

Project's website: <http://StudentEng2016.github.io/>

FarmBot

Figure 1:

Image source: (Day, 2016)

From: Alisha Singh Chauhan, Adanegbe Amadasun

Discipline: Computer Engineering Technology

Date Submitted: March 03,2017

Declaration of Joint Authorship

We, Alisha Singh Chauhan and Adanegbe Amadasun, students of the Applied Technology department hereby declare that the following technical report submitted for CENG 355 Computer Systems Project is expressed in our own words.

The research which has been used from various sources, such as words, numerical data, figures, tables etc. has been either paraphrased or cited separately. The original sources of cited work may be located using APA style in References page at the back.

Approved Proposal

Prepared by Adanegbe Amadasun, Alisha Singh Chauhan Computer Engineering Technology Students

Abstract

The Farmbot is basically CNC farming technique which has proved to be the great way for the production of small scale food. It has turned out to be a reliable and approachable source to accomplish the idea of integrating an artificial approach to take care of the cultivation. This project deals with the following hardware components, such as PCF8591 sensors, nozzels which an inject the substances controlled by axes with the software governed by Arduino/RAMPs stack and internet of Raspberry Pi. This project is designed to be completed under the time span of 3-4 months to put together everything. It gives user the opportunity to customize their own farm using the web app. The software is also able to manipulate data maps, real-time logging and access an open plant data in the Open Farm database. All software is available under the [MIT license](#) and is available on [GitHub](#). The hardware is designed around reproduce-ability and availability of components, it can be created using common tools and processes meaning it is not reliant on a single supplier.

Executive Summary

As students in the Computer Engineering Technology program, we will be integrating the knowledge and skills we have learned from our program into this Internet of Things themed capstone project. This proposal requests the approval to build the hardware portion that will connect to a database as well as to a mobile device application. The Internet connected hardware will include a custom PCB with sensors and actuators for an automated farming device. The mobile device functionality will include photo sensors, temperature sensors and moisture sensors, which will be further detailed in the mobile application proposal. We will be collaborating with the following company/department. In the winter

semester, we planned to form a group together as we both are building similar hardware this term and working on its mobile application. The hardware was completed in CENG 317 Hardware Production Techniques independently and the application was completed in CENG 319 Software Project. These will be integrated in CENG 355 Computer Systems Project.

Background

FarmBot is going to address some the problems the agricultural industry faces, such as loss of money, inefficiency of some equipment and exploitation of resources. FarmBot is going to be more economical and ecofriendly unlike other agricultural equipment being used. It incorporates precision farming, which happens to be a concept based on observing, measuring and responding to inter- and intra-field variability in crops. The device is going to be constructed in the FarmBot company. It is going to be made of an Arduino Mega 2560, Raspberry Pi 3, disassembled hardware packages and other software sources. The FarmBot Genesis runs on custom built tracks and other supporting infrastructure which needs to be self assembled. The robot itself relies on a GUI platform which users can access through the FarmBot's web app. The physical robotic system is set in alignment with the crops that are plotted out in the virtual version on the web app. This is how FarmBot can be efficient and reliably distribute water, fertilizer and other elements to keep the plants healthy and striving with minimum wastage. The device is going to be cheaper than conventional tools and cost-effective.

We have searched for prior art via Humber's IEEE subscription selecting "My Subscribed Content" (Billingsley, Oetomo, & Reid, 2009) and have found and read (Bergerman et al., 2015) which provides insight into similar efforts.

In the Computer Engineering Technology program, we have learned about the following topics from the respective relevant courses:

- Java Docs from CENG 212 Programming Techniques In Java,
- Construction of circuits from CENG 215 Digital And Interfacing Systems,
- Rapid application development and Gantt charts from CENG 216 Intro to Software Engineering,
- Micro computing from CENG 252 Embedded Systems,
- SQL from CENG 254 Database With Java,
- Web access of databases from CENG 256 Internet Scripting; and,
- Wireless protocols such as 802.11 from TECH152 Telecom Networks.

This knowledge and skill set will enable me to build the subsystems and integrate them together as my capstone project.

Methodology

This proposal is assigned in the first week of class and is due at the beginning of class in the second week of the fall semester. My coursework will focus on the first two of the 3 phases of this project:

Phase 1 Hardware build.

Phase 2 System integration.

Phase 3 Demonstration to future employers.

Phase 1 Hardware build

The hardware build will be completed in the fall term. It will fit within the CENG Project maximum dimensions of 12 13/16" x 6" x 2 7/8" (32.5cm x 15.25cm x 7.25cm) which represents the space below the tray in the parts kit. The highest AC voltage that will be used is 16Vrms from a wall adaptor from which +/- 15V or as high as 45 VDC can be obtained. Maximum power consumption will be 20 Watts.

Phase 2 System integration

The system integration will be completed in the fall term.

Phase 3 Demonstration to future employers

This project will showcase the knowledge and skills that we have learned to potential employers.

The tables below provide rough effort and non-labour estimates respectively for each phase. A Gantt chart will be added by week 3 to provide more project schedule details and a more complete budget will be added by week 4. It is important to start tasks as soon as possible to be able to meet deadlines.

Labour Estimates

Hrs

Notes

Phase 1

Writing proposal.

9

Tech identification quiz.

Creating project schedule. Initial project team meeting.

9

Proposal due.

Creating budget. Status Meeting.

9

Project Schedule due.

Acquiring components and writing progress report.

9

Budget due.

Mechanical assembly and writing progress report. Status Meeting.

9

Progress Report due (components acquired milestone).

PCB fabrication.

9

Progress Report due (Mechanical Assembly milestone).

Interface wiring, Placard design, Status Meeting.

9

PCB Due (power up milestone).

Preparing for demonstration.

9

Placard due.

Writing progress report and demonstrating project.

9

Progress Report due (Demonstrations at Open House Saturday, November 7, 2015 from 10 a.m. - 2 p.m.).

Editing build video.

9

Peer grading of demonstrations due.

Incorporation of feedback from demonstration and writing progress report. Status Meeting.

9

30 second build video due.

Practice presentations

9

Progress Report due.

1st round of Presentations, Collaborators present.

9

Presentation PowerPoint file due.

2nd round of Presentations

9

Build instructions up due.

Project videos, Status Meeting.

9

30 second script due.

Phase 1 Total

135

Phase 2

Meet with collaborators

9

Status Meeting

Initial integration.

9

Progress Report

Meet with collaborators

9

Status Meeting

Testing.

9

Progress Report

Meet with collaborators

9

Status Meeting

Meet with collaborators

9

Status Meeting

Incorporation of feedback.

9

Progress Report

Meet with collaborators

9

Status Meeting

Testing.

9

Progress Report

Meet with collaborators

9

Status Meeting

Prepare for demonstration.

9

Progress Report

Complete presentation.

9

Demonstration at Open House Saturday, April 9, 2016 10 a.m. to 2 p.m.

Complete final report. 1st round of Presentations.

9

Presentation PowerPoint file due.

Write video script. 2nd round of Presentations, delivery of project.

9

Final written report including final budget and record of expenditures, covering both this semester and the previous semester.

Project videos.

9

Video script due

Phase 2 Total

135

Phase 3

Interviews

TBD

Phase 3 Total

TBD

Material Estimates

Cost

Notes

Phase 1

A microcomputer composed of a quad-core Windows 10 IoT core compatible Broadcom BCM2836 SoC with a 900MHz Application ARM Cortex-A7 32 bit RISC v7-A processor core stacked under 1GB of 450MHz SDRAM, 10/100 Mbit/s Ethernet, GPIO, UART, I²C bus, SPI bus, 8 GB of Secure Digital storage, a power supply, and a USB Wi-Fi adaptor.

>\$80.00

An example of a retailer: [3].

Peripherals with cables

Sensors

Actuators

Hardware, etc.

Phase 1 Total

>\$200.00

Phase 2

Materials to improve functionality, fit, and finish of project.

Phase 2 Total

TBD

Phase 3

<\$100.00

An example: [4].

Shipping

TBD

Tax

TBD

Duty

TBD

Phase 3 Total

TBD

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1. Introduction

As we are stepping into the 21st century, industrialization is reaching new heights which indeed is giving birth to various problem that could be anywhere. For this reason, technologist have being working to figure out all these technical issues and farmbot is one of that.

FarmBot is an open source automated farming device which operates like a 3D printer. But instead of extruding plastic, its tools are seed injectors, watering nozzles, sensors etc. The techincal report is going to address some the problems the agricultural industry faces, such as loss of money, inefficiency of some equipment and exploitation of resources. The device is going to be more economical and ecofriendly unlike other conventional agricultural equipment being used.

The FarmBot Genesis is able to plant over 30 different crops including [potatoes](#), [peas](#), [squash](#), [arti-chokes](#) and [chard](#) in an area of 2.9 meters × 1.4 meters with a maximum plant height of 0.5 meters. It can cultivate a variety of crops within same area at the same time and is able to operate indoors, outdoors and covered areas. It is estimated that the FarmBot Genesis produces 25% fewer [carbon dioxide](#) emissions.

2. Project Description

2.1 Purpose

Farmers are faced with new challenges and opportunities every day -- from feeding an expanding global population while meeting strict new emissions requirements, to producing more food on fewer acres while minimizing their environmental footprint.

FarmBot is going to address some of the problems the agricultural industry faces like loss of money, how ineffective some of their equipment are and how they waste resources.

The various issues are:

- Supplying the growing global demand for commodities arising from developing economies and world population growth.
- Availability and price of land for expansion
- Development and use of bio-based fuels
- Nearly 25 percent of respondents indicate that equipment dealers/experts will be one of the top advisors to influence their decision making, along with their financial advisor and agronomist advisors

2.2 Hardware Specification

Figure 2:

Image source: (Krassenstein, 2014)

Figure 3:

Image source: (Inc, 2017)

(Describe farmbot parts)

FarmBot will be able to perform the following task:

- Monitor the temperature around the plant,
- Provide light to the plant.

The hardware component for FarmBot that We have are:

- Raspberry pi 3 – It is used to receive data from FarmBot and send it to the Arduino
- Arduino mega 2560 – It is used to control the bi-polar stepper motor
- Sensor Hat (light and temperature) – It is used to receive data about light and temperature from surrounding.
- Bi-polar Stepper motor – It controls the movement of the FarmBot

2.3 Software Specification

Figure 4:

Image source: (Aronson, 2017)

2.3.1 Database work breakdown

Currently, We only have a local database for our FarmBot project. The database stores the plant number, date, and name locally. Once the app is deleted the users will lose access to all their data.

We plan on getting a server to so all users data can be stored in the cloud and can be accessed by them at any time.

(Developed by Adanegbe Amadasun)

2.3.2 Application work breakdown

FarmBot is going to be more economical and ecofriendly unlike other agricultural equipment being used. It incorporates precision farming, which happens to be a concept based on observing, measuring and responding to inter and intra-field variability in crops. The device is going to be constructed by the FarmBot company, it is going to be made of an Arduino Mega 2560, Raspberry Pi 3, Sensor hat (which can read temperature, light, and soil condition), and Bi-polar stepper motor.

We plan on using the an arduino mege2560 to control the bi-polar stepper motor to make it move on its X-axis.

(Developed by Alisha Singh Chauhan)

2.3.3 Web and work breakdown

An app was created to use for the FarmBot, this app would be used to control the FarmBot to plant seed at desire position in the bed. Also, the user can choose the option of giving the FarmBot light for a duration of time, watering the plant etc.

After installing the app on your mobile phone, users will be prompt to create an account by choosing user name and password. This will then give them access to their FarmBot and its data stored in the cloud.

The user can then pick the seed of the crop they want to plant, and the care option they want to apply to the seed (i.e. The light duration, or how frequently they want to water the plant) and submit the options they picked

The user would be given the access to control the FarmBot and apply the option picked from the previous screen.

We plan on connecting FarmBot's app with raspberry pi, so that users can be able to send data to it.

We would both work on this.

(Developed by Adanegbe Amadasun and Alisha Singh Chauhan)

2.5 Build Instruction

2.5.1 Introduction

The Farmbot is designed in a such a way that it will work and execute the commands given by the user through software. The working is clearly explained with the design model given below.

2.5.2 Bill of Materials

- Raspberry Pi 3 Complete Starter Kit - 32 GB Edition - \$74.35 (Corporation, 2017)

Figure 5:

Image source: (Pimoroni, 2017)

- Arduino Mega - \$49.95 (Inc., 2017e)

Figure 6:

Image source: (Robotics & Electronics, 2017)

- 5v Switching Power Supply - \$15 (???)
Image source: (Inc., 2017c)
- Ramps 1.4 for 3D Printer – \$35.95 (Inc., 2017h)

Figure 7:

Figure 8:

Image source: (Inc., 2017h)

- Stepper Motor Driver - \$14.25 (Inc., 2017f)

Figure 9:

Image source: (Inc., 2017f)

- Bipolar Stepper Motor - \$29.50 (Inc., 2017d)

Image source: (Controls, 2017)

- Time Pulley - \$9.00 (Inc., 2017b)

Image source: (Inc., 2017b)

- Rotary - \$4.95 (Inc., 2017g)

Image source: (Inc., 2017g)

- Timing Belt - \$19 (Inc., 2017a)

Image source: (Inc., 2017a)

- Total = \$284.70 + HST

2.5.3 Time Commitment

The design model needs at least 5-6 hours to put everything all together. It includes the laser cutting of the outer cage and then soldering all the components into the case appropriately.

Task

Estimated Time

Printing PCBs

30 mins

Soldering PCBs

2 hrs

Testing Sensors and motor

2 hrs

Designing and Laser-cutting Box

40 mins

Assembling parts

1 hr

Uploading FarmBot firmware (Raspberry pi 3)

30 mins

Uploading FarmBot firmware (Arduino)

25 mins

2.5.4 Mechanical Assembly

Figure 10:

Figure 11:

- The outer case was made by laser cutter and have a transparent shielding to have a clear view of the components placed inside.
- The Arduino is placed underneath the Ramp Shield with approximately the gap of half an inch.
- Adjacent to that the stepper motor is being placed with its one end outwards to have a connection with the belt
- Setup the Raspberry Pi with the farmbot firmware on it so that it generates a gateway for the connection in between web application and the mobile device.
- Get the firmware for the Arduino as well.
- Assemble the firmware for the Ramp shield.
- Add the stepper motor and generate the connection of Arduino and pi.
- Enable the stepper motor and ramp shield by giving an adequate power supply.

2.5.5 PCB and Soldering

2.5.6 Power Up and Testing

The project can be tested by giving the commands from the mobile application and the belt moves according to the distance mentioned by the user. The Raspberry Pi becomes a hotspot and enables the Wi-Fi connection for the mobile device so that it can connect

3. Progress Report

3.1 Report 1 (Week 5)

From: Adanegbe Amadasun Cc: Alisha Singh Chauhan

Dear Sir,

This is our email regarding progress report and the milestone we have covered so far on our project. We are still behind schedule because I did not make a case from last semester for our project. Last semester, I could not keep up with the schedule I created for myself because of my course load and some of the parts I was working with were new to me. But this semester, I have a better understanding of my project and how to do it. We are trying to come up with ideals on how on the stepper motor move different parts of the FarmBot. After we are done with that, we would start working on the code need to move the stepper motor. We have an android app working which we would use to connect to our FarmBot. We have built a case for our FarmBot and we are currently trying to create a pulley system.

Last week Friday, we had success in uploading teacup firmware into our Arduino for the pulley system. Our budget has changed because I have planning on purchasing new parts. I am first going to check the Alisha's parts to m Alisha project to know which of the we can use.

Sincerely, Adanegbe Amadasun

3.2 Report 2 (Week 6)

From: Adanegbe Amadasun Cc: Alisha Singh Chauhan Dear Sir,

This is our email regarding progress report and the milestone we have covered so far on our project. We now have a better understanding on how to go about our project. We worked with Vlad last week Friday

Figure 12:

Figure 13:

to accomplish various task for our project such as: • Tuning our stepper driver to allow 0.6 amps of current • Lasercut a hole through our case for the pulling system • We also learnt how to crimp wires, we crimp our stepper motor wire to make it easier to connect it to ramp shield. We have built a case for our FarmBot and are still working on creating our pulley system. Also, we had success in uploading teacup firmware into our Arduino for the pulley system, and we are currently trying to figure out the distance to use for stepper more to move.

Work breakdown: we have distributed the workload among us in the following way. Database Work Breakdown: Adanegbe will be working on the database part of the project. Currently, we only have a local database for our FarmBot project. The database stores the plant number, date, and name locally. Once the app is deleted the users will lose access to all their data. (Developed by Adanegbe Amadasun)

We plan on getting a server to so all users data can be stored in the cloud and can be accessed by them at any time

Application and work breakdown: Alisha will be proceeding with this. FarmBot is going to be more economical and ecofriendly unlike other agricultural equipment being used. It incorporates precision farming, which happens to be a concept based on observing, measuring and responding to inter and intra-field variability in crops. The device is going to be constructed be the FarmBot company, it is going to be made of an Arduino Mega 2650, Raspberry Pi 3, Sensor hat (which can read temperature, light, and soil condition), and Bi-polar stepper motor.

Hardware breakdown: We are working on the hardware together.

Sincerely, Adanegbe Amadasun

Concluding Remarks

This proposal presents a plan for providing an IoT solution for FarmBot This is an opportunity to integrate the knowledge and skills developed in our program to create a collaborative IoT capstone project demonstrating my ability to learn how to support projects. By preparing this technical report we request the approval of this project as our Farmbot tries to get rid of all these problems by providing all the advantages listed underneath:

- Ability to plant polycrops in a machine efficient manner
- Ability to optimize operations such as watering, spraying, and seed spacing
- Full automation and 24/7 possible operation
- Virtually unlimited farm design possibilities
- Incorporates "Big Data" acquisition and analysis for data-driven decision making and "Smart Farming"
- Ability to plant in the most space efficient layouts
- Scalable from a backyard system to an industrial operation
- Allows for the democratization and decentralization of food production
- Free and open-source, fully documented, hackable, and accessible

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FarmBot

Figure 14:

Image source: (Day, 2016)

From: Alisha Singh Chauhan, Adanegbe Amadasun

Discipline: Computer Engineering Technology

Date Submitted: March 03, 2017

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Phase 3 Demonstration to future employers.

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Incorporation of feedback from demonstration and writing progress report. Status Meeting.

9

30 second build video due.

Practice presentations

9

Progress Report due.

1st round of Presentations, Collaborators present.

9

Presentation PowerPoint file due.

2nd round of Presentations

9

Build instructions up due.

Project videos, Status Meeting.

9

30 second script due.

Phase 1 Total

135

Phase 2

Meet with collaborators

9

Status Meeting

Initial integration.

9

Progress Report

Meet with collaborators

9

Status Meeting

Testing.

9

Progress Report

Meet with collaborators

9

Status Meeting

Meet with collaborators

9

Status Meeting

Incorporation of feedback.

9

Progress Report

Meet with collaborators

9

Status Meeting

Testing.

9

Progress Report

Meet with collaborators

9

Status Meeting

Prepare for demonstration.

9

Progress Report

Complete presentation.

9

Demonstration at Open House Saturday, April 9, 2016 10 a.m. to 2 p.m.

Complete final report. 1st round of Presentations.

9

Presentation PowerPoint file due.

Write video script. 2nd round of Presentations, delivery of project.

9

Final written report including final budget and record of expenditures, covering both this semester and the previous semester.

Project videos.

9

Video script due

Phase 2 Total

135

Phase 3

Interviews

TBD

Phase 3 Total

TBD

Material Estimates

Cost

Notes

Phase 1

A microcomputer composed of a quad-core Windows 10 IoT core compatible Broadcom BCM2836 SoC with a 900MHz Application ARM Cortex-A7 32 bit RISC v7-A processor core stacked under 1GB of 450MHz SDRAM, 10/100 Mbit/s Ethernet, GPIO, UART, I²C bus, SPI bus, 8 GB of Secure Digital storage, a power supply, and a USB Wi-Fi adaptor.

>\$80.00

An example of a retailer: [3].

Peripherals with cables

Sensors

Actuators

Hardware, etc.

Phase 1 Total

>\$200.00

Phase 2

Materials to improve functionality, fit, and finish of project.

Phase 2 Total

TBD

Phase 3

<\$100.00

An example: [4].

Shipping

TBD

Tax

TBD

Duty

TBD

Phase 3 Total

TBD

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1. Introduction

As we are stepping into the 21st century, industrialization is reaching new heights which indeed is giving birth to various problem that could be anywhere. For this reason, technologist have being working to figure out all these technical issues and farmbot is one of that.

FarmBot is an open source automated farming device which operates like a 3D printer. But instead of extruding plastic, its tools are seed injectors, watering nozzles, sensors etc. The techincal report is going to address some the problems the agricultural industry faces, such as loss of money, inefficiency of some equipment and exploitation of resources. The device is going to be more economical and ecofriendly unlike other conventional agricultural equipment being used.

The FarmBot Genesis is able to plant over 30 different crops including [potatoes](#), [peas](#), [squash](#), [arti-chokes](#) and [chard](#) in an area of 2.9 meters × 1.4 meters with a maximum plant height of 0.5 meters. It can cultivate a variety of crops within same area at the same time and is able to operate indoors, outdoors and covered areas. It is estimated that the FarmBot Genesis produces 25% fewer [carbon dioxide](#) emissions.

2. Project Description

2.1 Purpose

Farmers are faced with new challenges and opportunities every day -- from feeding an expanding global population while meeting strict new emissions requirements, to producing more food on fewer acres while minimizing their environmental footprint.

FarmBot is going to address some of the problems the agricultural industry faces like loss of money, how ineffective some of their equipment are and how they waste resources.

The various issues are:

- Supplying the growing global demand for commodities arising from developing economies and world population growth.
- Availability and price of land for expansion
- Development and use of bio-based fuels
- Nearly 25 percent of respondents indicate that equipment dealers/experts will be one of the top advisors to influence their decision making, along with their financial advisor and agronomist advisors

2.2 Hardware Specification

Figure 15:

Image source: (Krassenstein, 2014)

Figure 16:

Image source: (Inc, 2017)

(Describe farmbot parts)

FarmBot will be able to perform the following task:

- Monitor the temperature around the plant,
- Provide light to the plant.

The hardware component for FarmBot that We have are:

- Raspberry pi 3 – It is used to receive data from FarmBot and send it to the Arduino
- Arduino mega 2560 – It is used to control the bi-polar stepper motor
- Sensor Hat (light and temperature) – It is used to receive data about light and temperature from surrounding.
- Bi-polar Stepper motor – It controls the movement of the FarmBot

2.3 Software Specification

Figure 17:

Image source: (Aronson, 2017)

2.3.1 Database work breakdown

Currently, We only have a local database for our FarmBot project. The database stores the plant number, date, and name locally. Once the app is deleted the users will lose access to all their data.

We plan on getting a server to so all users data can be stored in the cloud and can be accessed by them at any time.

(Developed by Adanegbe Amadasun)

2.3.2 Application work breakdown

FarmBot is going to be more economical and ecofriendly unlike other agricultural equipment being used. It incorporates precision farming, which happens to be a concept based on observing, measuring and responding to inter and intra-field variability in crops. The device is going to be constructed by the FarmBot company, it is going to be made of an Arduino Mega 2650, Raspberry Pi 3, Sensor hat (which can read temperature, light, and soil condition), and Bi-polar stepper motor.

We plan on using the an arduino mege2560 to control the bi-polar stepper motor to make it move on its X-axis.

(Developed by Alisha Singh Chauhan)

2.3.3 Web and work breakdown

An app was created to use for the FarmBot, this app would be used to control the FarmBot to plant seed at desire position in the bed. Also, the user can choose the option of giving the FarmBot light for a duration of time, watering the plant etc.

After installing the app on your mobile phone, users will be prompt to create an account by choosing user name and password. This will then give them access to their FarmBot and its data stored in the cloud.

The user can then pick the seed of the crop they want to plant, and the care option they want to apply to the seed (i.e. The light duration, or how frequently they want to water the plant) and submit the options they picked

The user would be given the access to control the FarmBot and apply the option picked from the previous screen.

We plan on connecting FarmBot's app with raspberry pi, so that users can be able to send data to it.

We would both work on this.

(Developed by Adanegbe Amadasun and Alisha Singh Chauhan)

2.5 Build Instruction

2.5.1 Introduction

The Farmbot is designed in a such a way that it will work and execute the commands given by the user through software. The working is clearly explained with the design model given below.

2.5.2 Bill of Materials

- Raspberry Pi 3 Complete Starter Kit - 32 GB Edition - \$74.35 (Corporation, 2017)

Figure 18:

Image source: (Pimoroni, 2017)

- Arduino Mega - \$49.95 (Inc., 2017e)

Figure 19:

Image source: (Robotics & Electronics, 2017)

- 5v Switching Power Supply - \$15 (???)

Figure 20:

Image source: (Inc., 2017c)

- Ramps 1.4 for 3D Printer – \$35.95 (Inc., 2017h)

Image source: (Inc., 2017h)

- Stepper Motor Driver - \$14.25 (Inc., 2017f)

Image source: (Inc., 2017f)

- Bipolar Stepper Motor - \$29.50 (Inc., 2017d)

Image source: (Controls, 2017)

- Time Pulley - \$9.00 (Inc., 2017b)

Image source: (Inc., 2017b)

- Rotary - \$4.95 (Inc., 2017g)

Image source: (Inc., 2017g)

- Timing Belt - \$19 (Inc., 2017a)

Image source: (Inc., 2017a)

- Total = \$284.70 + HST

2.5.3 Time Commitment

The design model needs at least 5-6 hours to put everything all together. It includes the laser cutting of the outer cage and then soldering all the components into the case appropriately.

Task

Figure 21:

Figure 22:

Estimated Time

Printing PCBs

30 mins

Soldering PCBs

2 hrs

Testing Sensors and motor

2 hrs

Designing and Laser-cutting Box

40 mins

Assembling parts

1 hr

Uploading FarmBot firmware (Raspberry pi 3)

30 mins

Uploading FarmBot firmware (Arduino)

25 mins

2.5.4 Mechanical Assembly

- The outer case was made by laser cutter and have a transparent shielding to have a clear view of the components placed inside.
- The Arduino is placed underneath the Ramp Shield with approximately the gap of half an inch.
- Adjacent to that the stepper motor is being placed with its one end outwards to have a connection with the belt
- Setup the Raspberry Pi with the farmbot firmware on it so that it generates a gateway for the connection in between web application and the mobile device.
- Get the firmware for the Arduino as well.
- Assemble the firmware for the Ramp shield.
- Add the stepper motor and generate the connection of Arduino and pi.
- Enable the stepper motor and ramp shield by giving an adequate power supply.

2.5.5 PCB and Soldering

2.5.6 Power Up and Testing

The project can be tested by giving the commands from the mobile application and the belt moves according to the distance mentioned by the user. The Raspberry Pi becomes a hotspot and enables the Wi-Fi connection for the mobile device so that it can connect

Figure 23:

Figure 24:

Figure 25:

3. Progress Report

3.1 Report 1 (Week 5)

From: Adanegbe Amadasun Cc: Alisha Singh Chauhan

Dear Sir,

This is our email regarding progress report and the milestone we have covered so far on our project. We are still behind schedule because I did not make a case from last semester for our project. Last semester, I could not keep up with the schedule I created for myself because of my course load and some of the parts I was working with were new to me. But this semester, I have a better understanding of my project and how to do it. We are trying to come up with ideals on how on the stepper motor move different parts of the FarmBot. After we are done with that, we would start working on the code need to move the stepper motor. We have an android app working which we would use to connect to our FarmBot. We have built a case for our FarmBot and we are currently trying to create a pulley system. Last week Friday, we had success in uploading teacup firmware into our Arduino for the pulley system. Our budget has changed because I have planning on purchasing new parts. I am first going to check the Alisha's parts to m Alisha project to know which of the we can use.

Sincerely, Adanegbe Amadasun

3.2 Report 2 (Week 6)

From: Adanegbe Amadasun Cc: Alisha Singh Chauhan Dear Sir,

This is our email regarding progress report and the milestone we have covered so far on our project. We now have a better understanding on how to go about our project. We worked with Vlad last week Friday to accomplish various task for our project such as: • Tuning our stepper driver to allow 0.6 amps of current • Lasercut a hole through our case for the pulling system • We also learnt how to crimp wires, we crimp our stepper motor wire to make it easier to connect it to ramp shield. We have built a case for our FarmBot and are still working on creating our pulley system. Also, we had success in uploading teacup firmware into our Arduino for the pulley system, and we are currently trying to figure out the distance to use for stepper more to move.

Work breakdown: we have distributed the workload among us in the following way. Database Work Breakdown: Adanegbe will be working on the database part of the project. Currently, we only have a local database for our FarmBot project. The database stores the plant number, date, and name locally. Once the app is deleted the users will lose access to all their data. (Developed by Adanegbe Amadasun)

We plan on getting a server to so all users data can be stored in the cloud and can be accessed by them at any time

Application and work breakdown: Alisha will be proceeding with this. FarmBot is going to be more economical and ecofriendly unlike other agricultural equipment being used. It incorporates precision farming, which happens to be a concept based on observing, measuring and responding to inter and intra-field variability in crops. The device is going to be constructed be the FarmBot company, it is going to be made of an Arduino Mega 2650, Raspberry Pi 3, Sensor hat (which can read temperature, light, and soil condition), and Bi-polar stepper motor.

Hardware breakdown: We are working on the hardware together.

Sincerely, Adanegbe Amadasun

Figure 26:

Concluding Remarks

This proposal presents a plan for providing an IoT solution for FarmBot. This is an opportunity to integrate the knowledge and skills developed in our program to create a collaborative IoT capstone project demonstrating my ability to learn how to support projects. By preparing this technical report we request the approval of this project as our Farmbot tries to get rid of all these problems by providing all the advantages listed underneath:

- Ability to plant polycrops in a machine efficient manner
- Ability to optimize operations such as watering, spraying, and seed spacing
- Full automation and 24/7 possible operation
- Virtually unlimited farm design possibilities
- Incorporates "Big Data" acquisition and analysis for data-driven decision making and "Smart Farming"
- Ability to plant in the most space efficient layouts
- Scalable from a backyard system to an industrial operation
- Allows for the democratization and decentralization of food production
- Free and open-source, fully documented, hackable, and accessible

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