3 - 19 - 84 2nd Version Note (2-10-85) Added Dual Peripheral IC to this board to control waist motor. The input signal originantes from the motor interface card on the main belay board. Motor Speed Controlo 33 300 1: Adjust R, for max speed 2: = Power gnd = Signal gnd SN75446 Right relay 14 13 Gra Ø CLR J & CLR J +5V +5V Vee +5V +5V +5V Vcc +5V

Clock

From Kin3-

555