



SAN JOSÉ STATE UNIVERSITY

CMPE-258 PROJECT REPORT

“Image Out - painting Using GANs”

Team: BTS

Bharath Gunasekaran

Tamanna Mehta

Stuti Agarwal

TABLE OF CONTENTS

1. Abstract.....

2. Introduction.....

3. Related Work.....

4. Data.....

5. Methods.....

6. Experiments.....

7. Conclusion.....

Abstract:

Deep Learning has been highly successful with numerous computer vision tasks but still there are many computer vision problems that can be better resolved with traditional computer vision techniques and Image out-painting is one of them. Image Out-painting is a computer vision problem and involves restoring the missing portions of an image. The aim is to extrapolate unknown areas in such a way that it appears realistic to human eyes. In areas like panorama creation, texture creation and vertically filmed video expansion, image out-painting has been hugely successful with its visually logical structures and textures. We propose to develop an end to end model with a tfx model deployed on some cloud platform using Deep Convolutional Generative Adversarial Networks that implements image out painting on the basis of the neighboring information.

Introduction:

Image out painting has received little attention compared to Image Inpainting. Where Image inpainting involves restoring the missing interior portions of images, Image out painting restores exterior portions of images referred to as boundaries. As both the techniques are closely related, we can use Generative Adversarial networks in order to hallucinate boundaries with minimal neighboring Information. The whole idea has been implemented on deep learning technique which is based on adversarial training of the network. In this project, we will use the centre portion of image in order to compute a realistic image which is of the same size as the Input Image.



Figure 1:Image outpainting

Related work:

The initial papers used a data driven approach along with graphical representation of the source image for Image out painting. Although the results obtained were realistic, using adversarial training can lead to better results. In [2], Pathak et al. introduced the concept of Context Encoders, a CNN which was trained adversarially to reconstruct missing portions of the images based on the neighboring pixels. Our painting concept is inspired from the Inpainting as both are closely related. Our work is inspired from the Stanford Research paper Painting Outside the Box: Image Outpainting with GANs. which is written by Mark Sabini and Gili Rusak.

Dataset:

We used [Places 365 dataset](#) which is the most common dataset used for this domain research. It involves a diverse set of images from buildings, landscapes, rooms and scenes from everyday life. It includes 1.8 million colored images with 365 different categories. Images are resized to 128 x 128 from 256 x 256 in order to speed up the training process. The output image produced is of the same size as Input size. The resized image is cropped and masking is done before feeding into the model. For training purposes, we used 500 images and 100 images for the validation dataset.



Figure 2: Places 365 dataset

Data Preprocessing:

In order to prepare images for training the model, the images were normalized in range from 0 to 1. We define a mask of size $128 * 128$. Masking is done to mask out the centre portion of the images. The final masked images are fed to the generator model.

Methodology:

We used DCGAN architecture which includes Generator and Discriminator with convolutional layers. Generator acts as an encode-decoder convolutional network while the Discriminator uses strided convolutions repeatedly to downsample an image for binary classification as whether the image is real or fake. Figure 3 shows the training pipeline of the model where the generator produces fake images as an output from the input masked images.

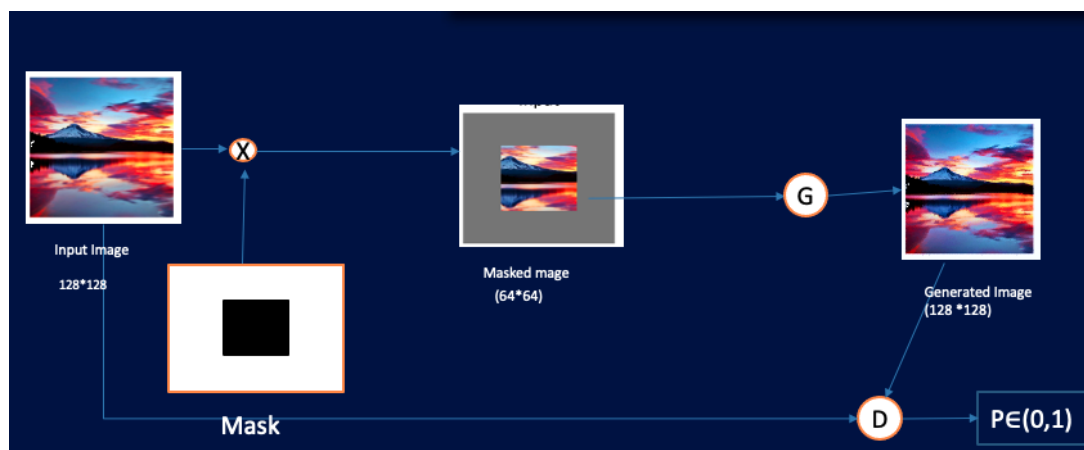


Figure 3: Training pipeline

These generated images along with the real images are fed into the discriminator in order to classify images as fake or real. During training, the mini batch of random sample images are fed during each epoch. The parameters of the model are updated based on loss computed in the form of MSE.

Network Architecture:

For Generator G, we used dilated convolutions along with an Encoder Decoder network in order to increase the receptive field of neurons and provide realistic

images. Figure 3 and 4 provides the layer architecture of the Generator and Discriminator model. It specifies the number of filters, strided convolutions , dilation rate and the number of outputs for each layer. Generator model has been trained with different dilation rates ranging from 1 to 8 inorder to improve realism in the output images. Generator first downsampled the image and then up-sampled it to the original image size.

Type	Filters size	Strides	Dilation rate	Outputs
CONV	5	1	1	64
CONV	3	2	1	128
CONV	3	1	1	256
CONV	3	1	2	256
CONV	3	1	4	256
CONV	3	1	8	256
CONV	3	1	1	256
DECONV	4	0.5	1	128
CONV	3	1	1	64
OUT	3	1	1	3

Figure 4: Generator Layer Architecture

Type	Filters size	Strides	Outputs
CONV	5	2	32
CONV	5	2	64
CONV	5	2	64
CONV	5	2	64
CONV	5	2	64
FC	-	-	512
FC(output)	-	-	1

Figure 5: Discriminator Layer Architecture

Figure 6 is the architecture of our DCGAN model. Every layer of discriminator is followed by the RELU activation except the final layer which uses sigmoid activation since it has to perform binary classification i.e. whether the image is real or not. Generator model uses LeakyRelu activation functions in his each layer as a parameter.

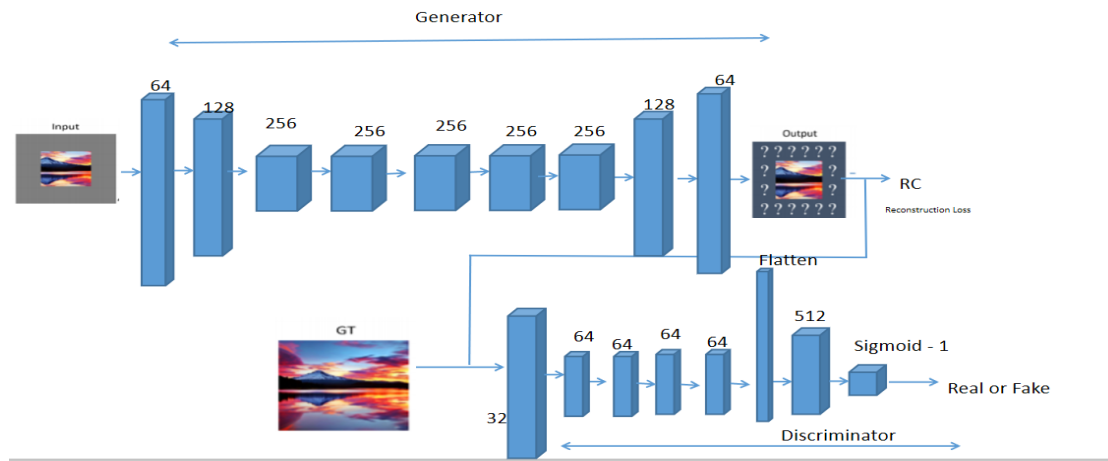


Figure 6: Architecture of DCGAN model

Evaluation Metrics:

Though the output of the Generator is sufficient to evaluate the model, we used MSE loss of our training batch and epoch as our quantitative metric. We also have the Tensor board visualization for the epoch loss and the batch loss (Figure 10 and 11).

Experiments & Deployment:

Initially, we built our 3 models namely Generator, Discriminator and GAN with different specifications. Figure 7, 8 and 9 is the summary model obtained after models creations. For Hyper parameter tuning, we used different dilation rates for our generator model. We used a batch size of 32 for our training. We built the TFX pipeline in which our features and labels were both images. So we have to do the same preprocessing to our labels. The trainer component was trained with all the 3 models after generating TF records, then computing Statistics and Schema Generation. Figure 10 and 11 depicts the visualization obtained from tensorboard. Generator was trained using 200 epochs, discriminator and GAN models were trained with 150 and 220 epochs. Since we had less computing resources, training the entire

dataset would take more than 48 hours and high compute power such as TPUs. So we trained our model on a small dataset and with limited resources.

Model: "model_1"

Layer (type)	Output Shape	Param #
input_2 (InputLayer)	[(None, 128, 128, 3)]	0
layer1conv2d (Conv2D)	(None, 64, 64, 32)	2432
layer1leakyRelu (LeakyReLU)	(None, 64, 64, 32)	0
layer1dropRate (Dropout)	(None, 64, 64, 32)	0
layer2conv2d (Conv2D)	(None, 32, 32, 64)	51264
layer2leakyRelu (LeakyReLU)	(None, 32, 32, 64)	0
layer2dropRate (Dropout)	(None, 32, 32, 64)	0
layer2batch (BatchNormalizat	(None, 32, 32, 64)	256
layer3conv2d (Conv2D)	(None, 16, 16, 64)	102464
layer3leakyRelu (LeakyReLU)	(None, 16, 16, 64)	0
layer3dropRate (Dropout)	(None, 16, 16, 64)	0
layer3batch (BatchNormalizat	(None, 16, 16, 64)	256
layer4conv2d (Conv2D)	(None, 8, 8, 64)	102464
layer4leakyRelu (LeakyReLU)	(None, 8, 8, 64)	0
layer4dropRate (Dropout)	(None, 8, 8, 64)	0
layer4batch (BatchNormalizat	(None, 8, 8, 64)	256
layer5conv2d (Conv2D)	(None, 4, 4, 64)	102464
layer5leakyRelu (LeakyReLU)	(None, 4, 4, 64)	0
layer5dropRate (Dropout)	(None, 4, 4, 64)	0
layer5batch (BatchNormalizat	(None, 4, 4, 64)	256
flatten_1 (Flatten)	(None, 1024)	0
dense_2 (Dense)	(None, 512)	524800
dense_3 (Dense)	(None, 1)	513
Total params: 887,425		
Trainable params: 0		
Non-trainable params: 887,425		

Figure 7: Model Summary for Generator



Model: "model_2"

Layer (type)	Output Shape	Param #
input_3 (InputLayer)	[(None, 128, 128, 3)]	0
conv2d (Conv2D)	(None, 128, 128, 64)	4864
activation (Activation)	(None, 128, 128, 64)	0
batch_normalization (BatchNo	(None, 128, 128, 64)	256
conv2d_1 (Conv2D)	(None, 64, 64, 128)	73856
activation_1 (Activation)	(None, 64, 64, 128)	0
batch_normalization_1 (Batch	(None, 64, 64, 128)	512
conv2d_2 (Conv2D)	(None, 64, 64, 256)	295168
activation_2 (Activation)	(None, 64, 64, 256)	0
batch_normalization_2 (Batch	(None, 64, 64, 256)	1024
conv2d_3 (Conv2D)	(None, 64, 64, 256)	590080
activation_3 (Activation)	(None, 64, 64, 256)	0
batch_normalization_3 (Batch	(None, 64, 64, 256)	1024
conv2d_4 (Conv2D)	(None, 64, 64, 256)	590080
activation_4 (Activation)	(None, 64, 64, 256)	0
batch_normalization_4 (Batch	(None, 64, 64, 256)	1024
conv2d_5 (Conv2D)	(None, 64, 64, 256)	590080
activation_5 (Activation)	(None, 64, 64, 256)	0
batch_normalization_5 (Batch	(None, 64, 64, 256)	1024
conv2d_6 (Conv2D)	(None, 64, 64, 256)	590080
activation_6 (Activation)	(None, 64, 64, 256)	0
batch_normalization_6 (Batch	(None, 64, 64, 256)	1024
conv2d_transpose (Conv2DTran	(None, 128, 128, 128)	524416
activation_7 (Activation)	(None, 128, 128, 128)	0
conv2d_7 (Conv2D)	(None, 128, 128, 64)	73792
activation_8 (Activation)	(None, 128, 128, 64)	0
batch_normalization_7 (Batch	(None, 128, 128, 64)	256
conv2d_8 (Conv2D)	(None, 128, 128, 3)	1731
Total params: 3,340,291		

Figure 8: Model Summary for Discriminator

Model: "model_2"

Layer (type)	Output Shape	Param #
input_3 (InputLayer)	[(None, 128, 128, 3)]	0
model_1 (Functional)	(None, 128, 128, 3)	3340291
model (Functional)	(None, 1)	887425

Total params: 4,227,716

Trainable params: 3,337,219

Non-trainable params: 890,497

Figure 9: Model Summary for GAN Model

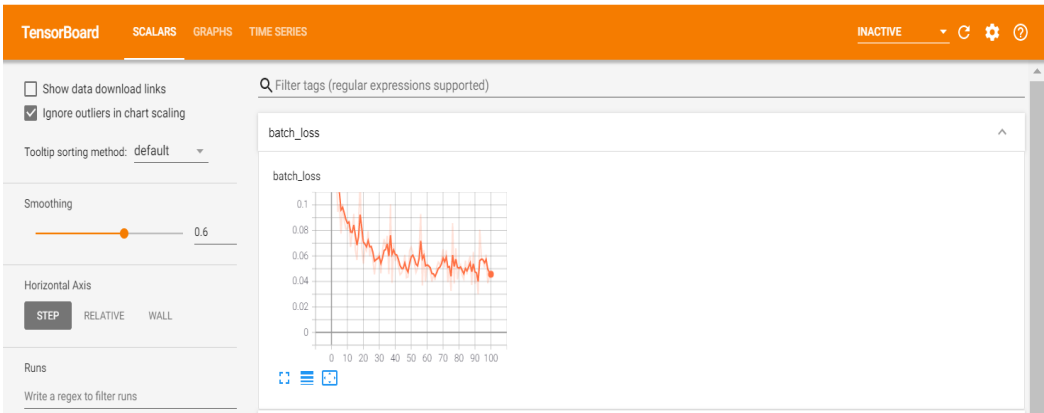


Figure 10: Visualizing Batch loss using tensorboard

The tfx pipeline was finally deployed on GCP cloud with Kube flow frameworks Figure 12 and 13 are the snapshots of Kubeflow Run Graph and notebook on GCP cloud where we have our tfx pipeline deployed. We made a flask application which accepts our colored image as input and predicts the output image of the same size as Input (Fig 14).

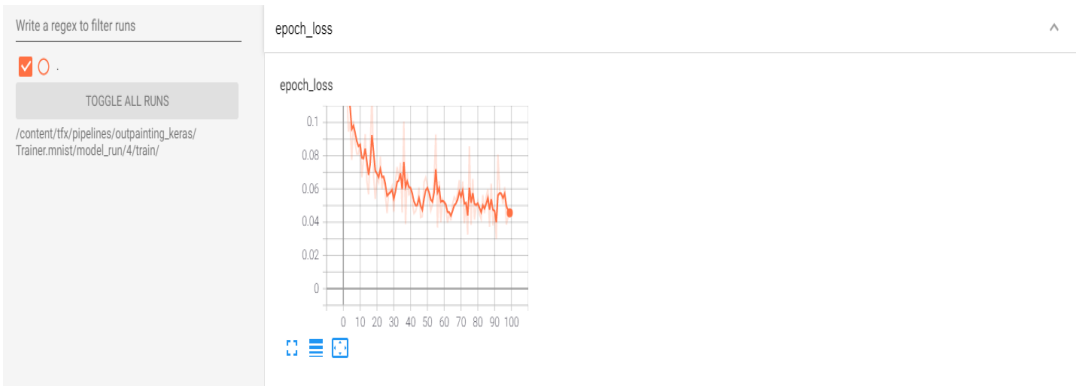


Figure 11: Visualizing Batch loss using tensorboard

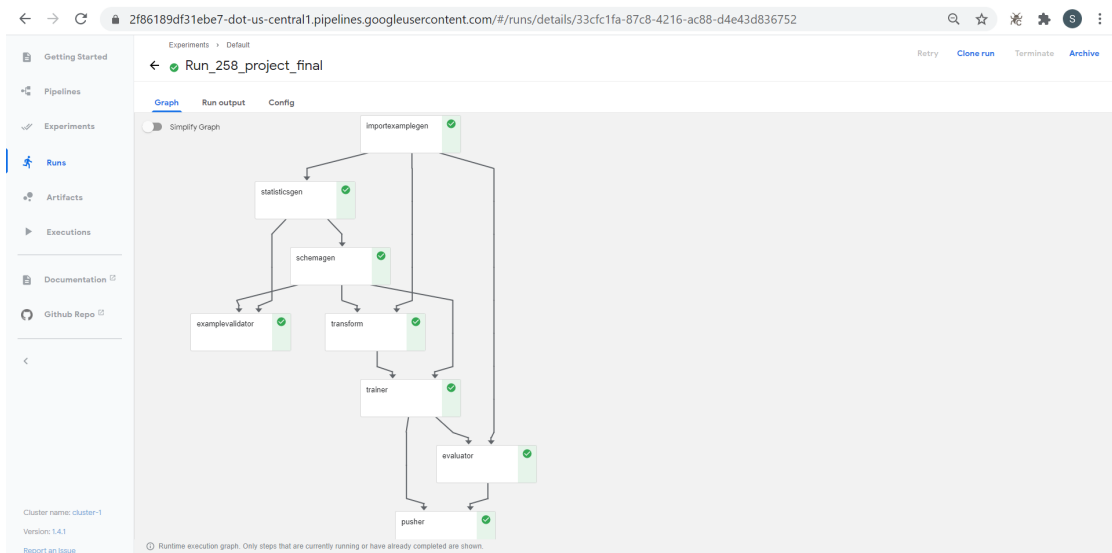


Figure 12: Kube flow Run Graph

The screenshot shows a Jupyter Notebook interface with a file explorer on the left and a code editor on the right. The file explorer shows a directory structure with files like 'data', 'model', 'tfx', 'build.yaml', 'Dockerfile', 'kubeflow_dag_runne...', 'local_runner.py', 'outpainting_kubeflo...', 'pipeline.py', and 'Version_2_bharath_te...'. The code editor displays the following code:

```
[ ]: # Install tfx and kfp Python packages.
import sys
!{sys.executable} -m pip install --user --upgrade -q tfx
!{sys.executable} -m pip install --user --upgrade -q kfp
# Download scaffold and set it executable.
!curl -Lo scaffold https://storage.googleapis.com/skaffold/releases/latest/skaffold-linux-amd64 && chmod +x scaffold && mv scaffold

[177]: # Set 'PATH' to include user python binary directory and a directory containing 'skaffold'.
PATH=$(env PATH)
%env PATH=$(PATH):/home/jupyter/.local/bin

env: PATH=/usr/local/cuda/bin:/opt/conda/bin:/opt/conda/condabin:/usr/local/bin:/usr/bin:/bin:/usr/local/games:/usr/games:/home/ju
pyter/.local/bin:/home/jupyter/.local/bin:/home/jupyter/.local/bin:/home/jupyter/.local/bin:/home/jupyter/.local/bin:/home/jupyter
r/.local/bin:/home/jupyter/.local/bin:/home/jupyter/.local/bin

[178]: !python3 -c "import tfx; print('TFX versions: {}'.format(tfx.__version__))"
TFX versions: 0.26.3

[180]: # Read GCP project id from env.
shell_output=$(gcloud config list --format 'value(cone.project)' 2>/dev/null
GOOGLE_CLOUD_PROJECT=$(shell_output[0])
%env GOOGLE_CLOUD_PROJECT=$(GOOGLE_CLOUD_PROJECT)
print("GCP project ID:" + GOOGLE_CLOUD_PROJECT)

env: GOOGLE_CLOUD_PROJECT=project258-311705
GCP project ID:project258-311705
```

Figure 13: Out painting notebook running on GCP Cloud



Figure 14: Image Out painting (Flask Application Snapshot)

Conclusion:-

We were able to successfully do image out painting. Dilated convolutions provided sufficient receptive fields to perform out painting. The quality of the output image can be improvised by increasing the number of epochs during the training process, and increasing the training data. But this is only possible with high compute power and memory resources.

Future Work:

Image Extrapolation can be done by out painting out of the image boundaries. Recursive Outpainting can also be done in order to increase realism in the image outputs.

References:

- [1]. Mark Sabini, Gill Rusak , “Painting outside the box: Image Outpainting with GANs.” In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*, Aug 25, 2018.
- [2].D. Pathak, P. Krahenbuhl, J. Donahue, T. Darrell, and A. A. Efros. Context encoders: Feature learning by inpainting. In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*, pages 2536–2544, 2016.
- [3].Basile Van Hoorick, “Image Out painting and Harmonization using Generative Adversarial Networks” In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*, Feb 28, 2017.