QMHW2 Python

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```
[45]: import os

[46]: os.chdir("F:\IDEA\Second Year\Quantitative Macroeconomics\PS2")

[47]: from scipy.optimize import fsolve
    from scipy.optimize import minimize
    import numpy as np
    import matplotlib.pyplot as plt
    import pandas as pd
    import seaborn as sns
```

0.1 Exercise a) Compute a steady state

```
[48]: # First, we define the parameters that the problem give us.
      #labor share
      theta=0.67
      #labor suply
      h=0.31
      # Parameter of producivity
      z=1.629
      # Now I define the system of equations that must hold in the Steady State and \Box
      ⇒solve for root:
      def SteadyState(vars):
          k_ss,c_ss,y_ss,beta,delta=vars
          Euler=beta*((1-theta)*(k_s**(-theta))*((z*h)**theta)+(1-delta))-1
          ResourceC =y_ss-delta*k_ss-c_ss
          Production=y_ss-(k_ss**(1-theta))*((z*h)**theta)
          CYratio=(k_ss/y_ss)-4
          IYratio_2=((delta*k_ss)/y_ss)-0.25
          return [Euler, ResourceC, Production, CYratio, IYratio_2]
      x0=[4,0.75,1,0.98,0.06]
      #Solving for the Steady State
```

```
k_ss,c_ss,y_ss,beta,delta=fsolve(SteadyState,x0)
#Investment in steady state
i_ss=delta*k_ss
SteadyState={"k_ss":k_ss,"c_ss":c_ss,"y_ss":y_ss,"":beta,"":delta,"i_ss":i_ss}
print(SteadyState)
```

```
{'k_ss': 3.9983405378022554, 'c_ss': 0.749688850837957, 'y_ss': 0.9995851344505639, '': 0.9803921568576601, '': 0.06250000000000001, 'i_ss': 0.24989628361264102}
```

0.2 Exercise b) introduce a shock

```
[49]: # Productivity shock
      z_new=2*z
      # Now I define the system of equations that must hold in the Steady State and \Box
       ⇒solve for root:
      def SteadyState_2(vars):
          k_ss2,c_ss2,y_ss2,beta_2,delta_2=vars
          Euler_2=beta_2*((1-theta)*(k_ss2**(-theta))*((z_new*h)**theta)+(1-delta_2))-1
          ResourceC_2=v_ss2-delta_2*k_ss2-c_ss2
          Production_2=y_ss2-(k_ss2**(1-theta))*((z_new*h)**theta)
          CYratio_2=(k_ss2/y_ss2)-4
          IYratio_2=((delta_2*k_ss2)/y_ss2)-0.25
          return [Euler_2, ResourceC_2, Production_2, CYratio_2, IYratio_2]
      x02=[4,0.75,1,0.98,0.06]
      #Solving for the Steady State 2
      k_ss2,c_ss2,y_ss2,beta_2,delta_2=fsolve(SteadyState_2,x02)
      #Investment in steady state 2
      i_ss2=delta_2*k_ss2
      SteadyState_2={"k_ss2":k_ss2,"c_ss2":c_ss2,"y_ss2":y_ss2,"2":beta_2,"2":
       \rightarrowdelta_2,"i_ss2":i_ss2}
      print(SteadyState_2)
```

```
{'k_ss2': 7.996681074161963, 'c_ss2': 1.499377701669063, 'y_ss2': 1.9991702688108393, '2': 0.9803921568935487, '2': 0.06250000000067645, 'i_ss2': 0.49979256714053205}
```

0.3 Exercise c) Compute the transition from the first to the second steady state and report the time-path for savings, consumption, labor and output.

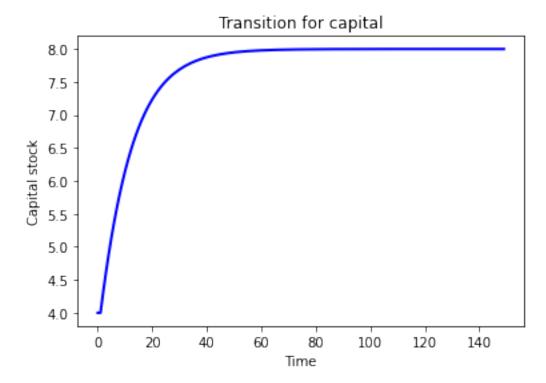
```
[50]: def u_p(c):
    return 1/c
#And the second one is the production function:
    def y(k,z):
        return k**(1-theta)*(z*h)**theta
```

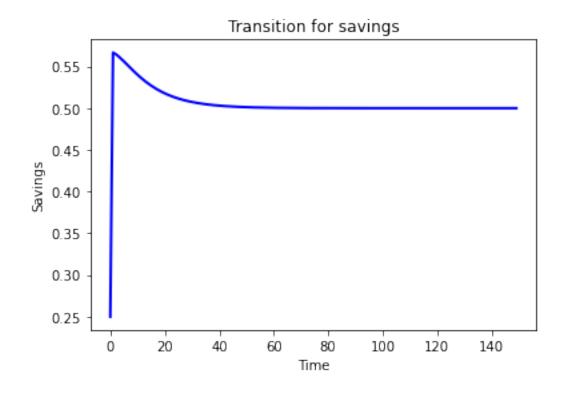
```
#The solution for the following problem of non linear equations is a sequence of \Box
  →capitals such that Euler eq.
#holds every period. With a sufficiently large number of simulations we should _{f U}
  →see how economy approaches to steady state.
                 #number of periods I siumlate
n=149
def transition(k, n=n):
        k_0=k_s
         k_{end}=k_{ss2}
         k[0]=k_ss #Initial condition
         k[n-1]=k_ss2 #Final condition
         k_vector=np.zeros(n)
         for i in range(0,n-2):
                   if i==0:
  -k_{\text{vector}}[i+1] = u_p(y(k_0,z_{\text{new}}) + (1-\text{delta})*k_0-k[i+1]) - \text{beta}*u_p(y(k[i+1],z_{\text{new}}) + (1-\text{delta})*k[i+1])
  \hookrightarrow (k[i+1])**(theta))*((y(k_0,z_new))/(k_0**(1-theta))))
                   elif i==(n-2):
  \rightarrowk_vector[i+1]=u_p(y(k[i],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])
  \leftarrow (k[i+1])**(theta))*((y(k[i],z_new))/(k[i]**(1-theta))))
                   else:
  \rightarrowk_vector[i+1]=u_p(y(k[i],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z_new)+(1-delta)*k[i]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]-k[i+1]
  \leftarrow (k[i+1])**(theta))*((y(k[i],z_new))/(k[i]**(1-theta))))
         return(k_vector)
x0=np.linspace(4,8,n) #Initial values. I choosed them in a manner such that they
  \rightarroware not too far of what I guess that will be the solution.
trans_k=fsolve(transition,x0) #This is the transition path for capital
# Since I have the transition for the capital, we solve for the rest of equations
#Transition path output
trans_y=y(trans_k,z_new) #Transition path output
#Transition path for savings:
trans_s=np.zeros(n)
for i in range(0,n-1):
                   trans_s[i]=trans_k[i+1]-(1-delta)*trans_k[i]
trans_s[n-1] = trans_s[n-2]
#Transition path for consumption.
```

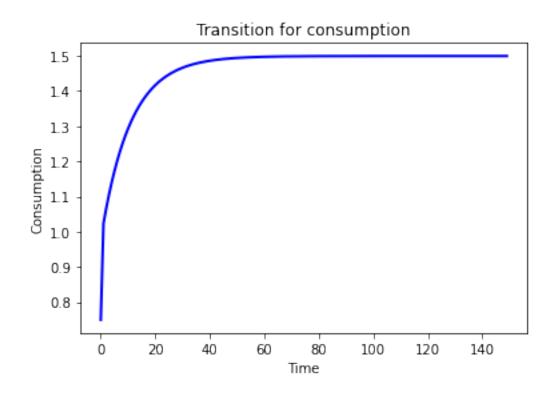
```
trans_pathcons=trans_y-trans_s
##Transition path for labour, since labour is unchanged
{\tt trans\_pathlabor=np.ones(n)*h}
#Now let me add the steady state observations at the beginning of each transition_{\sqcup}
\rightarrow path.
trans_k=np.insert(trans_k,0,k_ss)
trans_y=np.insert(trans_y,0,y_ss)
trans_s=np.insert(trans_s,0,i_ss) #iss because investment equals savings in_
\rightarrow this models.
trans_pathcons=np.insert(trans_pathcons,0,c_ss)
trans_pathlabor=np.insert(trans_pathlabor,0,h)
#Create time vector
time=np.array(list(range(0,(n+1))))
#And finally plot the figures:
fig,ax = plt.subplots()
ax.plot(time, trans_k,'-', color='blue', linewidth=2)
ax.set_title('Transition for capital')
ax.set_ylabel('Capital stock')
ax.set_xlabel('Time')
plt.show()
fig,ax = plt.subplots()
ax.plot(time, trans_s,'-', color='blue', linewidth=2)
ax.set_title('Transition for savings')
ax.set_ylabel('Savings')
ax.set_xlabel('Time')
plt.show()
fig,ax = plt.subplots()
ax.plot(time, trans_pathcons,'-', color='blue', linewidth=2)
ax.set_title('Transition for consumption')
ax.set_ylabel('Consumption')
ax.set_xlabel('Time')
plt.show()
fig,ax = plt.subplots()
ax.plot(time, trans_pathlabor, 'blue', linewidth=2)
```

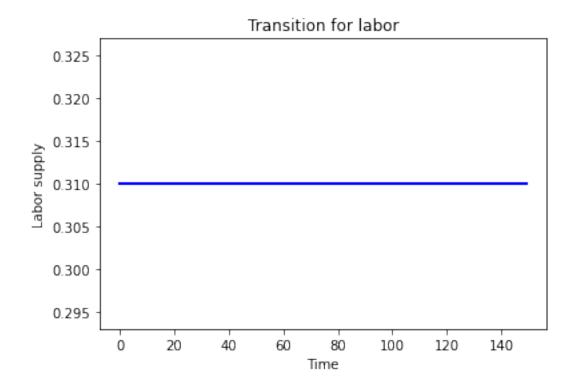
```
ax.set_title('Transition for labor')
ax.set_ylabel('Labor supply')
ax.set_xlabel('Time')
plt.show()

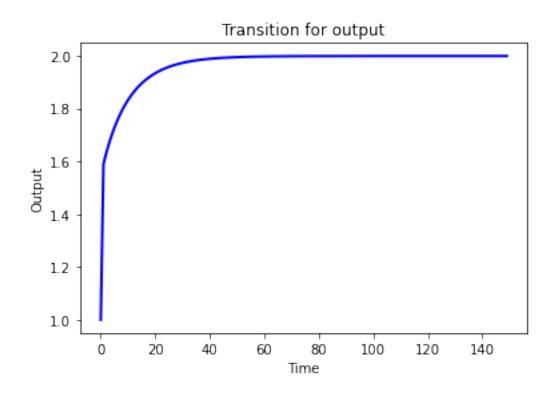
fig,ax = plt.subplots()
ax.plot(time, trans_y,'-', color='blue', linewidth=2)
ax.set_title('Transition for output')
ax.set_ylabel('Output')
ax.set_xlabel('Time')
plt.show()
```









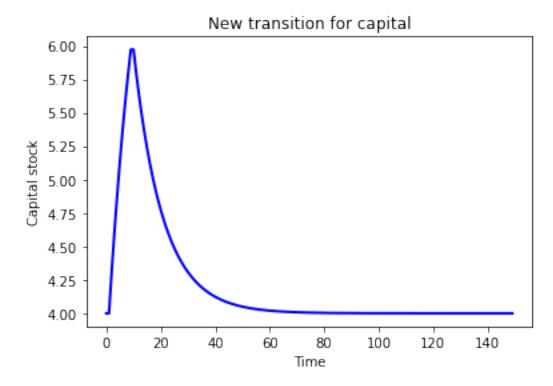


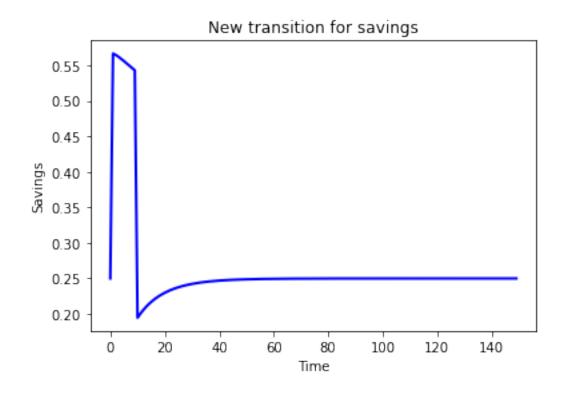
0.3.1 Exercise d) Unexpected shock

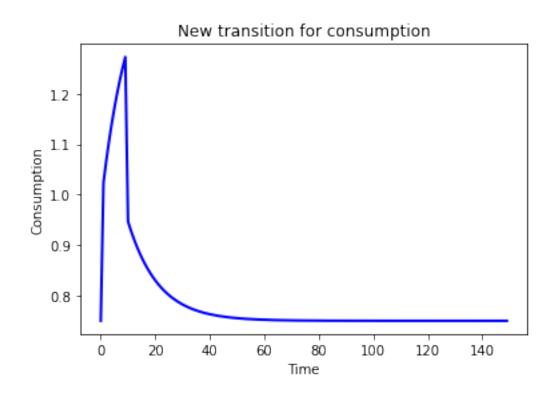
```
[51]: n2=140
                 def secondtransition(k, n2=n2):
                            k_0=trans_k[9]
                            k_{end}=k_{ss}
                            k[0]=trans_k[9]
                            k[n2-1]=k_s
                            k_vector2=np.zeros(n2)
                            for i in range(0,n2-2):
                                        if i==0:
                    -k_{vector2[i+1]} = u_p(y(k_0,z) + (1-delta)*k_0-k[i+1]) - beta*u_p(y(k[i+1],z) + (1-delta)*k[i+1]-k[i+2]) - beta*u_p(y(k[i+1],z) + (1-delta)*k[i+2]) - be
                    \rightarrow (k[i+1])**(theta))*((y(k_0,z))/(k_0**(1-theta))))
                                        elif i==(n2-2):
                    \rightarrowk_vector2[i+1]=u_p(y(k[i],z)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z)+(1-delta)*k[i+1]-k_e=0
                    _{\hookrightarrow}(k[i+1])**(theta))*((y(k[i],z))/(k[i]**(1-theta))))
                                        else:
                    \rightarrowk_vector2[i+1]=u_p(y(k[i],z)+(1-delta)*k[i]-k[i+1])-beta*u_p(y(k[i+1],z)+(1-delta)*k[i+1]-k[i+1])
                    _{\hookrightarrow}(k[i+1])**(theta))*((y(k[i],z))/(k[i]**(1-theta))))
                            return(k_vector2)
                 x02=np.linspace(6,4,n2)
                 trans_k2=fsolve(secondtransition,x02)
                 # Since I have the transition for the capital, we solve for the rest of equations
                 #Transition path output
                 trans_y2=y(trans_k2,z)
                 trans_s2=np.zeros(n2)
                 for i in range(0,n2-1):
                                        trans_s2[i]=trans_k2[i+1]-(1-delta)*trans_k2[i]
                 #Transition path for savings
                 trans_s2[n2-1]=trans_s2[n2-2]
                 #Transition path for consumption
                 trans_pathcons2=trans_y2-trans_s2
                 #Transitions path for labour is straight to.
                 trans_pathlabor2=np.ones(n2)*h
```

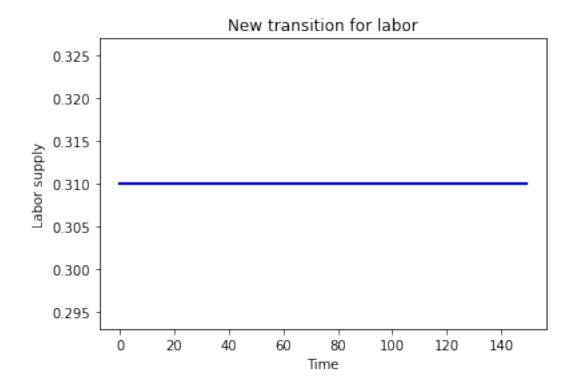
```
#Finally, add periods 0 to 9 of part c) vectors to get the complete transition \Box
 → dynamics:
trans_k2=np.concatenate((trans_k[0:10],trans_k2))
trans_y2=np.concatenate((trans_y[0:10],trans_y2))
trans_s2=np.concatenate((trans_s[0:10],trans_s2))
trans_pathcons2=np.concatenate((trans_pathcons[0:10],trans_pathcons2))
trans_pathlabor2=np.concatenate((trans_pathlabor[0:10],trans_pathlabor2))
#And plot results:
fig,ax = plt.subplots()
ax.plot(time, trans_k2,'-', color='blue', linewidth=2)
ax.set_title('New transition for capital')
ax.set_ylabel('Capital stock')
ax.set_xlabel('Time')
plt.show()
fig,ax = plt.subplots()
ax.plot(time, trans_s2,'-', color='blue', linewidth=2)
ax.set_title('New transition for savings')
ax.set_ylabel('Savings')
ax.set_xlabel('Time')
plt.show()
fig,ax = plt.subplots()
ax.plot(time, trans_pathcons2,'-', color='blue', linewidth=2)
ax.set_title('New transition for consumption')
ax.set_ylabel('Consumption')
ax.set_xlabel('Time')
plt.show()
fig,ax = plt.subplots()
ax.plot(time, trans_pathlabor2, 'b-', linewidth=2)
ax.set_title('New transition for labor')
ax.set_ylabel('Labor supply')
ax.set_xlabel('Time')
plt.show()
fig,ax = plt.subplots()
```

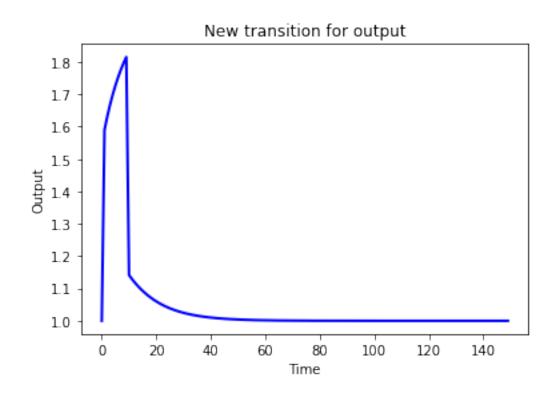
```
ax.plot(time, trans_y2,'-', color='blue', linewidth=2)
ax.set_title('New transition for output')
ax.set_ylabel('Output')
ax.set_xlabel('Time')
plt.show()
```











0.3.2 Exercise e) Introducing a labour in the utility function

```
[52]: # First I define the parameters that we know
      #labor share
      # I give a value for mu, v and z otherwise the function is not working.
      theta=0.67
      v = 0.31
      mu=0.4
      # Parameter of producivity
      z=1.62
      # Now I define the equations that must hold in the Steady State and solve for \Box
       \hookrightarrow roots
      def SteadyStateh(vars):
          k_ss,c_ss,y_ss,beta,delta,h_t,l=vars
          Euler=beta*((1-theta)*(k_s**(-theta))*((z*h)**theta)+(1-delta))-1
          ResourceC=y_ss-delta*k_ss-c_ss
          Production=y_ss-(k_ss**(1-theta))*((z*h_t)**theta)
          CYratio=(k_ss/y_ss)-4
          IYratio=((delta*k_ss)/y_ss)-0.25
          labour_market = h_t + 1 - 1
          labourmarket_ss = beta + mu*h_t**(1/
       \rightarrowv)-theta*h_t**(1-theta)*z**theta*h_t**(theta-1)
          zeta = z - (y_ss/k_s**(1-theta)*k_s**theta)**1/theta
          return [Euler, ResourceC, Production, CYratio, IYratio, labour_market, __
       →labourmarket_ss]
      x0=[4,0.75,1,0.98,0.0625,0.7,0.3]
      #Solving for the Steady State
      k_ss,c_ss,y_ss,beta,delta,h_t,l= fsolve(SteadyStateh,x0)
      #Investment in steady state
      i_ss=delta*k_ss
      SteadyStateh={"k_ss":k_ss,"c_ss":c_ss,"y_ss":y_ss,"":beta,"":delta,"i_ss":
       →i_ss,"h_ss":h_t,"1":1}
      print(SteadyStateh)
     {'k_ss': 1.7394666933206147, 'c_ss': 0.326150004999251, 'y_ss':
     0.4348666733317894, '': 0.9250211247621346, '': 0.0625, 'i_ss':
     0.10871666833253842, 'h_ss': 0.13561386730360667, 'l': 0.8643861326963933}
[53]: z_new=2*z
      # I set the equations such that they have to be equal to zero, we are solving \Box
       → for roots
      def SteadyState2(vars):
         k_ss2,c_ss2,y_ss2,beta_2,delta_2,h_t2,12=vars
```

```
\rightarrowEuler_2=beta_2*((1-theta)*(k_ss2**(-theta))*((z_new*h_t2)**theta)+(1-delta_2))-1
    ResourceC_2=y_ss2-delta*k_ss2-c_ss2
    Production_2 = y_ss_2 - (k_ss_2 ** (1-theta)) * ((z_new *h_t2) ** theta)
    CYratio_2=(k_ss2/y_ss2)-4
    IYratio_2=((delta_2*k_ss2)/y_ss2)-0.25
    labour_market2 = h_t2 + 12 - 1
    labourmarket_2 = beta_2 + mu*h_t2**(1/
 \rightarrowv)-theta*h_t2**(1-theta)*z_new**theta*h_t2**(theta-1)
    zeta = z_new - (y_ss2/k_ss2**(1-theta)*k_ss2**theta)**1/theta
    return [Euler_2, ResourceC_2, Production_2, CYratio_2,__
 →IYratio_2,labour_market2, labourmarket_2]
x02=[4,0.75,1,0.98,0.0625,0.5,0.5]
#Solving for the Steady State
k_ss2,c_ss2,y_ss2,beta_2,delta_2,h_t2,l2= fsolve(SteadyState2,x02)
#Investment in steady state
i_ss2=delta_2*k_ss2
SteadyState2={"k_ss2":k_ss2,"c_ss2":c_ss2,"y_ss2":y_ss2,"2":beta_2,"2":
 \rightarrowdelta_2,"i_ss2":i_ss2,"h_ss2":h_t2,"12":12}
print(SteadyState2)
```

```
{'k_ss2': 27.360284865823214, 'c_ss2': 5.130053412343243, 'y_ss2': 6.840071216457194, '2': 0.9803921568627518, '2': 0.0625, 'i_ss2': 1.7100178041139509, 'h_ss2': 1.0665435720612506, 'l2': -0.06654357206125057}
```

0.3.3 Exercise 2: Show the result of problem of Covid

```
[54]: A_f = 1
A_nf = 1
rho = 1.1
k_f = 0.2
k_nf = 0.2
w = 20
gamma = 0.9
i_0 = 0.2
N = 1
H = 1
n=10

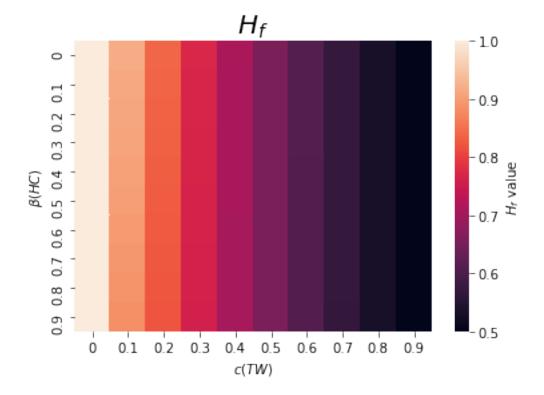
#Define the objective function

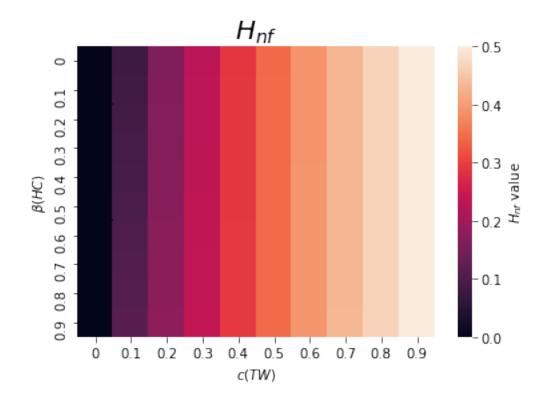
cov = lambda s: -1*((A_f*s[0]**((rho-1)/rho) + x[j]*A_nf*s[1]**((rho-1)/
-rho))**(rho/(rho-1)) - k_f*s[0] -k_nf *s[1] -w*((1-gamma)*x[i]*(i_0*s[0]**2/
-N)))
```

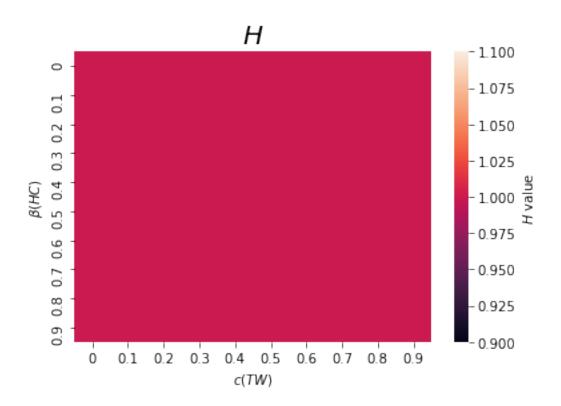
```
#Define the constraint
cons = ({'type':'ineq','fun': lambda s: N - s[0] - s[1] })
x = np.linspace(0,1,n)
# Array of results for H_f
H_f = np.zeros(shape=(n,n))
# Array of results for H_nf
H_nf = np.zeros(shape=(n,n))
for i in range(n):
   for j in range(n):
       bnds = [(0,1),(0,1)]
       opt = minimize(cov, [0.5,0.5], constraints = cons, bounds=bnds)
       H_f[i][j] = opt.x[0]
       H_nf[i][j] = opt.x[1]
result = np.zeros(shape=(n,n))
for i in range (n):
   for j in range(n):
       result[i][j]=(A_f*H_f[i][j]**((rho-1)/rho) +_{\sqcup}
\rightarrow x[j]*A_nf*H_nf[i][j]**((rho-1)/rho))**(rho/(rho-1))
H = H_f + H_nf
H_fH = H_f/H
# Infections
I = np.zeros(shape = (n,n))
for i in range(n):
   for j in range(n):
       I[i][j] = H_f[i][j]**2*10*x[i]
## Deaths:
D = (1-gamma)*I
# Welfare:
welfare = np.zeros(shape=(n,n))
for i in range (n):
   for j in range(n):
       welfare[i][j] = (A_f*H_f[i][j]**((rho-1)/rho) +_{\sqcup}
 \rightarrow *H_nf[i][j] -w*((1-gamma)*x[i]*(i_0*H_f[i][j]**2/N))
#plot the resault with heatmap
```

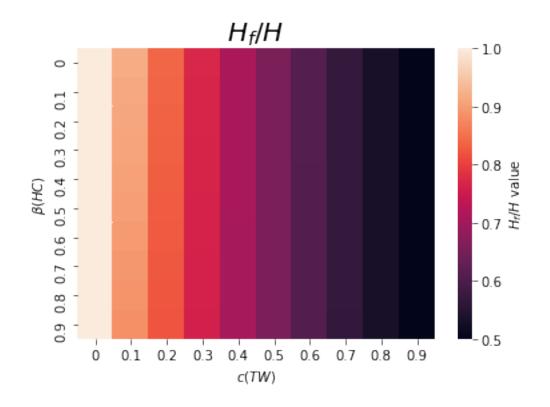
```
values = [0,0.1,0.2,0.3,0.4,0.5,0.6,0.7,0.8,0.9]
fig, ax = plt.subplots()
\verb|sns.heatmap(H_f,cbar_kws={"label":"$H_f$ value"}, xticklabels_{\sqcup}|
→=values,yticklabels=values)
plt.title("$H_f$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
sns.heatmap(H_nf,cbar_kws={"label":"$H_{nf}$ value"},xticklabels_
→=values, yticklabels=values)
plt.title("$H_{nf}$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
H_2 = np.ones(shape=(n,n)) # I'm having a problem ploting H, that's why I_{\sqcup}
→create this variable
fig, ax = plt.subplots()
sns.heatmap(H_2,cbar_kws={"label":"$H$ value"},xticklabels⊔
→=values,yticklabels=values)
plt.title("$H$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
sns.heatmap(H_f_H,cbar_kws={"label":"$H_f/H$ value"},xticklabels_
→=values,yticklabels=values)
plt.title("$H_f/H$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
\verb|sns.heatmap(I,cbar_kws={"label":"$I$ value"}, xticklabels_{\sqcup}|
→=values,yticklabels=values)
plt.title("$Infections$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
sns.heatmap(D,cbar_kws={"label":"Deads value"},xticklabels⊔
 →=values,yticklabels=values)
plt.title("Deads",fontsize=20)
```

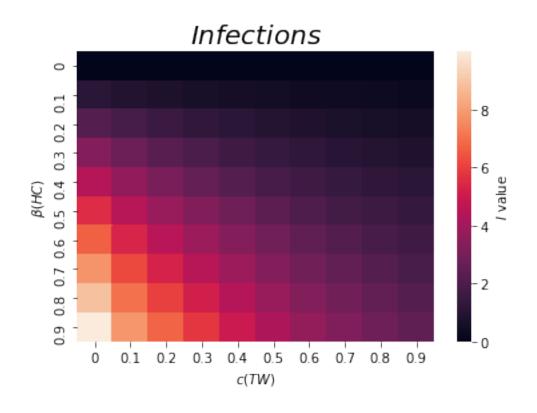
[54]: Text(33.0, 0.5, '\$(HC)\$')

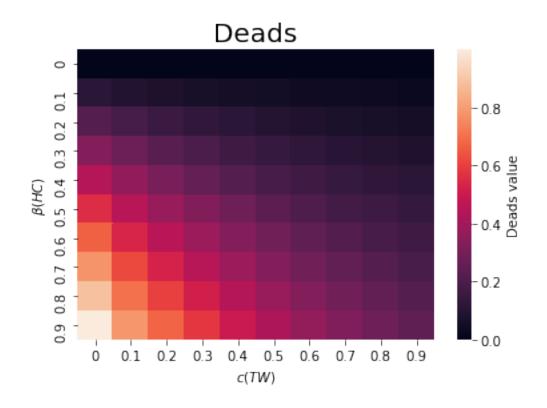


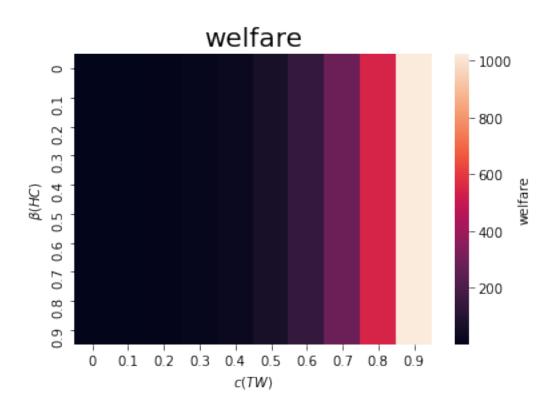


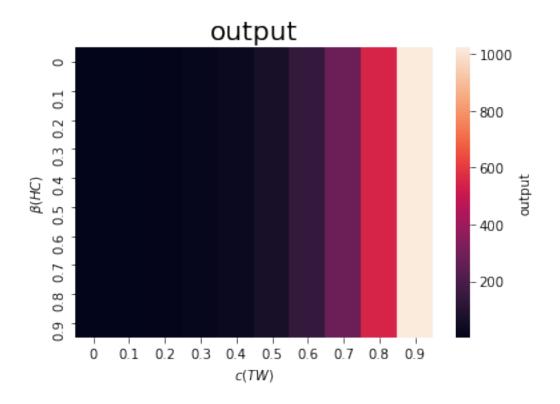












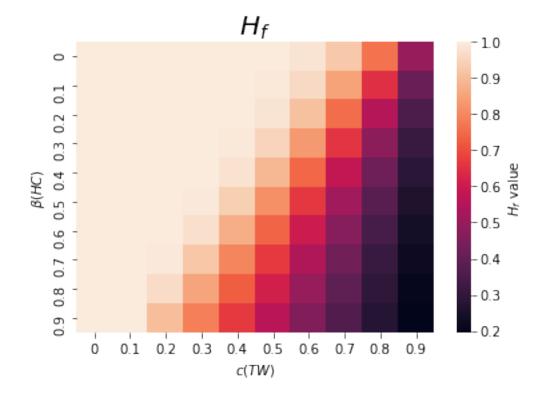
0.3.4 Exercise b) Change rho = 8.5

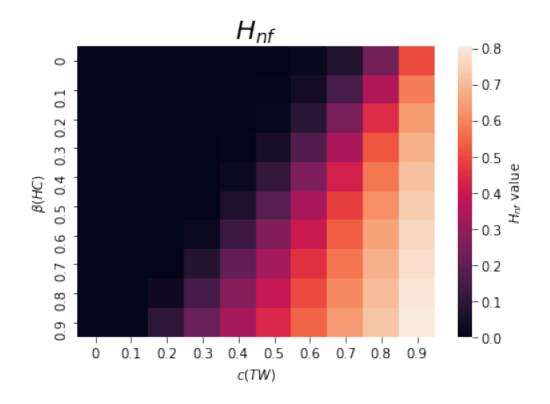
```
#Define the constraint
cons = ({'type':'ineq','fun': lambda s: N - s[0] - s[1] })
x = np.linspace(0,1,n)
# Array of results for H_f
H_f = np.zeros(shape=(n,n))
# Array of results for H_nf
H_nf = np.zeros(shape=(n,n))
for i in range(n):
    for j in range(n):
        bnds = [(0,1),(0,1)]
        opt = minimize(cov, [0.5,0.5], constraints = cons, bounds=bnds)
        H_f[i][j] = opt.x[0]
        H_nf[i][j] = opt.x[1]
result = np.zeros(shape=(n,n))
for i in range (n):
    for j in range(n):
        result[i][j]=(A_f*H_f[i][j]**((rho-1)/rho) +_{\sqcup}
 \rightarrow x[j]*A_nf*H_nf[i][j]**((rho-1)/rho))**(rho/(rho-1))
H = H_f + H_nf
H_f_H = H_f/H
# Infections
I = np.zeros(shape = (n,n))
for i in range(n):
    for j in range(n):
        I[i][j] = H_f[i][j]**2*10*x[i]
## Deaths:
D = (1-gamma)*I
# Welfare:
welfare = np.zeros(shape=(n,n))
for i in range (n):
    for j in range(n):
        welfare[i][j]= (A_f*H_f[i][j]**((rho-1)/rho) +_{\sqcup}
 \rightarrow x[j]*A_nf*H_nf[i][j]**((rho-1)/rho))**(rho/(rho-1)) - k_f*H_f[i][j] -k_nf_{\cup}
 \rightarrow *H_nf[i][j] -w*((1-gamma)*x[i]*(i_0*H_f[i][j]**2/N))
#plot the resault with heatmap
```

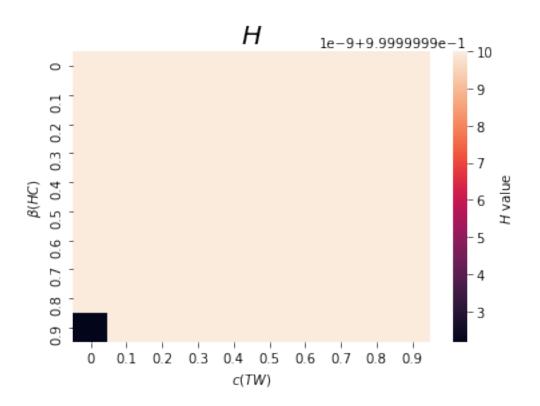
```
values = [0,0.1,0.2,0.3,0.4,0.5,0.6,0.7,0.8,0.9]
fig, ax = plt.subplots()
sns.heatmap(H_f,cbar_kws={"label":"$H_f$ value"},xticklabels_
→=values, yticklabels=values)
plt.title("$H_f$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
\verb|sns.heatmap(H_nf,cbar_kws={"label":"$H_{nf}$ value"}, \verb|xticklabels_u||
→=values,yticklabels=values)
plt.title("$H_{nf}$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
\#H_2 = np.ones(shape=(n,n)) \# I'm having a problem plotting H, that's why I_{\sqcup}
⇔create this variable
fig, ax = plt.subplots()
sns.heatmap(H,cbar_kws={"label":"$H$ value"},xticklabels

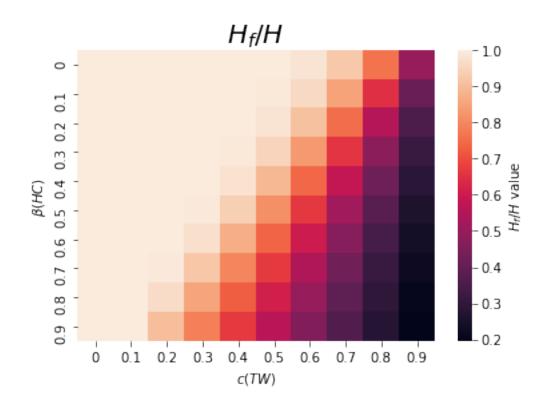
→=values, yticklabels=values)
plt.title("$H$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
sns.heatmap(H_f_H,cbar_kws={"label":"$H_f/H$ value"},xticklabels_
→=values,yticklabels=values)
plt.title("$H_f/H$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
sns.heatmap(I,cbar_kws={"label":"$I$ value"},xticklabels_
→=values,yticklabels=values)
plt.title("$Infections$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
sns.heatmap(D,cbar_kws={"label":"Deads value"},xticklabels_
→=values, yticklabels=values)
plt.title("Deads",fontsize=20)
plt.xlabel("$c(TW)$")
```

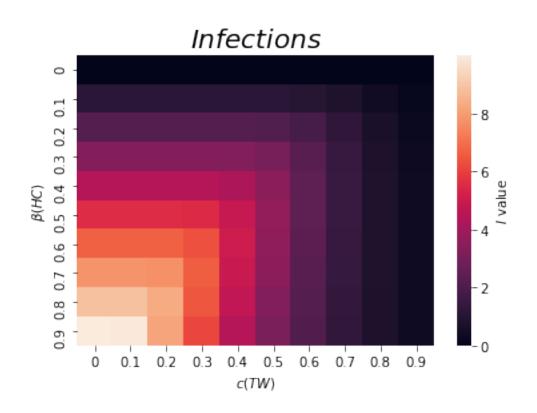
[55]: Text(33.0, 0.5, '\$(HC)\$')

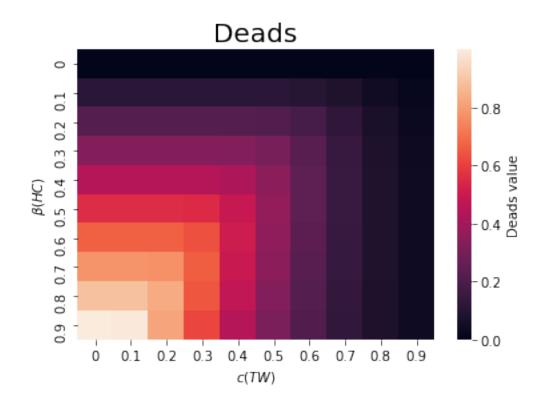


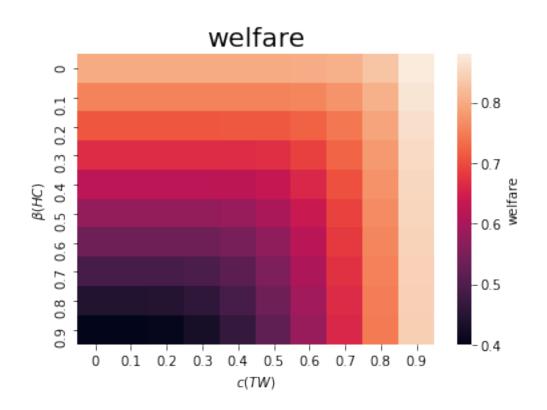


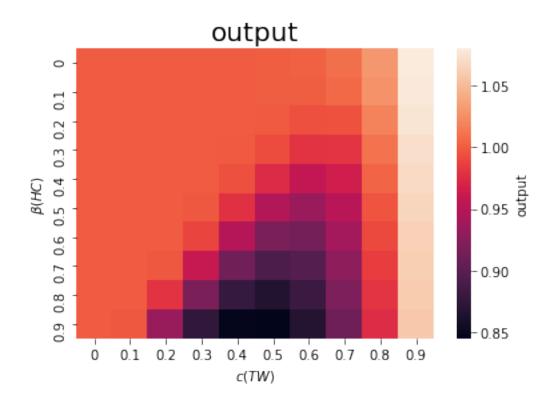












0.3.5 Exercise b) Change omega = 80

```
[56]: A_-f = 1

A_-nf = 1

rho = 1.1

k_-f = 0.2

k_-nf = 0.2

w = 80

gamma = 0.9

i_-0 = 0.2

N = 1

H = 1

n=10

#Define the objective function

cov = lambda s: -1*((A_-f*s[0]**((rho-1)/rho) + x[j]*A_-nf*s[1]**((rho-1)/rho)))**(rho/(rho-1)) - k_-f*s[0] -k_-nf *s[1] -w*((1-gamma)*x[i]*(i_-0*s[0]**2/rho))))
```

```
#Define the constraint
cons = ({'type':'ineq','fun': lambda s: N - s[0] - s[1] })
x = np.linspace(0,1,n)
# Array of results for H_f
H_f = np.zeros(shape=(n,n))
# Array of results for H_nf
H_nf = np.zeros(shape=(n,n))
for i in range(n):
   for j in range(n):
       bnds = [(0,1),(0,1)]
       opt = minimize(cov, [0.5,0.5], constraints = cons, bounds=bnds)
       H_f[i][j] = opt.x[0]
       H_nf[i][j] = opt.x[1]
result = np.zeros(shape=(n,n))
for i in range (n):
   for j in range(n):
       result[i][j]=(A_f*H_f[i][j]**((rho-1)/rho) +_{\sqcup}
 \rightarrow x[j]*A_nf*H_nf[i][j]**((rho-1)/rho))**(rho/(rho-1))
H = H_f + H_nf
H_fH = H_f/H
# Infections
I = np.zeros(shape = (n,n))
for i in range(n):
   for j in range(n):
       I[i][j] = H_f[i][j]**2*10*x[i]
## Deaths:
D = (1-gamma)*I
# Welfare:
welfare = np.zeros(shape=(n,n))
for i in range (n):
   for j in range(n):
       welfare[i][j] = (A_f*H_f[i][j]**((rho-1)/rho) +_{\sqcup}
 \rightarrow *H_nf[i][j] -w*((1-gamma)*x[i]*(i_0*H_f[i][j]**2/N))
#plot the resault with heatmap
```

```
values = [0,0.1,0.2,0.3,0.4,0.5,0.6,0.7,0.8,0.9]
fig, ax = plt.subplots()
sns.heatmap(H_f,cbar_kws={"label":"$H_f$ value"},xticklabels_
→=values,yticklabels=values)
plt.title("$H_f$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
sns.heatmap(H_nf,cbar_kws={"label":"$H_{nf}$ value"},xticklabels_
→=values,yticklabels=values)
plt.title("$H_{nf}$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
sns.heatmap(H,cbar_kws={"label":"$H$ value"},xticklabels⊔
→=values,yticklabels=values)
plt.title("$H$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
\#H_2 = np.ones(shape=(n,n)) \#I'm having a problem plotting H, that's why I_{\sqcup}
→ create this variable
fig, ax = plt.subplots()
sns.heatmap(H_f_H,cbar_kws={"label":"$H_f/H$ value"},xticklabels_
→=values,yticklabels=values)
plt.title("$H_f/H$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
sns.heatmap(I,cbar_kws={"label":"$I$ value"},xticklabels⊔
 ⇒=values, yticklabels=values)
plt.title("$Infections$",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
fig, ax = plt.subplots()
\verb|sns.heatmap(D,cbar_kws={"label":"Deaths value"}, \verb|xticklabels_{|}|
 →=values,yticklabels=values)
```

```
plt.title("Deaths",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")

fig, ax = plt.subplots()
sns.heatmap(welfare,cbar_kws={"label":"welfare"},xticklabels_\_
\times=values,yticklabels=values)
plt.title("welfare",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")

fig, ax = plt.subplots()
sns.heatmap(result,cbar_kws={"label":"output"},xticklabels_\_
\times=values,yticklabels=values)
plt.title("output",fontsize=20)
plt.xlabel("$c(TW)$")
plt.ylabel("$(HC)$")
```

[56]: Text(33.0, 0.5, '\$(HC)\$')

