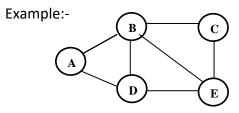
# **Graph Prerequisites**

Graph is a nonlinear data structure, consists of a set of nodes and a set of links. A node is called **vertex**. A link is called the **edge** that connects two vertices. In Graph, relationship among the nodes is less restricted. It means a node can have multiple predecessors.

**Definition:** A Graph G= (V, E) consist of two sets: A set of V of vertices and set E of edges.



[Figure 1: Graph]

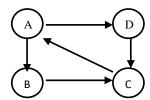
Graph G=(V,E) set V ={A,B,C,D,E} set E = { (A,B), (A,D), (B,C), (B,D), (B,E), ( C,E),(D,E) }

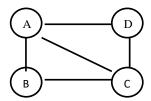
## **Graph Terminology**

#### Directed graph and Un-directed graph:

A graph is called directed graph if each edge is identified by an ordered pair of vertices (vi,vj), such that the edge (vi,vj) connects vertex vi to vertex vj. A directed graph G also called digraph. The graph, in which no such ordered edge exists, is called undirected Graph. So the pair (vi,vj) is equal to (vj,vi).







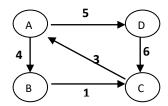
[Figure 2: Directed Graph and Undirected Graph]

#### Adjacent/Incident:

Let there is an edge( $E_i$ ) between two vertices  $V_i$  and  $V_j$  in graph then the vertices  $V_i$  and  $V_j$  are called adjacent and edge  $E_i$  called incident on vertices  $V_i$  and  $V_j$ .

#### Weighted Graph:

A weighted graph is a graph in which edges are assigned with some weights. Weight may be considered as cost or time to travel from one vertex to another.



[Figure 3: Weighted Graph]

#### Degree , Indegree , Outdegree:

The **indegree** of a vertex x is the number of edge with x as their end vertex.

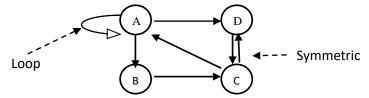
The **out degree** of vertex x is the number of edges whose start vertex is x .

The **degree** of a vertex is the number of edges incident on this vertex. The degree of a vertex x is indegree of x + outdegree of x

Example: In figure 3, indegree(A)=1, outdegree(A)=2, degree(A)=3

**Loop/self loop**: An edge e is called a loop if its two end points are same. If an edge connected two vertices Vi and Vj where i=j, then the edge is called the Loop.

**Symmetric:** A directed graph is called symmetric if the existence of an edge from  $V_i$  to  $V_j$  implies that there must also be an edge directed from  $V_i$  to  $V_i$ .



[Figure 4: Graph having Loop and symmetric]

**Parallel edge:** If there is more than one edge exist between same pair of vertices, then they are called parallel edge.

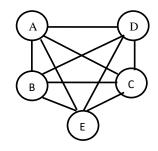
**Path:** Path is a sequence of vertices in graph in which each vertex is adjacent to next vertex. The length of such path is the number of edges in that path.

**Cycle:** A path in which the start vertex and end vertex are the same called cycle. A cycle consist of minimum of 3 vertices.

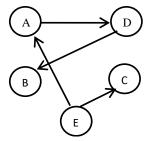
Directed Acyclic graph (DAG): A directed graph having no cycle is called DAG or Tree

**Tree:** It can be defined as a connected graph without any cycle.

**Complete Graph:** A graph is said to be complete if each and every pair of vertices are adjacent. For a complete graph with N number of vertices, number of edge=  $(N \times (N-1))/2$ 



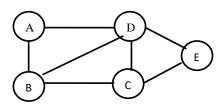
[Figure 5: Complete Graph]

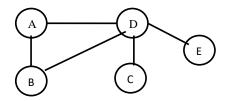


[Figure 6: DAG]

#### **Sub Graph**

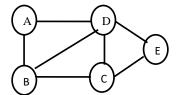
A graph G' = (V', E') is called sub graph of G = (V, E) if  $V' \in S$  and  $E' \in E$ . For G' to be a sub graph of G, all the edges and vertices of G' should be in G.

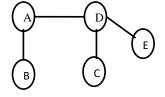


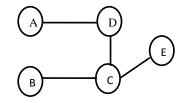


[Figure 7: The Graph G and its sub graph]

**Spanning tree:** A sub graph of a graph (G) which is a tree containing all the vertices of G is called spanning tree. The spanning tree, where the sum of weight of all the edges is minimum, it is called minimal cost of spanning tree.







[Figure 8: The Graph G and its two Spanning Trees]

## **Representation of Graph**

A. Sequential Representation: 1. Adjacency Matrix

2. Incidence Matrix

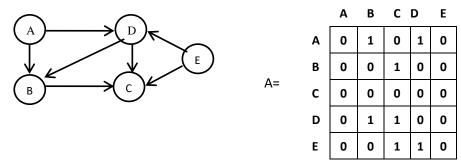
B. Linked List Representation: 3. Adjacency List

### 1. Adjacency Matrix:

Suppose G is a simple directed graph with N vertices and the vertices have been ordered as v1, v2,..., vn. Then the adjacency matrix A is an N X N matrix, where each element  $A_{ij}$  is defined as follows:

$$A_{ij} = \left\{ \begin{array}{ll} 1 & \quad \text{if there is an edge ($v_i$,$v_j$) from vertex $v_i$ to vertex $v_j$} \\ 0 & \quad \text{otherwise} \end{array} \right.$$

If the graph is undirected, then the adjacency matrix is symmetric, i,e Aij = Aji Example:



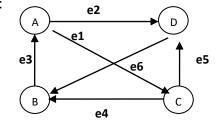
[Figure 9: The Directed graph and its adjacency matrix A]

#### Incidence matrix:

Incidence matrix (I) for a Graph G=(V,E) is a  $|V| \times |E|$  matrix whose elements are 0,1 or -1. An edge Ek between  $V_i$  to  $V_j$  means

 $I[V_i, E_k] = 1$ ,  $I[V_j, E_k] = 0$  and rest of the cells in  $E_k$  column are set to 0.

Example:



	<b>e1</b>	e2	е3	e4	е5	e6
Α	1	1	-1	0	0	0
В	0	0	1	-1	0	-1
С	-1	0	0	1	1	0
D	0	-1	0	0	-1	1

[Figure 10: The directed Graph and its incidence Matrix]

### Path Matrix/ Reachability Matrix:

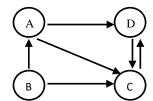
Let G be a simple directed graph with M nodes, v1,v2,...,vm. The path matrix or reachability matrix of G is the M X M matrix P where Pij defined as follows:

$$P_{ij} = \begin{cases} 1 & \text{if there is a path from } v_i \text{ to } v_j \\ \\ 0 & \text{Otherwise} \end{cases}$$

Path Matrix is computed as follows:

Let A be the adjacent matrix of a graph, then  $A_{ij}^k$  that is, the entry in i<sup>th</sup> row and j<sup>th</sup> column of Matrix  $A_k$  gives the number of path of path length k from  $V_i$  to  $V_j$ .

Example: For following Graph We need to compute Path matrix



	Α	В	C D	
Α	0	0	1	1
В	1	0	1	0
C	0	0	0	1
D	0	0	1	0

A: Path Matrix of path length 1 (Same as the adjacency Matrix A)

	Α	В	С	D
Α	0	0	1	1
В	0	0	2	1
r	0	0	0	1

A<sup>3</sup>: Path Matrix of path length 3

	Α	В	С	D
Α	0	0	1	1
В	0	0	1	2
С	0	0	1	0
D	0	0	0	1

A2: Path Matrix of path length 2

	Α	В	C D	
Α	0	0	1	1
В	0	0	1	2
c	0	0	1	0
D	0	0	0	1

A4: Path Matrix of path length 4

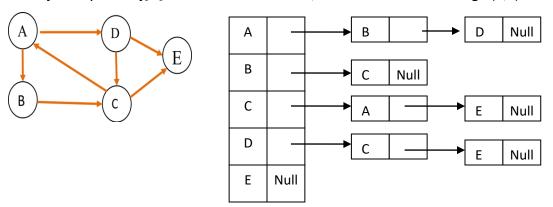
Let the Matrix  $Bk = A + A^2 + A^3 + A^4$ , then  $B^k[i,j]$  gives number of path of length k or less from node Vi to Vj.

Then The Path Matrix can be defined as

$$Pij= \begin{cases} 1, & \text{if } B^{k}[i,j] >= 1 \\ \\ 0, & \text{if } B^{k}[i,j] = 0 \end{cases}$$

## 3. Adjacency List

Adjacency List consists of |V| number of linked list, one list for each vertex. For each vertex V, the adjacency list Adj[U] contains all vertices V, such that there is an edge  $(u,v) \in Set E$ 



For a directed graph, number of nodes = |V| + |E| For a Undirected graph, number of nodes = |V| + 2 \* |E|