

- Turn in your solutions electronically at the moodle page. The submission should be a pdf file typeset either using LaTeX or any other software that generates pdf. No handwritten solutions are accepted.
- Collaboration is encouraged, but all write-ups must be done individually and independently. For each question, you are required to mention the set of collaborators, if any.
- Submissions will be checked for **plagiarism**. Each case of plagiarism will be reported to the institute disciplinary committee (DISCO).

1. (8 points) Let  $P = \{p_1, \dots, p_n\}$  be a set of  $n$  points from the unit square  $[0, 1]^2$ . A triangulation  $\tau$  of  $P$  is a maximal planar graph with  $P$  as the vertex set (i.e., the locations of points in  $P$  should be an embedding of the graph). A minimum weight triangulation (denoted by  $mwt$ ) is a triangulation with minimum total edge weight. Let  $MWT$  denote the corresponding Euclidean functional. The convex hull (denoted by  $CH$ ) of  $P$  is the smallest convex set (i.e. polygon) containing  $P$ . Let  $|CH(P)|$  denote the number of vertices in the convex hull of  $P$ . Suppose  $Q_1, Q_2, Q_3$  and  $Q_4$  be a partition of  $[0, 1]^2$  of equal sized squares. Show that

$$MWT(P, [0, 1]^2) \leq \sum_{i=1}^4 MWT(P \cap Q_i, Q_i) + \sum_{i=1}^4 O(|CH(P \cap Q_i)|).$$

2. (16 points) In the vehicle routing problem, we are given a set of depots  $D = \{d_1, \dots, d_k\}$  from  $[0, 1]^d$  and a set of  $n$  points  $P = \{p_1, \dots, p_n\}$  (called customers) which are again points from  $[0, 1]^d$ . The job is to compute minimum cost  $k$  vertex disjoint cycles such that every cycle has exactly one depot and every depot is in exactly one cycle. Let  $MDP$  denote the corresponding Euclidean functional.
  - (a) (7 points) Formally define the functional  $MDP$ . Prove that  $MDP$  is subadditive but not superadditive.
  - (b) (9 points) Define a canonical boundary functional  $MDP_B$  for  $MDP$  and show that it is superadditive. Show that the boundary functional is also a smooth Euclidean functional.
3. (6 points) Refer to phase 3 of the algorithm for computing Hamiltonian cycle given in Page 6 of Frieze's survey. Show that for any tractable graph, the phase 3 of the algorithm always succeeds in computing a Hamiltonian cycle, if exists.