













MSP430F5529, MSP430F5528, MSP430F5527, MSP430F5526 MSP430F5525, MSP430F5524, MSP430F5522, MSP430F5521 MSP430F5519, MSP430F5517, MSP430F5515, MSP430F5514, MSP430F5513

ZHCSIR7N - MARCH 2009 - REVISED SEPTEMBER 2018

MSP430F552x、MSP430F551x 混合信号微控制器

1 器件概述

1.1 特性

- 低电源电压范围:
 从 3.6V 低至 1.8V
- 超低功耗
 - 激活模式 (AM):
 - 所有系统时钟激活:
 - 8MHz 时为 290μA/MHz、3.0V、闪存程序 执行(典型值)
 - 8MHz 时为 150μA/MHz、3.0V、RAM 程 序执行(典型值)
 - 待机模式 (LPM3):
 - 含晶体的实时时钟 (RTC)、看门狗、电源监控器可用、完全 RAM 保持、快速唤醒:
 - 2.2V 时为 1.9μA, 3.0V 时为 2.1μA (典型 值)
 - 低功耗振荡器 (VLO)、通用计数器、看门狗、 电源监控器可用、完全 RAM 保持、快速唤 醒:
 - 3.0V 时为 1.4µA (典型值)
 - 关闭模式 (LPM4):
 - 完全 RAM 保持、电源监视器可用、快速唤醒:
 - 3.0V 时为 1.1µA (典型值)
 - 关断模式 (LPM4.5):
 - 3.0V 时为 0.18µA (典型值)
- 在 3.5µs(典型值)内从待机模式唤醒
- 16 位精简指令集计算机 (RISC) 架构,扩展内存, 高达 25MHz 的系统时钟
- 灵活的电源管理系统
 - 内置可编程的低压降稳压器 (LDO)
 - 电源电压监控、监视和临时限电
- 统一时钟系统
 - 针对频率稳定的锁相环 (FLL) 控制环路
 - 低功耗低频内部时钟源 (VLO)

1.2 应用范围

- 模拟和数字传感器系统
- 数据记录器

- 低频修整内部基准源 (REFO)
- 32kHz 手表晶振 (XT1)
- 高达 32MHz 的高频晶振 (XT2)
- 具有5个捕捉/比较寄存器的16位定时器 TA0, Timer_A
- 具有3个捕捉/比较寄存器的16位定时器 TA1, Timer_A
- 具有3个捕捉/比较寄存器的16位定时器 TA2, Timer_A
- 具有7个捕捉/比较影子寄存器的16位定时器 TB0, Timer B
- 2个通用串行通信接口
 - USCI A0 和 USCI A1 均支持:
 - 增强型通用异步收发器 (UART) 支持自动波特率检测
 - IrDA 编码和解码
 - 同步串行外设接口 (SPI)
 - USCI_B0 和 USCI_B1 每个都支持:
 - I^2C
 - 同步串行外设接口 (SPI)
- 全速通用串行总线 (USB)
 - 集成的 USB 物理层 (PHY)
 - 集成 3.3V 和 1.8V USB 电源系统
 - 集成 USB- 锁相环 (PLL)
 - 8 输入和 8 输出端点
- 具有内部基准、采样保持和自动扫描功能的 12 位模数转换器 (ADC)(仅限 MSP430F552x)
- 比较器
- 硬件乘法器支持 32 位运算
- 串行板上编程,无需外部编程电压
- 3 通道内部 DMA
- 具有 RTC 特性的基本计时器
- 器件比较 总结了可用的系列产品成员
- 连接到 USB 主机

1.3 说明

TI 的 MSP430™系列的超低功耗微控制器包含数个采用外设集的器件,可广泛应用于各种 应用。此架构与多种低功耗模式配合使用,是延长便携式测量应用电池寿命的最优 选择。该微控制器 具有 一个强大的 16 位精简指令集 (RISC) CPU,使用 16 位寄存器以及常数发生器,以便获得最高编码效率。此数控振荡器 (DCO) 可使器件在 3.5μs(典型值)内从低功耗模式唤醒至激活模式。



MSP430F5529、MSP430F5527、MSP430F5525 和 MSP430F5521 微控制器具有支持 USB 2.0 的集成 USB 和 PHY、4 个 16 位计时器、1 个高性能 12 位模数转换器 (ADC)、2 个 USCI、1 个硬件乘法器、 DMA、1 个带有警报功能的 RTC 模块和 63 个 I/O 引脚。MSP430F5528、MSP430F5526、MSP430F5524 和 MSP430F5522 微控制器包含同样的外设,但具有 47 个 I/O 引脚。

MSP430F5519、MSP430F5517 和 MSP430F5515 微控制器具有支持 USB 2.0 的集成 USB 和 PHY、4 个 16 位计时器、2 个 USCI、1 个硬件乘法器、DMA、1 个带有警报功能的 RTC 模块和 63 个 I/O 引脚。 MSP430F5514 和 MSP430F5513 微控制器包含同样的外设,但具有 47 个 I/O 引脚。

典型 应用 包括需要与多种 USB 主机连接的模拟和数字传感器系统、数据记录器和其它应用。

要获得完整的模块说明,请参阅《MSP430F5xx 和 MSP430F6xx 系列用户指南》

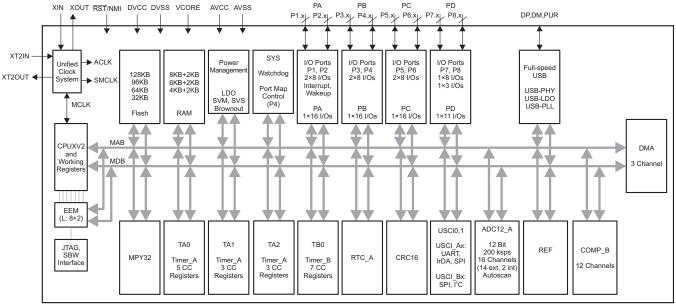
器件信息(1)

器件型号	封装	封装尺寸 ⁽²⁾
MSP430F5529IPN	LQFP (80)	12mm x 12mm
MSP430F5528IRGC	VQFN (64)	9mm x 9mm
MSP430F5528IYFF	DSBGA (64)	请参见 节 8
MSP430F5528IZQE	MicroStar Junior™BGA (80)	5mm x 5mm

- (1) 要获得所有可用器件的最新部件、封装和订购信息,请参见封装选项附录(节8)或浏览 TI 网站www.ti.com.cn。
- 2) 这里显示的尺寸为近似值。要获得包含误差值的封装尺寸,请参见机械数据(节8)。

1.4 功能方框图

图 1-1 展示了采用 PN 封装的 MSP430F5529、MSP430F5527、MSP430F5525 和 MSP430F5521 器件的功能方框图。

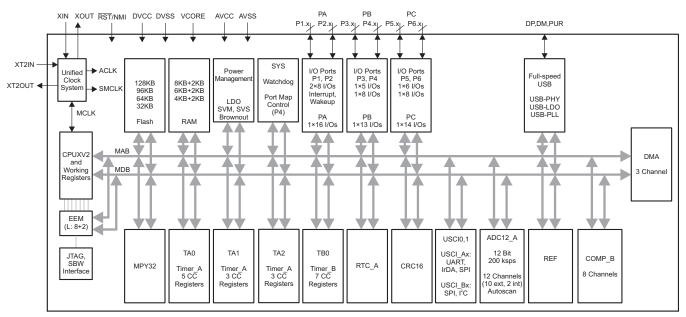


Copyright © 2017, Texas Instruments Incorporated

图 1-1. 功能方框图 – MSP430F5529IPN、MSP430F5527IPN、MSP430F5525IPN、MSP430F5521IPN

图 1-2 展示了采用 RGC 和 ZQE 封装的 MSP430F5528、MSP430F5526、MSP430F5524 和 MSP430F5522 器件的功能方框图,以及采用 YFF 封装的 MSP430F5528、MSP430F5526 和 MSP430F5524 器件的功能方框图。



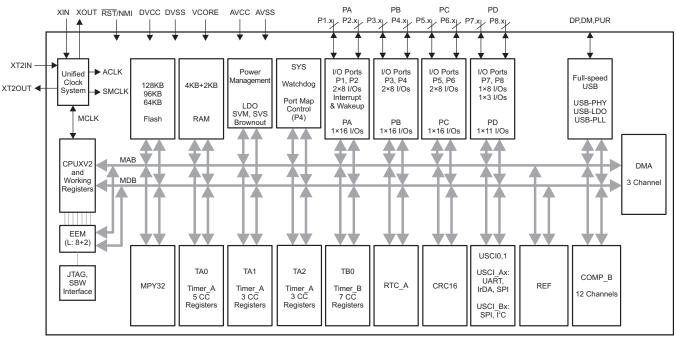


Copyright © 2017, Texas Instruments Incorporated

图 1-2. 功能方框图 -

MSP430F5528IRGC、MSP430F5526IRGC、MSP430F5524IRGC、MSP430F5522IRGC MSP430F5528IZQE、MSP430F5526IZQE、MSP430F5524IZQE、MSP430F5522IZQE MSP430F5528IYFF、MSP430F5526IYFF、MSP430F5524IYFF

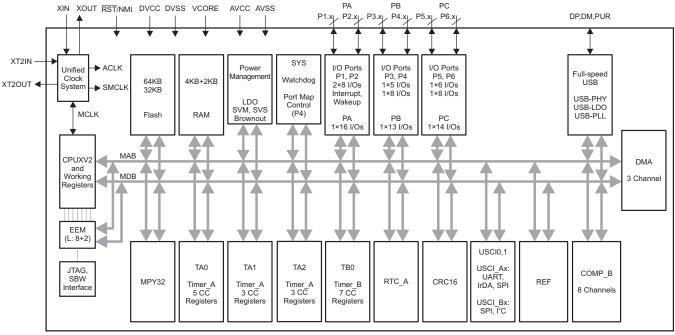
图 1-3 展示了采用 PN 封装的 MSP430F5519、MSP430F5517 和 MSP430F5515 器件的功能方框图。



Copyright © 2017, Texas Instruments Incorporated

图 1-3. 功能方框图 – MSP430F5519IPN、MSP430F5517IPN、MSP430F5515IPN

图 1-4 展示了采用 RGC 和 ZQE 封装的 MSP430F5514 和 MSP430F5513 器件的功能方框图。



Copyright © 2017, Texas Instruments Incorporated

图 1-4. 功能方框图 – MSP430F5514IRGC、MSP430F5513IRGC、MSP430F5514IZQE、MSP430F5513IZQE





内容

1	器件	既述	<u>1</u>		5.21	PMM, Core Voltage	34
	1.1	特性	<u>1</u>		5.22	PMM, SVS High Side	34
	1.2	应用范围	<u>1</u>		5.23	PMM, SVM High Side	35
	1.3	说明	<u>1</u>		5.24	PMM, SVS Low Side	<u>35</u>
	1.4	功能方框图	2		5.25	PMM, SVM Low Side	<u>35</u>
2	修订	历史记录	<u>6</u>		5.26	Wake-up Times From Low-Power Modes and	
3	Devi	ce Comparison	7			Reset	_
	3.1	Related Products	8		5.27	Timer_A	<u>36</u>
4	Term	ninal Configuration and Functions	9		5.28	Timer_B	<u>36</u>
	4.1	Pin Diagrams	_		5.29	USCI (UART Mode) Clock Frequency	37
	4.2	Signal Descriptions	_ 15		5.30	USCI (UART Mode)	37
5	Spec	cifications	21		5.31	USCI (SPI Master Mode) Clock Frequency	37
	5.1	Absolute Maximum Ratings			5.32	USCI (SPI Master Mode)	37
	5.2	ESD Ratings			5.33	USCI (SPI Slave Mode)	39
	5.3	Recommended Operating Conditions	_		5.34	USCI (I ² C Mode)	41
	5.4	Active Mode Supply Current Into V _{CC} Excluding	<u></u>		5.35	12-Bit ADC, Power Supply and Input Range	
	0. 1	External Current	23			Conditions	42
	5.5	Low-Power Mode Supply Currents (Into V _{CC})	_		5.36	12-Bit ADC, Timing Parameters	42
		Excluding External Current	<u>24</u>		5.37	, ,	
	5.6	Thermal Resistance Characteristics	<u>25</u>			Reference Voltage or AVCC as Reference Voltage	_
	5.7	Schmitt-Trigger Inputs – General-Purpose I/O			5.38	12-Bit ADC, Linearity Parameters Using the Interna	
		(P1.0 to P1.7, P2.0 to P2.7, P3.0 to P3.7, P4.0 to P4.7,			- 20	Reference Voltage	43
		P5.0 to P5.7, P6.0 to P6.7, P7.0 to P7.7, P8.0 to				12-Bit ADC, Temperature Sensor and Built-In V _{MID}	
		P8.2, PJ.0 to PJ.3, RST/NMI)	<u>26</u>		5.40	REF, External Reference	
	5.8	Inputs – Ports P1 and P2			5.41	REF, Built-In Reference	_
		(P1.0 to P1.7, P2.0 to P2.7)	<u>26</u>		5.42	Comparator_B	
	5.9	Leakage Current – General-Purpose I/O	7\		5.43	Ports PU.0 and PU.1	_
		(P1.0 to P1.7, P2.0 to P2.7, P3.0 to P3.7, P4.0 to P4 (P5.0 to P5.7, P6.0 to P6.7, P7.0 to P7.7, P8.0 to	1.7)		5.44	USB Output Ports DP and DM	
		P8.2, PJ.0 to PJ.3, RST/NMI)	26		5.45	USB Input Ports DP and DM	
	5.10	Outputs - General-Purpose I/O (Full Drive Strength)	_		5.46	USB-PWR (USB Power System)	
		(P1.0 to P1.7, P2.0 to P2.7, P3.0 to P3.7, P4.0 to			5.47	USB-PLL (USB Phase-Locked Loop)	<u>50</u>
		P4.7, P5.0 to P5.7, P6.0 to P6.7, P7.0 to P7.7, P8.0 to			5.48	Flash Memory	<u>50</u>
		P8.2, PJ.0 to PJ.3)	26		5.49	JTAG and Spy-Bi-Wire Interface	<u>50</u>
	5.11	Outputs – General-Purpose I/O (Reduced Drive	_	6	Deta	iled Description	<u>51</u>
		Strength)			6.1	CPU (Link to User's Guide)	<u>51</u>
		(P1.0 to P1.7, P2.0 to P2.7, P3.0 to P3.7, P4.0 to P4.7,			6.2	Operating Modes	<u>52</u>
		P5.0 to P5.7, P6.0 to P6.7, P7.0 to P7.7, P8.0 to			6.3	Interrupt Vector Addresses	53
		P8.2, PJ.0 to PJ.3)	<u>27</u>		6.4	Memory Organization	 54
	5.12				6.5	Bootloader (BSL)	
		(P1.0 to P1.7, P2.0 to P2.7, P3.0 to P3.7, P4.0 to P4.7,			6.6	JTAG Operation	
		P5.0 to P5.7, P6.0 to P6.7, P7.0 to P7.7, P8.0 to			6.7	Flash Memory (Link to User's Guide)	
		P8.2, PJ.0 to PJ.3)	<u>27</u>		6.8	RAM (Link to User's Guide)	_
	5.13	Typical Characteristics – Outputs, Reduced Drive			6.9	Peripherals	
		Strength (PxDS.y = 0)	<u>28</u>		6.10	Input/Output Diagrams	_
	5.14	Typical Characteristics – Outputs, Full Drive			6.11	Device Descriptors (TLV)	
		Strength (PxDS.y = 1)	<u>29</u>	7			112
	5.15	Crystal Oscillator, XT1, Low-Frequency Mode		•	7.1	入门和后续步骤	
	5.16	Crystal Oscillator, XT2	<u>31</u>				
	5.17	Internal Very-Low-Power Low-Frequency Oscillator	22		7.2	Device Nomenclature	
	E 10	(VLO)	<u>32</u>		7.3	工具与软件	
	5.18	(REFO)	32		7.4	文档支持	
	5.19	DCO Frequency	_		7.5	相关链接	
	5.20	PMM, Brownout Reset (BOR)			7.6	社区资源	<u>118</u>
	0.20	, Diownout Roset (DON)	U -1				





www.ti.com.cn

7.7	商标	<u>118</u>		7.10	Glossary	<u>119</u>
7.8	静电放电警告	<u>119</u>	8	机械、	封装和可订购信息	<u>119</u>
7.9	Export Control Notice	119				

2 修订历史记录

ZHCSIR7N-MARCH 2009-REVISED SEPTEMBER 2018

注: 之前版本的页码可能与当前版本有所不同。

Changes from November 3, 2015 to September 20, 2018	Page
 更改了器件信息 表中 DSBGA 封装的封装尺寸条目. Added Section 3.1, Related Products. Removed D and E dimension lines from the YFF pinout (for package dimensions, see the Mechanical Data in 节8). Added typical conditions statements at the beginning of Section 5, Specifications. Changed the MIN value of the V_(DVCC_BOR_hys) parameter from 60 mV to 50 mV in Section 5.20, PMM, Brownout Reset (BOR) 	<u>8</u> . <u>14</u>
 Updated notes (1) and (2) and added note (3) in Section 5.26, Wake-up Times From Low-Power Modes and Reset Removed ADC12DIV from the formula for the TYP value in the second row of the t_{CONVERT} parameter in 	. 36
Section 5.36, 12-Bit ADC, Timing Parameters, because ADC12CLK is after division	. 42
 Section 5.42, Comparator_B. Renamed FCTL4.MGR0 and MGR1 bits in the f_{MCLK,MGR} parameter in Section 5.48, Flash Memory, to be consistent with header files 	
 Throughout document, changed all instances of "bootstrap loader" to "bootloader" Added YFF pin numbers to Table 6-11, TAO Signal Connections Added YFF pin numbers to Table 6-12, TA1 Signal Connections 	. <u>63</u>
 Added YFF pin numbers to Table 6-13, TA2 Signal Connections. 已将先前的"开发工具支持"部分替换为"节 7.3、工具与软件". 更改了格式并添加内容至节 7.4文档支持 	



3 Device Comparison

Table 3-1 summarizes the available family members.

Table 3-1. Device Comparison⁽¹⁾⁽²⁾

				US	SCI					
DEVICE	FLASH (KB)	SRAM (KB) ⁽³⁾	Timer_A ⁽⁴⁾	Timer_B ⁽⁵⁾	CHANNEL A: UART, IrDA, SPI	CHANNEL B: SPI, I ² C	ADC12_A (Ch)	COMP_B (Ch)	I/Os	PACKAGE
MSP430F5529	128	8 + 2	5, 3, 3	7	2	2	14 ext, 2 int	12	63	80 PN
MSP430F5528	128	8 + 2	5, 3, 3	7	2	2	10 ext, 2 int	8	47	64 RGC, 64 YFF, 80 ZQE
MSP430F5527	96	6 + 2	5, 3, 3	7	2	2	14 ext, 2 int	12	63	80 PN
MSP430F5526	96	6+2	5, 3, 3	7	2	2	10 ext, 2 int	8	47	64 RGC, 64 YFF, 80 ZQE
MSP430F5525	64	4 + 2	5, 3, 3	7	2	2	14 ext, 2 int	12	63	80 PN
MSP430F5524	64	4+2	5, 3, 3	7	2	2	10 ext, 2 int	8	47	64 RGC, 64 YFF, 80 ZQE
MSP430F5522	32	8 + 2	5, 3, 3	7	2	2	10 ext, 2 int	8	47	64 RGC, 80 ZQE
MSP430F5521	32	6 + 2	5, 3, 3	7	2	2	14 ext, 2 int	12	63	80 PN
MSP430F5519	128	8 + 2	5, 3, 3	7	2	2	_	12	63	80 PN
MSP430F5517	96	6 + 2	5, 3, 3	7	2	2	-	12	63	80 PN
MSP430F5515	64	4 + 2	5, 3, 3	7	2	2	ı	12	63	80 PN
MSP430F5514	64	4 + 2	5, 3, 3	7	2	2	1	8	47	64 RGC, 80 ZQE
MSP430F5513	32	4 + 2	5, 3, 3	7	2	2	_	8	47	64 RGC, 80 ZQE

⁽¹⁾ For the most current part, package, and ordering information for all available devices, see the *Package Option Addendum* in 节 8, or see the TI website at www.ti.com.

⁽²⁾ Package drawings, thermal data, and symbolization are available at www.ti.com/packaging.

⁽³⁾ The additional 2KB of USB SRAM that is listed can be used as general-purpose SRAM when USB is not in use.

⁽⁴⁾ Each number in the sequence represents an instantiation of Timer_A with its associated number of capture/compare registers and PWM output generators available. For example, a number sequence of 3, 5 would represent two instantiations of Timer_A, the first instantiation having 3 and the second instantiation having 5 capture/compare registers and PWM output generators, respectively.

⁽⁵⁾ Each number in the sequence represents an instantiation of Timer_B with its associated number of capture/compare registers and PWM output generators available. For example, a number sequence of 3, 5 would represent two instantiations of Timer_B, the first instantiation having 3 and the second instantiation having 5 capture/compare registers and PWM output generators, respectively.



3.1 Related Products

For information about other devices in this family of products or related products, see the following links.

- **Products for TI Microcontrollers** TI's low-power and high-performance MCUs, with wired and wireless connectivity options, are optimized for a broad range of applications.
- Products for MSP430 Ultra-Low-Power Microcontrollers One platform. One ecosystem. Endless possibilities. Enabling the connected world with innovations in ultra-low-power microcontrollers with advanced peripherals for precise sensing and measurement.
- Companion Products for MSP430F5529 Review products that are frequently purchased or used with this product.
- Reference Designs for MSP430F5529 The TI Designs Reference Design Library is a robust reference design library that spans analog, embedded processor, and connectivity. Created by TI experts to help you jump start your system design, all TI Designs include schematic or block diagrams, BOMs, and design files to speed your time to market.



4 Terminal Configuration and Functions

4.1 Pin Diagrams

Figure 4-1 shows the pinout for the MSP430F5529, MSP430F5527, MSP430F5525, and MSP430F5521 devices in the 80-pin PN package.

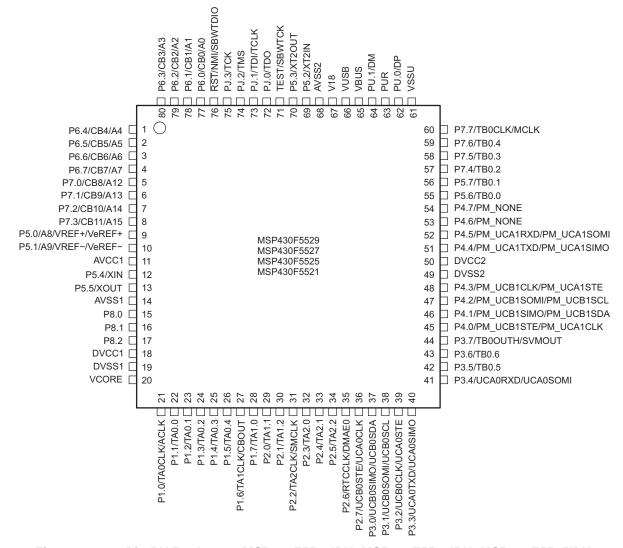
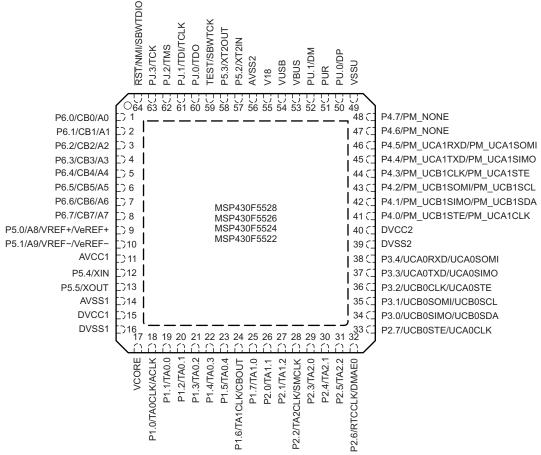


Figure 4-1. 80-Pin PN Package – MSP430F5529IPN, MSP430F5527IPN, MSP430F5525IPN, MSP430F5525IPN (Top View)



Figure 4-2 shows the pinout for the MSP430F5528, MSP430F5526, MSP430F5524, and MSP430F5522 devices in the 64-pin RGC package.



NOTE: TI recommends connecting the exposed thermal pad to V_{SS}.

Figure 4-2. 64-Pin RGC Package – MSP430F5528IRGC, MSP430F5526IRGC, MSP430F5524IRGC, MSP430F5522IRGC (Top View)



Figure 4-3 shows the pinout for the MSP430F5519, MSP430F5517, and MSP430F5515 devices in the 80-pin PN package.

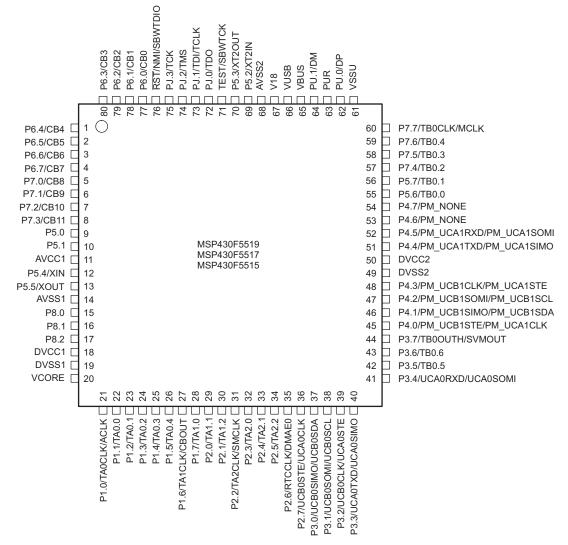
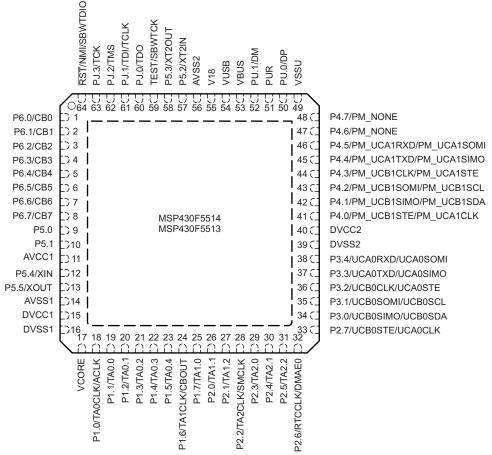


Figure 4-3. 80-Pin PN Package – MSP430F5519IPN, MSP430F5517IPN, MSP430F5515IPN (Top View)

Figure 4-4 shows the pinout for the MSP430F5514 and MSP430F5513 devices in the 64-pin RGC package.



NOTE: TI recommends connecting the exposed thermal pad to V_{SS}.

Figure 4-4. 64-Pin RGC Package - MSP430F5514IRGC, MSP430F5513IRGC (Top View)



Figure 4-5 shows the pinout for the MSP430F5528, MSP430F5526, MSP430F5524, MSP430F5522, MSP430F5514, and MSP430F5513 devices in the 80-pin ZQE package.

P6.0	RST/NM	PJ.2	TEST	AVSS2	VUSB	VBUS	PU.1	PU.0 (A9)
P6.2	P6.1 (B2)	PJ.3 (B3)	P5.3	P5.2	V18	PUR (B7)	VSSU (B8)	VSSU (B9)
P6.4 (C1)	P6.3		PJ.1 (C4)	PJ.0 (C5)	Reserved (C6)	P4.7	P4.6 (C8)	P4.5
P6.6	P6.5	P6.7	Reserved	Reserved	Reserved	P4.4 (D7)	P4.3	P4.2
P5.0 (E1)	P5.1	Reserved	Reserved	Reserved	Reserved (E6)	P4.1	P4.0 (E8)	DVCC2
P5.4 (F1)	AVCC1	Reserved (F3)	Reserved (F4)	Reserved (F5)	Reserved (F6)	Reserved	Reserved	DVSS2
P5.5 (G1)	AVSS1	Reserved	P1.3	P1.6 (G5)	P2.1	P3.4 (G7)	P3.2 (G8)	P3.3 (G9)
DVCC1	P1.0 (H2)	P1.1 (H3)	P1.4 (H4)	P1.7	P2.3	P2.7	P3.0 (H8)	P3.1 (H9)
DVSS1	VCORE	P1.2	P1.5	P2.0 (J5)	P2.2	P2.4	P2.5	P2.6

Figure 4-5. 80-Pin ZQE Package – MSP430F5528IZQE, MSP430F5526IZQE, MSP430F5524IZQE, MSP430F5522IZQE, MSP430F5514IZQE, MSP430F5513IZQE (Top View)

Figure 4-6 shows the pinout for the MSP430F5528, MSP430F5526, and MSP430F5524 devices in the 64-pin YFF package. For package dimensions, see the *Mechanical Data* in 节 8.

			Top V	/iew			
(H8)	(H7)	(H6)	(H5)	(H4)	(H3)	(H2)	(H1)
P2.7	P3.1	DVSS2	DVCC2	P4.1	P4.4	VSSU	PU.0
(G8)	(G7)	(G6)	(G5)	(G4)	(G3)	(G2)	(G1)
P3.0	P3.2	P3.3	P3.4	P4.2	P4.5	PÚR	PU.1
(F8)	F7,	(F6)	(F5)	(F4)	F3)	(F2)	(F1)
P2.4	P2.5	P2.6	P4.0	P4.3	P4.6	VBÚS	VUSB
(E8)	(É7)	(E6)	(E5)	(É4)	(É3)	(E2)	E1,
P2.1	P2.2	P2.3	P2.0	P4.7	TEST	V18	P5.2
(D8)	(D7)	(D6)	(D5)	(D4)	(D3)	(D2)	D1,
P1.7	P1.6	P1.5	RST/NMI	PJ.1	PJ.0	AVSS2	P5.3
(C8)	(C7)	(C6)	(C5)	(C4)	(C3)	(C2)	(C1)
P1.3	P1.4	P1.2	P6.7	P6.3	P6.1	PJ.3	PJ.2
VCORE	(B7)	(B6)	(B5)	(B4)	(B3)	(B2)	(B1)
	P1.0	P1.1	P5.1	P5.0	P6.5	P6.4	P6.0
(Á8)	(Á7)	(A6)	(A5)	(Á4)	(Á3),	P6.6	(A1)
DVŠS1	DVĆC1	P5.5	P5.4	AVSS1	AVCC1		P6.2

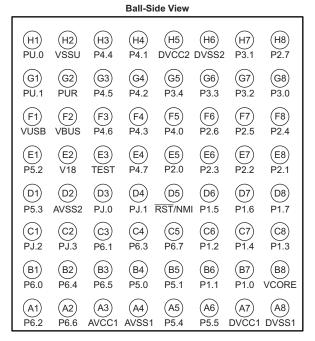


Figure 4-6. 64-Pin YFF Package - MSP430F5528IYFF, MSP430F5526IYFF, MSP430F5524IYFF



4.2 Signal Descriptions

Table 4-1 describes the signals for all device and package options.

Table 4-1. Terminal Functions

TERMINAL								
		N	10.		I/O ⁽¹⁾	DESCRIPTION		
NAME	PN	RGC	YFF	ZQE				
						General-purpose digital I/O		
P6.4/CB4/A4	1	5	B2	C1	I/O	Comparator_B input CB4		
						Analog input A4 for ADC (not available on F551x devices)		
						General-purpose digital I/O		
P6.5/CB5/A5	2	6	В3	D2	I/O	Comparator_B input CB5		
						Analog input A5 for ADC (not available on F551x devices)		
						General-purpose digital I/O		
P6.6/CB6/A6	3	7	A2	D1	I/O	Comparator_B input CB6		
						Analog input A6 for ADC (not available on F551x devices)		
						General-purpose digital I/O		
P6.7/CB7/A7	4	8	C5	D3	I/O	Comparator_B input CB7		
						Analog input A7 for ADC (not available on F551x devices)		
						General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)		
P7.0/CB8/A12	5	N/A	N/A	N/A	I/O	Comparator_B input CB8 (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)		
						Analog input A12 for ADC (not available on F551x devices)		
						General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)		
P7.1/CB9/A13	6	N/A	N/A	N/A	I/O	Comparator_B input CB9 (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)		
						Analog input A13 for ADC (not available on F551x devices)		
						General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)		
P7.2/CB10/A14	7	N/A	N/A	N/A	I/O	Comparator_B input CB10 (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)		
						Analog input A14 for ADC (not available on F551x devices)		
						General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)		
P7.3/CB11/A15	8	N/A	N/A	N/A	I/O	Comparator_B input CB11 (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)		
						Analog input A15 for ADC (not available on F551x devices)		
						General-purpose digital I/O		
						Output of reference voltage to the ADC (not available on F551x devices)		
P5.0/A8/VREF+/VeREF+	9	9	B4	E1	I/O	Input for an external reference voltage to the ADC (not available on F551x devices)		
						Analog input A8 for ADC (not available on F551x devices)		
						General-purpose digital I/O		
P5.1/A9/VREF-/VeREF-	10	10	B5	E2	I/O	Negative terminal for the ADC reference voltage for both sources, the internal reference voltage, or an external applied reference voltage (not available on F551x devices)		
						Analog input A9 for ADC (not available on F551x devices)		
AVCC1	11	11	А3	F2		Analog power supply		



NAME							runctions (continued)	
P5.4/XIN	IE	TERMINAL					DECODINE	
P5.4/XIN	NAME	DNI			70E	1/0(1)	DESCRIPTION	
P5.4XIN		FIN	NGC	IFF	ZQL		General-purpose digital I/O	
P5.5/XOUT	P5.4/XIN	12	12	A5	F1	I/O		
P5.5/XOUT 13 13 A6 G1 I/O Output terminal of crystal oscillator XT1								
AVSS1	P5.5/XOUT	13	13	A6	G1	I/O		
P8.1	AVSS1	14	14	A4	G2			
P8.2	P8.0	15	N/A	N/A	N/A	I/O	General-purpose digital I/O	
DVCC1	P8.1	16	N/A	N/A	N/A	I/O	General-purpose digital I/O	
DVSS1	P8.2	17	N/A	N/A	N/A	I/O	General-purpose digital I/O	
VCORE 20	DVCC1	18	15	A7	H1		Digital power supply	
P1.0/TA0CLK/ACLK 21	DVSS1	19	16	A8	J1		Digital ground supply	
P1.0/TAOCLK/ACLK	VCORE ⁽²⁾	20	17	В8	J2			
ACLK output (divided by 1, 2, 4, 8, 16, or 32) P1.1/TA0.0							General-purpose digital I/O with port interrupt	
P1.1/TA0.0 22 19 B6 H3 I/O General-purpose digital I/O with port interrupt	P1.0/TA0CLK/ACLK	21	18	B7	H2	I/O	TA0 clock signal TA0CLK input	
P1.1/TA0.0 22 19 B6 H3 I/O TA0 CCR0 capture: CCI0A input, compare: Out0 output BSL transmit output							ACLK output (divided by 1, 2, 4, 8, 16, or 32)	
BSL transmit output General-purpose digital I/O with port interrupt TA0 CCR1 capture: CCI1A input, compare: Out1 output BSL receive input P1.3/TA0.2 24 21 C8 G4 I/O General-purpose digital I/O with port interrupt TA0 CCR2 capture: CCI2A input, compare: Out2 output P1.4/TA0.3 25 22 C7 H4 I/O General-purpose digital I/O with port interrupt TA0 CCR2 capture: CCI2A input, compare: Out3 output P1.5/TA0.4 26 23 D6 J4 I/O General-purpose digital I/O with port interrupt TA0 CCR3 capture: CCI3A input compare: Out3 output General-purpose digital I/O with port interrupt TA0 CCR4 capture: CCI3A input compare: Out4 output General-purpose digital I/O with port interrupt TA1 clock signal TA1CLK input Comparator_B output P1.5/TA1.0 28 25 D8 H5 I/O General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output P2.0/TA1.1 29 26 E5 J5 I/O General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out1 output P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI0A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR2 capture: CCI2A input, compare: Out3 output General-purpose digital I/O with port interrupt TA2 CCR2 capture: CCI2A input, compare: Out3 output Gener							General-purpose digital I/O with port interrupt	
P1.2/TA0.1 23 20 C6 J3 I/O General-purpose digital I/O with port interrupt TA0 CCR1 capture: CCI1A input, compare: Out1 output BSL receive input General-purpose digital I/O with port interrupt TA0 CCR2 capture: CCI2A input, compare: Out2 output TA0 CCR2 capture: CCI2A input, compare: Out2 output CGeneral-purpose digital I/O with port interrupt TA0 CCR2 capture: CCI3A input compare: Out3 output CGeneral-purpose digital I/O with port interrupt TA0 CCR3 capture: CCI3A input compare: Out3 output CGeneral-purpose digital I/O with port interrupt TA0 CCR4 capture: CCI4A input, compare: Out4 output CGeneral-purpose digital I/O with port interrupt TA1 clock signal TA1CLK input COMPARTING COMPART	P1.1/TA0.0	22	19	B6	H3	I/O	TA0 CCR0 capture: CCI0A input, compare: Out0 output	
P1.2/TA0.1 23 20 C6 J3 I/O TA0 CCR1 capture: CCI1A input, compare: Out1 output BSL receive input							BSL transmit output	
BSL receive input							General-purpose digital I/O with port interrupt	
P1.3/TA0.2 24 21 C8 G4 I/O General-purpose digital I/O with port interrupt TA0 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA0 CCR3 capture: CCI3A input compare: Out3 output General-purpose digital I/O with port interrupt TA0 CCR3 capture: CCI3A input compare: Out3 output General-purpose digital I/O with port interrupt TA0 CCR4 capture: CCI4A input, compare: Out4 output General-purpose digital I/O with port interrupt TA1 clock signal TA1CLK input Comparator_B output General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out1 output General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digita	P1.2/TA0.1	23	20	C6	J3	I/O	TA0 CCR1 capture: CCl1A input, compare: Out1 output	
P1.3/TA0.2 24 21 C8 G4 I/O TA0 CCR2 capture: CCI2A input, compare: Out2 output P1.4/TA0.3 25 22 C7 H4 I/O General-purpose digital I/O with port interrupt TA0 CCR3 capture: CCI3A input compare: Out3 output P1.5/TA0.4 26 23 D6 J4 I/O General-purpose digital I/O with port interrupt TA0 CCR4 capture: CCI4A input, compare: Out4 output General-purpose digital I/O with port interrupt TA0 CCR4 capture: CCI4A input, compare: Out4 output General-purpose digital I/O with port interrupt TA1 CCR3 capture: CCI4A input, compare: Out4 output General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output P2.0/TA1.1 29 26 E5 J5 I/O General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI0A input, compare: Out1 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI2A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt							BSL receive input	
P1.4/TA0.3 25 22 C7 H4 I/O General-purpose digital I/O with port interrupt TA0 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA0 CCR3 capture: CCI3A input compare: Out3 output P1.5/TA0.4 26 23 D6 J4 I/O General-purpose digital I/O with port interrupt TA0 CCR4 capture: CCI4A input, compare: Out4 output General-purpose digital I/O with port interrupt TA1 clock signal TA1CLK input Comparator_B output P1.7/TA1.0 28 25 D8 H5 I/O General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out1 output General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output P2.0/TA1.1 29 26 E5 J5 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output interrupt TA3 CCR0 capture: CCI0A input, compare: Out0 output	P1.3/TA0.2	24	21	C8	G4	I/O		
P1.4/TA0.3 25 22 C7 H4 I/O TA0 CCR3 capture: CCI3A input compare: Out3 output P1.5/TA0.4 26 23 D6 J4 I/O General-purpose digital I/O with port interrupt TA0 CCR4 capture: CCI4A input, compare: Out4 output General-purpose digital I/O with port interrupt TA1 clock signal TA1CLK input Comparator_B output P1.7/TA1.0 28 25 D8 H5 I/O General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output P2.0/TA1.1 29 26 E5 J5 I/O General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output								
P1.5/TA0.4 26 23 D6 J4 I/O General-purpose digital I/O with port interrupt TA0 CCR4 capture: CCI4A input, compare: Out4 output General-purpose digital I/O with port interrupt TA1 clock signal TA1CLK input Comparator_B output General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output TA1 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output TA1 CCR1 capture: CCI1A input, compare: Out1 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR3 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR3 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR3 capture: CCI2A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR3 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR3 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR3 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR3 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR3 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR3 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR3 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA3 CCR3 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA3 CCR3 capture: CCI0A input, compare: Out0 output General-purpose	P1.4/TA0.3	25	22	C7	H4	I/O		
P1.5/TA0.4 26 23 D6 J4 I/O TA0 CCR4 capture: CCI4A input, compare: Out4 output General-purpose digital I/O with port interrupt TA1 clock signal TA1CLK input Comparator_B output P1.7/TA1.0 28 25 D8 H5 I/O General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output P2.0/TA1.1 P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI1A input, compare: Out1 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output								
P1.6/TA1CLK/CBOUT 27 24 D7 G5 I/O General-purpose digital I/O with port interrupt TA1 clock signal TA1CLK input Comparator_B output P1.7/TA1.0 28 25 D8 H5 I/O General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output P2.0/TA1.1 29 26 E5 J5 I/O General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output	P1.5/TA0.4	26	23	D6	J4	I/O		
P1.6/TA1CLK/CBOUT 27 24 D7 G5 I/O TA1 clock signal TA1CLK input Comparator_B output P1.7/TA1.0 28 25 D8 H5 I/O General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output P2.0/TA1.1 29 26 E5 J5 I/O General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output								
P1.7/TA1.0 28 25 D8 H5 I/O General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output P2.0/TA1.1 29 26 E5 J5 I/O General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output								
P1.7/TA1.0 28 25 D8 H5 I/O General-purpose digital I/O with port interrupt TA1 CCR0 capture: CCI0A input, compare: Out0 output P2.0/TA1.1 29 26 E5 J5 I/O General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output	P1.6/TA1CLK/CBOUT	27	24	D7	G5	I/O		
P1.7/TA1.0 28 25 D8 H5 I/O TA1 CCR0 capture: CCI0A input, compare: Out0 output P2.0/TA1.1 29 26 E5 J5 I/O General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output								
P2.0/TA1.1 29 26 E5 J5 I/O General-purpose digital I/O with port interrupt TA1 CCR1 capture: CCI1A input, compare: Out1 output P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output	P1.7/TA1.0	28	25	D8	H5	I/O		
P2.0/TA1.1 29 26 E5 J5 I/O TA1 CCR1 capture: CCI1A input, compare: Out1 output P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output								
P2.1/TA1.2 30 27 E8 G6 I/O General-purpose digital I/O with port interrupt TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output	P2.0/TA1.1	29	26	E5	J5	I/O		
P2.1/TA1.2 30 27 E8 G6 I/O TA1 CCR2 capture: CCI2A input, compare: Out2 output General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O Compare: Out2 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt								
P2.2/TA2CLK/SMCLK 31 28 E7 J6 I/O General-purpose digital I/O with port interrupt TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output P2.4/TA2.1 33 30 E8 I/O General-purpose digital I/O with port interrupt General-purpose digital I/O with port interrupt General-purpose digital I/O with port interrupt	P2.1/TA1.2	30	27	E8	G6	I/O		
P2.2/TA2CLK/SMCLK 31 28 E7 J6 I/O TA2 clock signal TA2CLK input SMCLK output P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output P2.4/TA2.1 33 30 E8 I/7 I/O General-purpose digital I/O with port interrupt General-purpose digital I/O with port interrupt								
P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output General-purpose digital I/O with port interrupt General-purpose digital I/O with port interrupt	P2 2/TA2CLK/SMCLK	31	28	F7	16	1/0		
P2.3/TA2.0 32 29 E6 H6 I/O General-purpose digital I/O with port interrupt TA2 CCR0 capture: CCI0A input, compare: Out0 output P2.4/TA2.1 33 30 E8 I/O General-purpose digital I/O with port interrupt General-purpose digital I/O with port interrupt	1 2.2/ TAZOLIV SIVIOLIX	31	20	Li	30	1/0		
P2.3/TA2.0 32 29 E6 H6 I/O TA2 CCR0 capture: CCI0A input, compare: Out0 output P2.4/TA2.1 33 30 F8 I/O General-purpose digital I/O with port interrupt								
P2 4/TA2 1 33 30 F8 J7 I/O General-purpose digital I/O with port interrupt	P2.3/TA2.0	32	29	E6	H6	I/O		
P2 4/TA2 1								
	P2.4/TA2.1	33	30	F8	J7	I/O	TA2 CCR1 capture: CCI1A input, compare: Out1 output	

⁽²⁾ VCORE is for internal use only. No external current loading is possible. Connect VCORE to the recommended capacitor value, C_{VCORE} (see Section 5.3).



TERMINAL									
NAME		N	0.		I/O ⁽¹⁾	DESCRIPTION			
NAME	PN	RGC	YFF	ZQE					
P2.5/TA2.2	34	31	F7	J8	I/O	General-purpose digital I/O with port interrupt			
1 2.0/17(2.2	0-1	01		00	1,0	TA2 CCR2 capture: CCI2A input, compare: Out2 output			
						General-purpose digital I/O with port interrupt			
P2.6/RTCCLK/DMAE0	35	32	F6	J9	I/O	RTC clock output for calibration			
						DMA external trigger input			
						General-purpose digital I/O with port interrupt			
P2.7/UCB0STE/UCA0CLK	36	33	H8	H7	I/O	Slave transmit enable – USCI_B0 SPI mode			
						Clock signal input – USCI_A0 SPI slave mode			
						Clock signal output – USCI_A0 SPI master mode			
P3.0/UCB0SIMO/	27	24	Co	110	1/0	General-purpose digital I/O			
UCB0SDA	37	34	G8	H8	I/O	Slave in, master out – USCI_B0 SPI mode I ² C data – USCI_B0 I ² C mode			
P3.1/UCB0SOMI/UCB0SC	38	35	H7	H9	I/O	General-purpose digital I/O Slave out, master in – USCI_B0 SPI mode			
L	30	35	П/	пэ	1/0	I ² C clock – USCI B0 I ² C mode			
						General-purpose digital I/O			
						Clock signal input – USCI_B0 SPI slave mode			
P3.2/UCB0CLK/UCA0STE	39	36	G7	G8	I/O	Clock signal output – USCI_B0 SPI master mode			
						Slave transmit enable – USCI_A0 SPI mode			
						General-purpose digital I/O			
P3.3/UCA0TXD/	40	37	G6	G9	I/O	Transmit data – USCI_A0 UART mode			
UCA0SIMO						Slave in, master out – USCI_A0 SPI mode			
						General-purpose digital I/O			
P3.4/UCA0RXD/ UCA0SOMI	41	38	G5	G7	I/O	Receive data – USCI_A0 UART mode			
OCAUSOIVII						Slave out, master in – USCI_A0 SPI mode			
P3.5/TB0.5	42	N/A	N/A	N/A	I/O	General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)			
						TB0 CCR5 capture: CCI5A input, compare: Out5 output			
P3.6/TB0.6	43	N/A	N/A	N/A	I/O	General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)			
						TB0 CCR6 capture: CCI6A input, compare: Out6 output			
						General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)			
P3.7/TB0OUTH/SVMOUT	44	N/A	N/A	N/A	I/O	Switch all PWM outputs high impedance input – TB0 (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)			
						SVM output (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)			
						General-purpose digital I/O with reconfigurable port mapping secondary function			
P4.0/PM_UCB1STE/ PM_UCA1CLK	45	41	F5	E8	I/O	Default mapping: Slave transmit enable – USCI_B1 SPI mode			
I W_OOATOLK						Default mapping: Clock signal input – USCI_A1 SPI slave mode			
						Default mapping: Clock signal output – USCI_A1 SPI master mode			
P4.1/PM_UCB1SIMO/	46	40		E7	I/O	General-purpose digital I/O with reconfigurable port mapping secondary function			
PM_UCB1SDA	46	42	H4			Default mapping: Slave in, master out – USCI_B1 SPI mode			
						Default mapping: I ² C data – USCI_B1 I ² C mode			



TERMINAL						
NAME		N	Ю.		I/O ⁽¹⁾	DESCRIPTION
NAIVIE	PN	RGC	YFF	ZQE		
P4.2/PM_UCB1SOMI/	47	40	G4	Do	1/0	General-purpose digital I/O with reconfigurable port mapping secondary function
PM_UCB1SCL	47	43	G4	D9	I/O	Default mapping: Slave out, master in – USCI_B1 SPI mode
						Default mapping: I ² C clock – USCI_B1 I ² C mode
						General-purpose digital I/O with reconfigurable port mapping secondary function
P4.3/PM_UCB1CLK/ PM_UCA1STE	48	44	F4	D8	I/O	Default mapping: Clock signal input – USCI_B1 SPI slave mode
						Default mapping: Clock signal output – USCI_B1 SPI master mode
						Default mapping: Slave transmit enable – USCI_A1 SPI mode
DVSS2	49	39	H6	F9		Digital ground supply
DVCC2	50	40	H5	E9		Digital power supply
P4.4/PM_UCA1TXD/	51	45	НЗ	D7	I/O	General-purpose digital I/O with reconfigurable port mapping secondary function
PM_UCA1SIMO	31	75	110	Di	1/0	Default mapping: Transmit data – USCI_A1 UART mode
						Default mapping: Slave in, master out – USCI_A1 SPI mode
P4.5/PM_UCA1RXD/	5/PM_UCA1RXD/ 52 46 G3 C9	1/0	General-purpose digital I/O with reconfigurable port mapping secondary function			
PM_UCA1SOMI	52	40	GS	C9	I/O	Default mapping: Receive data – USCI_A1 UART mode
					Default mapping: Slave out, master in – USCI_A1 SPI mode	
P4.6/PM_NONE	53	47	F3	C8	I/O	General-purpose digital I/O with reconfigurable port mapping secondary function
						Default mapping: no secondary function.
P4.7/PM_NONE	7/PM_NONE 54 48 E4 C7	C7	I/O	General-purpose digital I/O with reconfigurable port mapping secondary function		
						Default mapping: no secondary function.
P5.6/TB0.0	55	N/A	N/A	N/A	I/O	General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
F3.0/1B0.0	33	IN/A	IN/A	IN/A	1/0	TB0 CCR0 capture: CCI0A input, compare: Out0 output (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
DE 7/TD0 4	50	NI/A	NI/A	N1/A		General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
P5.7/TB0.1	56	N/A	N/A	N/A	I/O	TB0 CCR1 capture: CCl1A input, compare: Out1 output (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
D7 4/TD0 0		N1/A	N1/A	N1/A	1/0	General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
P7.4/TB0.2	57	N/A	N/A	N/A	I/O	TB0 CCR2 capture: CCl2A input, compare: Out2 output (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
						General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
P7.5/TB0.3	58	N/A	N/A	N/A	I/O	TB0 CCR3 capture: CCl3A input, compare: Out3 output (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
DZ 0/FD0 1		N 1/2	N 1/2	.		General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
P7.6/TB0.4	59	N/A	N/A	N/A	I/O	TB0 CCR4 capture: CCI4A input, compare: Out4 output (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
						General-purpose digital I/O (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
P7.7/TB0CLK/MCLK	60	N/A	N/A	N/A	I/O	TB0 clock signal TBCLK input (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)
						MCLK output (not available on F5528, F5526, F5524, F5522, F5514, F5513 devices)



TF	RMINAL					runctions (continued)
			IO.		I/O ⁽¹⁾	DESCRIPTION
NAME	PN	RGC	YFF	ZQE	""	
VSSU	61	49	H2	B8, B9		USB PHY ground supply
PU.0/DP	62	50	H1	A9	I/O	General-purpose digital I/O. Controlled by USB control register USB data terminal DP
PUR	63	51	G2	В7	I/O	USB pullup resistor pin (open drain). The voltage level at the PUR pin is used to invoke the default USB BSL. Recommended 1-M Ω resistor to ground. See Section 6.5.1 for more information.
PU.1/DM	64	52	G1	A8	I/O	General-purpose digital I/O. Controlled by USB control register USB data terminal DM
VBUS	65	53	F2	A7		USB LDO input (connect to USB power source)
VUSB	66	54	F1	A6		USB LDO output
V18	67	55	E2	В6		USB regulated power (internal use only, no external current loading)
AVSS2	68	56	D2	A5		Analog ground supply
DE OVENIN	00		- 4	DE	1/0	General-purpose digital I/O
P5.2/XT2IN	69	57	E1	B5	I/O	Input terminal for crystal oscillator XT2
DE 2/VT2OLIT	70	50	D4	D.4	I/O	General-purpose digital I/O
P5.3/XT2OUT	70	58	D1	B4	1/0	Output terminal of crystal oscillator XT2
TEOT/ODW/TO/(3)	74	50	5 0			Test mode pin – selects 4-wire JTAG operation
TEST/SBWTCK ⁽³⁾	71	59	E3	A4	ı	Spy-Bi-Wire input clock when Spy-Bi-Wire operation activated
D 1 0/TD 0 (4)	70	00	D.O.	0.5		General-purpose digital I/O
PJ.0/TDO ⁽⁴⁾	72	60	D3	C5	I/O	JTAG test data output port
						General-purpose digital I/O
PJ.1/TDI/TCLK ⁽⁴⁾	73	61	D4	C4	I/O	JTAG test data input
						Test clock input
PJ.2/TMS ⁽⁴⁾	74	62	C1	A3	I/O	General-purpose digital I/O
PJ.2/TWIS	74	62	CI	AS	1/0	JTAG test mode select
PJ.3/TCK ⁽⁴⁾	75	63	C2	В3	I/O	General-purpose digital I/O
PJ.3/10K /	75	63	02	DO	1/0	JTAG test clock
						Reset input, active low ⁽⁵⁾
RST/NMI/SBWTDIO (3)	76	64	D5	A2	I/O	Nonmaskable interrupt input
						Spy-Bi-Wire data input/output when Spy-Bi-Wire operation activated
						General-purpose digital I/O
P6.0/CB0/A0	77	1	B1	A1	I/O	Comparator_B input CB0
						Analog input A0 for ADC (not available on F551x devices)
						General-purpose digital I/O
P6.1/CB1/A1	78	2	C3	B2	I/O	Comparator_B input CB1
	\perp					Analog input A1 for ADC (not available on F551x devices)
						General-purpose digital I/O
P6.2/CB2/A2	79	3	A1	B1	I/O	Comparator_B input CB2
	\perp				L	Analog input A2 for ADC (not available on F551x devices)
						General-purpose digital I/O
P6.3/CB3/A3	80	4	C4	C2	I/O	Comparator_B input CB3
	<u></u>				L	Analog input A3 for ADC (not available on F551x devices)

⁽³⁾ See Section 6.5 and Section 6.6 for use with BSL and JTAG functions.

MSP430F5522 MSP430F5521 MSP430F5519 MSP430F5517 MSP430F5515 MSP430F5514 MSP430F5513

⁽⁴⁾ See Section 6.6 for use with JTAG function.

⁵⁾ When this pin is configured as reset, the internal pullup resistor is enabled by default.

www.ti.com.cn



Table 4-1. Terminal Functions (continued)

TER	TERMINAL					
NAME	NO.				I/O ⁽¹⁾	DESCRIPTION
NAME	PN	RGC	YFF	ZQE		
Reserved	N/A	N/A	N/A	(6)		Reserved. Connect to ground.
QFN Pad	N/A	Pad	N/A	N/A		QFN package pad. TI recommends connecting to V _{SS} .

(6) C6, D4, D5, D6, E3, E4, E5, E6, F3, F4, F5, F6, F7, F8, G3 are reserved and should be connected to ground.



5 Specifications

All graphs in this section are for typical conditions, unless otherwise noted.

Typical (TYP) values are specified at $V_{CC} = 3.3 \text{ V}$ and $T_A = 25^{\circ}\text{C}$, unless otherwise noted.

5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

	MIN	MAX	UNIT
Voltage applied at V _{CC} to V _{SS}	-0.3	4.1	V
Voltage applied to any pin (excluding VCORE, VBUS, V18) (2)	-0.3	$V_{CC} + 0.3$	V
Diode current at any device pin		±2	mA
Maximum operating junction temperature, T _J		95	°C
Storage temperature, T _{stg} ⁽³⁾	-55	150	°C

⁽¹⁾ Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltages referenced to V_{SS}. VCORE is for internal device use only. No external DC loading or voltage should be applied.

5.2 ESD Ratings

			VALUE	UNIT
\/	Floatractatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±1000	V
V _(ESD)	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±250	V

⁽¹⁾ JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Pins listed as ±1000 V may actually have higher performance.

5.3 Recommended Operating Conditions

			MIN	NOM	MAX	UNIT
		PMMCOREVx = 0	1.8		3.6	
\/	Supply voltage during program execution and flash	PMMCOREVx = 0, 1	2.0		3.6	V
v _{CC}	programming (AV _{CC} = DV _{CC1} = DV _{CC2} = DV _{CC}) ⁽¹⁾⁽²⁾	PMMCOREVx = 0, 1, 2	2.2		3.6	V
		PMMCOREVx = 0, 1, 2, 3	2.4		3.6	
		PMMCOREVx = 0	1.8		3.6	
	Supply voltage during USB operation, USB PLL disabled,	PMMCOREVx = 0, 1	2.0		3.6	
VCC, USB VSS TA CVCORE COURT	USB_EN = 1, UPLLEN = 0	PMMCOREVx = 0, 1, 2	2.2		3.6	V
		PMMCOREVx = 0, 1, 2, 3	2.4		3.6	
	Supply voltage during USB operation, USB PLL enabled (3),	PMMCOREVx = 2	2.2		3.6	
	USB_EN = 1, UPLLEN = 1	PMMCOREVx = 2, 3	2.4		3.6 3.6 3.6 3.6 3.6 3.6 3.6 3.6	
V_{SS}	Supply voltage (AV _{SS} = DV _{SS1} = DV _{SS2} = DV _{SS})			0		V
T _A	Operating free-air temperature	I version	-40		85	°C
T_{J}	Operating junction temperature	I version	-40		85	°C
C _{VCORE}	Recommended capacitor at VCORE ⁽⁴⁾			470		nF
C _{DVCC} / C _{VCORE}	Capacitor ratio of DVCC to VCORE		10			ratio

⁽¹⁾ TI recommends powering AVCC and DVCC from the same source. A maximum difference of 0.3 V between AVCC and DVCC can be tolerated during power up and operation.

⁽³⁾ Higher temperature may be applied during board soldering according to the current JEDEC J-STD-020 specification with peak reflow temperatures not higher than classified on the device label on the shipping boxes or reels.

⁽²⁾ JEDEC document JÉP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process. Pins listed as ±250 V may actually have higher performance.

⁽²⁾ The minimum supply voltage is defined by the supervisor SVS levels when it is enabled. See the Section 5.22 threshold parameters for the exact values and further details.

³⁾ USB operation with USB PLL enabled requires PMMCOREVx ≥ 2 for proper operation.

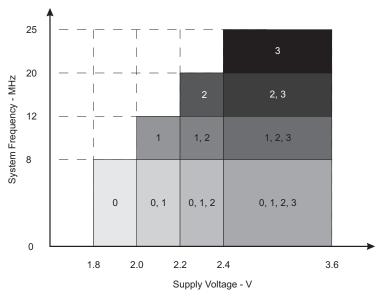
⁽⁴⁾ A capacitor tolerance of ±20% or better is required.



Recommended Operating Conditions (continued)

			MIN	NOM	MAX	UNIT
f _{SYSTEM}		PMMCOREVx = 0, 1.8 V \leq V _{CC} \leq 3.6 V (default condition)	0		8.0	
	Processor frequency (maximum MCLK frequency) (5)	PMMCOREVx = 1, 2.0 V \leq V _{CC} \leq 3.6 V	0		12.0	MHz
	(see Figure 5-1)	PMMCOREVx = 2, 2.2 V \leq V _{CC} \leq 3.6 V	0		20.0	
		PMMCOREVx = 3, 2.4 V \leq V _{CC} \leq 3.6 V	0		25.0	
f _{SYSTEM_USB}	Minimum processor frequency for USB operation		1.5			MHz
USB_wait	Wait state cycles during USB operation			16		cycles

(5) Modules may have a different maximum input clock specification. See the specification of the respective module in this data sheet.



NOTE: The numbers within the fields denote the supported PMMCOREVx settings.

Figure 5-1. Maximum System Frequency



Active Mode Supply Current Into V_{CC} Excluding External Current

over recommended operating free-air temperature (unless otherwise noted) (1) (2) (3)

				FREQUENCY (f _{DCO} = f _{MCLK} = f _{SMCLK})										
PARAMETER	EXECUTION MEMORY	V _{CC}	PMMCOREVx PMMCOREVX	1 MHz		8 MHz		12 MHz		20 MHz		25 MHz		UNIT
	III EIII OKT			TYP	MAX	TYP	MAX	TYP	MAX	TYP	MAX	TYP	MAX	
			0	0.36	0.47	2.32	2.60							
	Flash	3.0 V	1	0.40		2.65		4.0	4.4					mA
I _{AM, Flash}			2	0.44		2.90		4.3		7.1	7.7			
			3	0.46		3.10		4.6		7.6		10.1	11.0	
			0	0.20	0.24	1.20	1.30							
	DAM	0.01/	1	0.22		1.35		2.0	2.2					0
I _{AM} , RAM	RAM	3.0 V	2	0.24		1.50		2.2		3.7	4.2			mA
			3	0.26		1.60		2.4		3.9		5.3	6.2	

All inputs are tied to 0 V or to V_{CC} . Outputs do not source or sink any current. The currents are characterized with a Micro Crystal MS1V-T1K crystal with a load capacitance of 12.5 pF. The internal and external load capacitance are chosen to closely match the required 12.5 pF.

Characterized with program executing typical data processing. USB disabled (VUSBEN = 0, SLDOEN = 0).

 f_{ACLK} = 32786 Hz, f_{DCO} = f_{MCLK} = f_{SMCLK} at specified frequency. XTS = CPUOFF = SCG0 = SCG1 = OSCOFF= SMCLKOFF = 0.



5.5 Low-Power Mode Supply Currents (Into V_{cc}) Excluding External Current

	DADAMETED	.,	DMMCODEV.	-40	°C	25°	С	60°	С	85°	С	UNIT
	PARAMETER	V _{CC}	PMMCOREVx	TYP	MAX	TYP	MAX	TYP	MAX	TYP	MAX	UNIT
	Low-power mode 0 ⁽³⁾⁽⁴⁾	2.2 V	0	73		77	85	80		85	97	
I _{LPM0,1MHz}	Low-power mode o	3.0 V	3	79		83	92	88		95	105	μΑ
	J	2.2 V	0	6.5		6.5	12	10		11	17	
I _{LPM2}	Low-power mode 2 ⁽⁵⁾⁽⁴⁾	3.0 V	3	7.0		7.0	13	11		12	18	μΑ
			0	1.60		1.90		2.6		5.6		
		2.2 V	1	1.65		2.00		2.7		5.9		
			2	1.75		2.15		2.9		6.1		
I _{LPM3,XT1LF}	Low-power mode 3, crystal mode (6) (4)	3.0 V	0	1.8		2.1	2.9	2.8		5.8	8.3	· -
			1	1.9		2.3		2.9		6.1		
			2	2.0		2.4		3.0		6.3		
			3	2.0		2.5	3.9	3.1		6.4	9.3	
			0	1.1		1.4	2.7	1.9		4.9	7.4	
	Low-power mode 3,	3.0 V	1	1.1		1.4		2.0		5.2		
I _{LPM3,VLO}	VLO mode ⁽⁷⁾⁽⁴⁾	3.0 V	2	1.2		1.5		2.1		5.3		μΑ
			3	1.3		1.6	3.0	2.2		5.4	8.5	
			0	0.9		1.1	1.5	1.8		4.8	7.3	
	Low navier made 4 (8) (4)	201/	1	1.1		1.2		2.0		5.1		
l _{LPM4} L	Low-power mode 4 ⁽⁸⁾⁽⁴⁾	3.0 V	2	1.2		1.2		2.1		5.2		μΑ
			3	1.3		1.3	1.6	2.2		5.3	8.1	
I _{LPM4.5}	Low-power mode 4.5 ⁽⁹⁾	3.0 V		0.15		0.18	0.35	0.26		0.5	1.0	μΑ

- (1) All inputs are tied to 0 V or to V_{CC} . Outputs do not source or sink any current.
- (2) The currents are characterized with a Micro Crystal MS1V-T1K crystal with a load capacitance of 12.5 pF. The internal and external load capacitance are chosen to closely match the required 12.5 pF.
- (3) Current for watchdog timer clocked by SMCLK included. ACLK = low frequency crystal operation (XTS = 0, XT1DRIVEx = 0). CPUOFF = 1, SCG0 = 0, SCG1 = 0, OSCOFF = 0 (LPM0); f_{ACLK} = 32768 Hz, f_{MCLK} = 0 MHz, f_{SMCLK} = f_{DCO} = 1 MHz USB disabled (VUSBEN = 0, SLDOEN = 0).
- (4) Current for brownout, high-side supervisor (SVS_H) normal mode included. Low-side supervisor and monitor disabled (SVS_L, SVM_L). High-side monitor disabled (SVM_H). RAM retention enabled.
- (5) Current for watchdog timer and RTC clocked by ACLK included. ACLK = low frequency crystal operation (XTS = 0, XT1DRIVEx = 0). CPUOFF = 1, SCG0 = 0, SCG1 = 1, OSCOFF = 0 (LPM2); f_{ACLK} = 32768 Hz, f_{MCLK} = 0 MHz, f_{SMCLK} = f_{DCO} = 0 MHz; DCO setting = 1 MHz operation, DCO bias generator enabled. USB disabled (VUSBEN = 0, SLDOEN = 0)
- (6) Current for watchdog timer and RTC clocked by ACLK included. ACLK = low frequency crystal operation (XTS = 0, XT1DRIVEx = 0). CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 0 (LPM3); f_{ACLK} = 32768 Hz, f_{MCLK} = f_{SMCLK} = f_{DCO} = 0 MHz USB disabled (VUSBEN = 0, SLDOEN = 0)
- (7) Current for watchdog timer and RTC clocked by ACLK included. ACLK = VLO. CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 0 (LPM3); f_{ACLK} = f_{VLO}, f_{MCLK} = f_{DCO} = 0 MHz USB disabled (VUSBEN = 0, SLDOEN = 0)
- (8) CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 1 (LPM4); f_{DCO} = f_{ACLK} = f_{MCLK} = 0 MHz USB disabled (VUSBEN = 0, SLDOEN = 0)
- (9) Internal regulator disabled. No data retention.
- CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 1, PMMREGOFF = 1 (LPM4.5); fDC0 = fACLK = fMCLK = fSMCLK = 0 MHz



5.6 Thermal Resistance Characteristics

	THERMAL I	METRIC		VALUE	UNIT
			LQFP (PN)	70	
		Low-K board (JESD51-3)	VQFN (RGC)	55	
D0	$R\theta_{\perp A}$ Junction-to-ambient thermal resistance, still air		BGA (ZQE)	84	°C/W
$R\theta_{JA}$	Junction-to-ambient thermal resistance, still air		LQFP (PN)	45	3C/VV
		High-K board (JESD51-7)	VQFN (RGC)	25	
			BGA (ZQE)	46	
			LQFP (PN)	12	
$R\theta_{JC}$	Junction-to-case thermal resistance		VQFN (RGC)	12	°C/W
			BGA (ZQE)	30	
			LQFP (PN)	22	
$R\theta_{JB}$	Junction-to-board thermal resistance		VQFN (RGC)	6	°C/W
		BGA (ZQE)	20		



5.7 Schmitt-Trigger Inputs – General-Purpose I/O⁽¹⁾ (P1.0 to P1.7, P2.0 to P2.7, P3.0 to P3.7, P4.0 to P4.7, P5.0 to P5.7, P6.0 to P6.7, P7.0 to P7.7, P8.0 to P8.2, PJ.0 to PJ.3, RST/NMI)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
V	Docitive going input threshold voltage		1.8 V	0.80		1.40	V
V _{IT+}	Positive-going input threshold voltage		3 V	1.50		2.10	V
\/	Negative-going input threshold voltage		1.8 V	0.45		1.00	V
V_{IT-}	Negative-going input tilleshold voltage		3 V	0.75		1.65	V
\/	Input valtage bystereeig (V V V		1.8 V	0.3		0.85	V
V_{hys}	Input voltage hysteresis (V _{IT+} – V _{IT-})		3 V	0.4		1.0	V
R _{Pull}	Pullup and pulldown resistor ⁽²⁾	For pullup: $V_{IN} = V_{SS}$ For pulldown: $V_{IN} = V_{CC}$		20	35	50	kΩ
CI	Input capacitance	$V_{IN} = V_{SS}$ or V_{CC}			5		pF

⁽¹⁾ Same parametrics apply to clock input pin when crystal bypass mode is used on XT1 (XIN) or XT2 (XT2IN).

5.8 Inputs – Ports P1 and P2⁽¹⁾ (P1.0 to P1.7, P2.0 to P2.7)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V _{cc}	MIN	MAX	UNIT
t _(int)	External interrupt timing (2)	External trigger pulse duration to set interrupt flag	2.2 V, 3 V	20		ns

⁽¹⁾ Some devices may contain additional ports with interrupts. See the block diagram and terminal function descriptions.

5.9 Leakage Current – General-Purpose I/O (P1.0 to P1.7, P2.0 to P2.7, P3.0 to P3.7, P4.0 to P4.7) (P5.0 to P5.7, P6.0 to P6.7, P7.0 to P7.7, P8.0 to P8.2, PJ.0 to PJ.3, RST/NMI)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	MAX	UNIT
$I_{lkg(Px.y)}$	High-impedance leakage current	See (1) (2)	1.8 V, 3 V	-50	50	nA

The leakage current is measured with V_{SS} or V_{CC} applied to the corresponding pin(s), unless otherwise noted.

5.10 Outputs – General-Purpose I/O (Full Drive Strength) (P1.0 to P1.7, P2.0 to P2.7, P3.0 to P3.7, P4.0 to P4.7, P5.0 to P5.7, P6.0 to P6.7, P7.0 to P7.7, P8.0 to P8.2, PJ.0 to PJ.3)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	MAX	UNIT
		$I_{(OHmax)} = -3 \text{ mA}^{(1)}$	1.8 V	V _{CC} - 0.25	V_{CC}	
V _{OH}	High-level output voltage	$I_{(OHmax)} = -10 \text{ mA}^{(2)}$	1.0 V	$V_{CC} - 0.60$	V_{CC}	
	(see Figure 5-8 and Figure 5-9)	ure 5-8 and Figure 5-9) $I_{(OHmax)} = -5 \text{ mA}^{(1)}$ $V_{CC} = 0.0$	V _{CC} - 0.25	V_{CC}	V	
		$I_{(OHmax)} = -15 \text{ mA}^{(2)}$	3 V	V _{CC} - 0.60	V_{CC}	
		$I_{(OLmax)} = 3 \text{ mA}^{(1)}$	1.8 V	V _{SS}	$V_{SS} + 0.25$	V
V	Low-level output voltage	$I_{(OLmax)} = 10 \text{ mA}^{(2)}$		V _{SS}	$V_{SS} + 0.60$	
V _{OL}	(see Figure 5-6 and Figure 5-7)	$I_{(OLmax)} = 5 \text{ mA}^{(1)}$	3 V	V _{SS}	$V_{SS} + 0.25$	
		$I_{(OLmax)} = 15 \text{ mA}^{(2)}$	3 V	V _{SS}	V _{SS} + 0.60	

⁽¹⁾ The maximum total current, I_(OHmax) and I_(OLmax), for all outputs combined should not exceed ±48 mA to hold the maximum voltage drop specified.

⁽²⁾ Also applies to RST pin when pullup or pulldown resistor is enabled.

⁽²⁾ An external signal sets the interrupt flag every time the minimum interrupt pulse duration t_(int) is met. It may be set by trigger signals shorter than t_(int).

⁽²⁾ The leakage of the digital port pins is measured individually. The port pin is selected for input and the pullup or pulldown resistor is disabled.

⁽²⁾ The maximum total current, I_(OHmax) and I_(OLmax), for all outputs combined should not exceed ±100 mA to hold the maximum voltage drop specified.



5.11 Outputs – General-Purpose I/O (Reduced Drive Strength) (P1.0 to P1.7, P2.0 to P2.7, P3.0 to P3.7, P4.0 to P4.7, P5.0 to P5.7, P6.0 to P6.7, P7.0 to P7.7, P8.0 to P8.2, PJ.0 to PJ.3)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)(1)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	MAX	UNIT
		$I_{(OHmax)} = -1 \text{ mA}^{(2)}$	101/	V _{CC} - 0.25	V_{CC}	
V _{OH}	High-level output voltage	1.6 V	V _{CC} - 0.60	V_{CC}	V	
	(see Figure 5-4 and Figure 5-5)	$I_{(OHmax)} = -2 \text{ mA}^{(2)}$	3.0 V	V _{CC} - 0.25	V_{CC}	
		$I_{(OHmax)} = -6 \text{ mA}^{(3)}$		V _{CC} - 0.60	V_{CC}	
		I _(OLmax) = 1 mA ⁽²⁾	1.8 V	V _{SS}	V _{SS} + 0.25	V
.,		I _(OLmax) = 3 mA ⁽³⁾		V _{SS}	V _{SS} + 0.60	
V_{OL}	(see Figure 5-2 and Figure 5-3)	$I_{(OLmax)} = 2 \text{ mA}^{(2)}$	201/	V _{SS}	V _{SS} + 0.25	
		$I_{(OLmax)} = 6 \text{ mA}^{(3)}$	3.0 V	V _{SS}	V _{SS} + 0.60	

Selecting reduced drive strength may reduce EMI.

5.12 Output Frequency – General-Purpose I/O (P1.0 to P1.7, P2.0 to P2.7, P3.0 to P3.7, P4.0 to P4.7, P5.0 to P5.7, P6.0 to P6.7, P7.0 to P7.7, P8.0 to P8.2, PJ.0 to PJ.3)

	PARAMETER	TEST CONDITIONS		MIN	MAX	UNIT
f _{Px.y}	Port output frequency (with load)	See ⁽¹⁾⁽²⁾	V _{CC} = 1.8 V, PMMCOREVx = 0		16	NAL I-
		See VVV	V _{CC} = 3 V, PMMCOREVx = 3		25	MHz
f _{Port_CLK}	Clock output frequency	ACLK, SMCLK, MCLK,	V _{CC} = 1.8 V, PMMCOREVx = 0		16	MHz
		ACLK, SMCLK, MCLK, $C_L = 20 \text{ pF}^{(2)}$	V _{CC} = 3 V, PMMCOREVx = 3		25	IVIIIZ

⁽¹⁾ A resistive divider with 2 x R1 between V_{CC} and V_{SS} is used as load. The output is connected to the center tap of the divider. For full drive strength, R1 = 550 Ω. For reduced drive strength, R1 = 1.6 kΩ. C_L = 20 pF is connected to the output to V_{SS}.

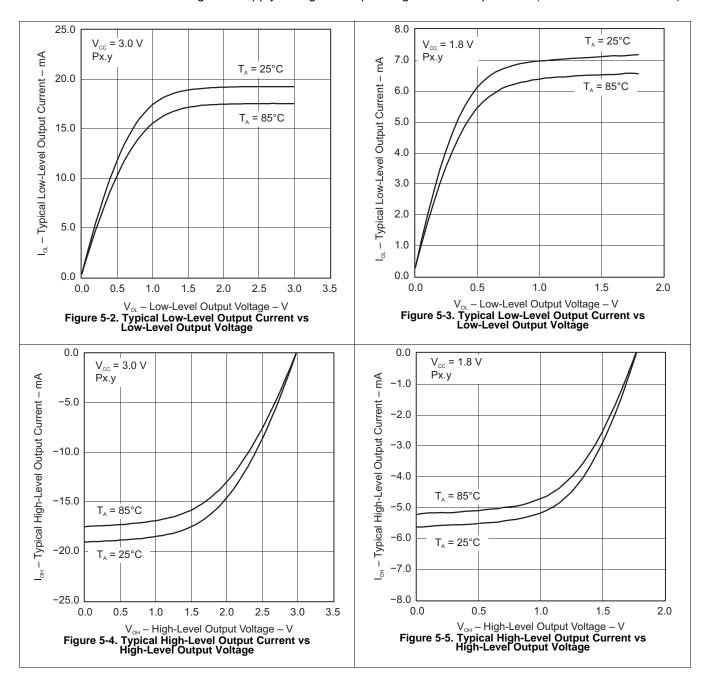
⁽²⁾ The maximum total current, I_(OHmax) and I_(OLmax), for all outputs combined, should not exceed ±48 mA to hold the maximum voltage drop specified.

⁽³⁾ The maximum total current, I_(OHmax) and I_(OLmax), for all outputs combined, should not exceed ±100 mA to hold the maximum voltage drop specified.

⁽²⁾ The output voltage reaches at least 10% and 90% V_{CC} at the specified toggle frequency.

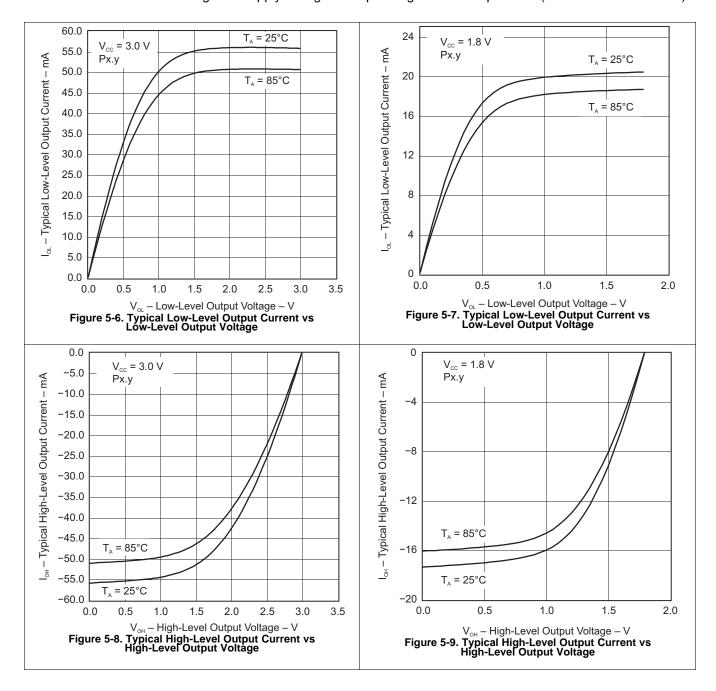


5.13 Typical Characteristics – Outputs, Reduced Drive Strength (PxDS.y = 0)





5.14 Typical Characteristics – Outputs, Full Drive Strength (PxDS.y = 1)





5.15 Crystal Oscillator, XT1, Low-Frequency Mode⁽¹⁾

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
	Differential XT1 oscillator	f_{OSC} = 32768 Hz, XTS = 0, XT1BYPASS = 0, XT1DRIVEx = 1, T_A = 25°C			0.075		
$\Delta I_{DVCC.LF}$	crystal current consumption from lowest drive setting, LF	f_{OSC} = 32768 Hz, XTS = 0, XT1BYPASS = 0, XT1DRIVEx = 2, T_A = 25°C	3.0 V		0.170		μΑ
	mode	f_{OSC} = 32768 Hz, XTS = 0, XT1BYPASS = 0, XT1DRIVEx = 3, T_A = 25°C			0.290		
f _{XT1,LF0}	XT1 oscillator crystal frequency, LF mode	XTS = 0, XT1BYPASS = 0			32768		Hz
f _{XT1,LF,SW}	XT1 oscillator logic-level square-wave input frequency, LF mode	XTS = 0, XT1BYPASS = 1 ⁽²⁾ (3)		10	32.768	50	kHz
OA _{LF}	Oscillation allowance for LF crystals ⁽⁴⁾	$XTS = 0$, $XT1BYPASS = 0$, $XT1DRIVEx = 0$, $f_{XT1,LF} = 32768$ Hz, $C_{L,eff} = 6$ pF			210		kΩ
		$XTS = 0$, $XT1BYPASS = 0$, $XT1DRIVEx = 1$, $f_{XT1,LF} = 32768$ Hz, $C_{L,eff} = 12$ pF			300		K22
		$XTS = 0$, $XCAPx = 0^{(6)}$			1		
0	Integrated effective load	XTS = 0, XCAPx = 1			5.5		_
$C_{L,eff}$	capacitance, LF mode (5)	XTS = 0, XCAPx = 2			8.5		pF
		XTS = 0, XCAPx = 3			12.0		•
	Duty cycle, LF mode	XTS = 0, Measured at ACLK, $f_{XT1,LF} = 32768 \text{ Hz}$		30%		70%	
f _{Fault,LF}	Oscillator fault frequency, LF mode ⁽⁷⁾	$XTS = 0^{(8)}$		10		10000	Hz
	Start-up time, LF mode	f_{OSC} = 32768 Hz, XTS = 0, XT1BYPASS = 0, XT1DRIVEx = 0, T _A = 25°C, C _{L,eff} = 6 pF	201/		1000		
t _{START,LF}		f _{OSC} = 32768 Hz, XTS = 0, XT1BYPASS = 0, XT1DRIVEx = 3, T _A = 25°C, C _{L,eff} = 12 pF	3.0 V		500		ms

- (1) To improve EMI on the XT1 oscillator, the following guidelines should be observed.
 - Keep the trace between the device and the crystal as short as possible.
 - Design a good ground plane around the oscillator pins.
 - Prevent crosstalk from other clock or data lines into oscillator pins XIN and XOUT.
 - Avoid running PCB traces underneath or adjacent to the XIN and XOUT pins.
 - Use assembly materials and processes that avoid any parasitic load on the oscillator XIN and XOUT pins.
 - If conformal coating is used, ensure that it does not induce capacitive or resistive leakage between the oscillator pins.
- (2) When XT1BYPASS is set, XT1 circuits are automatically powered down. Input signal is a digital square wave with parametrics defined in the Schmitt-trigger Inputs section of this data sheet.
- (3) Maximum frequency of operation of the entire device cannot be exceeded.
- Oscillation allowance is based on a safety factor of 5 for recommended crystals. The oscillation allowance is a function of the XT1DRIVEx settings and the effective load. In general, comparable oscillator allowance can be achieved based on the following guidelines, but should be evaluated based on the actual crystal selected for the application:

 - For XT1DRIVEx = 0, $C_{L,eff} \le 6$ pF. For XT1DRIVEx = 1, 6 pF $\le C_{L,eff} \le 9$ pF.
- For XT1DRIVEx = 2, 6 pF ≤ C_{L,eff} ≤ 10 pF.
 For XT1DRIVEx = 3, C_{L,eff} ≥ 6 pF.
 Includes parasitic bond and package capacitance (approximately 2 pF per pin).
 - Because the PCB adds additional capacitance, verify the correct load by measuring the ACLK frequency. For a correct setup, the effective load capacitance should always match the specification of the used crystal.
- Requires external capacitors at both terminals. Values are specified by crystal manufacturers.
- Frequencies below the MIN specification set the fault flag. Frequencies above the MAX specification do not set the fault flag. Frequencies between the MIN and MAX specifications might set the flag.
- Measured with logic-level input frequency but also applies to operation with crystals.



5.16 Crystal Oscillator, XT2

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT	
		$f_{OSC} = 4 \text{ MHz}, \text{ XT2OFF} = 0, \text{ XT2BYPASS} = 0, \text{ XT2DRIVEx} = 0, \text{ T}_{A} = 25^{\circ}\text{C}$			200			
	XT2 oscillator crystal	f_{OSC} = 12 MHz, XT2OFF = 0, XT2BYPASS = 0, XT2DRIVEx = 1, T_A = 25°C	3.0 V		260		μA	
I _{DVCC.XT2}	current consumption	f_{OSC} = 20 MHz, XT2OFF = 0, XT2BYPASS = 0, XT2DRIVEx = 2, T_A = 25°C	3.0 V		325		μΑ	
		f_{OSC} = 32 MHz, XT2OFF = 0, XT2BYPASS = 0, XT2DRIVEx = 3, T_A = 25°C			450			
f _{XT2,HF0}	XT2 oscillator crystal frequency, mode 0	XT2DRIVEx = 0, XT2BYPASS = 0 ⁽³⁾		4		8	MHz	
f _{XT2,HF1}	XT2 oscillator crystal frequency, mode 1	XT2DRIVEx = 1, XT2BYPASS = 0 ⁽³⁾		8		16	MHz	
f _{XT2,HF2}	XT2 oscillator crystal frequency, mode 2	XT2DRIVEx = 2, XT2BYPASS = 0 ⁽³⁾		16		24	MHz	
f _{XT2,HF3}	XT2 oscillator crystal frequency, mode 3	XT2DRIVEx = 3, XT2BYPASS = 0 ⁽³⁾		24		32	MHz	
f _{XT2,HF,SW}	XT2 oscillator logic-level square-wave input frequency, bypass mode	XT2BYPASS = 1 ⁽⁴⁾ (3)		0.7		32	MHz	
	Oscillation allowance for	$XT2DRIVEx = 0$, $XT2BYPASS = 0$, $f_{XT2,HF0} = 6$ MHz, $C_{L,eff} = 15$ pF			450			
04		$XT2DRIVEx = 1$, $XT2BYPASS = 0$, $f_{XT2,HF1} = 12$ MHz, $C_{L,eff} = 15$ pF			320		0	
OA _{HF}	HF crystals ⁽⁵⁾	$XT2DRIVEx = 2$, $XT2BYPASS = 0$, $f_{XT2,HF2} = 20$ MHz, $C_{L,eff} = 15$ pF			200		Ω	
		$XT2DRIVEx = 3$, $XT2BYPASS = 0$, $f_{XT2,HF3} = 32$ MHz, $C_{L,eff} = 15$ pF			200			
	Chart was time a	$f_{OSC} = 6$ MHz, XT2BYPASS = 0, XT2DRIVEx = 0, $T_A = 25$ °C, $C_{L,eff} = 15$ pF	3.0 V		0.5			
^t START,HF	Start-up time	f_{OSC} = 20 MHz, XT2BYPASS = 0, XT2DRIVEx = 2, T_A = 25°C, $C_{L,eff}$ = 15 pF	3.0 V		0.3		ms	
$C_{L,eff}$	Integrated effective load capacitance, HF mode ^{(6) (1)}				1		pF	
	Duty cycle	Measured at ACLK, f _{XT2,HF2} = 20 MHz		40%	50%	60%		
f _{Fault,HF}	Oscillator fault frequency ⁽⁷⁾	XT2BYPASS = 1 ⁽⁸⁾		30		300	kHz	

- (1) Requires external capacitors at both terminals. Values are specified by crystal manufacturers. In general, an effective load capacitance of up to 18 pF can be supported.
- (2) To improve EMI on the XT2 oscillator the following guidelines should be observed.
 - Keep the traces between the device and the crystal as short as possible.
 - Design a good ground plane around the oscillator pins.
 - Prevent crosstalk from other clock or data lines into oscillator pins XT2IN and XT2OUT.
 - Avoid running PCB traces underneath or adjacent to the XT2IN and XT2OUT pins.
 - Use assembly materials and processes that avoid any parasitic load on the oscillator XT2IN and XT2OUT pins.
 - If conformal coating is used, ensure that it does not induce capacitive or resistive leakage between the oscillator pins.
- (3) This represents the maximum frequency that can be input to the device externally. Maximum frequency achievable on the device operation is based on the frequencies present on ACLK, MCLK, and SMCLK cannot be exceed for a given range of operation.
- (4) When XT2BYPASS is set, the XT2 circuit is automatically powered down. Input signal is a digital square wave with parametrics defined in the Schmitt-trigger Inputs section of this data sheet.
- (5) Oscillation allowance is based on a safety factor of 5 for recommended crystals.
- (6) Includes parasitic bond and package capacitance (approximately 2 pF per pin). Because the PCB adds additional capacitance, verify the correct load by measuring the ACLK frequency. For a correct setup, the effective load capacitance should always match the specification of the used crystal.
- (7) Frequencies below the MIN specification set the fault flag. Frequencies above the MAX specification do not set the fault flag. Frequencies between the MIN and MAX specifications might set the flag.
- 8) Measured with logic-level input frequency but also applies to operation with crystals.



5.17 Internal Very-Low-Power Low-Frequency Oscillator (VLO)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	TYP	MAX	UNIT
f_{VLO}	VLO frequency	Measured at ACLK	1.8 V to 3.6 V	6	9.4	14	kHz
df_{VLO}/d_{T}	VLO frequency temperature drift	Measured at ACLK ⁽¹⁾	1.8 V to 3.6 V		0.5		%/°C
df_{VLO}/dV_{CC}	VLO frequency supply voltage drift	Measured at ACLK ⁽²⁾	1.8 V to 3.6 V		4		%/V
	Duty cycle	Measured at ACLK	1.8 V to 3.6 V	40%	50%	60%	

Calculated using the box method: (MAX(-40° C to 85° C) – MIN(-40° C to 85° C)) / MIN(-40° C to 85° C) / (85° C – (-40° C)) Calculated using the box method: (MAX(1.8 V to 3.6 V) – MIN(1.8 V to 3.6 V)) / MIN(1.8 V to 3.6 V) / (3.6 V – 1.8 V)

5.18 Internal Reference, Low-Frequency Oscillator (REFO)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	TYP	MAX	UNIT
I _{REFO}	REFO oscillator current consumption	T _A = 25°C	1.8 V to 3.6 V		3		μΑ
f _{REFO}	REFO frequency calibrated	Measured at ACLK	1.8 V to 3.6 V		32768		Hz
	REFO absolute tolerance calibrated	Full temperature range	1.8 V to 3.6 V	-3.5%		3.5%	
		T _A = 25°C	3 V	-1.5%		1.5%	
df_{REFO}/d_{T}	REFO frequency temperature drift	Measured at ACLK ⁽¹⁾	1.8 V to 3.6 V		0.01		%/°C
df_{REFO}/dV_{CC}	REFO frequency supply voltage drift	Measured at ACLK ⁽²⁾	1.8 V to 3.6 V		1.0		%/V
	Duty cycle	Measured at ACLK	1.8 V to 3.6 V	40%	50%	60%	
t _{START}	REFO start-up time	40%/60% duty cycle	1.8 V to 3.6 V		25		μs

Calculated using the box method: $(MAX(-40^{\circ}C \text{ to } 85^{\circ}C) - MIN(-40^{\circ}C \text{ to } 85^{\circ}C)) / MIN(-40^{\circ}C \text{ to } 85^{\circ}C) / (85^{\circ}C - (-40^{\circ}C))$

Calculated using the box method: (MAX(1.8 V to 3.6 V) – MIN(1.8 V to 3.6 V)) / MIN(1.8 V to 3.6 V) / (3.6 V – 1.8 V)



5.19 DCO Frequency

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
f _{DCO(0,0)}	DCO frequency (0, 0) ⁽¹⁾	DCORSELx = 0, DCOx = 0, MODx = 0	0.07		0.20	MHz
f _{DCO(0,31)}	DCO frequency (0, 31) ⁽¹⁾	DCORSELx = 0, DCOx = 31, MODx = 0	0.70		1.70	MHz
f _{DCO(1,0)}	DCO frequency (1, 0) ⁽¹⁾	DCORSELx = 1, $DCOx = 0$, $MODx = 0$	0.15		0.36	MHz
f _{DCO(1,31)}	DCO frequency (1, 31) ⁽¹⁾	DCORSELx = 1, DCOx = 31, MODx = 0	1.47		3.45	MHz
f _{DCO(2,0)}	DCO frequency (2, 0) ⁽¹⁾	DCORSELx = 2, $DCOx = 0$, $MODx = 0$	0.32		0.75	MHz
f _{DCO(2,31)}	DCO frequency (2, 31) ⁽¹⁾	DCORSELx = 2, $DCOx = 31$, $MODx = 0$	3.17		7.38	MHz
f _{DCO(3,0)}	DCO frequency (3, 0) ⁽¹⁾	DCORSELx = 3, $DCOx = 0$, $MODx = 0$	0.64		1.51	MHz
f _{DCO(3,31)}	DCO frequency (3, 31) ⁽¹⁾	DCORSELx = 3, DCOx = 31, MODx = 0	6.07		14.0	MHz
f _{DCO(4,0)}	DCO frequency (4, 0) ⁽¹⁾	DCORSELx = 4, $DCOx = 0$, $MODx = 0$	1.3		3.2	MHz
f _{DCO(4,31)}	DCO frequency (4, 31) ⁽¹⁾	DCORSELx = 4, DCOx = 31, MODx = 0	12.3		28.2	MHz
f _{DCO(5,0)}	DCO frequency (5, 0) ⁽¹⁾	DCORSELx = 5, DCOx = 0, MODx = 0	2.5		6.0	MHz
f _{DCO(5,31)}	DCO frequency (5, 31) ⁽¹⁾	DCORSELx = 5, DCOx = 31, MODx = 0	23.7		54.1	MHz
f _{DCO(6,0)}	DCO frequency (6, 0) ⁽¹⁾	DCORSELx = 6, DCOx = 0, MODx = 0	4.6		10.7	MHz
f _{DCO(6,31)}	DCO frequency (6, 31) ⁽¹⁾	DCORSELx = 6, DCOx = 31, MODx = 0	39.0		88.0	MHz
f _{DCO(7,0)}	DCO frequency (7, 0) ⁽¹⁾	DCORSELx = 7, DCOx = 0, MODx = 0	8.5		19.6	MHz
f _{DCO(7,31)}	DCO frequency (7, 31) ⁽¹⁾	DCORSELx = 7, DCOx = 31, MODx = 0	60		135	MHz
S _{DCORSEL}	Frequency step between range DCORSEL and DCORSEL + 1	$S_{RSEL} = f_{DCO(DCORSEL+1,DCO)}/f_{DCO(DCORSEL,DCO)}$	1.2		2.3	ratio
S _{DCO}	Frequency step between tap DCO and DCO + 1	$S_{DCO} = f_{DCO(DCORSEL,DCO+1)}/f_{DCO(DCORSEL,DCO)}$	1.02		1.12	ratio
	Duty cycle	Measured at SMCLK	40%	50%	60%	
df _{DCO} /dT	DCO frequency temperature drift ⁽²⁾	f _{DCO} = 1 MHz		0.1		%/°C
df _{DCO} /dV _{CC}	DCO frequency voltage drift ⁽³⁾	f _{DCO} = 1 MHz		1.9		%/V

- (1) When selecting the proper DCO frequency range (DCORSELx), the target DCO frequency, f_{DCO}, should be set to reside within the range of f_{DCO(n, 0),MAX} ≤ f_{DCO} ≤ f_{DCO(n, 31),MIN}, where f_{DCO(n, 0),MAX} represents the maximum frequency specified for the DCO frequency, range n, tap 0 (DCOx = 0) and f_{DCO(n,31),MIN} represents the minimum frequency specified for the DCO frequency, range n, tap 31 (DCOx = 31). This ensures that the target DCO frequency resides within the range selected. It should also be noted that if the actual f_{DCO} frequency for the selected range causes the FLL or the application to select tap 0 or 31, the DCO fault flag is set to report that the selected range is at its minimum or maximum tap setting.
- (2) Calculated using the box method: (MAX(-40°C to 85°C) MIN(-40°C to 85°C)) / MIN(-40°C to 85°C) / (85°C (-40°C))
- (3) Calculated using the box method: (MAX(1.8 V to 3.6 V) MIN(1.8 V to 3.6 V)) / MIN(1.8 V to 3.6 V) / (3.6 V 1.8 V)

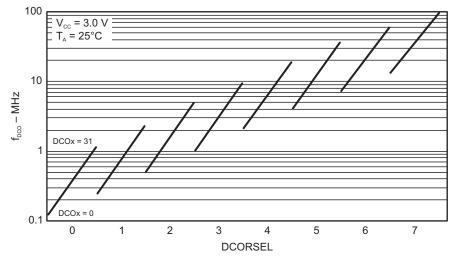


Figure 5-10. Typical DCO Frequency



5.20 PMM, Brownout Reset (BOR)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _(DVCC_BOR_IT-)	BOR _H on voltage, DV _{CC} falling level	$\mid dDV_{CC}/d_t \mid < 3 \text{ V/s}$			1.45	V
V _(DVCC_BOR_IT+)	BOR _H off voltage, DV _{CC} rising level	$\mid dDV_{CC}/d_t \mid < 3 \text{ V/s}$	0.80	1.30	1.50	V
V _(DVCC_BOR_hys)	BOR _H hysteresis		50		250	mV
t _{RESET}	Pulse duration required at RST/NMI pin to accept a reset		2			μs

5.21 PMM, Core Voltage

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN TYP MAX	UNIT
V _{CORE3} (AM)	Core voltage, active mode, PMMCOREV = 3	$2.4 \text{ V} \leq \text{DV}_{\text{CC}} \leq 3.6 \text{ V}$	1.90	V
V _{CORE2} (AM)	Core voltage, active mode, PMMCOREV = 2	$2.2 \text{ V} \leq \text{DV}_{\text{CC}} \leq 3.6 \text{ V}$	1.80	V
V _{CORE1} (AM)	Core voltage, active mode, PMMCOREV = 1	$2.0 \text{ V} \leq \text{DV}_{\text{CC}} \leq 3.6 \text{ V}$	1.60	V
V _{CORE0} (AM)	Core voltage, active mode, PMMCOREV = 0	$1.8 \text{ V} \leq \text{DV}_{\text{CC}} \leq 3.6 \text{ V}$	1.40	V
V _{CORE3} (LPM)	Core voltage, low-current mode, PMMCOREV = 3	$2.4 \text{ V} \leq \text{DV}_{\text{CC}} \leq 3.6 \text{ V}$	1.94	V
V _{CORE2} (LPM)	Core voltage, low-current mode, PMMCOREV = 2	$2.2 \text{ V} \leq \text{DV}_{\text{CC}} \leq 3.6 \text{ V}$	1.84	V
V _{CORE1} (LPM)	Core voltage, low-current mode, PMMCOREV = 1	$2.0 \text{ V} \leq \text{DV}_{\text{CC}} \leq 3.6 \text{ V}$	1.64	V
V _{CORE0} (LPM)	Core voltage, low-current mode, PMMCOREV = 0	$1.8 \text{ V} \leq \text{DV}_{\text{CC}} \leq 3.6 \text{ V}$	1.44	V

5.22 PMM, SVS High Side

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		SVSHE = 0, DV _{CC} = 3.6 V		0		» A
I _(SVSH)	SVS current consumption	$SVSHE = 1$, $DV_{CC} = 3.6 V$, $SVSHFP = 0$		200		nA
		SVSHE = 1, DV_{CC} = 3.6 V, $SVSHFP$ = 1		1.5		μΑ
		SVSHE = 1, SVSHRVL = 0	1.57	1.68	1.78	
.,	SVS _H on voltage level ⁽¹⁾	SVSHE = 1, SVSHRVL = 1	1.79	1.88	1.98	V
V _(SVSH_IT-)		SVSHE = 1, SVSHRVL = 2	1.98	2.08	2.21	
		SVSHE = 1, SVSHRVL = 3	2.10	2.18	2.31	
		SVSHE = 1, SVSMHRRL = 0	1.62	1.74	1.85	
	SVS _H off voltage level ⁽¹⁾	SVSHE = 1, SVSMHRRL = 1	1.88	1.94	2.07	V
		SVSHE = 1, SVSMHRRL = 2	2.07	2.14	2.28	
.,		SVSHE = 1, SVSMHRRL = 3	2.20	2.30	2.42	
V _(SVSH_IT+)		SVSHE = 1, SVSMHRRL = 4	2.32	2.40	2.55	V
		SVSHE = 1, SVSMHRRL = 5	2.52	2.70	2.88	
		SVSHE = 1, SVSMHRRL = 6	2.90	3.10	3.23	
		SVSHE = 1, SVSMHRRL = 7	2.90	3.10	3.23	
	CV/C managedian dalay	SVSHE = 1, dV _{DVCC} /dt = 10 mV/µs, SVSHFP = 1		2.5		
t _{pd} (SVSH)	SVS _H propagation delay	SVSHE = 1, $dV_{DVCC}/dt = 1 \text{ mV/}\mu\text{s}$, SVSHFP = 0		20		μs
	CV/C an arraff dalay time	SVSHE = $0 \rightarrow 1$, SVSHFP = 1		12.5		
t _(SVSH)	SVS _H on or off delay time	SVSHE = $0 \rightarrow 1$, SVSHFP = 0		100		μs
dV _{DVCC} /dt	DVCC rise time		0		1000	V/s

⁽¹⁾ The SVS_H settings available depend on the VCORE (PMMCOREVx) setting. See the Power Management Module and Supply Voltage Supervisor chapter in the MSP430F5xx and MSP430F6xx Family User's Guide on recommended settings and use.



5.23 PMM, SVM High Side

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		SVMHE = 0, DV _{CC} = 3.6 V		0		~ ^
I _(SVMH)	SVM _H current consumption	SVMHE= 1, DV _{CC} = 3.6 V, SVMHFP = 0		200		nA
		SVMHE = 1, DV _{CC} = 3.6 V, SVMHFP = 1		1.5		μΑ
		SVMHE = 1, SVSMHRRL = 0	1.62	1.74	1.85	
		SVMHE = 1, SVSMHRRL = 1	1.88	1.94	2.07	
	SVM _H on or off voltage level ⁽¹⁾	SVMHE = 1, SVSMHRRL = 2	2.07	2.14	2.28	
		SVMHE = 1, SVSMHRRL = 3	2.20	2.30	2.42	
V _(SVMH)		SVMHE = 1, SVSMHRRL = 4	2.32	2.40	2.55	V
		SVMHE = 1, SVSMHRRL = 5	2.52	2.70	2.88	
		SVMHE = 1, SVSMHRRL = 6	2.90	3.10	3.23	
		SVMHE = 1, SVSMHRRL = 7	2.90	3.10	3.23	
		SVMHE = 1, SVMHOVPE = 1		3.75		
	CV/M recognition dolor.	SVMHE = 1, dV _{DVCC} /dt = 10 mV/µs, SVMHFP = 1		2.5		
t _{pd(SVMH)}	SVM _H propagation delay	SVMHE = 1, dV _{DVCC} /dt = 1 mV/µs, SVMHFP = 0		20		μs
	CV/M on or off doloy time	SVMHE = 0 → 1, SVMHFP = 1		12.5		
t _(SVMH)	SVM _H on or off delay time	SVMHE = $0 \rightarrow 1$, SVMHFP = 0		100		μs

⁽¹⁾ The SVM_H settings available depend on the VCORE (PMMCOREVx) setting. See the *Power Management Module and Supply Voltage Supervisor* chapter in the *MSP430F5xx and MSP430F6xx Family User's Guide* on recommended settings and use.

5.24 PMM, SVS Low Side

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
I _(SVSL)	SVS _L current consumption	SVSLE = 0, PMMCOREV = 2		0		nA	
		SVSLE = 1, PMMCOREV = 2, SVSLFP = 0		200			
		SVSLE = 1, PMMCOREV = 2, SVSLFP = 1		1.5		μΑ	
t _{pd(SVSL)}	CVC proposition dolor	SVSLE = 1, dV _{CORE} /dt = 10 mV/µs, SVSLFP = 1		2.5		5	
	SVS _L propagation delay	SVSLE = 1, dV _{CORE} /dt = 1 mV/µs, SVSLFP = 0		20		μs	
t _(SVSL)	CVC on or off dolov time	SVSLE = $0 \rightarrow 1$, $dV_{CORE}/dt = 10 \text{ mV/}\mu\text{s}$, SVSLFP = 1	12.5				
	SVS _L on or off delay time	SVSLE = $0 \rightarrow 1$, $dV_{CORE}/dt = 1$ mV/ μ s, SVSLFP = 0		100		μs	

5.25 PMM, SVM Low Side

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
I _(SVML)	SVM _L current consumption	SVMLE = 0, PMMCOREV = 2	0				
		SVMLE= 1, PMMCOREV = 2, SVMLFP = 0		200		nA	
		SVMLE= 1, PMMCOREV = 2, SVMLFP = 1		1.5		μΑ	
t _{pd(SVML)}	SVM _L propagation delay	SVMLE = 1, dV _{CORE} /dt = 10 mV/µs, SVMLFP = 1	2.5				
		SVMLE = 1, dV _{CORE} /dt = 1 mV/µs, SVMLFP = 0		20		μs	
t _(SVML)	SVM _L on or off delay time	SVMLE = $0 \rightarrow 1$, $dV_{CORE}/dt = 10 \text{ mV/}\mu\text{s}$, SVMLFP = 1		12.5			
		SVMLE = $0 \rightarrow 1$, $dV_{CORE}/dt = 1 \text{ mV/}\mu\text{s}$, SVMLFP = 0		100		μs	



5.26 Wake-up Times From Low-Power Modes and Reset

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIO	NS	MIN	TYP	MAX	UNIT
	Wake-up time from LPM2,	PMMCOREV = SVSMLRRL = n	f _{MCLK} ≥ 4.0 MHz		3.5	7.5	
t _{WAKE-UP-FAST}	LPM3, or LPM4 to active mode ⁽¹⁾	(where n = 0, 1, 2, or 3), SVSLFP = 1	1.0 MHz < f _{MCLK} < 4.0 MHz		4.5	9	μs
twake-up-slow	Wake-up time from LPM2, LPM3 or LPM4 to active mode ⁽²⁾⁽³⁾	PMMCOREV = SVSMLRRL = n (where n = 0, 1, 2, or 3), SVSLFP	= 0		150	165	μs
t _{WAKE-UP-LPM5}	Wake-up time from LPM4.5 to active mode (4)				2	3	ms
t _{WAKE-UP-RESET}	Wake-up time from RST or BOR event to active mode (4)				2	3	ms

⁽¹⁾ This value represents the time from the wake-up event to the first active edge of MCLK. The wake-up time depends on the performance mode of the low-side supervisor (SVS_L) and low-side monitor (SVM_L). t_{WAKE-UP-FAST} is possible with SVS_L and SVM_L in full performance mode or disabled. For specific register settings, see the Low-Side SVS and SVM Control and Performance Mode Selection section in the Power Management Module and Supply Voltage Supervisor chapter of the MSP430F5xx and MSP430F6xx Family User's Guide.

- (2) This value represents the time from the wake-up event to the first active edge of MCLK. The wake-up time depends on the performance mode of the low-side supervisor (SVS_L) and low-side monitor (SVM_L). t_{WAKE-UP-SLOW} is set with SVS_L and SVM_L in normal mode (low current mode). For specific register settings, see the *Low-Side SVS and SVM Control and Performance Mode Selection* section in the *Power Management Module and Supply Voltage Supervisor* chapter of the *MSP430F5xx and MSP430F6xx Family User's Guide*.
- (3) The wake-up times from LPM0 and LPM1 to AM are not specified. They are proportional to MCLK cycle time but are not affected by the performance mode settings as for LPM2, LPM3, and LPM4.
- (4) This value represents the time from the wake-up event to the reset vector execution.

5.27 Timer_A

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	MAX	UNIT
f _{TA}	Timer_A input clock frequency	Internal: SMCLK or ACLK, External: TACLK, Duty cycle = 50% ±10%	1.8 V, 3 V		25	MHz
t _{TA,cap}	Timer_A capture timing	All capture inputs, minimum pulse duration required for capture	1.8 V, 3 V	20		ns

5.28 Timer B

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN MAX	UNIT
f _{TB}	Timer_B input clock frequency	Internal: SMCLK or ACLK, External: TBCLK, Duty cycle = 50% ±10%	1.8 V, 3 V	2!	5 MHz
t _{TB,cap}	Timer_B capture timing	All capture inputs, minimum pulse duration required for capture	1.8 V, 3 V	20	ns



5.29 USCI (UART Mode) Clock Frequency

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	CONDITIONS	MIN	MAX	UNIT
f _{USCI}	USCI input clock frequency	Internal: SMCLK or ACLK, External: UCLK, Duty cycle = 50% ±10%		f _{SYSTEM}	MHz
f _{BITCLK}	BITCLK clock frequency (equals baud rate in MBaud)			1	MHz

5.30 USCI (UART Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	V _{CC}	MIN	MAX	UNIT
	t _t UART receive deglitch time ⁽¹⁾	2.2 V	50	600	20
		3 V	50	600	ns

⁽¹⁾ Pulses on the UART receive input (UCxRX) shorter than the UART receive dealitch time are suppressed. To ensure that pulses are correctly recognized, their duration should exceed the maximum specification of the deglitch time.

5.31 USCI (SPI Master Mode) Clock Frequency

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
f _{USCI}	USCI input clock frequency	Internal: SMCLK or ACLK, Duty cycle = 50% ±10%		f _{SYSTEM}	MHz

5.32 USCI (SPI Master Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)(1) (see Figure 5-11 and Figure 5-12)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	MAX	UNIT
f _{USCI}	USCI input clock frequency	SMCLK or ACLK, Duty cycle = 50% ±10%			f _{SYSTEM}	MHz
		PMMCOREV = 0	1.8 V	55		
	COMI input data actus tima	FIVIIVICOREV = 0	3.0 V	38		20
t _{SU,MI}	SOMI input data setup time	PMMCOREV = 3	2.4 V	30		ns
		PIVIIVICOREV = 3	3.0 V	25		
		PMMCOREV = 0	1.8 V	0		
	SOMI input data hold time	PIVIIVICOREV = 0	3.0 V	0		ns
t _{HD,MI}		DMMCODEV 2	2.4 V	0		
		PMMCOREV = 3	3.0 V	0		
		UCLK edge to SIMO valid,	1.8 V		20	
	CINAC autout data valid time (2)	C _L = 20 pF, PMMCOREV = 0	3.0 V		18	
t _{VALID,MO}	SIMO output data valid time (2)	UCLK edge to SIMO valid,	2.4 V		16	ns
		$C_L = 20 \text{ pF}, PMMCOREV = 3$	3.0 V		15	
		0 00 5 514400551/ 0	1.8 V	-10		ns
	SIMO output data hold time ⁽³⁾	$C_L = 20 \text{ pF}, \text{PMMCOREV} = 0$	3.0 V	-8		
t _{HD,MO}		C _L = 20 pF, PMMCOREV = 3	2.4 V	-10		
			3.0 V	-8		

 $f_{UCXCLK} = 1/2t_{LO/HI} \ \, \text{with} \ \, t_{LO/HI} \ge max(t_{VALID,MO(USCI)} + t_{SU,SI(Slave)}, \ \, t_{SU,MI(USCI)} + t_{VALID,SO(Slave)}) \\ \text{For the slave parameters} \ \, t_{SU,SI(Slave)} \ \, \text{and} \ \, t_{VALID,SO(Slave)}, \ \, \text{see the SPI parameters of the attached slave}. \\ \text{Specifies the time to drive the next valid data to the SIMO output after the output changing UCLK clock edge. See the timing diagrams}$

in Figure 5-11 and Figure 5-12.

Specifies how long data on the SIMO output is valid after the output changing UCLK clock edge. Negative values indicate that the data on the SIMO output can become invalid before the output changing clock edge observed on UCLK. See the timing diagrams in Figure 5-11 and Figure 5-12.

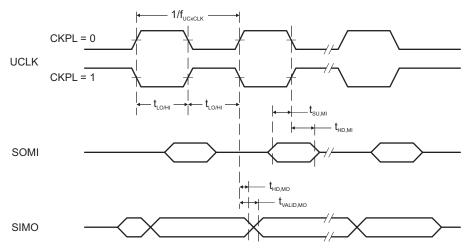


Figure 5-11. SPI Master Mode, CKPH = 0

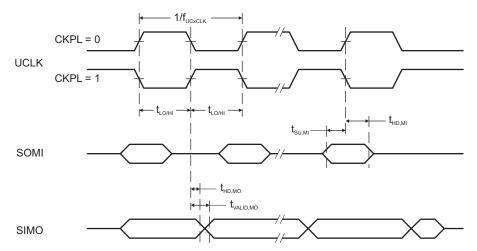


Figure 5-12. SPI Master Mode, CKPH = 1





5.33 USCI (SPI Slave Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (1) (see Figure 5-13 and Figure 5-14)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	MAX	UNIT
		DMMOODEW 0	1.8 V	11		
	OTE lead the OTE levels shade	PMMCOREV = 0	3.0 V	8		
t _{STE,LEAD}	STE lead time, STE low to clock	DMM 400 DEV	2.4 V	7		ns
		PMMCOREV = 3	3.0 V	6		
		DMMOODEV 0	1.8 V	3		
	0.751	PMMCOREV = 0	3.0 V	3		ns
t _{STE,LAG}	STE lag time, Last clock to STE high	DMM 400 DEV	2.4 V	3		
		PMMCOREV = 3	3.0 V	3		
		DMMOODEV 0	1.8 V		66	
	OTE Core OTE levels COMI data and	PMMCOREV = 0	3.0 V		50	
t _{STE,ACC}	STE access time, STE low to SOMI data out		2.4 V		36	ns
		PMMCOREV = 3	3.0 V		30	
		DM 400DEV 0	1.8 V		30	ns
	OTE II II II OTE II I OOMIII I	PMMCOREV = 0	3.0 V		23	
t _{STE,DIS}	STE disable time, STE high to SOMI high impedance	DMM 400 DEV	2.4 V		16	
		PMMCOREV = 3	3.0 V		13	
		PMMCOREV = 0	1.8 V	5		ns
			3.0 V	5		
t _{SU,SI}	SIMO input data setup time	PMMCOREV = 3	2.4 V	2		
			3.0 V	2		
			1.8 V	5		
		PMMCOREV = 0	3.0 V	5		
t _{HD,SI}	SIMO input data hold time		2.4 V	5		ns
		PMMCOREV = 3	3.0 V	5		
		UCLK edge to SOMI valid,	1.8 V		76	
	(2)	$C_L = 20 \text{ pF}, PMMCOREV = 0$	3.0 V		60	
t _{VALID,SO}	SOMI output data valid time (2)	UCLK edge to SOMI valid,	2.4 V		44	ns
		$C_L = 20 \text{ pF}, \text{ PMMCOREV} = 3$	3.0 V		40	
		0 00 5 5 5 4 4 0 0 5 5 7 6	1.8 V	18		
	2011	$C_L = 20 \text{ pF}, \text{ PMMCOREV} = 0$	3.0 V	12		ns
t _{HD,SO}	SOMI output data hold time ⁽³⁾	C _L = 20 pF, PMMCOREV = 3	2.4 V	10		
			3.0 V	8		

 ⁽¹⁾ f_{UCxCLK} = 1/2t_{LO/HI} with t_{LO/HI} ≥ max(t_{VALID,MO(Master)} + t_{SU,SI(USCI)}, t_{SU,MI(Master)} + t_{VALID,SO(USCI)})
 For the master parameters t_{SU,MI(Master)} and t_{VALID,MO(Master)}, see the SPI parameters of the attached master.
 (2) Specifies the time to drive the next valid data to the SOMI output after the output changing UCLK clock edge. See the timing diagrams in Figure 5-13 and Figure 5-14.

Specifies how long data on the SOMI output is valid after the output changing UCLK clock edge. See the timing diagrams in Figure 5-13 and Figure 5-14.

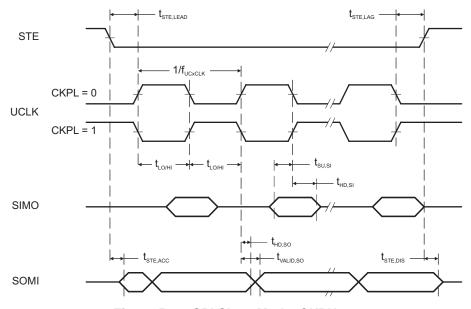


Figure 5-13. SPI Slave Mode, CKPH = 0

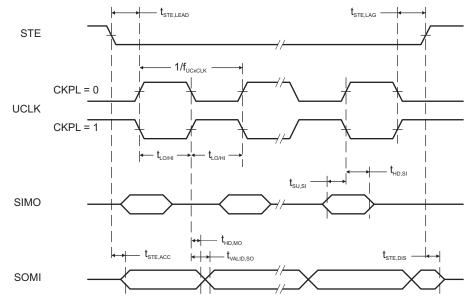


Figure 5-14. SPI Slave Mode, CKPH = 1



5.34 USCI (I²C Mode)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	MAX	UNIT
f _{USCI}	USCI input clock frequency	Internal: SMCLK or ACLK, External: UCLK, Duty cycle = 50% ±10%			f _{SYSTEM}	MHz
f _{SCL}	SCL clock frequency		2.2 V, 3 V	0	400	kHz
	Hold time (repeated) CTART	f _{SCL} ≤ 100 kHz	2.2 V, 3 V	4.0		
t _{HD,STA}	Hold time (repeated) START	$f_{SCL} > 100 \text{ kHz}$	2.2 V, 3 V	0.6		μs
	Setup time for a repeated START	f _{SCL} ≤ 100 kHz	2.2 V, 3 V	4.7		μs
t _{SU,STA}		$f_{SCL} > 100 \text{ kHz}$		0.6		
t _{HD,DAT}	Data hold time		2.2 V, 3 V	0		ns
t _{SU,DAT}	Data setup time		2.2 V, 3 V	250		ns
	Cation time to CTOD	f _{SCL} ≤ 100 kHz	227/27/	4.0		
t _{SU,STO}	Setup time for STOP	f _{SCL} > 100 kHz	2.2 V, 3 V	0.6		μs
	Pulse duration of spikes suppressed by input filter		2.2 V	50	600	ns
t _{SP}			3 V	50	600	

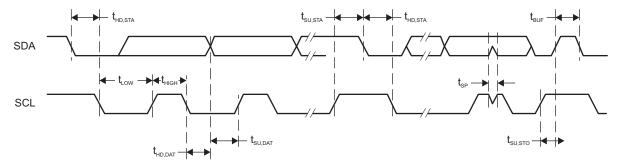


Figure 5-15. I²C Mode Timing



5.35 12-Bit ADC, Power Supply and Input Range Conditions

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)(1)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
AV _{CC}	Analog supply voltage	AVCC and DVCC are connected together, AVSS and DVSS are connected together, $V_{(AVSS)} = V_{(DVSS)} = 0 \text{ V}$		2.2		3.6	V
$V_{(Ax)}$	Analog input voltage range (2)	All ADC12 analog input pins Ax		0		AV_CC	V
	Operating supply current into	f _{ADC12CLK} = 5.0 MHz ⁽⁴⁾	2.2 V		125	155	
I _{ADC12_A}	Operating supply current into AVCC terminal (3)		3 V		150	220	μA
Cı	Input capacitance	Only one terminal Ax can be selected at one time	2.2 V		20	25	pF
R _I	Input MUX ON resistance	0 V ≤ V _{Ax} ≤ AVCC		10	200	1900	Ω

⁽¹⁾ The leakage current is specified by the digital I/O input leakage.

5.36 12-Bit ADC, Timing Parameters

P	ARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
		For specified performance of ADC12 linearity parameters using an external reference voltage or AVCC as reference ⁽¹⁾		0.45	4.8	5.0	
f _{ADC12CLK}	ADC conversion clock	For specified performance of ADC12 linearity parameters using the internal reference (2)	2.2 V, 3 V	0.45	2.4	4.0	MHz
		For specified performance of ADC12 linearity parameters using the internal reference (3)		0.45	2.4	2.7	
f _{ADC12OSC}	Internal ADC12 oscillator (4)	ADC12DIV = 0, f _{ADC12CLK} = f _{ADC12OSC}	2.2 V, 3 V	4.2	4.8	5.4	MHz
	Conversion time	REFON = 0, internal oscillator, ADC12OSC used for ADC conversion clock	2.2 V, 3 V	2.4		3.1	;
tCONVERT	Conversion time	External $f_{ADC12CLK}$ from ACLK, MCLK, or SMCLK, ADC12SSEL $\neq 0$				μs	
t _{Sample}	Sampling time	$R_S = 400 \ \Omega, \ R_I = 1000 \ \Omega, \ C_I = 20 \ pF, $ $t = (R_S + R_I) \times C_I^{(5)}$	2.2 V, 3 V	1000			ns

⁽¹⁾ REFOUT = 0, external reference voltage: SREF2 = 0, SREF1 = 1, SREF0 = 0. AVCC as reference voltage: SREF2 = 0, SREF1 = 0, SREF1 = 0, SREF0 = 0. The specified performance of the ADC12 linearity is ensured when using the ADC12OSC. For other clock sources, the specified performance of the ADC12 linearity is ensured with f_{ADC12CLK} maximum of 5.0 MHz.

⁽²⁾ The analog input voltage range must be within the selected reference voltage range V_{R+} to V_{R-} for valid conversion results. If the reference voltage is supplied by an external source or if the internal reference voltage is used and REFOUT = 1, then decoupling capacitors are required. See Section 5.40 and Section 5.41.

⁽³⁾ The internal reference supply current is not included in current consumption parameter IADC12 A-

⁽⁴⁾ ADC12ON = 1, REFON = 0, SHT0 = 0, SHT1 = 0, ADC12DIV = 0

⁽²⁾ SREF2 = 0, SREF1 = 1, SREF0 = 0, ADC12SR = 0, REFOUT = 1

⁽³⁾ SREF2 = 0, SREF1 = 1, SREF0 = 0, ADC12SR = 0, REFOUT = 0. The specified performance of the ADC12 linearity is ensured when using the ADC12OSC divided by 2.

⁽⁴⁾ The ADC12OSC is sourced directly from MODOSC inside the UCS.

⁽⁵⁾ Approximately 10 Tau (t) are needed to get an error of less than ±0.5 LSB: $t_{Sample} = ln(2^{n+1}) \times (R_S + R_I) \times C_I + 800 \text{ ns, where n} = ADC \text{ resolution} = 12, R_S = \text{external source resistance}$



5.37 12-Bit ADC, Linearity Parameters Using an External Reference Voltage or AVCC as Reference Voltage

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN TYP	MAX	UNIT
г	Integral linearity array(1)	1.4 V ≤ dVREF ≤ 1.6 V ⁽²⁾	2.2 V, 3 V		±2.0	LSB
EI	Integral linearity error ⁽¹⁾	1.6 V < dVREF ⁽²⁾	2.2 V, 3 V		±1.7	LOD
E _D	Differential linearity error ⁽¹⁾	See (2)	2.2 V, 3 V		±1.0	LSB
_	0" : (3)	dVREF ≤ 2.2 V ⁽²⁾	001/01/	±1.0	±2.0	⊢ LSB
Eo	Offset error ⁽³⁾	dVREF > 2.2 V ⁽²⁾	2.2 V, 3 V	±1.0	±2.0	
E _G	Gain error ⁽³⁾	See (2)	2.2 V, 3 V	±1.0	±2.0	LSB
_	Totaladiatad aa	dVREF ≤ 2.2 V ⁽²⁾	001/01/	±1.4	±3.5	LSB
E _T	Total unadjusted error	dVREF > 2.2 V ⁽²⁾	2.2 V, 3 V	±1.4	±3.5	

⁽¹⁾ Parameters are derived using the histogram method.

5.38 12-Bit ADC, Linearity Parameters Using the Internal Reference Voltage

	PARAMETER	TEST COND	TIONS ⁽¹⁾	V _{CC}	MIN	TYP	MAX	UNIT
_	Integral linearity error ⁽²⁾	ADC12SR = 0, REFOUT = 1	f _{ADC12CLK} = 4.0 MHz	001/01/			±1.7	5
El		ADC12SR = 0, REFOUT = 0	f _{ADC12CLK} = 2.7 MHz	2.2 V, 3 V			±2.5	LSB
	E _D Differential linearity error ⁽²⁾	ADC12SR = 0, REFOUT = 1	f _{ADC12CLK} = 4.0 MHz	2.2 V, 3 V	-1.0		+2.0	
E _D		ADC12SR = 0, REFOUT = 1	f _{ADC12CLK} = 2.7 MHz		-1.0		+1.5	-
		ADC12SR = 0, REFOUT = 0	f _{ADC12CLK} = 2.7 MHz		-1.0		+2.5	
_	Offset error ⁽³⁾	ADC12SR = 0, REFOUT = 1	$f_{ADC12CLK} = 4.0 \text{ MHz}$	0.01/.01/		±1.0	±2.0	⊢ LSB ∣
Eo	Offset effor	ADC12SR = 0, REFOUT = 0	f _{ADC12CLK} = 2.7 MHz	2.2 V, 3 V		±1.0	±2.0	
_	Gain error ⁽³⁾	ADC12SR = 0, REFOUT = 1	f _{ADC12CLK} = 4.0 MHz	221/21/		±1.0	±2.0	LSB
E _G	Gain enor	ADC12SR = 0, REFOUT = 0	f _{ADC12CLK} = 2.7 MHz	2.2 V, 3 V			±1.5% ⁽⁴⁾	VREF
_	Total unadjusted	ADC12SR = 0, REFOUT = 1	f _{ADC12CLK} = 4.0 MHz	227/27/		±1.4	±3.5	LSB
E _T	error	ADC12SR = 0, REFOUT = 0	f _{ADC12CLK} = 2.7 MHz	2.2 V, 3 V			±1.5% ⁽⁴⁾	VREF

⁽¹⁾ The internal reference voltage is selected by: SREF2 = 0 or 1, SREF1 = 1, SREF0 = 1. dVREF = V_{R+} - V_{R-}.

The external reference voltage is selected by: SREF2 = 0 or 1, SREF1 = 1, SREF0 = 0. dVREF = V_{R+} - V_{R-}, V_{R+} < AVCC, V_{R-} > AVSS. Unless otherwise mentioned, dVREF > 1.5 V. Impedance of the external reference voltage R < 100 Ω, and two decoupling capacitors, 10 μF and 100 nF, should be connected to VREF+ and VREF- to decouple the dynamic current. Also see the MSP430F5xx and MSP430F6xx Family User's Guide.</p>

⁽³⁾ Parameters are derived using a best fit curve.

⁽²⁾ Parameters are derived using the histogram method.

⁽³⁾ Parameters are derived using a best fit curve.

⁽⁴⁾ The gain error and total unadjusted error are dominated by the accuracy of the integrated reference module absolute accuracy. In this mode the reference voltage used by the ADC12 A is not available on a pin.



5.39 12-Bit ADC, Temperature Sensor and Built-In V_{MID}⁽¹⁾

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	TYP	MAX	UNIT
V	See ⁽²⁾	ADC12ON = 1, INCH = 0Ah,	2.2 V		680		\/
V _{SENSOR}	See (-)	$T_A = 0$ °C	3 V		680		mV
TO		ADCASON A INCL. OAL	2.2 V		2.25		mV/°C
TC _{SENSOR}		ADC12ON = 1, INCH = 0Ah	3 V		2.25		IIIV/ C
SENSOR(sample)	Sample time required if	ADC12ON = 1, INCH = 0Ah, Error of conversion result ≤ 1 LSB	2.2 V	100			
	channel 10 is selected (3)		3 V	100			μs
	AV _{CC} divider at channel 11, V _{AVCC} factor	ADC12ON = 1, INCH = 0Bh		0.48	0.5	0.52	V _{AVCC}
V_{MID}	ANA divides at about 144	ADCASON A INCLL ODI	2.2 V	1.06	1.1	1.14	
	AV _{CC} divider at channel 11	ADC12ON = 1, INCH = 0Bh	3 V	1.44	1.5	1.56	V
t _{VMID(sample)}	Sample time required if channel 11 is selected (4)	ADC12ON = 1, INCH = 0Bh, Error of conversion result ≤ 1 LSB	2.2 V, 3 V	1000			ns

- (1) The temperature sensor is provided by the REF module. See the REF module parametric, I_{REF+}, regarding the current consumption of the temperature sensor.
- (2) The temperature sensor offset can be significant. TI recommends a single-point calibration to minimize the offset error of the built-in temperature sensor. The TLV structure contains calibration values for 30°C ±3°C and 85°C ±3°C for each of the available reference voltage levels. The sensor voltage can be computed as V_{SENSOR} × (Temperature, °C) + V_{SENSOR}, where TC_{SENSOR} and V_{SENSOR} can be computed from the calibration values for higher accuracy. See also the MSP430F5xx and MSP430F6xx Family User's Guide.
- (3) The typical equivalent impedance of the sensor is 51 k Ω . The sample time required includes the sensor-on time $t_{SENSOR(on)}$.
- (4) The on-time t_{VMID(on)} is included in the sampling time t_{VMID(sample)}; no additional on time is needed.

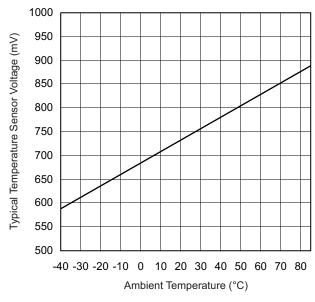


Figure 5-16. Typical Temperature Sensor Voltage



5.40 REF, External Reference

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)(1)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	TYP MAX	UNIT
V _{eREF+}	Positive external reference voltage input	$V_{\text{eREF+}} > V_{\text{REF-}}$ and $V_{\text{eREF-}}$ (2)		1.4	AV_CC	V
V _{REF} -, V _{eREF} -	Negative external reference voltage input	$V_{\text{eREF+}} > V_{\text{REF-}}$ and $V_{\text{eREF-}}$ (3)		0	1.2	V
(V _{eREF+} – V _{REF-} or V _{eREF-})	Differential external reference voltage input	$V_{\text{eREF+}} > V_{\text{REF-}}$ and $V_{\text{eREF-}}$ ⁽⁴⁾		1.4	AV_CC	V
IveREF+, IvREF-, VeREF-	Static input ourrent	$ \begin{array}{l} 1.4~V \leq V_{eREF+} \leq V_{AVCC}, \\ V_{eREF-} = 0~V, ~f_{ADC12CLK} = 5~MHz, \\ ADC12SHTx = 1h, \\ Conversion~rate~200~ksps \end{array} $	22727	-26	26	μΑ
	Static input current	$ \begin{array}{l} 1.4~\text{V} \leq \text{V}_{\text{eREF+}} \leq \text{V}_{\text{AVCC}}, \\ \text{V}_{\text{eREF-}} = 0~\text{V}, \text{f}_{\text{ADC12CLK}} = 5~\text{MHz}, \\ \text{ADC12SHTx} = 8\text{h}, \\ \text{Conversion rate 20 ksps} \\ \end{array} $	2.2 V, 3 V	-1	1	μΑ
C _{VREF+} , C _{VREF-}	Capacitance at V _{VREF+} , V _{VREF-} terminal			⁽⁵⁾ 10		μF

- (1) The external reference is used during ADC conversion to charge and discharge the capacitance array. The input capacitance (C_i) is also the dynamic load for an external reference during conversion. The dynamic impedance of the reference supply should follow the recommendations on analog-source impedance to allow the charge to settle for 12-bit accuracy.
- (2) The accuracy limits the minimum positive external reference voltage. Lower reference voltage levels may be applied with reduced accuracy requirements.
- (3) The accuracy limits the maximum negative external reference voltage. Higher reference voltage levels may be applied with reduced accuracy requirements.
- (4) The accuracy limits minimum external differential reference voltage. Lower differential reference voltage levels may be applied with reduced accuracy requirements.
- (5) Two decoupling capacitors, 10 μF and 100 nF, should be connected to VREF to decouple the dynamic current required for an external reference source if it is used for the ADC12_A. See also the MSP430F5xx and MSP430F6xx Family User's Guide.

5.41 REF, Built-In Reference

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
		REFVSEL = $\{2\}$ for 2.5 V, REFON = REFOUT = 1, $I_{VREF+} = 0$ A	3 V	2.4625	2.50	2.5375	
V _{REF+}	Positive built-in reference voltage output	REFVSEL = $\{1\}$ for 2.0 V, REFON = REFOUT = 1, $I_{VREF+} = 0$ A	3 V	1.9503	1.98	2.0097	V
		REFVSEL = $\{0\}$ for 1.5 V, REFON = REFOUT = 1, $I_{VREF+} = 0$ A	2.2 V, 3 V	1.4677	1.49	1.5124	
	AVCC minimum voltage,	REFVSEL = {0} for 1.5 V		2.2			V
AV _{CC(min)}	Positive built-in reference	REFVSEL = {1} for 2.0 V		2.3			V
	active	REFVSEL = {2} for 2.5 V		2.8			
		ADC12SR = $1^{(4)}$, REFON = 1, REFOUT = 0, REFBURST = 0			70	100	μΑ
	Operating supply current into	ADC12SR = $1^{(4)}$, REFON = 1, REFOUT = 1, REFBURST = 0	3 V		0.45	0.75	mA
I _{REF+}	AVCC terminal (2)(3)	ADC12SR = $0^{(4)}$, REFON = 1, REFOUT = 0, REFBURST = 0	3 V		210	310	μΑ
		ADC12SR = $0^{(4)}$, REFON = 1, REFOUT = 1, REFBURST = 0			0.95	1.7	mA

- (1) The reference is supplied to the ADC by the REF module and is buffered locally inside the ADC. The ADC uses two internal buffers, one smaller and one larger for driving the VREF+ terminal. When REFOUT = 1, the reference is available at the VREF+ terminal, as well as, used as the reference for the conversion and uses the larger buffer. When REFOUT = 0, the reference is only used as the reference for the conversion and uses the smaller buffer.
- (2) The internal reference current is supplied by the AVCC terminal. Consumption is independent of the ADC12ON control bit, unless a conversion is active. REFOUT = 0 represents the current contribution of the smaller buffer. REFOUT = 1 represents the current contribution of the larger buffer without external load.
- (3) The temperature sensor is provided by the REF module. Its current is supplied via terminal AVCC and is equivalent to I_{REF+} with REFON =1 and REFOUT = 0.
- (4) For devices without the ADC12, the parametrics with ADC12SR = 0 are applicable.



REF, Built-In Reference (continued)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
I _{L(VREF+)}	Load-current regulation, VREF+ terminal ⁽⁵⁾	$\label{eq:REFVSEL} \begin{split} \text{REFVSEL} &= (0,1,2), \\ I_{\text{VREF+}} &= +10\;\mu\text{A}, -1000\;\mu\text{A}, \\ \text{AV}_{\text{CC}} &= \text{AV}_{\text{CC}}(\text{min}) \; \text{for each reference level}, \\ \text{REFVSEL} &= (0,1,2), \; \text{REFON} = \text{REFOUT} = 1 \end{split}$				2500	μV/mA
C _{VREF+}	Capacitance at VREF+ terminal	REFON = REFOUT = 1		20		100	pF
TC _{REF+}	Temperature coefficient of built-in reference ⁽⁶⁾	$I_{VREF+} = 0$ A, REFVSEL = (0, 1, 2), REFON = 1, REFOUT = 0 or 1			30	50	ppm/ °C
PSRR_DC	Power supply rejection ratio (DC)	$\begin{array}{l} \text{AV}_{\text{CC}} = \text{AV}_{\text{CC}}(\text{min}) \text{ to AV}_{\text{CC}}(\text{max}), \\ \text{T}_{\text{A}} = 25^{\circ}\text{C}, \\ \text{REFVSEL} = (0, 1, 2), \text{ REFON} = 1, \\ \text{REFOUT} = 0 \text{ or } 1 \end{array}$			120	300	μV/V
PSRR_AC	Power supply rejection ratio (AC)	$\begin{array}{l} AV_{CC} = AV_{CC}(min) \text{ to } AV_{CC}(max), \\ T_A = 25^{\circ}C, \\ f = 1 \text{ kHz}, \Delta Vpp = 100 \text{ mV}, \\ REFVSEL = (0, 1, 2), REFON = 1, \\ REFOUT = 0 \text{ or } 1 \end{array}$			6.4		mV/V
	Cattling time of reference	$AV_{CC} = AV_{CC}$ (min) to AV_{CC} (max), REFVSEL = (0, 1, 2), REFOUT = 0, REFON = 0 \rightarrow 1			75		
t _{SETTLE}	Settling time of reference voltage ⁽⁷⁾	$\begin{array}{l} AV_{CC} = AV_{CC}(min) \ to \ AV_{CC}(max), \\ C_{VREF} = C_{VREF}(max), \\ REFVSEL = (0, 1, 2), \ REFOUT = 1, \\ REFON = 0 \rightarrow 1 \end{array}$			75		μs

⁽⁵⁾ Contribution only due to the reference and buffer including package. This does not include resistance due to PCB trace.

⁽⁶⁾ Calculated using the box method: (MAX(-40°C to 85°C) - MIN(-40°C to 85°C)) / MIN(-40°C to 85°C)/(85°C - (-40°C)).

⁽⁷⁾ The condition is that the error in a conversion started after t_{REFON} is less than ±0.5 LSB. The settling time depends on the external capacitive load when REFOUT = 1.



5.42 Comparator_B

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V _{cc}	MIN	TYP	MAX	UNIT	
V _{CC}	Supply voltage			1.8		3.6	V	
			1.8 V			40		
	Comparator operating supply	CBPWRMD = 00	2.2 V		30	50		
I _{AVCC_COMP}	current into AVCC, excludes		3.0 V		40	65	μΑ	
	reference resistor ladder	reference resistor ladder CBPWRMD = 01	2.2 V, 3 V		10	30		
		CBPWRMD = 10	2.2 V, 3 V		0.1	0.5		
I _{AVCC_REF}	Quiescent current of local reference voltage amplifier into AVCC	CBREFACC = 1, CBREFLx = 01				22	μΑ	
V_{IC}	Common mode input range			0		V _{CC} – 1	V	
V	Input offeet voltage	CBPWRMD = 00		-20		20	mV	
V _{OFFSET}	Input offset voltage	CBPWRMD = 01, 10		-10		10	IIIV	
C _{IN}	Input capacitance				5		pF	
D	Series input resistance	On (switch closed)			3	4	4 kΩ	
R _{SIN}	Series input resistance	Off (switch open)		30			$M\Omega$	
	Propagation delay, response time	CBPWRMD = 00, CBF = 0				450	ns	
t _{PD}		CBPWRMD = 01, CBF = 0				600	115	
		CBPWRMD = 10, CBF = 0				50	μs	
		CBPWRMD = 00, CBON = 1, CBF = 1, CBFDLY = 00		0.35	0.6	1.0		
	Propagation delay with filter	CBPWRMD = 00, CBON = 1, CBF = 1, CBFDLY = 01		0.6	1.0	1.8		
^t PD,filter	active	CBPWRMD = 00, CBON = 1, CBF = 1, CBFDLY = 10		1.0	1.8	3.4	μs	
		CBPWRMD = 00, CBON = 1, CBF = 1, CBFDLY = 11		1.8	3.4	6.5		
	Comparator enable time,	CBON = 0 to CBON = 1, CBPWRMD = 00, 01			1	2		
t _{EN_CMP}	settling time	CBON = 0 to CBON = 1, CBPWRMD = 10				100	μs	
t _{EN_REF}	Resistor reference enable time	CBON = 0 to CBON = 1			1	1.5	μs	
V _{CB_REF}	Reference voltage for a given tap	VIN = reference into resistor ladder (n = 0 to 31)		VIN x (n + 0.5) / 32	VIN x (n + 1) / 32	VIN x (n + 1.5) / 32	V	

5.43 Ports PU.0 and PU.1

	PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
V _{OH}	High-level output voltage	V_{USB} = 3.3 V ±10%, I_{OH} = -25 mA, See Figure 5-18 for typical characteristics	2.4		V
V _{OL}	Low-level output voltage	V _{USB} = 3.3 V ±10%, I _{OL} = 25 mA, See Figure 5-17 for typical characteristics		0.4	V
V _{IH}	High-level input voltage	V _{USB} = 3.3 V ±10%, See Figure 5-19 for typical characteristics	2.0		V
V _{IL}	Low-level input voltage	V _{USB} = 3.3 V ±10%, See Figure 5-19 for typical characteristics		0.8	V

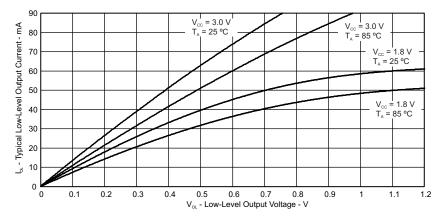


Figure 5-17. Ports PU.0, PU.1 Typical Low-Level Output Characteristics

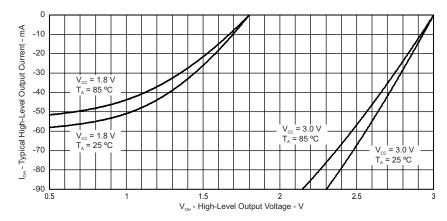


Figure 5-18. Ports PU.0, PU.1 Typical High-Level Output Characteristics

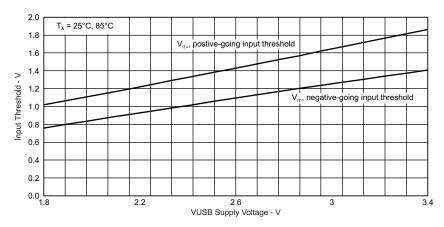


Figure 5-19. Ports PU.0, PU.1 Typical Input Threshold Characteristics



5.44 USB Output Ports DP and DM

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
V _{OH}	D+, D- single ended	USB 2.0 load conditions	2.8	3.6	V
V_{OL}	D+, D- single ended	USB 2.0 load conditions	0	0.3	V
Z _(DRV)	D+, D- impedance	Including external series resistor of 27 Ω	28	44	Ω
t _{RISE}	Rise time	Full speed, differential, C _L = 50 pF, 10%/90%, Rpu on D+	4	20	ns
t _{FALL}	Fall time	Full speed, differential, C _L = 50 pF, 10%/90%, Rpu on D+	4	20	ns

5.45 USB Input Ports DP and DM

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	MIN	MAX	UNIT
$V_{(CM)}$	Differential input common mode range	0.8	2.5	V
$Z_{(IN)}$	Input impedance	300		$k\Omega$
V _{CRS}	Crossover voltage	1.3	2.0	V
V_{IL}	Static SE input logic low level		0.8	V
V _{IH}	Static SE input logic high level	2.0		V
V_{DI}	Differential input voltage		0.2	V

5.46 USB-PWR (USB Power System)

	PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
V_{LAUNCH}	V _{BUS} detection threshold					3.75	٧
V _{BUS}	USB bus voltage	Normal operation		3.76		5.5	V
V _{USB}	USB LDO output voltage			3.003	3.3	3.597	V
V ₁₈	Internal USB voltage ⁽¹⁾				1.8		V
I _{USB_EXT}	Maximum external current from VUSB terminal (2)	USB LDO is on				12	mA
I _{DET}	USB LDO current overload detection (3)			60		100	mA
I _{SUSPEND}	Operating supply current into VBUS terminal (4)	USB LDO is on, USB PLL disabled				250	μΑ
I _{USB_LDO}	Operating supply current into VBUS terminal, represents the current of the 3.3-V LDO only	USB LDO is on, USB 1.8-V LDO is disabled, V _{BUS} = 5.0 V, USBDETEN = 0 or 1	1.8 V, 3 V		60		μA
I _{VBUS_DETECT}	Operating supply current into VBUS terminal, represents the current of the VBUS detection logic	USB LDO is disabled, USB 1.8-V LDO is disabled, VBUS > V _{LAUNCH} , USBDETEN = 1	1.8 V, 3 V		30		μA
C _{BUS}	VBUS terminal recommended capacitance				4.7		μF
C _{USB}	VUSB terminal recommended capacitance				220		nF
C ₁₈	V18 terminal recommended capacitance				220		nF
t _{ENABLE}	Settling time V _{USB} and V ₁₈	Within 2%, recommended capacitances				2	ms
R _{PUR}	Pullup resistance of PUR terminal ⁽⁵⁾			70	110	150	Ω

¹⁾ This voltage is for internal uses only. No external DC loading should be applied.

⁽²⁾ This represents additional current that can be supplied to the application from the VUSB terminal beyond the needs of the USB operation.

⁽³⁾ A current overload is detected when the total current supplied from the USB LDO, including I_{USB EXT}, exceeds this value.

⁽⁴⁾ Does not include current contribution of Rpu and Rpd as outlined in the USB specification.

⁽⁵⁾ This value, in series with an external resistor between PUR and D+, produces the Rpu as outlined in the USB specification.



5.47 USB-PLL (USB Phase-Locked Loop)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
I _{PLL}	Operating supply current				7	mA
f _{PLL}	PLL frequency			48		MHz
f _{UPD}	PLL reference frequency		1.5		3	MHz
t _{LOCK}	PLL lock time				2	ms
t _{Jitter}	PLL jitter			1000		ps

5.48 Flash Memory

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TJ	MIN	TYP	MAX	UNIT
DV _{CC(PGM,ERASE)}	Program and erase supply voltage		1.8		3.6	V
I _{PGM}	Average supply current from DVCC during program ⁽¹⁾			3	5	mΑ
I _{ERASE}	Average supply current from DVCC during erase ⁽¹⁾			6	11	mA
I _{MERASE} , I _{BANK}	Average supply current from DVCC during mass erase or bank erase ⁽¹⁾			6	11	mA
t _{CPT}	Cumulative program time ⁽²⁾				16	ms
	Program and erase endurance		10 ⁴	10 ⁵		cycles
t _{Retention}	Data retention duration	25°C	100			years
t _{Word}	Word or byte program time ⁽³⁾		64		85	μs
t _{Block, 0}	Block program time for first byte or word ⁽³⁾		49		65	μs
t _{Block, 1-(N-1)}	Block program time for each additional byte or word, except for last byte or word (3)		37		49	μs
t _{Block, N}	Block program time for last byte or word (3)		55		73	μs
t _{Erase}	Erase time for segment, mass erase, and bank erase when available (3)		23		32	ms
f _{MCLK,MGR}	MCLK frequency in marginal read mode (FCTL4.MGR0 = 1 or FCTL4.MGR1 = 1)		0		1	MHz

⁽¹⁾ Default clock system frequency of MCLK = 1 MHz, ACLK = 32768 Hz, SMCLK = 1 MHz. No peripherals are enabled or active.

5.49 JTAG and Spy-Bi-Wire Interface

	PARAMETER	V _{CC}	MIN	TYP	MAX	UNIT	
f _{SBW}	Spy-Bi-Wire input frequency	2.2 V, 3 V	0		20	MHz	
t _{SBW,Low}	Spy-Bi-Wire low clock pulse duration	2.2 V, 3 V	0.025		15	μs	
t _{SBW, En}	Spy-Bi-Wire enable time (TEST high to acceptance of first clock edge) ⁽¹⁾	2.2 V, 3 V			1	μs	
t _{SBW,Rst}	Spy-Bi-Wire return to normal operation time		15		100	μs	
£	TCV input fraguancy 4 wire ITAC(2)	2.2 V	0		5	MHz	
f _{TCK}	ITCK I I CK I I I I I I I I I I I I I I I	TCK input frequency, 4-wire JTAG ⁽²⁾	3 V	0		10	IVI□Z
R _{internal}	Internal pulldown resistance on TEST	2.2 V, 3 V	45	60	80	$k\Omega$	

⁽¹⁾ Tools that access the Spy-Bi-Wire interface must wait for the t_{SBW,En} time after pulling the TEST/SBWTCK pin high before applying the first SBWTCK clock edge.

⁽²⁾ The cumulative program time must not be exceeded when writing to a 128-byte flash block. This parameter applies to all programming methods: individual word- or byte-write and block-write modes.

⁽³⁾ These values are hardwired into the state machine of the flash controller.

⁽²⁾ f_{TCK} may be restricted to meet the timing requirements of the module selected.



6 Detailed Description

6.1 CPU (Link to User's Guide)

The MSP430 CPU has a 16-bit RISC architecture that is highly transparent to the application. All operations, other than program-flow instructions, are performed as register operations in conjunction with seven addressing modes for source operand and four addressing modes for destination operand.

The CPU is integrated with 16 registers that provide reduced instruction execution time. The register-to-register operation execution time is one cycle of the CPU clock.

Four of the registers, R0 to R3, are dedicated as program counter, stack pointer, status register, and constant generator, respectively. The remaining registers are general-purpose registers (see Figure 6-1).

Peripherals are connected to the CPU using data, address, and control buses. The peripherals can be managed with all instructions.

The instruction set consists of the original 51 instructions with three formats and seven address modes and additional instructions for the expanded address range. Each instruction can operate on word and byte data.

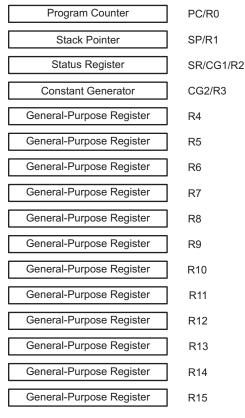


Figure 6-1. Integrated CPU Registers



6.2 Operating Modes

These microcontrollers have one active mode and six software-selectable low-power modes of operation. An interrupt event can wake up the device from any of the low-power modes, service the request, and restore back to the low-power mode on return from the interrupt program.

Software can configure the following operating modes:

- Active mode (AM)
 - All clocks are active
- Low-power mode 0 (LPM0)
 - CPU is disabled
 - ACLK and SMCLK remain active, MCLK is disabled
 - FLL loop control remains active
- Low-power mode 1 (LPM1)
 - CPU is disabled
 - FLL loop control is disabled
 - ACLK and SMCLK remain active, MCLK is disabled
- Low-power mode 2 (LPM2)
 - CPU is disabled
 - MCLK, FLL loop control, and DCOCLK are disabled
 - DC generator of the DCO remains enabled
 - ACLK remains active
- Low-power mode 3 (LPM3)
 - CPU is disabled
 - MCLK, FLL loop control, and DCOCLK are disabled
 - DC generator of the DCO is disabled
 - ACLK remains active
- Low-power mode 4 (LPM4)
 - CPU is disabled
 - ACLK is disabled
 - MCLK, FLL loop control, and DCOCLK are disabled
 - DC generator of the DCO is disabled
 - Crystal oscillator is stopped
 - Complete data retention
- Low-power mode 4.5 (LPM4.5)
 - Internal regulator disabled
 - No data retention
 - Wake-up signal from RST/NMI, P1, and P2



6.3 Interrupt Vector Addresses

The interrupt vectors and the power-up start address are in the address range 0FFFFh to 0FF80h (see Table 6-1). The vector contains the 16-bit address of the appropriate interrupt-handler instruction sequence.

Table 6-1. Interrupt Sources, Flags, and Vectors

INTERRUPT SOURCE	INTERRUPT FLAG	SYSTEM INTERRUPT	WORD ADDRESS	PRIORITY
System Reset Power up External reset Watchdog time-out, password violation Flash memory password violation	WDTIFG, KEYV (SYSRSTIV) ⁽¹⁾⁽²⁾	Reset	0FFFEh	63, highest
System NMI PMM Vacant memory access JTAG mailbox	SVMLIFG, SVMHIFG, DLYLIFG, DLYHIFG, VLRLIFG, VLRHIFG, VMAIFG, JMBNIFG, JMBOUTIFG (SYSSNIV) ⁽¹⁾	(Non)maskable	0FFFCh	62
User NMI NMI Oscillator fault Flash memory access violation	NMIIFG, OFIFG, ACCVIFG, BUSIFG (SYSUNIV) ⁽¹⁾⁽²⁾	(Non)maskable	0FFFAh	61
Comp_B	Comparator B interrupt flags (CBIV) ⁽¹⁾⁽³⁾	Maskable	0FFF8h	60
TB0	TB0CCR0 CCIFG0 ⁽³⁾	Maskable	0FFF6h	59
TB0	TB0CCR1 CCIFG1 to TB0CCR6 CCIFG6, TB0IFG (TB0IV) ⁽¹⁾⁽³⁾	Maskable	0FFF4h	58
Watchdog Timer_A interval timer mode	WDTIFG	Maskable	0FFF2h	57
USCI_A0 receive or transmit	UCA0RXIFG, UCA0TXIFG (UCA0IV) (1) (3)	Maskable	0FFF0h	56
USCI_B0 receive or transmit	UCB0RXIFG, UCB0TXIFG (UCB0IV) (1)(3)	Maskable	0FFEEh	55
ADC12_A	ADC12IFG0 to ADC12IFG15 (ADC12IV) (1) (3) (4)	Maskable	0FFECh	54
TA0	TA0CCR0 CCIFG0 ⁽³⁾	Maskable	0FFEAh	53
TA0	TA0CCR1 CCIFG1 to TA0CCR4 CCIFG4, TA0IFG (TA0IV) ⁽¹⁾⁽³⁾	Maskable	0FFE8h	52
USB_UBM	USB interrupts (USBIV) ⁽¹⁾⁽³⁾	Maskable	0FFE6h	51
DMA	DMA0IFG, DMA1IFG, DMA2IFG (DMAIV) (1)(3)	Maskable	0FFE4h	50
TA1	TA1CCR0 CCIFG0 ⁽³⁾	Maskable	0FFE2h	49
TA1	TA1CCR1 CCIFG1 to TA1CCR2 CCIFG2, TA1IFG (TA1IV) ⁽¹⁾⁽³⁾	Maskable	0FFE0h	48
I/O port P1	P1IFG.0 to P1IFG.7 (P1IV) ⁽¹⁾⁽³⁾	Maskable	0FFDEh	47
USCI_A1 receive or transmit	UCA1RXIFG, UCA1TXIFG (UCA1IV) (1)(3)	Maskable	0FFDCh	46
USCI_B1 receive or transmit	UCB1RXIFG, UCB1TXIFG (UCB1IV) (1)(3)	Maskable	0FFDAh	45
TA2	TA2CCR0 CCIFG0 ⁽³⁾	Maskable	0FFD8h	44
TA2	TA2CCR1 CCIFG1 to TA2CCR2 CCIFG2, TA2IFG (TA2IV) ⁽¹⁾⁽³⁾	Maskable	0FFD6h	43
I/O port P2	P2IFG.0 to P2IFG.7 (P2IV) ⁽¹⁾⁽³⁾	Maskable	0FFD4h	42
RTC_A	RTCRDYIFG, RTCTEVIFG, RTCAIFG, RT0PSIFG, RT1PSIFG (RTCIV) ⁽¹⁾⁽³⁾	Maskable	0FFD2h	41
			0FFD0h	40
Reserved	Reserved ⁽⁵⁾			÷
			0FF80h	0, lowest

⁽¹⁾ Multiple source flags

⁽²⁾ A reset is generated if the CPU tries to fetch instructions from within peripheral space or vacant memory space. (Non)maskable: the individual interrupt enable bit can disable an interrupt event, but the general interrupt enable bit cannot disable it.

⁽³⁾ Interrupt flags are in the module.

⁽⁴⁾ Only on devices with ADC, otherwise reserved.

⁽⁵⁾ Reserved interrupt vectors at addresses are not used in this device and can be used for regular program code if necessary. To maintain compatibility with other devices, TI recommends reserving these locations.



6.4 Memory Organization

Table 6-2 summarizes the memory map of the devices.

Table 6-2. Memory Organization⁽¹⁾

		MSP430F5522 MSP430F5521 MSP430F5513	MSP430F5525 MSP430F5524 MSP430F5515 MSP430F5514	MSP430F5527 MSP430F5526 MSP430F5517	MSP430F5529 MSP430F5528 MSP430F5519
Memory (flash) Main: interrupt vector	Total Size	32KB 00FFFFh to 00FF80h	64KB 00FFFFh to 00FF80h	96KB 00FFFFh to 00FF80h	128KB 00FFFFh to 00FF80h
	Bank D	N/A	N/A	N/A	32KB 0243FFh to 01C400h
Main: aada mamari	Bank C	N/A	N/A	32KB 01C3FFh to 014400h	32KB 01C3FFh to 014400h
Main: code memory	Bank B	15KB 00FFFFh to 00C400h	32KB 0143FFh to 00C400h	32KB 0143FFh to 00C400h	32KB 0143FFh to 00C400h
	Bank A	17KB 00C3FFh to 008000h	32KB 00C3FFh to 004400h	32KB 00C3FFh to 004400h	32KB 00C3FFh to 004400h
	Sector 3	2KB ⁽²⁾ 0043FFh to 003C00h	N/A	N/A	2KB 0043FFh to 003C00h
RAM	Sector 2	2KB ⁽³⁾ 003BFFh to 003400h	N/A	2KB 003BFFh to 003400h	2KB 003BFFh to 003400h
RAIVI	Sector 1	2KB 0033FFh to 002C00h	2KB 0033FFh to 002C00h	2KB 0033FFh to 002C00h	2KB 0033FFh to 002C00h
	Sector 0	2KB 002BFFh to 002400h	2KB 002BFFh to 002400h	2KB 002BFFh to 002400h	2KB 002BFFh to 002400h
USB RAM ⁽⁴⁾	Sector 7	2KB 0023FFh to 001C00h	2KB 0023FFh to 001C00h	2KB 0023FFh to 001C00h	2KB 0023FFh to 001C00h
	Info A	128 B 0019FFh to 001980h	128 B 0019FFh to 001980h	128 B 0019FFh to 001980h	128 B 0019FFh to 001980h
Information memory	Info B	128 B 00197Fh to 001900h	128 B 00197Fh to 001900h	128 B 00197Fh to 001900h	128 B 00197Fh to 001900h
(flash)	Info C	128 B 0018FFh to 001880h	128 B 0018FFh to 001880h	128 B 0018FFh to 001880h	128 B 0018FFh to 001880h
	Info D	128 B 00187Fh to 001800h	128 B 00187Fh to 001800h	128 B 00187Fh to 001800h	128 B 00187Fh to 001800h
	BSL 3	512 B 0017FFh to 001600h	512 B 0017FFh to 001600h	512 B 0017FFh to 001600h	512 B 0017FFh to 001600h
Bootloader (BSL)	BSL 2	512 B 0015FFh to 001400h	512 B 0015FFh to 001400h	512 B 0015FFh to 001400h	512 B 0015FFh to 001400h
memory (flash)	BSL 1	512 B 0013FFh to 001200h	512 B 0013FFh to 001200h	512 B 0013FFh to 001200h	512 B 0013FFh to 001200h
	BSL 0	512 B 0011FFh to 001000h	512 B 0011FFh to 001000h	512 B 0011FFh to 001000h	512 B 0011FFh to 001000h
Peripherals	Size	4KB 000FFFh to 0h	4KB 000FFFh to 0h	4KB 000FFFh to 0h	4KB 000FFFh to 0h

⁽¹⁾ N/A = Not available

⁽²⁾ MSP430F5522 only

⁽³⁾ MSP430F5522 and MSP430F5521 only

⁽⁴⁾ USB RAM can be used as general purpose RAM when not used for USB operation.



6.5 **Bootloader (BSL)**

The BSL enables users to program the flash memory or RAM using various serial interfaces. Access to the device memory by the BSL is protected by an user-defined password. For further details on interfacing to development tools and device programmers, see the MSP430 Hardware Tools User's Guide. For complete description of the features of the BSL and its implementation, see MSP430 Programming With the Bootloader (BSL).

6.5.1 USB BSL

All devices come preprogrammed with the USB BSL. Table 6-3 lists the required pins for the USB BSL. In addition to these pins, the application must support external components necessary for normal USB operation; for example, the proper crystal on XT2IN and XT2OUT, proper decoupling, and so on.

Table 6-3. USB BSL Pin Requirements and Functions

DEVICE SIGNAL	BSL FUNCTION
PU.0/DP	USB data terminal DP
PU.1/DM	USB data terminal DM
PUR	USB pullup resistor terminal
VBUS	USB bus power supply
VSSU	USB ground supply

NOTE

The default USB BSL evaluates the logic level of the PUR pin after a BOR reset. If the PUR pin is pulled high externally, then the BSL is invoked. Therefore, unless the application is invoking the BSL, it is important to keep PUR pulled low after a BOR reset, even if BSL or USB is never used. TI recommends applying a 1-M Ω resistor to ground.

6.5.2 UART BSL

A UART BSL is also available that can be programmed by the user into the BSL memory by replacing the preprogrammed, factory supplied, USB BSL. Table 6-4 lists the required pins for the UART BSL.

Table 6-4. UART BSL Pin Requirements and Functions

DEVICE SIGNAL	BSL FUNCTION
RST/NMI/SBWTDIO	Entry sequence signal
TEST/SBWTCK	Entry sequence signal
P1.1	Data transmit
P1.2	Data receive
VCC	Power supply
VSS	Ground supply



6.6 JTAG Operation

6.6.1 JTAG Standard Interface

The MSP430 family supports the standard JTAG interface, which requires four signals for sending and receiving data. The JTAG signals are shared with general-purpose I/O. The TEST/SBWTCK pin is used to enable the JTAG signals. In addition to these signals, the RST/NMI/SBWTDIO is required to interface with MSP430 development tools and device programmers. Table 6-5 lists the required pins for the JTAG interface. For further details on interfacing to development tools and device programmers, see the MSP430 Hardware Tools User's Guide. For a complete description of the features of the JTAG interface and its implementation, see MSP430 Programming With the JTAG Interface.

Table 6-5. JTAG Pin Requirements and Functions

DEVICE SIGNAL	E SIGNAL DIRECTION FUNCT	
PJ.3/TCK	IN	JTAG clock input
PJ.2/TMS	IN	JTAG state control
PJ.1/TDI/TCLK	IN	JTAG data input, TCLK input
PJ.0/TDO	OUT	JTAG data output
TEST/SBWTCK	IN	Enable JTAG pins
RST/NMI/SBWTDIO	IN	External reset
VCC		Power supply
VSS		Ground supply

6.6.2 Spy-Bi-Wire Interface

In addition to the standard JTAG interface, the MSP430 family supports the two wire Spy-Bi-Wire interface. Spy-Bi-Wire can be used to interface with MSP430 development tools and device programmers. Table 6-6 lists the required pins for the Spy-Bi-Wire interface. For further details on interfacing to development tools and device programmers, see the *MSP430 Hardware Tools User's Guide*. For a complete description of the features of the JTAG interface and its implementation, see *MSP430 Programming With the JTAG Interface*.

Table 6-6. Spy-Bi-Wire Pin Requirements and Functions

DEVICE SIGNAL	DIRECTION	FUNCTION
TEST/SBWTCK	IN	Spy-Bi-Wire clock input
RST/NMI/SBWTDIO	IN, OUT	Spy-Bi-Wire data input/output
VCC		Power supply
VSS		Ground supply



6.7 Flash Memory (Link to User's Guide)

The flash memory can be programmed through the JTAG port, Spy-Bi-Wire (SBW), the BSL, or in-system by the CPU. The CPU can perform single-byte, single-word, and long-word writes to the flash memory. Features of the flash memory include:

- Flash memory has n segments of main memory and four segments of information memory (A to D) of 128 bytes each. Each segment in main memory is 512 bytes in size.
- Segments 0 to n may be erased in one step, or each segment may be individually erased.
- Segments A to D can be erased individually. Segments A to D are also called information memory.
- Segment A can be locked separately.

6.8 RAM (Link to User's Guide)

The RAM is made up of n sectors. Each sector can be completely powered down to save leakage; however; all data is lost. Features of the RAM include:

- RAM has n sectors. The size of a sector can be found in Section 6.4.
- Each sector 0 to n can be complete disabled; however, data retention is lost.
- Each sector 0 to n automatically enters low-power retention mode when possible.
- For devices that contain USB memory, the USB memory can be used as normal RAM if USB is not required.

6.9 Peripherals

Peripherals are connected to the CPU through data, address, and control buses. Peripherals can be controlled using all instructions. For complete module descriptions, see the MSP430F5xx and MSP430F6xx Family User's Guide.

6.9.1 Digital I/O (Link to User's Guide)

Up to eight 8-bit I/O ports are implemented: For 80-pin packages, P1, P2, P3, P4, P5, P6, and P7 are complete, and P8 is reduced to 3-bit I/O. For 64-pin packages, P3 and P5 are reduced to 5-bit I/O and 6-bit I/O, respectively, and P7 and P8 are completely removed. Port PJ contains four individual I/O ports, common to all devices.

- All individual I/O bits are independently programmable.
- Any combination of input, output, and interrupt conditions is possible.
- Pullup or pulldown on all ports is programmable.
- Drive strength on all ports is programmable.
- All bits of ports P1 and P2 support edge-selectable interrupt and LPM4.5 wake-up input.
- Read and write access to port-control registers is supported by all instructions.
- Ports can be accessed byte-wise (P1 through P8) or word-wise in pairs (PA through PD).



6.9.2 Port Mapping Controller (Link to User's Guide)

The port mapping controller allows the flexible and reconfigurable mapping of digital functions to port P4 (see Table 6-7). Table 6-8 shows the default mappings.

Table 6-7. Port Mapping Mnemonics and Functions

VALUE	PxMAPy MNEMONIC	INPUT PIN FUNCTION	OUTPUT PIN FUNCTION		
0	PM_NONE	None	DVSS		
4	PM_CBOUT0 -		Comparator_B output		
1	PM_TB0CLK	TB0 clock input			
2	PM_ADC12CLK	-	ADC12CLK		
2	PM_DMAE0	DMAE0 input			
	PM_SVMOUT	-	SVM output		
3	PM_TB0OUTH	TB0 high impedance input TB0OUTH			
4	PM_TB0CCR0A	TB0 CCR0 capture input CCI0A	TB0 CCR0 compare output Out0		
5	PM_TB0CCR1A	TB0 CCR1 capture input CCI1A	TB0 CCR1 compare output Out1		
6	PM_TB0CCR2A	TB0 CCR2 capture input CCI2A	TB0 CCR2 compare output Out2		
7	PM_TB0CCR3A	TB0 CCR3 capture input CCI3A	TB0 CCR3 compare output Out3		
8	PM_TB0CCR4A	TB0 CCR4 capture input CCI4A	TB0 CCR4 compare output Out4		
9	PM_TB0CCR5A	TB0 CCR5 capture input CCI5A	TB0 CCR5 compare output Out5		
10	PM_TB0CCR6A	TB0 CCR6 capture input CCI6A	TB0 CCR6 compare output Out6		
4.4	PM_UCA1RXD	USCI_A1 UART RXD (Direction controlled by USCI – input)			
11	PM_UCA1SOMI	USCI_A1 SPI slave out master i	in (direction controlled by USCI)		
40	PM_UCA1TXD	USCI_A1 UART TXD (Direction	n controlled by USCI – output)		
12	PM_UCA1SIMO	USCI_A1 SPI slave in master or	ut (direction controlled by USCI)		
13	PM_UCA1CLK	USCI_A1 clock input/output (direction controlled by USCI)			
13	PM_UCB1STE	USCI_B1 SPI slave transmit enab	ble (direction controlled by USCI)		
4.4	PM_UCB1SOMI	USCI_B1 SPI slave out master i	in (direction controlled by USCI)		
14	PM_UCB1SCL	USCI_B1 I ² C clock (open drain a	and direction controlled by USCI)		
45	PM_UCB1SIMO	USCI_B1 SPI slave in master or	ut (direction controlled by USCI)		
15	PM_UCB1SDA	USCI_B1 I ² C data (open drain a	nd direction controlled by USCI)		
40	PM_UCB1CLK	USCI_B1 clock input/output (direction controlled by USCI)		
16	PM_UCA1STE	USCI_A1 SPI slave transmit enat	ble (direction controlled by USCI)		
17	PM_CBOUT1	None	Comparator_B output		
18	PM_MCLK	None	MCLK		
19–30	Reserved	None	DVSS		
31 (0FFh) ⁽¹⁾	PM_ANALOG	Disables the output driver and the input Schmitt-trigger to prevent parasitic cross currents when applying analog signals.			

⁽¹⁾ The value of the PM_ANALOG mnemonic is set to 0FFh. The port mapping registers are only 5 bits wide, and the upper bits are ignored, resulting in a read out value of 31.



Table 6-8. Default Mapping

PIN	PxMAPy MNEMONIC	INPUT PIN FUNCTION	OUTPUT PIN FUNCTION		
P4.0/P4MAP0	PM_UCB1STE/PM_UCA1CLK	USCI_B1 SPI slave transmit enable (direction controlled by USCI) USCI_A1 clock input/output (direction controlled by USCI)			
P4.1/P4MAP1	PM_UCB1SIMO/PM_UCB1SDA	USCI_B1 SPI slave in master out (direction controlled by USCI) USCI_B1 I ² C data (open drain and direction controlled by USCI)			
P4.2/P4MAP2	PM_UCB1SOMI/PM_UCB1SCL	USCI_B1 SPI slave out master in (direction controlled by USCI) USCI_B1 I ² C clock (open drain and direction controlled by USCI)			
P4.3/P4MAP3	PM_UCB1CLK/PM_UCA1STE	USCI_A1 SPI slave transmit enable (direction controlled by USCI) USCI_B1 clock input/output (direction controlled by USCI)			
P4.4/P4MAP4	PM_UCA1TXD/PM_UCA1SIMO	USCI_A1 UART TXD (Direction controlled by USCI – output) USCI_A1 SPI slave in master out (direction controlled by USCI)			
P4.5/P4MAP5	PM_UCA1RXD/PM_UCA1SOMI	USCI_A1 UART RXD (Direction controlled by USCI – input) USCI_A1 SPI slave out master in (direction controlled by USCI)			
P4.6/P4MAP6	PM_NONE	None DVSS			
P4.7/P4MAP7	PM_NONE	None	DVSS		

6.9.3 Oscillator and System Clock (Link to User's Guide)

The clock system in the MSP430F552x and MSP430F551x family of devices is supported by the Unified Clock System (UCS) module that includes support for a 32-kHz watch crystal oscillator (XT1 in LF mode) (XT1 in HF mode is not supported), an internal very-low-power low-frequency oscillator (VLO), an internal trimmed low-frequency oscillator (REFO), an integrated internal digitally controlled oscillator (DCO), and a high-frequency crystal oscillator (XT2). The UCS module is designed to meet the requirements of both low system cost and low power consumption. The UCS module features digital frequency-locked loop (FLL) hardware that, in conjunction with a digital modulator, stabilizes the DCO frequency to a programmable multiple of the selected FLL reference frequency. The internal DCO provides a fast turnon clock source and stabilizes in 3.5 µs (typical). The UCS module provides the following clock signals:

- Auxiliary clock (ACLK), sourced from a 32-kHz watch crystal (XT1), a high-frequency crystal (XT2), the internal low-frequency oscillator (VLO), the trimmed low-frequency oscillator (REFO), or the internal digitally controlled oscillator (DCO).
- Main clock (MCLK), the system clock used by the CPU. MCLK can be sourced by same sources made available to ACLK.
- Sub-Main clock (SMCLK), the subsystem clock used by the peripheral modules. SMCLK can be sourced by same sources made available to ACLK.
- ACLK/n, the buffered output of ACLK, ACLK/2, ACLK/4, ACLK/8, ACLK/16, ACLK/32.

6.9.4 Power-Management Module (PMM) (Link to User's Guide)

The PMM includes an integrated voltage regulator that supplies the core voltage to the device and contains programmable output levels to provide for power optimization. The PMM also includes supply voltage supervisor (SVS) and supply voltage monitoring (SVM) circuitry, as well as brownout protection. The brownout circuit is implemented to provide the proper internal reset signal to the device during power on and power off. The SVS and SVM circuitry detects if the supply voltage drops below a user-selectable level and supports both supply voltage supervision (SVS) (the device is automatically reset) and supply voltage monitoring (SVM) (the device is not automatically reset). SVS and SVM circuitry is available on the primary supply and core supply.

6.9.5 Hardware Multiplier (Link to User's Guide)

The multiplication operation is supported by a dedicated peripheral module. The module performs operations with 32-, 24-, 16-, and 8-bit operands. The module supports signed and unsigned multiplication as well as signed and unsigned multiply-and-accumulate operations.



6.9.6 Real-Time Clock (RTC_A) (Link to User's Guide)

The RTC_A module can be used as a general-purpose 32-bit counter (counter mode) or as an integrated real-time clock (RTC) (calendar mode). In counter mode, the RTC_A also includes two independent 8-bit timers that can be cascaded to form a 16-bit timer/counter. Both timers can be read and written by software. Calendar mode integrates an internal calendar that compensates for months with less than 31 days and includes leap year correction. The RTC_A also supports flexible alarm functions and offset-calibration hardware.

6.9.7 Watchdog Timer (WDT_A) (Link to User's Guide)

The primary function of the WDT_A module is to perform a controlled system restart after a software problem occurs. If the selected time interval expires, a system reset is generated. If the watchdog function is not needed in an application, the module can be configured as an interval timer and can generate interrupts at selected time intervals.

6.9.8 System Module (SYS) (Link to User's Guide)

The SYS module handles many of the system functions within the device. These include power-on reset and power-up clear handling, NMI source selection and management, reset interrupt vector generators, bootstrap loader entry mechanisms, and configuration management (device descriptors). It also includes a data exchange mechanism through JTAG called a JTAG mailbox that can be used in the application. Table 6-9 lists the SYS module interrupt vector registers.

Table 6-9. System Module Interrupt Vector Registers

INTERRUPT VECTOR REGISTER	ADDRESS	INTERRUPT EVENT	VALUE	PRIORITY
		No interrupt pending	00h	
		Brownout (BOR)	02h	Highest
		RST/NMI (POR)	04h	
		PMMSWBOR (BOR)	06h	
		Wakeup from LPMx.5	08h	
		Security violation (BOR)	0Ah	
	019Eh	SVSL (POR)	0Ch	
		SVSH (POR)	0Eh	
CVCDCTIV Contain Deart		SVML_OVP (POR)	10h	
SYSRSTIV, System Reset		SVMH_OVP (POR)	12h	
		PMMSWPOR (POR)	14h	
		WDT time-out (PUC)	16h	
		WDT password violation (PUC)	18h	
		KEYV flash password violation (PUC)	1Ah	
		Reserved	1Ch	
		Peripheral area fetch (PUC)	1Eh	
		PMM password violation (PUC)	20h	
		Reserved	22h to 3Eh	Lowest



Table 6-9. System Module Interrupt Vector Registers (continued)

INTERRUPT VECTOR REGISTER	ADDRESS	INTERRUPT EVENT	VALUE	PRIORITY
		No interrupt pending	00h	
		SVMLIFG	02h	Highest
		SVMHIFG	04h	
		SVSMLDLYIFG	06h	
		SVSMHDLYIFG	08h	
SYSSNIV, System NMI	019Ch	VMAIFG	0Ah	
		JMBINIFG	0Ch	
		JMBOUTIFG	0Eh	
		SVMLVLRIFG	10h	
		SVMHVLRIFG	12h	
		Reserved	14h to 1Eh	Lowest
		No interrupt pending	00h	
		NMIIFG	02h	Highest
0)(0)(1)(1)	0.40.41	OFIFG	04h	
SYSUNIV, User NMI	019Ah	ACCVIFG	06h	
		BUSIFG	08h	
		Reserved	0Ah to 1Eh	Lowest

6.9.9 DMA Controller (Link to User's Guide)

The DMA controller allows movement of data from one memory address to another without CPU intervention. For example, the DMA controller can be used to move data from the ADC12_A conversion memory to RAM. Using the DMA controller can increase the throughput of peripheral modules. The DMA controller reduces system power consumption by allowing the CPU to remain in sleep mode, without having to awaken to move data to or from a peripheral.

The USB timestamp generator also uses the DMA trigger assignments described in Table 6-10.

Table 6-10. DMA Trigger Assignments⁽¹⁾

TDIOOFD	CHANNEL						
TRIGGER	0	1	2				
0	DMAREQ	DMAREQ	DMAREQ				
1	TA0CCR0 CCIFG	TA0CCR0 CCIFG	TA0CCR0 CCIFG				
2	TA0CCR2 CCIFG	TA0CCR2 CCIFG	TA0CCR2 CCIFG				
3	TA1CCR0 CCIFG	TA1CCR0 CCIFG	TA1CCR0 CCIFG				
4	TA1CCR2 CCIFG	TA1CCR2 CCIFG	TA1CCR2 CCIFG				
5	TA2CCR0 CCIFG	TA2CCR0 CCIFG	TA2CCR0 CCIFG				
6	TA2CCR2 CCIFG	TA2CCR2 CCIFG	TA2CCR2 CCIFG				
7	TB0CCR0 CCIFG	TB0CCR0 CCIFG	TB0CCR0 CCIFG				
8	TB0CCR2 CCIFG	TB0CCR2 CCIFG	TB0CCR2 CCIFG				
9	Reserved	Reserved	Reserved				
10	Reserved	Reserved	Reserved				
11	Reserved	Reserved	Reserved				
12	Reserved	Reserved	Reserved				
13	Reserved	Reserved	Reserved				
14	Reserved	Reserved	Reserved				
15	Reserved	Reserved	Reserved				

(1) If a reserved trigger source is selected, no Trigger1 is generated.



Table 6-10. DMA Trigger Assignments⁽¹⁾ (continued)

TRIGGER	CHANNEL						
IRIGGER	0	1	2				
16	UCA0RXIFG	UCA0RXIFG	UCA0RXIFG				
17	UCA0TXIFG	UCA0TXIFG	UCA0TXIFG				
18	UCB0RXIFG	UCB0RXIFG	UCB0RXIFG				
19	UCB0TXIFG	UCB0TXIFG	UCB0TXIFG				
20	UCA1RXIFG	UCA1RXIFG	UCA1RXIFG				
21	UCA1TXIFG UCA1TXIFG		UCA1TXIFG				
22	UCB1RXIFG	UCB1RXIFG UCB1RXIFG					
23	UCB1TXIFG	UCB1TXIFG UCB1TXIFG					
24	ADC12IFGx ⁽²⁾	ADC12IFGx ⁽²⁾ ADC12IFGx ⁽²⁾					
25	Reserved Reserved		Reserved				
26	Reserved	Reserved	Reserved				
27	USB FNRXD	USB FNRXD	USB FNRXD				
28	USB ready USB ready		USB ready				
29	MPY ready MPY ready		MPY ready				
30	DMA2IFG	DMA0IFG	DMA1IFG				
31	DMAE0	DMAE0	DMAE0				

⁽²⁾ Only on devices with ADC. Reserved on devices without ADC.

6.9.10 Universal Serial Communication Interface (USCI) (Links to User's Guide: UART Mode, SPI Mode, &C Mode)

The USCI modules are used for serial data communication. The USCI module supports synchronous communication protocols such as SPI (3- or 4-pin) and I^2C , and asynchronous communication protocols such as UART, enhanced UART with automatic baud-rate detection, and IrDA. Each USCI module contains two portions, A and B.

The USCI_An module provides support for SPI (3- or 4-pin), UART, enhanced UART, or IrDA.

The USCI Bn module provides support for SPI (3- or 4-pin) or I²C.

The MSP430F55xx series includes two complete USCI modules (n = 0, 1).



6.9.11 TA0 (Link to User's Guide)

TA0 is a 16-bit timer and counter (Timer_A type) with five capture/compare registers. TA0 can support multiple capture/compare registers, PWM outputs, and interval timing (see Table 6-11). TA0 also has extensive interrupt capabilities. Interrupts can be generated from the counter on overflow conditions and from each of the capture/compare registers.

Table 6-11. TA0 Signal Connections

INPUT PIN	NUMBER	DEVICE	MODULE	MODULE	MODULE	DEVICE	OUTPUT PI	N NUMBER	
RGC, YFF, ZQE	PN	INPUT SIGNAL	INPUT SIGNAL	BLOCK	OUTPUT SIGNAL	OUTPUT SIGNAL	RGC, YFF, ZQE	PN	
18, B7, H2 - P1.0	21 - P1.0	TA0CLK	TACLK	Timer					
		ACLK (internal)	ACLK			NA	NA		
		SMCLK (internal)	SMCLK		INA	INA			
18, B7, H2 - P1.0	21 - P1.0	TA0CLK	TACLK						
19, B6, H3 - P1.1	22 - P1.1	TA0.0	CCI0A				19, B6, H3 - P1.1	22 - P1.1	
		DV _{SS}	CCI0B	CCR0	CCR0 TA0 T.	TA0.0			
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						
20, C6, J3 - P1.2	23 - P1.2	TA0.1	CCI1A	CCR1 TA1				20, C6, J3 - P1.2	23 - P1.2
		CBOUT (internal)	CCI1B		CCR1	CCR1	TA1	TA0.1	ADC12 (internal) ⁽¹⁾ ADC12SHSx = {1}
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						
21, C8, G4 - P1.3	24 - P1.3	TA0.2	CCI2A				21, C8, G4 - P1.3	24 - P1.3	
		ACLK (internal)	CCI2B	CCR2	TA2	TA0.2			
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						
22, C7, H4 - P1.4	25 - P1.4	TA0.3	CCI3A				22, C7, H4 - P1.4	25 - P1.4	
		DV _{SS}	CCI3B	CCR3	TA3	TA0.3			
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						
23, D6, J4 - P1.5	26 - P1.5	TA0.4	CCI4A				23, D6, J4 - P1.5	26 - P1.5	
		DV _{SS}	CCI4B	CCR4	TA4	TA0.4			
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						

⁽¹⁾ Only on devices with ADC.



6.9.12 TA1 (Link to User's Guide)

TA1 is a 16-bit timer and counter (Timer_A type) with three capture/compare registers. TA1 can support multiple capture/compare registers, PWM outputs, and interval timing (see Table 6-12). TA1 also has extensive interrupt capabilities. Interrupts can be generated from the counter on overflow conditions and from each of the capture/compare registers.

Table 6-12. TA1 Signal Connections

INPUT PIN NUMBER		DEVICE	MODULE	MODULE	MODULE	DEVICE	OUTPUT PI	OUTPUT PIN NUMBER	
RGC, YFF, ZQE	PN	INPUT SIGNAL	INPUT SIGNAL	BLOCK	OUTPUT SIGNAL	OUTPUT SIGNAL	RGC, YFF, ZQE	PN	
24, D7, G5 - P1.6	27 - P1.6	TA1CLK	TACLK						
		ACLK (internal)	ACLK	Timer	NIA	NIA			
		SMCLK (internal)	SMCLK		NA	NA			
24, D7, G5 - P1.6	27 - P1.6	TA1CLK	TACLK						
25, D8, H5 - P1.7	28 - P1.7	TA1.0	CCI0A	CCR0			25, D8, H5 - P1.7	28 - P1.7	
		DV _{SS}	CCI0B		TA0	TA1.0			
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						
26, E5, J5 - P2.0	29 - P2.0	TA1.1	CCI1A	CCR1			26, E5, J5 - P2.0	29 - P2.0	
		CBOUT (internal)	CCI1B CCR1		TA1	TA1.1			
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						
27, E8, G6 - P2.1	30 - P2.1	TA1.2	CCI2A	CCR2			27, E8, G6 - P2.1	30 - P2.1	
		ACLK (internal)	CCI2B		TA2	TA1.2			
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						



6.9.13 TA2 (Link to User's Guide)

TA2 is a 16-bit timer and counter (Timer_A type) with three capture/compare registers. TA2 can support multiple capture/compare registers, PWM outputs, and interval timing (see Table 6-13). TA2 also has extensive interrupt capabilities. Interrupts can be generated from the counter on overflow conditions and from each of the capture/compare registers.

Table 6-13. TA2 Signal Connections

INPUT PIN NUMBER		DEVICE	MODULE	MODULE	MODULE	DEVICE	OUTPUT PI	N NUMBER	
RGC, YFF, ZQE	PN	INPUT SIGNAL	INPUT SIGNAL	MODULE BLOCK	OUTPUT SIGNAL	OUTPUT SIGNAL	RGC, YFF, ZQE	PN	
28, E7, J6 - P2.2	31 - P2.2	TA2CLK	TACLK						
		ACLK (internal)	ACLK	Timor	NIA	NIA			
		SMCLK (internal)	SMCLK	Timer	NA	NA			
28, E7, J6 - P2.2	31 - P2.2	TA2CLK	TACLK						
29, E6, H6 - P2.3	32 - P2.3	TA2.0	CCI0A				29, E6, H6 - P2.3	32 - P2.3	
		DV _{SS}	CCI0B	CCR0	TA0	TA2.0			
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						
30, F8, J7 - P2.4	33 - P2.4	TA2.1	CCI1A				30, F8, J7 - P2.4	33 - P2.4	
		CBOUT (internal)	CCI1B	CCR1 TA1	CCR1 TA1 TA2.	TA1	TA2.1		
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						
31, F7, J8 - P2.5	34 - P2.5	TA2.2	CCI2A				31, F7, J8 - P2.5	34 - P2.5	
		ACLK (internal)	CCI2B	CCR2	TA2	TA2.2			
		DV _{SS}	GND						
		DV _{CC}	V _{CC}						



6.9.14 TB0 (Link to User's Guide)

TB0 is a 16-bit timer and counter (Timer_B type) with seven capture/compare registers. TB0 can support multiple capture/compare registers, PWM outputs, and interval timing (see Table 6-14). TB0 also has extensive interrupt capabilities. Interrupts can be generated from the counter on overflow conditions and from each of the capture/compare registers.

Table 6-14. TB0 Signal Connections

INPUT PIN	INPUT PIN NUMBER	DEVICE	MODULE	MODULE	MODULE	DEVICE	OUTPUT PI	N NUMBER							
RGC, YFF, ZQE ⁽¹⁾	PN	INPUT SIGNAL	INPUT SIGNAL	BLOCK	OUTPUT SIGNAL	OUTPUT SIGNAL	RGC, YFF, ZQE ⁽¹⁾	PN							
	60 - P7.7	TB0CLK	TBCLK												
		ACLK (internal)	ACLK	Timer	NA	NA									
		SMCLK (internal)	SMCLK	rimei	NA	INA									
	60 - P7.7	TB0CLK	TBCLK												
	55 - P5.6	TB0.0	CCI0A					55 - P5.6							
	55 - P5.6	TB0.0	CCI0B	CCR0	TB0	TB0.0	ADC12 (internal) $^{(2)}$ ADC12SHSx = $\{2\}$	ADC12 (internal) $^{(2)}$ ADC12SHSx = $\{2\}$							
		DV _{SS}	GND												
		DV _{CC}	V _{CC}												
	56 - P5.7	TB0.1	CCI1A					56 - P5.7							
		CBOUT (internal)	CCI1B	CCR1	TB1	B1 TB0.1	ADC12 (internal) ADC12SHSx = {3}	ADC12 (internal) ADC12SHSx = {3}							
		DV _{SS}	GND												
		DV _{CC}	V _{CC}												
	57 - P7.4	TB0.2	CCI2A					57 - P7.4							
	57 - P7.4	TB0.2	CCI2B		CCR2 TB2 1	TD 0 0									
		DV _{SS}	GND	CCR2		CCR2 IB2 IE	TB0.2								
		DV _{CC}	V _{CC}												
	58 - P7.5	TB0.3	CCI3A					58 - P7.5							
	58 - P7.5	TB0.3	CCI3B	0000	TDO	TD0.0									
		DV _{SS}	GND	CCR3	IBS	183	183	183	183	183	TB3	1B3 1B0.	TB0.3		
		DV _{CC}	V _{CC}												
	59 - P7.6	TB0.4	CCI4A					59 - P7.6							
	59 - P7.6	TB0.4	CCI4B	0004	TD 4	TD0 4									
		DV _{SS}	GND	CCR4	TB4	TB0.4									
		DV _{CC}	V _{CC}												
	42 - P3.5	TB0.5	CCI5A					42 - P3.5							
	42 - P3.5	TB0.5	CCI5B	0005	TDE	TD0 5									
		DV _{SS}	GND	CCR5	TB5 TB	TB0.5									
		DV _{CC}	V _{CC}												
	43 - P3.6	TB0.6	CCI6A					43 - P3.6							
		ACLK (internal)	CCI6B	CCR6	TB6	TB6	TB0.6								
		DV _{SS}	GND												
		DV _{CC}	V _{CC}												

⁽¹⁾ Timer functions are selectable through the port mapping controller.

⁽²⁾ Only on devices with ADC



6.9.15 Comparator_B (Link to User's Guide)

The primary function of the Comparator_B module is to support precision slope analog-to-digital conversions, battery voltage supervision, and monitoring of external analog signals.

6.9.16 ADC12_A (Link to User's Guide)

The ADC12_A module supports fast 12-bit analog-to-digital conversions. The module implements a 12-bit SAR core, sample select control, reference generator, and a 16 word conversion-and-control buffer. The conversion-and-control buffer allows up to 16 independent ADC samples to be converted and stored without any CPU intervention.

6.9.17 CRC16 (Link to User's Guide)

The CRC16 module produces a signature based on a sequence of entered data values and can be used for data checking purposes. The CRC16 module signature is based on the CRC-CCITT standard.

6.9.18 Voltage Reference (REF) Module (Link to User's Guide)

The REF module generates all critical reference voltages that can be used by the various analog peripherals in the device.

6.9.19 Universal Serial Bus (USB) (Link to User's Guide)

The USB module is a fully integrated USB interface that is compliant with the USB 2.0 specification. The module supports full-speed operation of control, interrupt, and bulk transfers. The module includes an integrated LDO, PHY, and PLL. The PLL is highly flexible and supports a wide range of input clock frequencies. USB RAM, when not used for USB communication, can be used by the system.

6.9.20 Embedded Emulation Module (EEM) (Link to User's Guide)

The EEM supports real-time in-system debugging. The L version of the EEM has the following features:

- Eight hardware triggers or breakpoints on memory access
- Two hardware triggers or breakpoints on CPU register write access
- Up to 10 hardware triggers can be combined to form complex triggers or breakpoints
- Two cycle counters
- Sequencer
- State storage
- · Clock control on module level

MSP430F5522 MSP430F5521 MSP430F5519 MSP430F5517 MSP430F5515 MSP430F5514 MSP430F5513



6.9.21 Peripheral File Map

Table 6-15 lists the base address for the registers of each module. Table 6-16 through Table 6-45 list the available registers in each module.

Table 6-15. Peripherals

MODULE NAME	BASE ADDRESS	OFFSET ADDRESS RANGE
Special Functions (see Table 6-16)	0100h	000h to 01Fh
PMM (see Table 6-17)	0120h	000h to 010h
Flash Control (see Table 6-18)	0140h	000h to 00Fh
CRC16 (see Table 6-19)	0150h	000h to 007h
RAM Control (see Table 6-20)	0158h	000h to 001h
Watchdog (see Table 6-21)	015Ch	000h to 001h
UCS (see Table 6-22)	0160h	000h to 01Fh
SYS (see Table 6-23)	0180h	000h to 01Fh
Shared Reference (see Table 6-24)	01B0h	000h to 001h
Port Mapping Control (see Table 6-25)	01C0h	000h to 002h
Port Mapping Port P4 (see Table 6-25)	01E0h	000h to 007h
Port P1 and P2 (see Table 6-26)	0200h	000h to 01Fh
Port P3 and P4 (see Table 6-27)	0220h	000h to 00Bh
Port P5 and P6 (see Table 6-28)	0240h	000h to 00Bh
Port P7 and P8 (see Table 6-29)	0260h	000h to 00Bh
Port PJ (see Table 6-30)	0320h	000h to 01Fh
TA0 (see Table 6-31)	0340h	000h to 02Eh
TA1 (see Table 6-32)	0380h	000h to 02Eh
TB0 (see Table 6-33)	03C0h	000h to 02Eh
TA2 (see Table 6-34)	0400h	000h to 02Eh
Real-Time Clock (RTC_A) (see Table 6-35)	04A0h	000h to 01Bh
32-Bit Hardware Multiplier (see Table 6-36)	04C0h	000h to 02Fh
DMA General Control (see Table 6-37)	0500h	000h to 00Fh
DMA Channel 0 (see Table 6-37)	0510h	000h to 00Ah
DMA Channel 1 (see Table 6-37)	0520h	000h to 00Ah
DMA Channel 2 (see Table 6-37)	0530h	000h to 00Ah
USCI_A0 (see Table 6-38)	05C0h	000h to 01Fh
USCI_B0 (see Table 6-39)	05E0h	000h to 01Fh
USCI_A1 (see Table 6-40)	0600h	000h to 01Fh
USCI_B1 (see Table 6-41)	0620h	000h to 01Fh
ADC12_A (see Table 6-42)	0700h	000h to 03Eh
Comparator_B (see Table 6-43)	08C0h	000h to 00Fh
USB Configuration (see Table 6-44)	0900h	000h to 014h
USB Control (see Table 6-45)	0920h	000h to 01Fh



Table 6-16. Special Function Registers (Base Address: 0100h)

REGISTER DESCRIPTION	REGISTER	OFFSET
SFR interrupt enable	SFRIE1	00h
SFR interrupt flag	SFRIFG1	02h
SFR reset pin control	SFRRPCR	04h

Table 6-17. PMM Registers (Base Address: 0120h)

REGISTER DESCRIPTION	REGISTER	OFFSET
PMM control 0	PMMCTL0	00h
PMM control 1	PMMCTL1	02h
SVS high-side control	SVSMHCTL	04h
SVS low-side control	SVSMLCTL	06h
PMM interrupt flags	PMMIFG	0Ch
PMM interrupt enable	PMMIE	0Eh
PMM power mode 5 control	PM5CTL0	10h

Table 6-18. Flash Control Registers (Base Address: 0140h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Flash control 1	FCTL1	00h
Flash control 3	FCTL3	04h
Flash control 4	FCTL4	06h

Table 6-19. CRC16 Registers (Base Address: 0150h)

REGISTER DESCRIPTION	REGISTER	OFFSET
CRC data input	CRC16DI	00h
CRC data input reverse byte	CRCDIRB	02h
CRC initialization and result	CRCINIRES	04h
CRC result reverse byte	CRCRESR	06h

Table 6-20. RAM Control Registers (Base Address: 0158h)

REGISTER DESCRIPTION	REGISTER	OFFSET
RAM control 0	RCCTL0	00h

Table 6-21. Watchdog Registers (Base Address: 015Ch)

REGISTER DESCRIPTION	REGISTER	OFFSET
Watchdog timer control	WDTCTL	00h



Table 6-22. UCS Registers (Base Address: 0160h)

REGISTER DESCRIPTION	REGISTER	OFFSET
UCS control 0	UCSCTL0	00h
UCS control 1	UCSCTL1	02h
UCS control 2	UCSCTL2	04h
UCS control 3	UCSCTL3	06h
UCS control 4	UCSCTL4	08h
UCS control 5	UCSCTL5	0Ah
UCS control 6	UCSCTL6	0Ch
UCS control 7	UCSCTL7	0Eh
UCS control 8	UCSCTL8	10h

Table 6-23. SYS Registers (Base Address: 0180h)

REGISTER DESCRIPTION	REGISTER	OFFSET
System control	SYSCTL	00h
Bootloader configuration area	SYSBSLC	02h
JTAG mailbox control	SYSJMBC	06h
JTAG mailbox input 0	SYSJMBI0	08h
JTAG mailbox input 1	SYSJMBI1	0Ah
JTAG mailbox output 0	SYSJMBO0	0Ch
JTAG mailbox output 1	SYSJMBO1	0Eh
Bus error vector generator	SYSBERRIV	18h
User NMI vector generator	SYSUNIV	1Ah
System NMI vector generator	SYSSNIV	1Ch
Reset vector generator	SYSRSTIV	1Eh

Table 6-24. Shared Reference Registers (Base Address: 01B0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Shared reference control	REFCTL	00h

Table 6-25. Port Mapping Registers (Base Address of Port Mapping Control: 01C0h, Port P4: 01E0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port mapping key and ID	PMAPKEYID	00h
Port mapping control	PMAPCTL	02h
Port P4.0 mapping	P4MAP0	00h
Port P4.1 mapping	P4MAP1	01h
Port P4.2 mapping	P4MAP2	02h
Port P4.3 mapping	P4MAP3	03h
Port P4.4 mapping	P4MAP4	04h
Port P4.5 mapping	P4MAP5	05h
Port P4.6 mapping	P4MAP6	06h
Port P4.7 mapping	P4MAP7	07h



Table 6-26. Port P1 and P2 Registers (Base Address: 0200h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P1 input	P1IN	00h
Port P1 output	P1OUT	02h
Port P1 direction	P1DIR	04h
Port P1 resistor enable	P1REN	06h
Port P1 drive strength	P1DS	08h
Port P1 selection	P1SEL	0Ah
Port P1 interrupt vector word	P1IV	0Eh
Port P1 interrupt edge select	P1IES	18h
Port P1 interrupt enable	P1IE	1Ah
Port P1 interrupt flag	P1IFG	1Ch
Port P2 input	P2IN	01h
Port P2 output	P2OUT	03h
Port P2 direction	P2DIR	05h
Port P2 resistor enable	P2REN	07h
Port P2 drive strength	P2DS	09h
Port P2 selection	P2SEL	0Bh
Port P2 interrupt vector word	P2IV	1Eh
Port P2 interrupt edge select	P2IES	19h
Port P2 interrupt enable	P2IE	1Bh
Port P2 interrupt flag	P2IFG	1Dh

Table 6-27. Port P3 and P4 Registers (Base Address: 0220h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P3 input	P3IN	00h
Port P3 output	P3OUT	02h
Port P3 direction	P3DIR	04h
Port P3 resistor enable	P3REN	06h
Port P3 drive strength	P3DS	08h
Port P3 selection	P3SEL	0Ah
Port P4 input	P4IN	01h
Port P4 output	P4OUT	03h
Port P4 direction	P4DIR	05h
Port P4 resistor enable	P4REN	07h
Port P4 drive strength	P4DS	09h
Port P4 selection	P4SEL	0Bh



Table 6-28. Port P5 and P6 Registers (Base Address: 0240h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P5 input	P5IN	00h
Port P5 output	P5OUT	02h
Port P5 direction	P5DIR	04h
Port P5 resistor enable	P5REN	06h
Port P5 drive strength	P5DS	08h
Port P5 selection	P5SEL	0Ah
Port P6 input	P6IN	01h
Port P6 output	P6OUT	03h
Port P6 direction	P6DIR	05h
Port P6 resistor enable	P6REN	07h
Port P6 drive strength	P6DS	09h
Port P6 selection	P6SEL	0Bh

Table 6-29. Port P7 and P8 Registers (Base Address: 0260h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P7 input	P7IN	00h
Port P7 output	P7OUT	02h
Port P7 direction	P7DIR	04h
Port P7 resistor enable	P7REN	06h
Port P7 drive strength	P7DS	08h
Port P7 selection	P7SEL	0Ah
Port P8 input	P8IN	01h
Port P8 output	P8OUT	03h
Port P8 direction	P8DIR	05h
Port P8 resistor enable	P8REN	07h
Port P8 drive strength	P8DS	09h
Port P8 selection	P8SEL	0Bh

Table 6-30. Port J Registers (Base Address: 0320h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port PJ input	PJIN	00h
Port PJ output	PJOUT	02h
Port PJ direction	PJDIR	04h
Port PJ resistor enable	PJREN	06h
Port PJ drive strength	PJDS	08h



Table 6-31. TA0 Registers (Base Address: 0340h)

REGISTER DESCRIPTION	REGISTER	OFFSET
TA0 control	TA0CTL	00h
Capture/compare control 0	TA0CCTL0	02h
Capture/compare control 1	TA0CCTL1	04h
Capture/compare control 2	TA0CCTL2	06h
Capture/compare control 3	TA0CCTL3	08h
Capture/compare control 4	TA0CCTL4	0Ah
TA0 counter	TA0R	10h
Capture/compare 0	TA0CCR0	12h
Capture/compare 1	TA0CCR1	14h
Capture/compare 2	TA0CCR2	16h
Capture/compare 3	TA0CCR3	18h
Capture/compare 4	TA0CCR4	1Ah
TA0 expansion 0	TA0EX0	20h
TA0 interrupt vector	TAOIV	2Eh

Table 6-32. TA1 Registers (Base Address: 0380h)

REGISTER DESCRIPTION	REGISTER	OFFSET
TA1 control	TA1CTL	00h
Capture/compare control 0	TA1CCTL0	02h
Capture/compare control 1	TA1CCTL1	04h
Capture/compare control 2	TA1CCTL2	06h
TA1 counter	TA1R	10h
Capture/compare 0	TA1CCR0	12h
Capture/compare 1	TA1CCR1	14h
Capture/compare 2	TA1CCR2	16h
TA1 expansion 0	TA1EX0	20h
TA1 interrupt vector	TA1IV	2Eh



Table 6-33. TB0 Registers (Base Address: 03C0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
TB0 control	TB0CTL	00h
Capture/compare control 0	TB0CCTL0	02h
Capture/compare control 1	TB0CCTL1	04h
Capture/compare control 2	TB0CCTL2	06h
Capture/compare control 3	TB0CCTL3	08h
Capture/compare control 4	TB0CCTL4	0Ah
Capture/compare control 5	TB0CCTL5	0Ch
Capture/compare control 6	TB0CCTL6	0Eh
TB0 counter	TB0R	10h
Capture/compare 0	TB0CCR0	12h
Capture/compare 1	TB0CCR1	14h
Capture/compare 2	TB0CCR2	16h
Capture/compare 3	TB0CCR3	18h
Capture/compare 4	TB0CCR4	1Ah
Capture/compare 5	TB0CCR5	1Ch
Capture/compare 6	TB0CCR6	1Eh
TB0 expansion 0	TB0EX0	20h
TB0 interrupt vector	TB0IV	2Eh

Table 6-34. TA2 Registers (Base Address: 0400h)

REGISTER DESCRIPTION	REGISTER	OFFSET
TA2 control	TA2CTL	00h
Capture/compare control 0	TA2CCTL0	02h
Capture/compare control 1	TA2CCTL1	04h
Capture/compare control 2	TA2CCTL2	06h
TA2 counter	TA2R	10h
Capture/compare 0	TA2CCR0	12h
Capture/compare 1	TA2CCR1	14h
Capture/compare 2	TA2CCR2	16h
TA2 expansion 0	TA2EX0	20h
TA2 interrupt vector	TA2IV	2Eh



Table 6-35. Real-Time Clock Registers (Base Address: 04A0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
RTC control 0	RTCCTL0	00h
RTC control 1	RTCCTL1	01h
RTC control 2	RTCCTL2	02h
RTC control 3	RTCCTL3	03h
RTC prescaler 0 control	RTCPS0CTL	08h
RTC prescaler 1 control	RTCPS1CTL	0Ah
RTC prescaler 0	RTCPS0	0Ch
RTC prescaler 1	RTCPS1	0Dh
RTC interrupt vector word	RTCIV	0Eh
RTC seconds, RTC counter 1	RTCSEC, RTCNT1	10h
RTC minutes, RTC counter 2	RTCMIN, RTCNT2	11h
RTC hours, RTC counter 3	RTCHOUR, RTCNT3	12h
RTC day of week, RTC counter 4	RTCDOW, RTCNT4	13h
RTC days	RTCDAY	14h
RTC month	RTCMON	15h
RTC year low	RTCYEARL	16h
RTC year high	RTCYEARH	17h
RTC alarm minutes	RTCAMIN	18h
RTC alarm hours	RTCAHOUR	19h
RTC alarm day of week	RTCADOW	1Ah
RTC alarm days	RTCADAY	1Bh



Table 6-36. 32-Bit Hardware Multiplier Registers (Base Address: 04C0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
16-bit operand 1 – multiply	MPY	00h
16-bit operand 1 – signed multiply	MPYS	02h
16-bit operand 1 – multiply accumulate	MAC	04h
16-bit operand 1 – signed multiply accumulate	MACS	06h
16-bit operand 2	OP2	08h
16 x 16 result low word	RESLO	0Ah
16 x 16 result high word	RESHI	0Ch
16 x 16 sum extension	SUMEXT	0Eh
32-bit operand 1 – multiply low word	MPY32L	10h
32-bit operand 1 – multiply high word	MPY32H	12h
32-bit operand 1 – signed multiply low word	MPYS32L	14h
32-bit operand 1 – signed multiply high word	MPYS32H	16h
32-bit operand 1 – multiply accumulate low word	MAC32L	18h
32-bit operand 1 – multiply accumulate high word	MAC32H	1Ah
32-bit operand 1 – signed multiply accumulate low word	MACS32L	1Ch
32-bit operand 1 – signed multiply accumulate high word	MACS32H	1Eh
32-bit operand 2 – low word	OP2L	20h
32-bit operand 2 – high word	OP2H	22h
32 x 32 result 0 – least significant word	RES0	24h
32 x 32 result 1	RES1	26h
32 x 32 result 2	RES2	28h
32 x 32 result 3 – most significant word	RES3	2Ah
MPY32 control 0	MPY32CTL0	2Ch



Table 6-37. DMA Registers (Base Address DMA General Control: 0500h, DMA Channel 0: 0510h, DMA Channel 1: 0520h, DMA Channel 2: 0530h)

REGISTER DESCRIPTION	REGISTER	OFFSET
DMA channel 0 control	DMA0CTL	00h
DMA channel 0 source address low	DMA0SAL	02h
DMA channel 0 source address high	DMA0SAH	04h
DMA channel 0 destination address low	DMA0DAL	06h
DMA channel 0 destination address high	DMA0DAH	08h
DMA channel 0 transfer size	DMA0SZ	0Ah
DMA channel 1 control	DMA1CTL	00h
DMA channel 1 source address low	DMA1SAL	02h
DMA channel 1 source address high	DMA1SAH	04h
DMA channel 1 destination address low	DMA1DAL	06h
DMA channel 1 destination address high	DMA1DAH	08h
DMA channel 1 transfer size	DMA1SZ	0Ah
DMA channel 2 control	DMA2CTL	00h
DMA channel 2 source address low	DMA2SAL	02h
DMA channel 2 source address high	DMA2SAH	04h
DMA channel 2 destination address low	DMA2DAL	06h
DMA channel 2 destination address high	DMA2DAH	08h
DMA channel 2 transfer size	DMA2SZ	0Ah
DMA module control 0	DMACTL0	00h
DMA module control 1	DMACTL1	02h
DMA module control 2	DMACTL2	04h
DMA module control 3	DMACTL3	06h
DMA module control 4	DMACTL4	08h
DMA interrupt vector	DMAIV	0Eh

Table 6-38. USCI_A0 Registers (Base Address: 05C0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
USCI control 1	UCA0CTL1	00h
USCI control 0	UCA0CTL0	01h
USCI baud rate 0	UCA0BR0	06h
USCI baud rate 1	UCA0BR1	07h
USCI modulation control	UCA0MCTL	08h
USCI status	UCA0STAT	0Ah
USCI receive buffer	UCA0RXBUF	0Ch
USCI transmit buffer	UCA0TXBUF	0Eh
USCI LIN control	UCA0ABCTL	10h
USCI IrDA transmit control	UCA0IRTCTL	12h
USCI IrDA receive control	UCA0IRRCTL	13h
USCI interrupt enable	UCA0IE	1Ch
USCI interrupt flags	UCA0IFG	1Dh
USCI interrupt vector word	UCA0IV	1Eh



Table 6-39. USCI_B0 Registers (Base Address: 05E0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
USCI synchronous control 1	UCB0CTL1	00h
USCI synchronous control 0	UCB0CTL0	01h
USCI synchronous bit rate 0	UCB0BR0	06h
USCI synchronous bit rate 1	UCB0BR1	07h
USCI synchronous status	UCB0STAT	0Ah
USCI synchronous receive buffer	UCB0RXBUF	0Ch
USCI synchronous transmit buffer	UCB0TXBUF	0Eh
USCI I2C own address	UCB0I2COA	10h
USCI I2C slave address	UCB0I2CSA	12h
USCI interrupt enable	UCB0IE	1Ch
USCI interrupt flags	UCB0IFG	1Dh
USCI interrupt vector word	UCB0IV	1Eh

Table 6-40. USCI_A1 Registers (Base Address: 0600h)

REGISTER DESCRIPTION	REGISTER	OFFSET
USCI control 1	UCA1CTL1	00h
USCI control 0	UCA1CTL0	01h
USCI baud rate 0	UCA1BR0	06h
USCI baud rate 1	UCA1BR1	07h
USCI modulation control	UCA1MCTL	08h
USCI status	UCA1STAT	0Ah
USCI receive buffer	UCA1RXBUF	0Ch
USCI transmit buffer	UCA1TXBUF	0Eh
USCI LIN control	UCA1ABCTL	10h
USCI IrDA transmit control	UCA1IRTCTL	12h
USCI IrDA receive control	UCA1IRRCTL	13h
USCI interrupt enable	UCA1IE	1Ch
USCI interrupt flags	UCA1IFG	1Dh
USCI interrupt vector word	UCA1IV	1Eh



Table 6-41. USCI_B1 Registers (Base Address: 0620h)

REGISTER DESCRIPTION	REGISTER	OFFSET
USCI synchronous control 1	UCB1CTL1	00h
USCI synchronous control 0	UCB1CTL0	01h
USCI synchronous bit rate 0	UCB1BR0	06h
USCI synchronous bit rate 1	UCB1BR1	07h
USCI synchronous status	UCB1STAT	0Ah
USCI synchronous receive buffer	UCB1RXBUF	0Ch
USCI synchronous transmit buffer	UCB1TXBUF	0Eh
USCI I2C own address	UCB1I2COA	10h
USCI I2C slave address	UCB1I2CSA	12h
USCI interrupt enable	UCB1IE	1Ch
USCI interrupt flags	UCB1IFG	1Dh
USCI interrupt vector word	UCB1IV	1Eh



Table 6-42. ADC12_A Registers (Base Address: 0700h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Control 0	ADC12CTL0	00h
Control 1	ADC12CTL1	02h
Control 2	ADC12CTL2	04h
Interrupt flag	ADC12IFG	0Ah
Interrupt enable	ADC12IE	0Ch
Interrupt vector word	ADC12IV	0Eh
ADC memory control 0	ADC12MCTL0	10h
ADC memory control 1	ADC12MCTL1	11h
ADC memory control 2	ADC12MCTL2	12h
ADC memory control 3	ADC12MCTL3	13h
ADC memory control 4	ADC12MCTL4	14h
ADC memory control 5	ADC12MCTL5	15h
ADC memory control 6	ADC12MCTL6	16h
ADC memory control 7	ADC12MCTL7	17h
ADC memory control 8	ADC12MCTL8	18h
ADC memory control 9	ADC12MCTL9	19h
ADC memory control 10	ADC12MCTL10	1Ah
ADC memory control 11	ADC12MCTL11	1Bh
ADC memory control 12	ADC12MCTL12	1Ch
ADC memory control 13	ADC12MCTL13	1Dh
ADC memory control 14	ADC12MCTL14	1Eh
ADC memory control 15	ADC12MCTL15	1Fh
Conversion memory 0	ADC12MEM0	20h
Conversion memory 1	ADC12MEM1	22h
Conversion memory 2	ADC12MEM2	24h
Conversion memory 3	ADC12MEM3	26h
Conversion memory 4	ADC12MEM4	28h
Conversion memory 5	ADC12MEM5	2Ah
Conversion memory 6	ADC12MEM6	2Ch
Conversion memory 7	ADC12MEM7	2Eh
Conversion memory 8	ADC12MEM8	30h
Conversion memory 9	ADC12MEM9	32h
Conversion memory 10	ADC12MEM10	34h
Conversion memory 11	ADC12MEM11	36h
Conversion memory 12	ADC12MEM12	38h
Conversion memory 13	ADC12MEM13	3Ah
Conversion memory 14	ADC12MEM14	3Ch
Conversion memory 15	ADC12MEM15	3Eh



Table 6-43. Comparator_B Registers (Base Address: 08C0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Comp_B control 0	CBCTL0	00h
Comp_B control 1	CBCTL1	02h
Comp_B control 2	CBCTL2	04h
Comp_B control 3	CBCTL3	06h
Comp_B interrupt	CBINT	0Ch
Comp_B interrupt vector word	CBIV	0Eh

Table 6-44. USB Configuration Registers (Base Address: 0900h)

REGISTER DESCRIPTION	REGISTER	OFFSET
USB key and ID	USBKEYID	00h
USB module configuration	USBCNF	02h
USB PHY control	USBPHYCTL	04h
USB power control	USBPWRCTL	08h
USB PLL control	USBPLLCTL	10h
USB PLL divider	USBPLLDIV	12h
USB PLL interrupts	USBPLLIR	14h

Table 6-45. USB Control Registers (Base Address: 0920h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Input endpoint_0 configuration	USBIEPCNF_0	00h
Input endpoint_0 byte count	USBIEPCNT_0	01h
Output endpoint_0 configuration	USBOEPCNF_0	02h
Output endpoint_0 byte count	USBOEPCNT_0	03h
Input endpoint interrupt enables	USBIEPIE	0Eh
Output endpoint interrupt enables	USBOEPIE	0Fh
Input endpoint interrupt flags	USBIEPIFG	10h
Output endpoint interrupt flags	USBOEPIFG	11h
USB interrupt vector	USBIV	12h
USB maintenance	USBMAINT	16h
Timestamp	USBTSREG	18h
USB frame number	USBFN	1Ah
USB control	USBCTL	1Ch
USB interrupt enables	USBIE	1Dh
USB interrupt flags	USBIFG	1Eh
Function address	USBFUNADR	1Fh



6.10 Input/Output Diagrams

6.10.1 Port P1 (P1.0 to P1.7) Input/Output With Schmitt Trigger

Figure 6-2 shows the port diagram. Table 6-46 summarizes the selection of the pin function.

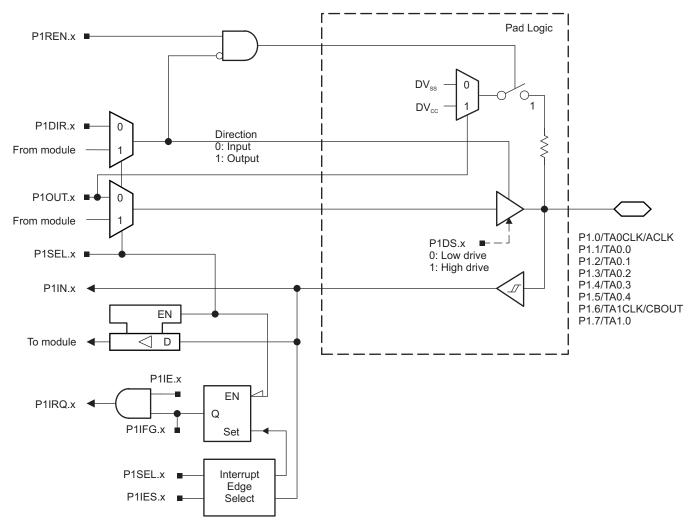


Figure 6-2. Port P1 (P1.0 to P1.7) Diagram



Table 6-46. Port P1 (P1.0 to P1.7) Pin Functions

DINI NIAME (D4)		FUNCTION	CONTROL BITS	S OR SIGNALS
PIN NAME (P1.x)	X	FUNCTION	P1DIR.x	P1SEL.x
		P1.0 (I/O)	I: 0; O: 1	0
P1.0/TA0CLK/ACLK	0	TAOCLK	0	1
		ACLK	1	1
		P1.1 (I/O)	I: 0; O: 1	0
P1.1/TA0.0	1	TA0.CCI0A	0	1
		TA0.0	1	1
		P1.2 (I/O)	I: 0; O: 1	0
P1.2/TA0.1	2	TA0.CCI1A	0	1
		TA0.1	1	1
		P1.3 (I/O)	I: 0; O: 1	0
P1.3/TA0.2	3	TA0.CCI2A	0	1
		TA0.2	1	1
		P1.4 (I/O)	I: 0; O: 1	0
P1.4/TA0.3	4	TA0.CCI3A	0	1
		TA0.3	1	1
		P1.5 (I/O)	I: 0; O: 1	0
P1.5/TA0.4	5	TA0.CCI4A	0	1
		TA0.4	1	1
		P1.6 (I/O)	I: 0; O: 1	0
P1.6/TA1CLK/CBOUT	6	TA1CLK	0	1
		CBOUT comparator B	1	1
		P1.7 (I/O)	I: 0; O: 1	0
P1.7/TA1.0	7	TA1.CCI0A	0	1
		TA1.0	1	1

6.10.2 Port P2 (P2.0 to P2.7) Input/Output With Schmitt Trigger

Figure 6-3 shows the port diagram. Table 6-47 summarizes the selection of the pin function.

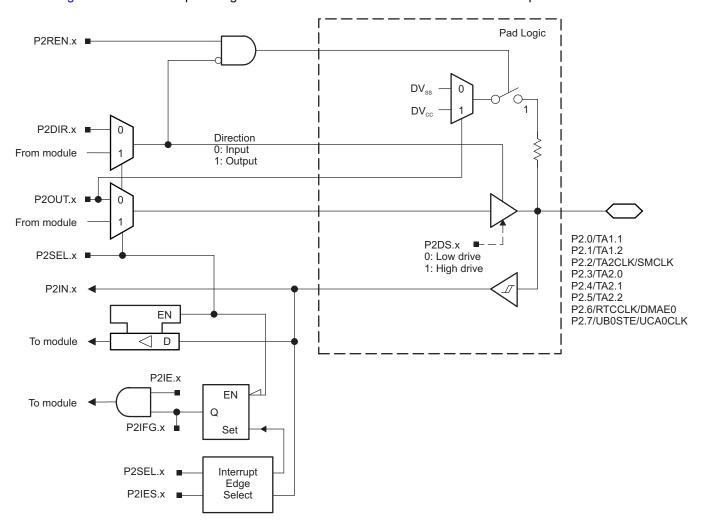


Figure 6-3. Port P2 (P2.0 to P2.7) Diagram



Table 6-47. Port P2 (P2.0 to P2.7) Pin Functions

DIN NAME (D2 v)		FUNCTION	CONTROL BITS	CONTROL BITS OR SIGNALS ⁽¹⁾		
PIN NAME (P2.x)	X	FUNCTION	P2DIR.x	P2SEL.x		
		P2.0 (I/O)	I: 0; O: 1	0		
P2.0/TA1.1	0	TA1.CCI1A	0	1		
		TA1.1	1	1		
		P2.1 (I/O)	I: 0; O: 1	0		
P2.1/TA1.2	1	TA1.CCI2A	0	1		
		TA1.2	1	1		
		P2.2 (I/O)	I: 0; O: 1	0		
P2.2/TA2CLK/SMCLK	2	TA2CLK	0	1		
		SMCLK	1	1		
		P2.3 (I/O)	I: 0; O: 1	0		
P2.3/TA2.0	3	TA2.CCI0A	0	1		
		TA2.0	1	1		
		P2.4 (I/O)	I: 0; O: 1	0		
P2.4/TA2.1	4	TA2.CCI1A	0	1		
		TA2.1	1	1		
		P2.5 (I/O)	I: 0; O: 1	0		
P2.5/TA2.2	5	TA2.CCI2A	0	1		
		TA2.2	1	1		
		P2.6 (I/O)	I: 0; O: 1	0		
P2.6/RTCCLK/DMAE0	6	DMAE0	0	1		
		RTCCLK	1	1		
D0 7/LICDOCTE/LICACOLIA	7	P2.7 (I/O)	I: 0; O: 1	0		
P2.7/UCB0STE/UCA0CLK	7	UCB0STE/UCA0CLK(2) (3)	X	1		

⁽¹⁾ X = Don't care

²⁾ The pin direction is controlled by the USCI module.

⁽³⁾ UCAOCLK function takes precedence over UCBOSTE function. If the pin is required as UCAOCLK input or output, USCI B0 is forced to 3-wire SPI mode if 4-wire SPI mode is selected.

6.10.3 Port P3 (P3.0 to P3.7) Input/Output With Schmitt Trigger

Figure 6-4 shows the port diagram. Table 6-48 summarizes the selection of the pin function.

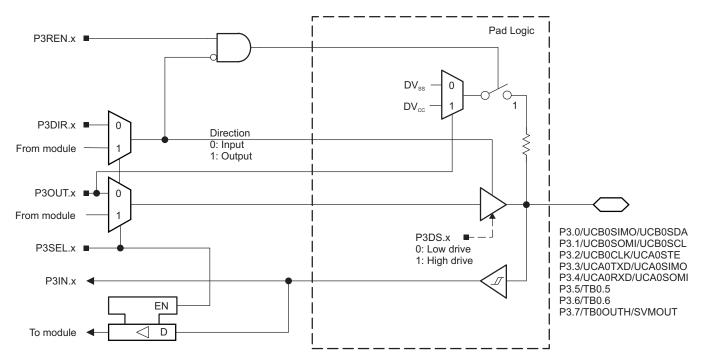


Figure 6-4. Port P3 (P3.0 to P3.7) Diagram



www.ti.com.cn

Table 6-48. Port P3 (P3.0 to P3.7) Pin Functions

DIN NAME (DO)		FUNCTION	CONTROL BITS OR SIGNALS ⁽¹⁾		
PIN NAME (P3.x)	X	FUNCTION	P3DIR.x	P3SEL.x	
P3.0/UCB0SIMO/UCB0SDA	0	P3.0 (I/O)	I: 0; O: 1	0	
F3.0/UCBUSINIO/UCBUSDA	U	UCB0SIMO/UCB0SDA (2) (3)	X	1	
P3.1/UCB0SOMI/UCB0SCL	4	P3.1 (I/O)	I: 0; O: 1	0	
F3.1/UCBUSOWII/UCBUSCL	ı	UCB0SOMI/UCB0SCL (2) (3)	X	1	
P3.2/UCB0CLK/UCA0STE	2	P3.2 (I/O)	I: 0; O: 1	0	
P3.2/UCBUCLN/UCAUSTE	2	UCB0CLK/UCA0STE (2) (4)	X	1	
D2 2/LICAOTYD/LICAOSIMO	3	P3.3 (I/O)	I: 0; O: 1	0	
P3.3/UCA0TXD/UCA0SIMO	3	UCA0TXD/UCA0SIMO ⁽²⁾	X	1	
D0 4/110 4 0D VD /110 4 00 0 MI	4	P3.4 (I/O)	I: 0; O: 1	0	
P3.4/UCA0RXD/UCA0SOMI	4	UCA0RXD/UCA0SOMI(2)	X	1	
		P3.5 (I/O)	I: 0; O: 1	0	
P3.5/TB0.5 ⁽⁵⁾	5	TB0.CCI5A	0	1	
		TB0.5	1	1	
		P3.6 (I/O)	I: 0; O: 1	0	
P3.6/TB0.6 ⁽⁵⁾	6	TB0.CCI6A	0	1	
		TB0.6	1	1	
		P3.7 (I/O)	I: 0; O: 1	0	
P3.7/TB0OUTH/SVMOUT ⁽⁵⁾	7	TB0OUTH	0	1	
		SVMOUT	1	1	

X = Don't care

The pin direction is controlled by the USCI module.

⁽³⁾

If the I^2 C functionality is selected, the output drives only the logical 0 to V_{SS} level. UCB0CLK function takes precedence over UCA0STE function. If the pin is required as UCB0CLK input or output, USCI A0 is forced to 3-wire SPI mode if 4-wire SPI mode is selected.

F5529, F5527, F5525, F5521, F5519, F5517, F5515 devices only.

6.10.4 Port P4 (P4.0 to P4.7) Input/Output With Schmitt Trigger

Figure 6-5 shows the port diagram. Table 6-49 summarizes the selection of the pin function.

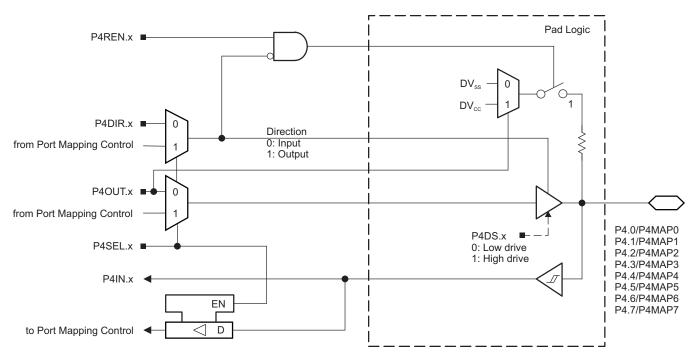


Figure 6-5. Port P4 (P4.0 to P4.7) Diagram

Table 6-49. Port P4 (P4.0 to P4.7) Pin Functions

DINI NAME (D4 m)		FUNCTION	CONTR	CONTROL BITS OR SIGNALS			
PIN NAME (P4.x)	X		P4DIR.x ⁽¹⁾	P4SEL.x	P4MAPx		
P4.0/P4MAP0	0	P4.0 (I/O)	I: 0; O: 1	0	X		
P4.0/P4IVIAP0	U	Mapped secondary digital function	X	1	≤ 30		
D4.4/D4MAD4	1	P4.1 (I/O)	I: 0; O: 1	0	Х		
P4.1/P4MAP1	1	Mapped secondary digital function	X	1	≤ 30		
D4 2/D4MAD2	2	P4.2 (I/O)	I: 0; O: 1	0	X		
P4.2/P4MAP2	2	Mapped secondary digital function	Х	1	≤ 30		
D4 2/D4MA D2		P4.3 (I/O)	I: 0; O: 1	0	X		
P4.3/P4MAP3	3	Mapped secondary digital function	Х	1	≤ 30		
D4 4/D4MAD4	4	P4.4 (I/O)	I: 0; O: 1	0	Х		
P4.4/P4MAP4	4	Mapped secondary digital function	Х	1	≤ 30		
D4.5/D4MAD5	5	P4.5 (I/O)	I: 0; O: 1	0	X		
P4.5/P4MAP5	5	Mapped secondary digital function	Х	1	≤ 30		
DA C/DAMA DC	_	P4.6 (I/O)	I: 0; O: 1	0	Х		
P4.6/P4MAP6	6	Mapped secondary digital function	Х	1	≤ 30		
D4.7/D4MAD7	7	P4.7 (I/O)	I: 0; O: 1	0	Х		
P4.7/P4MAP7	1	Mapped secondary digital function	X	1	≤ 30		

⁽¹⁾ The direction of some mapped secondary functions are controlled directly by the module. See Table 6-7 for specific direction control information of mapped secondary functions.



6.10.5 Port P5 (P5.0 and P5.1) Input/Output With Schmitt Trigger

Figure 6-6 shows the port diagram. Table 6-50 summarizes the selection of the pin function.

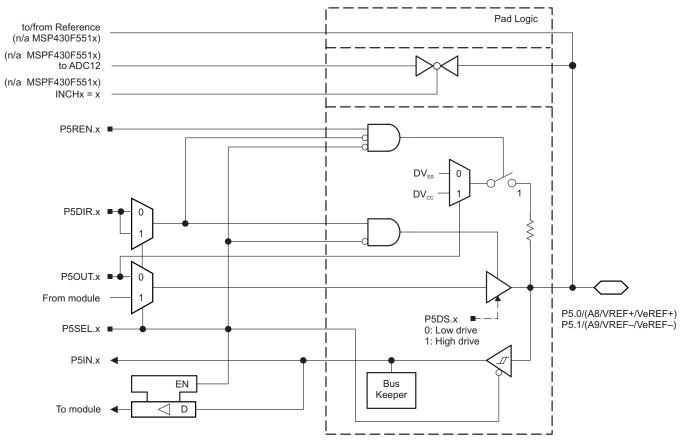


Figure 6-6. Port P5 (P5.0 and P5.1) Diagram



Table 6-50. Port P5 (P5.0 and P5.1) Pin Functions

DIN MAME (DE)	x	FUNCTION	CONTROL BITS OR SIGNALS ⁽¹⁾		
PIN NAME (P5.x)			P5DIR.x	P5SEL.x	REFOUT
P5.0/A8/VREF+/VeREF+ ⁽²⁾	0	P5.0 (I/O) ⁽³⁾	I: 0; O: 1	0	Х
		A8/VeREF+ ⁽⁴⁾	Х	1	0
		A8/VREF+ ⁽⁵⁾	Х	1	1
P5.1/A9/VREF-/VeREF- ⁽⁶⁾	1	P5.1 (I/O) ⁽³⁾	I: 0; O: 1	0	Х
		A9/VeREF-(7)	Х	1	0
		A9/VREF-(8)	X	1	1

- (1) X = Don't care
- (2) VREF+/VeREF+ available on MSP430F552x devices only.
- 3) Default condition
- (4) Setting the P5SEL.0 bit disables the output driver and the input Schmitt trigger to prevent parasitic cross currents when applying analog signals. An external voltage can be applied to VeREF+ and used as the reference for the ADC12_A when available. Channel A8, when selected with the INCHx bits, is connected to the VREF+/VeREF+ pin.
- (5) Setting the P5SEL.0 bit disables the output driver and the input Schmitt trigger to prevent parasitic cross currents when applying analog signals. The VREF+ reference is available at the pin. Channel A8, when selected with the INCHx bits, is connected to the VREF+/VeREF+ pin.
- (6) VREF-/VeREF- available on MSP430F552x devices only.
- (7) Setting the P5SEL.1 bit disables the output driver and the input Schmitt trigger to prevent parasitic cross currents when applying analog signals. An external voltage can be applied to VeREF- and used as the reference for the ADC12_A when available. Channel A9, when selected with the INCHx bits, is connected to the VREF-/VeREF- pin.
- (8) Setting the P5SEL.1 bit disables the output driver and the input Schmitt trigger to prevent parasitic cross currents when applying analog signals. The VREF- reference is available at the pin. Channel A9, when selected with the INCHx bits, is connected to the VREF-/VeREF- pin.



6.10.6 Port P5 (P5.2 and P5.3) Input/Output With Schmitt Trigger

Figure 6-7 and Figure 6-8 show the port diagrams. Table 6-51 summarizes the selection of the pin function.

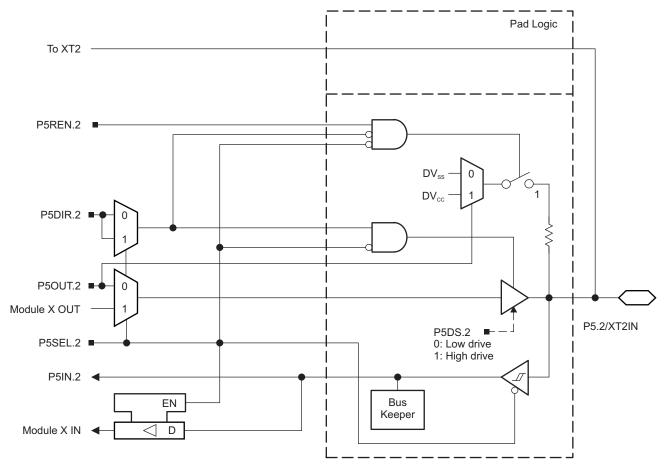


Figure 6-7. Port P5 (P5.2) Diagram

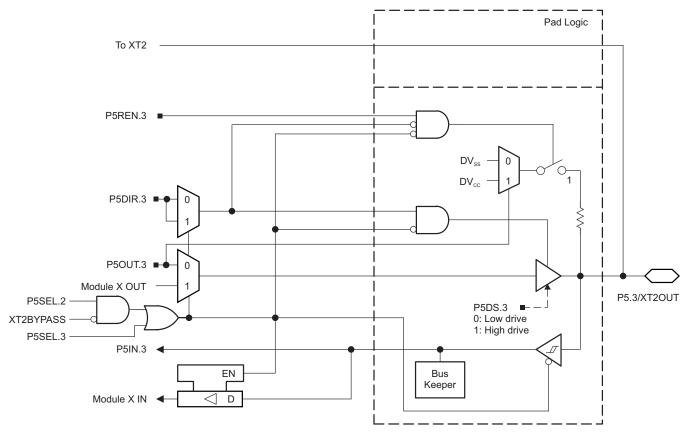


Figure 6-8. Port P5 (P5.3) Diagram

Table 6-51. Port P5 (P5.2 and P5.3) Pin Functions

DIN NAME (DE v.)		FUNCTION	CONTROL BITS OR SIGNALS ⁽¹⁾			
PIN NAME (P5.x)	X	FUNCTION	P5DIR.x	P5SEL.2	P5SEL.3	XT2BYPASS
		P5.2 (I/O)	I: 0; O: 1	0	X	X
P5.2/XT2IN	2	XT2IN crystal mode (2)	Х	1	Х	0
		XT2IN bypass mode (2)	Х	1	Х	1
		P5.3 (I/O)	I: 0; O: 1	0	0	Х
P5.3/XT2OUT	3	XT2OUT crystal mode (3)	Х	1	Х	0
		P5.3 (I/O) ⁽³⁾	Х	1	0	1

⁽¹⁾ X = Don't care

⁽²⁾ Setting P5SEL.2 causes the general-purpose I/O to be disabled. Pending the setting of XT2BYPASS, P5.2 is configured for crystal mode or bypass mode.

⁽³⁾ Setting PSSEL.2 causes the general-purpose I/O to be disabled in crystal mode. When using bypass mode, P5.3 can be used as general-purpose I/O.



6.10.7 Port P5 (P5.4 and P5.5) Input/Output With Schmitt Trigger

Figure 6-9 and Figure 6-10 show the port diagrams. Table 6-52 summarizes the selection of the pin function.

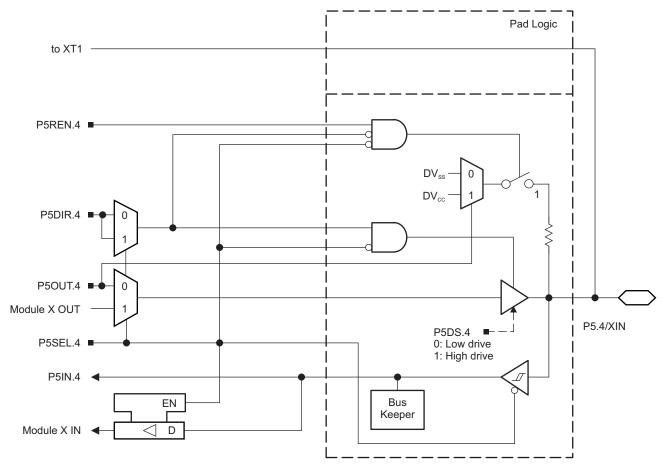


Figure 6-9. Port P5 (P5.4) Diagram

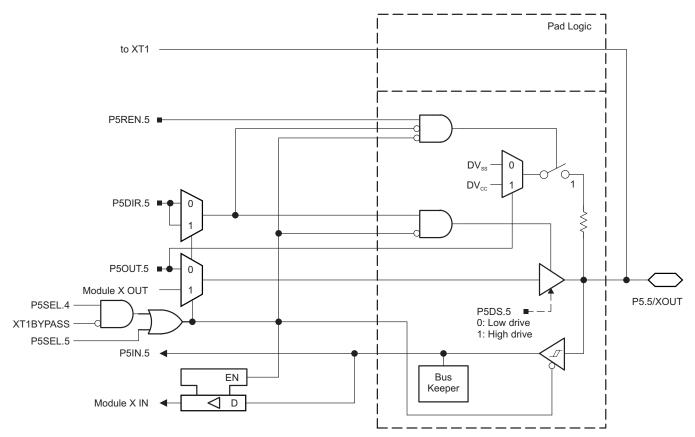


Figure 6-10. Port P5 (P5.5) Diagram

Table 6-52. Port P5 (P5.4 and P5.5) Pin Functions

DIN NAME (DE)	.,	FUNCTION	CONTROL BITS OR SIGNALS ⁽¹⁾				
PIN NAME (P5.x)	X	FUNCTION	P5DIR.x	P5SEL.4	P5SEL.5	XT1BYPASS	
		P5.4 (I/O)	I: 0; O: 1	0	X	X	
P5.4/XIN	4	XIN crystal mode ⁽²⁾	X	1	Х	0	
		XIN bypass mode ⁽²⁾	X	1	Х	1	
P5.5/XOUT		P5.5 (I/O)	I: 0; O: 1	0	0	Х	
	5	XOUT crystal mode ⁽³⁾	Х	1	Х	0	
		P5.5 (I/O) ⁽³⁾	Х	1	0	1	

⁽¹⁾ X = Don't care

⁽²⁾ Setting P5SEL.4 causes the general-purpose I/O to be disabled. Pending the setting of XT1BYPASS, P5.4 is configured for crystal mode or bypass mode.

⁽³⁾ Setting PSSEL.4 causes the general-purpose I/O to be disabled in crystal mode. When using bypass mode, P5.5 can be used as general-purpose I/O.



6.10.8 Port P5 (P5.6 and P5.7) Input/Output With Schmitt Trigger

Figure 6-11 shows the port diagram. Table 6-53 summarizes the selection of the pin function.

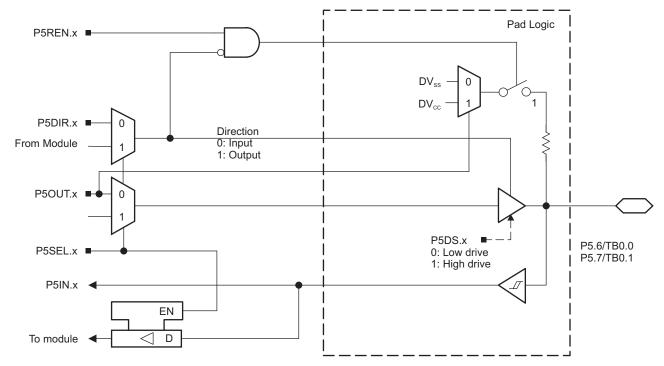


Figure 6-11. Port P5 (P5.6 and P5.7) Diagram

Table 6-53. Port P5 (P5.6 and P5.7) Pin Functions

PIN NAME (P5.x)		FUNCTION	CONTROL BITS OR SIGNALS		
	X		P5DIR.x	P5SEL.x	
		P5.6 (I/O)	I: 0; O: 1	0	
P5.6/TB0.0 ⁽¹⁾	6	TB0.CCI0A	0	1	
		TB0.0	1	1	
P5.7/TB0.1 ⁽¹⁾	7	TB0.CCI1A	0	1	
	′	TB0.1	1	1	

⁽¹⁾ F5529, F5527, F5525, F5521, F5519, F5517, F5515 devices only.

6.10.9 Port P6 (P6.0 to P6.7) Input/Output With Schmitt Trigger

Figure 6-12 shows the port diagram. Table 6-54 summarizes the selection of the pin function.

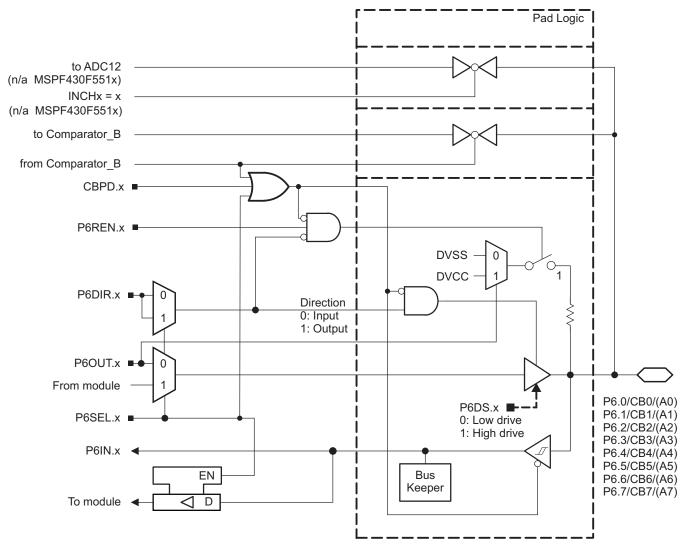


Figure 6-12. Port P6 (P6.0 to P6.7) Diagram



Table 6-54. Port P6 (P6.0 to P6.7) Pin Functions

DIN NAME (DC :-)		FUNCTION	CONTR	CONTROL BITS OR SIGNALS			
PIN NAME (P6.x)	X		P6DIR.x	P6SEL.x	CBPD		
		P6.0 (I/O)	I: 0; O: 1	0	0		
P6.0/CB0/(A0)	0	A0 (only MSP430F552x)	X	1	Х		
		CB0 ⁽¹⁾	X	Х	1		
		P6.1 (I/O)	I: 0; O: 1	0	0		
P6.1/CB1/(A1)	1	A1 (only MSP430F552x)	X	1	X		
		CB1 ⁽¹⁾	X	X	1		
		P6.2 (I/O)	I: 0; O: 1	0	0		
P6.2/CB2/(A2)	2	A2 (only MSP430F552x)	X	1	Х		
		CB2 ⁽¹⁾	Х	Х	1		
		P6.3 (I/O)	I: 0; O: 1	0	0		
P6.3/CB3/(A3)	3	A3 (only MSP430F552x)	X	1	Х		
		CB3 ⁽¹⁾	X	Х	1		
		P6.4 (I/O)	I: 0; O: 1	0	0		
P6.4/CB4/(A4)	4	A4 (only MSP430F552x)	Х	1	Х		
		CB4 ⁽¹⁾	Х	Х	1		
		P6.5 (I/O)	I: 0; O: 1	0	0		
P6.5/CB5/(A5)	5	A5 (only MSP430F552x)	X	1	Χ		
		CB5 ⁽¹⁾	X	X	1		
		P6.6 (I/O)	I: 0; O: 1	0	0		
P6.6/CB6/(A6)	6	A6 (only MSP430F552x)	Х	1	Χ		
		CB6 ⁽¹⁾	Х	Х	1		
		P6.7 (I/O)	I: 0; O: 1	0	0		
P6.7/CB7/(A7)	7	A7 (only MSP430F552x)	Х	1	Χ		
		CB7 ⁽¹⁾	Х	Х	1		

⁽¹⁾ Setting the CBPD.x bit disables the output driver and the input Schmitt trigger to prevent parasitic cross currents when applying analog signals. Selecting the CBx input pin to the comparator multiplexer with the CBx bits automatically disables output driver and input buffer for that pin, regardless of the state of the associated CBPD.x bit.

6.10.10 Port P7 (P7.0 to P7.3) Input/Output With Schmitt Trigger

Figure 6-13 shows the port diagram. Table 6-55 summarizes the selection of the pin function.

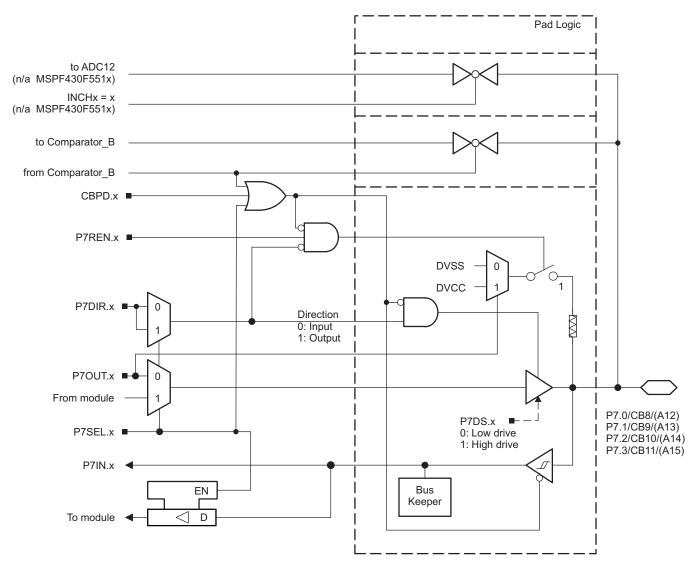


Figure 6-13. Port P7 (P7.0 to P7.3) Diagram



Table 6-55. Port P7 (P7.0 to P7.3) Pin Functions

PIN NAME (P7.x)		FUNCTION	CONTROL BITS OR SIGNALS						
PIN NAME (P7.X)	X	FUNCTION	P7DIR.x	P7SEL.x	CBPD				
		P7.0 (I/O) ⁽¹⁾	I: 0; O: 1	0	0				
P7.0/CB8/(A12)	0	A12 ⁽²⁾	X	1	Х				
		CB8 ⁽³⁾ (1)	X	Х	1				
		P7.1 (I/O) ⁽¹⁾	I: 0; O: 1	0	0				
7.0/CB8/(A12) 7.1/CB9/(A13) 7.2/CB10/(A14)	1	A13 ⁽²⁾	Х	1	Х				
		CB9 ⁽³⁾ (1)	X	Х	1				
		P7.2 (I/O) ⁽¹⁾	I: 0; O: 1	0	0				
P7.2/CB10/(A14)) 2 / (C) F (C) F (C) F (C) F (C) F (C) F	A14 ⁽²⁾	X	1	Х				
		CB10 ⁽³⁾ (1)	X	P7SEL.x CB 0 (0) 1 (1) X (1) 0 (1) 1 (2)	1				
		P7.3 (I/O) ⁽¹⁾	I: 0; O: 1	0	0				
P7.3/CB11/(A15)	3	A15 ⁽²⁾	X	1	Х				
		CB11 ⁽³⁾ (1)	Х	Х	1				

F5529, F5527, F5525, F5521, F5519, F5517, F5515 devices only

F5529, F5527, F5525, F5521 devices only

Setting the CBPD.x bit disables the output driver and the input Schmitt trigger to prevent parasitic cross currents when applying analog signals. Selecting the CBx input pin to the comparator multiplexer with the CBx bits automatically disables output driver and input buffer for that pin, regardless of the state of the associated CBPD.x bit.

6.10.11 Port P7 (P7.4 to P7.7) Input/Output With Schmitt Trigger

Figure 6-14 shows the port diagram. Table 6-56 summarizes the selection of the pin function.

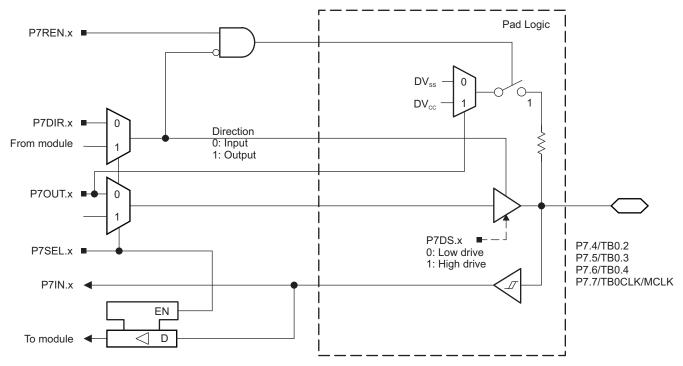


Figure 6-14. Port P7 (P7.4 to P7.7) Diagram

Table 6-56. Port P7 (P7.4 to P7.7) Pin Functions

PIN NAME (P7.x) x FUNCTION		FUNCTION	CONTROL BITS OR SIGNA			
PIN NAME (P7.X)	X	FUNCTION	P7DIR.x	P7SEL.x		
		P7.4 (I/O)	I: 0; O: 1	0		
P7.4/TB0.2 ⁽¹⁾	4	TB0.CCI2A	0	1		
		TB0.2	1	1		
P7.5/TB0.3 ⁽¹⁾		P7.5 (I/O)	I: 0; O: 1	0		
	5	TB0.CCI3A	0	1		
		TB0.3	1	1		
		P7.6 (I/O)	I: 0; O: 1	0		
P7.6/TB0.4 ⁽¹⁾	6	TB0.CCI4A	0	1		
		TB0.4	1	1		
		P7.7 (I/O)	I: 0; O: 1	0		
P7.7/TB0CLK/MCLK ⁽¹⁾	7	TB0CLK	0	1		
		MCLK	1	1		

⁽¹⁾ F5529, F5527, F5525, F5521, F5519, F5517, F5515 devices only



6.10.12 Port P8 (P8.0 to P8.2) Input/Output With Schmitt Trigger

Figure 6-15 shows the port diagram. Table 6-57 summarizes the selection of the pin function.

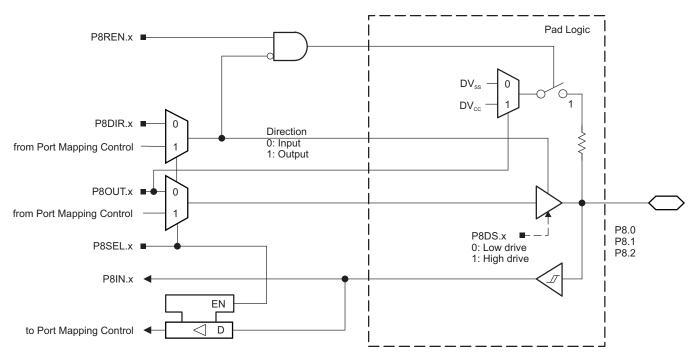


Figure 6-15. Port P8 (P8.0 to P8.2) Diagram

Table 6-57. Port P8 (P8.0 to P8.2) Pin Functions

PIN NAME (P8.x)		FUNCTION	CONTROL BITS OR SIGNALS			
	X	FUNCTION	P8DIR.x	P8SEL.x		
P8.0 ⁽¹⁾	0	P8.0(I/O)	I: 0; O: 1	0		
P8.1 ⁽¹⁾	1	P8.1(I/O)	I: 0; O: 1	0		
P8.2 ⁽¹⁾	2	P8.2(I/O)	I: 0; O: 1	0		

(1) F5529, F5527, F5525, F5521, F5519, F5517, F5515 devices only

6.10.13 Port PU (PU.0/DP, PU.1/DM, PUR) USB Ports

Figure 6-16 shows the port diagram. Table 6-58 through Table 6-60 summarize the pin function selection.

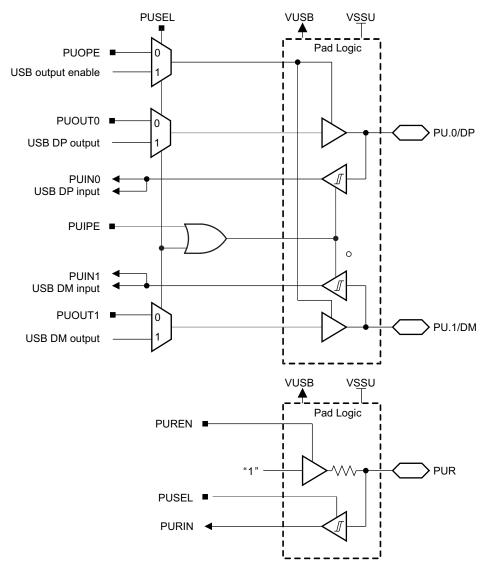


Figure 6-16. Port PU (PU.0/DP, PU.1/DM) Diagram



Table 6-58. Port PU (PU.0/DP, PU.1/DM) Output Functions (1)

	CONTR	OL BITS	PIN NAME			
PUSEL	PUOPE	PUOUT1	IT1 PUOUT0 PU.1		PU.0/DP	
0	0	X	X	Output disabled	Output disabled	
0	1	0	0	Output low	Output low	
0	1	0	1	Output low	Output high	
0	1	1	0	Output high	Output low	
0	1	1	1	Output high	Output high	
1	Х	Х	Х	DM ⁽²⁾	DP ⁽²⁾	

⁽¹⁾ PU.1/DM and PU.0/DP inputs and outputs are supplied from VUSB. VUSB can be generated by the device using the integrated 3.3-V LDO when enabled. VUSB can also be supplied externally when the 3.3-V LDO is not being used and is disabled.

Table 6-59. Port PU (PU.0/DP, PU.1/DM) Input Functions (1)

CONTRO	OL BITS	PIN NAME					
PUSEL	PUIPE	PU.1/DM	PU.0/DP				
0	0	Input disabled	Input disabled				
0	1	Input enabled	Input enabled				
1	X	DM input	DP input				

⁽¹⁾ PU.1/DM and PU.0/DP inputs and outputs are supplied from VUSB. VUSB can be generated by the device using the integrated 3.3-V LDO when enabled. VUSB can also be supplied externally when the 3.3-V LDO is not being used and is disabled.

Table 6-60. Port PUR Input Functions

CONTR	OL BITS	FUNCTION
PUSEL	PUREN	FUNCTION
0	0	Input disabled Pullup disabled
0	1	Input disabled Pullup enabled
1	0	Input enabled Pullup disabled
1	1	Input enabled Pullup enabled

⁽²⁾ Output state set by the USB module.

6.10.14 Port PJ (PJ.0) JTAG Pin TDO, Input/Output With Schmitt Trigger or Output

Figure 6-17 shows the port diagram. Table 6-61 summarizes the selection of the pin function.

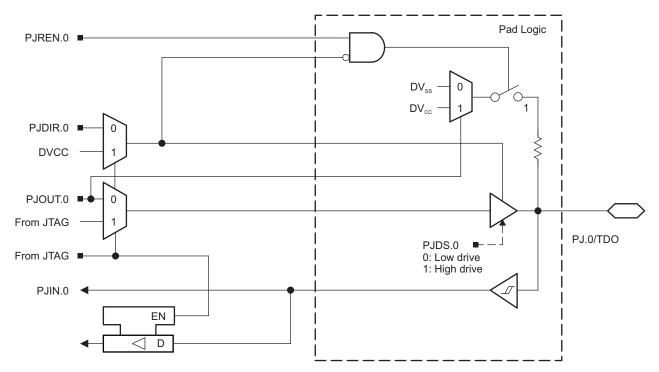


Figure 6-17. Port J (PJ.0) Diagram



6.10.15 Port PJ (PJ.1 to PJ.3) JTAG Pins TMS, TCK, TDI/TCLK, Input/Output With Schmitt Trigger or Output

Figure 6-18 shows the port diagram. Table 6-61 summarizes the selection of the pin function.

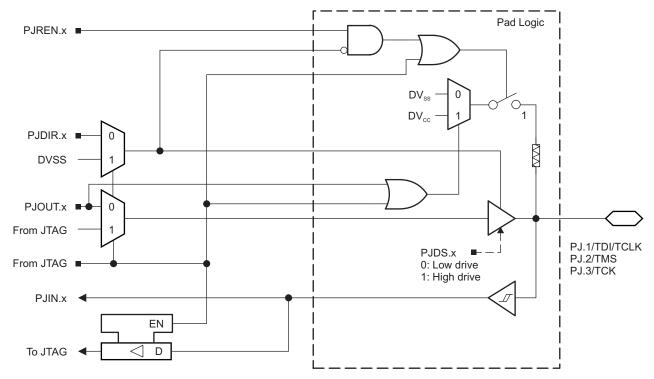


Figure 6-18. Port J (PJ.1 to PJ.3) Diagram

Table 6-61. Port PJ (PJ.0 to PJ.3) Pin Functions

PIN NAME (PJ.x)	х	FUNCTION	CONTROL BITS OR SIGNALS ⁽¹⁾
,			PJDIR.x
DIO/TDO	0	PJ.0 (I/O) ⁽²⁾	I: 0; O: 1
PJ.0/TDO	0	TDO ⁽³⁾	X
DIA/TDI/TOLK		PJ.1 (I/O) ⁽²⁾	I: 0; O: 1
PJ.1/TDI/TCLK	1	TDI/TCLK ⁽³⁾ (4)	X
D LO/TMC	0	PJ.2 (I/O) ⁽²⁾	I: 0; O: 1
PJ.2/TMS	2	TMS ⁽³⁾ (4)	X
D L 2/TCV	2	PJ.3 (I/O) ⁽²⁾	I: 0; O: 1
PJ.3/TCK	3	TCK ⁽³⁾ (4)	X

⁽¹⁾ X = Don't care

⁽²⁾ Default condition

⁽³⁾ The pin direction is controlled by the JTAG module.

⁽⁴⁾ In JTAG mode, pullups are activated automatically on TMS, TCK, and TDI/TCLK. PJREN.x are do not care.



6.11 Device Descriptors (TLV)

Table 6-62 and Table 6-63 list the complete contents of the device descriptor tag-length-value (TLV) structure for each device type.

Table 6-62. MSP430F552x Device Descriptor Table (1)

_	ACCORIDATION.	ADDRESS	SIZE				VA	LUE			
DESCRIPTION		ADDRESS	(bytes)	F5529	F5528	F5527	F5526	F5525	F5524	F5522	F5521
	Info length	01A00h	1	06h							
Info Block	CRC length	01A01h	1	06h							
	CRC value	01A02h	2	Per unit							
	Device ID	01A04h	1	55h							
	Device ID	01A05h	1	29h	28h	27h	26h	25h	24h	22h	21h
	Hardware revision	01A06h	1	Per unit							
	Firmware revision	01A07h	1	Per unit							
	Die record tag	01A08h	1	08h							
Die Record	Die record length	01A09h	1	0Ah							
	Lot/wafer ID	01A0Ah	4	Per unit							
Die Record	Die X position	01A0Eh	2	Per unit							
	Die Y position	01A10h	2	Per unit							
	Test results	01A12h	2	Per unit							
	ADC12 calibration tag	01A14h	1	11h							
	ADC12 calibration length	01A15h	1	10h							
	ADC gain factor	01A16h	2	Per unit							
	ADC offset	01A18h	2	Per unit							
	ADC 1.5-V reference Temperature sensor 30°C	01A1Ah	2	Per unit							
ADC12 Calibration	ADC 1.5-V reference Temperature sensor 85°C	01A1Ch	2	Per unit							
Calibration	ADC 2.0-V reference Temperature sensor 30°C	01A1Eh	2	Per unit							
	ADC 2.0-V reference Temperature sensor 85°C	01A20h	2	Per unit							
	ADC 2.5-V reference Temperature sensor 30°C	01A22h	2	Per unit							
	ADC 2.5-V reference Temperature sensor 85°C	01A24h	2	Per unit							
	REF calibration tag	01A26h	1	12h							
	REF calibration length	01A27h	1	06h							
REF	REF 1.5-V reference factor	01A28h	2	Per unit							
Calibration	REF 2.0-V reference factor	01A2Ah	2	Per unit							
	REF 2.5-V reference factor	01A2Ch	2	Per unit							



Table 6-62. MSP430F552x Device Descriptor Table⁽¹⁾ (continued)

DESCRIPTION ADDRESS		SIZE	VALUE								
		ADDRESS	(bytes)	F5529	F5528	F5527	F5526	F5525	F5524	F5522	F5521
	Peripheral descriptor tag	01A2Eh	1	02h							
	Peripheral descriptor length	01A2Fh	1	63h	61h	65h	63h	63h	61h	61h	64h
	Memory 1		2	08h 8Ah							
	Memory 2		2	0Ch 86h							
	Memory 3		2	0Eh 2Ah							
	Memory 4		2	12h 2Eh	12h 2Eh	12h 2Dh	12h 2Dh	12h 2Ch	12h 2Ch	12h 2Eh	12h 2Dh
	Memory 5		2	22h 96h	22h 96h	2Ah 22h	2Ah 22h	22h 94h	22h 94h	40h 92h	2Ah 40h
	Memory 6		1/2	N/A	N/A	95h 92h	95h 92h	N/A	N/A	N/A	92h
	Delimiter		1	00h							
	Peripheral count		1	21h	20h	21h	20h	21h	20h	20h	21h
	MSP430CPUXV2		2	00h 23h							
	JTAG		2	00h 09h							
	SBW		2	00h 0Fh							
	EEM-L		2	00h 05h							
	TI BSL		2	00h FCh							
Peripheral Descriptor	SFR		2	10h 41h							
	PMM		2	02h 30h							
	FCTL		2	02h 38h							
	CRC16		2	01h 3Ch							
	CRC16_RB		2	00h 3Dh							
	RAMCTL		2	00h 44h							
	WDT_A		2	00h 40h							
	ucs		2	01h 48h							
	SYS		2	02h 42h							
	REF		2	03h A0h							
	Port mapping		2	01h 10h							
	Port 1 and 2		2	04h 51h							
	Port 3 and 4		2	02h 52h							
	Port 5 and 6		2	02h 53h							
	Port 7 and 8		2	02h 54h	N/A	02h 54h	N/A	02h 54h	N/A	N/A	02h 54h



Table 6-62. MSP430F552x Device Descriptor Table⁽¹⁾ (continued)

		SIZE				VA	LUE	· ·			
D	ESCRIPTION	ADDRESS	(bytes)	F5529	F5528	F5527	F5526	F5525	F5524	F5522	F5521
	JTAG		2	0Ch 5Fh	0Eh 5Fh	0Ch 5Fh	0Eh 5Fh	0Ch 5Fh	0Eh 5Fh	0Eh 5Fh	0Ch 5Fh
	TA0		2	02h 62h							
	TA1		2	04h 61h							
	ТВ0		2	04h 67h							
	TA2		2	04h 61h							
	RTC		2	0Ah 68h							
Peripheral Descriptor (continued)	MPY32		2	02h 85h							
,	DMA-3		2	04h 47h							
	USCI_A and USCI_B		2	0Ch 90h							
	USCI_A and USCI_B		2	04h 90h							
	ADC12_A		2	10h D1h							
	COMP_B		2	1Ch A8h							
	USB		2	04h 98h							
	COMP_B		1	A8h							
	TB0.CCIFG0		1	64h							
	TB0.CCIFG16		1	65h							
	WDTIFG		1	40h							
	USCI_A0		1	90h							
	USCI_B0		1	91h							
	ADC12_A		1	D0h							
	TA0.CCIFG0		1	60h							
	TA0.CCIFG14		1	61h							
	USB		1	98h							
Interrupts	DMA		1	46h							
	TA1.CCIFG0		1	62h							
	TA1.CCIFG12		1	63h							
	P1		1	50h							
	USCI_A1		1	92h							
	USCI_B1		1	93h							
	TA1.CCIFG0		1	66h							
	TA1.CCIFG12		1	67h							
	P2		1	51h							
	RTC_A		1	68h							
	Delimiter		1	00h							



Table 6-63. MSP430F551x Device Descriptor Table (1)

55	COURTION	4000000	SIZE			VALUE		
DE	SCRIPTION	ADDRESS	(bytes)	F5519	F5517	F5515	F5514	F5513
	Info length	01A00h	1	55h	55h	55h	55h	55h
	CRC length	01A01h	1	19h	17h	15h	14h	13h
Info Block	CRC value	01A02h	2	Per unit				
Info Block	Device ID	01A04h	1	22h	21h	55h	55h	20h
	Device ID	01A05h	1	80h	80h	15h	14h	80h
	Hardware revision	01A06h	1	Per unit				
	Firmware revision	01A07h	1	Per unit				
	Die record tag	01A08h	1	08h	08h	08h	08h	08h
	Die record length	01A09h	1	0Ah	0Ah	0Ah	0Ah	0Ah
Die Desemb	Lot/wafer ID	01A0Ah	4	Per unit				
Die Record	Die X position	01A0Eh	2	Per unit				
	Die Y position	01A10h	2	Per unit				
	Test results	01A12h	2	Per unit				
	ADC12 calibration tag	01A14h	1	05h	05h	11h	11h	05h
	ADC12 calibration length	01A15h	1	10h	10h	10h	10h	10h
	ADC gain factor	01A16h	2	blank	blank	blank	blank	blank
	ADC offset	01A18h	2	blank	blank	blank	blank	blank
	ADC 1.5-V reference Temperature sensor 30°C	01A1Ah	2	blank	blank	blank	blank	blank
ADC12 Calibration	ADC 1.5-V reference Temperature sensor 85°C	01A1Ch	2	blank	blank	blank	blank	blank
	ADC 2.0-V reference Temperature sensor 30°C	01A1Eh	2	blank	blank	blank	blank	blank
	ADC 2.0-V reference Temperature sensor 85°C	01A20h	2	blank	blank	blank	blank	blank
	ADC 2.5-V reference Temperature sensor 30°C	01A22h	2	blank	blank	blank	blank	blank
	ADC 2.5-V reference Temperature sensor 85°C	01A24h	2	blank	blank	blank	blank	blank
	REF calibration tag	01A26h	1	12h	12h	12h	12h	12h
	REF calibration length	01A27h	1	06h	06h	06h	06h	06h
REF Calibration	REF 1.5-V reference factor	01A28h	2	Per unit				
	REF 2.0-V reference factor	01A2Ah	2	Per unit				
	REF 2.5-V reference factor	01A2Ch	2	Per unit				



Table 6-63. MSP430F551x Device Descriptor Table⁽¹⁾ (continued)

	Table 0-03. IVI	71 4301 331			,	VALUE					
DI	ESCRIPTION	ADDRESS	SIZE (bytes)	F5519	F5517	F5515	F5514	F5513			
	Peripheral descriptor tag	01A2Eh	1	02h	02h	02h	02h	02h			
	Peripheral descriptor length	01A2Fh	1	61h	63h	61h	5Fh	5Fh			
	Memory 1		2	08h 8Ah	08h 8Ah	08h 8Ah	08h 8Ah	08h 8Ah			
	Memory 2		2	0Ch 86h	0Ch 86h	0Ch 86h	0Ch 86h	0Ch 86h			
	Memory 3		2	0Eh 2Ah	0Eh 2Ah	0Eh 2Ah	0Eh 2Ah	0Eh 2Ah			
	Memory 4		2	12h 2Eh	12h 2Dh	12h 2Ch	12h 2Ch	12h 2Ch			
	Memory 5		2	22h 96h	2Ah 22h	22h 94h	22h 94h	40h 92h			
	Memory 6		1/2	N/A	95h 92h	N/A	N/A	N/A			
	Delimiter		1	00h	00h	00h	00h	00h			
	Peripheral count		1	20h	20h	20h	1Fh	1Fh			
	MSP430CPUXV2		2	00h 23h	00h 23h	00h 23h	00h 23h	00h 23h			
	JTAG		2	00h 09h	00h 09h	00h 09h	00h 09h	00h 09h			
	SBW		2	00h 0Fh	00h 0Fh	00h 0Fh	00h 0Fh	00h 0Fh			
	EEM-L		2	00h 05h	00h 05h	00h 05h	00h 05h	00h 05h			
	TI BSL		2	00h FCh	00h FCh	00h FCh	00h FCh	00h FCh			
Peripheral Descriptor	SFR		2	10h 41h	10h 41h	10h 41h	10h 41h	10h 41h			
Descriptor	PMM		2	02h 30h	02h 30h	02h 30h	02h 30h	02h 30h			
	FCTL		2	02h 38h	02h 38h	02h 38h	02h 38h	02h 38h			
	CRC16		2	01h 3Ch	01h 3Ch	01h 3Ch	01h 3Ch	01h 3Ch			
	CRC16_RB		2	00h 3Dh	00h 3Dh	00h 3Dh	00h 3Dh	00h 3Dh			
	RAMCTL		2	00h 44h	00h 44h	00h 44h	00h 44h	00h 44h			
	WDT_A		2	00h 40h	00h 40h	00h 40h	00h 40h	00h 40h			
	UCS		2	01h 48h	01h 48h	01h 48h	01h 48h	01h 48h			
	SYS		2	02h 42h	02h 42h	02h 42h	02h 42h	02h 42h			
	REF		2	03h A0h	03h A0h	03h A0h	03h A0h	03h A0h			
	Port mapping		2	01h 10h	01h 10h	01h 10h	01h 10h	01h 10h			
	Port 1 and 2		2	04h 51h	04h 51h	04h 51h	04h 51h	04h 51h			
	Port 3 and 4		2	02h 52h	02h 52h	02h 52h	02h 52h	02h 52h			
	Port 5 and 6		2	02h 53h	02h 53h	02h 53h	02h 53h	02h 53h			
	Port 7 and 8		2	02h 54h	02h 54h	02h 54h	N/A	N/A			



Table 6-63. MSP430F551x Device Descriptor Table⁽¹⁾ (continued)

	COORIDITION	4000000	SIZE			VALUE		
DE	SCRIPTION	ADDRESS	(bytes)	F5519	F5517	F5515	F5514	F5513
	JTAG		2	0Ch 5Fh	0Ch 5Fh	0Ch 5Fh	0Eh 5Fh	0Eh 5Fh
	TA0		2	02h 62h	02h 62h	02h 62h	02h 62h	02h 62h
	TA1		2	04h 61h	04h 61h	04h 61h	04h 61h	04h 61h
	ТВ0		2	04h 67h	04h 67h	04h 67h	04h 67h	04h 67h
	TA2		2	04h 61h	04h 61h	04h 61h	04h 61h	04h 61h
Peripheral	RTC		2	0Ah 68h	0Ah 68h	0Ah 68h	0Ah 68h	0Ah 68h
Descriptor (continued)	MPY32		2	02h 85h	02h 85h	02h 85h	02h 85h	02h 85h
	DMA-3		2	04h 47h	04h 47h	04h 47h	04h 47h	04h 47h
	USCI_A and USCI_B		2	0Ch 90h	0Ch 90h	0Ch 90h	0Ch 90h	0Ch 90h
	USCI_A and USCI_B		2	04h 90h	04h 90h	04h 90h	04h 90h	04h 90h
	ADC12_A		2	N/A	N/A	N/A	N/A	N/A
	COMP_B		2	2Ch A8h	2Ch A8h	2Ch A8h	2Ch A8h	2Ch A8h
	USB		2	04h 98h	04h 98h	04h 98h	04h 98h	04h 98h
	COMP_B		1	A8h	A8h	A8h	A8h	A8h
	TB0.CCIFG0		1	64h	64h	64h	64h	64h
	TB0.CCIFG16		1	65h	65h	65h	65h	65h
	WDTIFG		1	40h	40h	40h	40h	40h
	USCI_A0		1	90h	90h	90h	90h	90h
	USCI_B0		1	91h	91h	91h	91h	91h
	ADC12_A		1	01h	01h	01h	01h	01h
	TA0.CCIFG0		1	60h	60h	60h	60h	60h
	TA0.CCIFG14		1	61h	61h	61h	61h	61h
	USB		1	98h	98h	98h	98h	98h
Interrupts	DMA		1	46h	46h	46h	46h	46h
	TA1.CCIFG0		1	62h	62h	62h	62h	62h
	TA1.CCIFG12		1	63h	63h	63h	63h	63h
	P1		1	50h	50h	50h	50h	50h
	USCI_A1		1	92h	92h	92h	92h	92h
	USCI_B1		1	93h	93h	93h	93h	93h
	TA1.CCIFG0		1	66h	66h	66h	66h	66h
	TA1.CCIFG12		1	67h	67h	67h	67h	67h
	P2		1	51h	51h	51h	51h	51h
	RTC_A		1	68h	68h	68h	68h	68h
	Delimiter		1	00h	00h	00h	00h	00h



器件和文档支持

入门和后续步骤

关于 MSP 系列器件以及开发协助工具和库的简介,请访问入门页面。

7.2 **Device Nomenclature**

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all MSP MCU devices. Each MSP MCU commercial family member has one of two prefixes: MSP or XMS. These prefixes represent evolutionary stages of product development from engineering prototypes (XMS) through fully qualified production devices (MSP).

XMS - Experimental device that is not necessarily representative of the final device's electrical specifications

MSP - Fully qualified production device

XMS devices are shipped against the following disclaimer:

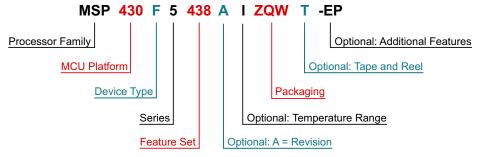
"Developmental product is intended for internal evaluation purposes."

MSP devices have been characterized fully, and the quality and reliability of the device have been demonstrated fully. TI's standard warranty applies.

Predictions show that prototype devices (XMS) have a greater failure rate than the standard production devices. TI recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

TI device nomenclature also includes a suffix with the device family name. This suffix indicates the temperature range, package type, and distribution format. 图 7-1 provides a legend for reading the complete device name.





Processor Family MCU Platform	CC = Embedded RF Radio MSP = Mixed-Signal Processor XMS = Experimental Silicon PMS = Prototype Device 430 = MSP430 low-power microcor	ntroller platform						
Device Type	Memory Type C = ROM F = Flash FR = FRAM G = Flash or FRAM (Value Line) L = No Nonvolatile Memory	Specialized Application AFE = Analog Front End BQ = Contactless Power CG = ROM Medical FE = Flash Energy Meter FG = Flash Medical FW = Flash Electronic Flow Meter						
Series	1 = Up to 8 MHz 2 = Up to 16 MHz 3 = Legacy 4 = Up to 16 MHz with LCD	5 = Up to 25 MHz 6 = Up to 25 MHz with LCD 0 = Low-Voltage Series						
Feature Set	Various levels of integration within a	a series						
Optional: A = Revision	N/A							
Optional: Temperature Range	S = 0°C to 50°C C = 0°C to 70°C I = -40°C to 85°C T = -40°C to 105°C							
Packaging	http://www.ti.com/packaging							
Optional: Tape and Reel	「 = Small reel R = Large reel No markings = Tube or tray							
Optional: Additional Features	-EP = Enhanced Product (–40°C to -HT = Extreme Temperature Parts (-Q1 = Automotive Q100 Qualified							

图 7-1. Device Nomenclature

7.3 工具与软件

所有 MSP 微控制器均受多种软件和硬件开发工具的支持。相关工具由 TI 以及多家第三方供应商提供。请参阅 MSP430 超低功耗 MCU – 工具与软件,了解所有工具。

表 7-1 列出了 MSP430FR203x 微控制器所 了 的调试功能。关于可用特性的详细信息,请参见《适用于 MSP430 的 Code Composer Studio 用户指南》。

表 7-1. 硬件调试 特性

MSP430 架构	四线制 JTAG	2线 JTAG	断点 (N)	范围断点	时钟控制	状态序列发生器	跟踪缓冲器	LPMx.5 调试支 持
MSP430Xv2	有	是	8	是	是	是	是	否

设计套件与评估模块

- MSP430F5529 USB LaunchPad 评估套件 利用集成的 全速 USB 2.0 (HID/MSC/CDC) 开发 连接 PC 的低功耗应用。MSP-EXP430F5529LP LaunchPad 是适用于 MSP430F5529 USB 微控制器的廉价、简单的微控制器开发套件。这是在 MSP430 MCU 上开始开发的一种简单方法,具有用于编程和调试的板载仿真功能,以及用于简化用户界面的按钮和 LED。
- MSP430F5529 USB 实验板 MSP430F5529 实验板 (MSP-EXP430F5529) 是一个用于 MSP430F5529 器件(来自最新一代具有集成 USB 的 MSP430 器件)的开发平台。该实验板兼容多种 TI 低功耗射频无线评估模块(例如,CC2520EMK)。实验板可帮助设计人员利用新型 F55xx MCU快速学习和开发,F55xx MCU为能量收集、无线传感以及自动抄表基础设施 (AMI) 等 应用 提供低功耗、更多内存和领先的集成技术。
- 适用于 MSP430F5x MCU 的 64 引脚目标开发板和 MSP-FET 编程器捆绑包 MSP-FET430U64USB 是一款强大的闪存仿真工具,可在 MSP430 MCU 上快速开始应用开发。它包含 USB 调试接口,用于通过 JTAG 接口或节省引脚的 Spy Bi-Wire(2 线 JTAG)协议在系统内对 MSP430 进行编程和调试。只需使用几个按键即可在数秒钟内擦除闪存并对其进行编程。由于 MSP430 闪存的功耗极低,因此无需外部电源。
- 适用于 MSP430F5x MCU 的 80 引脚目标开发板和 MSP-FET 编程器捆绑包 MSP-FET 是一款强大的闪存 仿真工具,可在 MSP430 MCU 上快速开始应用开发。它包含 USB 调试接口,用于通过 JTAG 接口或节省引脚的 Spy-Bi-Wire(2 线 JTAG)协议在系统内对 MSP430 进行编程和调试。只需使用几个按键即可在数秒钟内擦除闪存并对其进行编程。由于 MSP430 闪存的功耗 极低,因此无需外部电源。调试工具可将 MSP430 连接到附带的集成软件环境,提供的代码可帮助您立即开始设计工作。

软件

- MSP430Ware™ 软件 MSP430Ware 软件集合了所有 MSP430 器件的代码示例、产品说明书以及其他设计资源,打包提供给用户。除了提供已有 MSP430 设计资源的完整集合外,MSP430Ware 软件还包含名为 MSP 驱动程序库的高级 API。借助该库可以轻松地对 MSP430 硬件进行编程。 MSP430Ware 软件可作为 Code Composer Studio™IDE 的一部分提供,也可以以独立软件包的形式提供。
- MSP430F552x 代码示例 根据不同应用需求配置各集成外设的每个 MSP 器件均具备相应的 C 代码示例。
- MSP 驱动程序库 驱动程序库的抽象化 API 通过提供易于使用的函数调用使您不再拘泥于 MSP430 硬件的 细节。完整的文档通过具有帮助意义的 API 指南交付,其中包括有关每个函数调用和经过验证的参数的详细信息。开发人员可以使用驱动程序库功能,以最低开销编写完整项目。
- MSP EnergyTrace™ 技术 MSP430 微控制器的 EnergyTrace 技术是基于能量的代码分析工具,用于测量和显示应用的能量配置,同时协助优化应用以实现超低功耗。
- ULP(超低功耗)Advisor ULP Advisor™软件是一款辅助工具,旨在指导开发人员编写更为高效的代码,从而充分利用 MSP 和 MSP432 微控制器独特的 超低功耗 功能。ULP Advisor 的目标人群是微控制器的资深开发者和开发新手,可以根据详尽的 ULP 检验表检查代码,以便最大限度地利用应用程序。在编译时,ULP Advisor 会提供通知和备注以突出显示代码中可以进一步优化的区域,进而实现更低功耗。
- IEC60730 软件包 IEC60730 MSP430 软件包经过专门开发,用于协助客户达到 IEC 60730-1:2010 (家用及类似用途的自动化电气控制 第 1 部分:一般要求) B 类产品的要求。其中涵盖家用电器、电弧检测器、电源转换器、电动工具、电动自行车及其他诸多产品。IEC60730 MSP430 软件包可以嵌入在 MSP430 中 运行的客户应用,从而帮助客户简化其消费类器件在功能安全方面遵循 IEC 60730-1:2010 B 类规范的认证工作。
- 适用于 MSP 的定点数学运算库 MSP IQmath 和 Qmath 库是为 C 语言开发者提供的一套经过高度优化的高



精度数学运算函数集合,能够将浮点算法无缝嵌入 MSP430 和 MSP432 器件的定点代码中。这些例程通常用于计算密集型实时 应用, 而优化的执行速度、高精度以及超低能耗通常是影响这些实时应用的关键因素。与使用浮点数学算法编写的同等代码相比,使用 IQmath 和 Qmath 库可以大幅提高执行速度并显著降低能耗。

适用于 MSP430 的浮点数学运算库 TI 在低功耗和低成本微控制器领域锐意创新,为您提供 MSPMATHLIB。这是标量函数的浮点数学运算库,能够充分利用器件的智能外设,使性能提 升高达 26 倍。Mathlib 能够轻松集成到您的设计中。该运算库免费使用并集成在 Code Composer Studio 和 IAR IDE 中。如需深入了解该数学运算库及相关基准,请阅读用户指南。

开发工具

- 适用于 MSP 微控制器的 Code Composer Studio™集成开发环境 Code Composer Studio 是一种集成开发环境 (IDE),支持所有 MSP 微控制器。Code Composer Studio 包含一整套开发和调试嵌入式应用 的嵌入式软件实用程序的工具。它包含了优化的 C/C++ 编译器、源代码编辑器、项目构建环境、调试器、描述器以及其他多种 功能。直观的 IDE 提供了单个用户界面,有助于完成应用程序开发流程的每个步骤。熟悉的实用程序和界面可提升用户的入门速度。Code Composer Studio 将 Eclipse 软件框架的优点和 TI 先进的嵌入式调试功能相结合,为嵌入式开发人员提供了一种功能丰富的优异开发环境。当 CCS 与 MSP MCU 搭配使用时,可以使用独特而强大的插件和嵌入式软件实用程序,从而充分利用 MSP 微控制器的功能。
- 命令行编程器 MSP Flasher 是一款基于 shell 的开源接口,可使用 JTAG 或 Spy-Bi-Wire (SBW) 通信通过 FET 编程器或 eZ430 对 MSP 微控制器进行编程。MSP Flasher 可用于将二进制文件(.txt 或 .hex 文件)直接下载到 MSP 微控制器,而无需使用 IDE。
- MSP MCU 编程器和调试器 MSP-FET 是一款强大的仿真开发工具(通常称为调试探针),可帮助用户在 MSP 低功耗微控制器 (MCU) 中快速开发应用。创建 MCU 软件通常需要将生成的二进制程序 下载到 MSP 器件,以进行验证和调试。MSP-FET 在主机和目标 MSP 间提供调试通信通道。 此外,MSP-FET 还可在计算机的 USB 接口和 MSP UART 间提供反向通道 UART 连接。这 为 MSP 编程器提供了一种在 MSP 和计算机上运行的终端之间进行串行通信的便捷方法。它 还支持使用 BSL(引导加载程序)通过 UART 和 I²C 通信协议将程序(通常称为固件)加载 到 MSP 目标中。

www.ti.com.cn



MSP-GANG 生产编程器 MSP Gang 编程器是一款 MSP430 或 MSP432™器件编程器,可同时对多达八个完全相同的 MSP430 或 MSP432 闪存或 FRAM 器件进行编程。MSP Gang 编程器可使用标准的 RS-232 或 USB 连接与主机 PC 相连并提供灵活的编程选项,允许用户完全自定义流程。MSP Gang 编程器配有扩展板,即"Gang 分离器",可在 MSP Gang 编程器和多个目标器件间实施互连。提供了八条电缆,用于将扩展板与八个目标器件相连(通过 JTAG 或 SPY-Bi-Wire 连接器)。编程工作可在 PC 或独立设备上完成。PC 端具备基于 DLL 的图形化用户界面。

7.4 文档支持

以下文档介绍了 MSP430F552x 和 MSP430F551x 器件。www.ti.com.cn 网站上提供了这些文档的副本。

接收文档更新通知

如需接收文档更新通知(包括芯片勘误表),请访问 ti.com.cn 网站上的器件产品文件夹(例如 MSP430F5529)。请单击右上角的"通知我"按钮。点击注册后,即可收到产品信息更改每周摘要(如有)。有关更改的详细信息,请查阅已修订文档的修订历史记录。

勘误

《MSP430F5529 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5528 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5527 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5526 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5525 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5524 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5522 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5521 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5519 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5517 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5515 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5514 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。
《MSP430F5513 器件勘误表》	描述了此器件所有芯片修订版本的功能技术规格的已知例外情况。



用户指南

- 《MSP430x5xx 和 MSP430x6xx 系列用户指南》 详细介绍了该器件系列提供的模块和外设。
- 《适用于 MSP430 MCU 的 Code Composer Studio IDE 用户指南》 此用户指南介绍如何将 TI Code Composer Studio IDE 与 MSP430 超低功耗微控制器结合使用。
- 《MSP430 闪存器件引导加载程序 (BSL) 用户指南》 MSP430 引导加载程序 (BSL) 允许用户在原型设计、投产和维护等各阶段与 MSP430 微控制器中的嵌入式存储器进行通信。可编程存储器(闪存)和数据存储器 (RAM) 可根据相关要求进行变更。不要将此处的引导加载程序与某些数字信号处理器 (DSP) 中将外部存储器中的程序代码(和数据)自动加载到 DSP 内部存储器的引导装载程序混为一谈。
- 《通过 JTAG 接口对 MSP430 进行编程》 此文档介绍了使用 JTAG 通信端口擦除、编程和验证基于 MSP430 闪存和 FRAM 的微控制器系列的存储器模块所需的功能。此外,该文档还介绍了如 何编程所有 MSP430 器件上均具备的 JTAG 访问安全保险丝。此文档介绍了使用标准四线制 JTAG 接口和两线制 JTAG 接口(也称为 Spy-Bi-Wire (SBW))的器件访问。
- 《MSP430 硬件工具用户指南》 此手册介绍了 TI MSP-FET430 闪存仿真工具 (FET) 的硬件。FET 是针对 MSP430 超低功耗微控制器的程序开发工具。文中对提供的接口类型,即并行端口接口和 USB 接口进行了说明。

应用报告

- 《MSP430 32kHz 晶体振荡器》 选择合适的晶体、正确的负载电路和适当的电路板布局是实现稳定的晶体振荡器的关键。该应用报告总结了晶体振荡器的功能,介绍了用于选择合适的晶体以实现 MSP430 超低功耗运行的参数。此外,还给出了正确电路板布局的提示和示例。此外,为了确保振荡器在大规模生产后能够稳定运行,还可能需要进行一些振荡器测试,该文档中提供了有关这些测试的详细信息。
- 《MSP430 系统级 ESD 注意事项》 系统级 ESD 对于低电压下的硅晶技术以及经济高效型和超低功耗组件的需求日益增加。此应用报告重点讨论了三个不同的 ESD 主题,以帮助板卡设计师和原始设备制造商 (OEM) 理解和设计稳健的系统级设计产品: (1) 组件级 ESD 测试和系统级 ESD 测试,二者的差异以及为何组件级 ESD 无法确保达到系统级的稳健性。(2) 系统级 ESD 保护在不同电平下的通用设计指南(包括外壳、电缆、PCB 布局和板载 ESD 防护器件)。(3) 介绍了系统高效 ESD 设计 (SEED)。这是一种板上和片上 ESD 保护协同设计的方法论,用于实现系统级 ESD 的稳健性,配备仿真示例和测试结果。另外,还讨论了一些真实的系统级 ESD 保护设计示例及其成果。



7.5 相关链接

表 7-2 列出了快速访问链接。类别包括技术文档、支持与社区资源、工具与软件,以及申请样片或购买产品 的快速链接。

表 7-2. 相关链接

器件	产品文件夹	立即订购	技术文档	工具与软件	支持和社区
MSP430F5529	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5528	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5527	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5526	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5525	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5524	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5522	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5521	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5519	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5517	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5515	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5514	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处
MSP430F5513	请单击此处	请单击此处	请单击此处	请单击此处	请单击此处

社区资源 7.6

下列链接提供到 TI 社区资源的连接。链接的内容由各个分销商"按照原样"提供。这些内容并不构成 TI 技术 规范,并且不一定反映 TI 的观点;请参见 TI 的 《使用条款》。

TI 的工程师交流 (E2E) 社区. 此社区的创建目的是为了促进工程师之间协作。在 e2e.ti.com 中, 您可以提 问、共享知识、拓展思路,在同领域工程师的帮助下解决问题。

TI 嵌入式处理器维基网页

*德州仪器 (TI) 嵌入式处理器维基网页。*此网站的建立是为了帮助开发人员熟悉德州仪器 (TI) 的嵌入式处理 器,并且也为了促进与这些器件相关的硬件和软件的总体知识的创新和增长。

7.7 商标

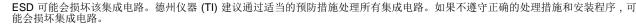
MSP430, MicroStar Junior, MSP430Ware, Code Composer Studio, EnergyTrace, ULP Advisor, 适用于 MSP 微控制器的 Code Composer Studio, MSP432, E2E are trademarks of Texas Instruments. All other trademarks are the property of their respective owners.



ZHCSIR7N - MARCH 2009 - REVISED SEPTEMBER 2018

7.8 静电放电警告

NSTRUMENTS





ESD 的损坏小至导致微小的性能降级,大至整个器件故障。 精密的集成电路可能更容易受到损坏,这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

7.9 Export Control Notice

Recipient agrees to not knowingly export or re-export, directly or indirectly, any product or technical data (as defined by the U.S., EU, and other Export Administration Regulations) including software, or any controlled product restricted by other applicable national regulations, received from disclosing party under nondisclosure obligations (if any), or any direct product of such technology, to any destination to which such export or re-export is restricted or prohibited by U.S. or other applicable laws, without obtaining prior authorization from U.S. Department of Commerce and other competent Government authorities to the extent required by those laws.

7.10 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

8 机械、封装和可订购信息

以下页中包括机械、封装和可订购信息。这些信息是指定器件的最新可用数据。数据如有变更,恕不另行通知,且不会对此文档进行修订。如需获取此数据表的浏览器版本,请查阅左侧的导航栏。

重要声明和免责声明

TI 均以"原样"提供技术性及可靠性数据(包括数据表)、设计资源(包括参考设计)、应用或其他设计建议、网络工具、安全信息和其他资源,不保证其中不含任何瑕疵,且不做任何明示或暗示的担保,包括但不限于对适销性、适合某特定用途或不侵犯任何第三方知识产权的暗示担保。

所述资源可供专业开发人员应用TI产品进行设计使用。您将对以下行为独自承担全部责任: (1)针对您的应用选择合适的TI产品; (2)设计、验证并测试您的应用; (3)确保您的应用满足相应标准以及任何其他安全、安保或其他要求。所述资源如有变更,恕不另行通知。TI对您使用所述资源的授权仅限于开发资源所涉及TI产品的相关应用。除此之外不得复制或展示所述资源,也不提供其它TI或任何第三方的知识产权授权许可。如因使用所述资源而产生任何索赔、赔偿、成本、损失及债务等,TI对此概不负责,并且您须赔偿由此对TI及其代表造成的损害。

TI 所提供产品均受TI 的销售条款 (http://www.ti.com.cn/zh-cn/legal/termsofsale.html) 以及ti.com.cn上或随附TI产品提供的其他可适用条款的约束。TI提供所述资源并不扩展或以其他方式更改TI 针对TI 产品所发布的可适用的担保范围或担保免责声明。

邮寄地址: 上海市浦东新区世纪大道 1568 号中建大厦 32 楼,邮政编码: 200122 Copyright © 2018 德州仪器半导体技术(上海)有限公司





15-Nov-2019

PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead/Ball Finish (6)	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
ASP00886IRGCR	ACTIVE	VQFN	RGC	64	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5522	Samples
ASP00886IRGCT	ACTIVE	VQFN	RGC	64	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5522	Samples
MSP430F5513IRGCR	ACTIVE	VQFN	RGC	64	2000	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5513	Samples
MSP430F5513IZQER	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	2500	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5513	Samples
MSP430F5514IRGCR	ACTIVE	VQFN	RGC	64	2000	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5514	Samples
MSP430F5514IRGCT	ACTIVE	VQFN	RGC	64	250	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5514	Samples
MSP430F5514IZQE	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	490	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5514	Samples
MSP430F5514IZQER	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	2500	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5514	Samples
MSP430F5515IPN	ACTIVE	LQFP	PN	80	119	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5515	Samples
MSP430F5515IPNR	ACTIVE	LQFP	PN	80	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5515	Samples
MSP430F5517IPN	ACTIVE	LQFP	PN	80	119	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5517	Samples
MSP430F5517IPNR	ACTIVE	LQFP	PN	80	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5517	Samples
MSP430F5519IPN	ACTIVE	LQFP	PN	80	119	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5519	Samples
MSP430F5519IPNR	ACTIVE	LQFP	PN	80	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5519	Samples
MSP430F5521IPN	ACTIVE	LQFP	PN	80	119	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5521	Samples
MSP430F5521IPNR	ACTIVE	LQFP	PN	80	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5521	Samples





www.ti.com

15-Nov-2019

Orderable Device	Status	Package Type	U	Pins	_	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
MSP430F5522IRGCR	ACTIVE	VQFN	RGC	64	2000	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5522	Samples
MSP430F5522IRGCT	ACTIVE	VQFN	RGC	64	250	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5522	Samples
MSP430F5522IZQE	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	490	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5522	Samples
MSP430F5522IZQER	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	2500	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5522	Samples
MSP430F5524IRGCR	ACTIVE	VQFN	RGC	64	2000	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5524	Samples
MSP430F5524IRGCT	ACTIVE	VQFN	RGC	64	250	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5524	Samples
MSP430F5524IZQE	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	490	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5524	Samples
MSP430F5524IZQER	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	2500	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5524	Samples
MSP430F5525IPN	ACTIVE	LQFP	PN	80	119	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5525	Samples
MSP430F5525IPNR	ACTIVE	LQFP	PN	80	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5525	Samples
MSP430F5526IRGCR	ACTIVE	VQFN	RGC	64	2000	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5526	Samples
MSP430F5526IRGCT	ACTIVE	VQFN	RGC	64	250	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5526	Samples
MSP430F5526IZQE	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	490	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5526	Samples
MSP430F5526IZQER	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	2500	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5526	Sample
MSP430F5527IPN	ACTIVE	LQFP	PN	80	119	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5527	Samples



PACKAGE OPTION ADDENDUM

15-Nov-2019

Orderable Device	Status	Package Type	_	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
MSP430F5527IPNR	ACTIVE	LQFP	PN	80	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5527	Samples
MSP430F5528IRGCR	ACTIVE	VQFN	RGC	64	2000	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5528	Samples
MSP430F5528IRGCT	ACTIVE	VQFN	RGC	64	250	Green (RoHS & no Sb/Br)	CU NIPDAU CU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	M430F5528	Samples
MSP430F5528IYFFR	ACTIVE	DSBGA	YFF	64	2500	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM	-40 to 85	M430F5528	Samples
MSP430F5528IZQE	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	490	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5528	Samples
MSP430F5528IZQER	ACTIVE	BGA MICROSTAR JUNIOR	ZQE	80	2500	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	M430F5528	Samples
MSP430F5529IPN	ACTIVE	LQFP	PN	80	119	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5529	Samples
MSP430F5529IPNR	ACTIVE	LQFP	PN	80	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	M430F5529	Samples

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

⁽³⁾ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

⁽⁴⁾ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.



PACKAGE OPTION ADDENDUM

15-Nov-2019

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

PACKAGE MATERIALS INFORMATION

www.ti.com 1-Jul-2019

TAPE AND REEL INFORMATION



TAPE DIMENSIONS + K0 - P1 - B0 W Cavity - A0 -

A0	Dimension designed to accommodate the component width
	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



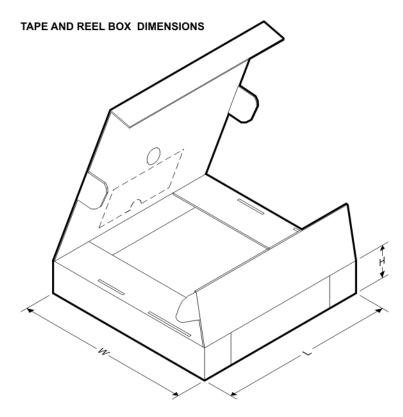
*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
MSP430F5513IRGCR	VQFN	RGC	64	2000	330.0	16.4	9.3	9.3	1.5	12.0	16.0	Q2
MSP430F5513IZQER	BGA MI CROSTA R JUNI OR	ZQE	80	2500	330.0	12.4	5.3	5.3	1.5	8.0	12.0	Q1
MSP430F5514IRGCT	VQFN	RGC	64	250	180.0	16.4	9.3	9.3	1.5	12.0	16.0	Q2
MSP430F5514IZQER	BGA MI CROSTA R JUNI OR	ZQE	80	2500	330.0	12.4	5.3	5.3	1.5	8.0	12.0	Q1
MSP430F5515IPNR	LQFP	PN	80	1000	330.0	24.4	15.0	15.0	2.1	20.0	24.0	Q2
MSP430F5517IPNR	LQFP	PN	80	1000	330.0	24.4	15.0	15.0	2.1	20.0	24.0	Q2
MSP430F5519IPNR	LQFP	PN	80	1000	330.0	24.4	15.0	15.0	2.1	20.0	24.0	Q2
MSP430F5521IPNR	LQFP	PN	80	1000	330.0	24.4	15.0	15.0	2.1	20.0	24.0	Q2
MSP430F5522IRGCT	VQFN	RGC	64	250	180.0	16.4	9.3	9.3	1.5	12.0	16.0	Q2
MSP430F5522IZQER	BGA MI CROSTA R JUNI OR	ZQE	80	2500	330.0	12.4	5.3	5.3	1.5	8.0	12.0	Q1
MSP430F5524IRGCT	VQFN	RGC	64	250	180.0	16.4	9.3	9.3	1.5	12.0	16.0	Q2
MSP430F5524IZQER	BGA MI	ZQE	80	2500	330.0	12.4	5.3	5.3	1.5	8.0	12.0	Q1

PACKAGE MATERIALS INFORMATION

www.ti.com 1-Jul-2019

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
	CROSTA R JUNI OR											
MSP430F5525IPNR	LQFP	PN	80	1000	330.0	24.4	15.0	15.0	2.1	20.0	24.0	Q2
MSP430F5526IRGCR	VQFN	RGC	64	2000	330.0	16.4	9.3	9.3	1.5	12.0	16.0	Q2
MSP430F5526IRGCT	VQFN	RGC	64	250	180.0	16.4	9.3	9.3	1.5	12.0	16.0	Q2
MSP430F5526IZQER	BGA MI CROSTA R JUNI OR	ZQE	80	2500	330.0	12.4	5.3	5.3	1.5	8.0	12.0	Q1
MSP430F5527IPNR	LQFP	PN	80	1000	330.0	24.4	15.0	15.0	2.1	20.0	24.0	Q2
MSP430F5528IRGCT	VQFN	RGC	64	250	180.0	16.4	9.3	9.3	1.5	12.0	16.0	Q2
MSP430F5528IZQER	BGA MI CROSTA R JUNI OR	ZQE	80	2500	330.0	12.4	5.3	5.3	1.5	8.0	12.0	Q1
MSP430F5529IPNR	LQFP	PN	80	1000	330.0	24.4	15.0	15.0	2.1	20.0	24.0	Q2



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
MSP430F5513IRGCR	VQFN	RGC	64	2000	367.0	367.0	38.0
MSP430F5513IZQER	BGA MICROSTAR	ZQE	80	2500	350.0	350.0	43.0



PACKAGE MATERIALS INFORMATION

www.ti.com 1-Jul-2019

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
	JUNIOR						
MSP430F5514IRGCT	VQFN	RGC	64	250	210.0	185.0	35.0
MSP430F5514IZQER	BGA MICROSTAR JUNIOR	ZQE	80	2500	350.0	350.0	43.0
MSP430F5515IPNR	LQFP	PN	80	1000	350.0	350.0	43.0
MSP430F5517IPNR	LQFP	PN	80	1000	350.0	350.0	43.0
MSP430F5519IPNR	LQFP	PN	80	1000	350.0	350.0	43.0
MSP430F5521IPNR	LQFP	PN	80	1000	350.0	350.0	43.0
MSP430F5522IRGCT	VQFN	RGC	64	250	210.0	185.0	35.0
MSP430F5522IZQER	BGA MICROSTAR JUNIOR	ZQE	80	2500	350.0	350.0	43.0
MSP430F5524IRGCT	VQFN	RGC	64	250	210.0	185.0	35.0
MSP430F5524IZQER	BGA MICROSTAR JUNIOR	ZQE	80	2500	350.0	350.0	43.0
MSP430F5525IPNR	LQFP	PN	80	1000	350.0	350.0	43.0
MSP430F5526IRGCR	VQFN	RGC	64	2000	367.0	367.0	38.0
MSP430F5526IRGCT	VQFN	RGC	64	250	210.0	185.0	35.0
MSP430F5526IZQER	BGA MICROSTAR JUNIOR	ZQE	80	2500	350.0	350.0	43.0
MSP430F5527IPNR	LQFP	PN	80	1000	350.0	350.0	43.0
MSP430F5528IRGCT	VQFN	RGC	64	250	210.0	185.0	35.0
MSP430F5528IZQER	BGA MICROSTAR JUNIOR	ZQE	80	2500	350.0	350.0	43.0
MSP430F5529IPNR	LQFP	PN	80	1000	350.0	350.0	43.0

ZQE (S-PBGA-N80)

PLASTIC BALL GRID ARRAY



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MO-225
- D. This is a Pb-free solder ball design.

MicroStar Junior is a trademark of Texas Instruments.



9 x 9, 0.5 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.

4224597/A





PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



PN (S-PQFP-G80)

PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Falls within JEDEC MS-026

YFF (R-XBGA-N64)

DIE-SIZE BALL GRID ARRAY



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. NanoFree™ package configuration.

NanoFree is a trademark of Texas Instruments.



重要声明和免责声明

TI 均以"原样"提供技术性及可靠性数据(包括数据表)、设计资源(包括参考设计)、应用或其他设计建议、网络工具、安全信息和其他资源,不保证其中不含任何瑕疵,且不做任何明示或暗示的担保,包括但不限于对适销性、适合某特定用途或不侵犯任何第三方知识产权的暗示担保。

所述资源可供专业开发人员应用TI产品进行设计使用。您将对以下行为独自承担全部责任: (1)针对您的应用选择合适的TI产品; (2)设计、验证并测试您的应用; (3)确保您的应用满足相应标准以及任何其他安全、安保或其他要求。所述资源如有变更,恕不另行通知。TI对您使用所述资源的授权仅限于开发资源所涉及TI产品的相关应用。除此之外不得复制或展示所述资源,也不提供其它TI或任何第三方的知识产权授权许可。如因使用所述资源而产生任何索赔、赔偿、成本、损失及债务等,TI对此概不负责,并且您须赔偿由此对TI及其代表造成的损害。

TI 所提供产品均受TI 的销售条款 (http://www.ti.com.cn/zh-cn/legal/termsofsale.html) 以及ti.com.cn上或随附TI产品提供的其他可适用条款的约束。TI提供所述资源并不扩展或以其他方式更改TI 针对TI 产品所发布的可适用的担保范围或担保免责声明。

邮寄地址: 上海市浦东新区世纪大道 1568 号中建大厦 32 楼,邮政编码: 200122 Copyright © 2019 德州仪器半导体技术(上海)有限公司