# Efficient-UCBV: An Almost Optimal Algorithm using Variance Estimates

Subhojyoti Mukherjee (IIT Madras)

Dr. K.P. Naveen (IIT Tirupati)

Dr. Nandan Sudarsanam (IIT Madras, RBC-DSAI)

Dr. Balaraman Ravindran (IIT Madras, RBC-DSAI)

Feb 6, 2018

#### Overview

- Stochastic Multi-Armed Bandit Problem
- Problem Definition of SMAB
- Contributions in SMAB
- EUCBV Algorithm for SMAB
- Theoretical Analysis of EUCBV
- Experiments in SMAB
- Conclusions

# Stochastic Multi-Armed Bandit Problem (SMAB)

• A finite set of actions or arms belonging to set  $\mathbb{A}$  such that  $|\mathbb{A}| = K$ .

# Stochastic Multi-Armed Bandit Problem (SMAB)

- A finite set of actions or arms belonging to set  $\mathbb{A}$  such that  $|\mathbb{A}| = K$ .
- The rewards for each of the arms are i.i.d random variables drawn from distribution specific to the arm which are fixed throughout the time horizon denoted by T.

# Stochastic Multi-Armed Bandit Problem (SMAB)

- A finite set of actions or arms belonging to set  $\mathbb{A}$  such that  $|\mathbb{A}| = K$ .
- The rewards for each of the arms are i.i.d random variables drawn from distribution specific to the arm which are fixed throughout the time horizon denoted by T.
- The learner does not know the mean  $r_i$ ,  $\forall i \in \mathbb{A}$  of the distribution or the variance  $\sigma_i^2$ .

#### **Problem Definition of SMAB**

• **Primary aim:** Minimize the cumulative regret by identifying the arm whose expected mean is  $r^*$  such that  $r^* > r_i, \forall i \in \mathbb{A}$ .

#### **Problem Definition of SMAB**

- **Primary aim:** Minimize the cumulative regret by identifying the arm whose expected mean is  $r^*$  such that  $r^* > r_i, \forall i \in \mathbb{A}$ .
- **Condition:** This has to be achieved within a finite *T* timesteps.

#### **Problem Definition of SMAB**

- **Primary aim:** Minimize the cumulative regret by identifying the arm whose expected mean is  $r^*$  such that  $r^* > r_i, \forall i \in \mathbb{A}$ .
- **Condition:** This has to be achieved within a finite *T* timesteps.
- The expected regret of an algorithm after T timesteps is give by,

$$\mathbb{E}[R_T] = \sum_{i=1}^K \mathbb{E}[z_i(T)] \Delta_i,$$

where  $\Delta_i = r^* - r_i$  is the gap.

 We propose the Efficient-UCB-Variance (EUCBV) algorithm for the SMAB setting.

- We propose the Efficient-UCB-Variance (EUCBV) algorithm for the SMAB setting.
- EUCBV takes into account the empirical variances of the arms along with mean estimates to quickly find the optimal arm.

- We propose the Efficient-UCB-Variance (EUCBV) algorithm for the SMAB setting.
- EUCBV takes into account the empirical variances of the arms along with mean estimates to quickly find the optimal arm.
- It is the first variance-based arm elimination algorithm for the considered SMAB setting.

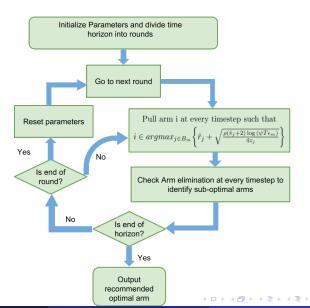
- We propose the Efficient-UCB-Variance (EUCBV) algorithm for the SMAB setting.
- EUCBV takes into account the empirical variances of the arms along with mean estimates to quickly find the optimal arm.
- It is the first variance-based arm elimination algorithm for the considered SMAB setting.
- It addresses an open problem discussed in Auer and Ortner (2010) of designing an algorithm that can eliminate arms based on variance estimates.

- We propose the Efficient-UCB-Variance (EUCBV) algorithm for the SMAB setting.
- EUCBV takes into account the empirical variances of the arms along with mean estimates to quickly find the optimal arm.
- It is the first variance-based arm elimination algorithm for the considered SMAB setting.
- It addresses an open problem discussed in Auer and Ortner (2010) of designing an algorithm that can eliminate arms based on variance estimates.
- Theoretically it achieves an order-optimal regret bound, the first for an arm elimination algorithm in SMAB setting.

- We propose the Efficient-UCB-Variance (EUCBV) algorithm for the SMAB setting.
- EUCBV takes into account the empirical variances of the arms along with mean estimates to quickly find the optimal arm.
- It is the first variance-based arm elimination algorithm for the considered SMAB setting.
- It addresses an open problem discussed in Auer and Ortner (2010) of designing an algorithm that can eliminate arms based on variance estimates.
- Theoretically it achieves an order-optimal regret bound, the first for an arm elimination algorithm in SMAB setting.
- Empirically, it outperforms all the state-of-the-art algorithms for the considered environments.



# **EUCBV Algorithm for SMAB**



# Expected Regret of EUCBV

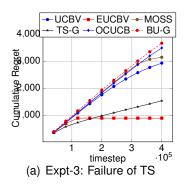
#### Corollary (Gap-Independent Bound)

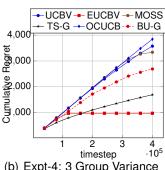
The regret of EUCBV is upper bounded by the following gap-independent expression:

$$\mathbb{E}[R_T] \leq \frac{C_3 K^5}{T^{\frac{1}{4}}} + 80\sqrt{KT}.$$

Algorithm	GD Bound		GI Bound	Var
EUCBV	0	$\left(rac{K\sigma_{max}^2\log(rac{T\Delta^2}{K})}{\Delta} ight)$	$O\left(\sqrt{KT}\right)$	Yes
UCBV	0 (	$\left(\frac{K\sigma_{\max}^2\log T}{\Delta}\right)$	$O\left(\sqrt{KT\log T}\right)$	Yes
MOSS	0 (	$\left(\frac{K^2 \log(T\Delta^2/K)}{\Delta}\right)$	$O\left(\sqrt{KT}\right)$	No
OCUCB	0 (	$\left(\frac{K\log(T/H_i)}{\Delta}\right)$	$O\left(\sqrt{KT}\right)$	No

# **Experiments in SMAB**





(b) Expt-4: 3 Group Variance

#### Conclusions

 We proposed the EUCBV algorithm for the SMAB setting which uses variance and mean estimation along with arm elimination to find the optimal arm.

#### Conclusions

- We proposed the EUCBV algorithm for the SMAB setting which uses variance and mean estimation along with arm elimination to find the optimal arm.
- Theoretically, EUCBV achieves an order-optimal regret guarantees, but further studies are required to reduce the constants.

#### Conclusions

- We proposed the EUCBV algorithm for the SMAB setting which uses variance and mean estimation along with arm elimination to find the optimal arm.
- Theoretically, EUCBV achieves an order-optimal regret guarantees, but further studies are required to reduce the constants.
- A more detailed analysis of the non-uniform arm selection and parameter selection is also required for EUCBV.

# Thank You