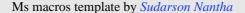
## **Table of Contents**

1. First Section	•		•	•	•	•	•		•	•	•	•	•	•	•	•	•	•	•	•	•	1
1.1. Pythogoram Theorem .																						1
2. Second Section																						
2.1. Subsection	•	٠	•		•	•		٠		٠	•			•		•	•		•	•		1
3. Last Section																						3
3.1. Links using .pdfhref .																						3
3.1.1. Internet Hyperlinks																						3
3.1.2. PDF links																						3
3.2. Table example																						3
List of Equations																						4
List of Figures																						5
List of Tables																						6



## Welcome to Groff

GNU troff (groff) - a GNU project





#### 1. First Section

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**Here is proof that forward referencing works.** Figure 2.1.1 shows an old monument in Bharathi Park, Pondicherry.

### 1.1. Pythogoram Theorem

This theorem states that given a triangle with sides a, b, and  $c \Rightarrow a^2 + b^2 = c^2$ 

#### 2. Second Section

Here, we take a look at indentation<sup>[1]</sup>

#### 2.1. Subsection

- Bullet point 1
- Bullet point 2

$$f(x) = 5x + 3 \tag{2.1.1}$$

$$e^{(i}\theta) = 1 + e^{(i}\theta) + \frac{1}{2!}(i\theta)^{2...}$$
(2.1.2)

$$+\frac{1}{N-1}(i\theta)^{N-1}+\frac{1}{N}(i\theta)^{N}$$

$$K_{e} = \int_{T_{e}} K \begin{bmatrix} (c_{1}^{k})^{2} & x_{k} & y_{k} \\ (c_{1}^{l})^{2} & x_{l} & y_{l} \\ (c_{1}^{m})^{2} & x_{m} & y_{m} \end{bmatrix} d\Omega$$
(2.1.3)

def myfunction(arg):
 arg = arg\*\*2 - arg + 1
 return int(arg)



Figure 2.1.1 This is a nice caption



This logo won't have a figure number



**Figure 2.1.2** 

### 3. Last Section

In this section, we will look at tables and PDF links. [2]

## 3.1. Links using .pdfhref

## 3.1.1. Internet Hyperlinks

Here is an internet hyperlink to the Groff Manual where you can find documentation for groff. Youtube is a great website for informational videos

### 3.1.2. PDF links

Affixed text to Equation (2.1.1) is the first equation

Fig(2.1.2) is the MSI logo

Table(3.2.1) contains the specs for carburetors found in Yamaha DT 125 motorcycle.

Notice that this does forward referencing.

## 3.2. Table example

Yamaha DT 125 Carburetor Specifications									
Bike Model	TZR	DT 3DBI	DT 3RN1 onward						
Make	Mikuni	Mikuni	Mikuni						
Туре	VM26SS	VM26SS	VM26SS						
ID Mark	2RH00	3BN00	3MB00						
Main Jet	180	125	210						
Air Jet	0.8	0.8	0.8						
Jet Needle	406	407	5J25						
Needle clip position	4th	3rd	4th						
Float height - all models	20-21mm (0.787-0.827in)								

 Table 3.2.1 Carburetor specifications for Yamaha DT 125

# **List of Equations**

Equation Number	Page No.
1. A linear equation (2.1.1)	1
2. A long mathematical series (2.1.2)	1
3. Example matrix equation (2.1.3)	1

# **List of Figures**

Figure Number	Page No.
1. This is a nice caption (Fig. 2.1.1)	2
2. Figure 2.1.2	2

## **List of Tables**

Table	Page No.
1. Carburetor specifications for Yamaha DT 125 (Table 3.2.1)	3

#### References

- 1. M O Tatar and A Pop, "Development of an in pipe inspection minirobot," *IOP Conf. Series: Materials Sceince and Engineering* **147** (2016).
- 2. By Atsushi Kakogawa and Shugen Ma, "Robotic Search and Resque through In-Pipe Movement" in *Unmanned Robotic Systems and Applications*, ed. Mahmut Reyhanglu and Geert De Cubber (2019).