

## Operations Manual





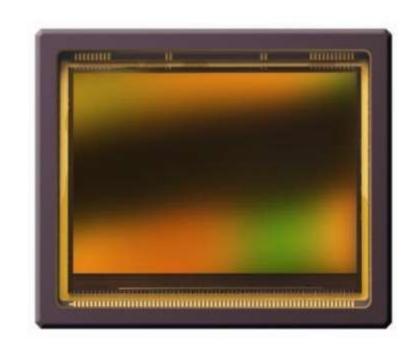
RMOD-71 and RMOD-71 TEC rev D www.illunis.com

Wednesday, October 02, 2019



Rev	Date	Modification
Α	2/27/18	Original Document
В	3/27/19	Added Image Grab and Display
С	8/01/19	Revised Trigger Mode Select to "W"
D	9/20/19	Command 04 03 to W and frame rate table

### REVISIONS RMOD-71/RMOD-71 TEC





### RMOD-71/RMOD-71 TEC Precautions

Do not drop, damage, disassemble, immerse, repair or alter the camera.

Applying incorrect power may damage the camera electronics.

The warranty is void if the camera is opened or modified in any way.

Care must be taken in handling as not to create static discharge that may permanently damage the device.

Camera Link is a DC based interface. The camera and capture device must share the same electrical ground. Failure to do so will damage the Camera Link interface chips and/or camera and capture card.

The maximum Camera Link data rate is 85Mhz. This limits the maximum pixel clock speed to 42.5Mhz, which is provided as an overclock mode. Operation is guaranteed at 30Mhz pixel clock and below.

PoCL cables are compatible with the RMOD-71/RMOD-71 TEC camera. PoCL camera power is not supported.

Specifications subject to change without notice.

### Precautions RMOD-71/RMOD-71 TEC



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### Contents RMOD-71/RMOD-71 TEC





# Camera

### **Camera Power**

Apply 6-12V DC Power to the Hirose 6 pin connector. Mating Connector: Hirose HR10A-7P-6P

PIN	SIGNAL NAME
1	+12V DC
2	DC Ground
3	Trigger In
4	Strobe Out
5	No Connect
6	No Connect



View from Camera Back

### **Capture Card**

Any Base Mode or Medium Mode Camera Link capture card Such as: Teledyne Dalsa Xtium-CL MX4 OR-Y4CO-XMX00.

### Imaging SDK

Available from your capture card supplier.

### Camera Link Cables

One or two Camera Link cables (Mini HDR to SDR) **must be** rated at 85Mhz or more (two cables for Medium Format).

The following 5M cable configurations have been tested: Standard MDR to HDR/SDR MVC-1-1-5-5M Available from Components Express.

http://www.componentsexpress.com/Configurator.aspx?cnfi=1

### **Camera Communication Software**

illunis Camera Serial Communication Software (GUI) Download at: <a href="http://illunis.com/illunis/downloads">http://illunis.com/illunis/downloads</a>



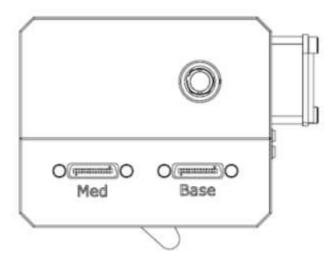


# Started Camera Link

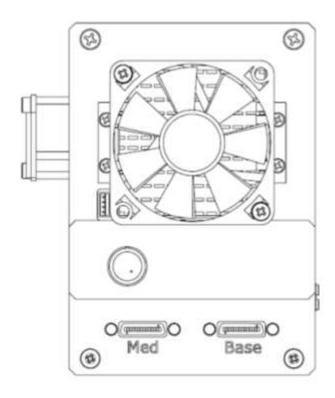
### To start imaging with the RMOD-71/RMOD-71 TEC CL:

Install the capture card and software per the capture card manufacturers instructions.

Connect the RMOD-71/RMOD-71 TEC Camera Link cables paying attention to the base and medium connections



RMOD-71



**RMOD-71 TEC** 





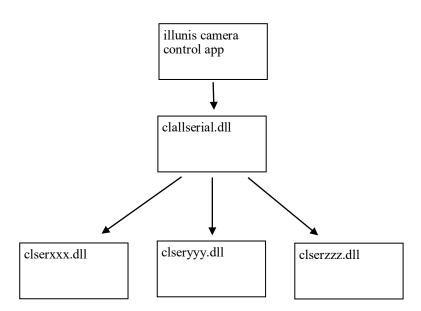
### **Installing the illunis Camera Serial Communication Software:**

Download and install the illunis Camera Serial Communication Software (GUI) from http://illunis.com/illunis/downloads

### **Background:**

Per the CameraLink standard, all serial communication is via the .dll clallserial.dll, which dynamically loads the serial communication .dll(s) specific to the frame grabber being used. illunis installs clallserial .dll in its application directory.

clallserial.dll examines the registry to see where the capture card specific communication dll's have been installed. The naming convention for the capture card specific communication dll's is clser\*\*\*.dll where \*\*\* is the manufacturer specific dll name. The files MUST be in the form clser\*\*\*.dll in order to be recognized. Some capture card manufacturers will append something like clser\*\*\*x64.dll for the 64 bit version of the .dll. This file name must be changed to clser\*\*\*.dll in order to be recognized by clallserial.dll.





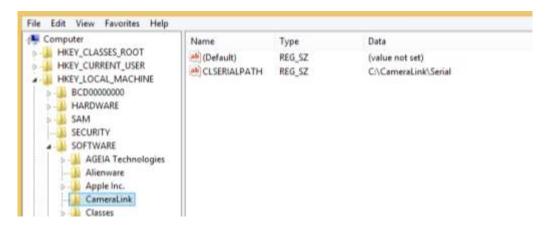


### The registry:

When clallserial.dll is loaded by the illunis serial communication application, it looks at the Registry entry:

HKEY\_LOCAL\_MACHINE\SOFTWARE\Cameralink CLSERIALPATH.

The location pointed to by CLSERIALPATH is typically C:\Cameralink\Serial, but could be any path that a capture card install might create. It is important to note that the capture card communication dll(s), clser\*\*\*.dll must be at this path location. clallserial.dll should NOT be in this location.



If the capture card communication dll is spec 1.1 compliant, the user will find this directory already created.

The illunis control app installs clallserial.dll for the appropriate operating system in the application folder. Depending on the application version, some documentation may be installed in the application folder as well.

If the registry entry above does not exist, create it as well as the directory C:\CameraLink\Serial

In either case—copy, paste the clser\*\*\*.dll files to the location specified by CLSERIALPATH





### Installing prerequisite software:

The status of these items can be checked in the Control Panel -> Programs and Features listing. If necessary download and install the following prerequisites.

1. .NET Framework 4.6 to be installed from:

https://www.microsoft.com/en-us/download/details.aspx?id=48130

2. Visual C++ 2010 Redistributable from:

https://www.microsoft.com/en-us/download/details.aspx?id=14632

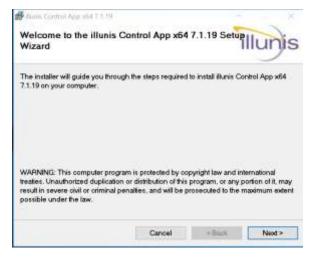
3. Visual C++ 2013 Redistributable from:

https://www.microsoft.com/en-us/download/details.aspx?id=40784





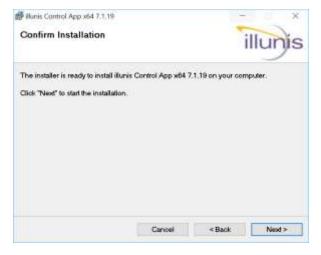
### **Install the Camera Serial Communication Software:**



Launch the installer



Select the installation folder...



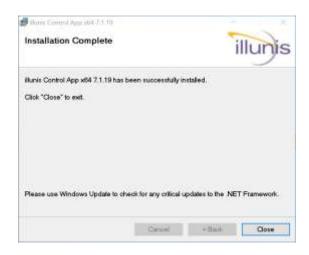
Confirm...





### Pra Link

## Camera



Install complete...

**Note:** A shortcut to the program will be placed on the desktop.

Power up the camera and run the illunis Camera Serial Communication Software.

If there are multiple clserxxx.dll's for multiple cards installed, a choice of possible connections will be presented.

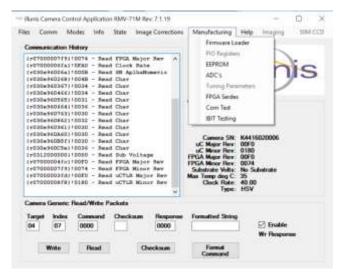
If there is only a single capture board present and one clserxxx.dll, the application will simply connect to that card/port.







### illunis Camera Serial Communication Software Main Window:

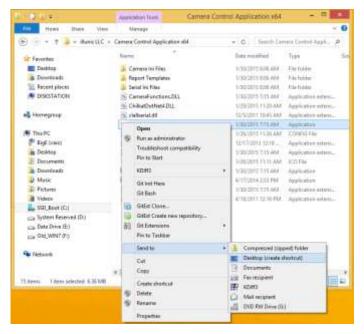


### **Disabled Menus**

By default, sensitive menu items are disabled to prevent inadvertent changes to the camera state. To enable them, a new shortcut has to be created on the desktop.

First, delete the desktop shortcut created by the installer.

### Creating a new shortcut for program options:



### Create a new Shortcut

Navigate to the program install directory and right click on the file with the illunis icon and extension .exe. Choose -> Send to -> Desktop. This creates a new desktop shortcut icon.





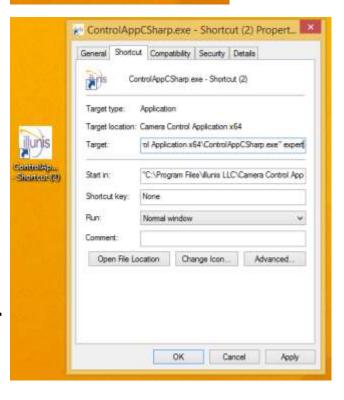
Camera Link

### Adding options to the shortcut command line:



Create shortcut.
Delete
Rename
Properties

Right click on the newly created desktop icon and select Properties.



Add a space and the word **expert** after the close quote on the Target: line of the dialog box: .exe" expert

Choose OK.
When the program is launched, all menus will be enabled. NOTE: Use care with all menus enabled as some changes cannot be undone and may require the camera be returned to the factory for remedy.

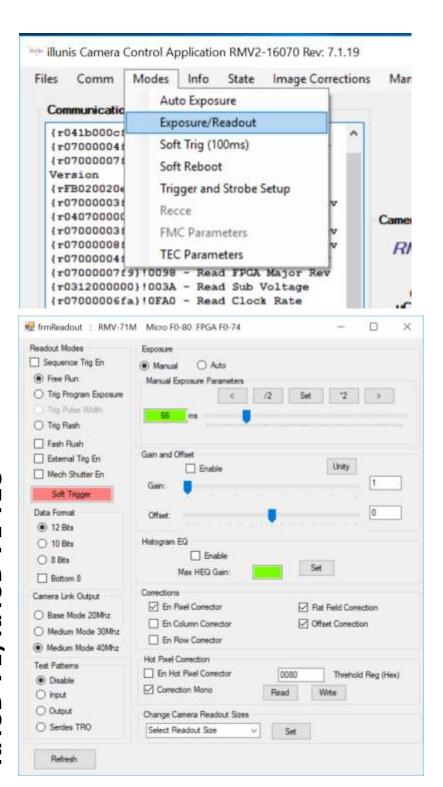




Camera

### Exposure / Readout:

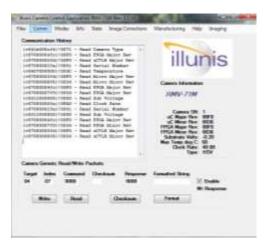
Start with this dialog box.







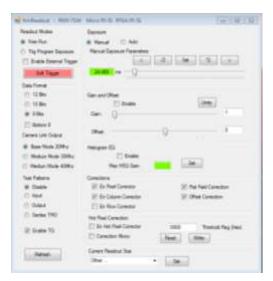
### **Camera Control Application Details:**



### **Main Dialog**

The main dialog box provides access to the various functions of the camera. Menus are used to access sub-dialogs. A generic camera register read/write feature is provided.

In addition, a history of communication is also provided in this dialog box.



### Modes->Exposure and Readout

This dialog box is used to set the Readout Mode, Free Run, or Trigger, as well as the bit depth and exposure of the camera. In addition, the user can set the Camera Link mode, test patterns, digital gain and offset, and histogram equalization.

Pre-defined windowing modes can be selected. A reset (Enable TG) is available.



### **Trigger and Strobe Setup**

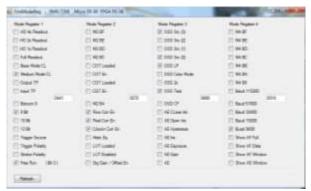
This dialog box is used to set the trigger source and polarity. The strobe output is only available in the Trigger Exposure Mode.





## Camera

### **Camera Control Application Details:**



### Mode

The mode dialog indicates the current mode that the camera is



### Firmware Loader

The firmware loader dialog is used to load FPGA and Microprocessor code as well as the EEPROM configuration data. See page 73 for details.

A useful feature of this dialog is the ability to save and restore the camera to and from a file. If there are problems with the camera, the camera state may be saved to a file and then emailed to illunis for support.



### **Defect Corrector Editor**

The defect corrector editor dialog provides editing of the defect corrector tables.





# Camera Link

### **General Comments:**

The control application is for communication with the camera until the user application takes over these functions. All buttons and sliders show the command that is being executed in the application main window.

In the main window, there is a generic read and write section allowing any command that can be found in the manual to be sent to the camera and see its response.

**NOTE:** If a camera mode is changed, the corresponding change in the capture environment will have to be made as they are independent.





### **Teledyne Dalsa CamExpert Setup**

### A B A B Cameralini Configuratio f of Segment per Line (TAPS) TAPS Geometry # of Channel Tap/Channel 1 Direction Tap/Charriel 2 Direction Left to Right, Top to Bottom Top/Channel 3 Direction Left to Right, Top to Botto Tap/Charmel & Direction Left to Right, Top to Bottom A F C DE F G H A ABAB ABAB

### **Medium Format**

Denu

Denu

Deno Deno

Demo

Denc

Demo:

Dens

Denn

Deno

#

8

C D C D

1

Demo

Dens

Demo

Demo Demo

Decro

Deno

Deno Deno

Demo

Demo

4 pixels per clock Left to Right, Top to Bottom

Note: Changing from Top to Bottom to Bottom to Top will flip the image vertically!

### **Base Format**

2 pixels per clock Left to Right, Top to Bottom

# Camera Link

1

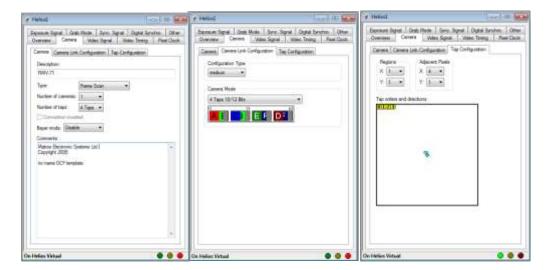
ABCDEFBH



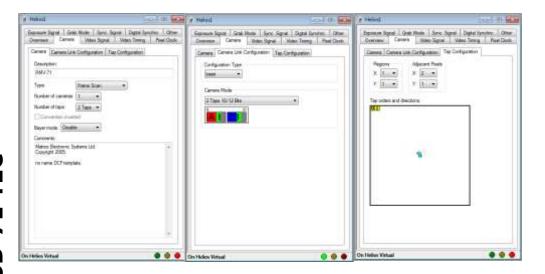


## tarted Camera Lin

### **Matrox Intellicam Setup**



Medium Format, 4 pixels per clock, Left to Right, Top to Bottom



Base Format, 2 pixels per clock, Left to Right, Top to Bottom





### Camera Power

Apply 6-12V DC Power to the Hirose 12 pin connector. Mating Connector: Hirose HR10A-10P-12S73

PIN	SIGNAL NAME
1	DC Ground
2	+12V DC
8	Trigger In
4	Strobe Out



### View from Camera Back

### **USB3 Port**

The USB camera connection requires a USB 3.0 compliant hardware port. The camera will not function connected to a USB 2.0 hardware port.

### Imaging SDK

illunis cameras utilize Pleora embedded USB3 hardware inside the camera. The imaging application/SDK are available to download from:

https://supportcenter.pleora.com/s/topic/0TO340000004X6dGAE/ebussdk?tabset-25adb=81d66&tabset-0c866=2

Go to downloads to select and download the current viewer for your environment.

### **USB3 Cables**

illunis recommends L-com cables, the camera requires a Micro-b connector.

http://www.l-com.com/usb-usb-30-vision-cable-assemblies-type-a-and-micro-b-with-thumbscrews

### **Camera Communication Software**

illunis Camera Serial Communication Software (GUI) Download at: http://illunis.com/illunis/downloads





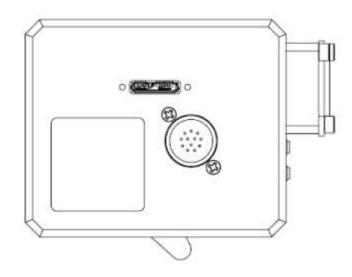
### To start imaging with the RMOD-71 USB3:

Install eBus SDK software.

Connect the RMOD-71 USB3 cable to the camera and PC.

Connect the power cable to the camera and apply power.









### To start imaging with the RMOD-71:

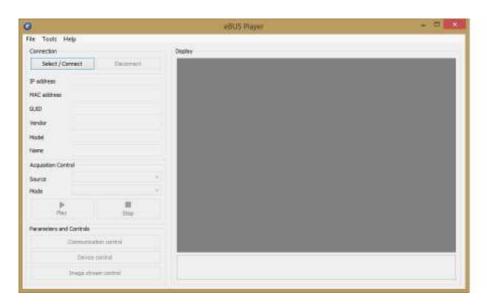
Install eBus SDK software

Additional SDK documentation and resources are available from: <a href="https://supportcenter.pleora.com/s/topic/0TO340000004X6dGAE/ebus-sdk?">https://supportcenter.pleora.com/s/topic/0TO340000004X6dGAE/ebus-sdk?</a> <a href="tabset-25adb=d1819&tabset-0c866=2&tabset-3b862=2">tabset-25adb=d1819&tabset-0c866=2&tabset-3b862=2</a>

Additional eBus Player documentation and resources are available from: <a href="https://supportcenter.pleora.com/s/topic/0TO3400000PW53GAG/ebus-player?tabset-25adb=70906&tabset-ec78c=2">https://supportcenter.pleora.com/s/topic/0TO3400000PW53GAG/ebus-player?tabset-25adb=70906&tabset-ec78c=2</a>

Install the illunis Camera Serial Communication Software. Follow the installation instructions beginning on page 7 of this manual, then return here prior to running the camera control application.

To begin imaging, launch the eBus player.



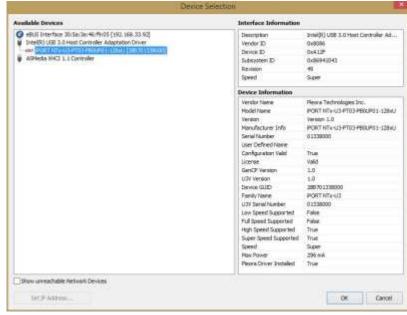
Press Select/Connect

### Started USB3

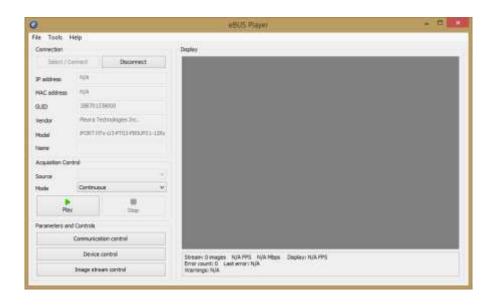








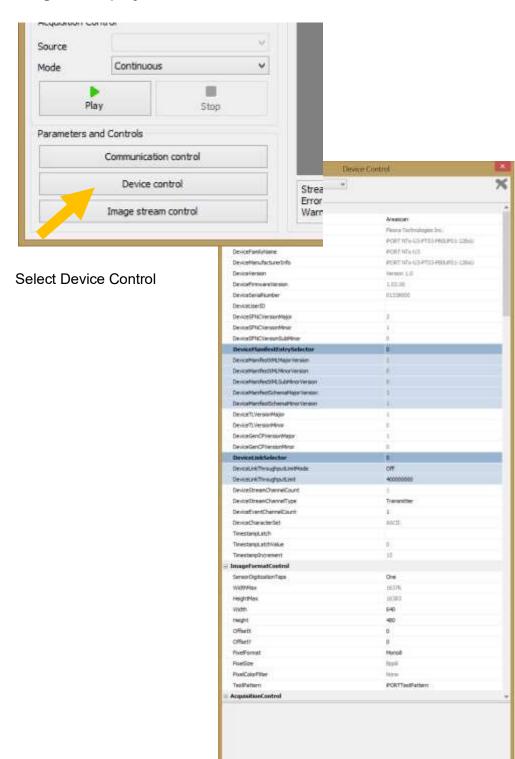
### eBus Player is ready to image





### Configure the player:



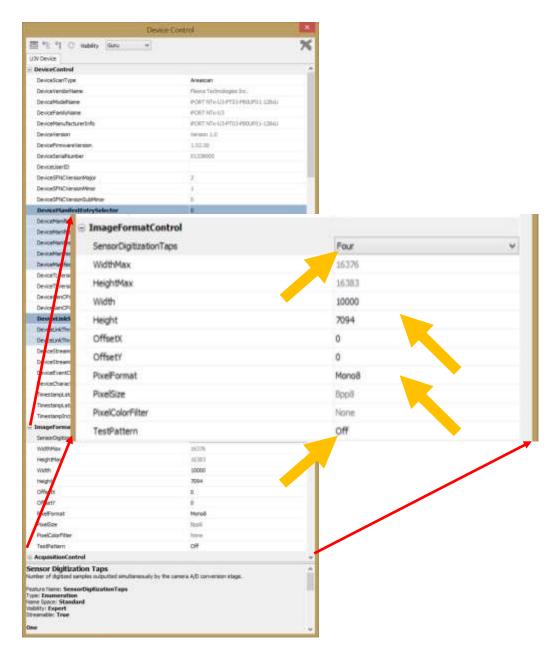


Getting Started USB3





### Getting Started USB3



### **Set the Device Control parameters**

Set the raster to Width = 10,000, Height = 7094

Turn the TestPattern = off

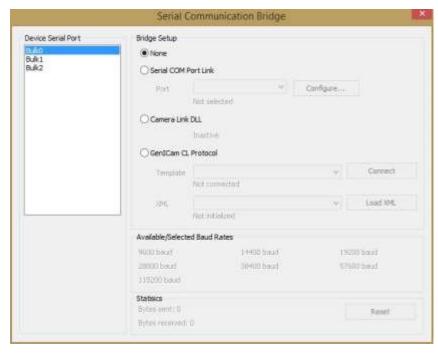
Set the SensorDigitationTaps = Two or Four

Set the PixelFormat = Mono8 or Mono12Packed

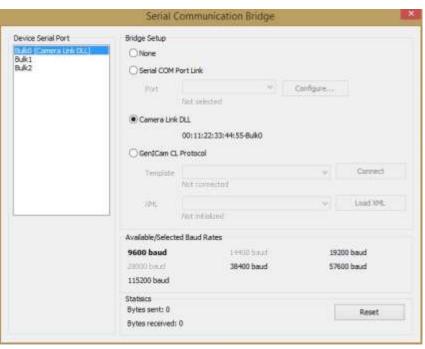








From the Tools Menu on the viewer, choose Serial Communication Bridge



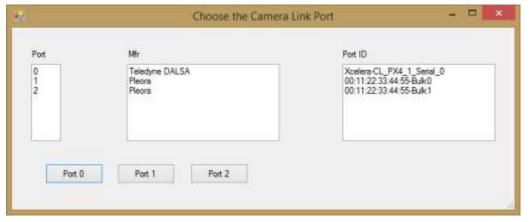
Choose Camera Link DLL - **THEN LEAVE THIS WINDOW OPEN** 



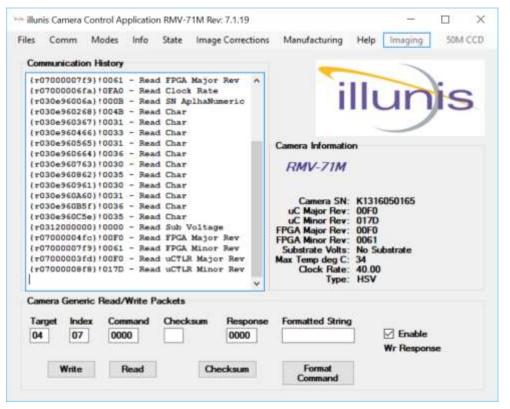
### Run the illunis Camera Serial Communication Software that was installed previously:







### Choose the **BULK0** Interface

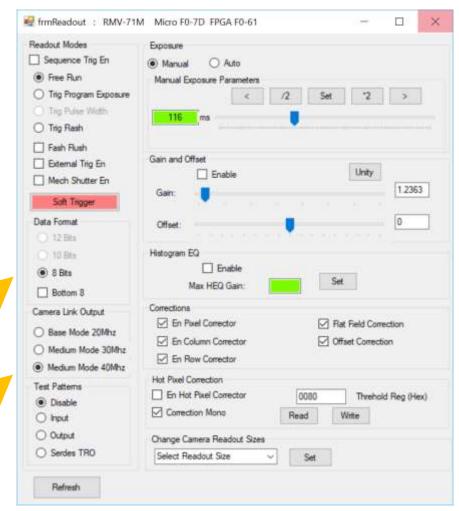


The camera serial communication software main window will appear.



### S O N S I

### From the Modes menu choose Exposure/Readout



Choose the same settings that were set in the Player Device Control earlier.

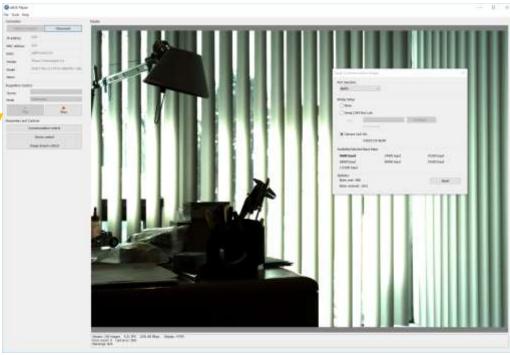
### For the RMOD-71/RMOD-71 TEC the following rates apply

Select **Base Mode 20Mhz** and Data format = **12Bits** or **8Bits**Select **Medium Mode 30Mhz** and Data format = **8Bits** for 3fps
Select **Medium Mode 40Mhz** and Data format = **8Bits** for 4.2fps









### **General Comments:**

The control application is for communication with the camera until the user application takes over these functions. All buttons and sliders show the command that is being executed in the application main window.

See the Getting Started Camera Link section for more camera control application dialog box documentation.

In the main window, there is a generic read and write section allowing any command that can be found in the manual to be sent to the camera and see its response.

**NOTE:** If a camera mode is changed, the corresponding change in the eBus Player will have to be made as they are independent.



### RMOD-71/RMOD-71 TEC Specifications:

Active Image	10,000 x 7096 (Windowing optional)
Sensor Type	ams/CMOSIS CHR71M Mono or Color

RMOD-71/RMOD-71 TEC

Pixel Size 3.1µm x 3.1µm

Sensor Output 8 taps

**Item** 

Video Output 8/10/12 bits

Memory 8 images are stored in internal 256 MB

memory.

Camera Interface Base or Medium Format Camera Link, USB3

Electronic Shutter Rolling shutter with Global reset

CL Data rate 2.11 fps (Base CL), 3.0/4.22 fps (Medium CL)

USB3 Data rate 2.11fps 12bit, 3.0/4.22fps 8 bit

Pixel Clock 21.25/30/42.5Mhz

Shutter Speed Increments of line time.

Windowing H increments of 16 columns, V increments of

8 rows

Black Level Adjustable
Analog Gain 1X ~40X

Digital Gain 1X-16X (1/4096 step)

Exposure Modes Programmed Free Run, Programmed

Triggered

External Trigger 3.3-5.0V TTL

Software Trigger Per Camera API

Dynamic Range 64dB

Defect Correction Pixel + Column + Row + Hot Pixel

Flat Field Correction Column Gain, Tap offset

Lens Mount OEM/M58, Nikon F, Canon EF

Power - varies with mode and 6-14V DC, Max 8W

data interface Base Mode ex. ~4.4W @ 12VDC

Medium Mode ex. 30Mhz ~5.4W @ 12 VDC Medium Mode ex. 42.5 Mhz ~6.4W @12 VDC

Environmental Operating 0C to 60C, Storage –40C to +85C

Vibration/Shock 10G (20-200Hz) XYZ 70G 10ms



### RMOD-71/RMOD-71 TEC Sensor Specifications:

### The RMOD-71/RMOD-71 TEC Digital Camera incorporates the ams/CMOSIS CHR71M-sensor.

### **Sensor Features**

- 10,000 x 7096 active pixels with a 3.1µm pitch.
- Frame rate at full resolution is 4 frames /sec.
- Windowing capability in 16 x 8 pixel increments.
- Moving window capability.
- Selectable pixel clock from two sources (30, 42.5Mhz).
- 8 analog outputs digitized to 12 bits.
- On chip timing for Free Run and Trigger Modes.
- Mono or Bayer pattern output.
- Mono is available as High Grade (No row or column defects)

### **Sensor Specifications**

- Full well charge: > 13ke.
- Sensitivity: 0.15A/W (@ 555nm).
- Dark Noise: 7e-
- Conversion factor: ~63uv/e.
- Dynamic range: 64dB.
- Dark Current: 3.2e-/s @ room temperature.
- Fixed Pattern noise: 0.09 (% of full swing).



### RMOD-71/RMOD-71 TEC Sensor Pixel Response:

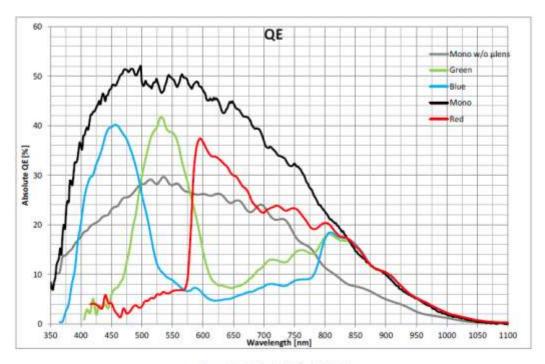


Figure 21: Typical QE of a CHR70M

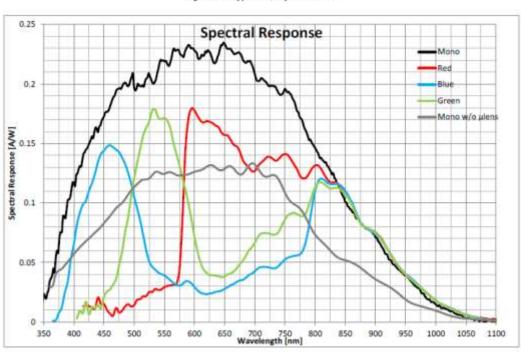
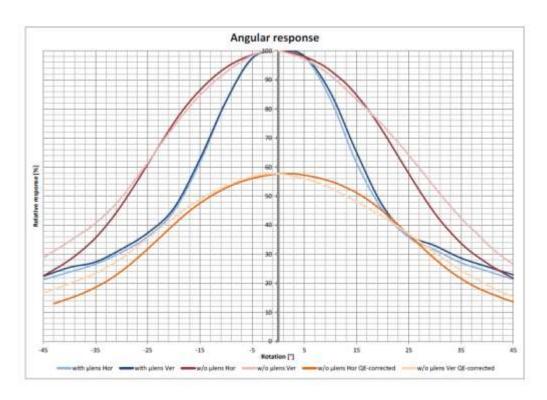


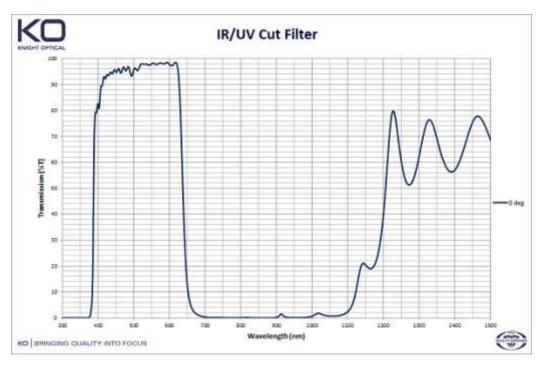
Figure 22: Typical spectral response of a CHR70M



### RMOD-71/RMOD-71 TEC Sensor Microlens Angular Response:

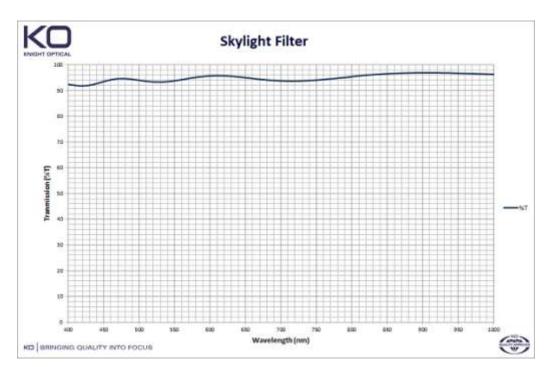


### RMOD-71/RMOD-71 TEC IR/UV Cut Filter response:





### RMOD-71/RMOD-71 TEC Clear Filter response:



### Camera - Overview RMOD-71/RMOD-71 TEC



### RMOD-71/RMOD-71 TEC Sensor Pixel Defects - Standard Grade

The RMOD-71/RMOD-71 TEC camera uses the ams/CMOSIS CHR71M sensor. The Standard grade sensor can have the following maximum allowable defects:

FPN: Max 2% RMS PRNU: Max 5% RMS

Defective Columns: 15\*
Defective Rows: 15\*
Defective Pixels: 5000
Clusters 2 pixels: 50
Clusters 3 pixels 20
Clusters 4 pixels 5

### RMOD-71/RMOD-71 TEC Sensor Pixel Defects - High Grade Sensor:

The RMOD-71/RMOD-71 TEC camera uses the ams/CMOSIS CHR71M sensor. The High grade sensor can have the following maximum allowable defects:

FPN: Max 2% RMS PRNU: Max 5% RMS

Defective Columns: 0
Defective Rows: 0
Defective Pixels: 5000
Clusters 2 pixels: 50
Clusters 3 pixels 20
Clusters 4 pixels 5

### NOTE:

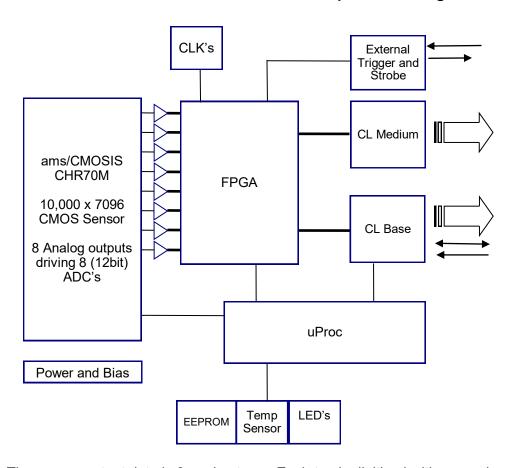
Defects are corrected in the camera hardware as part of the manufacturing process.

### Jamera – Overview

<sup>\*</sup>No adjacent column or row defects are allowed.



### RMOD-71/RMOD-71 TEC Camera Link output block diagram:



The sensor output data is 8 analog taps. Each tap is digitized with an analog to digital converter (ADC) with 12 bit precision. Each ADC is programmable in gain, offset, data phase, and sensing phase (typically the user never has to adjust the ADC).

The FPGA reorders the tap data into two paths of pixels (odd and even) and outputs the pixels onto a Camera Link bus. The output data can be formatted to Camera Link Base Mode (2 (12 bit) pixels per clock) or Camera Link Medium Mode (4 (12 bit) pixels per clock). The Camera Link interface includes trigger and serial communications.

In addition, an external trigger and strobe are provided on the power connector.

The on-board microprocessor controls the sensor and FPGA operation, as well as monitors the various sensors within the camera.

**Note:** In the case of USB3, the FPGA data is output directly to the USB3 interface board.



## Camera Link

Camera Link is a data interface for visual applications that use digital imaging. The Camera Link (CL) interface is built upon the National Semiconductor Channel Link technology and specifies how image data is formatted and transferred. Channel Link consists of a driver and a receiver pair. The driver accepts 28 single ended data signals and a single ended clock. The data is serialized 7:1 and the four data streams and a dedicated clock are transmitted over five LVDS pairs. The receiver accepts the four data streams and the clock, decodes the data, and drives the 28 bits of data to the capture circuit.

Image data and image enables are transmitted on the Camera Link bus. The four Enable signals are:

FVAL: Frame Valid is defined HIGH for valid lines. LVAL: Line Valid is defined HIGH for valid pixels. DVAL: Data Valid is defined HIGH for valid data.

SPARE: undefined, for future use.

Four LVDS pairs are reserved for general purpose camera control. They are defined as camera inputs and frame grabber outputs. The signals are CC1, CC2, CC3, CC4. The RMOD-71/RMOD-71 TEC uses CC1 as the trigger source.

The Camera Link interface has three configurations:

Base: Single Channel Link chip, single cable connector.
Medium: Two Channel Link chips, two cable connectors.
Full: Three Channel Link chips, two cable connectors.

**Note:** RMOD-71/RMOD-71 TEC can operate in a **Base** or **Medium** Camera Link configuration.



## RMOD-71/RMOD-71 TEC Performance Camera Link:

The RMOD-71/RMOD-71 TEC is user selectable in Base and Medium Format Camera Link outputs:

Base Mode is limited to 2 channels of data at 85Mhz = 170Mpix/s. Medium Mode outputs 4 channels of data at 85Mhz = 340Mpix/s.

Medium Mode can be selected to run at manufactures specified speed of 30Mhz per tap giving a clock rate of 60Mhz and a full frame rate of ~3 fps.

Medium Mode can also be selected to run at an overclocked speed of 42.5Mhz per tap giving a clock rate of 85Mhz and a full frame rate of ~4 fps.

All data rates can be output as 8, 10, or 12 bits per pixel.

## RMOD-71/RMOD-71 TEC Camera Link Performance:

Camera Link Mode	Cables	Bits/Pixel	Frame Rate
Base	1	8/10/12	2.1
Medium 30	2	8/10/12	3.0
Medium 42.5	2	8/10/12	4.2

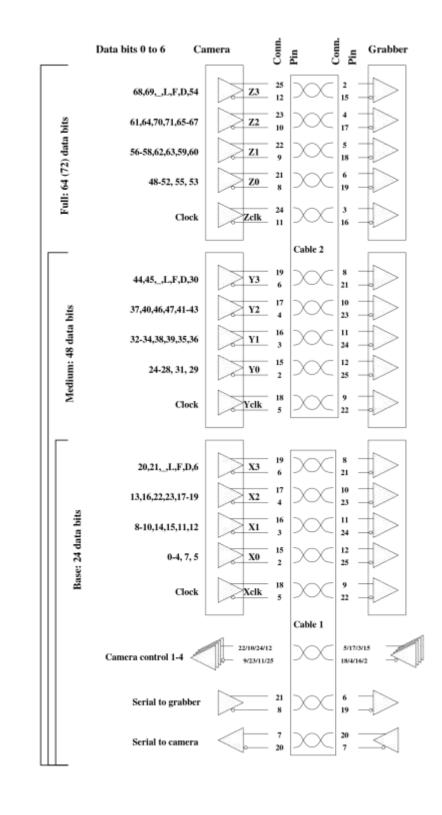
## nera – Overview 71/RMOD-71 TEC

## RMOD-71/RMOD-71 TEC UB3 Performance:

Bits/Pixel	Frame Rate
8 (42.5Mhz)	4.2
8 (30Mhz)	3.0
12 (21.5Mhz)	2.1



## Camera Link



## Camera - Overview RMOD-71/RMOD-71 TEC

## **Pixel Format**

The RMOD-71/RMOD-71 TEC camera samples the sensor with 12 bit precision and processes the data throughout the FPGA at 12 bits.

During the data format stage, the 12 bit image data can be down sampled to 10 or 8 bits. In addition, the bottom 8 bit data can be output as the top 8 (msb) of the 12 bit image sample.

Sensor AD	Sensor ADC pixel sample to Camera Link mapping								
ADC bits	12 bit CL	10 bit CL	8 bit CL						
11	11>11	11>9	11>7						
10	10>10	10>8	10>6						
9	9>9	9>7	9>5						
8	8>8	8>6	8>4						
7	7>7	7>5	7>3						
6	6>6	6>4	6>2						
5	5>5	5>3	5>1						
4	4>4	4>2	4>0						
3	3>3	3>1							
2	2>2	2>0							
1	1>1								
0	0>0								

## **Channel Format**

The Camera Link Base Mode used on the RMOD-71/RMOD-71 TEC camera, can transfer pixel data in 8, 10, 12 bit depths and in one or two channels. Two channel mode allows for a transfer clock frequency 1/2 of the single channel mode.

The Camera Link Medium Mode transfers four pixels per clock. The Medium Mode requires two Camera Link cables and a capture card that is compatible with the Medium format.



## RMOD-71/RMOD-71 TEC ROI Frame Rate Table Camera Link:

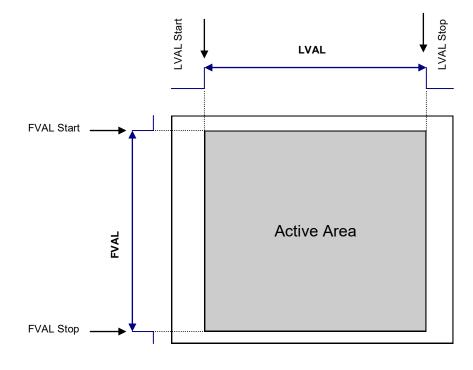
	Base	Full	4HD	2HD	HD	VGA
SensorX		10000	7680	3840	1920	640
SensorY		7096	4320	2160	1080	480
ROT clks		168	168	168	168	168
ClockMhz		21.25	21.25	21.25	21.25	21.25
Taps		8	8	8	8	8
LineTime us		66.73	53.08	30.49	19.20	11.67
FrameTime n	ns	473.5	229.3	65.9	20.7	5.6
Frames fp	5	2.11	4.36	15.18	48.23	178.51
	Medium CL	Full	4HD	2HD	HD	VGA
SensorX		10000	7680	3840	1920	640
SensorY		7096	4320	2160	1080	480
ROT clks		168	168	168	168	168
ClockMhz		30	30	30	30	30
Taps		8	8	8	8	8
LineTime us		47.27	37.60	21.60	13.60	8.27
FrameTime n	ns	335.4	162.4	46.7	14.7	4.0
Frames fp	S	2.98	6.16	21.43	68.08	252.02
	Medium CL Max	Full	4HD	2HD	HD	VGA
SensorX		10000	7680	3840	1920	640
SensorY		7096	4320	2160	1080	480
ROT clks		168	168	168	168	168
ClockMhz		42.5	42.5	42.5	42.5	42.5
Taps		8	8	8	8	8
LineTime us		33.36	26.54	15.25	9.60	5.84
FrameTime n	ns	236.8	114.7	32.9	10.4	2.8
Frames fp:	S	4.22	8.72	30.36	96.45	357.02

## Camera - Overview RMOD-71/RMOD-71 TEC



## **Camera Link Valids**

The RMOD-71/RMOD-71 TEC camera samples and processes the entire area of the image sensor. In the standard operating mode, only the active image area is output on the Camera Link as valid data. The LVAL/FVAL signals, which define the valid pixel data, can be programmed to output any part of the image, including the optical black clamping areas. FVAL start/stop are specified in lines. LVAL start is in pixels plus the overhead of the CCD vertical clocks. LVAL stop is specified as the same as LVAL start with the exception of its maximum value of 1. VALID start and stop changes are not stored on system save and must be reprogrammed each time they are needed.



Target	Index	Command	R/W	Description
0x04	0x1b	System Registers	R	0x0008 = LVAL Start 0x0009 = LVAL Stop 0x000a = FVAL Start 0x000b = FVAL Stop
0x04	0x27	System Registers	W	0x0008 = LVAL Start 0x0009 = LVAL Stop 0x000a = FVAL Start 0x000b = FVAL Stop

See the section 'Serial Communication' for the use of these commands



## **Channel Format**

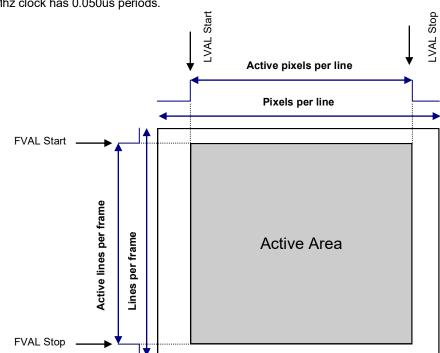
The RMOD-71/RMOD-71 TEC can generate many different raster formats. To document all possible combinations of binning, partial scan, and triggering is next to impossible; therefore, to alleviate this problem the RMOD-71/RMOD-71 TEC incorporates a set of Raster Detectors that measure the video image raster as sent to the capture device. These measured values can be used to set the capture parameters. In addition to the raster size, an Exposure Detector is included. The Exposure Detector measures the exposure of the CCD sensor in units of the master pixel clock rate. The frame CRC is used in the Built-in-test functions of the camera.

Target	Index	Command	R/W	Description
0x04	0x1b	System Registers	R	0x0000 = Pixels per line 0x0001 = Active pixels per line 0x0002 = Lines per frame 0x0003 = Active lines per frame 0x0012 = Exposure counter low word 0x0013 = Exposure counter high word 0x0014 = Frame CRC

See the section 'Serial Communication' for the use of these commands

## **NOTES**

- ► Active pixels per line = LVAL active pixel count.
- ► Active lines per frame = FVAL active line count.
- ▶ The Exposure Detector counter is a 32 bit integer. This gives a range of exposure from one clock period to over 2 seconds.
- ► Exposure is measured in pixel clock periods.
  - A 40Mhz clock has 0.025us periods.
- A 30Mhz clock has 0.033us periods.
- A 20Mhz clock has 0.050us periods.



Camera - Overview RMOD-71/RMOD-71 TEC

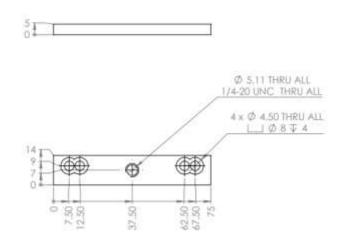


## **Drawings and CAD Models:**

The RMOD-71/RMOD-71 TEC case dimensions are available on the illunis web site under the camera and interface of interest. See the web page for the most current mechanical drawings.

CAD Models are available by request to info@illunis.com.

## **Tripod Adapter**



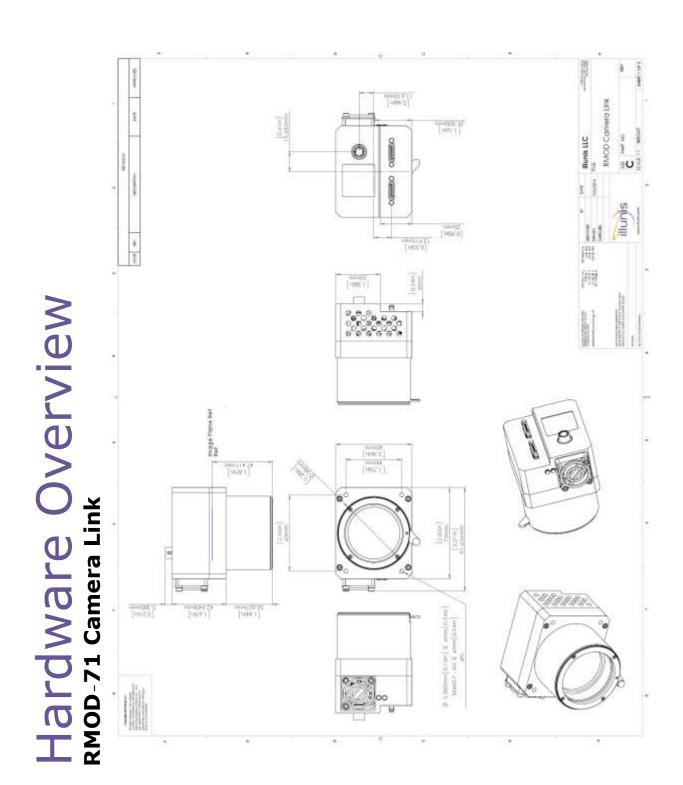
## Hardware Overview MOD-71/RMOD-71 TEC

## Lens Interfaces:

The RMOD-71/RMOD-71 TEC base configuration is Nikon F. Other mounts available by request.

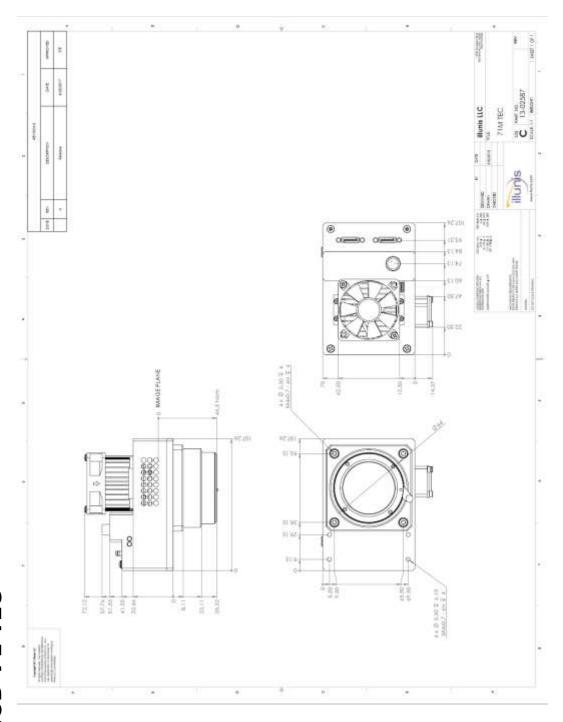


## **RMOD-71 Camera Link**





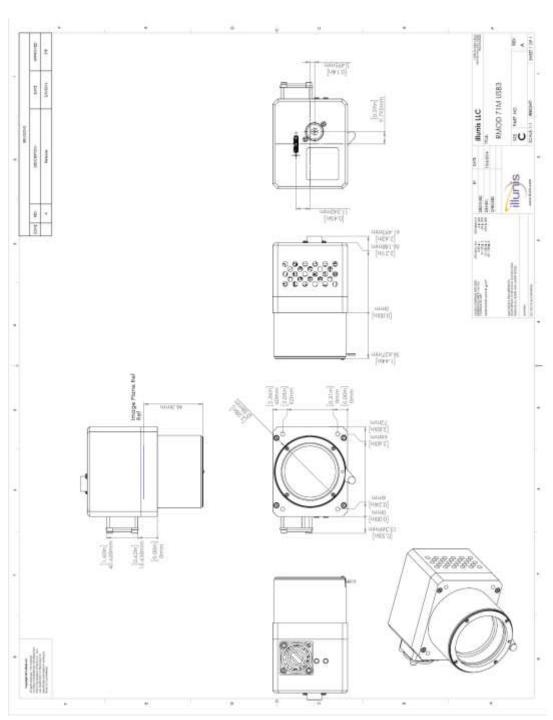
## **RMOD-71 TEC**



Hardware Overview RMOD-71 TEC



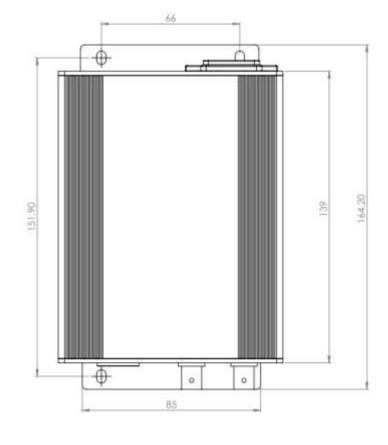
## RMOD-71 USB3

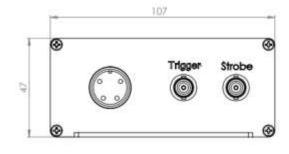


Hardware Overview RMOD-71 USB3



## **12V Universal Power Supply**







Communication

The RMOD-71/RMOD-71 TEC serial interface was developed for high reliability applications. The interface incorporates error checking and a handshake protocol, which responds with either a positive or negative acknowledge signal. The communication path from frame grabber to the RMOD-71/RMOD-71 TEC is through the Camera Link cable. The Camera Link committee has specified that devices connected must first communicate at 9600 baud, but the RMOD-71/RMOD-71 TEC has a selectable baud rate for faster communication speeds.

The RMOD-71/RMOD-71 TEC microprocessor is a flash programmable device with many features vital to the operation of the camera. Some of these features include:

- Hardware UART used for serial communications.
- A watchdog timer used to monitor communication errors and system faults.
- Onboard RAM and EEPROM for saving camera settings.
- Parallel data bus for high speed interfaces to the FPGA and NAND FLASH memories.
- Brown out detection and reset.

## SERIAL INTERFACE PROTOCOL

## Implementation

Camera communication is accomplished via asynchronous serial communication according to EIA Standard RS 232 C through the Camera Link cable.

Data rate: Full Duplex, 9600 baud.

- 1 START bit.
- 8 DATA bits The LSB (D0) is transferred first.
- 1 STOP bit.
- No parity.

## **Protocol**

The RMOD-71/RMOD-71 TEC camera is controlled through command packets. The RMOD-71/RMOD-71 TEC camera is considered a slave device and never generates data without a read request. The data packet formatting is described in detail below. *Note:* the checksum is calculated only on the 4 ascii characters comprising the Data.

## **Data Packets**

Data packets are of either 'read' or 'write' types. For example: to read the camera serial number, the packet sent to the camera would be  $\{r07000002fe\}$ . The camera would respond by issuing an acknowledge character! followed by the response  $\{r0700sssscc\}$ , where ssss is the camera serial number and cc is the checksum calculated in hex as 0x0100 - (ss (high byte hex) + ss (low byte).

Packe	t Format						
1 Char	2 Char	2 Char	2 Char	4 Char	2 Char	1 Char	1 Char
Start	Command	Target	Index	Data	Checksum	End	Ack/ Nack

## erial Communication

## Start:

Indicates the Start of the frame Size = 1 ascii character Value = 123 Decimal (ascii { )

## Command:

Command descriptor
Size = 1 ascii character

Value = 114 Decimal (ascii r ) for Read Value = 119 Decimal (ascii w ) for Write

## Target:

Command descriptor Size = 2 ascii characters

## Index:

Command descriptor Size = 2 ascii characters

## Data:

The data transferred Size = 4 ascii characters

## **Checksum of Data**

Size = 2 ascii characters - Intel-Standard - two's compliment of sum of data.

**Example 1**: Data = 2002, checksum = lower byte of (0x100 - (0x20 + 0x02)) =

0xde

**Example 2**: Data = 0000, checksum = lower byte of (0x100 - (0x00 + 0x00)) =

0x00

**Example 3**: Data = fef0, checksum = lower byte of (0x100 - (0xfe + 0xf0)) =

0x12

## End:

Indicates the End of the frame Size = 1 ascii character Value = 125 Decimal (ascii })

## Ack/Nack:

Positive Acknowledge - Negative acknowledge

Size = 1 ascii character

Ack Value = 33 Decimal (ascii!) Nack Value = 63 Decimal (ascii?)



## **COMMAND DESCRIPTIONS**

## Read Command Structure

The RMOD-71/RMOD-71 TEC camera parses the sequence byte by byte. An invalid read command, target, or index will cause the camera to issue a NACK. The Host (the user) will generate dummy data with a valid checksum then an end. The camera will respond with an ACK and re-send the command with valid data and checksum. If the Host detects an error, it will re-issue the command.

Host {r tt ii 0 0 0 0 cc}, camera issues! Camera issues {r tt ii data data data data cc} (NOTE no ACK).

## **Write Command Structure**

The RMOD-71/RMOD-71 TEC camera parses the sequence byte by byte. An invalid write command, target, index, or checksum will cause the camera to issue a NACK; otherwise, the write sequence will complete and the camera will issue an ACK after the command has been executed. The camera receives the checksum from the Host.

Host {w tt ii data data data data cc} camera issues!

## **Error Checking**

The RMOD-71/RMOD-71 TEC camera parser is character by character and will respond with an immediate NACK if any unrecognized command, target, index, or checksum occurs.

## Communication Timeouts

The RMOD-71/RMOD-71 TEC camera micro-controller uses a hardware watchdog timer that will time out if the time between bytes are longer than 500ms. When sending command frames to the camera, the host must not have significant delays between bytes sent.



## **Camera Control**

Target	Index	Description	Read	Modes
			Write	
0x04	0x00	CL Format	W	0x0000 = Camera Link Base
0.04	0.00	CETOIIIIAL	**	0x0000 = Camera Link Base 0x0001 = Camera Link Medium
				0x0002 = Camera Link Medium
				overclock
0x04	0x03	Trigger Mode Select	W	0x0000 = Free Run
			''	0x0001 = Trigger Program
				Exposure
				0x0009 = Trigger Source CL
				0x000a = Trigger Source
				External
0x5C	0x10	Window Y Start	R/W	Location in pixels, will be
				rounded to nearest 8th row.
0x5C	0x11	Window X Start	R/W	Location in pixels, will be
				rounded to nearest 16th
				column.
0x5C	0x12	Window Y Stop	R/W	Location in pixels, will be
				rounded to nearest 8th row.
0x5C	0x13	Window X Stop	R/W	Location in pixels, will be
				rounded to nearest 16th
0	000	Full Decelors	14/	column.
0x5E	0x00	Full Readout	W	Sensor 10,000x7096 output
0x5E	0x01	Pre-set Window	W	Window 1920x1080 in center of
				sensor
0x5E	0x02	Pre-set Window	W	Window 3830x2160 in center of
0 ==	0.00		100	sensor
0x5E	0x03	Pre-set Window	W	Window 640x480 in center of
0x5E	0x04	Pre-set Window	W	sensor Window 7680x4320 in center of
UXSE	0804	Pre-set willdow	VV	sensor
0x5E	0x05	Pre-set Window	W	Window 256x256 in center of
UNUL	0.00	Tre-set William	**	sensor
0x5E	0x06	Pre-set Window	W	Window 1024x1024 in center of
OXOL	ONOO	The section as well as	''	sensor
0x5E	0x07	Pre-set Window	W	Window 2048x2048 in center of
				sensor
0x5E	0x08	Pre-set Window	W	Window 4096x4096 in center of
				sensor
0x5E	0x09	Pre-set Window	W	Window 7096x7096 in center of
				sensor
0x5E	0x0A	Pre-set Window	W	Window 10000x1080 in center
				of sensor
0x5E	0x80	Set Window Readout	W	Must setup X/Y Size as below
0x5E	0x81	Set Window X Size	W	Sets width of centered window
0x5E	0x82	Set Window Y Size	W	Sets height of centered window
0x60	0x00	Low Noise Function	W	Stops internal sensors
0x60	0x01	Normal Function	W	Restores all functionality

## Serial Commands RMOD-71/RMOD-71 TEC



## Serial Commands RMOD-71/RMOD-71 TEC

Target	Index	Description	Read Write	Modes
0x04	0x06	Test Pattern	W	0x0000 = Normal Video 0x0001 = FPGA Input Test Pattern 0x0002 = Output Test Pattern
0x04	0x07	Camera Temperature	R	
0x04	0x09	Baud Rate	W	0x0000 = 9600 0x0001 = 19200 0x0002 = 38400 0x0003 = 57600 0x0004 = 115200
0x04	0xD2	Set Camera Link Boot Baud Rate (Requires reboot)	R/W	0x0000 = 9600 0x0001 = 19200 0x0002 = 38400 0x0003 = 57600 0x0004 = 115200
0x04	0x1c	Defect Correction (DC)	W	0x0000 = Load/Enable Pixel DC 0x0001 = Load/Enable Column DC 0x000A = Load/Enable Row DC 0x0005 = Disable Pixel DC 0x0004 = Disable Column DC 0x000B = Disable Row DC
0x04	0xA0	Hot Pixel Corrector	R/W	0x0000 = Disabled 0x0001 = Enabled
0x04	0xA1	Hot Pixel Correction Type	R/W	0x0000 = Color Bayer 0x0001 = Monochrome
0x04	0xA2	Hot Pixel Threshold	R/W	Threshold in dn
0x04	0xA3	# Hot pixels corrected	R	In # pixels * 256 ( 0x0001 = 256 cor.)
0x04	0x24	Digital Gain	R/W	In units of 1/4096 gain Example 0x1000 = 1X gain 0xC800 = 12.5X gain
0x04	0x30	Digital Offset	R/W	Signed value 0x0100 = offset of +256 0xFEFF = offset of -255
0x04	0x38	Digital Gain/Offset Ena- ble	R/W	1 = enable, 0 = disable
0x04	0x0d	Bit Depth	W	0x0000 = 12 bit mode 0x0001 = 10 bit mode 0x0002 = 8 bit mode 0x0003 = Enable bottom 8 bits 0x0004 = Disable bottom 8 bits
0x04	0x0e	Strobe Control	W	0x0000 = negative strobe polarity 0x0001 = positive strobe polarity



Target	Index	Description	Read Write	Modes
0x04	0x1b	System Registers	R	0x0000 = Read Pixels/Line 0x0001 = Read Active Pixels/Line 0x0002 = Read Lines per frame 0x0003 = Read Active Lines per frame 0x0008 = LVAL Start 0x0009 = Stop 0x000a = FVAL Start 0x000b = Stop 0x000d = FPGA Revision 0x0012 = Read Exposure value low 0x0013 = Read Exposure value high 0x0014 = Read CRC
0x04	0xFF	Base Reset	W	Resets camera mode to: free run no LUT, no PDC, no digital gain or offset, no test pattern, reset the LVAL and FVAL defaults. enable strobe in Free Run Mode
0x04	0xD8	Checksum Mode (Cleared on re- start)	W	0x0000 = Checksum of data 0x0001 = Checksum of command and data

## **Exposure Type**

The exposure type is either Free Run Mode or Trigger Mode. In Free Run Mode, the camera outputs continuous images in a rolling shutter mode. In Trigger Mode, the camera receives the trigger, erases the pixels, exposes the image, and then reads it out.

Target	Index	Description	Read Write	Modes
0x04	0x03	0x0000	W	Set Free Run Mode
0x04	0x03	0x0001	W	Set Trigger Mode
0x5C	0x01	# of frames	W	Set number frames read in Trigger Mode
0x04	0x03	0x0009	W	Set Trigger Source Camera Link
0x04	0x03	0x000A	W	Set Trigger Source power cable (external)



## **Exposure Control**

The exposure time is set in either milliseconds or microseconds. The resolution of the exposure is in horizontal line times. Two commands are provided for calculating the Free Run time from a specified time variable (milliseconds or microseconds). The closest available time is selected and set in the internal time variable.

Target	Index	Description	Read Write	Modes
0x02	0x02	Set Exposure ms	W	Set Exposure time in milliseconds
0x02	0x03	Set Exposure us	W	Set Exposure time in us
0x02	0x02	Get Exposure ms	R	Return actual time in milliseconds
0x02	0x03	Get Exposure us	R	Return actual time in us (0xFFFF = to large).
0x02	0x05	Soft Trigger Time	W	Software trigger in ms 1 - 65535
0x02	0x06	Set Trigger high	W	Sets internal trigger high (active)
0x02	0x07	Set Trigger low	W	Sets internal trigger low

## **Bit Depth**

Target	Index	Description	Read Write	Modes
0x04	0x0d	Output Bit Depth	W	0x0000 = 12 bit mode 0x0001 = 10 bit mode 0x0002 = 8 bit mode 0x0003 = Bottom 8 bits (as Msb)

## **Strobe Signal**

The RMOD-71/RMOD-71 TEC Strobe Signal is a 3.3V LVTTL signal that is active when the sensor is triggered and exposing an image. The Strobe Signal is useful for analyzing and optimizing imaging applications. The strobe can be used to activate an illumination source. If used in this fashion, the Strobe Signal cannot drive significant current and should be buffered.

Target	Index	Description	Read Write	Modes
0x04	0x0e	Strobe Control	Write	0x0000 = negative strobe polarity 0x0001 = positive strobe polarity



## **Memory Management**

Target	Index	Description	Read Write	Modes
0x03	0x00	Save Camera State	W	Wait for acknowledge before removing power.
0x03	0x00	Save Camera State in Background	W	Returns immediately, operates in background.
0x03	0x02	Restore Factory State	W	Wait for acknowledge before removing power.
0x03	0x03	Copy User to Factory	W	Wait for acknowledge before removing power.
0x03	0x09	Reset EEPROM CRC	W	
0x03	0x0d	EEPROM Word	R/W	0xaaaa = address Read address directly Write data word to 030c then write 030d with address.
0x03	0x0e	EEPROM Byte	R/W	0xaaaa - address Read address directly Write data byte to 030c then write 030e with address.

## **System and Status**

Target	Index	Description	Read Write	Modes
0x05	0x00	Camera Mode/Status	R	0x0000 = read mode register 1 0x0001 = read mode register 2 0x0002 = read mode register 3 0x0003 = read mode register 4 0x0005 = read status register 1 0x0006 = read status register 2
0x07	0x00	Camera Parameters	R	0x0000 = Camera Model 0x0001 = Camera Hardware Rev 0x0002 = Camera Serial Number 0x0003 = Micro-firmware Rev 0x0004 = FPGA Major Revision 0x0005 = Sensor Serial Number 0x0006 = Clock Rate 0x0007 = FPGA Sub/Minor Revision 0x0008 = Micro Sub/Minor Revision 0x0009 = Camera Type 0x000A = FPGA Clk Speed



## **Times**

Target	Index	Description	Read Write	Modes
0x5E	0xD0	Get Line Time	R	Returns line time in us
0x5E	0xD1	Get Frame Time	R	Returns frame time in us
0x5E	0xD2	Get Frame Time	R	Returns frame time in ms

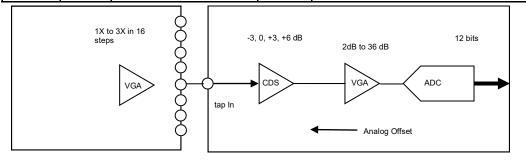
## **Gains and Offsets**

The RMOD-71/RMOD-71 TEC camera has 8 individual analog taps. Each tap is processed by an analog front end (AFE). Each AFE has two gain stages and a 12 bit analog to digital converter. The CMOS Sensor has an additional internal gain stage. This gain is normally set to minimum to reduce system noise.

ADC Gain can be calculated with the following equation.

Gain (dB) = 5.1 + (0.0359 \* code)Where code is the range of 0 to 1023.

Target	Index	Description	Read Write	Modes
0x00	0x00	ADC Gain	W	0x0000-0x3FF Writes all 8 ADC's with gain value
0x00	0x80	Black Level	R/W	Higher value is a darker image
0x00	0x44	Pre (CDS) Gain	R/W	Sets all 8 ADC's
0x5C	0x08	CHR71M Gain	R/W	0x0000-0x000F Write sensor gain





## Mode and Status Register Bit Assignments

```
typedef struct
                                                          // Status Register 1
         unsigned int
         WDT_ENABLED:
                                                          //1 = WDT enabled BIT 0
         XIL_CONFIG:
                                                          //1 = Xilinx config failed
         BROWNOUT:
                                                          //1 = Brownout reset
                                                          //1 = Normal power up reset
         PWR_NORMAL:
         WDT_RESET:
                                                          //1 = WDT timeout
                                                          //1 = UART ERROR
         UART_ERR:
         VSYNC_TIMEOUT:
                                                          //1 = VSYNC timeout received
         DCM_TIMEOUT:
                                                          //1 = DCM timeout
         HW_DCM_LOCKED:
                                                          //1 = DCM Locked
         S1_B9:
                                      1,
         VAFE_ERR:
                                                          //1 = AFE 1.8V error
                                      1,
         V3_ERR:
                                                          //1 = 3V Switcher error
                                                          //1 = 12V input error
//1 = 5V Switcher error
         VIN_ERR:
         V5_ERR:
                                                          //1 = FPGA 1.2 or 2.5V Error
         VF_ERR:
         FACT_CRC_ERR:
                                                          //1 =
    }status_register1_t;
typedef struct
                                                          // Status Register 2
         unsigned int
ADC_VID1_SAVE_FAIL:
                                                          //1 = ADC 1 state save fail
         ADC_VID2_SAVE_FAIL:
                                                          //1 = ADC 2 state save fail
         ADC_VID3_SAVE_FAIL:
                                                          //1 = ADC 3 state save fail
         ADC_VID4_SAVE_FAIL:
                                                          //1 = ADC 4 state save fail
         PIO_SAVE_FAIL:
                                                          //1 = PIO state save fail
         IBIT1_COMP:
                                                          //1 = IBIT1 Complete
         S2 B6:
                                                          //
                                      1.
         S2_B7:
                                                          //
         S2_B8:
         ADC_VID5_SAVE_FAIL:
                                                          //1 = ADC 5 state save fail
         ADC_VID6_SAVE_FAIL:
                                                          //1 = ADC 6 state save fail
         ADC_VID7_SAVE_FAIL: 1
                                                         //1 = ADC 7 state save fail
         ADC VID8 SAVE FAIL:
                                                          //1 = ADC 8 state save fail
                                      1,
         S2_NAD:
                                                          //1 =
         AE ERR:
                                                          //1 =
         USER_CRC_ERR:
                                                          //1 =
    }status_register2_t;
```



typedef struct

```
unsigned int
                                                                                               // 1 = free run mode 0 = trigger
// 1 = positive strobe polarity
                                free run:
                                strobe_polarity:
                                trigger_polarity:
                                                                                                // 1 = positive trigger polarity
                                trigger_source:
                                                                      1,
                                                                                                // 0 = CL 1 = External
                                twelve_bit:
                                                                                               // 1 = 12 bit readout
// 1 = 10 bit readout
                                ten_bit:
eight_bit:
                                                                                                // 1 = 8 bit readout
                                bottom_8:
                                                                                                // 1 = bottom 8 bit readout
                                input_TP:
                                                                                                // 1 = input test pattern enabled
                                                                                               // 1 = output test pattern enabled
//1 = Medium mode readout (4 tap path)
                                output_TP:
                                Med mode readout:
                                Base_mode_readout:
                                                                                               //1 = Base mode readout (2 tap path)
                                full readout:
                                                                                               // 1 = 10,000 x 7096 0 = window
                                osc_42mhz:
                                Osc_30mhz:
                                Osc div2:
                        } mode_register1_t;
                   typedef struct
                                                                                                // Mode Register 2 = Defect and image correction
                                unsigned int
                                DGO_enabled:
                                                                      1,
                                                                                               // Master Digital gain and offset
                                LUT_enabled:
LUT_LOADED:
                                                                      1,
                                                                                                //1 = LUT Loaded from EEPROM
                                HISTO_EQ:
                                                                                                //1 = Histogram equalization enabled
                                CDC_EN:
                                                                                                //1 = Column Defect Corrector Enabled
                                PDC_EN:
RDC EN:
                                                                                                //1 = Pixel Defect Corrector Enabled
                                                                                                //1 = Row Defect Corrector Enabled
                                M2_B7:
                                CGT_enabled:
CGT_LOADED:
                                                                      1,
                                                                                               //1 = Column Gain Table Loaded from EEPROM
                                COT_enabled:
                                                                      1,
1,
                                COT_LOADED:
                                                                                                //1 = Column Offset Table Loaded from EEPROM
                                M2_BC:
M2_BD:
                                                                      1.
                                M2_BE:
                                M2 BF:
                                                                                                //
                        } mode register2 t:
                   typedef struct
                                                                                                // Mode Register 3 = Detectors and AE
                                \quad \hbox{unsigned int} \quad
al Command
                                AE:
                                                                                                //1 = auto exposure enabled
                                                                                               //1 =
//1 = AE in exposure mode
                                AE_gain:
                                                                      1,
                                AE_exposure:
                                AE_iris:
                                                                                                //1 = AE within hysteresis
                                AE hysteresis:
                                                                                                //1 = AE at max gain - need more light BIT 0 PRESERVE
                                AE_CLOSE_IRIS:
                                                                                                //1 = AE at min exposure - need less light PRESERVE
                                OSD_CP:
                                                                      1,
                                OSD_TEXT:
OSD_2X:
                                                                      1,
                                                                                               //1 = OSD text display enabled PRESERVE //1 = 2X text box BIT0
                                                                      1,
                                OSD_COLOR_MODE:
                                                                                                //1 = OSD Color Mode
                                OSD_LP:
                                                                      1,
                                OSD_SCR:
                                                                      4;
                                                                                               //1 = OSD Screen type ( bits)
                        } mode_register3_t;
                   typedef struct
                                                                                               // Mode Register 4 = Communication and misc.
                                {
                                unsigned int
                                AE_WINDOW:
                                                                                                //1 = Show AE Window
                                AF_WINDOW:
AF_DATA:
                                                                                               //1 = Show AF Window
//1 = Show AF Data
                                                                                                //1 = Show AF Data Full Screen
                                AF_FULL:
                                                                      1,
                                BAUD_9600:
BAUD_19200:
                                                                      1.
                                                                                               //1 = 9600 baud
//1 = 19200 baud
                                                                                               //1 = 38400 baud
//1 = 57600 baud
                                BAUD_38400:
                                BAUD 57600:
                                                                      1.
                                BAUD_115200:
                                                                                                //1 = 115200 baud
                                HotPixelEnabled
HotPixelMono
                                M4_BB:
                                                                                               //
                                TriggeredFlash:
                                TriggeredShutter:
                                CLK_SEL:
PowerDown:
                        } mode_register4_t;
```

// Mode Register 1 = READOUT



## **Lookup Tables**

## **Preset LUTs**

Target

Index

The camera has some predefined look up tables that may be loaded quickly into the camera with one camera command. The tables and commands are listed below. Once these tables are loaded, the LUT is automatically enabled.

## Loading LUT for Use and/or Storage

LUT tables can be created on a PC and loaded into a camera. The illunis Camera Control Application has a table create feature, a load table into camera RAM and EEPROM (storage), and a load table into camera RAM.

To load tables into the camera or enable a stored table in the camera, the Lut mode register needs to be set to the desire function.

Read

Modes

## Write 0x04 0x31 **Preset Tables** W 0001 = Linear LUT I Commands 'RMOD-71 TEC 0002 = Invert LUT 0003 = Knee LUT 0004 = Gamma 0.45 LUT 0005 = Gamma 0.60 LUT 0006 = Gamma 0.70 LUT 0007 = Gamma 0.80 LUT 0x04 W 0x46 Load Gamma XXXX when XXXX > 0 and XXXX <= 100. Table Gamma value is xxxx/100 0x04 W 0x45 Lut mode 0000 = Load LUT From File on PC, No EEPROM Save 0001 = Load LUT From File on PC, EEPROM Save 0002 = Load LUT from EEPROM

Description



## **Communication BAUD Rates**

The Camera Link 1.0 specification allows for serial communication at 9600 baud only. The 1.1 specification (and later) provides for faster rates.

The RMOD-71/RMOD-71 TEC camera allows for the setting of the baud rate to one of five rates. This setting can be made for only the current power cycle or for the boot cycle.

The RMOD-71/RMOD-71 TEC camera allows the user the option of saving the communication speed in the camera EEPROM. This can cause communication with the camera to be lost if the command is not used carefully. *Note:* only one of the baud rates will be used so that if communication is lost it can be restored by trying the other baud rates.

Once the EEPROM baud rate is set, the camera must be re-powered to set the rate.

Target	Index	Description	Read Write	Modes
0x04	0x09	Set Current Baud Rate	W	0x0000 = 9600 0x0001 = 19200 0x0002 = 38400 0x0003 = 57600 0x0004 = 115200
0x04	0xD2	Set Camera Link Boot Baud Rate (Requires reboot)	R/W	0x0000 = 9600 0x0001 = 19200 0x0002 = 38400 0x0003 = 57600 0x0004 = 115200
0x04	0xD3	External Serial Boot Baud Rate (Requires reboot)	R/W	0x0000 = 9600 0x0001 = 19200 0x0002 = 38400 0x0003 = 57600 0x0004 = 115200
0x04	0xD0	Power Up	W	Resets camera and powers up circuits



## **Windowed Readout**

The Windowed Readout command changes the raster readout of the CHR71M sensor. Window sizes are rounded to 16 pixels horizontally and 8 pixels vertically.

Target	Index	Description	Read Write	Modes
0x5C	0x10	Window Y Start	R/W	Location in pixels, will be rounded to nearest 8th row.
0x5C	0x11	Window X Start	R/W	Location in pixels, will be rounded to nearest 16th column.
0x5C	0x12	Window Y Stop	R/W	Location in pixels, will be rounded to nearest 8th row.
0x5C	0x13	Window X Stop	R/W	Location in pixels, will be rounded to nearest 16th column.
0x5E	0x00	Full Readout	W	Sensor 10,000x7096 output
0x5E	0x01	Pre-set Window	W	Window 1920x1080 in center of sensor
0x5E	0x02	Pre-set Window	W	Window 3830x2160 in center of sensor
0x5E	0x03	Pre-set Window	W	Window 640x480 in center of sensor
0x5E	0x04	Pre-set Window	W	Window 7680x4320 in center of sensor
0x5E	0x05	Pre-set Window	W	Window 256x256 in center of sensor
0x5E	0x06	Pre-set Window	W	Window 1024x1024 in center of sensor
0x5E	0x07	Pre-set Window	W	Window 2048x2048 in center of sensor
0x5E	0x08	Pre-set Window	W	Window 4096x4096 in center of sensor
0x5E	0x09	Pre-set Window	W	Window 7096x7096 in center of sensor
0x5E	0x0A	Pre-set Window	W	Window 10000x1080 in center of sensor
0x5E	0x80	Set Window Readout	W	Must setup X/Y size as below
0x5E	0x81	Set Window X size	W	Sets width of centered window
0x5E	0x82	Set Window Y size	W	Sets height of centered window

## Serial Commands RMOD-71/RMOD-7



## Backup/Restore

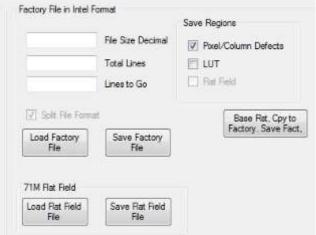
The RMOD-71/RMOD-71 TEC camera control program provides features for saving and restoring the camera state. Please save the camera state before changing the default state of the camera.

State data can be saved and restored (from files) for the following:

- Camera state with optional defect tables.
- 2) Flat Field Calibration data.

**Note:** The camera control program may change the communication rate during this operation.





## erial Commands

## Camera Save/Restore

**Save Factory File**: Saves the camera state to a file for future restores. Options include defect table.

**Load Factory File**: Restores camera state from a file. The camera state is saved in manufacturing and can be emailed to the user.

**Save FFC File**: Saves the camera Flat Field Correction (FFC) to a file for future restores.

Load FFC File: Restores camera FFC from a file.



## Overview

The RMOD-71/RMOD-71 TEC sensor operates with a rolling electronic shutter and integrates an internal signal sequencer for image readout.

The internal modes do not natively support the use of a trigger pulse width exposure control.

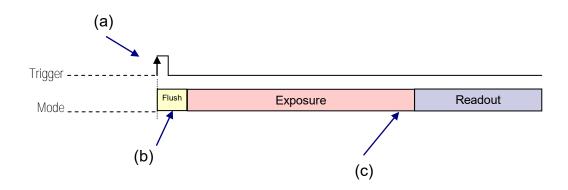
illunis has bypassed the limitations of the CHR70M sensor by designing a custom sensor sequencer that controls the sensor at a low level and provides new functionality as describe here:

A sensor flush mode: All lines of the sensor are erased in sequence. (< 1.5ms)

An externally controlled exposure: Allows for exposure to be pulse width controlled.

In addition, a programmable strobe output is provided for control of external synchronization to lighting. The following diagram shows the basic operation of the sequenced exposure:

- (a) Trigger is asserted, flush begins.
- (b) Each of the 7096 lines are reset, in order. Image exposure begins.
- (c) Exposure of the sensor ends, readout begins.



**Externally Sequenced Exposure** 



# ulse Width Mode

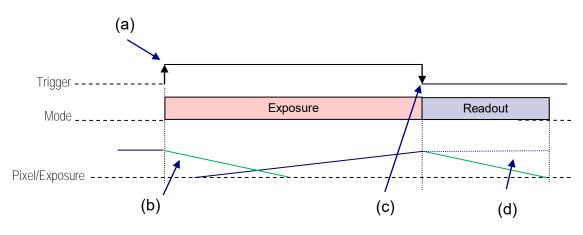
## **Pulse Width Exposure Control**

The external sequencing of the CHR70M sensor allows for a true pulse width controlled exposure. In this mode, a trigger rising edge begins the exposure sequence and the trigger falling edge ends the exposure, and then begins the readout sequence.

Some details of the operation:

- (a) Trigger is asserted, flush begins.
- (b) Each of the 7096 lines are reset, in order. Image integration begins.
- (c) Trigger is de-asserted, exposure of the sensor ends, readout begins.
- (d) During readout pixels are integrating.

There are two flush modes, a standard line time flush mode, that will result in uniform exposed images, and a fast flush mode for specialized applications.



Externally Sequenced Pulse Width Exposure



# se Width Mode

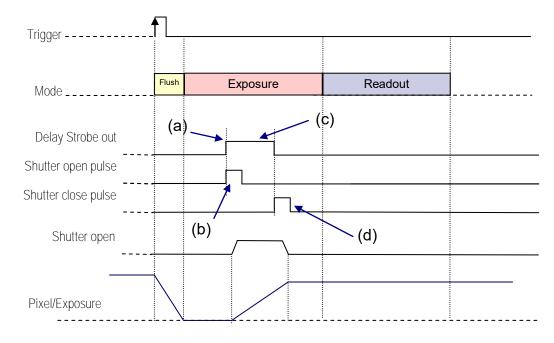
## **Triggered Mechanical Shutter**

A mechanical shutter can be used in the external sequencing mode to provide a true global shutter operation of the CHR70M. In this mode the shutter controls the integration of the image. Flush, exposure and readout all work the same as before. The strobe output as well as the shutter open and close pulses are all programmable in delay and duration.

Some details of the operation:

- (a) A programmable delay for both the strobe and shutter sequence is provided.
- (b) The shutter open pulse is programmable in duration (usually set at the factory).
- (c) A shutter/strobe delay is programmable.
- (d) The shutter close pulse is programmable in duration (usually set at the factory). (Note: image integration ends at the close of the mechanical shutter).

This mode requires special hardware consisting of a mechanical shutter, lens mount and electronics. The fast flush mode is used in this application.



**Triggered Mechanical Shutter Exposure Overview** 



ulse Width Mode

## Triggered Pulse Width Mechanical Shutter Continued

When using the mechanical shutter in pulse width exposure mode the shutter timing is as follows.

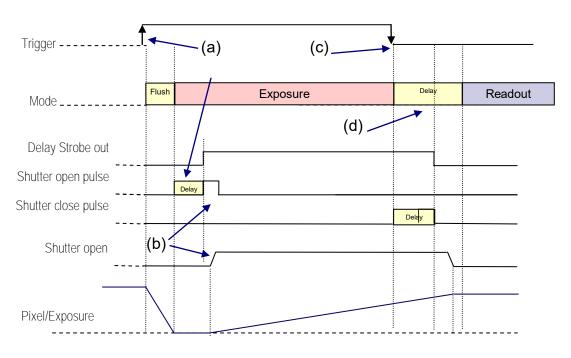
Some details of the operation:

- (a) On trigger assert a shutter open sequence is initiated.
- A programmable delay for both the strobe and shutter sequence is provided.
- (b) The shutter open pulse is programmable in duration (usually set at the factory).

Depending on the shutter mechanics, the timing of the shutter open is delayed.

- (c) On trigger de-assert a shutter close sequence is initiated.
- (d) A delay from trigger de-assert to readout is provided to allow the mechanical shutter to close completely.

This mode requires special hardware consisting of a mechanical shutter, lens mount and electronics. The fast flush mode is used in this application.



**Triggered Pulse Width Mechanical Shutter Exposure Overview** 

RMOD-71/RMOD-71 TEC Operations ManualCopyright illunis, LLC 10/2/2019

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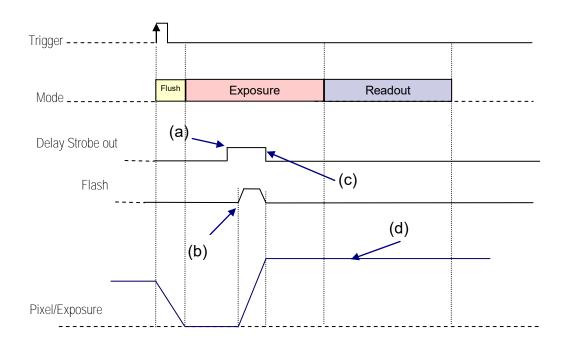
## **Triggered Flash Exposure**

A Flash exposure can be used in the external sequencing mode to provide a true global shutter operation of the CHR70M. In this mode the flash controls the integration of the image. Flush, exposure and readout all work the same as before. The sensor must operate and readout in complete darkness for the flash operation to function correctly.

Some details of the operation:

- (a) A programmable delay for the strobe is provided to sync the flash.
- (b) The flash illumination determines the exposure.
- (c) The strobe duration is programmable.
- (d) The readout of the image is in the dark so integration is constant. (Note: image integration ends at the end of the flash).

This mode requires special hardware consisting of a external flash control and flash hardware. The fast flush mode is used in this application.



Triggered Flash Exposure Overview

## **Triggered Flash Exposure Continued**

The flash timing is as follows:

- (a) Assert trigger
- (b) Camera performs fast flush of sensor, flash is delayed until flush complete.

The flush time for each readout mode is:

Base mode 21.25Mhz: 2.34ms
Medium mode 30Mhz: 1.65ms
Medium mode 42.5Mhz: 1.17ms

- (c) Exposure begins
- (d) Flash is asserted from camera strobe output
- (e) Programmed exposure ends and image is readout

The time for each readout mode is:

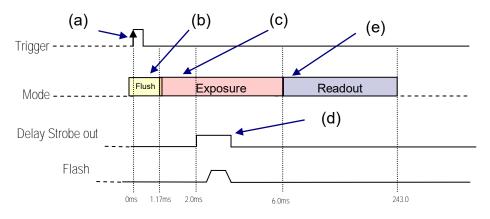
Base mode 21.25Mhz: 474ms
Medium mode 30Mhz: 333ms
Medium mode 42.5Mhz: 237ms

## Example:

Set the readout mode to medium 40Mhz	{w04000002fe}
Set the sequenced exposure mode active	{w02430001ff}
Set the programmed exposure mode active	{w04030001ff}
Set the exposure to 15,000 us (15ms)	{w02033A982e}
Set the fast flush mode	{w02220001ff}
Set the ms tick register to 42500	{w0216a60456}
Set the strobe delay to 2ms	{w02110002fe}
Set the strobe pulse width to 2ms	{w02120002fe}
Set the strobe delay enable	{w02100001ff}
Begin operation	

Or use Triggered Sequenced Flash

{w04030012ee}



**Triggered Pulse Width Shutter Exposure Details** 

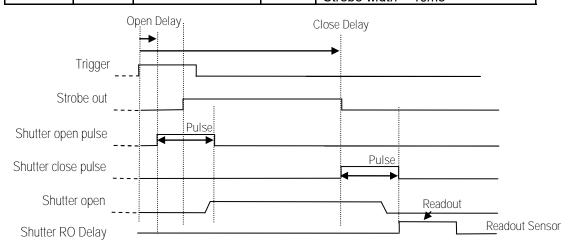


## **Sequencer Mode Commands**

These functions set the parameters associated with the external triggered modes and shutter/flash strobe output.

Mode	
Width	
Pulse	TEC
iggered	-71/RMOD-71
	RMOD.

Target	Index	Description	Read Write	Modes
0x02	0x43	0=disable, 1=enable	R/W	Set External Programmed Exposure
0x04	0x03	1=enable	W	Set External Programmed Mode
0x04	0x03	2=enable	W	Set External Pulse Width Mode
0x02	0x10	0=normal, 1=delay	R/W	Set Strobe output mode
0x02	0x11	Data = ms delay	R/W	Set Strobe Delay
0x02	0x12	Data = ms dura- tion	R/W	Set Strobe Duration
0x02	0x14	Data = ms dura- tion	R/W	Set Shutter Duration (Pulse Width)
0x02	0x17	Data = ms delay	R/W	Set Shutter Open Delay
0x02	0x18	Data = ms delay	R/W	Set Shutter Close Delay
0x02	0x19	Data = ms delay	R/W	Readout delay to allow the shutter to close.
0x02	0x20	0=disable, 1=enable	R/W	Trigger echo on strobe out line.
0x02	0X21	0=normal, 1=Manual	R/W	Manual Strobe Control
0x02	0x22	0=normal, 1=fast	R/W	Fast flush during Trigger Pulse Width Mode
0x04	0x03	0x0012	W	Sequenced Triggered Flash Exposure = 15ms Strobe delay = 2/3/3ms (base, med30,med40) Strobe width = 10ms



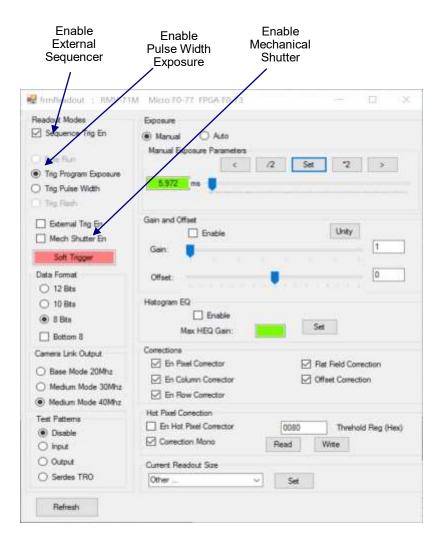


## Camera Control Application Support

The illunis control application has been extended to provide control of these new features. The most important feature is the selection between internal and external sequencing modes (Sequence Trig En). In the external mode, pulse width exposure control is enabled.

Strobe and shutter controls are also provided for flash and mechanical shutter modes.

The exposure and readout dialog is shown below.



se Width Mode



Strobe and mechanical shutter operation is controlled from the 'Trigger Strobe' dialog. The 'ms Tick register' controls the timing of the pulses by dividing the pixel clock to generate a ms clock. For each mode set it to the following:

Base mode 21.25Mhz: 21250

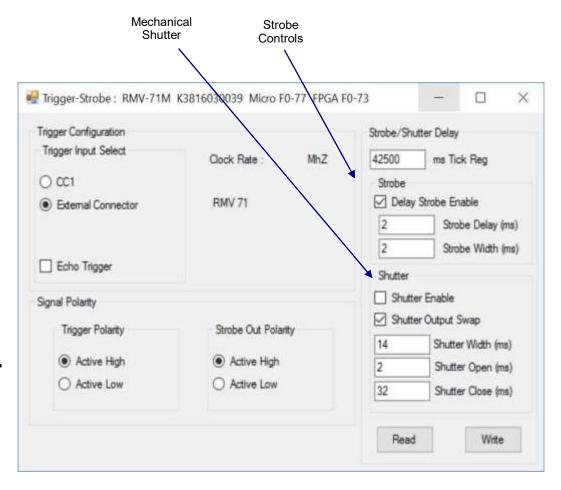
Medium mode 30Mhz: 33333

Medium mode 42.5Mhz: 42500

Note that the strobe can be set to echo the incoming trigger for debugging purposes.

Other debug modes are provided (Signal output on strobe signal)

Strobe debug off: {wFE0f000000}
Flush (fast) timing: {wFE0F00B749}
Expose (fast) timing: {wFE0F00c739}
Readout (fast) timing: {wFE0F00D729}



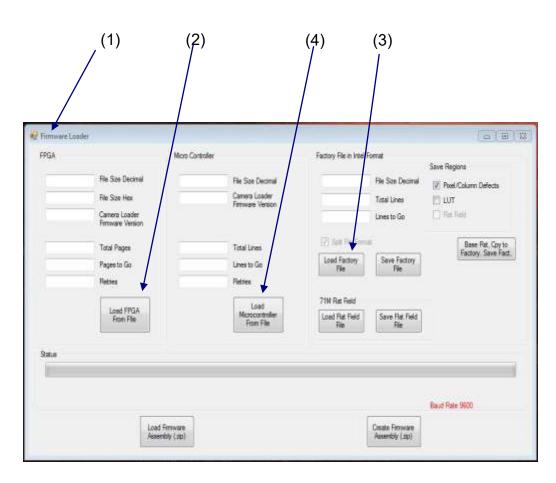
Pulse Width Mode



### **Firmware Update**

RMOD-71/RMOD-71 TEC firmware is updated using the illunis control application by following these steps:

- (1) Update to the recommended control application.
- (2) Update the FPGA file with the \*.bin file and the firmware loader dialog
- (3) Update the EEPROM configuration with the \*.fca file
- (4) Update the microprocessor with the \*.hex file
- (5) Repower the camera, reopen the control app, reconfigure the camera settings.
- (6) If needed recalibrate the black offset and bright FFC.



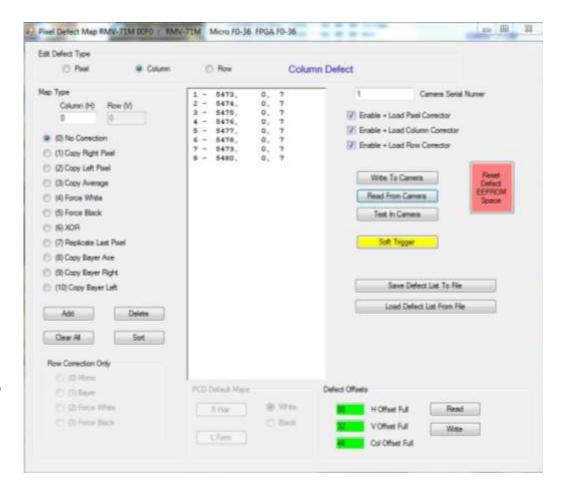


# w and Column Defects

### Pixel, Column and Row Defects

Defect correction is used to "map out " defective pixels in the camera and substitute synthesized pixel values. The illunis Camera Control Application provides a defect editor to simplify the editing of defect mapping.

Target	Index	Description	Read Write	Modes
0x04	0x1c	Defect Correction (DC)	Write	0x0000 = Load/Enable Pixel DC 0x0001 = Load/Enable Column DC 0x000A = Load/Enable Row DC 0x0005 = Disable Pixel DC 0x0004 = Disable Column DC 0x000B = Disable Row DC





### **Black Offset and Flat Field Correction**

The CHR71M sensor used in the RMOD-71/RMOD-71 TEC camera requires image processing for optimal operation. The sensor incorporates a dark field Offset Correction on the chip. The Offset Correction will correct the 16 column analog offsets through digital to analog converters. The sensor also requires a Digital Gain for each of the 10,000 columns. The Column Gain corrects non-uniformity of the sensor analog paths. The following image shows the effects of Offset and Gain Correction.

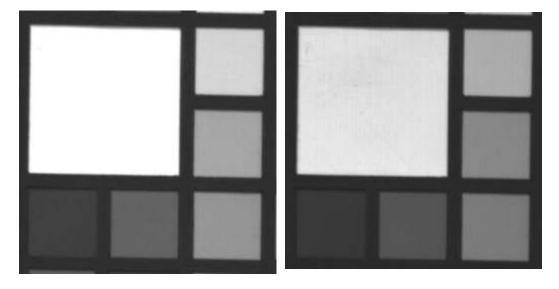


Image with (left) and without (right) Column Gain Correction

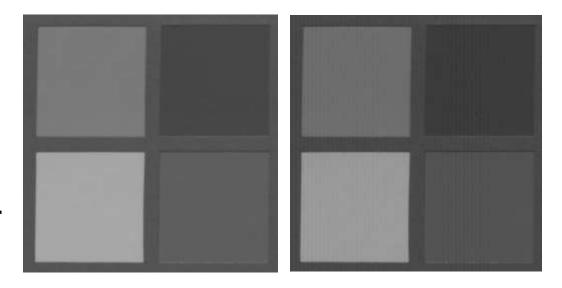


Image with (left) and without (right) 16 Column Offset Correction



### **Black Offset and Flat Field Correction**

**Warning:** Changing the Flat Field Correction (FFC) tables will impact the operation of the camera. Before resetting the FFC, make sure the current FFC table is saved to a file. Files can be saved and reloaded using the Camera Control Application.

The image processing features of the RMOD-71/RMOD-71 TEC camera can be easily setup by using the following procedure:

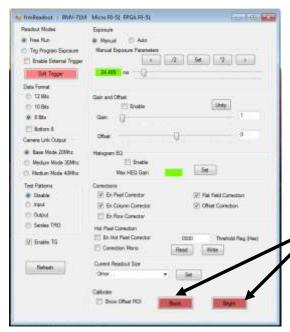
**For 16 Column Offset Correction:** Use the lens cap or light blocking device. This test is performed in the dark; therefore, no special equipment is needed. Only 16 words of data are stored for this correction.

**For Column Gain Correction:** Use the flat field light source. This can be as simple as a white balance lens cap and a flat background or "s" complex as a programmable light source. The flatter the field presented to the sensor the better the correction will be. The RMOD-71/RMOD-71 TEC processes the flat field in two passes, one for the even numbered columns and one for the odd numbered columns. A total of 10,000 Column Gains are calculated and saved in the EEPROM of the camera. This process may take over a minute to complete.

For optimum performance, the Offset and Gain calculations should be calculated under the conditions that the camera is used and should include the following parameters:

- Operating temperature.
- Exposure.
- Readout mode and pixel clock speed.

It is recommended to perform the Black (offset) calibration first followed by the Bright (gain) calibration.



### **Exposure and Readout Dialog**

The exposure and readout dialog contains the controls for calibrating the Offset (dark) and Column Gain (bright). The Column Gain (FF) can be enabled along with the defect corrections for pixel, row, and columns.

**NOTE**: Extend the dialog box by dragging the bottom to see the controls

Flat Field Correction RMOD-71/RMOD-71 TEC



### **Black Offset and Flat Field Correction**

Column Gain Correction (Bright)

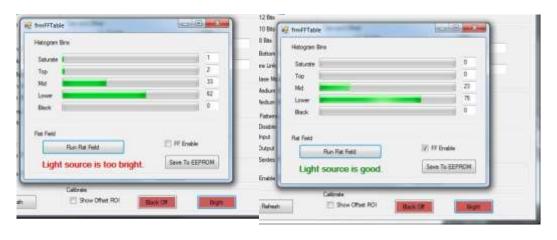
The Bright (column gain) calibration will present a dialog box with the 5 point histogram. The top two bar graphs represent the saturated pixels as well as the top 10% pixel counts. These two values must be zero to continue with the calibration.

**Note:** The image must be uniform (flat) to obtain correct calibration.

- Adjust the intensity of the light source so that the adjustment dialog reports the light source as "good".
- Press the "Run Flat Field" button. The calibration will complete and the Column Gains will be activated in the camera (but not saved to EEPROM).
- Examine the calibration result. If acceptable, press the "Save To EEPROM" button to save the results.

**Note:** Currently only one calibration can be saved to EEPROM.

**Note:** Saving to EEPROM can take several minutes. Watch the On Screen Display (OSD) frame count as it will restart once the save is complete. DO NOT POWER DOWN THE CAMERA DURING EEPROM WRITE.



lat Field Correction



### Offset Calibration

### Offset Correction (Black)

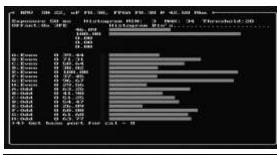
The Black (offset) calibration will present a dialog box asking the lens to be covered in order to obtain a completely dark image.

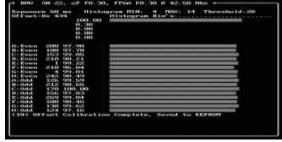
Clicking OK will start the Offset Calibration and an on-screen display will be activated to show the progress.

A series of bar graphs will display the current offset values and relative brightness. As the calibration proceeds the values will converge. Once an acceptable solution is found, the calibration data will be saved to EEPROM and the results will display in the OSD.

The lens cap may now be removed and the camera used.









qualization

### **Histogram Equalization**

The Histogram Equalization (HEQ) function is provided for applications that need to dynamically adjust the incoming image data to a full output range. This is typically needed in surveillance applications where image data is viewed but not measured.

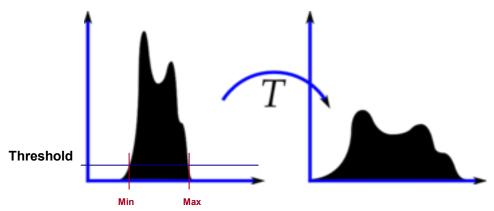
The Histogram Detector calculates a 512 point histogram, based on the image data within the brightness (AED) detector. The histogram is then measured using a threshold to determine its minimum and maximum values.

The minimum value is used to set the Master Digital Offset register, which shifts the histogram to restore the black level. The maximum value is used to calculate the gain needed to equalize the histogram to full range. This value is set in the Master Digital Gain register.

The Equalized Histogram is fit to 90% of the range to compensate for data lost by thresholding. The histogram endpoints are not considered in the equalization so that saturated pixels do not skew the equalization.

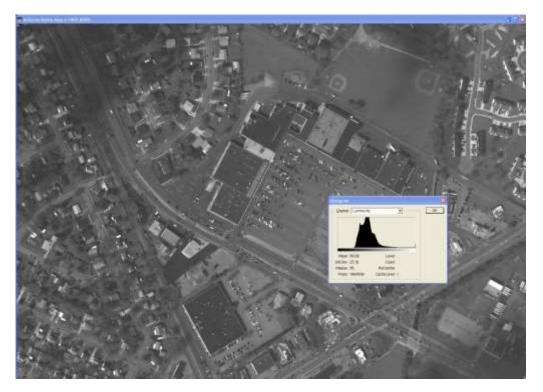
### Modes Target Index Description Read Write R/W 0x04 0x60 Histogram EQ Enable 0 = disable 0x04 0x61 Histogram Threshold R/W Range 0x00..0xFF, 0x04 0x62 R/W Histogram Detector 0 = disableEnable 0x04 0x63 Maximum HEQ Gain R/W Max digital gain in HEQ mode 0x04 R/W 0x24 Digital Gain R/W 0x04 0x30 **Digital Offset** 0x04 R/W 0x38 Master DGO Enable 1 = enable, 0 = disable







### **Histogram Equalization**



Low contrast image before Histogram Equalization



Low contrast image after Histogram Equalization

Histogram Equalization RMOD-71/RMOD-71 TEC



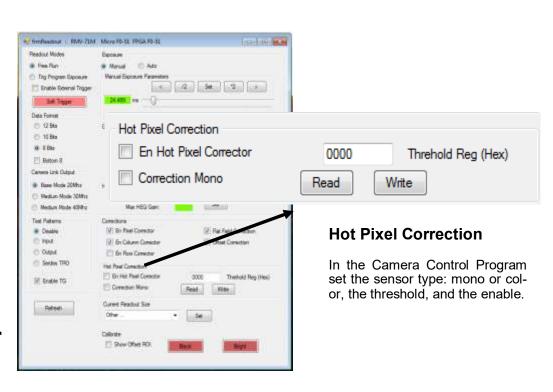
### **Hot Pixel Correction**

The Hot Pixel Correction (HPC) algorithm dynamically analyzes the video data for single bright (hot) pixels.

Hot pixels are generated by thermal noise in the photo diode of the sensor. Long exposures will create more hot pixels than short exposures.

The HPC does not require calibration. It compares a target pixel with its horizontally adjacent pixels. The difference of left/right neighbor and the pixel is calculated. If the difference is greater than the set **Threshold**, then the pixel is replaced with the average of the adjacent pixels.

Target	Index	Description	Read Write	Modes
0x04	0xA0	Hot Pixel Corrector	R/W	0x0000 = Disabled 0x0001 = Enabled
0x04	0xA1	Hot Pixel Correction Type	R/W	0x0000 = Color Bayer 0x0001 = Monochrome
0x04	0xA2	Hot Pixel Threshold	R/W	Threshold in dn Recommended > 0x0010



Hot Pixel Correction RMOD-71/RMOD-71 TEC



### **Hot Pixel Correction**

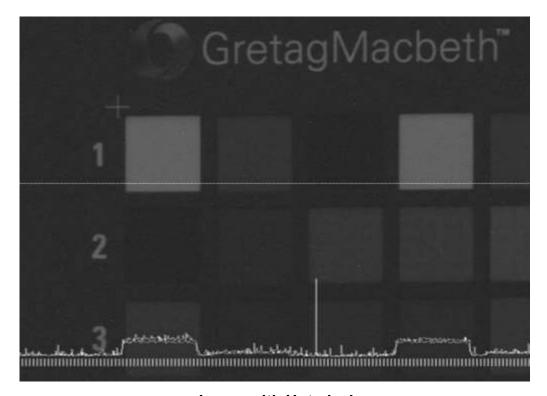


Image with Hot pixels

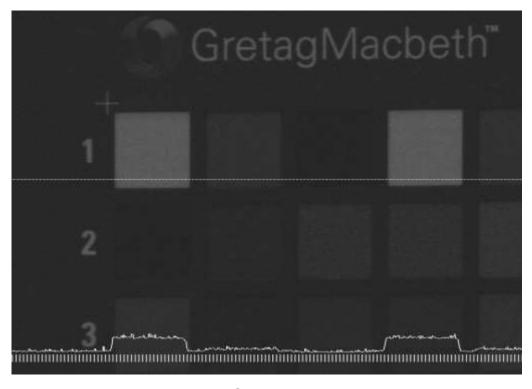


Image with Corrected Hot pixels

Hot Pixel Correction RMOD-71/R



### Long Exposures

The RMOD-71/RMOD-71 TEC use the ams/CMOSIS CHR71M sensor. This sensor is implemented in a CMOS process with 3.1µm pixels, and as such does not perform as well as CCD sensors with larger pixels. In particular the dark current performance is approximately 4.5x worse than a typical Interline CCD sensor with 5.5µm pixels.

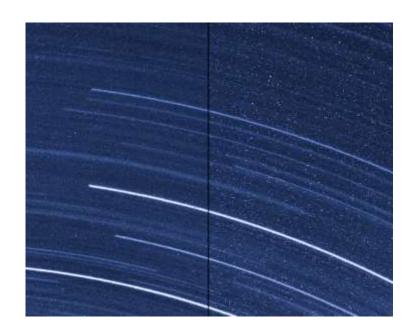
These are the recommended techniques to minimize the dark current:

- 1) Reduce the camera and sensor operating temperature (TEC Option)
- 2) Utilize a dark frame subtraction algorithm.
- 3) Break longer exposures into many short exposures, subtract a dark frame and sum the images.
- 4) Use the Hot Pixel Corrector feature.

The CHR71M specifications (v6) for Dark Signal:

Dark Noise Dark Signal	7e - 3.2 e-/s	(measured in high gain mode) at Room Temperature
DSNU	6 e/s	at Room Temperature
Full Well	> 13ke	·

### Long Exposures RMOD-71/RMOD-71/RMOD-71





### **TEC Cooling**



The TEC functions can be controlled by the Camera Control Application or by reading and writing the following commands:

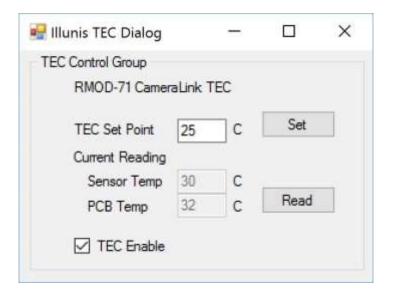
כ	<u></u>	1 TEC
		/RMOD-7
U Ш	)    -	RMOD-71

Target	Index	Description	Read Write	Modes
0x04	0x34	TEC Target Temp 2's complement integer	R/W	Target Temperature (Degrees C)
0x04	0x08	TEC PCB Temp	R	Internal Ambient Temperature
0x04	0x39	Camera Type Code	R	And this word with 0x0200 to determine If the TEC is installed.
0x00	0x73	Calibrate Sensor Temp	R	Run to calibrate sensor internal temperature sensor. Must be run on camera from cold start. Let camera rest unpowered for one hour before calibration.  Sensor temp and PCB temp are used for calibration.
0x03	0x00	Save System State	W	Saves TEC Temp Value



TEC parameters are controlled from the TEC dialog box in the Camera Control Application.

Choose Modes->TEC Parameters to open the following dialog box:



From this dialog box the TEC Set Point temperature may be set. The TEC may be enabled and disabled and the sensor temperature and Camera internal temperature may be read.



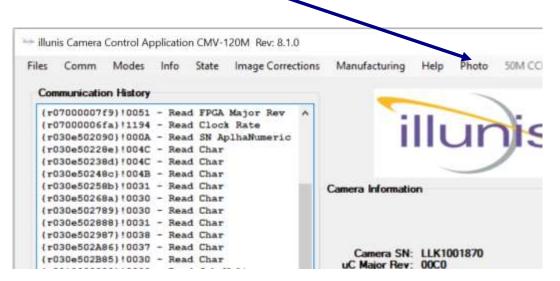


### Image Storage and Display

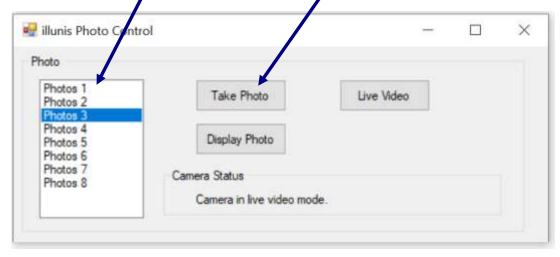
Up to 8 images may be stored and displayed by the camera. These images are stored in internal 256MB memory. The images remain in permanent memory and can be displayed after the camera power has been removed and re-applied.

The storage and display of stored images is accomplished through the Camera Control Application.

Choose the Photo menu item to open the image store and display dialog box.



Choose the Image number to store and press Take Photo to begin storing the image to memory.



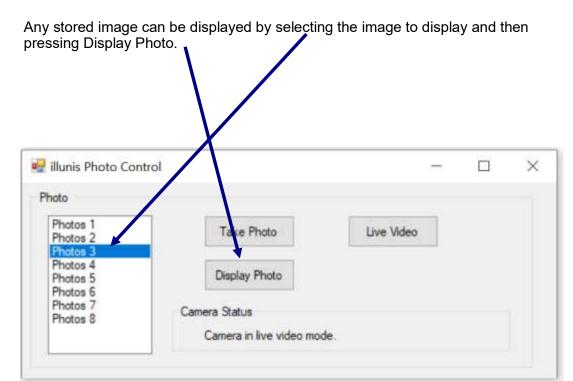
The camera will display an On Screen Display and a progress bar that moves down the image as the image is stored.

```
Shading Table Generation | Status: reg 8x40 | Table#: 3 | Scanning... | Block: 16 x 8 | Scanning
```

When the image storage is complete a dialog box appears indicating the process is complete.



## and Display



The image will be displayed without a delay.



### **Shading Correction Introduction**

This section details the setup and operation of the shading correction in the RMOD-71 and RMOD-71 TEC cameras. Note that this function is supported by only new hardware. Older versions of the RMOD-71 require a hardware update to add this function.

### **Minimum Firmware Revisions**

Micro Processor: F0.185 FPGA: F0.83 Control application: 7.1.35

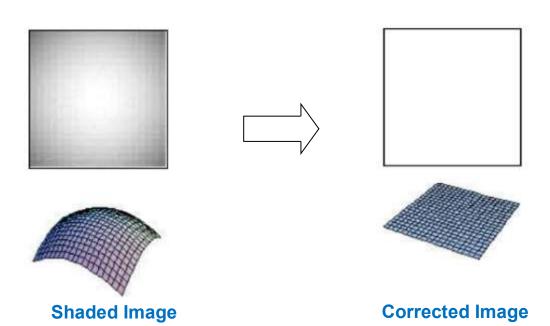
### **Final Note**

Shading correction is not preset in the camera. Shading correction requires the actual application lens and lighting. As such it is not possible to correctly configure the shading correction at the factory.

### Overview

Nearly all optics have some non-uniformity that results in a vignetting or "shading" of the images they create. This non-uniformity can be corrected within the camera using a block based gain of the image data. The image is divided into 16x8 pixel blocks which are used to correct the shading. For example; the image on the left is representative of optical shading before correction. The image on the right is the result after block based correction.







The internal shading correction coefficients are stored as tables in EEPROM. There are 10 tables that can be used in the RMOD-71 or RMOD-71 TEC cameras. The shading functions are controlled with the exposure and readout dialog in the illunis Camera Control Application. (default shading table data is 16x gain).

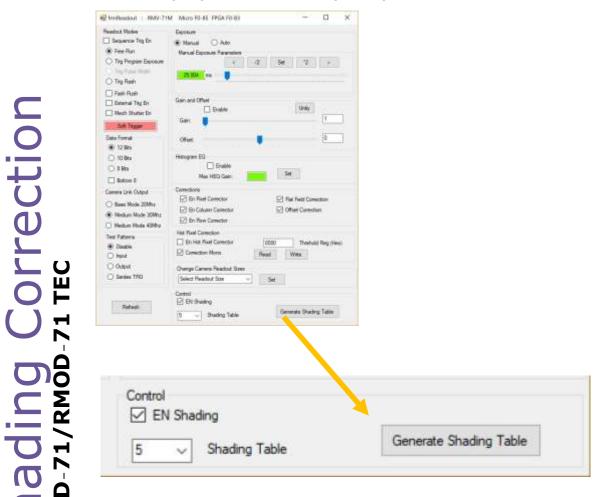
Steps to create a shading correction table:

- 1. Image a uniform light source with the optics set to the F-number and Aperture required.
- 2. Set the illumination to be 75% to 90% of saturation by adjusting the Aperture or exposure.

Note: noise will increase if shading tables are generated at low light levels. Make sure that the image does not have fully saturated or completely black pixels.

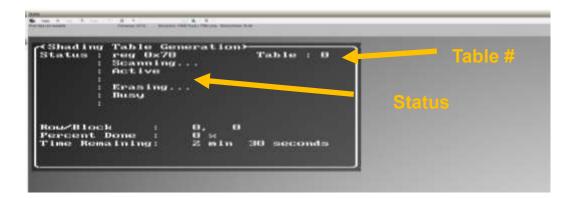
- 3. Select the desired table number for the correction.
- 4. Activate the "Generate Shading Table"
- 5. Wait for the table generation to complete.

The Following page shows the shading table generation process.





### **Generate Shading Process**



### Erasing Table ~ 10 seconds



### Scanning Image ~ Speed Depends on Readout Mode



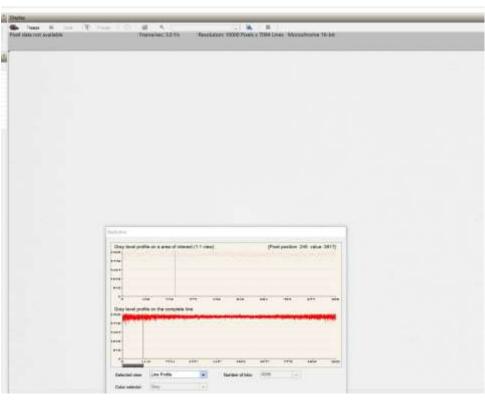
**Enable Shading Correction** 



Shading Correction RMOD-71/RMOD-71 TEC



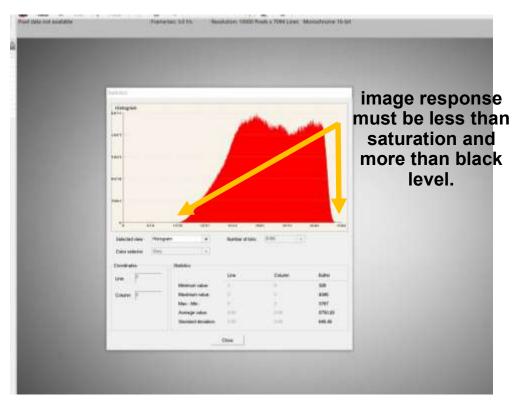
### **Row Response Before Shading Correction**



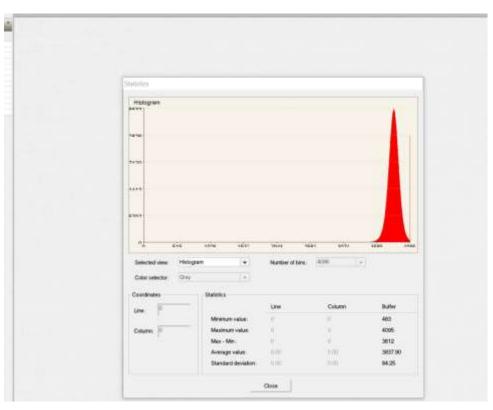
**Row Response After Shading Correction** 



Shading Correction RMOD-71/RMOD-71 TEC



### **Histogram Before Shading Correction**



**Histogram After Shading Correction** 



### **Shading Commands**

The following commands are used to create and use shading tables

Target	Index	Description	Read Write	Modes
0x5A	0x04	Enable Shading Cor- rection	R/W	1 = enable, 0 = disable
0x5A	0x05	Generate Shading Table	R/W	Requires 2-5 minutes
0x5A	0x00	Set Shading Table #	R/W	Table # 0-9
0x04	0x15	Set OSD	W	0x0000 = OSD Off
0x03	0x00	Save System State	W	Saves Shading table and enable status
0x07	0x03	Micro Major Revision	R	0xF0
0x07	0x08	Micro Minor Revision	R	0x185 or greater

## Shading Correction RMOD-71/RMOD-71 TEC



### **Shading Summary**

The shading correction hardware is used to compensate for lens or lighting non-uniformity.

The shading correction uses 16x8 pixel blocks within the image to apply a gain factor to equalize the image. All blocks are gained up to match the brightest block.

Offset correction is not required as it is applied through the black calibration of the RMOD-71/RMOD-71 TEC.

An On Screen Display (OSD) is used to show the status of the generation of the shading table. The OSD can be disabled on the OSD menu through the camera control application. Choose Info -> On Screen Display to display the OSD dialog box.

The shading table generation is performed by the camera FGPA logic. Do not send any commands to the camera during the table generation process.

The shading table should be created for each aperture or lens magnification used in the application.

Shading tables are not factory set as they are dependent on the lens and lighting combination used.

Use a separate shading table for each readout mode. For example Base Camera Link should have a separate shading table from 40Mhz Medium readout.

The quality of the calibration image is very important. The shading table generation corrects the image as presented during generation. The shading table generation requires several minutes as the scan of each block of lines requires a frame of readout. The calibration image must be stable and have no flicker or changes of intensity. **A faulty calibration image will result in a faulty correction table.** The use of an line plot or histogram will help in determining the suitability of the calibration image.

## Shading Correction Mod-71/RMOD-71 TEC