

```
/*Usage: For finding the real roots of any given Transcendental equation.
```

Specification: The program takes coefficients of the equation and upper and lower values of the interval as the input and computes the root for the given equation using Muller's method.

In this method, $f(x)$ is approximated by a second degree curve in the vicinity of a root. The roots of the quadratic are then assumed to be the approximations to the roots of the equation $f(x) = 0$.

The method is iterative, converges almost quadratically, and can be used to obtain complex roots.

```
*/
```

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
```

```
//Function prototypes
```

```
float muller1(float a, float b, float c);
float f(float x);
```

```
//Global Variables
```

```
float co_a, co_b, co_c;
```

```
int main(int argc, char **argv)
```

```
{
    float a, b, c, disc, root;

    if (argc != 7) //Verification of arguments
    {
        fprintf(stderr, "Usage: %s <x_(k-2)> <x_(k-1)> <x_k> <approximates to the root>\n", argv[0]);
        exit(1);
    }
}
```

```
//Getting the values of coefficients
```

```
co_a = atof(argv[1]);
co_b = atof(argv[2]);
co_c = atof(argv[3]);
```

```
//Calculating the discriminant
```

```
disc = ((co_b * co_b) - (4 * co_a * co_c));
```

```
// Checking whether discriminant < 0
```

```
if (disc < 0)
{
    fprintf(stderr, "The given Equation has no real roots.\n");
    exit(2);
}
```

```
//Getting approximate root values
```

```
a = atof(argv[4]);
b = atof(argv[5]);
c = atof(argv[6]);
```

```
root = muller1(a, b, c); //Calling Function
```

```
printf("Root of the given equation is: %f\n", root);
```

```
exit(0);
```

```
}
```

```
float muller1(float a, float b, float c)
```

```
{
    float h_b, h_c, lamk, sigk, gk, ck, lamda, lamda1;
    float val, val1, xk;
```

```
h_c = (c - b), h_b = (b - a), lamk = h_c/h_b, sigk = lamk + 1;
```

```
while (1)
{
    gk = ((lamk*lamk*f(a))-(sigk*sigk*f(b))+((lamk+sigk)*f(c))); //Value of gk
    ck = lamk*(((lamk*f(a))-(sigk*f(b))+f(c))); //Value of ck

    val = (gk*gk - 4*sigk*ck*f(c));
    val1 = sqrtf(val);

    lamda = -2*sigk*f(c) / (gk-val1); //Value of lamda1
    lamda1 = -2*sigk*f(c) / (gk+val1); //Value of lamda2

    //Checking the convergence of the equation
    if (floor(gk*10000) == floor(val1*10000))
    {
        return c;
    }

    if (lamda1 < lamda)
    {
        lamda = lamda1;
    }

    xk = c + lamda*(c-b);

    a = b;
    b = c;
    c = xk;

    if (floor(c*10000) == floor(b*10000)) //Comparing the roots
    {
        return c;
    }
}

float f(float x)
{
    float ans;

    ans = (co_a * x * x) + (co_b * x) + co_c; // Function Equation

    if(ans != ans)
    {
        printf("Cannot proceed further..Try changing the values\n");
        exit (2);
    }
    return ans;
}
```