

ADVANCED DATA ANALYSIS AND MACHINE LEARNING

Group project, Practical assignment

Lappeenranta-Lahti University of Technology LUT

BM20A6100 Data Summary and Visualisation, NASA Turbofan Jet Engine

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1. Data selection and communication

1.1. Data selected

As we are a B-level group we needed to only work on a single NASA Turbofan. We selected what we viewed as the "first" Turbofan FD001. The data was split into a few different files. The data will be discussed more later.

1.2. Communication Setup and code sharing

Communication will be done via Microsoft Teams with weekly meeting to discuss observations and distribute work properly between teammates. We are going to use GitHub for code sharing. This will allow us to work together fluidly and also have a remote storage for code recovery in case of equipment faults. Matlab was chosen as the working environment for data analysis and data visualization.

Data analysis and visualization	
Code sharing	
Communication	

Table 1 Tools used for the project

2. Data summarization and experimental scenario overview

2.1. Engine data and Fault development:

The dataset consists of multivariate time series from a fleet of turbofan engines split into training and test subsets capturing the engine's performance over time. As we are working

in a Errors start to appear in the training data and get worse until the system fails. Hence, the RUL must be predicted before the system failure.

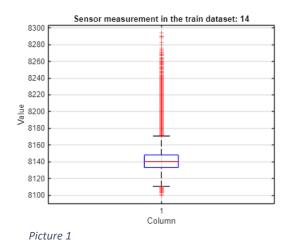
2.2. Operational Parameters

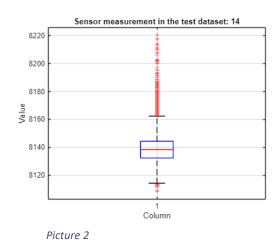
The performance of the engine is greatly impacted by three operational parameters. The data contains setting values (variables 3, 4 and 5 in the dataset) that have no clear indicator what they mean. There is sensor noise in the data which must be managed during analysis. The data is also split into different unit values which go through the time in cycles parameter values that can be viewed as time series data

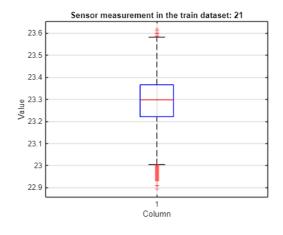
3. Data visualizations

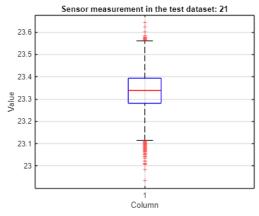
3.1. Visualizations

The data consists of 26 columns which have very differing measurement values, that are difficult to fit in a single plot. Some variables also don't change over the time the motor runs. Visualized below will be a few interesting occurrences and similarities between the split datasets of train and test datasets. Pictures 1, 2, and 3 show some interesting sensor measurement values with massive outliers on both sides of the regular occurrences in the data from the selected motors test data set. Visualized next to each other are the same sensors from both the test and train datasets





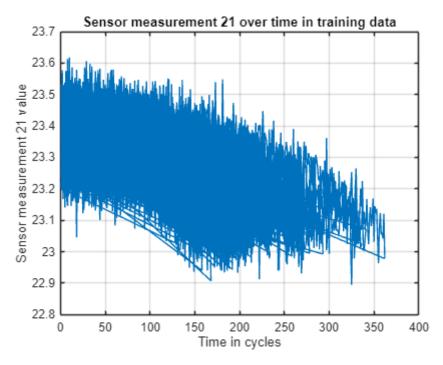




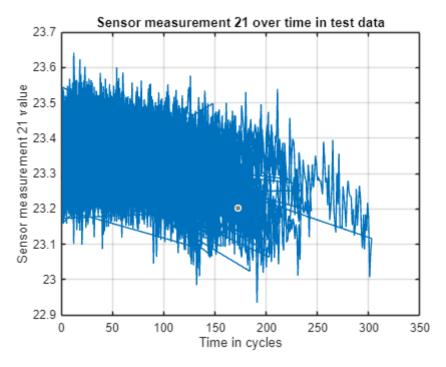
Picture 4

Picture 3

The boxplots help us detect a few initial points of interest in the data. Digging a bit deeper one can visualize these sensor measurements over the cycle times. Focusing on the sensor measurement number 21 (Variable 26 in the datasets) shows similar patterns. The plots below show that despite looking at all units at the same time a decrease in measurement values can be seen around the 100 to 150 marks of the time in cycles variable in both the train and test dataset (Pictures 5, 6).



Picture 5



Picture 6

3.2. Statistics and basics of the data

The test and train datasets are built similarly with the RUL-file being a single column vector.

Dataset	Rows	Columns
FD001 Train	26	20631
FD001 Test	26	13096
FD 001 RUL	1	429
Total Train + Test	26	33727

Table 2 data summaries

The data seems to be split in a 40/60 split where 40% of what could be viewed as the test dataset and 60% of the data is in the training dataset.

4. Challenges and Preprocessing Plan

4.1. Challenges:

The data overall isn't very well documented. The sensor measurement data doesn't really mean anything to a viewer despite it being floating point numbers or integers. The sensors and their functionality aren't explained at all.

As stated previously the data provided is split into different units that could potentially be analysed separately, or they might need to be analysed all together, there's no explanation on what units mean either.

The RUL file is also a unconnected singular vector that doesn't really connect to the main data in a consistent manner.

The largest challenge is the lack of full understanding of what one is looking at. Misunderstanding how to look at the dataset can lead to misanalysis and misguided machine learning development.

4.2. Preprocessing Plan:

To address these issues, the preprocessing plan involves imputing or removing missing values, detecting and managing outliers, and scaling the sensor data for consistency. The data is already split into a 40/60 split that we are ready to potentially alter if needed for a better split. Splitting the data in this manner should help us provide our machine learning models we create during the course in a reliable manner.