

# ~ Roots of Equations ~

## Bracketing Methods

### Chapter 5

# Roots of Equations

- Easy

$$ax^2 + bx + c = 0 \Rightarrow x = \frac{-b \mp \sqrt{b^2 - 4ac}}{2a}$$

- But, not easy

$$ax^5 + bx^4 + cx^3 + dx^2 + ex + f = 0 \Rightarrow x = ?$$

- How about these?

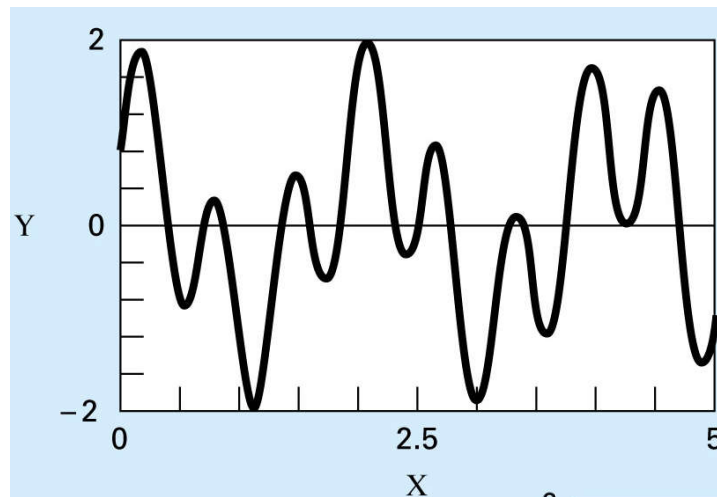
$$\sin x + x = 0 \Rightarrow x = ?$$

$$\cos(10x) + \sin(3x) = 0 \Rightarrow x = ?$$

# Graphical Approach

- Make a plot of the function  $f(x)$  and observe where it crosses the x-axis, i.e.  $f(x) = 0$
- Not very practical but can be used to obtain rough estimates for roots
- These estimates can be used as initial guesses for numerical methods that we'll study here.

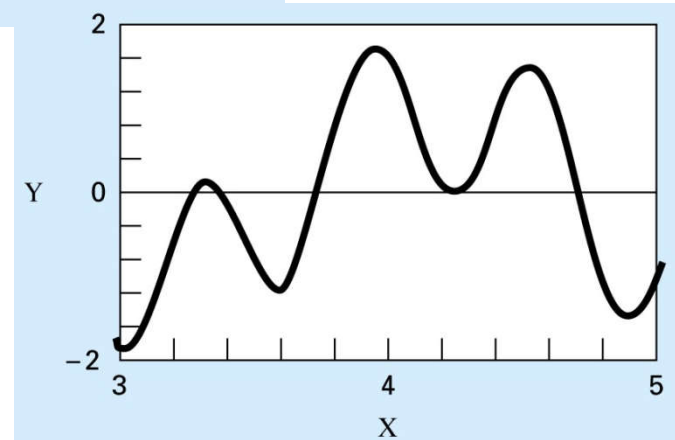
Using MATLAB, plot  $f(x)=\sin(10x)+\cos(3x)$



**Two distinct roots between**

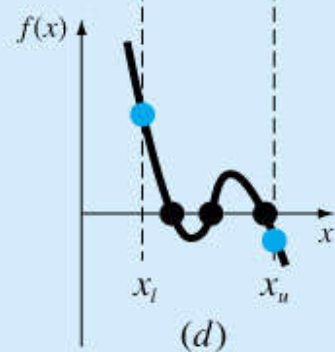
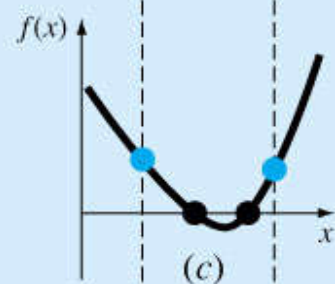
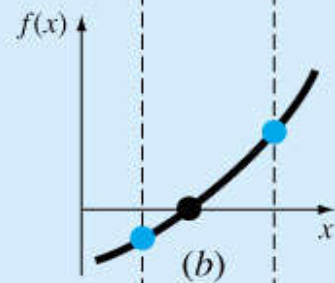
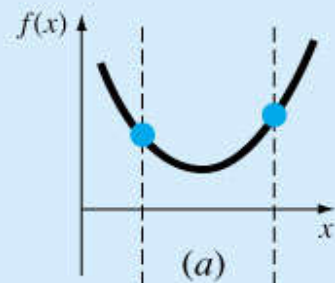
**$x = 4.2$  and  $4.3$**

**need to be careful**

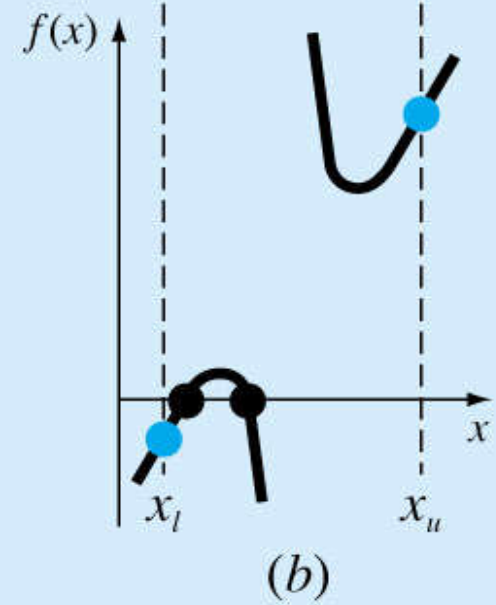
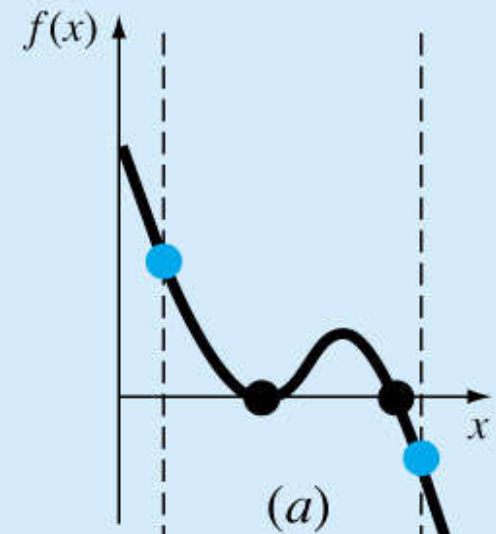


## Bracketing:

Odd and even  
number of roots



exceptions



# Bisection Method

Step 1: Choose lower  $x_l$  and upper  $x_u$  guesses for the root such that the function changes sign over the interval. This can be checked by ensuring that  $f(x_l)f(x_u) < 0$ .

Step 2: An estimate of the root  $x_r$  is determined by

$$x_r = \frac{x_l + x_u}{2}$$

Step 3: Make the following evaluations to determine in which subinterval the root lies:

- (a) If  $f(x_l)f(x_r) < 0$ , the root lies in the lower subinterval. Therefore, set  $x_u = x_r$  and return to step 2.
- (b) If  $f(x_l)f(x_r) > 0$ , the root lies in the upper subinterval. Therefore, set  $x_l = x_r$  and return to step 2.
- (c) If  $f(x_l)f(x_r) = 0$ , the root equals  $x_r$ ; terminate the computation.

Relative error estimate: 
$$\varepsilon = \frac{|x_r^{new} - x_r^{old}|}{|x_r^{new}|} 100\%$$

**Termination criteria:**  $\varepsilon < \varepsilon_{tol}$  OR *Max.Iteration* is reached

## MATLAB code

### *Bisection Method*

- Minimize function evaluations in the code.

### *Why?*

- Because they are costly (takes more time)

```
% Bisection Method
% function is available in another file e.g. func1.m
% A sample call:  bisection2(@func1, -2, 4, 0.001, 500)
```

```
function root = bisection(fx, xl, xu, es, imax);
```

```
if  fx(xl)*fx(xu) > 0           % if guesses do not bracket
    disp('no bracket')
    return
end
```

```
for i=1:1:imax
    xr=(xu+xl)/2
    ea = abs((xu-xl)/xl);
```

```
    test= fx(xl)*fx(xr);
```

```
    if test < 0
```

```
        xu=xr;
```

```
    end
```

```
    if test > 0
```

```
        xl=xr;
```

```
    end
```

```
    if test == 0
```

```
        ea=0;
```

```
    end
```

```
    if ea < es
```

```
        break;
```

```
    end
```

```
end
```

## How Many Iterations will It Take?

- Length of the first Interval  $L_0 = x_u - x_l$
- After 1 iteration  $L_1 = L_0/2$
- After 2 iterations  $L_2 = L_0/4$
- .....
- After k iterations  $L_k = L_0/2^k$
- Then we can write:

$$\left| \frac{L_k}{x_r} \right| \leq \text{error\_tolerance} \quad \text{where } x_r = \text{Min}\{|x_l|, |x_u|\}$$

$$\left| \frac{L_0}{2^k} \right| \leq |x_r| * \varepsilon_{tol}$$

$$2^k \geq \left| \frac{L_0}{|x_r| * \varepsilon_{tol}} \right| \Rightarrow k \geq \left\lceil \log_2 \left| \frac{L_0}{|x_r| * \varepsilon_{tol}} \right| \right\rceil$$

## \*here Bisection Method

### Pros

- Easy
- Always finds a root
- Number of iterations required to attain an absolute error can be computed a priori.

### Cons

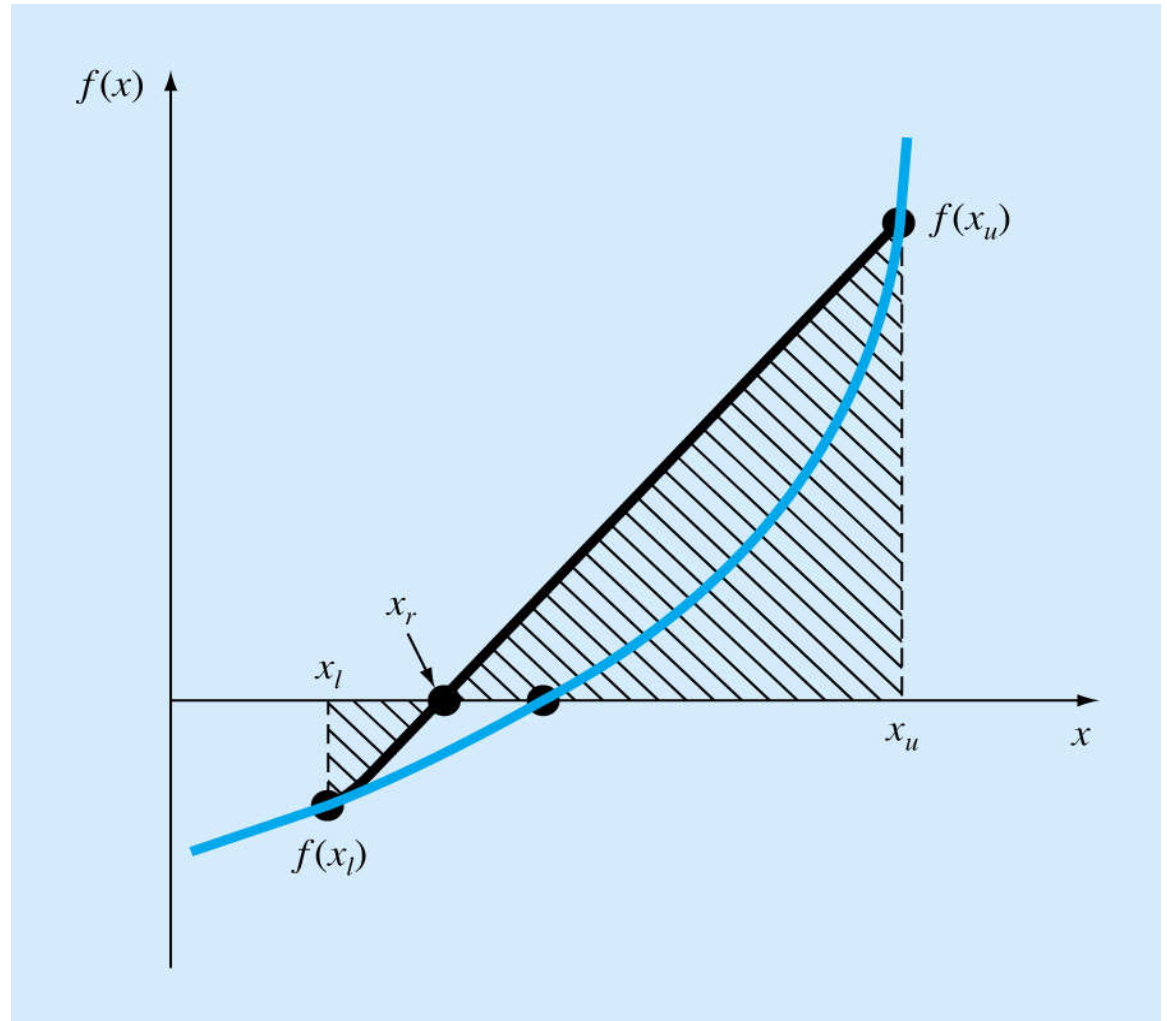
- Slow
- Need to find initial guesses for  $x_l$  and  $x_u$
- No account is taken of the fact that if  $f(x_l)$  is closer to zero, it is likely that root is closer to  $x_l$ .



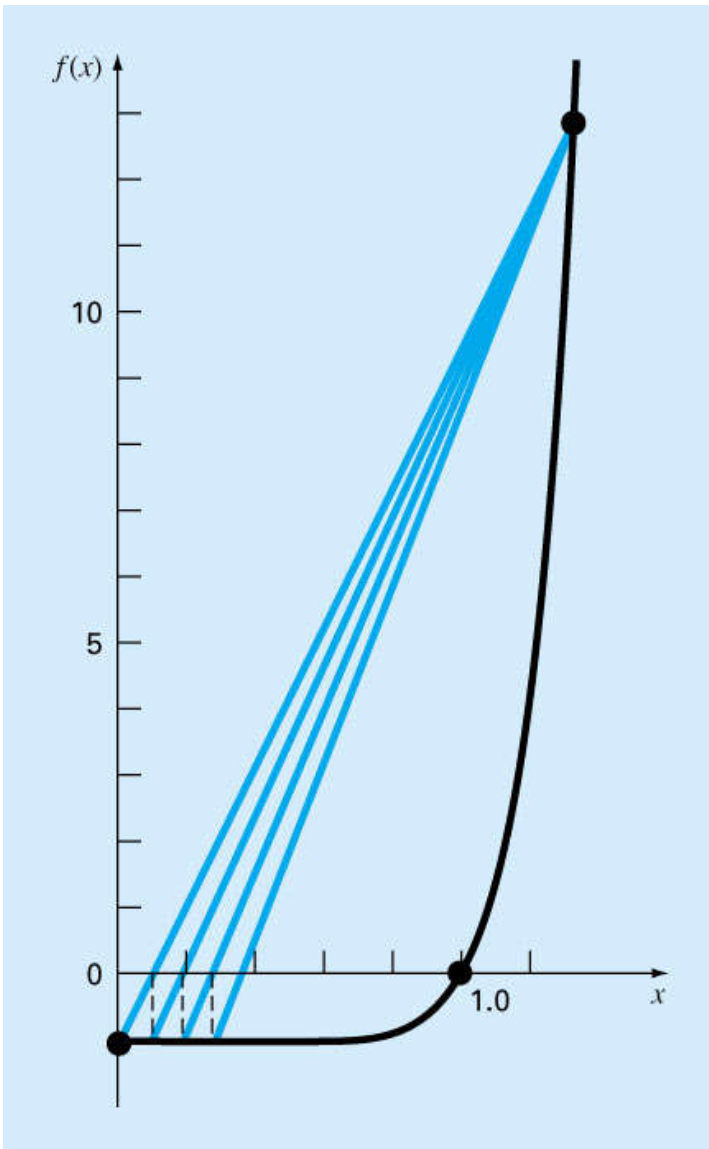
# The False-Position Method (Regula-Falsi)

- We can approximate the solution by doing a *linear interpolation* between  $f(x_u)$  and  $f(x_l)$
- Find  $x_r$  such that  $l(x_r)=0$ , where  $l(x)$  is the linear approximation of  $f(x)$  between  $x_l$  and  $x_u$
- Derive  $x_r$  using similar triangles

$$x_r = \frac{x_l f_u - x_u f_l}{f_u - f_l}$$



# The False-Position Method



Works well, but not always!  
←← Here is a pitfall ☹️

## Modified False-Position

One way to mitigate the “one-sided” nature of the **false position** (i.e. the pitfall case) is to have the algorithm pick the smallest bracket (between the Bisection Method & this one)

## How to find good initial guesses?

- Start at one end of the region of interest ( $x_a$ ) and evaluate  $f(x_a)$ ,  $f(x_a+\Delta x)$ ,  $f(x_a+2\Delta x)$ ,  $f(x_a+3\Delta x)$ , .....
- Continue until the *sign* of the result *changes*.  
If that happens between  $f(x_a+k*\Delta x)$  and  $f(x_a+(k+1)*\Delta x)$

then pick  $x_l = x_a + k*\Delta x$  and  $x_u = x_a + (k+1)*\Delta x$

### Problem:

if  $\Delta x$  is too small  $\rightarrow$  search is very time consuming

if  $\Delta x$  is too large  $\rightarrow$  could jump over two closely spaced roots

### Suggestions:

- Generate random  $x$  values and evaluate  $f(x)$  each time until you find two values that satisfy  $f(x_1)*f(x_2) < 0$
- Know the application and plot the function to see the location of the roots, and pick  $x_l$  and  $x_u$  accordingly to start the iterations.