

**VISVESVARAYA TECHNOLOGICAL
UNIVERSITY**

“JnanaSangama”, Belgaum -590014, Karnataka.



LAB REPORT

on

Artificial Intelligence (23CS5PCAIN)

Submitted by

Subramanya J (1BM23CS343)

in partial fulfillment for the award of the degree of

BACHELOR OF ENGINEERING

in

COMPUTER SCIENCE AND ENGINEERING



B.M.S. COLLEGE OF ENGINEERING

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Bull Temple Road, Bangalore 560019**
(Affiliated To Visvesvaraya Technological University, Belgaum)
Department of Computer Science and Engineering



CERTIFICATE

This is to certify that the Lab work entitled “Artificial Intelligence (23CS5PCAIN)” carried out by **Subramanya J (1BM23CS343)**, who is bonafide student of **B.M.S. College of Engineering**. It is in partial fulfillment for the award of **Bachelor of Engineering in Computer Science and Engineering** of the Visvesvaraya Technological University, Belgaum. The Lab report has been approved as it satisfies the academic requirements in respect of an Artificial Intelligence (23CS5PCAIN) work prescribed for the said degree.

Sonika Sharma D Assistant Professor Department of CSE, BMSCE	Dr. Kavitha Sooda Professor & HOD Department of CSE, BMSCE
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Github Link:

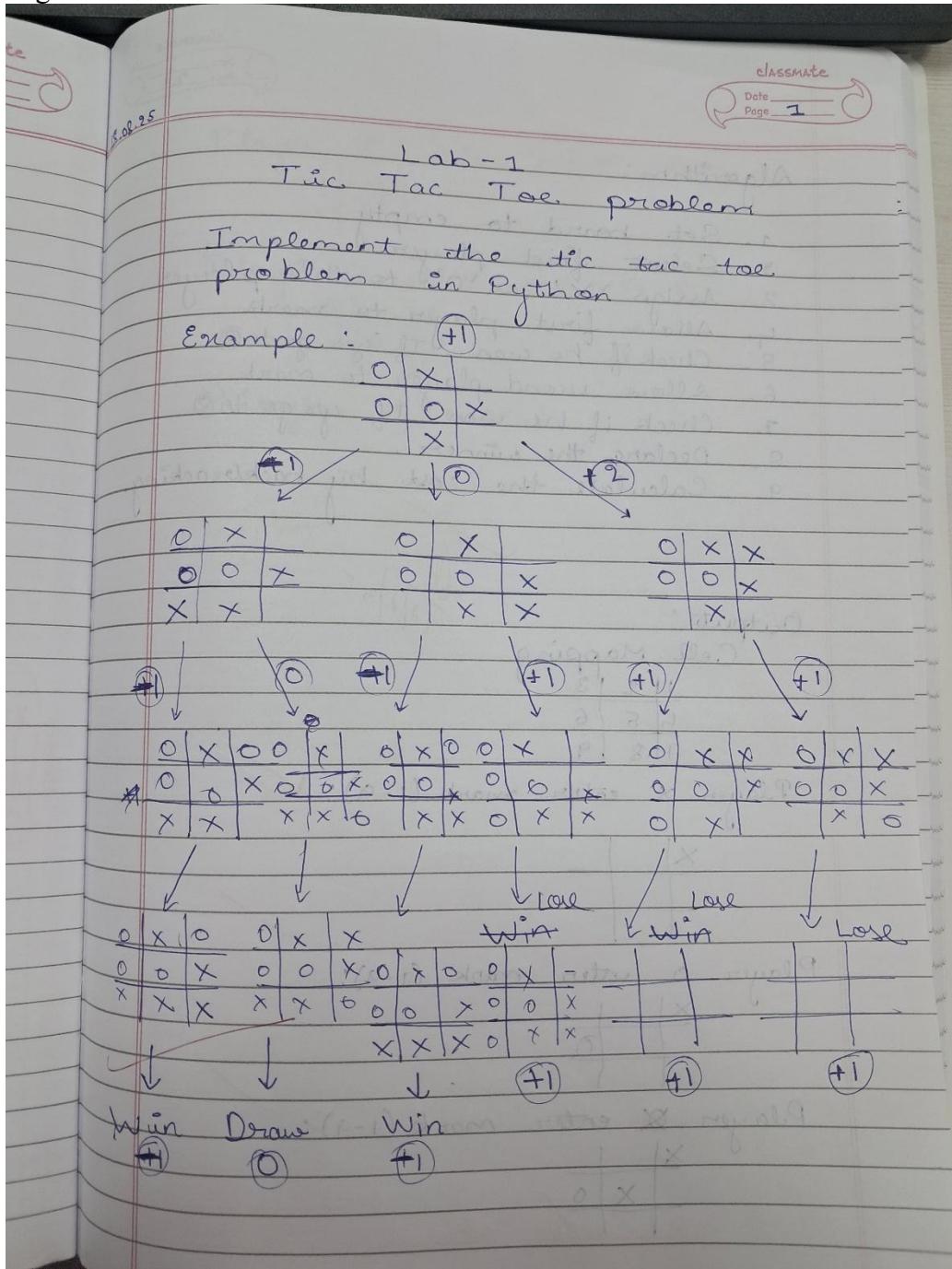
<https://github.com/SubramanyaJ/23CS5PCAIN>

Program 1

Implement Tic – Tac – Toe Game

Implement Vacuum Cleaner agent

Algorithm:



Algorithm:

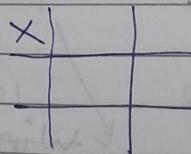
1. Set board to empty
2. Select first player.
3. Assign 'X' or 'O' to this player.
4. Allow first player to mark
5. Check if he won. If yes go to ⑧
6. Allow second player to mark
7. Check if he won. If yes go to ⑧
8. Declare the winner.
9. Calculate the cost by backtracking.

Output:

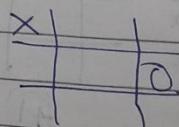
Cell Mapping

1	2	3
4	5	6
7	8	9

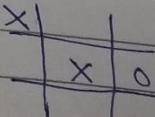
Player X enter mark (1-a):



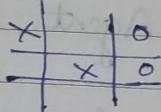
Player O enter mark (1-a):



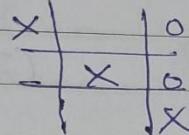
Player X enter mark (1-a):



Player O enter mark (1-a):



Player X enter mark (1-a):



Player X won! critical

Player

~~0/1 Puer~~

~~1/0 1/25~~

: Tugtu

[1,1] : state lottery

1/1 1/1 1/1 1/1 1/1 1/1

1/1 1/1 1/1 1/1 1/1 1/1

1/1 1/1 1/1 1/1 1/1 1/1

1/1 1/1 1/1 1/1 1/1 1/1

1/1 1/1 1/1 1/1 1/1 1/1

1/1 1/1 1/1 1/1 1/1 1/1

[0,0] : state lottery lottery

1/1 1/1 1/1 1/1 1/1 1/1

1/1 1/1 1/1 1/1 1/1 1/1

Lab-2 Vacuum Cleaner Agent

Implement the vacuum cleaner agent problem in Python

Example / Algorithm : (Two Rooms)

1. Initialize the Room
2. Place the cleaner in a room
3. Check if the room is dirty.
4. If dirty, suck the dirt.
5. Else, move to adjacent room
6. Repeat ③ → ④ → ⑤
7. If all rooms are clean, end program.

Output :

Initial states : [1, 1]

Cleaner is room 1

Cleaner is in room 1

Room is dirty

Clean? (y/n) : y

Room is now clean

Current room states : [0, 1]

Enter the room number to move to (1 or 2) : 1

Cleaner is in room: 1

Room is already

Current room states : [0, 1]

Enter the room to move to (1 or 2):

Cleaner is in room 1

Room is dirty.

Clean (y/n) : y

Room is now clean.

Current room states : [0, 0]

~~All rooms are clean. Program ends. cost :~~

~~Total cost : 3~~

✓ 208

Code:

```
def print_board(board):
    for row in board:
        print(" | ".join(row))
        print("-" * 9)
```

```
def print_cell_mapping():
```

```
    mapping = [
        "1 | 2 | 3",
        "-----",
        "4 | 5 | 6",
        "-----",
        "7 | 8 | 9"]
```

```
    print("\nCell Mapping:")
```

```
    for line in mapping:
        print(line)
```

```

print()

def check_winner(board):
    for i in range(3):
        if board[i][0] == board[i][1] == board[i][2] != " ":
            return board[i][0]
        if board[0][i] == board[1][i] == board[2][i] != " ":
            return board[0][i]

    if board[0][0] == board[1][1] == board[2][2] != " ":
        return board[0][0]
    if board[0][2] == board[1][1] == board[2][0] != " ":
        return board[0][2]
    return None

def is_board_full(board):
    return all(cell != " " for row in board for cell in row)

def tic_tac_toe():
    board = [[" " for _ in range(3)] for _ in range(3)]
    current_player = "X"
    print_cell_mapping()

    while True:
        print_board(board)
        move = int(input(f"Player {current_player}, enter the cell number (1-9): ")) - 1
        row, col = divmod(move, 3)

        if 0 <= move < 9 and board[row][col] == " ":
            board[row][col] = current_player
        else:
            print("Invalid move! Try again.")
            continue

        winner = check_winner(board)
        if winner:
            print_board(board)
            print(f"Player {winner} wins!")
            break

        if is_board_full(board):
            print_board(board)
            print("It's a draw!")
            break

        current_player = "O" if current_player == "X" else "X"

tic_tac_toe()

```

Output :

Cell Mapping:

1 | 2 | 3

4 | 5 | 6

7 | 8 | 9

| |

| |

| |

Player X, enter the cell number (1-9): 1

X | |

| |

| |

Player O, enter the cell number (1-9): 2

X | O |

| |

| |

Player X, enter the cell number (1-9): 5

X | O |

| X |

| |

Player O, enter the cell number (1-9): 3

X | O | O

| X |

| |

Player X, enter the cell number (1-9): 9

X | O | O

| X |

| | X

Player X wins!

Code :

```
import random
```

```
rooms = [1, 1]
```

```
print(f"Initial room states: {rooms}")
```

```
cleaner_location = random.randint(0, 1)
```

```
print(f"Cleaner starts in room: {cleaner_location + 1}")
```

```
cleaned_count = 0
```

```
cost_count = 0
```

```
while cleaned_count < 2:
```

```
    print(f"\nCleaner is in room: {cleaner_location + 1}")
```

```
    if rooms[cleaner_location]:
```

```
        print("Room is dirty.")
```

```
        clean_confirm = input("Clean? (y/n): ")
```

```
        if clean_confirm == 'y':
```

```
            rooms[cleaner_location] = 0
```

```
            cleaned_count += 1
```

```
            cost_count += 1
```

```
            print("Room is now clean.")
```

```
        else:
```

```
            print("Room not cleaned.")
```

```
    else:
```

```
        print("Room is already clean.")
```

```
    print(f"Current room states: {rooms}")
```

```
    print(f"Current cost: {cost_count}")
```

```
if cleaned_count < 2:
```

```
    while 1 == 1:
```

```
        move_to = int(input("Enter the room number to move to (1 or 2): ")) - 1
```

```
        if move_to in [0, 1]:
```

```
            cleaner_location = move_to
```

```
            cost_count += 1
```

```
            break
```

```
        else:
```

```
            print("Invalid room number. Please enter 1 or 2.")
```

```
print("\nAll rooms are clean. Program ends.")  
print(f"Total cost: {cost_count}")
```

Output :

Initial room states: [1, 1]

Cleaner starts in room: 2

Cleaner is in room: 2

Room is dirty.

Clean? (y/n): y

Room is now clean.

Current room states: [1, 0]

Current cost: 1

Enter the room number to move to (1 or 2): 1

Cleaner is in room: 1

Room is dirty.

Clean? (y/n): y

Room is now clean.

Current room states: [0, 0]

Current cost: 3

All rooms are clean. Program ends.

Total cost: 3

Program 2

Implement 8 puzzle problems using Depth First Search (DFS)

Implement Iterative deepening search algorithm

Algorithm:

Lab 3
Eight Puzzle Problem

A. Non - Heuristic

Algorithm

1. Start
2. Get valid movement
3. If valid, make movement
4. Else, goto ①
5. If solved exit
6. Else goto ②

Output :

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 6 \\ 7 & 5 & 8 \end{bmatrix}$$

Enter move : right

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 0 & 6 \\ 7 & 5 & 8 \end{bmatrix}$$

Enter move : down

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 0 & 8 \end{bmatrix}$$

Enter move: right

$$\begin{bmatrix} 1, & 2, & 3 \\ 4, & 5, & 6 \\ 7, & 8, & 0 \end{bmatrix}$$

Complete.



Heuristic (Mismatched tiles)

Algorithm

1. Start
2. Calculate number of mismatched tiles
3. Pick a valid move that minimizes number of mismatched tiles.
4. Repeat ③ till program ends.
5. Terminate

Complexity:

$$O(b^d)$$

$b \rightarrow$ branching factor
 $d \rightarrow$ depth

Output:

Initial state :

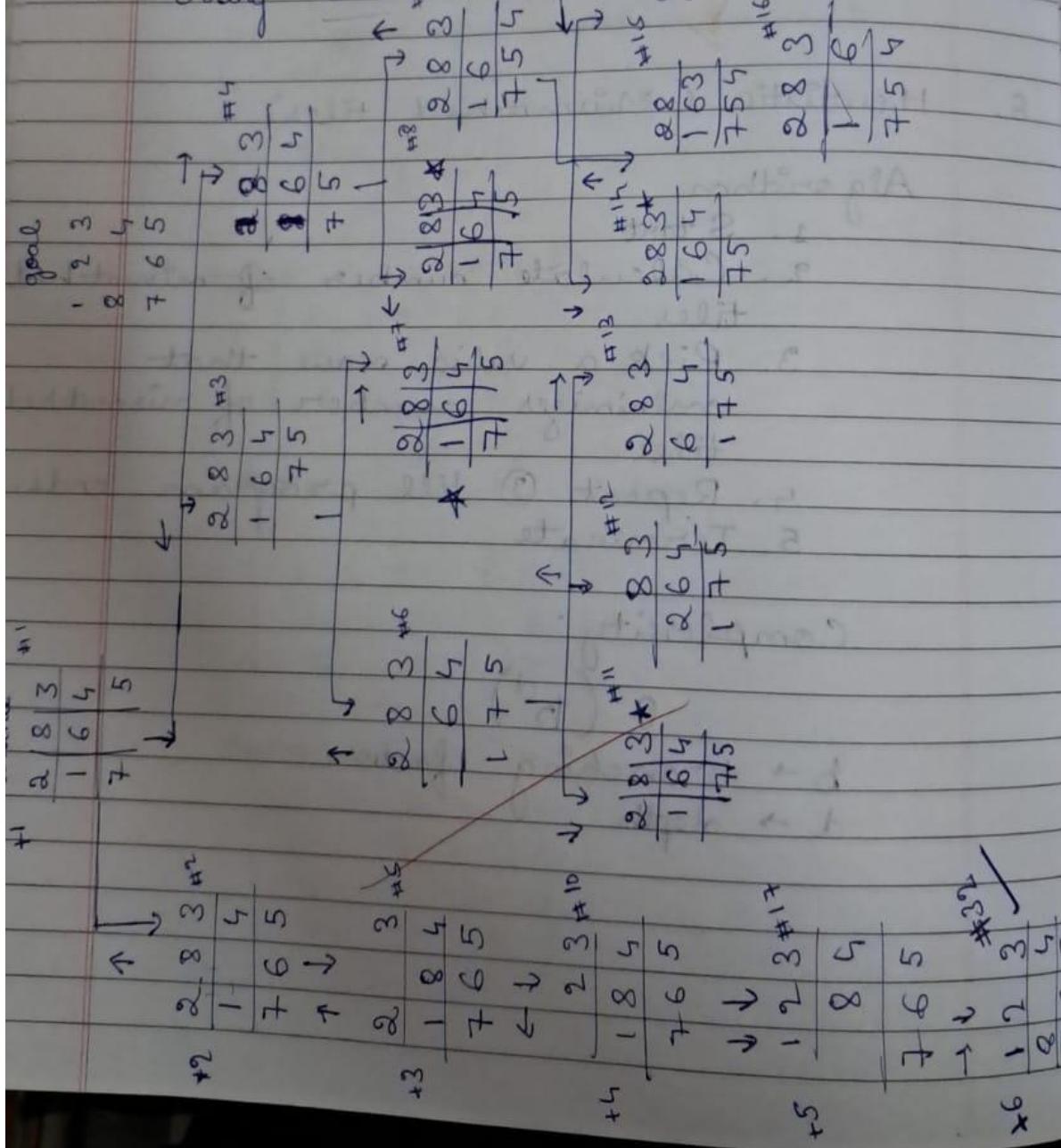
$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 6 \\ 7 & 5 & 8 \end{bmatrix}$$

Final state

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 0 \end{bmatrix}$$

1.09.25

Using BFS, solve 8 puzzle (without heuristic).



9.25

Using DFS:

$$\begin{array}{c} \text{initial} \\ \begin{array}{c} 2 & 8 & 3 \\ \hline 1 & 6 & 4 \\ \hline 7 & 5 \end{array} \end{array}$$

$$\begin{array}{c} \text{final} \\ \begin{array}{c} 2 & 8 & 3 \\ \hline 1 & 6 & 4 \\ \hline 7 & 5 \end{array} \end{array}$$

$$\begin{array}{c} T \\ \swarrow \\ \begin{array}{c} 2 & 8 & 3 \\ 1 & 6 & 4 \\ 7 & 5 \end{array} \end{array}$$

$$\begin{array}{c} \text{final} \\ \begin{array}{c} 2 & 3 & 4 \\ \hline 1 & 8 & 4 \\ \hline 7 & 6 & 5 \end{array} \end{array}$$

$$\begin{array}{c} \downarrow \uparrow \\ \begin{array}{c} 2 & 3 \\ 1 & 8 & 4 \\ 7 & 6 & 5 \end{array} \\ \uparrow \downarrow \\ \begin{array}{c} X | 2 | 3 \\ | 1 | 8 | 4 \\ 7 | 6 | 5 \end{array} \end{array}$$

Algorithm BFS

1. Start
2. Initialize first state to input.
3. Initialize queue and add start node to it.
4. While queue not empty, remove the node.
5. If this is target node, return
6. Else, add children to queue.

1.09.25

- 7) Repeat from step 2 till you get answer.
 8) Terminate

Algorithm DFS

- 1) Start
- 2) Initialize stack, add start node
- 3) Mark node as visited
- 4) Pop top node.
- 5) If this is target, terminate
- 6) Else, for each possible child, push onto stack
- 7) Repeat (2) till you get target
- 8) Terminate

Output [DFS]

Total states visited : 3528

Final path length : 3438

Final state :

1	2	3
8		4
7	6	5

Output [BFS]

Total states visited : 62

Final path length : 6

Final state :

1	2	3
8		4
7	6	5

B0101

Iterative Deepening Depth First Search

Algorithm

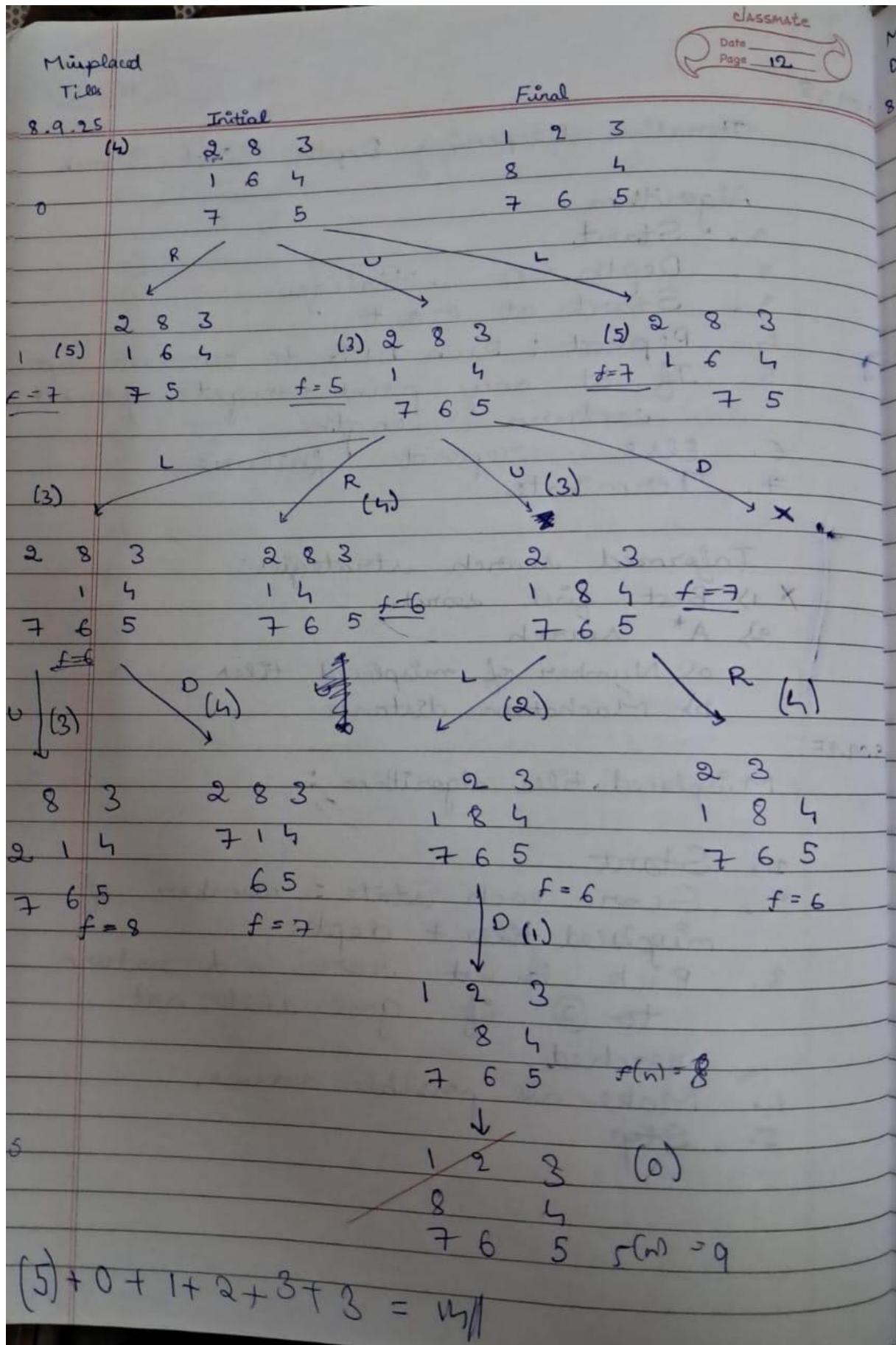
1. Start.
2. Depth = 0 initialize
3. Start at root
4. Repeat : Run DLS to current depth
5. If at any point target found, return length
6. Else, report failure
7. Terminate

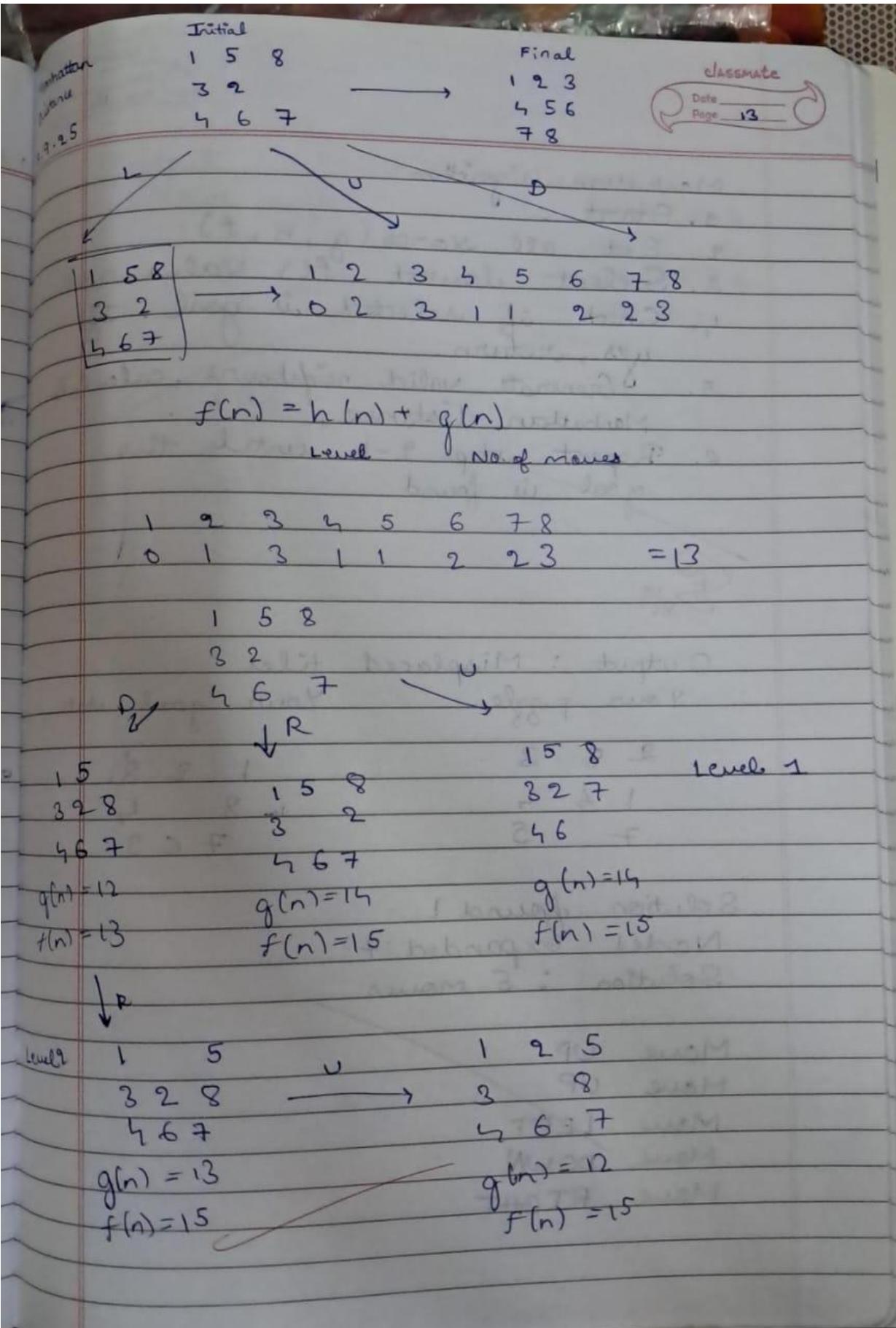
Informed search strategies:

- * 1) Best first search
- 2) A* search
 - a) Number of misplaced tiles
 - b) Manhattan distance

Misplaced tiles algorithm :

1. Start
2. Score each state = number of misplaced tiles + depth
3. Pick lowest score and return to ② if goal state not reached.
4. Make all possible moves.
5. Stop





Code:

Eight Puzzle

```
def swap(arr, x1, y1, x2, y2):
    arr[x1][y1], arr[x2][y2] = arr[x2][y2], arr[x1][y1]
```

```
arr = [[1, 2, 3], [0, 4, 6], [7, 5, 8]]
final = [[1, 2, 3], [4, 5, 6], [7, 8, 0]]
```

```
zero_pos = [1, 0]
```

```
def print_puzzle(arr):
```

```
    for row in arr:
        print(row)
        print("-" * 10)
```

```
moves = {
```

```
    'up': (-1, 0),
    'down': (1, 0),
    'left': (0, -1),
    'right': (0, 1)
```

```
}
```

```
while final != arr:
```

```
    print_puzzle(arr)
```

```
    move = input("Enter move (up, down, left, right): ").lower()
```

```
    dx, dy = moves[move]
```

```
    new_x, new_y = zero_pos[0] + dx, zero_pos[1] + dy
```

```
    if 0 <= new_x < 3 and 0 <= new_y < 3:
```

```
        swap(arr, zero_pos[0], zero_pos[1], new_x, new_y)
        zero_pos[0], zero_pos[1] = new_x, new_y
```

```
    else:
```

```
        print("Invalid move.")
```

```
print("Complete")
```

Output :

```
[1, 2, 3]
```

```
[0, 4, 6]
```

```
[7, 5, 8]
```

```
Enter move (up, down, left, right): right
```

```
[1, 2, 3]
```

```
[4, 0, 6]
```

```
[7, 5, 8]
```

```
Enter move (up, down, left, right): down
```

```
[1, 2, 3]
[4, 5, 6]
[7, 0, 8]
-----
```

```
Enter move (up, down, left, right): right
Complete
```

Eight puzzle with heuristic

```
import copy
def swap(arr, x1, y1, x2, y2):
    arr[x1][y1], arr[x2][y2] = arr[x2][y2], arr[x1][y1]

def get_zero_pos(arr):
    for r in range(len(arr)):
        for c in range(len(arr[r])):
            if arr[r][c] == 0:
                return [r, c]
    return None
def print_puzzle(arr):
    for row in arr:
        print(row)
    print("-" * 10)

def count_mismatched_tiles(current_arr, final_arr):
    count = 0
    for r in range(len(current_arr)):
        for c in range(len(current_arr[r])):
            if current_arr[r][c] != final_arr[r][c] and current_arr[r][c] != 0:
                count += 1
    return count

def solve_puzzle_heuristic(initial_arr, final_arr):
    open_list = [(initial_arr, [initial_arr], get_zero_pos(initial_arr))]
    closed_set = set()
    moves = {'up': (-1, 0), 'down': (1, 0), 'left': (0, -1), 'right': (0, 1)}
    while open_list:
        open_list.sort(key=lambda item: count_mismatched_tiles(item[0], final_arr))
        current_arr, path, zero_pos = open_list.pop(0)
        if current_arr == final_arr:
            return path
        current_tuple = tuple(tuple(row) for row in current_arr)
        if current_tuple in closed_set:
            continue
        closed_set.add(current_tuple)
        for move, (dx, dy) in moves.items():
            new_x, new_y = zero_pos[0] + dx, zero_pos[1] + dy
            if 0 <= new_x < 3 and 0 <= new_y < 3:
```

```

        new_arr = copy.deepcopy(current_arr)
        swap(new_arr, zero_pos[0], zero_pos[1], new_x, new_y)
        new_path = path + [new_arr]
        new_zero_pos = [new_x, new_y]
        open_list.append((new_arr, new_path, new_zero_pos))
    return None

initial_state = [[1, 2, 3], [0, 4, 6], [7, 5, 8]]
final_state = [[1, 2, 3], [4, 5, 6], [7, 8, 0]]

print("Initial State:")
print_puzzle(initial_state)

solution_path = solve_puzzle_heuristic(initial_state, final_state)

if solution_path:
    print("Solution Found:")
    for step in solution_path:
        print_puzzle(step)
    print("Complete")
else:
    print("No solution exists for this puzzle.")

```

Output :

Initial State:

[1, 2, 3]
[0, 4, 6]
[7, 5, 8]

Solution Found:

[1, 2, 3]
[0, 4, 6]
[7, 5, 8]

[1, 2, 3]
[4, 0, 6]
[7, 5, 8]

[1, 2, 3]
[4, 5, 6]
[7, 0, 8]

[1, 2, 3]
[4, 5, 6]
[7, 8, 0]

Complete

Program 3

Implement A* search algorithm

classmate
Date _____
Page 14

Manhattan algorithm

1. Start
2. Set all scores (g , h , f)
3. Select lowest f (f) value node
4. Check if selected is goal. If yes, return.
5. Generate valid neighbours, calculate Manhattan distance.
6. Repeat steps 2-5 until the goal is found

Sp 8/9

Output : Misplaced tiles

: Your puzzle	1 2 3
	8 4
	7 6 5

Solution found!

Nodes expanded : 7

Solution : 5 moves

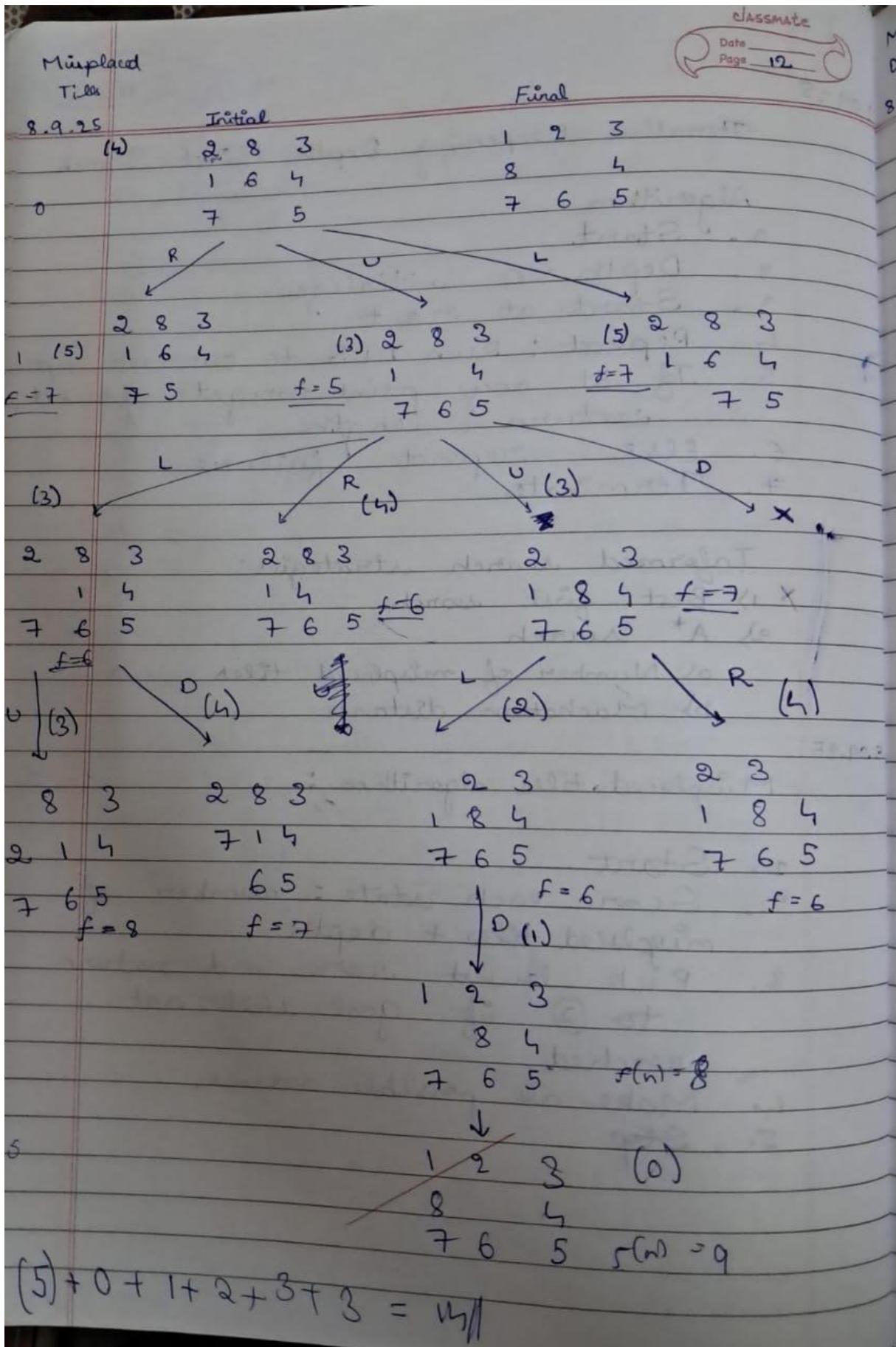
Move UP

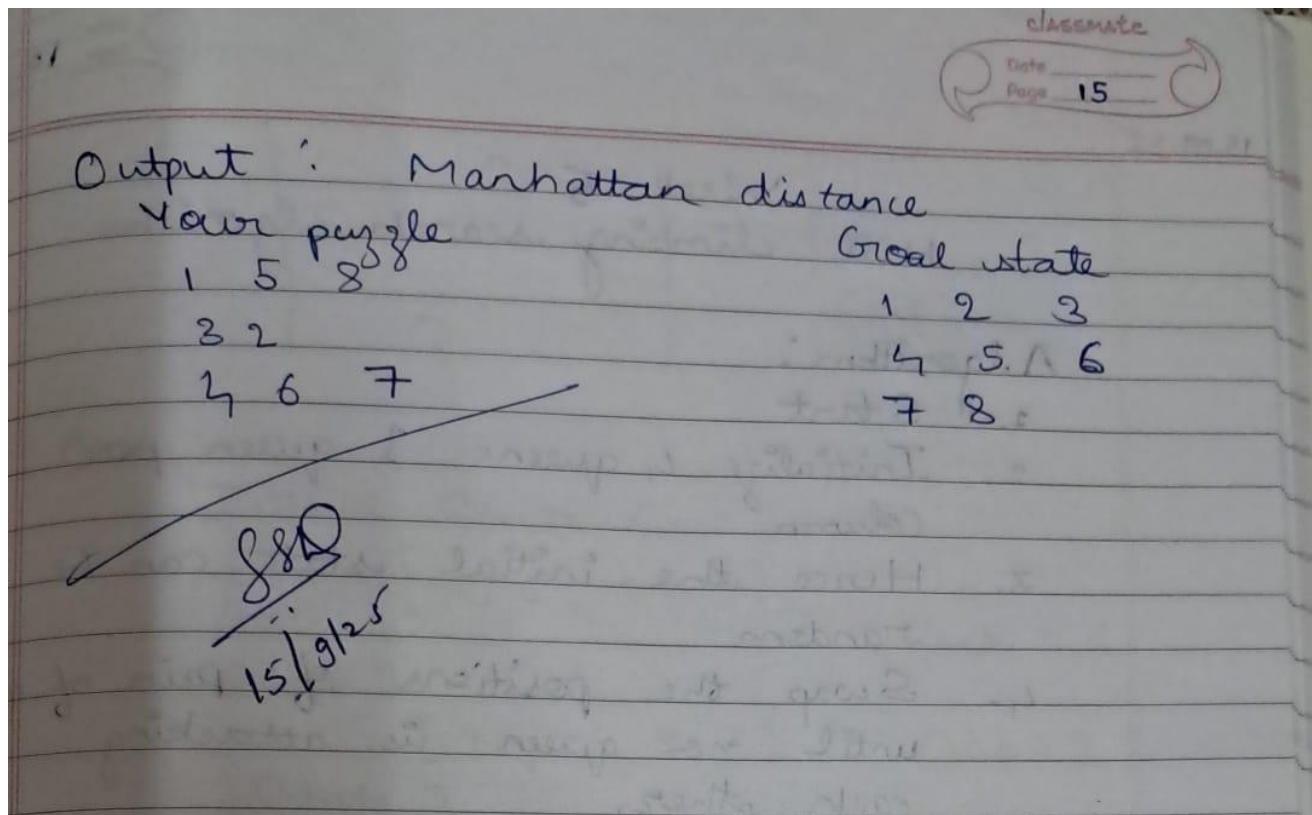
Move UP

Move LEFT

Move DOWN

Move RIGHT





Code :

```

def find_empty(board):
    """Find position of empty tile (0)"""
    for i in range(3):
        for j in range(3):
            if board[i][j] == 0:
                return i, j
    return 0, 0

def is_goal(board, goal_board):
    """Check if current state is goal state"""
    return board == goal_board

def copy_board(board):
    """Create a copy of the board"""
    new_board = []
    for i in range(3):
        row = []
        for j in range(3):
            row.append(board[i][j])
        new_board.append(row)
    return new_board
  
```

```

def get_neighbors(board):
    """Get all possible next states"""
    neighbors = []
    empty_row, empty_col = find_empty(board)

    # Try all 4 directions: up, down, left, right
    directions = [(-1, 0, "UP"), (1, 0, "DOWN"), (0, -1, "LEFT"), (0, 1, "RIGHT")]

    for dr, dc, move_name in directions:
        new_row = empty_row + dr
        new_col = empty_col + dc

        # Check if move is within bounds
        if 0 <= new_row < 3 and 0 <= new_col < 3:
            # Create new board by copying current board
            new_board = copy_board(board)

            # Swap empty tile with adjacent tile
            new_board[empty_row][empty_col] = new_board[new_row][new_col]
            new_board[new_row][new_col] = 0

            neighbors.append((new_board, move_name))

    return neighbors

def misplaced_tiles_heuristic(board, goal_board):
    """Count number of tiles in wrong position"""
    count = 0

    for i in range(3):
        for j in range(3):
            if board[i][j] != 0 and board[i][j] != goal_board[i][j]:
                count += 1

    return count

def manhattan_distance_heuristic(board, goal_board):
    """Calculate Manhattan distance for each tile"""
    # Goal positions for each number
    goal_positions = {}
    for i in range(3):
        for j in range(3):
            goal_positions[goal_board[i][j]] = (i, j)

    total_distance = 0

    for i in range(3):

```

```

for j in range(3):
    if board[i][j] != 0: # Don't calculate for empty tile
        goal_row, goal_col = goal_positions[board[i][j]]
        distance = abs(i - goal_row) + abs(j - goal_col)
        total_distance += distance

return total_distance

def print_board(board):
    """Print the board nicely"""
    print(" ┌─────────┐ ")
    for row in board:
        print(" | ", end="")
        for cell in row:
            if cell == 0:
                print(" ", end="")
            else:
                print(f" {cell} ", end="")
        print(" | ")
    print(" └─────────┘ ")

def board_to_string(board):
    """Convert board to string for comparison"""
    result = ""
    for row in board:
        for cell in row:
            result += str(cell)
    return result

def find_min_f_cost(open_list):
    """Find node with minimum f cost in open list"""
    min_f = float('inf')
    min_index = -1

    for i in range(len(open_list)):
        if open_list[i]['f_cost'] < min_f:
            min_f = open_list[i]['f_cost']
            min_index = i

    return min_index

def reconstruct_path(node):
    """Reconstruct path from goal to start"""
    path = []
    current = node

    while current['parent'] is not None:

```

```

path.append({'board': current['board'], 'move': current['move']})
current = current['parent']

path.reverse()
return path

def a_star_solver(start_board, goal_board, heuristic_type):
    """A* algorithm implementation"""

    # Choose heuristic function
    if heuristic_type == 1:
        heuristic_func = misplaced_tiles_heuristic
        heuristic_name = "Misplaced Tiles"
    else:
        heuristic_func = manhattan_distance_heuristic
        heuristic_name = "Manhattan Distance"

    print(f"\nUsing {heuristic_name} heuristic")
    print("="*40)

    # Check if already solved
    if is_goal(start_board, goal_board):
        print("Puzzle already solved!")
        return

    # Initialize open and closed lists
    open_list = []
    closed_list = []

    # Create start node
    start_node = {
        'board': start_board,
        'g_cost': 0,
        'h_cost': heuristic_func(start_board, goal_board),
        'f_cost': 0,
        'parent': None,
        'move': "START"
    }
    start_node['f_cost'] = start_node['g_cost'] + start_node['h_cost']

    open_list.append(start_node)
    nodes_expanded = 0

    while len(open_list) > 0:
        # Find node with minimum f cost
        current_index = find_min_f_cost(open_list)
        current_node = open_list.pop(current_index)

```

```

closed_list.append(current_node)
nodes_expanded += 1

# Check if goal reached
if is_goal(current_node['board'], goal_board):
    print(f"Solution found! Nodes expanded: {nodes_expanded}")
    print(f"Solution length: {current_node['g_cost']} moves\n")

# Reconstruct and print path
path = reconstruct_path(current_node)

print("Solution path:")
print("Initial state:")
print_board(start_board)

for step, state in enumerate(path):
    print(f"\nStep {step + 1}: Move {state['move']} ")
    print_board(state['board'])

return

# Get neighbors
neighbors = get_neighbors(current_node['board'])

for neighbor_board, move in neighbors:
    # Check if neighbor is in closed list
    neighbor_string = board_to_string(neighbor_board)
    in_closed = False

    for closed_node in closed_list:
        if board_to_string(closed_node['board']) == neighbor_string:
            in_closed = True
            break

    if in_closed:
        continue

    # Calculate costs
    g_cost = current_node['g_cost'] + 1
    h_cost = heuristic_func(neighbor_board, goal_board)
    f_cost = g_cost + h_cost

    # Check if neighbor is in open list with better cost
    in_open = False
    for open_node in open_list:
        if board_to_string(open_node['board']) == neighbor_string:
            if g_cost < open_node['g_cost']:

```

```

        open_node['g_cost'] = g_cost
        open_node['f_cost'] = f_cost
        open_node['parent'] = current_node
        open_node['move'] = move
        in_open = True
        break

# Add to open list if not already there
if not in_open:
    neighbor_node = {
        'board': neighbor_board,
        'g_cost': g_cost,
        'h_cost': h_cost,
        'f_cost': f_cost,
        'parent': current_node,
        'move': move
    }
    open_list.append(neighbor_node)

print("No solution found!")

def get_puzzle_input():
    """Get puzzle input from user"""
    print("Enter your 3x3 puzzle:")
    print("Use 0 for empty tile")
    print("Enter each row (3 numbers separated by spaces):")

    board = []
    for i in range(3):
        while True:
            try:
                row_input = input(f"Row {i+1}: ").strip()
                row = list(map(int, row_input.split()))
            except ValueError:
                print("Please enter exactly 3 numbers")
                continue

            if len(row) != 3:
                print("Please enter exactly 3 numbers")
                continue

            # Check if numbers are valid (0-8)
            valid = True
            for num in row:
                if num < 0 or num > 8:
                    print("Numbers must be between 0 and 8")
                    valid = False
                    break

            if valid:

```

```

        board.append(row)
        break

    except ValueError:
        print("Please enter valid integers")

    return board

def main():
    """Main function"""
    print("="*50)
    print("  A* SLIDING PUZZLE SOLVER")
    print("="*50)

    # Get puzzle input
    puzzle = get_puzzle_input()

    print("\nYour puzzle:")
    print_board(puzzle)

    # Get goal state input
    print("\nEnter your 3x3 goal state:")
    goal_puzzle = get_puzzle_input()

    print("\nYour goal state:")
    print_board(goal_puzzle)

    # Choose heuristic
    print("\nChoose heuristic:")
    print("1. Misplaced Tiles")
    print("2. Manhattan Distance")

while True:
    try:
        choice = int(input("Enter choice (1 or 2): "))
        if choice in [1, 2]:
            break
        else:
            print("Please enter 1 or 2")
    except ValueError:
        print("Please enter a valid number")

    # Solve puzzle
    a_star_solver(puzzle, goal_puzzle, choice)

if __name__ == "__main__":
    main()

```

Output:

Enter your 3x3 puzzle:

Start state:

2 8 3

1 6 4

7 5

Total states visited: 7

Solution found!

Moves: U U L D R

Number of moves: 5

Move 1: U

2 8 3

1 4

7 6 5

$g(n) = 1, h(n) = 3, f(n) = g(n) + h(n) = 4$

Move 2: U

2 3

1 8 4

7 6 5

$g(n) = 2, h(n) = 3, f(n) = g(n) + h(n) = 5$

Move 3: L

2 3

1 8 4

7 6 5

$g(n) = 3, h(n) = 2, f(n) = g(n) + h(n) = 5$

Move 4: D

1 2 3

8 4

7 6 5

$g(n) = 4, h(n) = 1, f(n) = g(n) + h(n) = 5$

Move 5: R

1 2 3

2 7

8 4

7 6 5

$g(n) = 5, h(n) = 0, f(n) = g(n) + h(n) = 5$

Output 2:

Start state:

1 2 3

6 7 8

4 5

Total states visited: 21

Solution found!

Moves: L U L D R R U L D R

Number of moves: 10

Move 1: L

1 2 3

6 7 8

4 5

$g(n) = 1, h(n) = 9, f(n) = g(n) + h(n) = 10$

Move 2: U

1 2 3

6 8

4 7 5

30

$g(n) = 2, h(n) = 8, f(n) = g(n) + h(n) = 10$

Move 3: L

1 2 3

6 8

4 7 5

$g(n) = 3, h(n) = 7, f(n) = g(n) + h(n) = 10$

Move 4: D

1 2 3

4 6 8

7 5

$g(n) = 4, h(n) = 6, f(n) = g(n) + h(n) = 10$

Move 5: R

1 2 3

4 6 8

7 5

$g(n) = 5, h(n) = 5, f(n) = g(n) + h(n) = 10$

Move 6: R

1 2 3

4 6 8

7 5

$g(n) = 6, h(n) = 4, f(n) = g(n) + h(n) = 10$

Move 7: U

1 2 3

4 6

7 5 8

$g(n) = 7, h(n) = 3, f(n) = g(n) + h(n) = 10$

Move 8: L

1 2 3

4 6

7 5 8

$g(n) = 8, h(n) = 2, f(n) = g(n) + h(n) = 10$

31

Move 9: D

1 2 3

4 5 6

7 8

$g(n) = 9$, $h(n) = 1$, $f(n) = g(n) + h(n) = 10$

Move 10: R

1 2 3

4 5 6

7 8

$g(n) = 10$, $h(n) = 0$, $f(n) = g(n) + h(n) = 10$

Program 4

Implement Hill Climbing search algorithm to solve N-Queens problem

Observation:

Date _____
Page 16

Week - 5
Hill climbing search algorithm

Algorithm:

1. Start
2. Initialize 4 queens, 1 queen per column
3. Hence the initial state can be random
4. Swap the positions of pair of queens until no queen is attacking each other.
5. Exit

Cost function is the number of queens attacking each other.

Initial state :

Cost : 6

A 4x4 grid representing the initial state of the 4-queens problem. Queens are placed at (Q1,1), (Q2,2), (Q3,3), and (Q4,4). Arrows point from the second column to the first, third, and fourth rows, indicating attacks between Q2 and Q1, Q2 and Q3, and Q2 and Q4 respectively.

↓

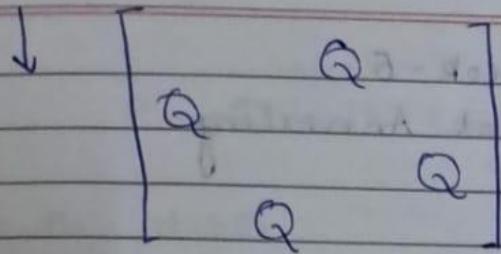
Cost : 2

A 4x4 grid showing a state after one move. Queens are now at (Q1,1), (Q2,3), (Q3,2), and (Q4,4). Arrows point from the second column to the first and third rows, indicating attacks between Q2 and Q1, and Q2 and Q3.

↓

Cost : 1

A 4x4 grid showing the goal state where no two queens are attacking each other. Queens are at (Q1,2), (Q2,4), (Q3,1), and (Q4,3). There are no arrows pointing to any row or column, indicating no attacks.



[Answer]

Cost: 0

Output :

Initial State (random) :

[0, 1, 2, 3]

Cost : 6

State 1 :

[1, 0, 2, 3] Cost = 2

State 2 :

[2, 0, 1, 3] Cost = 1

State 3 :

[2, 0, 3, 1] Cost = 0

~~Goal reached : [2, 0, 3, 1]~~

Q6.09

Code :

import random

def calculate_cost(state):

"""Calculates the number of attacking queen pairs."""

n = len(state)

cost = 0

for i in range(n):

 for j in range(i + 1, n):

 # Check for attacks in the same row or on diagonals

 if state[i] == state[j] or abs(state[i] - state[j]) == abs(i - j):

 cost += 1

```

return cost

def generate_random_state(n=4):
    """Generates a random initial state."""
    return [random.randint(0, n - 1) for _ in range(n)]

def generate_neighbours(state):
    """Generates all neighbours by swapping column positions."""
    n = len(state)
    neighbours = []
    for i in range(n):
        for j in range(i + 1, n):
            neighbour = list(state)
            neighbour[i], neighbour[j] = neighbour[j], neighbour[i]
            neighbours.append(neighbour)
    return neighbours

def hill_climbing_search():
    """Performs hill-climbing search for the 4-Queens problem."""
    current_state = generate_random_state()
    current_cost = calculate_cost(current_state)

    print("Initial State:", current_state, "Cost:", current_cost)

    while current_cost > 0:
        neighbours = generate_neighbours(current_state)
        best_neighbour = None
        best_neighbour_cost = current_cost

        for neighbour in neighbours:
            neighbour_cost = calculate_cost(neighbour)
            if neighbour_cost < best_neighbour_cost:
                best_neighbour_cost = neighbour_cost
                best_neighbour = neighbour

        if best_neighbour_cost < current_cost:
            current_state = best_neighbour
            current_cost = best_neighbour_cost
            print("Chosen Neighbour:", current_state, "Cost:", current_cost)
        else:
            print("No neighbour has a lower cost. Stopping.")
            break

    if current_cost == 0:
        print("Goal reached! Solution:", current_state)

```

Run the hill-climbing search

```
hill_climbing_search()
```

Output :

```
Initial State: [0, 1, 2, 3] Cost: 6
Chosen Neighbour: [1, 0, 2, 3] Cost: 2
Chosen Neighbour: [2, 0, 1, 3] Cost: 1
Chosen Neighbour: [2, 0, 3, 1] Cost: 0
Goal reached! Solution: [2, 0, 3, 1]
```

Program 5

Simulated Annealing to Solve 8-Queens problem

Observation:

CLASSmate
Date _____
Page 18

Week - 5
Simulated Annealing

Algorithm :

1. Start
2. Evaluate cost of current state
3. Generate neighbour, as in by swapping rows randomly.
4. Calculate $\Delta E = \text{current cost} - \text{next cost}$
 $P = e^{\frac{-\Delta E}{T}}$
5. Reduce temperature :
 $T \leftarrow q \times T$
6. Terminate

Output : [6, 5, 9, 10, 7]

Result : Best cost is 5

~~8/9/2021~~
~~15/9/2021~~

Code :

```
import random
import math
```

1. Implement State Representation and Initialization

```
def random_state():
    """Generates a random initial state, ensuring at least one 0."""
    state = [random.randint(0, 7) for _ in range(8)]
    # Ensure at least one 0 in the state
    if 0 not in state:
        state[random.randint(0, 7)] = 0
    return state
```

2. Implement Cost Function

```
def cost_function(state):
    """Calculates the number of attacking queen pairs."""
    attacks = 0
    n = len(state)
    for i in range(n):
        for j in range(i + 1, n):
            # Check for same row
            if state[i] == state[j]:
                attacks += 1
            # Check for diagonals
            elif abs(state[i] - state[j]) == abs(i - j):
                attacks += 1
    return attacks
```

3. Implement Neighbor Generation

```
def get_neighbor(state):
    """Generates a random neighbor state."""
    neighbor = list(state)
    col = random.randint(0, 7)
    row = random.randint(0, 7)
    neighbor[col] = row
    return neighbor
```

4. Implement Simulated Annealing

```
def simulated_annealing(initial_state, initial_temperature=100, cooling_rate=0.95):
    """Performs simulated annealing."""
    current_state = list(initial_state)
    current_cost = cost_function(current_state)
    best_state = list(current_state)
    best_cost = current_cost
    temperature = initial_temperature
```

Added a counter to limit the number of iterations if delta_e never reaches around 1

```

iterations = 0
max_iterations = 10000 # Set a reasonable limit

while temperature > 0 and current_cost > 0 and iterations < max_iterations:
    next_state = get_neighbor(current_state)
    next_cost = cost_function(next_state)

    delta_e = current_cost - next_cost

    # Stop when delta_e is around 1 (e.g., between 0.5 and 1.5)
    if 0.5 <= delta_e <= 1.5:
        #print(f"\nStopping condition met: delta_e is around {delta_e:.2f}") # Commented out for
        cleaner output during multiple runs
        break

if delta_e > 0:
    current_state = list(next_state)
    current_cost = next_cost
    if current_cost < best_cost:
        best_state = list(current_state)
        best_cost = current_cost
    else:
        acceptance_probability = math.exp(delta_e / temperature)
        if random.random() < acceptance_probability:
            current_state = list(next_state)
            current_cost = next_cost

temperature *= cooling_rate
iterations += 1

# Show intermediate updates (commented out for cleaner output during multiple runs)
#print(f"Temperature: {temperature:.4f}, Current Cost: {current_cost}")

#if iterations == max_iterations: # Commented out as we are running multiple times
#    print("\nStopped due to reaching maximum iterations.")

return best_state, best_cost

# 5. Run and Output - Modified to run multiple times
num_runs = 5 # Number of times to run the algorithm
overall_best_state = None
overall_best_cost = float('inf')

print(f"Running Simulated Annealing {num_runs} times...")

```

```

for run in range(num_runs):
    print(f"\n--- Run {run + 1} ---")
    initial_state = random_state()
    best_state, best_cost = simulated_annealing(initial_state)

    print(f"Run {run + 1} Best State Found: {best_state}")
    print(f"Run {run + 1} Best Cost Found: {best_cost}")

    if best_cost < overall_best_cost:
        overall_best_cost = best_cost
        overall_best_state = list(best_state)

    if overall_best_cost == 0:
        print("\nSolution with cost 0 found!")
        break # Stop if a solution with cost 0 is found

print("\n--- Overall Results ---")
print(f"Overall Best State Found: {overall_best_state}")
print(f"Overall Best Cost Found: {overall_best_cost}")

if overall_best_cost == 0:
    print("A solution with cost 0 was found in one of the runs.")
else:
    print("Could not find a solution with cost 0 in the given number of runs.")

```

Output :

Running Simulated Annealing 5 times...

--- Run 1 ---

Run 1 Best State Found: [6, 4, 1, 4, 0, 0, 3, 2]

Run 1 Best Cost Found: 5

--- Run 2 ---

Run 2 Best State Found: [1, 1, 0, 0, 4, 4, 7, 1]

Run 2 Best Cost Found: 9

--- Run 3 ---

Run 3 Best State Found: [5, 1, 6, 1, 3, 5, 2, 0]

Run 3 Best Cost Found: 5

--- Run 4 ---

Run 4 Best State Found: [0, 0, 1, 4, 7, 0, 7, 0]

Run 4 Best Cost Found: 10

--- Run 5 ---

Run 5 Best State Found: [0, 3, 3, 7, 2, 7, 3, 6]

Run 5 Best Cost Found: 5

--- Overall Results ---

Overall Best State Found: [6, 4, 1, 4, 0, 0, 3, 2]

Overall Best Cost Found: 5

Could not find a solution with cost 0 in the given number of runs.

Program 6

Create a knowledge base using propositional logic and show that the given query entails the knowledge base or not.

Observation:

classmate
Date _____
Page 19

Week - 7
Propositional Logic

Truth table

		not	and	or	nor
P	Q	$\neg P$	$P \wedge Q$	$P \vee Q$	$P \Leftrightarrow Q$
false	false	true	false	false	true
false	true	true	false	true	false
true	false	false	false	true	false
true	true	false	true	true	true

$q = A \vee B$ $KB = (A \vee C) \wedge (B \vee \neg C)$

A	B	C	$A \vee C$	$B \vee \neg C$	KB	q
false	false	false	false	true	false	false
false	false	true	true	false	false	false
false	true	false	false	true	false	true
false	true	true	true	true	true	true
true	false	false	true	true	true	true
true	false	true	true	false	false	true
true	true	false	true	true	true	true
true	true	true	true	true	true	true

Algorithm

1. Start
2. Define the knowledgebase and variables
3. Calculate the incremental values in the knowledgebase.
4. Complete the knowledgebase and alpha value
5. Evaluate where $KB \models q$.
6. Print variables where this is true.

99.09.25

Given S, T as variables,

a: $\Gamma(S \vee T)$

b: $(S \wedge T)$

c: $T \vee \Gamma T$

ii) $a \models b$? None

iii) $a \models c$? [False, False]

S	T	a	b	c
False 0	False 0	True	False	True
False	True	False	False	True
True	False	False	False	True
True	True	False	True	True

~~8/9/25~~

Code:

```
from itertools import product
import pandas as pd
```

```
def KB(combo):
    a,b,c = combo
    return ((a or c) and (b or not c))
```

```
def alpha(combo):
    a, b, c = combo
    return a or b
```

```
n = 3
binary = [list(i) for i in product([False, True], repeat=n)]
base = [KB(x) for x in binary]
alpha_values = [alpha(x) for x in binary]
```

```
result = [(base[i] and alpha_values[i]) for i in range(2**n)]  
  
df = pd.DataFrame(binary, columns=[f"V{i+1}" for i in range(n)])  
  
df['KB'] = base  
df['Alpha'] = alpha_values  
df['Final'] = result  
df  
for index, row in df[df['Final'] == True].iterrows():  
    print(row['V1'], row['V2'], row['V3'])
```

Output :

```
False True True  
True False False  
True True False  
True True True
```

Program 7

Implement unification in first order logic

Observation:

classmate
Date _____
Page 21

Week-8
Unification

Algorithm :

Unify (Ψ_1, Ψ_2) :

1. If Ψ_1 or Ψ_2 is variable / constant, then:
 - a) If $\Psi_1 = \Psi_2$ return NIL
 - b) If Ψ_2 is variable,
 - a. if Ψ_1 occurs in Ψ_2 , return FAILURE
 - b. else return $\{(\Psi_2 / \Psi_1)\}$
 - c) Else if Ψ_2 is a variable,
 - a. If Ψ_2 occurs in Ψ_1 return FAILURE
 - b. Else return $\{(\Psi_1 / \Psi_2)\}$
 - d) Else return FAILURE
2. If the initial predicate symbols in Ψ_1 and Ψ_2 are not done, then return FAILURE.
3. If Ψ_1 and Ψ_2 have a different number of arguments, return FAILURE.
4. Set Substitution set (SUBST) to NIL.
5. For i=1 to number of elements in Ψ_1
 - a) Call unify function with the ith element of Ψ_1 and ith element of Ψ_2 and put the result into S.
 - b) If S = failure return S
 - c) If S ≠ NIL then do,
 - a. Apply S to both Ψ_1, Ψ_2 remainder.
 - b. SUBST = APPEND(S, SUBST)

18.10.25

i) Unify $\{\text{Knows}(\text{John}, u), \text{Knows}(\text{John}, \text{lane})\}$
 $\Theta = u/lane$

ii) Unify $\{\text{Knows}(\text{John}, u), \text{Knows}(y, \text{Bill})\}$

$$\Theta = y/\text{John} \quad \text{OR} \quad \Theta = u/\text{Bill}$$

iii) Find Most General Unifier:

$$\left\{ \begin{array}{l} p(b, u, f(g(z))) \\ p(z, f(y), f(y)) \end{array} \right\}$$

$$\Theta = z \leftrightarrow b \quad \text{OR} \quad f(y) \leftrightarrow u \\ \text{OR} \quad y \leftrightarrow z$$

iv) MGU: $\{q(a, g(u, a), f(y)) \text{ and } q(a, g(f(b)), a), u\}$

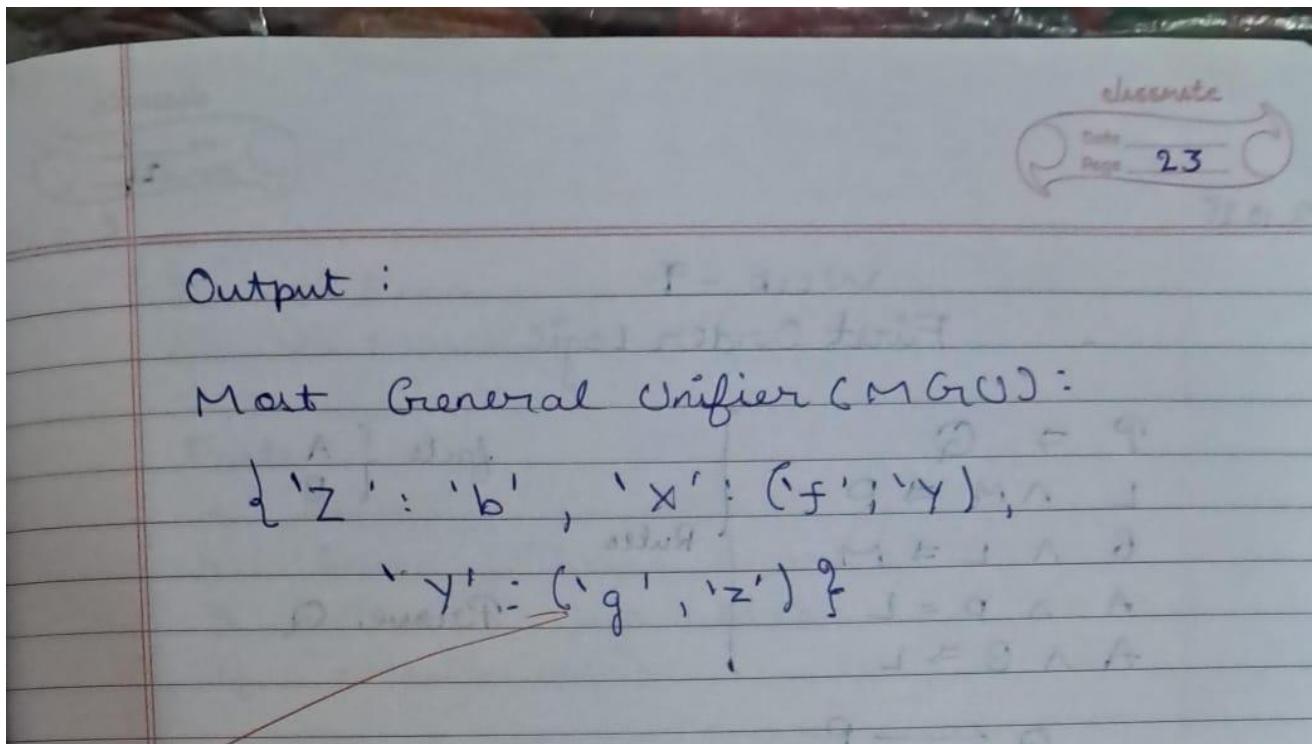
$$u/f(b)/f(y)$$

v) Find MGU: $\{p(f(a), g(y) \text{ and } p(x, x)\}$

$$x/f(a) \mid g(y)$$

vi) Unify $\text{prime}(11)$ and $\text{prime}(y)$
 $y \leftrightarrow 11$

vii) Unify $\{\text{knows}(\text{John}, x), \text{knows}(y, \text{Bill})\}$
 $x \leftrightarrow \text{mother}(y)$
 $y \leftrightarrow \text{mother}(\text{John})$



Code :

```

class UnificationError(Exception):
    pass

def occurs_check(var, term):
    """Check if a variable occurs in a term (to prevent infinite recursion)."""
    if var == term:
        return True
    if isinstance(term, tuple): # Term is a compound (function term)
        return any(occurs_check(var, subterm) for subterm in term)
    return False

def unify(term1, term2, substitutions=None):
    """Try to unify two terms, return the MGU (Most General Unifier)."""
    if substitutions is None:
        substitutions = {}

    # If both terms are equal, no further substitution is needed
    if term1 == term2:
        return substitutions

    # If term1 is a variable, we substitute it with term2
    elif isinstance(term1, str) and term1.isupper():
        # If term1 is already substituted, recurse
        if term1 in substitutions:
            return unify(substitutions[term1], term2, substitutions)

        # If term1 is not yet substituted, make a new substitution
        substitutions[term1] = term2
        return substitutions
    
```

```

        elif occurs_check(term1, term2):
            raise UnificationError(f"Occurs check fails: {term1} in {term2}")
        else:
            substitutions[term1] = term2
            return substitutions

# If term2 is a variable, we substitute it with term1
elif isinstance(term2, str) and term2.isupper():
    # If term2 is already substituted, recurse
    if term2 in substitutions:
        return unify(term1, substitutions[term2], substitutions)
    elif occurs_check(term2, term1):
        raise UnificationError(f"Occurs check fails: {term2} in {term1}")
    else:
        substitutions[term2] = term1
        return substitutions

# If both terms are compound (i.e., functions), unify their parts recursively
elif isinstance(term1, tuple) and isinstance(term2, tuple):
    # Ensure that both terms have the same "functor" and number of arguments
    # if len(term1) != len(term2):
    #     raise UnificationError(f"Function arity mismatch: {term1} vs {term2}")

    for subterm1, subterm2 in zip(term1, term2):
        substitutions = unify(subterm1, subterm2, substitutions)

    return substitutions

else:
    raise UnificationError(f"Cannot unify: {term1} with {term2}")

# Define the terms as tuples
term1 = ('p', 'b', 'X', ('f', ('g', 'Z')))
term2 = ('p', 'Z', ('f', 'Y'), ('f', 'Y'))

try:
    # Find the MGU
    result = unify(term1, term2)
    print("Most General Unifier (MGU):")
    print(result)
except UnificationError as e:
    print(f"Unification failed: {e}")

```

Output :
 Most General Unifier (MGU):
 {'Z': 'b', 'X': ('f', 'Y'), 'Y': ('g', 'Z')}

Program 8

Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

Observation :

classmate
Date _____
Page 24

13.10.25 week - 9
First Order Logic

$P \Rightarrow Q$
 $L \wedge M \Rightarrow P$
 $B \wedge L \Rightarrow M$
 $A \wedge p = L$
 $A \wedge B \Rightarrow L$

Rules facts { A, B }

Prove Q

$Q \leftarrow P$
 $P \leftarrow L$
 $L \leftarrow A \wedge B$
 A B
 $M \leftarrow L$
 $M \leftarrow B$

The law says that it is a crime for an Americans to sell weapons to hostile nations. The country Nono, an enemy of America, has missiles sold to it by Colonel West, an American. An enemy of America is hostile.

Prove that West is criminal.

Rules :

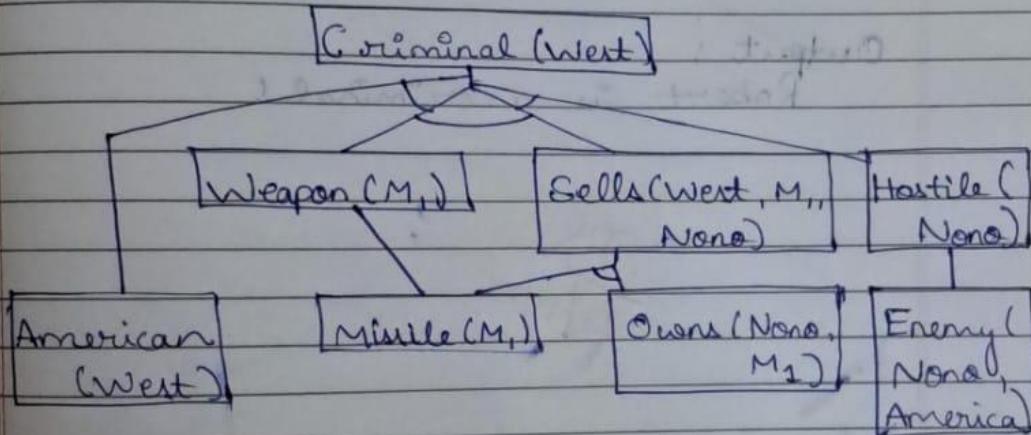
- $\forall x, y, z \text{ American}(x) \wedge \text{Weapon}(y) \wedge \text{Sells}(x, y, z) \wedge \text{Hostile}(z) \Rightarrow \text{Criminal}(x)$
- $\forall x \text{ Missile}(x) \wedge \text{Owens}(Nono, x) \Rightarrow \text{Sells}(\text{West}, x, \text{Nono})$

A.10.25

3. $\forall x \text{Enemy}(x, \text{America}) \Rightarrow \text{Hostile}(x)$
 4. $\forall x \text{Missile}(x) \Rightarrow \text{Weapon}(x)$

Facts :

1. American (West)
2. Enemy (None, America)
3. Owns (None, M1)
4. Missile (M1)



Algorithm:

```

function FOL-FC(KB, q) return a sub of false
  inputs: KB, a
  local variables: new , new sentences inferred
  on each iteration
repeat until new empty
  new  $\leftarrow \{\}$ 
  for each rule in KB do
     $(p_1 \wedge \dots \wedge p_n \Rightarrow q) \leftarrow \text{STANDARDIZE}(\text{rule})$ 
    for each  $\theta$  such  $\text{SUBST}(\theta, p_1 \wedge \dots \wedge p_n) = \text{SUBST}(\theta, p'_1 \wedge \dots \wedge p'_n)$ 
      for some  $p'_1 \dots p'_n$  in KB
  
```

$q' \leftarrow \text{SUBST}(\theta, q)$
 if q' does not unify with some sentence already in KB or new then
 add q' to new
 $\phi \leftarrow \text{UNIFY}(q', a)$
 if ϕ is not fail then return ϕ
 add new to KB
 return false

Output : Robert is a criminal!
 8/6
 13/10/25

Code :

```

def FOL_FC_ASK(KB, alpha):
  # Initialize the new sentences to be inferred in this iteration
  new = set()

  while new: # Repeat until new is empty
    new = set() # Clear new sentences on each iteration

    # For each rule in KB
    for rule in KB:
      # Standardize the rule variables to avoid conflicts
      standardized_rule = standardize_variables(rule)
      p1_to_pn, q = standardized_rule # Premises (p1, ..., pn) and conclusion (q)
  
```

```

# For each substitution  $\theta$  such that  $\text{Subst}(\theta, p_1, \dots, p_n)$  matches the premises
for theta in get_matching_substitutions(p1_to_pn, KB):
    q_prime = apply_substitution(theta, q)

    # If  $q_{\text{prime}}$  does not unify with some sentence already in KB or new
    if not any(unify(q_prime, sentence) != 'FAILURE' for sentence in KB.union(new)):
        new.add(q_prime) # Add  $q_{\text{prime}}$  to new

    # Unify  $q_{\text{prime}}$  with the query ( $\alpha$ )
    phi = unify(q_prime, alpha)
    if phi != 'FAILURE':
        return phi # Return the substitution if it unifies

# Add newly inferred sentences to the knowledge base
KB.update(new)

return False # Return false if no substitution is found

```

```

def standardize_variables(rule):
    """
    Standardize variables in the rule to avoid variable conflicts.
    Rule is assumed to be a tuple (premises, conclusion).
    """
    premises, conclusion = rule
    # Apply standardization logic here (for simplicity, assume no conflict in this case)
    return (premises, conclusion)

```

```

def get_matching_substitutions(premises, KB):
    """
    Get matching substitutions for the premises in the KB.
    This is a placeholder to represent how substitutions would be found.
    """
    # Implement substitution matching here
    return [] # This should return a list of valid substitutions

```

```

def apply_substitution(theta, expression):
    """
    Apply a substitution  $\theta$  to an expression.
    This function will replace variables in expression with their corresponding terms from  $\theta$ .
    """
    if isinstance(expression, str) and expression.startswith('?'):
        return theta.get(expression, expression) # Apply substitution to variable
    elif isinstance(expression, tuple):
        return tuple(apply_substitution(theta, arg) for arg in expression)

```

```

return expression

def unify(psi1, psi2, subst=None):
    """Unification algorithm (simplified)"""
    if subst is None:
        subst = {}

def apply_subst(s_map, expr):
    if isinstance(expr, str) and expr.startswith('?'):
        return s_map.get(expr, expr)
    elif isinstance(expr, tuple):
        return tuple(apply_subst(s_map, arg) for arg in expr)
    return expr

def is_variable(expr):
    return isinstance(expr, str) and expr.startswith('?')

_psi1 = apply_subst(subst, psi1)
_psi2 = apply_subst(subst, psi2)

if is_variable(_psi1) or is_variable(_psi2) or not isinstance(_psi1, tuple) or not isinstance(_psi2, tuple):
    if _psi1 == _psi2:
        return subst
    elif is_variable(_psi1):
        if _psi1 in str(_psi2):
            return 'FAILURE'
        return {**subst, _psi1: _psi2}
    elif is_variable(_psi2):
        if _psi2 in str(_psi1):
            return 'FAILURE'
        return {**subst, _psi2: _psi1}
    else:
        return 'FAILURE'

if _psi1[0] != _psi2[0] or len(_psi1) != len(_psi2):
    return 'FAILURE'

for arg1, arg2 in zip(_psi1[1:], _psi2[1:]):
    s = unify(arg1, arg2, subst)
    if s == 'FAILURE':
        return 'FAILURE'
    subst = s

return subst

```

```

# Knowledge Base (KB)
KB = set()

# Adding facts to KB:
KB.add('american', 'Robert') # Robert is an American
KB.add('hostile_nation', 'Country_A') # Country A is a hostile nation
KB.add('sell_weapons', 'Robert', 'Country_A') # Robert sold weapons to Country A

# Adding the rule (the law):
KB.add((('american(x)', 'hostile_nation(y)', 'sell_weapons(x, y)'), 'criminal(x)')))

# Goal: Prove that Robert is a criminal
goal = 'criminal(Robert)'

# Calling FOL_FC_ASK to prove the goal
result = FOL_FC_ASK(KB, goal)

if result != 'FAILURE':
    print("Robert is a criminal!")
else:
    print("Robert is not a criminal.")

```

Output :
 Robert is a criminal!

Program 9

Create a knowledge base consisting of first order logic statements and prove the given query using Resolution

Observation :

The image shows handwritten notes on a lined notebook page. At the top right, there is a circular stamp with the word "classmate" at the top, "Date _____", and "Page 27" at the bottom. The main title "Resolution in First Order Logic" is written in the center, with "Week - 10" written above it. Below the title, the word "Algorithm" is written. The algorithm steps are listed as follows:

- 1) Convert all sentences to CNF.
- 2) Negate conclusion S & convert resut to CNF.
- 3) Add negated conclusion S to premise clause.
- 4) Repeat until contradiction or no progress is made:
 - Select 2 clauses (call them parent clauses)
 - Resolve them together, performing all required unifications.
 - If resolvent is the empty clause a contradiction has been found.
 - If not, add resolvent to the premises.
- 5) If we succeed in step 4, we have proved the conclusion

Example:

- a. John likes all kind of food
- b. Apple and vegetables are food
- c. Anything anyone eats and not killed is food.
- d. Anil eats peanuts and is alive
- e. Harry eats everything Anil eats
- f. Anyone who is alive implies not killed.

g. Anyone killed is not alive

Prove :

n. John likes peanuts

I

- a) $\forall u : \text{food}(u) \rightarrow \text{likes}(\text{John}, u)$
- b) $\text{food}(\text{Apple}) \wedge \text{food}(\text{vegetables})$
- c) $\forall u \forall y : \text{eats}(u, y) \wedge \neg \text{killed}(u)$
 $\rightarrow \text{food}(y)$
- d) $\text{eats}(\text{Anil}, \text{Peanuts}) \wedge \text{alive}(\text{Anil})$
- e) $\forall u : \text{eats}(\text{Anil}, u) \rightarrow \text{eats}(\text{Harry}, u)$
- f) $\forall u : \neg \text{killed}(u) \rightarrow \text{alive}(u)$
- g). $\forall u : \text{alive}(u) \rightarrow \neg \text{killed}(u)$
- h) $\text{likes}(\text{John}, \text{Peanuts})$

II

- a) $\forall u \neg \text{food}(u) \vee \text{likes}(\text{John}, u)$
- b) ~~$\text{food}(\text{Apple}) \wedge \text{food}(\text{vegetables})$~~
- c) $\forall u \forall y \neg [\text{eats}(u, y) \wedge \neg \text{killed}(u)]$
 $\neg \text{food}(y)$
- d) $\text{eats}(\text{Anil}, \text{Peanuts}) \wedge \text{alive}(\text{Anil})$
- e) $\forall u \neg \text{eats}(\text{Anil}, u) \vee \text{eats}(\text{Harry}, u)$
- f) $\forall u \neg [\neg \text{killed}(u)] \vee \text{alive}(u)$
- g) $\forall u \neg \text{alive}(u) \vee \neg \text{killed}(u)$
- h) $\text{likes}(\text{John}, \text{Peanuts})$

- a) $\forall x \rightarrow \text{food}(x) \vee \text{likes}(\text{John}, x)$
 b) $\text{food}(\text{Apple}) \wedge \text{food}(\text{Vegetables})$
 c) $\forall x \forall y \rightarrow [\text{eats}(x, y) \wedge \neg \text{killed}(x)]$
 $\vee \text{food}(y)$
 d) $\text{eats}(\text{Anil}, \text{Peanuts}) \wedge \text{alive}(\text{Anil})$
 e) $\forall x \rightarrow \text{eats}(\text{Anil}, x) \vee \text{eats}(\text{Harry}, x)$
 f) $\forall x \rightarrow [\neg \text{killed}(x)] \vee \text{alive}(x)$
 g) $\forall x \rightarrow \text{alive}(x) \vee \neg \text{killed}(x)$
 h) $\text{likes}(\text{John}, \text{peanuts})$

- i) a) $\forall x \rightarrow \text{food}(x) \vee \text{likes}(\text{John}, x)$
 b) $\text{food}(\text{Apple}) \wedge \text{food}(\text{Vegetables})$
 c) $\forall x \forall y \rightarrow \text{eats}(x, y) \wedge \neg \text{killed}(x) \vee \text{food}(y)$
 d) $\text{eats}(\text{Anil}, \text{Peanuts}) \wedge \text{alive}(\text{Anil})$
 e) $\forall x \rightarrow \text{eats}(\text{Anil}, x) \vee \text{eats}(\text{Harry}, x)$
 f) $\forall x \neg \text{killed}(x) \vee \text{alive}(x)$
 g) $\forall x \rightarrow \text{alive}(x) \vee \neg \text{killed}(x)$
 h) $\text{likes}(\text{John}, \text{peanuts})$

- j) a) $\neg \text{Food}(x) \vee \text{likes}(\text{John}, x)$
 b) $\neg \text{food}(\text{Apple})$
 c) $\neg \text{food}(\text{Vegetables})$
 d) $\neg \text{eats}(y, z) \vee \neg \text{killed}(y) \vee \neg \text{food}(z)$
 e) $\neg \text{eats}(\text{Anil}, \text{Peanuts}) \vee \neg \text{alive}(\text{Anil})$
 f) $\neg \text{eats}(\text{Anil}, w) \vee \text{eats}(\text{Harry}, w)$
 g) $\neg \text{alive}(x) \vee \neg \text{killed}(x)$
 h) $\text{likes}(\text{John}, \text{peanuts})$

→ likes (John, Peanut)

7 food (Peanut)

$\neg \text{eath}(y, z) \vee \text{killed}(y)$
 $\vee \text{food}(z)$
 $\vee \{\text{Peanuts} / z\}$

death (e.g., Peanut) v. killed (e.g.)

eats (Anil, Peanuts)
{Anil & y }

- killed (Smile)

$\neg \text{alive}(u) \vee \neg \text{killed}(u)$

Talise (Anil)

alone (Anil) {Anil / u }

Output

Hence proved

Anil likes Peanuts

Code :

```
from itertools import combinations

def unify(x, y, theta=None):
    if theta is None:
        theta = {}
    if x == y:
        return theta
    elif isinstance(x, str) and x.islower():
        return unify_var(x, y, theta)
    elif isinstance(y, str) and y.islower():
        return unify_var(y, x, theta)
    elif isinstance(x, tuple) and isinstance(y, tuple) and len(x) == len(y):
        return unify(x[1:], y[1:], unify(x[0], y[0], theta))
    else:
        return None

def unify_var(var, x, theta):
    if var in theta:
        return unify(theta[var], x, theta)
    elif x in theta:
        return unify(var, theta[x], theta)
    else:
        theta[var] = x
        return theta

def negate(predicate):
    if isinstance(predicate, tuple) and predicate[0] == 'not':
        return predicate[1]
    else:
        return ('not', predicate)

def substitute_predicate(predicate, theta):
    if isinstance(predicate, str):
        return theta.get(predicate, predicate)
    elif isinstance(predicate, tuple):
        return (predicate[0],) + tuple(theta.get(arg, arg) for arg in predicate[1:])
    return predicate

def substitute(clause, theta):
    return {substitute_predicate(p, theta) for p in clause}

def resolve(clause1, clause2):
    resolvents = []
    for p1 in clause1:
        for p2 in clause2:
            if p1 == p2:
```

```

theta = unify(p1, negate(p2))
if theta is not None:
    new_clause = (substitute(clause1, theta) | substitute(clause2, theta)) - {p1, p2}
    resolvents.append(frozenset(new_clause))
return resolvents

def resolution(kb, query):
    negated_query = frozenset({negate(query)})
    clauses = kb | {negated_query}
    new = set()

    while True:
        pairs = list(combinations(clauses, 2))
        for (ci, cj) in pairs:
            resolvents = resolve(ci, cj)
            if frozenset() in resolvents:
                return True
            new |= set(resolvents)
        if new.issubset(clauses):
            return False
        clauses |= new

# Knowledge Base
kb = {
    frozenset([('not', ('Food', 'x')), ('Likes', 'John', 'x')]), # a
    frozenset([('Food', 'Apple'))), # b
    frozenset([('Food', 'Vegetables'))), # b
    frozenset([('not', ('Eats', 'x', 'y')), ('Killed', 'x'), ('Food', 'y'))]), # c
    frozenset([('Eats', 'Anil', 'Peanuts'))), # d
    frozenset([('Alive', 'Anil'))), # d
    frozenset([('not', ('Eats', 'Anil', 'x')), ('Eats', 'Harry', 'x')]), # e
    frozenset([('not', ('Alive', 'x')), ('not', ('Killed', 'x'))]), # f
    frozenset([('Killed', 'x'), ('Alive', 'x'))], # g
}
query = ('Likes', 'John', 'Peanuts')

# Run resolution
result = resolution(kb, query)

if result:
    print("Proved by resolution: John likes peanuts.")
else:
    print("Cannot prove that John likes peanuts.")

```

Output :
 Proved by resolution: John likes peanuts.

Program 10

Implement Alpha-Beta Pruning

Observation :

classmate
Date _____
Page _____
31

Week - 11
Alpha- Beta Pruning

Algorithm

function AB-SEARCH return an action
 $v \leftarrow \text{MAX- VALUE}(\text{state}, -\infty, -\infty)$
return the action in ACTIONS
(State) with value v

function MAX- VALUE(State, α , β)
returns a utility value
if TERMINAL- TEST(state) then
return UTILITY(state)
 $v \leftarrow -\infty$
for each a in ACTIONS(state) do
 $v \leftarrow \text{MAX}(v, \text{MIN- VALUE}(\text{RESULT}(s, a), \alpha, \beta))$
 if $v > \beta$ then return v
 $\alpha \leftarrow \text{MAX}(\alpha, v)$
return v

Output:

Best value for maximizer

88
90/10/25

Code :

```

import numpy as np

class Node:
    def __init__(self, value=None, children=None):
        self.value = value
        self.children = children if children else []

    def build_tree_from_array(arr):
        leaves = [Node(value=v) for v in arr.flatten()]
        num_leaves = len(leaves)

        while num_leaves > 1:
            new_level = []
            for i in range(0, num_leaves, 2):
                if i + 1 < num_leaves:
                    new_level.append(Node(None, [leaves[i], leaves[i + 1]]))
                else:
                    new_level.append(leaves[i])
            leaves = new_level
            num_leaves = len(leaves)

        return leaves[0]

    def alpha_beta_pruning(node, depth, alpha, beta, maximizing_player):
        if not node.children or depth == 0:
            return node.value

        if maximizing_player:
            max_eval = float('-inf')
            for child in node.children:
                eval = alpha_beta_pruning(child, depth - 1, alpha, beta, False)
                max_eval = max(max_eval, eval)
                alpha = max(alpha, eval)
                if beta <= alpha:
                    print(f"Pruned at MAX node (α={alpha}, β={beta})")
                    break
            node.value = max_eval
            return max_eval
        else:
            min_eval = float('inf')
            for child in node.children:
                eval = alpha_beta_pruning(child, depth - 1, alpha, beta, True)
                min_eval = min(min_eval, eval)
                beta = min(beta, eval)
                if beta <= alpha:

```

```

        print(f"Pruned at MIN node (\u03b1={alpha}, \u03b2={beta})")
        break
    node.value = min_eval
    return min_eval

def print_tree(node, level=0):
    print(" " * level + f"Node Value: {node.value}")
    for child in node.children:
        print_tree(child, level + 1)

if __name__ == "__main__":
    tree_array = np.array([
        [10, 9],
        [14, 18],
        [5, 4],
        [50, 3]
    ])

    root = build_tree_from_array(tree_array)

    print("Game Tree Before Alpha-Beta Pruning:")
    print_tree(root)

    depth = int(np.log2(tree_array.size))
    final_value = alpha_beta_pruning(root, depth, alpha=float('-inf'), beta=float('inf'),
maximizing_player=True)

    print("\nGame Tree After Alpha-Beta Pruning:")
    print_tree(root)

    print(f"\nFinal Value at MAX node: {final_value}")

```

Output :

Game Tree Before Alpha-Beta Pruning:

Node Value: None

Node Value: None

Node Value: None

Node Value: 10

Node Value: 9

Node Value: None

Node Value: 14

Node Value: 18

Node Value: None

Node Value: None

Node Value: 5

Node Value: 4

Node Value: None

Node Value: 50
Node Value: 3
Pruned at MAX node ($\alpha=14, \beta=10$)
Pruned at MIN node ($\alpha=10, \beta=5$)

Game Tree After Alpha-Beta Pruning:
Node Value: 10
Node Value: 10
Node Value: 10
Node Value: 10
Node Value: 9
Node Value: 14
Node Value: 14
Node Value: 18
Node Value: 5
Node Value: 5
Node Value: 5
Node Value: 4
Node Value: None
Node Value: 50
Node Value: 3

Final Value at MAX node: 10