



A Distributed and Wireless Sensing Display



Project Wireless Sensor Networks
Winter term 2015 / 2016



Project task

- Communication between sensor nodes via Contiki OS
- Use sensors on Platypus to interact with the user
- Communicate to user with a LCD display
- Intel Edison as platform for communication

Inertial Measurement Unit

Communication with
Platypus environment via
IPv6 TCP-sockets

Self defined protocol for
sensor nodes

- Temperature
- Humidity
- Acceleration
- Angular velocity
- Altitude (height)
- Magnetic / Compass

LCD Display

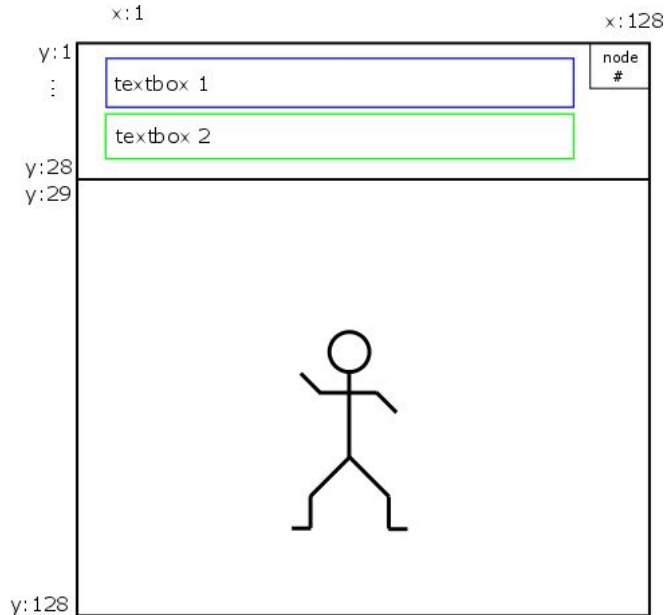
Communication with
Platypus environment via
IPv6 TCP-sockets

Self defined protocol for
display data

Supported resolutions:

- 128 x 128 Pixels
- 96 x 96 Pixels

LCD Display

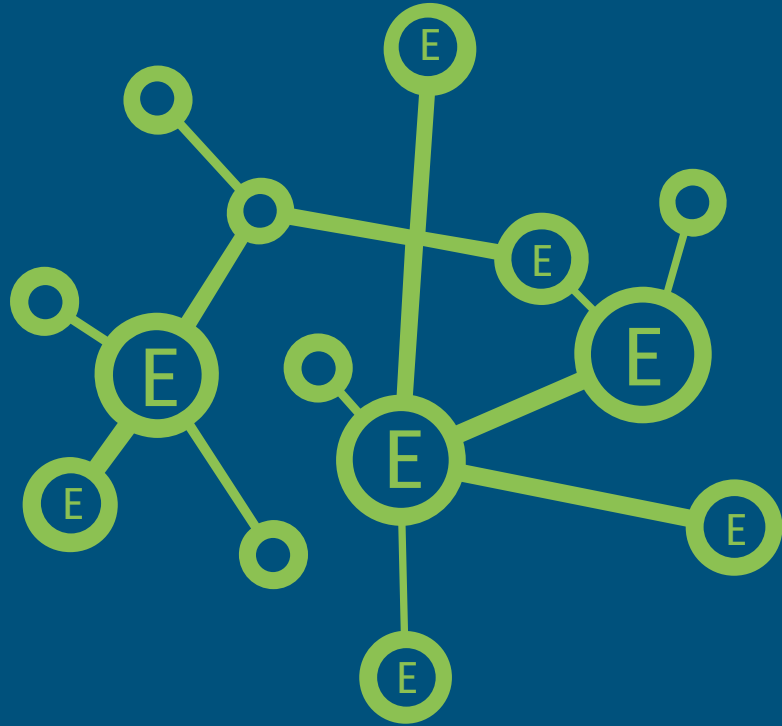


- Node number
- Stickman
- Textboxes for visual communication with user

Network

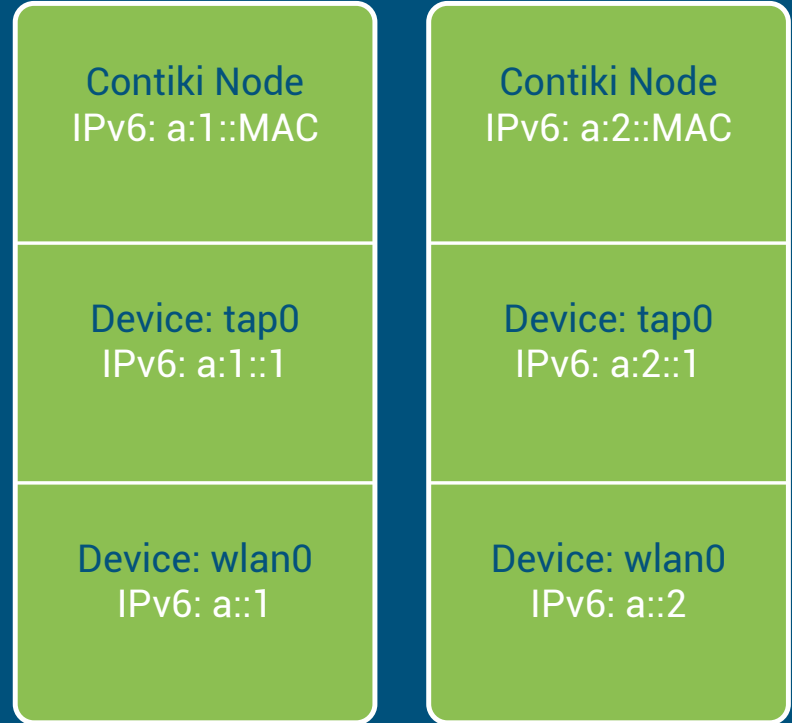
Wireless sensor nodes
via WLAN of the
Intel Edison

IPv6 communication
protocol



Communication with Contiki

- IPv6 communication only
- Network prefix 64 bit
- Contiki IPv6 is MAC Address of the node
- tap0 and contiki node in the same subnet
- All wlan0 devices of Edisons in one subnet



Communication with Contiki: BRIDGING

Advantages

- Equivalent configuration on all nodes
- Ad-hoc network possible

Problem

- Bridging only possible in access point mode

Communication with Contiki: BRIDGING

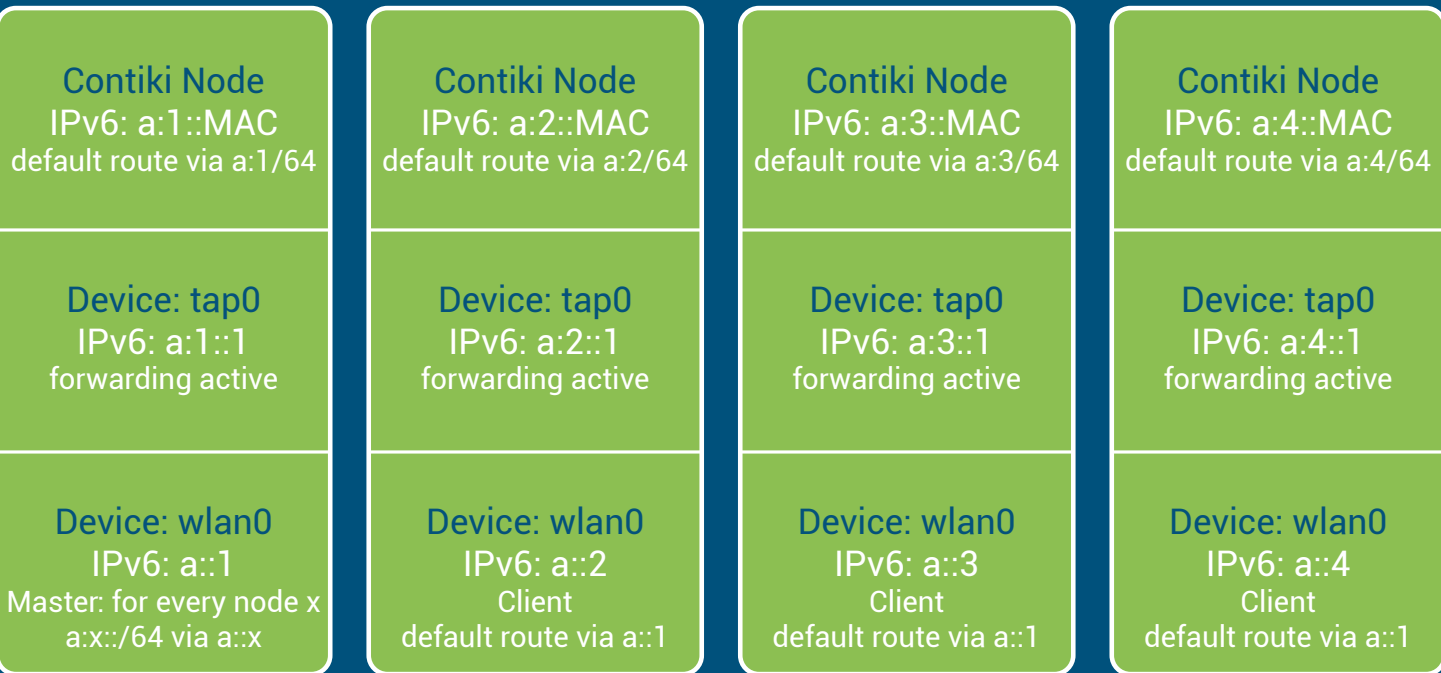
Next step: WLAN ad-hoc mode

- Enabled Wireless Distribution System (WDS) mode
- Used iw-tool to enable 4-address-mode

Problem

- Not supported by WIFI-driver

Communication with Contiki: ROUTING



Communication with Contiki: ROUTING

- Assignment of IPv6 addresses manually
- Routes manually created after Contiki node is started
- No wireless ad-hoc network possible due to manual configuration of addresses and routes
- Contiki nodes have different parts of code, because IPv6 addresses are hardcoded.
- Contiki core: “Segmentation fault” caused by nbr-table.c

Contiki Configuration

- Add IP-address in
contiki/platform/minimal-net/contiki-main.c (line 292)
- Add default route in
contiki/platform/minimal-net/contiki-main.c (line 313)
`uip_ds6_defrt_add(&ipaddr, 0);`
- Set “UIP_CONF_ROUTER” flag to 0 in
contiki/platform/minimal-net/contiki-conf.h (two-times)

Contiki Configuration

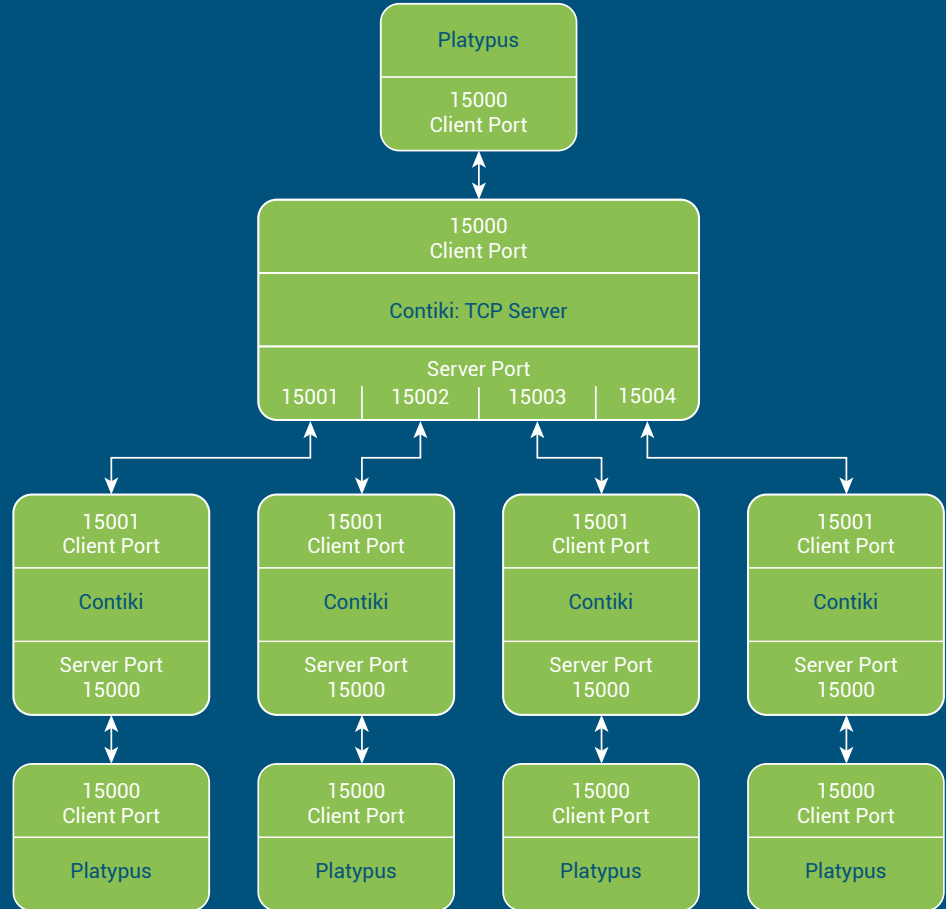
- Change node MAC-address in `contiki/core/net/ipv6/ui6.c` (line 118)
- Adjust makefile: `CONTIKI_WITH_RPL=0` it is important to disable RPL (else: the Contiki node is not pingable)
- Installed patches (from Phil)
- Start Contiki node with initialization script and assign IPv6 addresses

Communication with Contiki: possible now

- TCP Communication between Contiki nodes
- One node is contiki server with different sockets
- Up to four clients can connect to Contiki server node
- Implemented: simple time based messages from client to server and vice versa

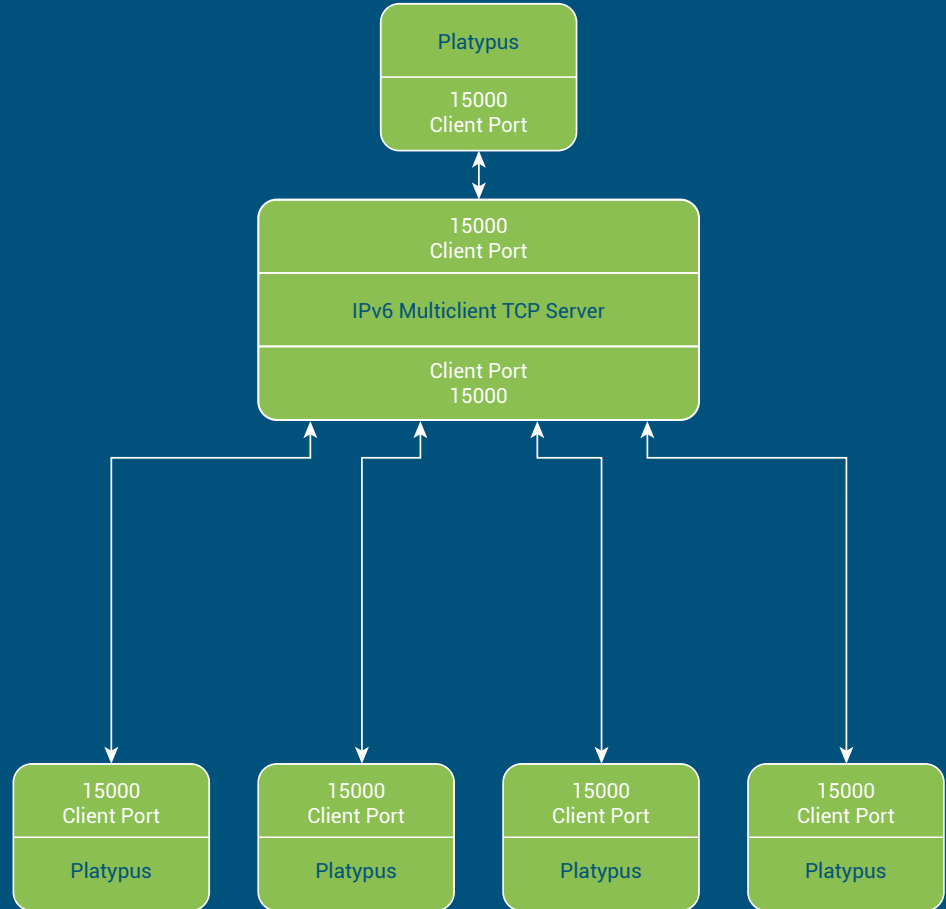
Communication with TCP-Sockets

- Platypus serves sensor data to Contiki and receives display commands
- Computing and communication via Contiki



Communication with TCP-Sockets

- Platypus for computing and communication
- IPv6 TCP Server on notebook
- Possibility to implement server in Contiki node



Communication with TCP-Sockets

- Self defined communication protocol
- Small game “hide & seek” to demonstrate functionality
- Simulate input data on the server if hardware is defect
- Stickman can jump from node to node - triggered by tapping

Communication with TCP-Sockets

Message Type

br : Broadcast

u# : Unicast to client #

Sender: client

Command

0: Clear Screen

1 : Response

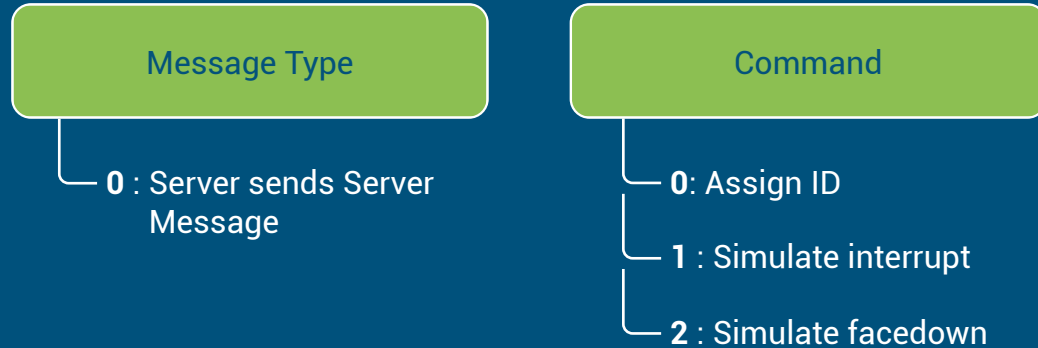
2 : Animation

3 : Display Text

4 : Start Game

5 : Stop Game

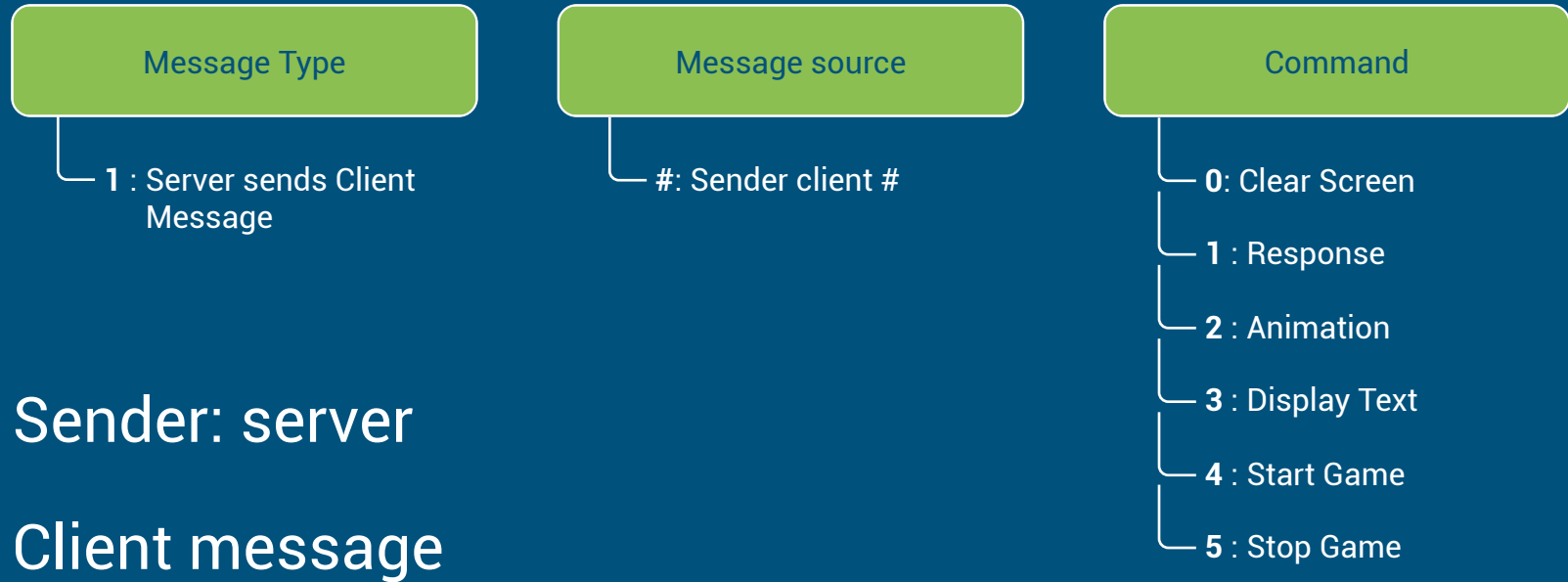
Communication with TCP-Sockets



Sender: server

Server message

Communication with TCP-Sockets





Questions?



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