

High Frequency Evolution of Macro Expectation and Disagreement

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Motivation

- Traditional theories, such as **FIRE**, suggest that there should be **no disagreement** among agents (Muth, 1961; Lucas Jr, 1972).
- Empirical evidence shows **persistent disagreement** among agents (Jonung, 1981).
- Models of **information rigidity** offer compelling explanations for these observations.
- Central to these models is the important role of information—or “**news**”.
- The **high-frequency** nature of this news and the **low-frequency** survey data are **misaligned**.
- Goal: develop a framework that can **simultaneously integrate** high-frequency news with low-frequency survey data.

Literature: Evolution of Expectations and Disagreement

Evolution of Expectations

- Economic agents **adjust their expectations** in response to **newly acquired information** (Coibion and Gorodnichenko, 2015).
- This dynamic process of expectation adjustment occurs at a **frequency** that **significantly exceeds** that of conventional survey reports.

Evolution of Disagreement

- Lahiri and Sheng (2008) estimate a Bayesian learning model to show three components of disagreement:
 - ① **prior-mean** heterogeneity.
 - ② the **weights** attached to these priors.
 - ③ diverse **interpretations** of new information.
- Several **econometric issues** arise in the estimation of the evolution equation for disagreement (Hsiao and Pesaran, 2008; Lahiri and Sheng, 2008).

Literature: Mixed-Frequency Method

Previous methods (Ghysels and Wright, 2009; Andreou et al., 2013; Chaudhry and Oh, 2020):

- Mixed-Data Sampling Regression (**MIDAS**)
- Kalman Filter (**KF**)
- Reinforcement Learning (**RL**)

Shortcomings of previous methods:

- **Estimation efficiency**: one may need to estimate many parameters, resulting in low estimation efficiency.
- **Empirical performance**: due to model complexity and computational limitations, one may encounter a poor out-of-sample performance.
- **Interpretability**: methods with good empirical performance are difficult to have a reasonable economic explanation.

This Paper

- We develop a novel **mixed-frequency** framework that enables the simultaneous analysis of **high-frequency news** and **low-frequency expectations**.
- By utilizing **representative forecasters** as proxies for real-world agents, we demonstrate that the **evolution of forecast disagreement** follows the equation:

$$\sigma(\mathbb{F}_{i,t+1}[\mathbf{x}_{t+1}]) = \sigma(\mathbb{F}_{i,t}[\mathbf{x}_{t+1}]) + (\Delta\beta)' \mathbf{r}_{t+1}$$

- We **reconstruct the unobserved daily series of both expectations and disagreement** regarding macroeconomic growth that span the interval between two quarterly survey releases.

Roadmap

Data and Variables

High-frequency Evolution of Expectations

High-frequency Evolution of Disagreement

Application: Construct Daily Measures of Both Aggregate
Growth Expectations and Disagreement

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Data

Growth Expectations: quarterly SPF surveys

- One-quarter ahead real GDP growth **forecast**

$$\mathbb{F}_t[x_{t+1}] = 100 \times \left[\left(\frac{\mathbb{F}_t[X_{t+1}]}{\mathbb{F}_t[X_t]} \right)^4 - 1 \right]$$

- Real-time quarterly **nowcast**

$$\mathbb{F}_{t+1}[x_{t+1}] = 100 \times \left[\left(\frac{\mathbb{F}_{t+1}[X_{t+1}]}{X_t} \right)^4 - 1 \right]$$

Asset Returns: proxies for new information

- We adopt a **broad interpretation** to asset prices, encompassing rate changes, spreads, returns, and other value-related metrics of financial assets.

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Relation between News and Growth Expectations

- The **DGP** is defined by $x_t = \rho x_{t-1} + u_t$, where $u_t \sim \mathcal{N}(0, \sigma_u^2)$ is i.i.d. over time and $\rho > 0$.
- Agent i observes the **noise signal** $s_t^i = x_t + \epsilon_t^i$, where $\epsilon_t^i \sim \mathcal{N}(0, \sigma_\epsilon^2)$ represents forecaster-specific i.i.d. noise.
- According to the **Kalman filter**, beliefs should be updated as follows

$$\underbrace{\mathbb{F}_{i,t+1}[x_{t+1}]}_{\text{nowcast}} = \underbrace{\mathbb{F}_{i,t}[x_{t+1}]}_{\text{forecast}} + \frac{\Sigma}{\Sigma + \sigma_\epsilon^2} \underbrace{(s_t^i - \mathbb{F}_{i,t}[x_{t+1}])}_{\text{new information}}$$

where Σ is the steady state variance of the prior $f(x_{t+1} | s_t^i, s_{t-1}^i, \dots)$.

- To help with interpretation of this equation, we transform it into a simpler form:

$$\mathbb{F}_{i,t+1}[x_{t+1}] = \mathbb{F}_{i,t}[x_{t+1}] + \text{News}_{t+1}$$

we interpret it as an **efficient Bayesian forecaster**.

Relation between News and Growth Expectations

- We need a model that allows for **heterogeneity** without making any specific assumptions:

$$\mathbb{F}_{i,t+1}[\mathbf{x}_{t+1}] = \alpha_i \mathbb{F}_{i,t}[\mathbf{x}_{t+1}] + \beta'_i \mathbf{r}_{t+1}$$

$$FR_{i,t+1} \equiv \mathbb{F}_{i,t+1}[\mathbf{x}_{t+1}] - \mathbb{F}_{i,t}[\mathbf{x}_{t+1}] = (\alpha_i - 1)\mathbb{F}_{i,t}[\mathbf{x}_{t+1}] + \beta'_i \mathbf{r}_{t+1}$$

- Motivated by this expression, we employ the following approximating moment:

$$\mathbb{F}_{t+1}[\mathbf{x}_{t+1}] = \alpha \mathbb{F}_t[\mathbf{x}_{t+1}] + \beta' \mathbf{r}_{t+1}$$

where \mathbf{r}_{t+1} represents a vector of **asset returns**, since they contain informative content for forecast revisions.

- We conduct several time series regressions to reinforce our use of **asset returns as proxies for news**, since we observe that certain pairs of assets yield sizable R^2 .

Mixed-Frequency Estimation Method

- We encounter the **issue with mixed frequencies**: forecasts are made quarterly, while the asset returns that represent news are recorded daily.
- A **recursive form** of the evolution equation:

$$\mathbb{F}_1[x] = \alpha \mathbb{F}_0[x] + \beta' \mathbf{r}_1$$

$$\mathbb{F}_2[x] = \alpha \mathbb{F}_1[x] + \beta' \mathbf{r}_2$$

...

$$\mathbb{F}_T[x] = \alpha \mathbb{F}_{T-1}[x] + \beta' \mathbf{r}_T$$

- This recursive approach allows us to clearly establish the relationship between $\mathbb{F}_0[x]$ and $\mathbb{F}_T[x]$ for two consecutive release dates:

$$\mathbb{F}_T[x^p] = \alpha^T \mathbb{F}_0[x^p] + \sum_{k=0}^{T-1} \alpha^k \beta' \mathbf{r}_{T-k}^p$$

Mixed-Frequency Estimation Method

- By setting α to a **fixed value** α_0 , we simplify the equation and therefore allow it to estimate using OLS:

$$\mathbb{F}_T[x^p] - \alpha_0^T \mathbb{F}_0[x^p] = \beta' \left(\sum_{k=0}^{T-1} \alpha_0^k \mathbf{r}_{T-k}^p \right)$$

Let $y = \mathbb{F}_T[x^p] - \alpha_0^T \mathbb{F}_0[x^p]$ and $\mathbf{X} = \sum_{k=0}^{T-1} \alpha_0^k \mathbf{r}_{T-k}^p$.

Then, the estimator $\hat{\beta}$ is given by $\hat{\beta} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'y$.

- Our current task is to identify the value of α_0 that **minimizes the SSR**:

$$\begin{aligned} \frac{\partial \text{SSR}}{\partial \alpha_0} &= 2T\alpha_0^{T-1} \mathbb{F}_0[x^p] \mathbf{X}'\hat{\beta} - 2y' \left(\sum_{k=0}^{T-1} k\alpha_0^{k-1} \mathbf{r}_{T-k}^p \right) \hat{\beta} \\ &\quad + \hat{\beta}' \left[\left(\sum_{k=0}^{T-1} k\alpha_0^{k-1} \mathbf{r}_{T-k}^p \right)' \mathbf{X} + \mathbf{X}' \left(\sum_{k=0}^{T-1} k\alpha_0^{k-1} \mathbf{r}_{T-k}^p \right) \right] \hat{\beta} \end{aligned}$$

Mixed-Frequency Estimation Method

We develop a **grid search method** to identify the optimal α :

- ① We construct a grid over the **feasible domain** of α and divide it into discrete intervals.
 - Each grid point corresponds to a potential value of α .
 - The domain for α is based on theoretical considerations.
 - We begin by setting a broad sampling range for α and gradually narrowing the interval to enhance accuracy.
- ② We employ a **rolling window** of 40 quarters.
 - The parameters cannot remain constant.
 - The window size should be carefully chosen to balance statistical power and parameter stability.
- ③ We restrict our analysis to **bivariate pairs of assets**.
 - A linear combination of two assets may approximate others.
 - We specifically choose those that yield the highest R^2 .

Estimation Results

The optimal coefficient α that minimize SSR is 1.

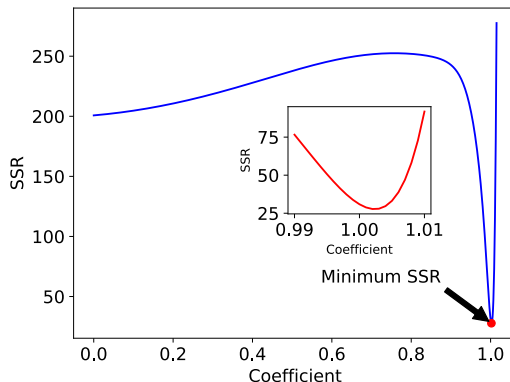


Figure 1: Relationship between SSR and α .

Estimation Results

$$FR^p \equiv \mathbb{F}_T[x^p] - \mathbb{F}_0[x^p] = \beta' \left(\sum_{k=0}^{T-1} \mathbf{r}_{T-k}^p \right) + (k\mathbb{F}_0[x^p] + b)$$

	(1)	(2)
β_1 (5YR Fixed-term Index)	-0.235*** (0.074)	-0.362*** (0.128)
β_2 (Change in AAA-10Y Spread)	0.024* (0.013)	0.035* (0.019)
b (constant)		0.609 (0.636)
k (past forecast $\mathbb{F}_0[x^p]$)		-0.086 (0.253)
R^2	0.224	0.280

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Intuition

- The **cross-sectional variance** is defined as

$$\text{Var}(\mathbb{F}_{i,t}[\mathbf{x}_{t+1}]) = \frac{1}{N} \sum_{i=1}^N (\mathbb{F}_{i,t}[\mathbf{x}_{t+1}] - \mathbb{F}_t[\mathbf{x}_{t+1}])^2$$

- By incorporating the **evolution equations** for both individual and consensus forecasts:

$$\text{Var}(\mathbb{F}_{i,t+1}[\mathbf{x}_{t+1}]) = \gamma \text{Var}(\mathbb{F}_{i,t}[\mathbf{x}_{t+1}]) + \boldsymbol{\zeta}' \mathbf{r}_{t+1} \mathbf{r}_{t+1}' \boldsymbol{\zeta} + \boldsymbol{\delta}' \mathbf{r}_{t+1} \mathbb{F}_t[\mathbf{x}_{t+1}]$$

where γ is a scalar related to α and α_i , $\boldsymbol{\zeta}$ is a vector of scalars related to β and β_i , and $\boldsymbol{\delta}$ is a vector of scalars related to α , α_i , β , and β_i .

- If we **relax these constraints** and apply the previous method, the results, although computable, do not reflect the **true “variance” parameters** as needed.

Representative Forecasters

- We posit the existence of two such forecasters:

$$\mathbb{F}_t^H [\mathbf{x}_{t+1}] = \mathbb{F}_t [\mathbf{x}_{t+1}] + \sigma (\mathbb{F}_{i,t} [\mathbf{x}_{t+1}])$$

$$\mathbb{F}_t^L [\mathbf{x}_{t+1}] = \mathbb{F}_t [\mathbf{x}_{t+1}] - \sigma (\mathbb{F}_{i,t} [\mathbf{x}_{t+1}])$$

we assume that the **position** of representative forecasts in relation to consensus forecast **remains constant** over time.

- Since we have

$$\mathbb{F}_{t+1}^H [\mathbf{x}_{t+1}] = \alpha^H \mathbb{F}_t^H [\mathbf{x}_{t+1}] + (\beta^H)' \mathbf{r}_{t+1}$$

$$\mathbb{F}_{t+1}^L [\mathbf{x}_{t+1}] = \alpha^L \mathbb{F}_t^L [\mathbf{x}_{t+1}] + (\beta^L)' \mathbf{r}_{t+1}$$

- The **relationship** between representative forecasters and consensus is

$$2\mathbb{F}_{t+1} [\mathbf{x}_{t+1}] = \mathbb{F}_{t+1}^H [\mathbf{x}_{t+1}] + \mathbb{F}_{t+1}^L [\mathbf{x}_{t+1}]$$

$$\begin{aligned} 2\alpha \mathbb{F}_t [\mathbf{x}_{t+1}] + 2\beta' \mathbf{r}_{t+1} &= (\alpha^H + \alpha^L) \mathbb{F}_t [\mathbf{x}_{t+1}] + [(\beta^H)' + (\beta^L)'] \mathbf{r}_{t+1} \\ &\quad + (\alpha^H - \alpha^L) \sigma (\mathbb{F}_{i,t} [\mathbf{x}_{t+1}]) \end{aligned}$$

Learning the Cross-sectional Variance

- Drawing from the conclusion that $\alpha^H = \alpha^L = \alpha = 1$:

$$\begin{aligned} [\mathbb{F}_{t+1} [x_{t+1}] + \sigma (\mathbb{F}_{i,t+1} [x_{t+1}])] &= [\mathbb{F}_t [x_{t+1}] + \sigma (\mathbb{F}_{i,t} [x_{t+1}])] + (\beta^H)' \mathbf{r}_{t+1} \\ \mathbb{F}_{t+1} [x_{t+1}] &= \mathbb{F}_t [x_{t+1}] + \beta' \mathbf{r}_{t+1} \end{aligned}$$

$$[\mathbb{F}_{t+1} [x_{t+1}] - \sigma (\mathbb{F}_{i,t+1} [x_{t+1}])] = [\mathbb{F}_t [x_{t+1}] - \sigma (\mathbb{F}_{i,t} [x_{t+1}])] + (\beta^L)' \mathbf{r}_{t+1}$$

- It becomes apparent that the cross-sectional standard deviation follows a straightforward evolution equation

$$\sigma (\mathbb{F}_{i,t+1} [x_{t+1}]) = \alpha \sigma (\mathbb{F}_{i,t} [x_{t+1}]) + (\Delta \beta)' \mathbf{r}_{t+1}$$

where $\Delta \beta = \beta^H - \beta = \beta - \beta^L$ represent the **differential interpretation of news** between two representative forecasts and the consensus forecast.

Discussion

- We now turn to a more general case:

$$\mathbb{F}_{i,t} [x_{t+1}] = \mathbb{F}_t [x_{t+1}] + k_i \cdot \sigma (\mathbb{F}_{i,t} [x_{t+1}])$$

where $k_i \neq 0$ **remains constant over time**.

- By substituting it into the evolution equation for individuals and consensus:

$$\sigma (\mathbb{F}_{i,t+1} [x_{t+1}]) = \alpha_i \sigma (\mathbb{F}_{i,t} [x_{t+1}]) + \frac{\alpha_i - \alpha}{k_i} \mathbb{F}_t [x_{t+1}] + \left(\frac{\beta_i - \beta}{k_i} \right)' \mathbf{r}_{t+1}$$

- Notice that this equation holds for any representative forecaster i , substitute $\alpha_i = \alpha$:

$$\sigma (\mathbb{F}_{i,t+1} [x_{t+1}]) = \alpha \sigma (\mathbb{F}_{i,t} [x_{t+1}]) + \left(\frac{\beta_i - \beta}{k_i} \right)' \mathbf{r}_{t+1}$$

This is equivalent to the evolution equation we derive previously, where $\Delta\beta = (\beta_i - \beta)/k_i$.

Estimation Results

The optimal α that minimize SSR for disagreement is also 1.

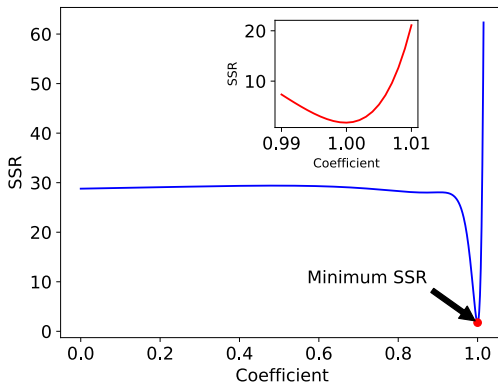


Figure 2: Relationship between SSR and α for disagreement.

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Extract Daily Time Series of Mean and Variance

Applying the previous mixed-frequency method, we derive the estimated daily-frequency time series:

$$\begin{bmatrix} \mathbb{F}_1 [x^p] \\ \mathbb{F}_2 [x^p] \\ \vdots \\ \mathbb{F}_T [x^p] \end{bmatrix} = \mathbf{D} \begin{bmatrix} \mathbb{F}_0 [x^p] \\ \mathbb{F}_0 [x^p] \\ \vdots \\ \mathbb{F}_0 [x^p] \end{bmatrix} + \mathbf{T} \begin{bmatrix} \mathbf{r}_1^p \\ \mathbf{r}_2^p \\ \vdots \\ \mathbf{r}_T^p \end{bmatrix}$$

where $\mathbf{D} = \text{diag}(\hat{\alpha}^1, \hat{\alpha}^2, \dots, \hat{\alpha}^T)$ is a scaling matrix that represents the contribution of the initial state $\mathbb{F}_0 [x^p]$. \mathbf{T} is a Toeplitz matrix that expresses the impact of asset returns:

$$\mathbf{T} = \begin{bmatrix} \hat{\beta}' & 0 & \dots & 0 \\ \hat{\alpha}\hat{\beta}' & \hat{\beta}' & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ \hat{\alpha}^{T-1}\hat{\beta}' & \hat{\alpha}^{T-2}\hat{\beta}' & \dots & \hat{\beta}' \end{bmatrix}$$

Results

Recursive estimation:

- We fit model on previous $T - 1$ quarters and apply to one quarter out-of-sample.

Evaluation:

- We construct the daily series for both cross-sectional mean and variance and achieve impressive R^2 of 93.3% and 84.5% against the actual data from surveys.

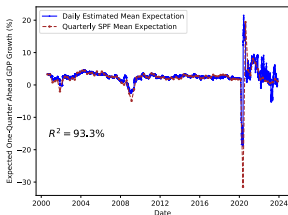


Figure 3: Expectations

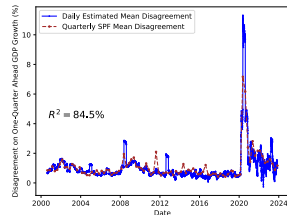


Figure 4: Disagreement

Comparison with RL Approach: ML Interpretability

Both the RL method and our mixed-frequency method demonstrate strong empirical performance, realizing R^2 values of 82.3% and 93.3% for the cross-sectional mean, respectively.

However, several important details warrant discussion:

- The RL method estimates the cross-sectional mean and variance jointly, which yields better estimates of the cross-sectional mean.
- Fixing α at one yields better performance than freely estimating α .
- The parameters that the RL method needs to estimate are identical to those we consider, why we get different estimated results and empirical performance?

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Conclusion

Main Findings:

- High-frequency dynamics of macro expectations and the corresponding evolution of disagreement among agents.
- A mixed-frequency framework that integrates high-frequency news with low-frequency survey data.
- Construction of daily time series for both cross-sectional mean and variance.

Future works:

- High-frequency series would enable clean identification in event studies.
- Our mixed-frequency framework can be applied to other macroeconomic variables to enhance the robustness of forecasting models.

Thanks!