

PROBLEM SOLVING 8

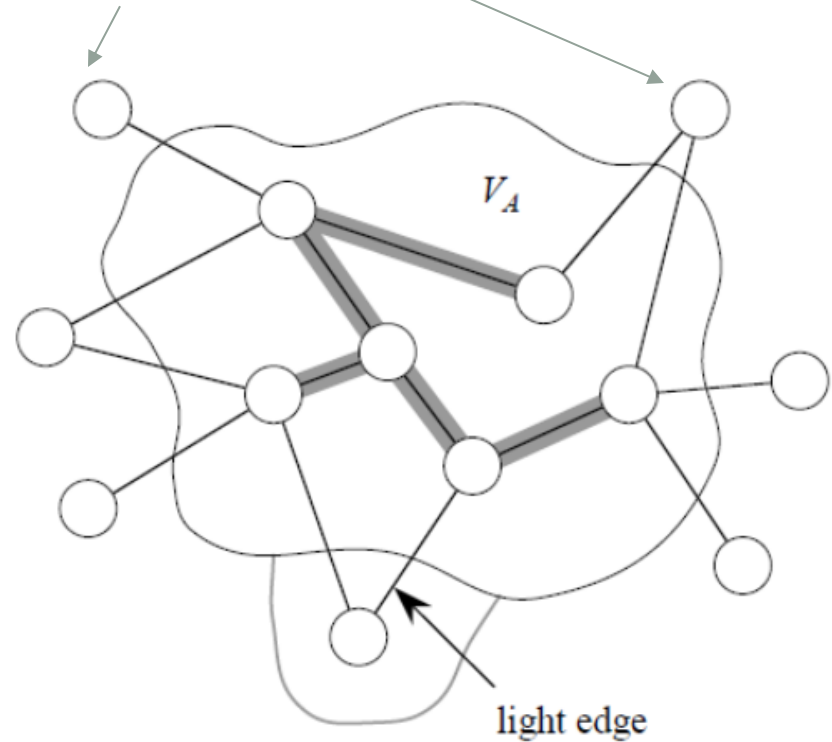
Prim and Dijkstra, Shortest Paths

CS340

Prim's Algorithm

- Builds one tree, so A is always a tree.
- Starts from an arbitrary “root” r .
- At each step, find a light edge crossing cut $(V_A, V - V_A)$, where $V_A =$ vertices that A is incident on. Add this edge to A .

Nodes in priority queue



Prim's Algorithm

- How to find the lightest edge quickly?

Use a priority queue:

- Each object is a vertex in $V - V_A$.
- Key is minimum weight of any edge (u,v) where $u \in V_A$.
- Then the vertex returned by EXTRACT-MIN is v such that there exists $u \in V_A$ and (u,v) is light edge crossing $(V_A, V-V_A)$.
- Key of v is ∞ if v is not adjacent to any vertices in V_A .

Prim's Algorithm

PRIM(G, w, r)

$Q = \emptyset$

for each $u \in G.V$

$u.key = \infty$

$u.\pi = \text{NIL}$

INSERT(Q, u)

DECREASE-KEY($Q, r, 0$) // $r.key = 0$

while $Q \neq \emptyset$

$u = \text{EXTRACT-MIN}(Q)$

for each $v \in G.Adj[u]$

if $v \in Q$ and $w(u, v) < v.key$

$v.\pi = u$

DECREASE-KEY($Q, v, w(u, v)$)

Notice that u is not changed.
 U is added to the MST.
 V is changed.

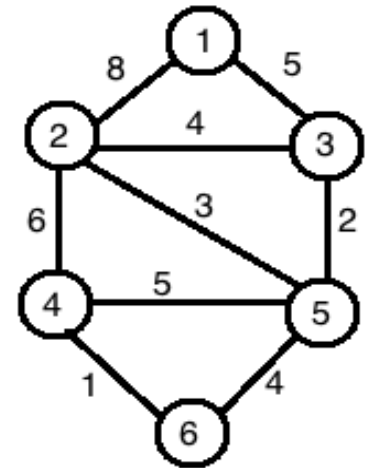
We don't know where v is in the priority queue, so use the location table.

Prim Efficiency

- Suppose Q is a binary heap.
- Initialize Q and first for loop: $O(V \lg V)$
- Decrease key of r : $O(\lg V)$
- while loop:
 - $|V|$ EXTRACT-MIN calls = $O(V \lg V) \geq$
 - $|E|$ DECREASE-KEY calls = $O(E \lg V)$
- Total: $O(E \lg V)$

Interview Questions

parent	nil					
step	1	2	3	4	5	6
init						
1						
2						
3						
4						
5						
6						



Interview Questions

- Can Prim and/or Kruskal be used to find a maximum spanning tree?

SHORTEST PATHS

Optimal substructure of a shortest path

- A shortest path between two vertices contains other shortest paths within it.

Initialization

- All the shortest-paths algorithms start with INIT-SINGLE-SOURCE.

INITIALIZE-SINGLE-SOURCE(G, s)

1 **for** each vertex $v \in G.V$

2 $v.d = \infty$ ←

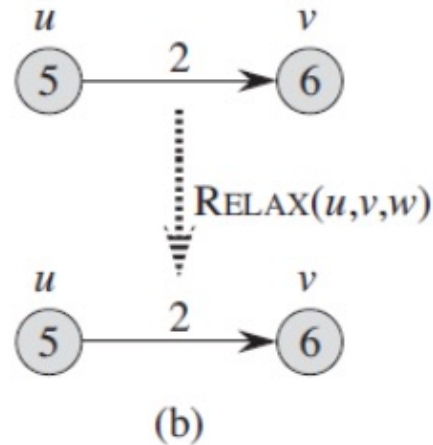
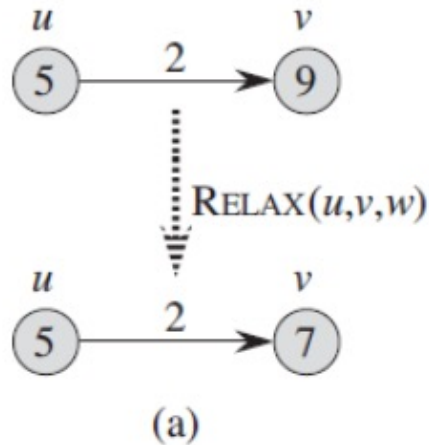
3 $v.\pi = \text{NIL}$

4 $s.d = 0$

This was
called “key”
in Prim’s
algorithm

Relaxing an edge

- Can we improve the shortest-path estimate for v by going through u and taking (u,v) ?




Relaxing an edge

RELAX(u, v, w)

```
1  if  $v.d > u.d + w(u, v)$   
2       $v.d = u.d + w(u, v)$   
3       $v.\pi = u$ 
```

This is a decreaseKey()
Or for us, changeKey()

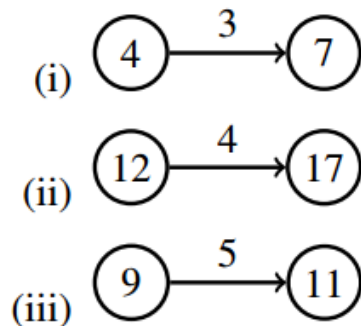


Properties of shortest paths and relaxation

- Path-relaxation property
 - If $p = \langle v_0, v_1, \dots, v_k \rangle$ is a shortest path from $s = v_0$ to v_k , and we relax the edges of p in the order $(v_0, v_1), (v_1, v_2), \dots, (v_{k-1}, v_k)$, then $v_k.d = \delta(s, v_k)$. This property holds **regardless** of any other relaxation steps that occur, even if they are intermixed with relaxations of the edges of p .

Interview Questions

What is the result of relaxing the following edges?



Dijkstra's Algorithm

- No **negative-weight** edges.
- Essentially a weighted version of breadth-first search.
- Instead of a FIFO queue, uses a priority queue.
- Keys are shortest-path weights ($v.d$).
- Have two sets of vertices:
 - S = vertices whose final shortest-path weights are determined
 - Q = priority queue = $V - S$.

Dijkstra's Algorithm

DIJKSTRA(G, w, s)

1 INITIALIZE-SINGLE-SOURCE(G, s)

2 $S = \emptyset$

3 $Q = G.V$

4 **while** $Q \neq \emptyset$

5 $u = \text{EXTRACT-MIN}(Q)$

6 $S = S \cup \{u\}$

7 **for** each vertex $v \in G.Adj[u]$

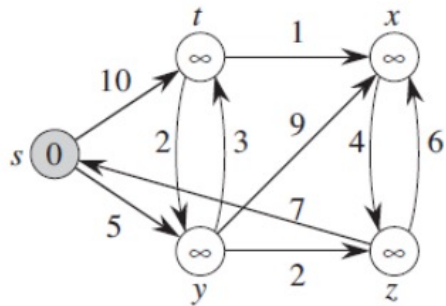
8 RELAX(u, v, w)

Note that u, v are
the IDs of the
nodes!

Dijkstra's Algorithm

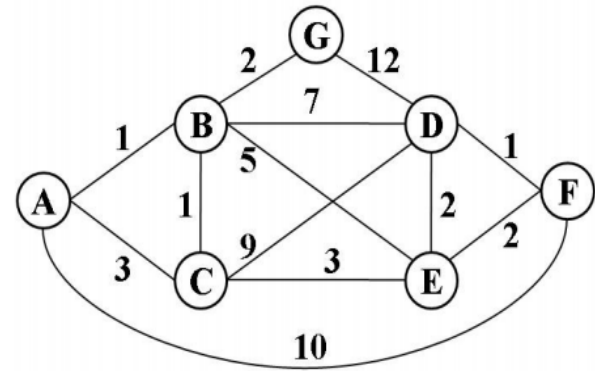
- Looks a lot like Prim's algorithm, but computing v.d, and using shortest-path weights as keys.
- Dijkstra's algorithm can be viewed as greedy, since it always chooses the “lightest” (“closest”) vertex in $V-S$ to add to S .

Dijkstra's Algorithm



parent	NIL				
step	s	t	x	y	z
init					
1					
2					
3					
4					
5					

Dijkstra's Algorithm



Parent							
vertex	A	B	C	D	E	F	G
Init							
Step 1							
Step 2							
Step 3							
Step 4							
Step 5							
Step 6							
Step 7							

Time Complexity of Dijkstra

- Time complexity depends on how it is implemented
- Matrix:
 - Each EXTRACT-MIN takes $O(V)$ time to look through the array
 - There are V EXTRACT-MIN instructions for $O(V^2)$
- Priority Queue
 - The algorithm is only 1 line different from Prim
 - $O(E \lg V)$

Interview Questions

- Suppose we change Dijkstra's algorithm such that the last vertex is not removed from the priority queue, and the while loop to executes $|V|-1$ times instead of $|V|$ times. Is this proposed algorithm correct?

Interview Question

- To implement Dijkstra's shortest paths algorithm on unweighted graphs so that it runs in linear time, what data structure can be used?
- 1. Stack
- 2. Queue
- 3. Priority Queue
- 4. All of the above
- 5. None of the above

Interview Questions

- In a weighted graph, assume that the shortest path from a source s to a destination t is correctly calculated using Dijkstra's algorithm. Is the following statement true? If we increase weight of every edge by 1, the shortest path always remains the same.

Interview Questions

- Given a graph, suppose we have calculated shortest path from a source to all other vertices. If we modify the graph such that the weights of all edges are doubled, does the shortest path remain the same?
- Given a weighted graph where weights of all edges are unique (no two edges have same weights), is there always a unique shortest path from a source to destination in such a graph?
- Each edge in a connected, unweighted graph G is colored either red or blue. Present an algorithm to compute a path between s and t that traverses the fewest number of red edges. Analyze its running time.