt{M}
M = 10;
%M = 3;
h = ones(M,1)/M;
h1 = h; h1(N) = 0;
subplot(224)
stem(h1,'b','Marker','none','LineWidth',1);
axis([1 N 0 0.2])
title('impulse response', 'fontsize',8)
% convolve noisy signal with impulse response
y = circonvt(x',h',50);
subplot(223)
%stem(y(M/2:N+M/2-1),'b','Marker','none','LineWidth',1);
stem(y,'b','Marker','none','LineWidth',1);
axis([1 N -1.5 1.5])
title('output','fontsize',8)
```



In [24]:



Out[25]:

```
function [Xk] = dft(xn,N)
% Computes Discrete Fourier Transform
% [Xk] = dft(xn,N)
% Xk = DFT coeff. array over 0 <= k <= N-1
% xn = N-point finite-duration sequence
% N = Length of DFT
n = [0:1:N-1];
                                     % row vector for n
k = [0:1:N-1];
                                     % row vecor for k
WN = exp(-1j*2*pi/N);
                                     % Wn factor
nk = n'*k;
                                     \% creates a N by N matrix of nk values
WNnk = WN.^nk;
                                   % DFT matrix
Xk = xn*WNnk;
                                   % row vector for DFT coefficients
```