

## DIJKSTA ALGORITHM

```
#include<stdio.h>

#include<conio.h>

#define INFINITY 9999

#define MAX 10

void dijkstra(int G[MAX][MAX],int n,int startnode);

int main()
{
    int G[MAX][MAX],i,j,n,u;
    printf("Enter no. of vertices:");
    scanf("%d",&n);
    printf("\nEnter the adjacency matrix:\n");
    for(i=0;i<n;i++)
    for(j=0;j<n;j++)
    scanf("%d",&G[i][j]);
    printf("\nEnter the starting node:");
    scanf("%d",&u);
    dijkstra(G,n,u);
    return 0;
}

void dijkstra(int G[MAX][MAX],int n,int startnode)
{
    int cost[MAX][MAX],distance[MAX],pred[MAX];
    int visited[MAX],count,mindistance,nextnode,i,j;
    //pred[] stores the predecessor of each node
    //count gives the number of nodes seen so far
```

```

//create the cost matrix
for(i=0;i<n;i++)
for(j=0;j<n;j++)
if(G[i][j]==0)
cost[i][j]=INFINITY;
else
cost[i][j]=G[i][j];
//initialize pred[], distance[] and visited[]
for(i=0;i<n;i++)
{
distance[i]=cost[startnode][i];
pred[i]=startnode;
visited[i]=0;
}
distance[startnode]=0;
visited[startnode]=1;
count=1;
while(count<n-1)
{
mindistance=INFINITY;
//nextnode gives the node at minimum distance
for(i=0;i<n;i++)
if(distance[i]<mindistance&&!visited[i])
{
mindistance=distance[i];
nextnode=i;
}
//check if a better path exists through nextnode
visited[nextnode]=1;
for(i=0;i<n;i++)

```

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if(!visited[i])
if(mindistance+cost[nextnode][i]<distance[i])
{
distance[i]=mindistance+cost[nextnode][i];
pred[i]=nextnode;
}
count++;
}

```

```

//print the path and distance of each node
for(i=0;i<n;i++)
if(i!=startnode)
{
printf("\nDistance of node%d=%d",i,distance[i]);
printf("\nPath=%d",i);
j=i;
do
{
j=pred[j];
printf("<-%d",j);
}while(j!=startnode);
}
}

```

OUTPUT:

```
Enter no. of vertices:5
```

```
Enter the adjacency matrix:
```

```
0 3 2 1 99
3 0 99 99 5
2 99 0 99 6
1 99 99 0 7
99 5 6 7 0
```

```
Enter the starting node:1
```

```
Distance of node0=3
```

```
Path=0<-1
```

```
Distance of node2=5
```

```
Path=2<-0<-1
```

```
Distance of node3=4
```

```
Path=3<-0<-1
```

```
Distance of node4=5
```

```
Path=4<-1
```