

~ Numerical Differentiation and Integration ~

## Integration of Equations

### Chapter 22

# Romberg Integration

Successive application of the *trapezoidal rule* to attain efficient numerical integrals of functions.

**Richardson's Extrapolation:** In numerical analysis, **Richardson extrapolation** is a sequence acceleration method, used to improve the rate of convergence of a sequence. Here we use two estimates of an integral to compute a third and more accurate approximation.

$$I = I(h) + E(h) \quad h = (b - a) / n \quad n = (b - a) / h$$

$$I(h_1) + E(h_1) = I(h_2) + E(h_2) \quad \begin{array}{l} I = \text{exact value of integral} \quad E(h) = \text{the truncation error} \\ I(h): \text{trapezoidal rule (n segments, step size h)} \end{array}$$

$$E \cong \frac{b-a}{12} h^2 \bar{f}'' = O(h^2) \quad (\text{assume } \bar{f}'' \text{ is constant for different step sizes})$$

$$\frac{E(h_1)}{E(h_2)} \cong \frac{h_1^2}{h_2^2} \quad \Rightarrow \quad E(h_1) \cong E(h_2) \left( \frac{h_1}{h_2} \right)^2$$

$$I(h_1) + E(h_2) \left( h_1 / h_2 \right)^2 \cong I(h_2) + E(h_2) \quad \Rightarrow \quad E(h_2) \cong \frac{I(h_2) - I(h_1)}{(h_1 / h_2)^2 - 1}$$

$$I = I(h_2) + E(h_2)$$

$$I \cong I(h_2) + \frac{1}{(h_1 / h_2)^2 - 1} [I(h_2) - I(h_1)]$$

**Improved estimate of the integral.**

It is shown that the error of this estimate is  $O(h^4)$ . Trapezoidal rule had an error estimate of  $O(h^2)$ .

$$I \cong I(h_2) + \frac{1}{(h_1 / h_2)^2 - 1} [I(h_2) - I(h_1)]$$

If  $(h_2 = h_1 / 2) \Rightarrow$

$$I \cong I(h_2) + \frac{1}{2^2 - 1} [I(h_2) - I(h_1)] = \frac{4}{3} I(h_2) - \frac{1}{3} I(h_1)$$

## Example

Evaluate the integral of  
from  $a=0$  to  $b=0.8$ .

$$f(x) = 0.2 + 25x - 200x^2 + 675x^3 - 900x^4 + 400x^5$$

$$I (\text{True Integral value}) = 1.6405$$

Segments	h	Integral	$\epsilon_{tr} \%$
1	0.8	0.1728	89.5
2	0.4	1.0688	34.9
4	0.2	1.4848	9.5

Segments 1 & 2 combined to give :

$$I \cong \frac{4}{3} (1.0688) - \frac{1}{3} (0.1728) = 1.3675$$

$$E_t = 1.6405 - 1.3675 = 0.273 \quad (\epsilon_t = 16.6\%)$$

Segments 2 & 4 combined to give :

$$I \cong \frac{4}{3} (1.4848) - \frac{1}{3} (1.0688) = 1.6234$$

$$E_t = 1.6405 - 1.6234 = 0.0171 \quad (\epsilon_t = 1\%)$$

In each case, two estimates with error  $O(h^2)$  are combined to give a third estimate with error  $O(h^4)$

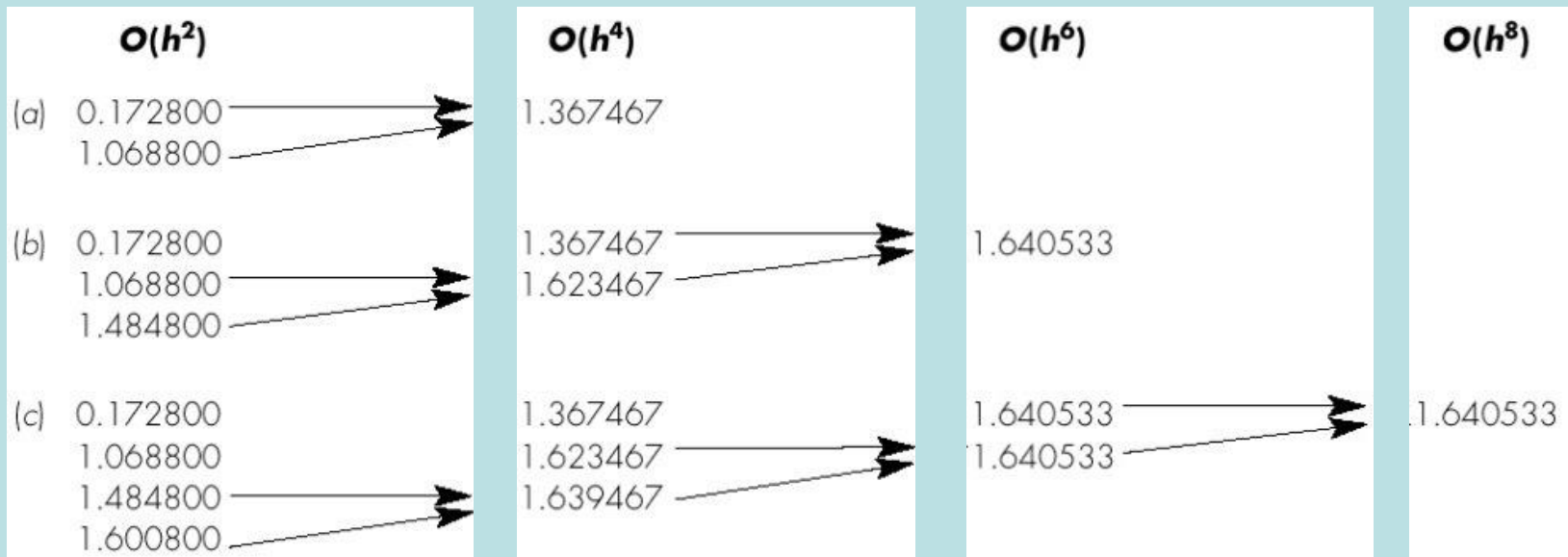
In Example 22.1, we computed two improved estimates of  $O(h^4)$ . These two estimates can, in turn, be combined to yield an even better value with error  $O(h^6)$ . For the special case where the original trapezoidal estimates are based on *successive halving* of the step size, the equation used for  $O(h^6)$  accuracy is:

$$I \cong \frac{16}{15} I_m - \frac{1}{15} I_l$$

where  $I_m$  and  $I_l$  are more and less accurate estimates

Similarly, two  $O(h^6)$  estimates can be combined to compute an  $I$  that is  $O(h^8)$ .

$$I \cong \frac{64}{63} I_m - \frac{1}{63} I_l$$



# The Romberg Integration Algorithm

$$I_{j,k} \cong \frac{4^{k-1} I_{j+1,k-1} - I_{j,k-1}}{4^{k-1} - 1}$$

k=1 refers to *trapezoidal* rule, hence  $O(h^2)$  accuracy.

k=2 refers to  $O(h^4)$  and k=3  $\rightarrow O(h^6)$

Index j is used to distinguish between the *more* (j+1) and the *less* (j) accurate estimates.

