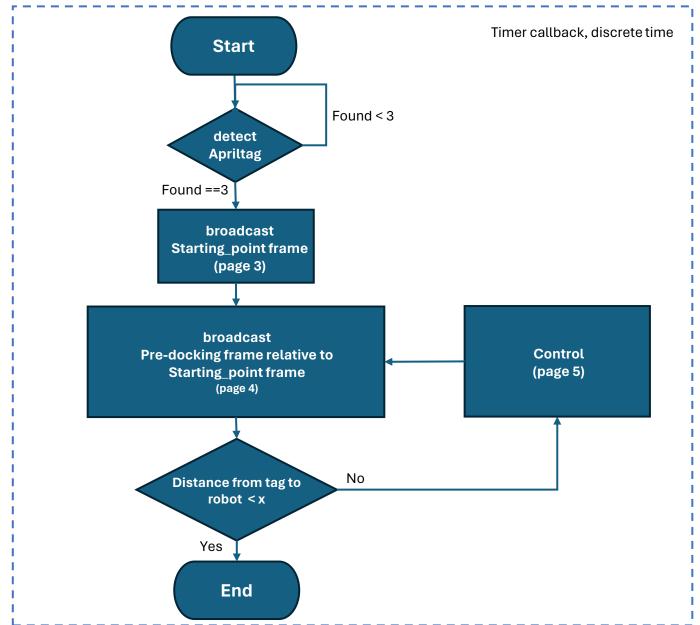
Auto-Docking with charging station

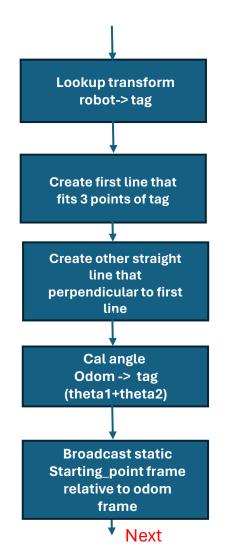
flowchart

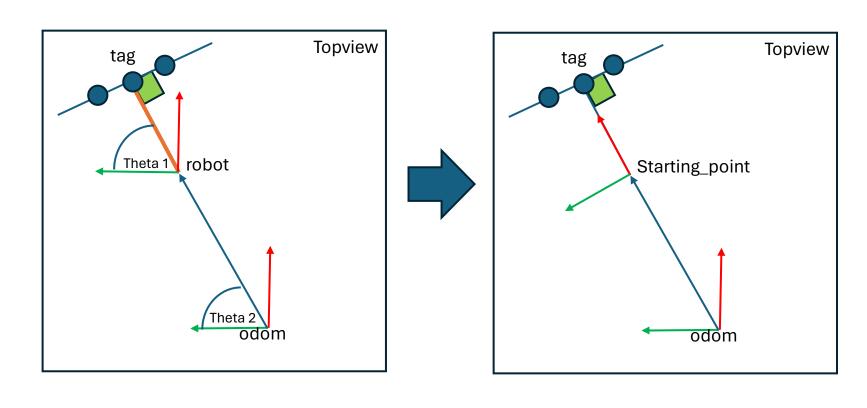
Systen overview



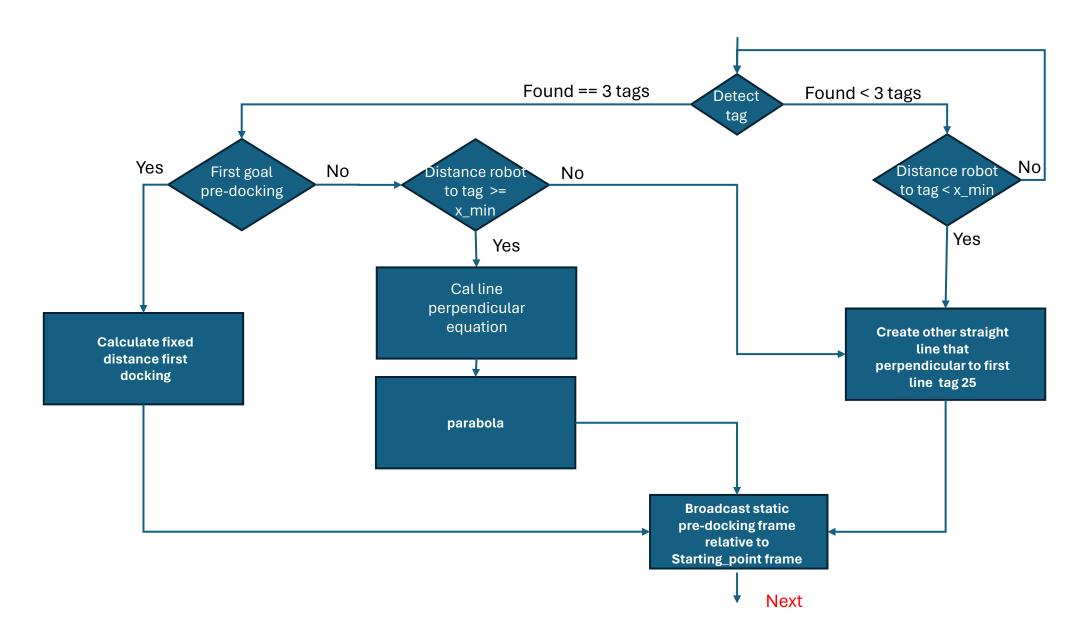
Broadcast **Starting_point** frame

Starting point frame is used for calculate line equation from starting_point to line that fit 3 points of tag and prevent the calculation of slope of the line that would be infinity.





Broadcast **Pre-docking frame** relative to **Starting_point frame**



Control

