Лабораторная работа №5. Применение сверточных нейронных сетей (бинарная классификация)

Данные: Набор данных DogsVsCats, который состоит из изображений различной размерности, содержащих фотографии собак и кошек. Обучающая выборка включает в себя 25 тыс. изображений (12,5 тыс. кошек: cat.0.jpg, ..., cat.12499.jpg и 12,5 тыс. собак: dog.0.jpg, ..., dog.12499.jpg), а контрольная выборка содержит 12,5 тыс. неразмеченных изображений. Скачать данные, а также проверить качество классификатора на тестовой выборке можно на сайте Kaggle -> https://www.kaggle.com/c/dogs-vs-cats/data (https://www.kaggle.com/c/dogs-vs-cats/data)

In [7]:

```
import numpy as np # linear algebra
import pandas as pd # data processing, CSV file I/O (e.g. pd.read_csv)
import os
import torch
import torch.nn as nn
import cv2
import matplotlib.pyplot as plt
import torchvision
from torch.utils.data import Dataset, DataLoader, ConcatDataset
from torchvision import transforms
import copy
import tqdm
from PIL import Image
%matplotlib inline
```

Загрузите данные. Разделите исходный набор данных на обучающую, валидационную и контрольную выборки.

```
In [8]:
```

```
import zipfile

zip_files = ['test1', 'train']
# Will unzip the files so that you can see them..
for zip_file in zip_files:
    with zipfile.ZipFile("../input/{}.zip".format(zip_file),"r") as z:
        z.extractall(".")
        print("{} unzipped".format(zip_file))
```

test1 unzipped train unzipped

In [9]:

```
train_dir = 'train'
test_dir = 'test1'
```

In [10]:

In [11]:

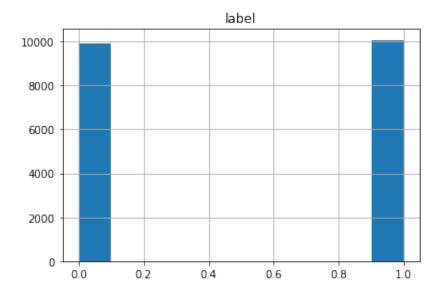
```
from sklearn.model_selection import train_test_split

train_data, test_data = train_test_split(data, test_size=0.2)
test_data, val_data = train_test_split(test_data, test_size=0.25)
```

In [12]:

```
train_data.hist()
```

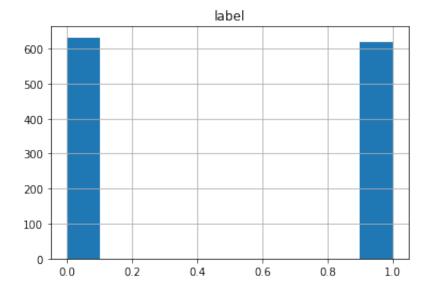
Out[12]:



```
In [13]:
```

```
val_data.hist()
```

Out[13]:



In [73]:

```
class CatDogDataset(Dataset):
    def __init__(self, data, transform = None):
        self.data = data
        self.transform = transform

def __len__(self):
        return len(self.data)

def __getitem__(self, idx):
        file = self.data.iloc[idx, 0]
        label = self.data.iloc[idx, 1]
        img = Image.open(file)
        if self.transform:
              img = self.transform(img)

img = img.numpy()
        return img.astype('float32'), label
```

In [15]:

```
data_transform = transforms.Compose([
    transforms.Resize((128, 128)),
    transforms.ToTensor()
])

train_dataset = CatDogDataset(train_data, transform = data_transform)
val_dataset = CatDogDataset(val_data, transform = data_transform)
```

In [16]:

```
train_loader = DataLoader(train_dataset, batch_size = 32, shuffle=True, num_wo
rkers=4)
val_loader = DataLoader(val_dataset, batch_size = 32, shuffle=False, num_worke
rs=4)
```

In [17]:

```
samples, labels = iter(train_loader).next()
plt.figure(figsize=(16,24))
grid_imgs = torchvision.utils.make_grid(samples[:8])
np_grid_imgs = grid_imgs.cpu().numpy()
# in tensor, image is (batch, width, height), so you have to transpose it to (
width, height, batch) in numpy to show it.
plt.imshow(np.transpose(np_grid_imgs, (1,2,0)))
```

Out[17]:

<matplotlib.image.AxesImage at 0x7f3d04643ac8>



Реализуйте глубокую нейронную сеть с как минимум тремя сверточными слоями.

```
class CNNModel(nn.Module):
    def __init__(self):
        super(CNNModel, self).__init__()
        self.cnn1 = nn.Conv2d(in channels=3, out channels=16, kernel size=5, s
tride=1, padding=2)
        self.relu1 = nn.ReLU()
        self.maxpool1 = nn.MaxPool2d(kernel size=2)
        self.cnn2 = nn.Conv2d(in_channels=16, out_channels=32, kernel_size=5,
stride=1, padding=2)
        self.relu2 = nn.ReLU()
        self.maxpool2 = nn.MaxPool2d(kernel size=2)
        self.cnn3 = nn.Conv2d(in channels=32, out channels=16, kernel size=5,
stride=1, padding=2)
        self.relu3 = nn.ReLU()
        self.maxpool3 = nn.MaxPool2d(kernel size=2)
        self.fc preout = nn.Linear(4096, 100)
        self.fc = nn.Linear(100, 2)
    def forward(self, x):
        out = self.cnn1(x)
        out = self.relu1(out)
        out = self.maxpool1(out)
        out = self.cnn2(out)
        out = self.relu2(out)
        out = self.maxpool2(out)
        out = self.cnn3(out)
        out = self.relu3(out)
        out = self.maxpool3(out)
        out = out.view(out.size(0), -1)
        out = self.fc preout(out)
        out = self.fc(out)
        return out
```

In [43]:

```
def validate(model, val_loader, criterion):
    correct = 0
    total = 0
    total_loss = 0
    for images, labels in val_loader:
        images = images.cuda()
        labels = labels.cuda()

        outputs = model(images)
        loss = criterion(outputs, labels)

        total_loss += loss.item()
        _, predicted = torch.max(outputs.data, 1)

        total += labels.size(0)
        correct += (predicted == labels).sum()
```

```
accuracy = correct.cpu().numpy() / total
    loss = total loss / len(val loader)
    return accuracy, loss
def train(model, train loader, val loader, num epochs, optimizer, criterion, s
cheduler):
    train acc = []
    val_acc = []
    for epoch in tqdm.tqdm(range(num epochs)):
        total loss = 0
        correct = 0
        total = 0
        for i, (images, labels) in enumerate(train_loader):
            images = images.cuda()
            labels = labels.cuda()
            outputs = model(images)
            loss = criterion(outputs, labels)
            optimizer.zero grad()
            loss.backward()
            optimizer.step()
            scheduler.step()
            total loss += loss.item()
            _, predicted = torch.max(outputs.data, 1)
            total += labels.size(0)
            correct += (predicted == labels).sum()
        train loss = total loss / len(train loader)
        train accuracy = correct.cpu().numpy() / total
        accuracy, loss = validate(model, val loader, criterion)
        # Print Loss
        print(f'[Epoch {epoch+1}/{num epochs}] Train Loss: {train loss:.4f}, A
ccuracy: {train accuracy:.3f}; Val Loss: {loss:.4f}, Accuracy: {accuracy:.3f}'
)
        val acc.append(accuracy)
        train_acc.append(train accuracy)
    return train_acc, val_acc
```

In [42]:

```
model = CNNModel().cuda()
criterion = nn.CrossEntropyLoss()
optimizer = torch.optim.Adam(model.parameters(), lr=0.002, amsgrad=True)
scheduler = torch.optim.lr_scheduler.MultiStepLR(optimizer, milestones=[500,10
00,1500], gamma=0.5)
train(model, train_loader, val_loader, 10, optimizer, criterion, scheduler)
```

```
| 0/10 [00:00<?, ?it/s]
```

```
10%|■ | 1/10 [01:26<12:57, 86.34s/it]
```

0 % |

[Epoch 1/10] Train Loss: 0.6917, Accuracy: 0.530; Val Loss: 0.6798, Accuracy: 0.565

```
20% | 2/10 [02:50<11:25, 85.74s/it]
```

[Epoch 2/10] Train Loss: 0.6736, Accuracy: 0.583; Val Loss: 0.6581, Accuracy: 0.593

```
30% 30% 3/10 [04:14<09:57, 85.31s/it]
```

[Epoch 3/10] Train Loss: 0.6490, Accuracy: 0.620; Val Loss: 0.6061, Accuracy: 0.682

```
40% | 4/10 [05:40<08:32, 85.38s/it]
```

[Epoch 4/10] Train Loss: 0.5803, Accuracy: 0.701; Val Loss: 0.5593, Accuracy: 0.722

```
50% | 5/10 [07:05<07:05, 85.13s/it]
```

[Epoch 5/10] Train Loss: 0.5335, Accuracy: 0.734; Val Loss: 0.5196, Accuracy: 0.738

60% | 6/10 [08:30<05:41, 85.33s/it]

[Epoch 6/10] Train Loss: 0.5038, Accuracy: 0.758; Val Loss: 0.5164, Accuracy: 0.746

70% | 7/10 [09:55<04:15, 85.11s/it]

[Epoch 7/10] Train Loss: 0.4852, Accuracy: 0.771; Val Loss: 0.5097, Accuracy: 0.744

80%| | 8/10 [11:21<02:50, 85.32s/it]

[Epoch 8/10] Train Loss: 0.4660, Accuracy: 0.781; Val Loss: 0.4841, Accuracy: 0.768

90% | 9/10 [12:46<01:25, 85.22s/it]

[Epoch 9/10] Train Loss: 0.4475, Accuracy: 0.795; Val Loss: 0.4684, Accuracy: 0.775

100% | 10/10 [14:11<00:00, 85.16s/it]

[Epoch 10/10] Train Loss: 0.4334, Accuracy: 0.798; Val Loss: 0.479 3, Accuracy: 0.766

In [46]:

```
test_dataset = CatDogDataset(test_data, transform = data_transform)
test_loader = DataLoader(test_dataset, batch_size = 32, shuffle=False, num_wor
kers=4)
accuracy, loss = validate(model, test_loader, criterion)
print(f'Test Loss: {loss:.4f}, Accuracy: {accuracy:.3f}')
```

Test Loss: 0.4625, Accuracy: 0.779

Примените дополнение данных (data augmentation).

In [54]:

```
data_transform = transforms.Compose([
    transforms.Resize((128, 128)),
    transforms.RandomHorizontalFlip(p=0.5),
    transforms.ToTensor()
])

aug_dataset = CatDogDataset(train_data, transform = data_transform)
aug_loader = DataLoader(aug_dataset, batch_size = 32, shuffle=True, num_worker s=4)
```

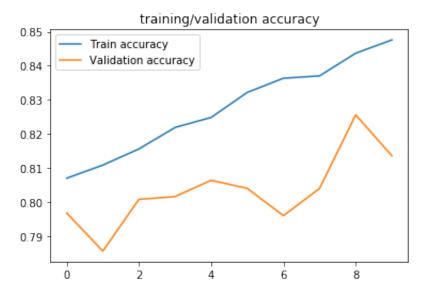
In []:

```
train_acc, val_acc = train(model, aug_loader, val_loader, 10, optimizer, crite
rion, scheduler)
```

[Epoch 10/10] Train Loss: 0.3521, Accuracy: 0.848; Val Loss: 0.4148, Accuracy: 0.814

In [57]:

```
plt.plot(train_acc, label='Train accuracy')
plt.plot(val_acc, label='Validation accuracy')
plt.legend()
plt.title('training/validation accuracy')
plt.show()
```



In [58]:

```
accuracy, loss = validate(model, test_loader, criterion)
print(f'After augmentation Test Loss: {loss:.4f}, Accuracy: {accuracy:.3f}')
```

After augmentation Test Loss: 0.4209, Accuracy: 0.815

Поэкспериментируйте с готовыми нейронными сетями (например, AlexNet, VGG16, Inception и т.п.), применив передаточное обучение.

In [60]:

```
from torchvision import models
from torch.optim import lr_scheduler

model = models.resnet18(pretrained=True)
num_features = model.fc.in_features
model.fc = nn.Linear(num_features, 2)
model = model.cuda()

criterion = nn.CrossEntropyLoss()
optimizer = torch.optim.Adam(model.parameters(), lr=0.002, amsgrad=True)
scheduler = lr_scheduler.CosineAnnealingLR(optimizer, 30)
```

In [63]:

```
ds = ConcatDataset([train_dataset, aug_dataset])
resnet_loader = DataLoader(ds, batch_size = 32, shuffle=True, num_workers=4)
```

```
In [64]:
```

```
train_acc, val_acc = train(model, resnet_loader, val_loader, 10, optimizer, cr
iterion, scheduler)
```

```
0% | 0/10 [00:00<?, ?it/s]
```

```
10% | 1/10 [02:53<26:00, 173.34s/it]
```

[Epoch 1/10] Train Loss: 0.2301, Accuracy: 0.904; Val Loss: 0.1713, Accuracy: 0.922

```
20% 20% 2/10 [05:51<23:17, 174.65s/it]
```

[Epoch 2/10] Train Loss: 0.1300, Accuracy: 0.948; Val Loss: 0.1156, Accuracy: 0.962

```
30% | 3/10 [08:48<20:28, 175.47s/it]
```

[Epoch 3/10] Train Loss: 0.0898, Accuracy: 0.965; Val Loss: 0.1253, Accuracy: 0.954

[Epoch 4/10] Train Loss: 0.0660, Accuracy: 0.975; Val Loss: 0.1657, Accuracy: 0.941

50% | 5/10 [14:36<14:32, 174.56s/it]

[Epoch 5/10] Train Loss: 0.0554, Accuracy: 0.980; Val Loss: 0.1920, Accuracy: 0.948

60% | 6/10 [17:34<11:42, 175.51s/it]

[Epoch 6/10] Train Loss: 0.0455, Accuracy: 0.982; Val Loss: 0.1520, Accuracy: 0.950

70% | 7/10 [20:31<08:47, 175.94s/it]

[Epoch 7/10] Train Loss: 0.0334, Accuracy: 0.988; Val Loss: 0.1390, Accuracy: 0.954

80% | 8/10 [23:29<05:53, 176.52s/it]

[Epoch 8/10] Train Loss: 0.0251, Accuracy: 0.991; Val Loss: 0.1584, Accuracy: 0.957

```
90% | 9/10 [26:29<02:57, 177.46s/it]

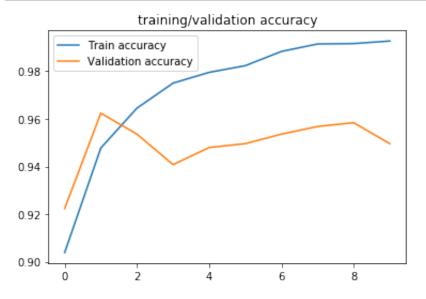
[Epoch 9/10] Train Loss: 0.0246, Accuracy: 0.992; Val Loss: 0.1353, Accuracy: 0.958
```

```
100% | 10/10 [29:27<00:00, 177.78s/it]

[Epoch 10/10] Train Loss: 0.0209, Accuracy: 0.993; Val Loss: 0.206
7, Accuracy: 0.950
```

In [81]:

```
plt.plot(train_acc, label='Train accuracy')
plt.plot(val_acc, label='Validation accuracy')
plt.legend()
plt.title('training/validation accuracy')
plt.show()
```



In [66]:

```
accuracy, loss = validate(model, test_loader, criterion)
print(f'ResNet18 Test Loss: {loss:.4f}, Accuracy: {accuracy:.3f}')
```

ResNet18 Test Loss: 0.1693, Accuracy: 0.949

```
In [68]:
```

```
filename_pth = 'resnet18_catdog.pth'
torch.save(model.state_dict(), filename_pth)
```

In [75]:

```
files labels = {os.path.join(train dir, file name): file name for file name in
os.listdir(train_dir)}
test_data = pd.DataFrame.from_dict({'image_file': list(files_labels.keys()), '
label': list(files labels.values())})
data transform = transforms.Compose([
    transforms.Resize((128, 128)),
   transforms.ToTensor()
])
test ds = CatDogDataset(test data, transform = data transform)
testloader = DataLoader(test ds, batch size = 32, shuffle=False, num workers=4
fn list = []
pred list = []
for x, fn in testloader:
   with torch.no grad():
        x = x.cuda()
        output = model(x)
        pred = torch.argmax(output, dim=1)
        fn list += [n[:-4] for n in fn]
        pred list += [p.item() for p in pred]
submission = pd.DataFrame({"id":fn list, "label":pred list})
submission.to csv('preds resnet18.csv', index=False)
```

In [79]:

```
samples, _ = iter(testloader).next()
samples = samples.cuda()
fig = plt.figure(figsize=(24, 16))
fig.tight_layout()
output = model(samples[:24])
pred = torch.argmax(output, dim=1)
pred = [p.item() for p in pred]
ad = {0:'cat', 1:'dog'}
for num, sample in enumerate(samples[:12]):
    plt.subplot(4,6,num+1)
    plt.title(ad[pred[num]])
    plt.axis('off')
    sample = sample.cpu().numpy()
    plt.imshow(np.transpose(sample, (1,2,0)))
```



Вывод:

В данной лабораторной мы использовали сверточную нейронную сеть для реализации бинарного классификатора на наборе данных Cats/Dogs. Использовали аугментацию данных и предаточное обучение.