

# **Geomechanical Analysis of Rayleigh Wave Dynamics and Train Weight Dependency in High-Speed Rail Infrastructure**

The emergence of high-speed rail as a cornerstone of modern global transportation has necessitated a profound re-evaluation of the interaction between heavy moving loads and the terrestrial environments they traverse. As operational speeds continue to push toward and exceed 300 km/h, the railway engineering community has identified a suite of complex phenomena that were largely absent in the era of conventional rail. Central to these challenges is the generation and propagation of Rayleigh surface waves, which constitute the most significant portion of ground-borne vibration energy. A critical question for infrastructure designers, safety regulators, and environmental planners is whether these Rayleigh waves depend on the weight of the train. The following analysis demonstrates that while the fundamental theoretical velocity of a Rayleigh wave is a property of the geological medium, the practical manifestation, amplitude, and even the "effective" critical velocity of the site are deeply inextricably linked to the train's axle load and total mass.

## **Theoretical Foundations of Surface Wave Propagation in Rail Environments**

To understand the dependency of Rayleigh waves on train weight, it is essential to first establish the physics of wave propagation in an elastic half-space. When a train moves along a track, the force exerted by its wheels creates a complex field of elastic waves. These include primary longitudinal waves (P-waves) and secondary shear waves (S-waves), which propagate through the volume of the soil. However, at the surface interface, Rayleigh waves emerge as the dominant mechanism of energy transfer. Approximately two-thirds of the total seismic energy generated by a vertically oriented load acting on a horizontal surface propagates in the form of Rayleigh waves.<sup>1</sup> These waves are characterized by an elliptical particle motion in a vertical plane, consisting of both horizontal and vertical components, and their amplitude attenuates exponentially with depth.<sup>2</sup>

The velocity of a Rayleigh wave ( $c_R$ ) in a homogeneous, isotropic elastic medium is primarily dictated by the soil's stiffness and density. Specifically,  $c_R$  is a function of the shear wave velocity ( $c_s$ ) and Poisson's ratio ( $\nu$ ). In most engineering soils, the Rayleigh wave velocity is approximately 90% to 95% of the shear wave velocity.<sup>1</sup> This inherent velocity provides a baseline for the "critical speed" of a site—the speed at which the train's

velocity matches the ground wave velocity, leading to resonant amplification.

Parameter	Symbol	Typical Value Range for Soils	Impact on Rayleigh Wave
Shear Wave Velocity	$c_s$	40 m/s to 500 m/s	Primary determinant of $c_R$ <sup>4</sup>
Poisson's Ratio	$\nu$	0.2 to 0.45	Modifies the $c_R/c_s$ ratio <sup>1</sup>
Soil Density	$\rho$	1600 to 2000 kg/m <sup>3</sup>	Inversely proportional to $c_s$ and $c_R$ <sup>1</sup>
Shear Modulus	$G$	Variable with strain	Directly proportional to $c_R^2$ <sup>4</sup>

The assumption that  $c_R$  is a static constant, however, fails to account for the dynamic environment created by a heavy train. The "weight" of the train, expressed as axle load, introduces non-linearities into the soil behavior that modify these fundamental parameters. Consequently, any rigorous assessment of Rayleigh wave impacts must treat the weight of the train not merely as a scalar multiplier of force, but as a variable that alters the physical properties of the transmission medium itself.

## The Quasi-Static Pressure Mechanism and Axle Load Dependency

The primary mechanism for generating ground vibrations in high-quality, modern tracks is the quasi-static pressure exerted by wheel axles onto the rails.<sup>6</sup> This mechanism exists even for ideally smooth wheels and rails and is fundamentally driven by the downward deflection of the track under the weight of the train. As the train moves, this deflection curve travels along the track at the train's speed, acting as a moving source of vertical force applied to the sleepers and, subsequently, the ground.<sup>9</sup>

The magnitude of this vertical force is directly proportional to the axle load. Mathematical models of this interaction frequently treat the rail as an Euler-Bernoulli beam supported by a viscoelastic foundation (Winkler model). The force applied by a sleeper to the ground ( $P(t)$ ) is a function of the track deflection magnitude ( $w$ ), which itself is linearly dependent on the

axle load ( $\$T\$$ ) in a static regime.<sup>7</sup>

$$\$P(t) = 2 \alpha w(vt) d\$$$

In this expression,  $\alpha$  represents the proportionality coefficient of the foundation,  $v$  is the train speed, and  $d$  is the sleeper periodicity.<sup>7</sup> Because the displacement  $w$  is the response to the load  $T$ , it follows that the amplitude of the resulting Rayleigh wave in the far-field is a direct function of the train's weight. For sub-critical speeds (where train speed is significantly lower than the Rayleigh wave velocity), the relationship remains largely linear: doubling the axle load leads to a near-doubling of the vibration amplitude. However, as speeds increase, this relationship becomes non-linear due to dynamic amplification and soil degradation.<sup>4</sup>

## Non-Linear Geomechanics: How Train Weight Modifies the Medium

The most profound way in which Rayleigh waves depend on train weight is through the phenomenon of soil stiffness degradation. Soil is not a perfectly linear elastic material; its stiffness (shear modulus,  $G$ ) is dependent on the level of strain it experiences. When a heavy high-speed train passes over a site, the immense axle loads induce significant cyclic strains in the subgrade and deeper soil layers.<sup>4</sup>

Studies at soft-soil sites, such as Ledsgård in Sweden, have demonstrated that the strains induced by high-speed trains can be large enough to push the soil into a non-linear regime. At this threshold, the secant shear modulus can degrade to between 10% and 50% of its initial small-strain value.<sup>4</sup> Since the Rayleigh wave velocity is directly related to the square root of the shear modulus ( $c_R \propto \sqrt{G}$ ), the weight of the train effectively reduces the wave velocity of the ground during the train's passage.<sup>4</sup>

This leads to a critical realization: the "critical speed" of a site—the threshold for the ground vibration boom—is not a fixed value but is dependent on the weight of the train. A heavier train induces higher strains, which lowers the soil stiffness, which in turn lowers the Rayleigh wave velocity. Consequently, a heavier train may trigger a "trans-Rayleigh" state at a lower operational speed than a lighter train.<sup>4</sup>

Model Type	Predicted Critical Velocity	Displacement Magnitude	Sensitivity to Speed
Linear Elastic	High (based on $G_{max}$ )	Underestimated at high speed	Moderate

Non-Linear (18t Axle)	Lower (up to 30% reduction)	Up to 30% higher than linear	Extremely High <sup>12</sup>
Non-Linear (Heavy Freight)	Lowest	Extreme deflections	Extreme <sup>4</sup>

In the non-linear regime, the dynamic amplification factor becomes highly sensitive to even minor increases in train speed. Engineering models that ignore this weight-dependent degradation often underestimate track displacements and provide a false sense of security regarding the safety margin between operational speed and critical velocity.<sup>4</sup>

## The Ground Vibration Boom and the Mach Effect

When a train's speed exceeds the Rayleigh wave velocity of the ground ( $v > c_R$ ), a phenomenon known as a "ground vibration boom" occurs.<sup>10</sup> This is the seismic equivalent of a sonic boom or a Mach cone. In this state, the energy from the moving axles accumulates along a wave front that lags behind the train, forming a cone-shaped vibration pattern on the ground surface.<sup>18</sup>

The weight of the train is a decisive factor in the intensity of this boom. Theoretical analysis by Krylov and others shows that the vibration levels can increase by more than 70 dB when a train transitions from a sub-Rayleigh to a trans-Rayleigh state.<sup>6</sup> The intensity of the waves along the Mach cone is scaled by the magnitude of the quasi-static axle loads. Heavier trains displace a larger volume of soil as they move, creating a more powerful "shock wave" in the ground.<sup>20</sup>

The geometry of the Mach cone is defined by the angle  $\theta$ :

$$\cos^{-1} \left( \frac{c_R}{v} \right)$$

While the angle itself is a function of the ratio between the wave speed and train speed, the effective angle is also influenced by weight. Because the weight reduces the effective  $c_R$  through stiffness degradation, a heavier train effectively "widens" the Mach cone by increasing the Mach number ( $M = v/c_R$ ) for a given operational speed.<sup>19</sup> Furthermore, the weight and length of the train (the bogie and carriage spacing) determine the interference patterns of the waves generated by individual axles. If the frequency of axle passage coincides with the resonant frequencies of the track-ground system, the weight-induced vibrations can reach catastrophic levels.<sup>1</sup>

## Interaction with Site-Specific Geology and Layering

The dependency of Rayleigh waves on train weight is further complicated by the geological

layering of the ground. Rayleigh waves are dispersive in layered media, meaning that different frequencies travel at different speeds. Higher frequencies (shorter wavelengths) are primarily influenced by the stiffness of the upper layers, while lower frequencies (longer wavelengths) penetrate deeper into the crust.<sup>6</sup>

The weight of the train influences which layers are "excited" most intensely. Heavier trains, particularly those with long carriage lengths or heavy locomotives, tend to generate more energy at lower frequencies.<sup>16</sup> These low-frequency vibrations penetrate deeper into the soil profile. If the ground consists of a stiff upper crust over a soft layer (a common occurrence in marshy or alluvial regions), the weight of the train can bypass the protective stiff layer and trigger resonance in the soft underlying strata.<sup>6</sup>

At the Ledsgård site, the soft organic "gyttja" layer was only 3 meters thick, yet it was the primary driver of the massive vibrations experienced by the X2000 trains.<sup>16</sup> The weight of the train caused the soil in this thin layer to behave non-linearly, while the more substantial axle loads of the locomotive, compared to the passenger cars, resulted in significantly higher particle displacements in the 5–15 Hz frequency range.<sup>16</sup>

## Frequency Spectra and Train Configuration

The total vibration spectrum generated by a passing train is a superposition of the waves generated by each individual axle. This makes the "weight distribution" as important as the "total weight." The spacing between wheels in a bogie and the distance between bogies on a carriage create a characteristic "frequency signature" for a train.<sup>11</sup>

Train Component	Typical Distance (m)	Frequency Component	Weight Influence
Axle Spacing (Bogie)	2.5 - 3.0	20 - 40 Hz	High-frequency stress in ballast <sup>25</sup>
Bogie Spacing	15.0 - 20.0	5 - 10 Hz	Near-field ground displacement <sup>23</sup>
Carriage Length	25.0 - 27.0	1 - 5 Hz	Far-field Rayleigh wave energy <sup>6</sup>

As train weight increases, the amplitude of these specific frequency peaks increases. Moreover, for very heavy axle loads, the peripheral bulges and the potential for temporary loss of contact between the track and soil can lead to more pronounced high-frequency components in the spectra.<sup>24</sup> The interaction between the train speed (\$v\$) and the sleeper

periodicity ( $d$ ) also creates a "passage frequency" ( $f_p = v/d$ ), where the vibration energy is concentrated.<sup>11</sup> The weight of the train determines the absolute energy at these peaks, which can cause severe resonance if they align with the natural frequencies of nearby buildings or bridge structures.

## Mach Cone Focusing: Acceleration and Curvature Effects

An advanced aspect of Rayleigh wave theory in high-speed rail is the potential for focusing. Similar to how a supersonic aircraft can create a "superboom" during acceleration or maneuvers, a trans-Rayleigh train can experience focusing of Rayleigh wave energy under specific operational conditions.<sup>26</sup>

If a train is traveling at trans-Rayleigh speeds and undergoes acceleration ( $a$ ), the generated Rayleigh waves can become focused along a caustic line, leading to a localized and massive increase in vibration amplitude.<sup>9</sup> The weight of the train is the primary driver of the energy available for this focusing effect. A heavier train accelerating on a straight track will create a more intense caustic than a lighter train, as the initial source strength (the axle load) is higher.

Similarly, track curvature can cause focusing. As the train rounds a bend at high speed, the wave fronts generated at different points along the curve can converge at a single observation point on the concave side of the track.<sup>8</sup> While train speeds are typically reduced on curves to maintain stability, the potential for focusing remains a critical design consideration for heavy high-speed lines where the margin between operational speed and  $c_R$  is slim.

## Impact on Underground Infrastructure: Tunnels and Deep Foundations

The influence of train weight on Rayleigh waves is not limited to surface-level interactions. In urban environments, high-speed rail often passes over or under tunnels and through loess or clay regions where the soil response is highly sensitive to dynamic loading. Research into shield tunnel excavation shows that the stability of the tunnel face and the internal earth pressure are significantly affected by the coupling of shield advancement and the surface vibrations from high-speed trains.<sup>29</sup>

When a heavy train passes over a tunnel under construction, the vibration-induced loads can significantly increase the horizontal displacement of the tunnel face. The "critical load" for the tunnel face is higher under the coupling of shield and train loads compared to shield loads alone, indicating that the weight of the train on the surface contributes to the overall stress field in the subsoil.<sup>29</sup> Furthermore, these vibrations can exacerbate mining subsidence in

vulnerable areas, creating a feedback loop where the weight of the train degrades the infrastructure that supports it.<sup>20</sup>

## Environmental and Human Perceptibility

From an environmental standpoint, the dependency of Rayleigh waves on train weight is a primary factor in residential annoyance and structural risk. Ground-borne vibration is typically categorized by peak particle velocity (PPV). High-speed trains, due to their significant mass and velocity, consistently generate the highest PPVs compared to commuter trains or light rail transit (LRT) systems.<sup>23</sup>

Train Type	Speed Range (km/h)	Typical PPV at 7m	Perceptibility Level
High-Speed Train	80 - 160	> 0.8 mm/s	Noticeable to Very Strong <sup>23</sup>
Commuter Train	60 - 100	0.3 - 0.8 mm/s	Perceptible <sup>23</sup>
LRT / Tram	30 - 60	< 0.3 mm/s	Barely Perceptible <sup>23</sup>

Human sensitivity to vibrations is highest in the 1–80 Hz range, which perfectly overlaps with the frequency spectra of heavy high-speed trains.<sup>23</sup> For residents living near a rail route, the "heaviness" of the train translates directly into the duration and amplitude of the "low-pitched rumble" and the potential for sleep disturbance.<sup>23</sup> Because the Rayleigh wave energy is confined to the surface, it does not attenuate as quickly with distance as P or S waves, meaning the weight of the train determines the "footprint" of the environmental impact zone.<sup>23</sup>

## Engineering Mitigation and the "West Coast Line" Solution

The recognition that Rayleigh waves depend on train weight has led to innovative mitigation strategies. When the Swedish Railway Authority (Banverket) discovered the severity of the vibrations at Ledsgård, they were forced to reduce train speeds from the design speed of 200 km/h to 130 km/h until a solution could be found.<sup>16</sup>

The eventual solution—soil stabilization using lime-cement columns—directly addressed the weight-stiffness interaction. By creating a reinforced soil mass under the track, engineers

achieved three things:

1. They increased the small-strain shear modulus ( $G_{\max}$ ), effectively raising the "theoretical" Rayleigh wave velocity.
2. They increased the "bearing capacity," ensuring that the heavy axle loads induced lower strains in the soil, thereby preventing non-linear stiffness degradation.
3. They created a "barrier effect" or in-filled trench that blocked the propagation of surface waves to the surrounding environment.<sup>16</sup>

Measurements taken after stabilization showed that the maximum particle displacement did not change significantly with train speed, because the improved ground stiffness had pushed the critical velocity far beyond the operational range of the X2000 train.<sup>16</sup> This case study serves as the definitive proof that managing Rayleigh waves requires managing the interaction between train weight and ground mechanics.

## Future Outlook: Ultra-High-Speed Rail and the 400 km/h Barrier

As nations like the UK plan for ultra-high-speed networks such as High Speed 2 (HS2), designed for speeds of up to 400 km/h, the dependency of Rayleigh waves on train weight becomes even more critical.<sup>8</sup> At 400 km/h (approx. 111 m/s), trains will exceed the Rayleigh wave velocity for a significant portion of potential routes, particularly those crossing alluvial plains or river catchments.<sup>1</sup>

In these scenarios, the design of the rolling stock must be tightly integrated with the design of the track. Minimizing axle loads and optimizing bogie spacing can help mitigate the intensity of the ground vibration boom. However, the fundamental reality remains that a heavy vehicle traveling at these speeds will displace massive amounts of air and soil. Just as the aircraft industry had to overcome the "sound barrier" through aerodynamic shaping and engine power, the rail industry must overcome the "Rayleigh barrier" through geomechanical reinforcement and precision weight management.<sup>8</sup>

The ongoing development of 3D finite element models, such as DART3D and ABAQUS-based time-domain simulations, is essential for this task.<sup>14</sup> These models allow engineers to simulate the complex, non-linear interaction between a moving train and a multi-layered, strain-sensitive ground. By accounting for the weight of the train and its effect on soil stiffness, these tools can predict the onset of Mach cone formation and the effectiveness of mitigation strategies like stone columns or stiffened embankments.<sup>19</sup>

## Final Synthesis on Weight Dependency

The cumulative evidence from theoretical modeling, laboratory testing, and field measurements confirms that Rayleigh waves generated by high-speed trains are

fundamentally dependent on the weight of the train. This dependency is manifested in three primary ways. First, the axle load provides the input force for the quasi-static pressure mechanism, directly scaling the amplitude of the generated waves. Second, the mass of the train induces strains in the soil that degrade its stiffness, effectively lowering the Rayleigh wave velocity and the critical speed of the site. Third, the total mass and geometry of the train determine the energy distribution across the frequency spectrum, influencing the depth of wave penetration and the intensity of the ground vibration boom.

For the professional peer, the implication is clear: the critical velocity of a high-speed line is not a constant value inherent to the geology, but a dynamic threshold that shifts based on the loading characteristics of the rolling stock. Failure to account for the weight-dependent non-linearity of the subgrade can lead to catastrophic infrastructure failure, train derailment, and severe environmental disturbance. As rail technology advances toward higher speeds and heavier loads, the mastery of this geomechanical interaction will remain the defining challenge of the field.

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