





Out[23]: (-0.5, 235.5, 184.5, -0.5)



### Question 5.a

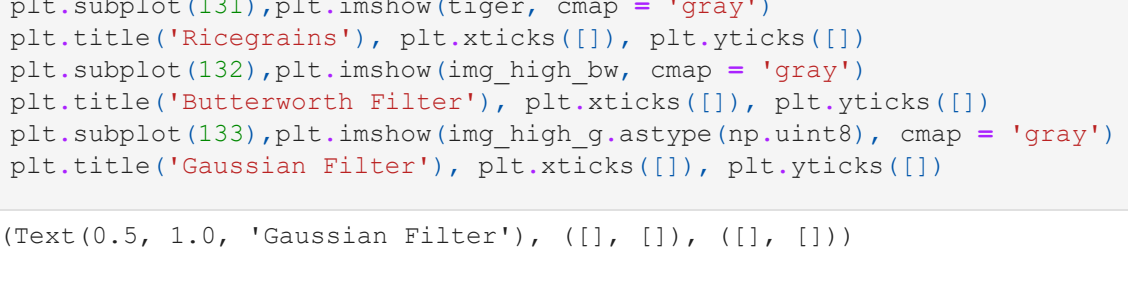
```
In [24]: #unsharp masking
K=1.5
kernel = cv2.getGaussianKernel(5, 5)
blurred = cv2.filter2D(tiger, -1, kernel * kernel.T)
mask = tiger-blurred
tiger_um = tiger + K*mask

#Sobel Edge Detector
sobel_x = cv2.Sobel(tiger, cv2.CV_64F, 1, 0, ksize=3)
sobel_y = cv2.Sobel(tiger, cv2.CV_64F, 0, 1, ksize=3)
sobel = np.sqrt(sobel_x**2 + sobel_y**2)
sobel = np.uint8(sobel)

#Laplace Edge detector
blur = cv2.GaussianBlur(tiger, (3, 3), 0)
laplace = cv2.Laplacian(blur, cv2.CV_64F)
laplace = np.uint8(np.absolute(laplace))
```

```
In [25]: plt.figure(figsize=(10, 10))
plt.subplot(141),plt.imshow(tiger, cmap = 'gray')
plt.title('Tiger'), plt.xticks([],), plt.yticks([])
plt.subplot(142),plt.imshow(tiger_um, cmap = 'gray')
plt.title('Unsharp Masking'), plt.xticks([],), plt.yticks([])
plt.subplot(143),plt.imshow(sobel, cmap = 'gray')
plt.title('Sobel Edge Detector'), plt.xticks([],), plt.yticks([])
plt.subplot(144),plt.imshow(laplace, cmap = 'gray')
plt.title('Laplace Edge Detector'), plt.xticks([],), plt.yticks([])
```

Out[25]: (Text(0.5, 1.0, 'Laplace Edge Detector'), ((), ()), ((), ()))



### Question 5.b

```
In [26]: #Butterworth highpass frequency filter

#fourier transform of the image
fshift_bw = np.fft.fftfshift(np.fft.fft2(tiger))
h,w = tiger.shape
img_high_bw = np.zeros((h,w))
K_high_bw = np.zeros((h,w))

for i in range(h):
    for j in range(w):
        dist = np.sqrt((i-h/2)**2 + (j-w/2)**2)
        K_high_bw[i,j] = 1/(1+(dist/20)**(2*4))
img_high_bw = np.abs(np.fft.ifft2(fshift_bw*(1-K_high_bw)))
```

```
In [27]: #Gaussian highpass frequency filter

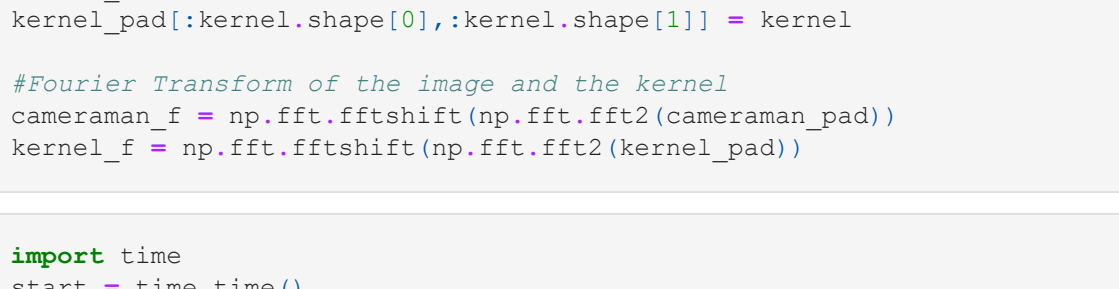
#fourier transform of the image
fshift_g = np.fft.fftfshift(np.fft.fft2(tiger))
h,w = tiger.shape
img_high_g = np.zeros((h,w))
K_high_g = np.zeros((h,w))

for i in range(h):
    for j in range(w):
        dist = np.sqrt((i-h/2)**2 + (j-w/2)**2)
        K_high_g[i,j] = np.exp(-(dist/(2*(20**2))))

img_high_g = np.abs(np.fft.ifft2(fshift_g*(1-K_high_g)))
```

```
In [28]: plt.figure(figsize=(10, 10))
plt.subplot(131),plt.imshow(tiger, cmap = 'gray')
plt.title('Ricegrains'), plt.xticks([],), plt.yticks([])
plt.subplot(132),plt.imshow(img_high_bw, cmap = 'gray')
plt.title('Butterworth Filter'), plt.xticks([],), plt.yticks([])
plt.subplot(133),plt.imshow(img_high_g.astype(np.uint8), cmap = 'gray')
plt.title('Gaussian Filter'), plt.xticks([],), plt.yticks([])
```

Out[28]: (Text(0.5, 1.0, 'Laplace Filter'), ((), ()), ((), ()))

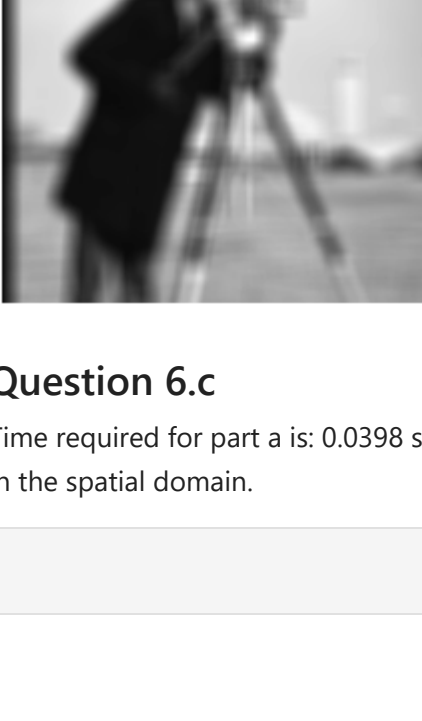


### Question 6

```
In [29]: #loading and plotting the image
cameraman = cv2.imread("cameraman.jpg", cv2.IMREAD_GRAYSCALE)

plt.imshow(cameraman, "gray")
plt.axis("off")
```

Out[29]: (-0.5, 224.5, 224.5, -0.5)



### Question 6.a

```
In [38]: #average filter of size 11*11
kernel_size = (11, 11)
kernel = np.ones(kernel_size, np.float32) / (kernel_size[0] * kernel_size[1])
from scipy.signal import convolve2d
```

```
In [41]: import time
start = time.time()
#applying the average filter
avg = convolve2d(cameraman, kernel, mode="same")
end = time.time()
print(end-start)

0.0398249626159668
```

```
In [32]: #plotting the result
plt.imshow(avg, 'gray')
```

Out[32]: <matplotlib.image.AxesImage at 0x224117ac250>



### Question 6.b

```
In [33]: #padding the image and the kernel
P,Q = 2*cameraman.shape[0],2*cameraman.shape[1]
cameraman_pad = np.zeros((P,Q), dtype=np.uint8)
cameraman_pad[cameraman.shape[0]:cameraman.shape[1]] = cameraman
kernel_pad = np.zeros((P,Q), dtype=np.float32)
kernel_pad[kernel.shape[0]:kernel.shape[1]] = kernel

#Fourier Transform of the image and the kernel
cameraman_f = np.fft.fftfshift(np.fft.fft2(cameraman_pad))
kernel_f = np.fft.fftfshift(np.fft.fft2(kernel_pad))
```

```
In [40]: import time
start = time.time()
#multiplying them
multi = np.multiply(cameraman_f, kernel_f)
end = time.time()
print(end-start)

0.008026123046875
```

```
In [35]: #Inverse Fourier transform
cameraman_if = np.abs(np.fft.ifft2(multi))

#useful content of transformed image
cameraman_cut = cameraman_if.astype(np.uint8)[:cameraman.shape[0]:cameraman.shape[1]]
```

```
In [36]: #plotting the transformed image
plt.imshow(cameraman_cut, "gray")
plt.axis("off")
```

Out[36]: (-0.5, 224.5, 224.5, -0.5)



### Question 6.c

Time required for part a is 0.0398 s and for part b is 0.008026 s \ Multiplication in the frequency domain is 5 times faster than Convolution in the spatial domain.

In [ ]: