





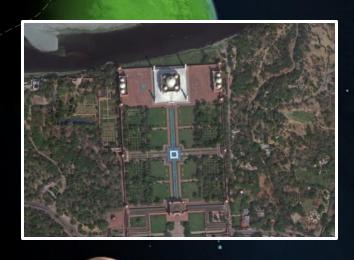


+ The TensorFlow Object Detection API is an open-source framework built on top of TensorFlow that makes it easy to construct, train and deploy object detection models.



Collecting Dataset

Gathering images of famous monuments

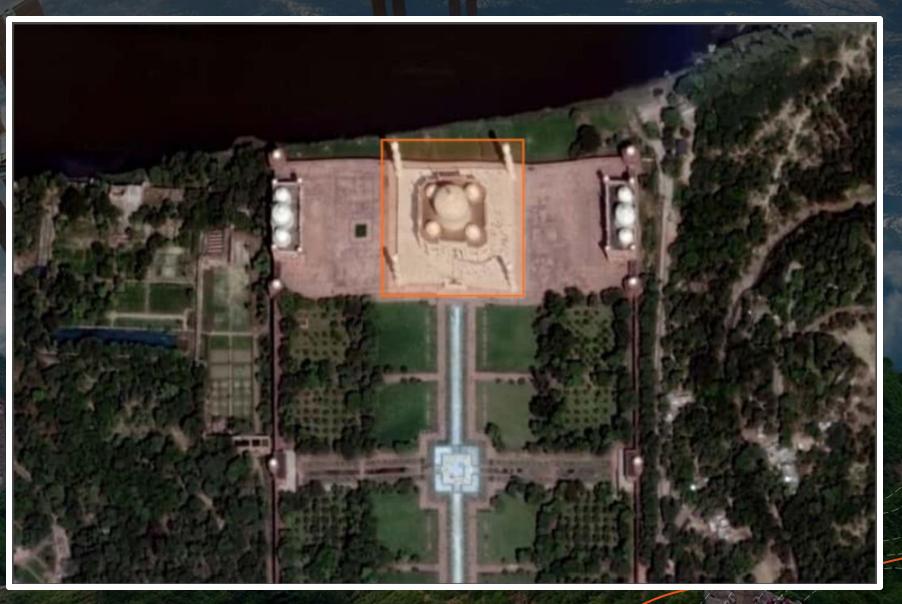


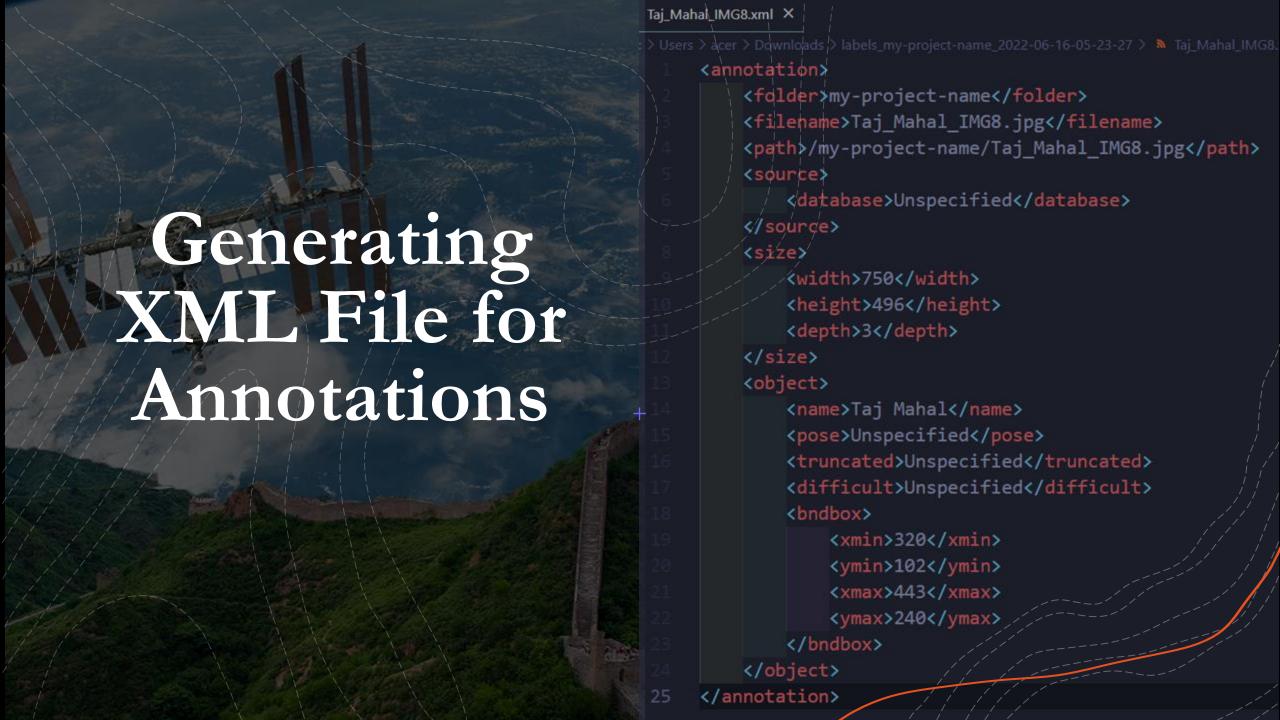


Sources:

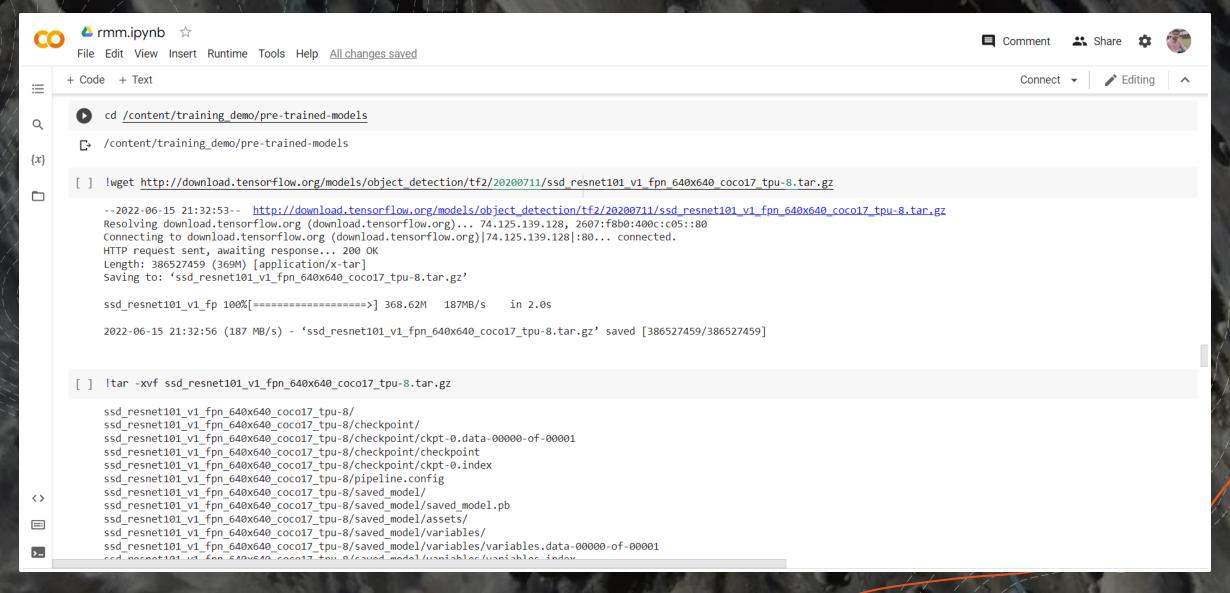
- Google Images
- Google Earth
- iStock
- Shutterstock

Making Annotation





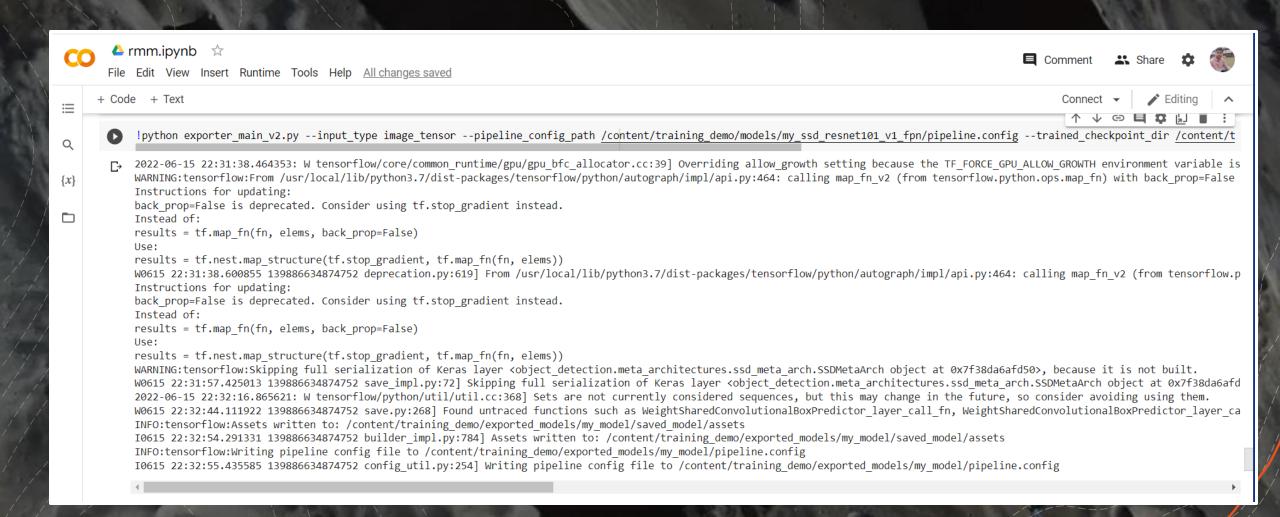
Getting Pre-trained Model



Training Custom Monument Detector

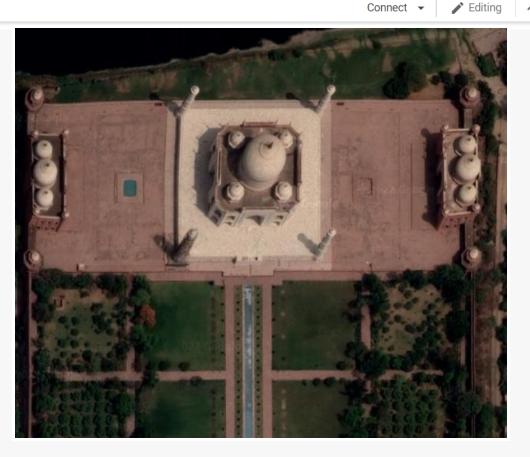
```
♠ rmm.ipvnb ☆
                File Edit View Insert Runtime Tools Help All changes saved
            + Code + Text
                         | python model main tf2.py --model dir=/content/training demo/models/my ssd resnet101 v1 fpn --pipeline config path=/content/training demo/models/my ssd resnet101 v1 fpn --pipeline config path=/cont
                           'Loss/regularization loss': 2.1549718,
                          'Loss/total loss': 2.4730835,
\{x\}
                           'learning rate': 0.025333151}
                        I0615 22:07:59.587969 139747739174784 model lib v2.py:708] {'Loss/classification loss': 0.20783213,
                           'Loss/localization loss': 0.11027953,
'Loss/regularization loss': 2.1549718,
                           'Loss/total loss': 2.4730835,
                           'learning rate': 0.025333151}
                         INFO:tensorflow:Step 1000 per-step time 0.787s
                        I0615 22:09:18.327965 139747739174784 model lib v2.py:707] Step 1000 per-step time 0.787s
                        INFO:tensorflow:{'Loss/classification loss': 0.16494603,
                           'Loss/localization loss': 0.14156711,
                           'Loss/regularization loss': 2.1134496,
                           'Loss/total loss': 2.4199626,
                           'learning rate': 0.0266665}
                        I0615 22:09:18.328323 139747739174784 model lib v2.py:708] {'Loss/classification loss': 0.16494603,
                           'Loss/localization loss': 0.14156711,
                           'Loss/regularization loss': 2.1134496,
                           'Loss/total loss': 2.4199626,
                           'learning rate': 0.0266665}
                         INFO:tensorflow:Step 1100 per-step time 0.808s
                        I0615 22:10:39.099520 139747739174784 model lib v2.py:707] Step 1100 per-step time 0.808s
                        INFO:tensorflow:{'Loss/classification loss': 0.2859589,
                           'Loss/localization loss': 0.071680404,
                           'Loss/regularization loss': 2.0793965,
                           'Loss/total loss': 2.4370358,
                           'learning rate': 0.02799985}
<>
                         I0615 22:10:39.099871 139747739174784 model lib v2.py:708] {'Loss/classification loss': 0.2859589,
                           'Loss/localization loss': 0.071680404,
                           'Loss/regularization loss': 2.0793965,
                           'Loss/total loss': 2.4370358,
                            'learning rate': 0.02799985}
```

Exporting The Model



Testing The Model

```
+ Code + Text
      os.environ['TF_CPP_MIN_LOG_LEVEL'] = '2' # Suppress TensorFlow logging (1)
      import pathlib
      import tensorflow as tf
      import cv2
      import argparse
     from google.colab.patches import cv2 imshow
      # Enable GPU dynamic memory allocation
      gpus = tf.config.experimental.list physical devices('GPU')
      for gpu in gpus:
          tf.config.experimental.set_memory_growth(gpu, True)
      # PROVIDE PATH TO IMAGE DIRECTORY
      IMAGE PATHS = '/content/training demo/images/test/Screenshot 2022-06-15 223223.png'
      # PROVIDE PATH TO MODEL DIRECTORY
      PATH TO MODEL DIR = '/content/training demo/exported models/my model'
      # PROVIDE PATH TO LABEL MAP
     PATH_TO_LABELS = '/content/training_demo/annotations/label map.pbtxt'
      # PROVIDE THE MINIMUM CONFIDENCE THRESHOLD
      MIN_CONF_THRESH = float(0.60)
      # LOAD THE MODEL
      import time
      from object detection.utils import label map util
      from object detection utils import visualization utils as vizutils
```



Input Image

Final Output

