Approach based on pairwise conditional probabilities, M signals and N+1 nodes

Drazen Prelec, March 23, 2019

1 Notation: Images, pixels, responses

The setup is the same as the note of 3/16/19, with an 'image' variable S, taking on values $s = (s_1, ..., s_M)$, $s_i \in \{0, 1\}$, and N + 1 binary node response variables, Y^j , j = 0, ..., N. Each pixel i = 1, ..., M, can be On $(s_i = 1)$ or Off $(s_i = 0)$. The set of images is I.

As before, the 'strategy' for node Y^k is a vector of real-valued weights $y^j = (y_1^j, ..., y_M^j)$ which determines response probabilities for each image,

$$\Pr(Y^j = 1|S = s) = \frac{1}{1 + \exp(-y_0^j - \sum_{i=1}^M y_i^j s_i)}$$
(1)

and $Pr(Y^j = 2|S = s) = 1 - Pr(Y^j = 1|S = s)$.

There are four changes in notation relative to previous versions:

- there is an additional 'baseline' parameter y_0^j in equation (1); without it, we would necessarily have $\Pr(Y^j = 1 | S = (0, .0)) = 0.5$, which may not always be desirable.
- averages are replaced by sums in the λ, κ parts of the utility function (2) below; this just rescales the relations between μ, λ, κ .
- the complete expected utility function is expressed as $EV(Y^k)$ instead of $U(Y^k)$, to avoid confusion with common notation for entropy, U = 'uncertainty'
- $Pr(Y^k = i)$ is abbreviated as $p(y_i^k)$, etc..

Remark. If we constrain images so that exactly one pixel i is On, $s_i = 1$, and all others Off, $s_k = 0$, $k \neq i$, then this is equivalent to the earlier model. Using the old $x_1(s_i)$ notation, and letting $x_0 = 0$ in (1):

$$x_1(s_i) = \frac{1}{1 + \exp(-\sum_{i=1}^{M} x_i s_i)} = \frac{1}{1 + \exp(-x_i)}$$

so the 'weight' x_i in the new notation is:

$$x_i = \log \frac{x_1(s_i)}{1 - x_1(s_i)}$$

One would expect that the new 'image' model will perform just well as the old 'stimulus' model on these elementary patterns, unless there are differences in the updating process.

2 Entropies

The utility functions and mutual information are linear combinations of the following entropies,

$$\begin{split} H(S) &= -\sum_{s \in I} p(s) \log p(s) \\ H(S,Y^k) &= -\sum_{s \in I} \sum_{y^k} p(s,y^k) \log p(s,y^k) \\ H(Y^k) &= -\sum_{y^k} p(y^k) \log p(y^k) \\ H(Y^j,Y^k) &= -\sum_{y^j} \sum_{y^k} p(y^j,y^k) \log p(y^j,y^k) \\ H(Y^0,..,Y^N) &= -\sum_{y^0} ... \sum_{y^N} p(y^0,..,y^N) \log p(y^0,..,y^N) \\ \end{split} \qquad \qquad y^k = 1,2; k = 0,..., N \\ y^k &= 1,2; k = 0,..., N \\ y^k &= 1,2; y^j = 1,2; k, j = 0,..., N; j \neq k \\ H(Y^0,..,Y^N) &= -\sum_{y^0} ... \sum_{y^N} p(y^0,...,y^N) \log p(y^0,...,y^N) \\ y^j &= 1,2; j = 0,..., N \end{split}$$

Remark. It is probably most efficient to compute, at each update step for node Y^k , the entropies $H(Y^k)$, $H(S,Y^k)$, $H(Y^j,Y^k)$. The final term $H(Y^0,..,Y^N)$ is needed for mutual information $I(S:(Y^0,..,Y^N))$, but not for the utilities. It could therefore be computed off-line, after the learning process ends. H(S) is of course a constant.

3 Utilities

As before, Y^k adjusts strategies at each update step to maximize an expected score (utility) function, treating the strategies of nodes Y^j , $j \neq k$, as parameters:

$$\begin{split} EV(Y^k) = & \mu \sum_{s \in I} \sum_{y^k} p(s, y^k) \log p(y^k | s) \\ + & \lambda \sum_{s \in I} \sum_{j \neq k} \sum_{y^k} \sum_{y^j} p(y^j, y^k, s) \log \Pr(y^j | y^k) \\ - & \kappa \sum_{s \in I} \sum_{j \neq k} \sum_{y^k} \sum_{y^j} p(y^j, y^k, s) \log \Pr(y^k | y^j) \end{split}$$

 $EV(Y^k)$ is also a linear function of the entropies (S disappears from the λ and κ weighted terms):

$$EV(Y^k) = \mu(H(S) - H(S, Y^k))$$

$$+\lambda \sum_{j \neq k} (H(Y^k) - H(Y^j, Y^k))$$

$$-\kappa \sum_{j \neq k} (H(Y^j) - H(Y^j, Y^k))$$
(2)

An alternative (equivalent) formulation highlights the mutual information terms:

$$EV(Y^k) = \mu I(S:Y^k)$$

$$-(\kappa - \lambda) \sum_{j \neq k} I(Y^j:Y^k)$$

$$+(N\kappa - \mu)H(Y^k)$$

$$-\lambda \sum_{j \neq k} H(Y^j)$$
(3)

Remark. If stimulus s is presented, the expected utility for $Y^k = i$ is:

$$\begin{split} EV(Y^k = i|s) = & \mu \log p(y_i^k|s) \\ + & \lambda \sum_{j \neq k} \sum_{y^j} p(y^j|s) \log p(y^j|y_i^k) \\ - & \kappa \sum_{j \neq k} \sum_{x^j} p(y^j|s) \log p(y_i^k|y^j) \end{split}$$

The difference in expected utilities, which is a plausible candidate for reinforcement signal, is:

$$\begin{split} EV(Y^k = 1|s) - EV(Y^k = 2|s) = & \mu \log \frac{p(y_1^k|s)}{p(y_2^k|s)} \\ + & \lambda \sum_{j \neq k} \sum_{y^j} p(y^j|s) \log \frac{p(y^j|y_1^k)}{p(y^j|y_2^k)} \\ - & \kappa \sum_{j \neq k} \sum_{y^j} p(y^j|s) \log \frac{p(y_1^k|y^j)}{p(y_2^k|y^j)} \end{split}$$

From (1) we have $\Pr(Y^j = 1 | S = s) / \Pr(Y^j = 2 | S = s) = (\exp(y_0^j - \sum_{i=1}^M y_i^j s_i))^{-1}$, hence the first term above is:

$$\log \frac{p(y_1^k|s)}{p(y_2^k|s)} = y_0^j + \sum_{i=1}^M y_i^j s_i$$

The other two terms have more complicated expressions however.

4 Mutual information

The mutual information between S and the ensemble is a simple function of stimulus entropy, pairwise node entropies and the additional term $H(Y^0,..,Y^N)$:

$$I(S:(Y^{0},..,Y^{N})) = (N+1)H(S) - \sum_{j=0}^{N} H(S,Y^{j}) + H(Y^{0},..,Y^{N})$$
(3)

The above equation exploits conditional independence

$$p(s, y^0, ..., y^N) = \sum_{s \in S} p(s) \prod_{i=0}^N p(y^i | s)$$

or $H(S, Y^0, ..., Y^N) = \sum_{j=0}^N H(S, Y^j) - NH(S)$. Although $H(Y^0, ..., Y^N)$ needs to be evaluated for 2^{N+1} distinct combinations, this is also somewhat simplified by conditional independence.

5 Objective for each node

Ideally, one would like 'local' maximization of $EV(Y^k)$ by each node to also improve the 'global' encoding quality, as measured by $I(S:(Y^0,..,Y^N))$. This condition does not hold exactly, but an interesting relationship between mutual information $I(S:(Y^0,..,Y^N))$ and the utilities $EV(Y^k)$ can nevertheless be derived.

We start with an alternative expression for:

$$I(S:(Y^{0},..,Y^{N})) = \sum_{j=0}^{N} I(S:Y^{j}) - \sum_{j=0}^{N} H(Y^{j}) + H(Y^{0},..,Y^{N})$$

and solve for $I(S:Y^k)$:

$$I(S:Y^k) = I(S:(Y^0,..,Y^N)) - \sum_{j \neq k} I(S:Y^j) + \sum_{j=0}^N H(Y^j) - H(Y^0,..,Y^N)$$

After substituting $I(S:Y^k)$ into (3) and some manipulations, we obtain:

$$\begin{split} EV(Y^k) = & \mu I(S:(Y^0,..,Y^N)) \\ & - \mu H(Y^0,..,Y^N) \\ & + (\mu - \lambda) \sum_{j \neq k} H(Y^j | Y^k) \\ & + \kappa \sum_{j \neq k} H(Y^k | Y^j) \end{split}$$

For example, if $\lambda = \mu$, the conditional entropies $H(Y^j|Y^k)$ disappear, and the objective for Y^k will be to maximize information about S plus internal response constraint (that is, negative ensemble entropy, $-H(Y^0,..,Y^N)$) while alsostriving for pairwise independence (that is, increasing $H(Y^k|Y^j)$). Holding $I(S:(Y^0,..,Y^N))$ constant, the utility function puts a premium on higher-order, i.e., above pairwise statistical relationships in the ensemble response vector. Individual optimization by each node should produce complex response patterns.