view\_frames Result Recorded at time: 143.166 odom Broadcaster: /gazebo Average rate: 20.113 Hz Most recent transform: 143.129 (0.037 sec old) Buffer length: 1.939 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.526 Hz Average rate: 10.526 Hz Most recent transform: 143.151 (0.015 sec old) Most recent transform: 0.000 (143.166 sec old) Most recent transform: 0.000 (143.166 sec old) Most recent transform: 143.151 (0.015 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 1.900 sec Buffer length: 1.900 sec link\_01 left\_leg right\_leg link\_11 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.526 Hz Average rate: 10.526 Hz Most recent transform: 0.000 (143.166 sec old) Most recent transform: 0.000 (143.166 sec old) Most recent transform: 143.151 (0.015 sec old) Most recent transform: 143.151 (0.015 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 1.900 sec Buffer length: 1.900 sec link\_12 left\_base right\_base link\_02 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.526 Hz Most recent transform: 143.151 (0.015 sec old) Buffer length: 1.900 sec link\_03 link\_13 left\_front\_wheel right\_back\_wheel right\_front\_wheel left\_back\_wheel Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.526 Hz Average rate: 10.526 Hz Most recent transform: 143.151 (0.015 sec old) Most recent transform: 143.151 (0.015 sec old) Buffer length: 1.900 sec Buffer length: 1.900 sec link\_04 link\_14 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.526 Hz Average rate: 10.526 Hz Most recent transform: 143.151 (0.015 sec old) Most recent transform: 143.151 (0.015 sec old) Buffer length: 1.900 sec Buffer length: 1.900 sec link\_05 link\_15 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.526 Hz Average rate: 10.526 Hz Average rate: 10.526 Hz Average rate: 10.526 Hz Most recent transform: 143.151 (0.015 sec old) Buffer length: 1.900 sec Buffer length: 1.900 sec Buffer length: 1.900 sec Buffer length: 1.900 sec down\_left\_gripper down\_right\_gripper top\_left\_gripper top\_right\_gripper Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (143.166 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec top\_left\_tip down\_left\_tip down\_right\_tip top\_right\_tip