

# Sequence to Sequence Models with Attention

Mausam

(Slides by Yoav Goldberg, Graham Neubig, Prabhakar Raghavan)

# BACKGROUND

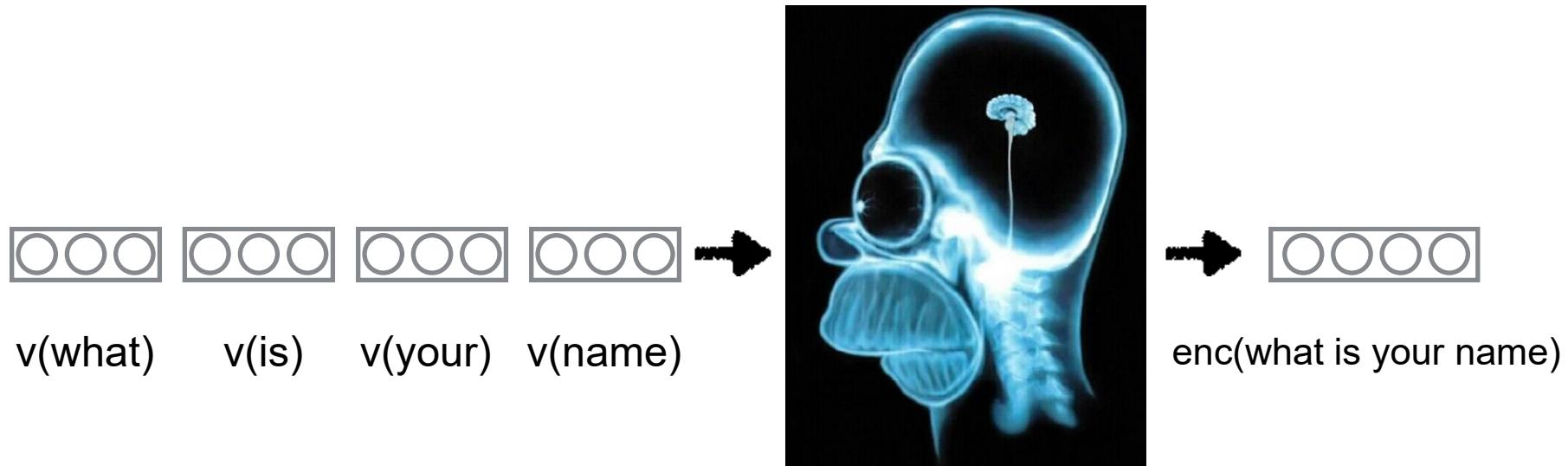
# A Primer on D.L. Building Blocks

- A single vector for an ordered pair of vectors? •  $x; y$
- A single vector for a variable-sized bag of vectors? •  $\sum_i x_i$
- Project a vector to a new space? •  $Wx$
- Are two vectors (from same space) similar? •  $x.y$
- Are two vectors (from different space) similar? •  $xWy$
- A new vector that depends on some vector input? •  $g(Wx+b)$

# A Primer on D.L. Building Blocks

- Output a probability •  $\sigma$
- Output one of two classes •  $\sigma$
- Output one of many classes • softmax
- A feature w/ positive & negative influence • tanh
- A feature w/ positive influence for “deep” nets • ReLu

# Recurrent Neural Networks



- Very strong models of sequential data.
- **Trainable** function from  $n$  vectors to a single vector.

# Recurrent Neural Networks

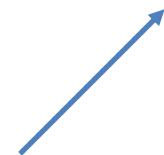
$$RNN(\mathbf{s}_0, \mathbf{x}_{1:n}) = \mathbf{s}_n, \mathbf{y}_n$$

$$\mathbf{x}_i \in \mathbb{R}^{d_{in}}, \mathbf{y}_i \in \mathbb{R}^{d_{out}}, \mathbf{s}_i \in \mathbb{R}^{f(d_{out})}$$

- Very strong models of sequential data.
- **Trainable** function from  $n$  vectors to a single\* vector.

# Recurrent Neural Networks

$$RNN(\mathbf{s}_0, \mathbf{x}_{1:n}) = \mathbf{s}_n, \mathbf{y}_n$$



\*this one is internal. we only care about the  $\mathbf{y}$

$$\mathbf{x}_i \in \mathbb{R}^{d_{in}}, \mathbf{y}_i \in \mathbb{R}^{d_{out}}, \mathbf{s}_i \in \mathbb{R}^{f(d_{out})}$$

- Very strong models of sequential data.
- **Trainable** function from  $n$  vectors to a single\* vector.

# Recurrent Neural Networks

$$RNN(\mathbf{s_0}, \mathbf{x_{1:n}}) = \mathbf{s_n}, \mathbf{y_n}$$

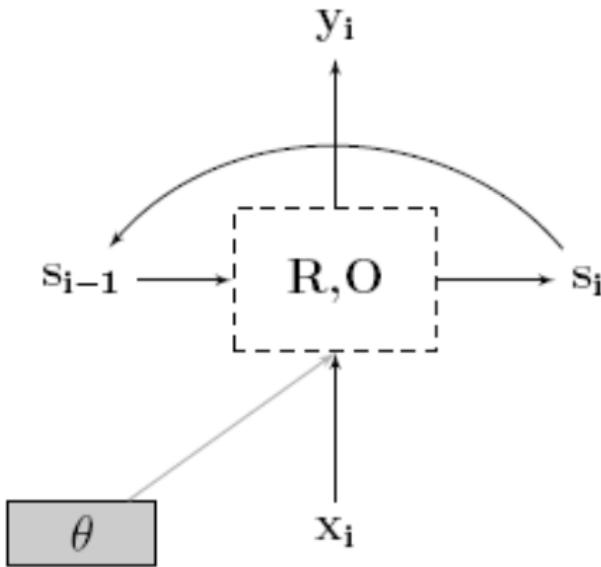
$$\mathbf{s_i} = R(\mathbf{s_{i-1}}, \mathbf{x_i})$$

$$\mathbf{y_i} = O(\mathbf{s_i})$$

$$\mathbf{x_i} \in \mathbb{R}^{d_{in}}, \mathbf{y_i} \in \mathbb{R}^{d_{out}}, \mathbf{s_i} \in \mathbb{R}^{f(d_{out})}$$

- **Recursively defined.**
- There's a vector  $\mathbf{y_i}$  for every prefix  $\mathbf{x_{1:i}}$

# Recurrent Neural Networks



$$RNN(s_0, x_{1:n}) = s_n, y_n$$

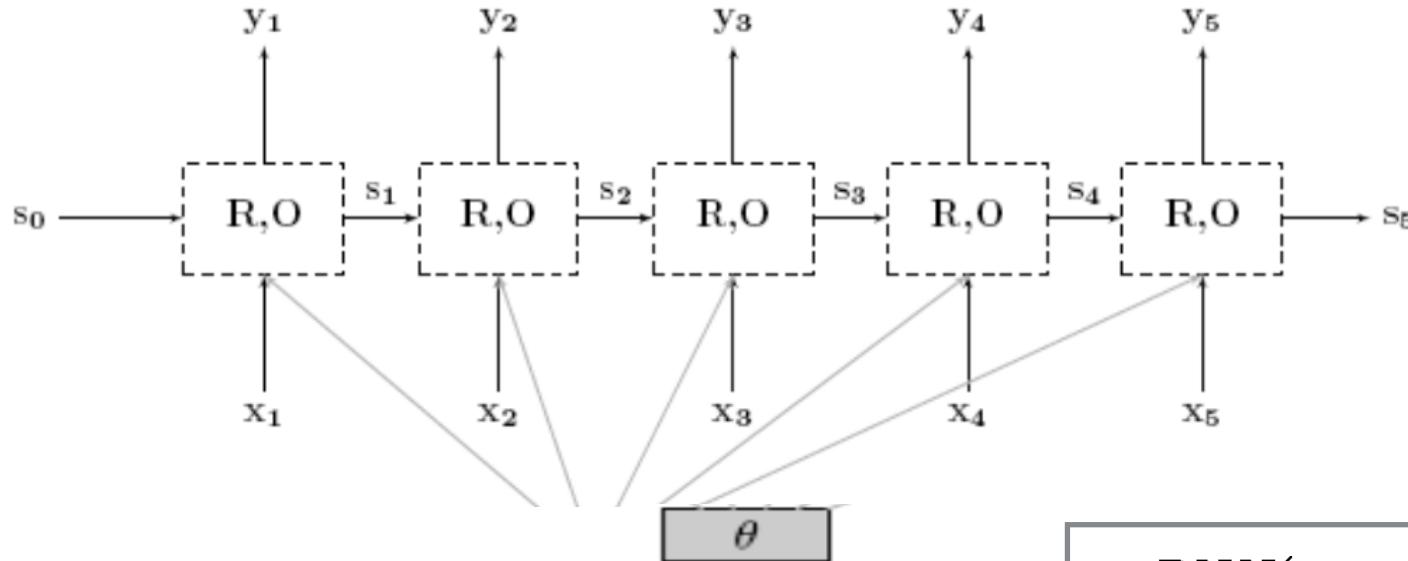
$$s_i = R(s_{i-1}, x_i)$$

$$y_i = O(s_i)$$

$$x_i \in \mathbb{R}^{d_{in}}, y_i \in \mathbb{R}^{d_{out}}, s_i \in \mathbb{R}^{f(d_{out})}$$

- **Recursively defined.**
- There's a vector  $y_i$  for every prefix  $x_{1:i}$

# Recurrent Neural Networks



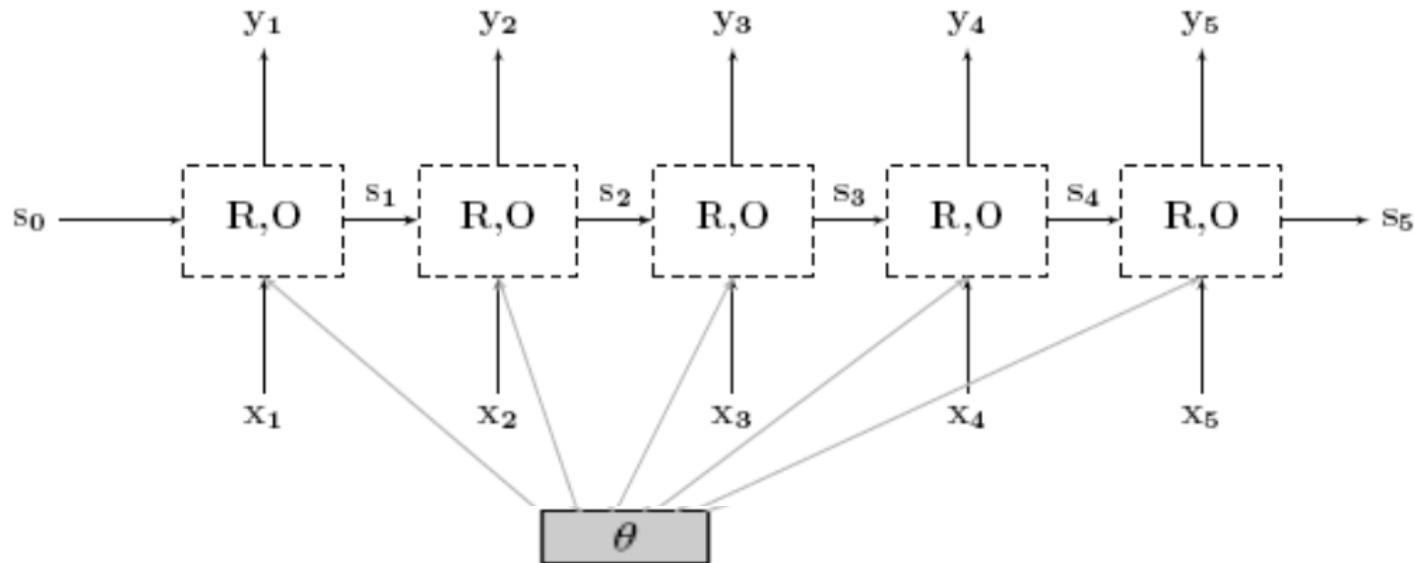
for every finite input sequence,  
can unroll the recursion.

- Recursively defined.
- There's a vector  $\mathbf{y}_i$  for every prefix  $\mathbf{x}_{1:i}$

$$\begin{aligned} RNN(\mathbf{s}_0, \mathbf{x}_{1:n}) &= \mathbf{s}_n, \mathbf{y}_n \\ \mathbf{s}_i &= R(\mathbf{s}_{i-1}, \mathbf{x}_i) \\ \mathbf{y}_i &= O(\mathbf{s}_i) \end{aligned}$$

$$\mathbf{x}_i \in \mathbb{R}^{d_{in}}, \mathbf{y}_i \in \mathbb{R}^{d_{out}}, \mathbf{s}_i \in \mathbb{R}^{f(d_{out})}$$

# Recurrent Neural Networks



for every finite input sequence,  
can unroll the recursion.

State  $s_i$  encodes **history** till this point

# Simple RNN (Elman RNN)

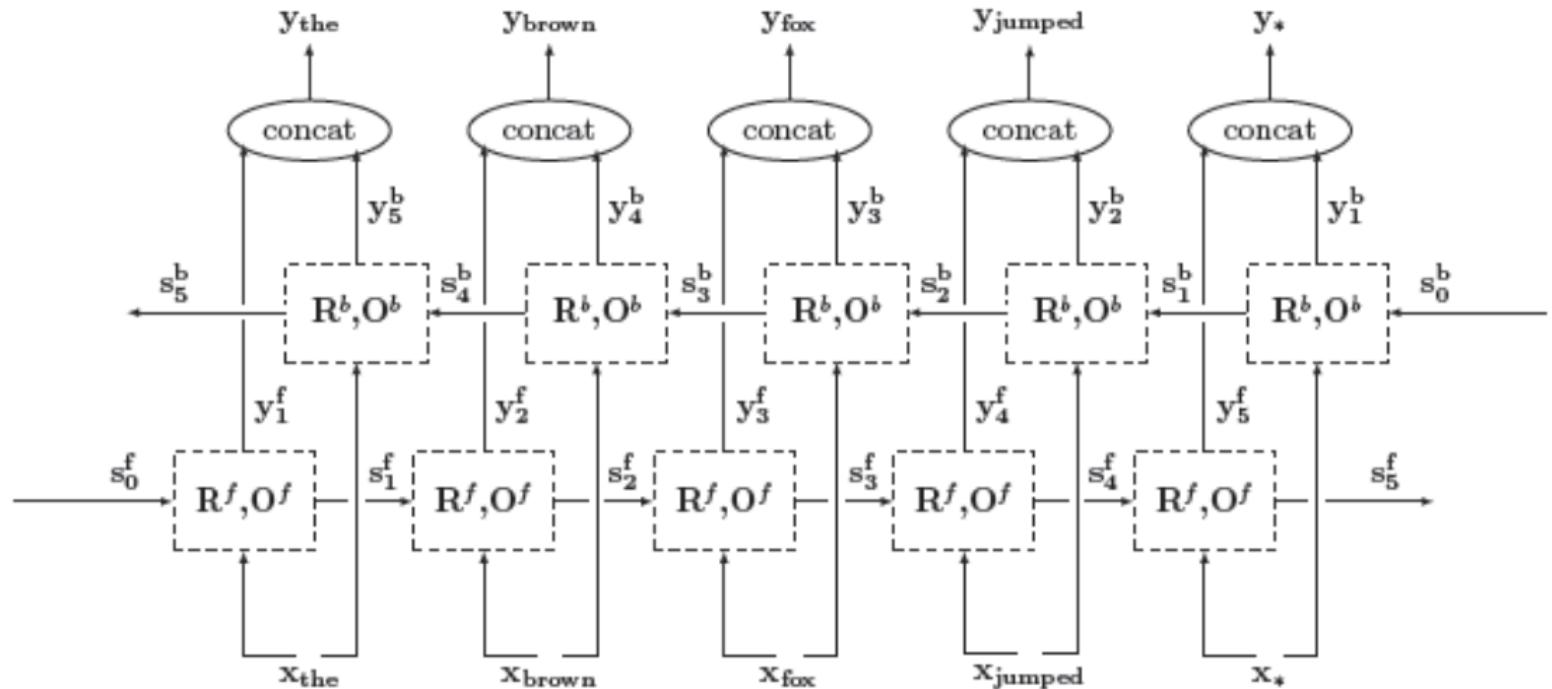
$$R_{SRNN}(\mathbf{s}_{i-1}, \mathbf{x}_i) = \tanh(\mathbf{W}^s \cdot \mathbf{s}_{i-1} + \mathbf{W}^x \cdot \mathbf{x}_i)$$

In principle: capture infinite history upto this point  
In practice: have issues with long sequences

RNN → LSTM

Good for backpropagating through long chain sequences

# Bidirectional RNNs

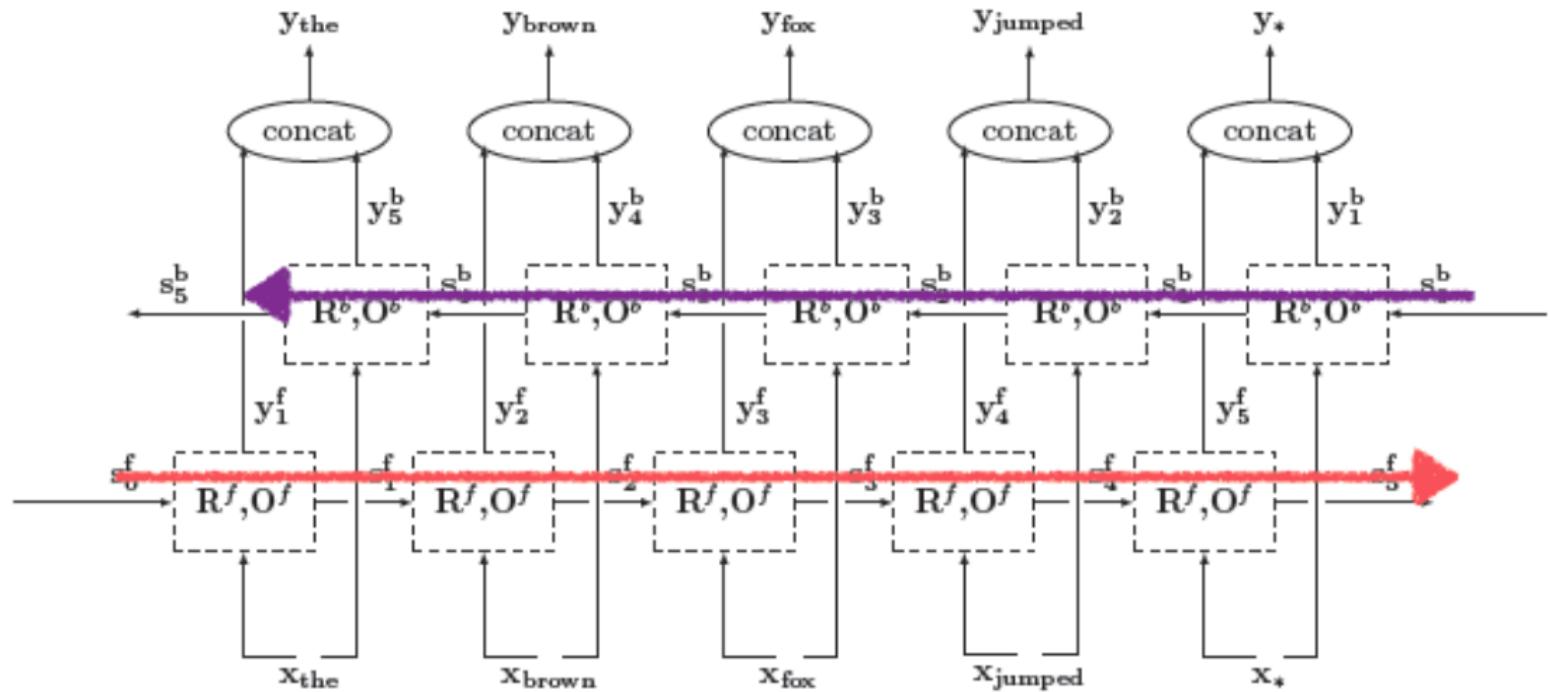


One RNN runs left to right.

Another runs right to left.

Encode **both future and history** of a word.

# Bidirectional RNNs



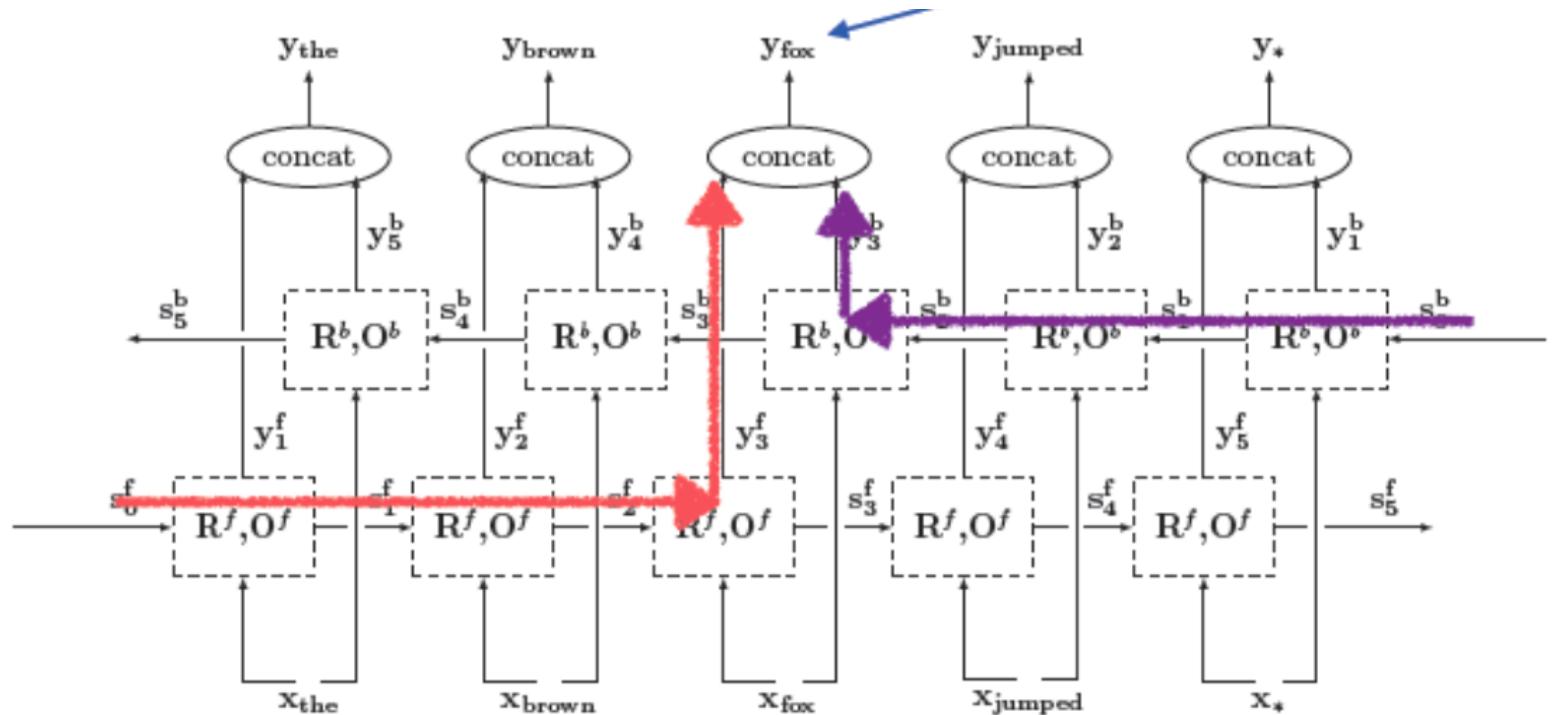
One RNN runs left to right.

Another runs right to left.

Encode **both future and history** of a word.

# Bidirectional RNNs

Infinite window around the word



One RNN runs left to right.

Another runs right to left.

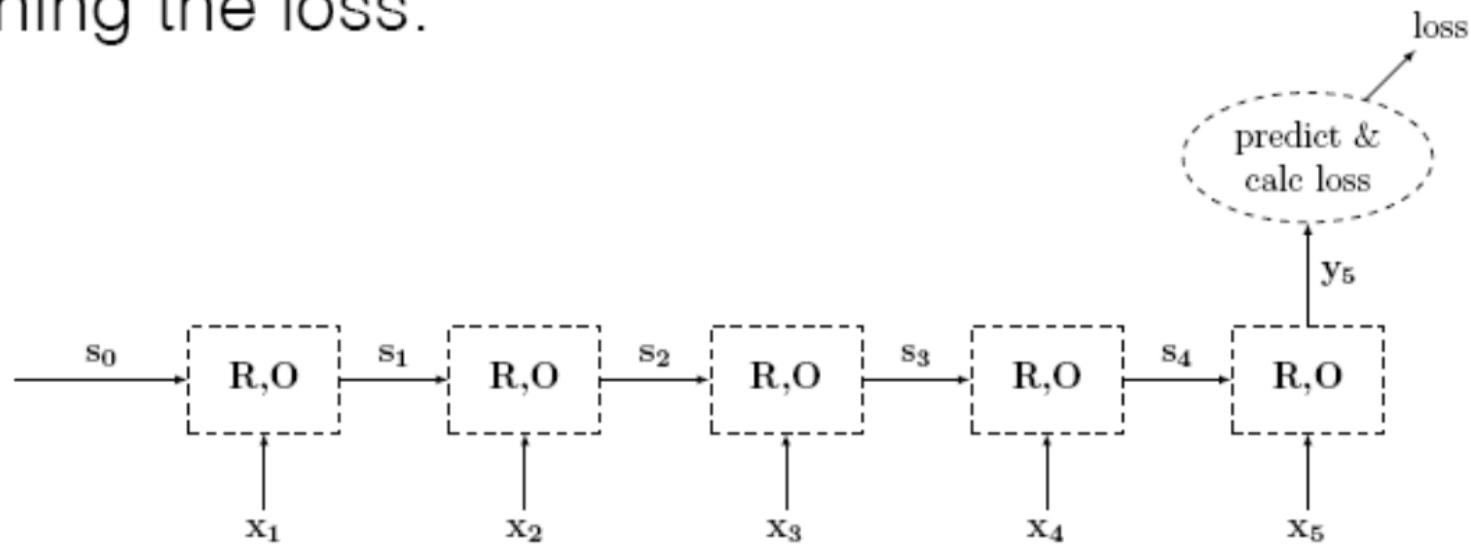
Encode **both future and history** of a word.

# Neural Architectures

- Mapping from a sequence to a single decision.
  - with RNN acceptor.
- Mapping from a sequence to a sequence of same length.
  - with RNN transducer

# RNN Acceptor

Defining the loss.

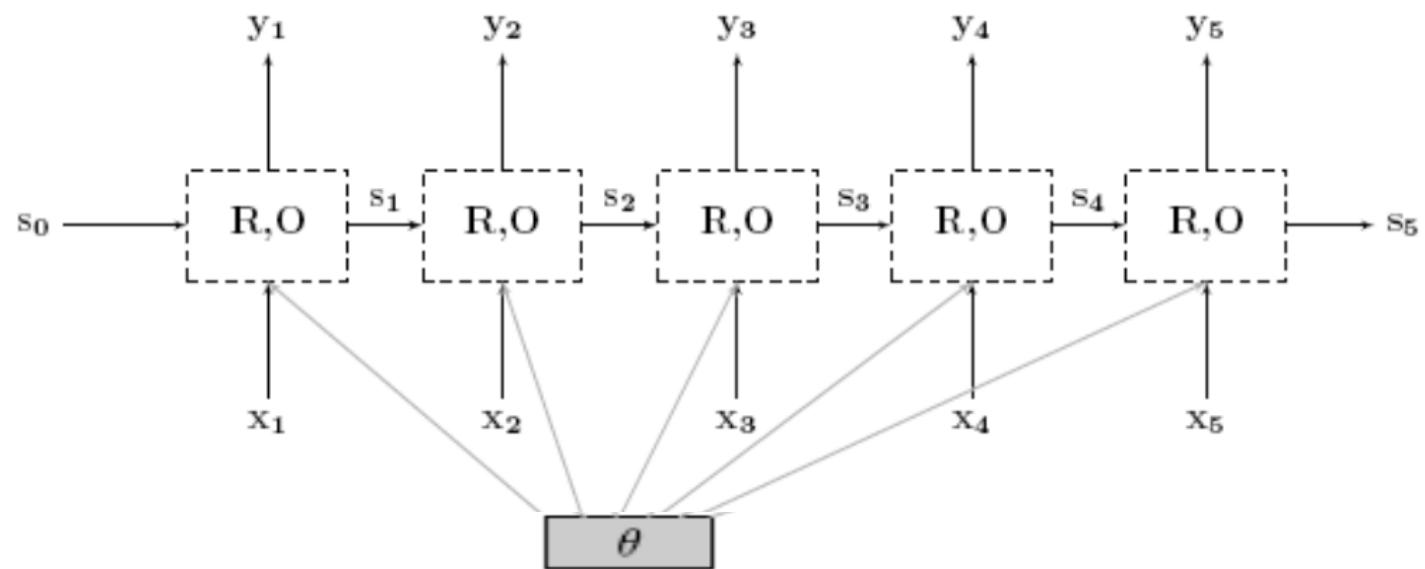


**Acceptor:** predict something from end state.

Backprop the error all the way back.

Train the network to capture meaningful information

# RNN Transducer



what do we do if the input and output sequences are of **different lengths**?

# Sequence Generation

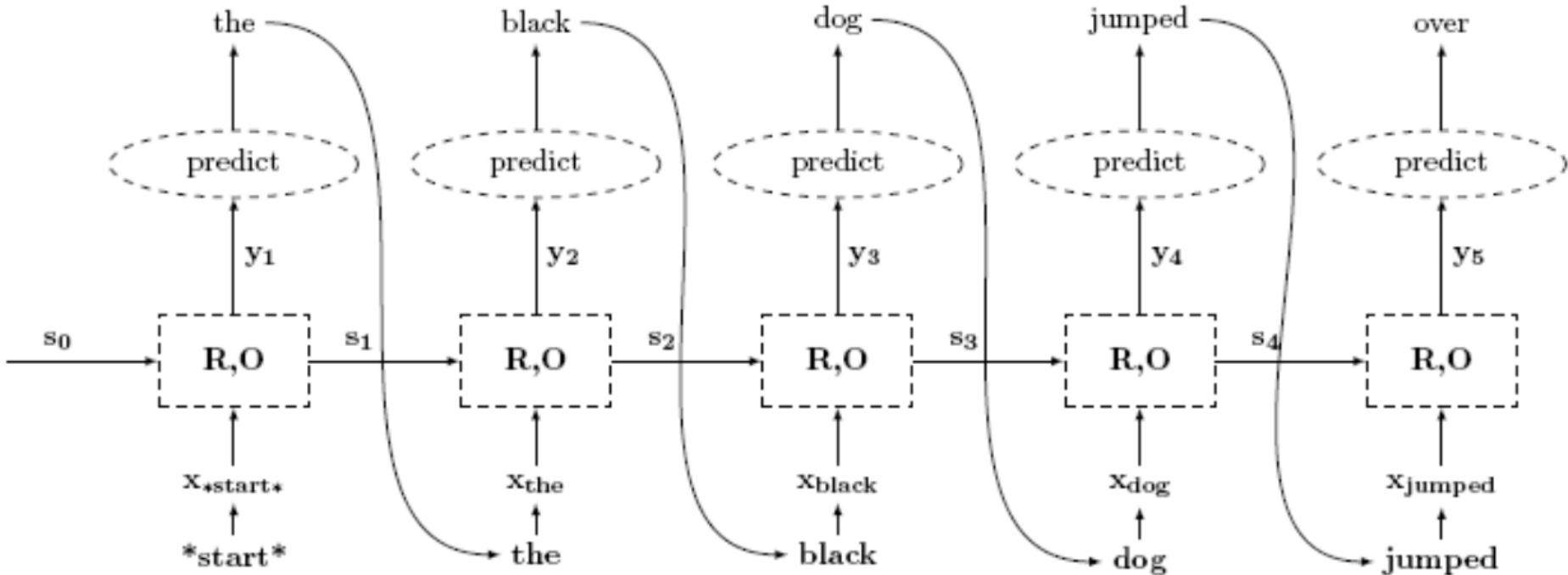
# Aside

How about an architecture for  
**0 to n** mapping.

(Neural Language Model)

# RNN Language Models

- *Training*: similar to an RNN Transducer.
- *Generation*: the output of step  $i$  is input to step  $i+1$ .



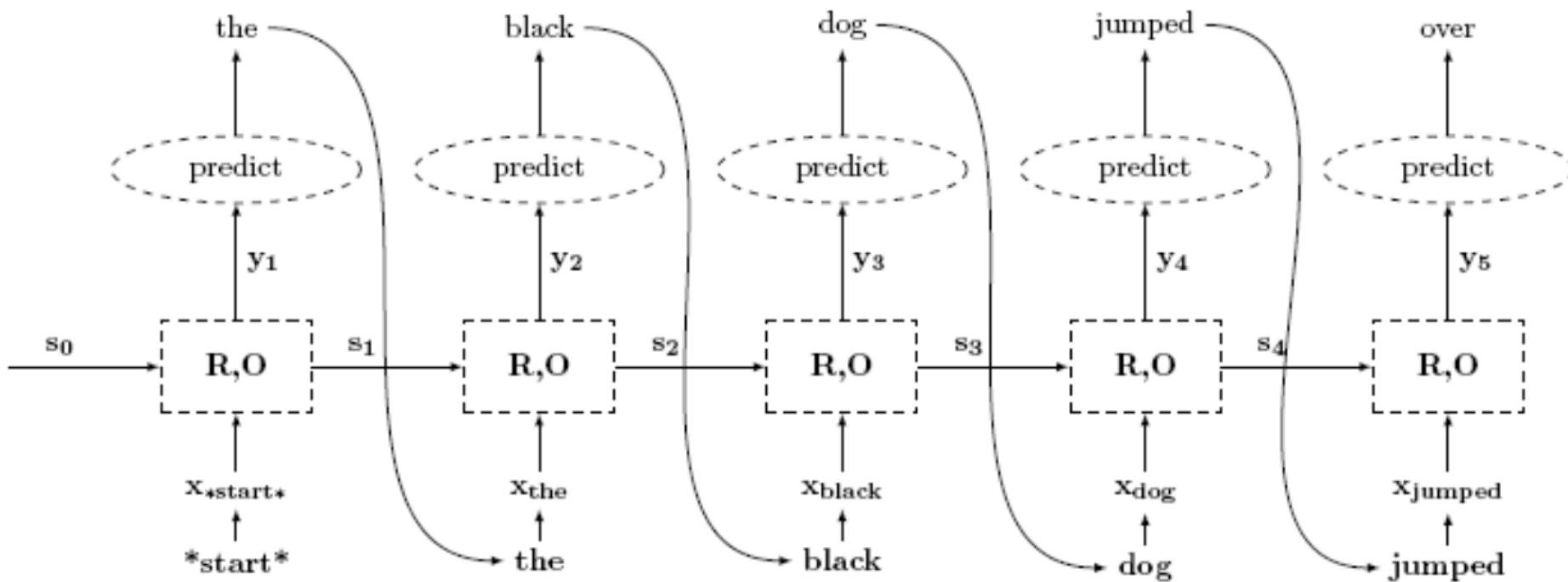
# RNN Language Model for generation

- Define the probability distribution over the next item in a sequence (and hence the probability of a sequence).

$$P(w_{1:n}) = P(w_1)P(w_2 \mid w_1)P(w_3 \mid w_{1:2})P(w_4 \mid w_{1:3}) \dots P(w_n \mid w_{1:n-1})$$

$$P(w_1, \dots, w_n) = \prod_{i=1}^n P(t_i = w_i \mid w_1, \dots, w_{i-1})$$

# RNN Language Models



$$p(t_{j+1} = k \mid \hat{t}_{1:j}) = f(\text{RNN}(\hat{\mathbf{t}}_{1:j}))$$

$$\hat{t}_j \sim p(t_j \mid \hat{t}_{1:j-1})$$

$$p(t_{j+1} = k \mid \hat{t}_{1:j}) = f(O(s_{j+1}))$$

$$s_{j+1} = R(\hat{\mathbf{t}}_j, s_j)$$

$$\hat{t}_j \sim p(t_j \mid \hat{t}_{1:j-1})$$

# Sequence 2 Sequence

Part I: No attention

# Back to Original question

How about an architecture for  
**m to n** mapping.

Generating sentences is nice, but what if we want  
to add some additional conditioning contexts?

# Conditioned Language Model

- Not just generate text, generate text according to some specification

<u>Input X</u>	<u>Output Y (Text)</u>	<u>Task</u>
Structured Data	NL Description	NL Generation
English	Japanese	Translation
Document	Short Description	Summarization
Utterance	Response	Response Generation
Image	Text	Image Captioning
Speech	Transcript	Speech Recognition

# RNN Language Model for Conditioned generation

Let's add the condition variable to the equation.

$$P(\tau) = \prod_{i=1}^I P(t_i | t_1, \dots, t_{i-1})$$

Next Word      Context

$$P(\tau | C) = \prod_{j=1}^J P(t_j | c, t_1, \dots, t_{j-1})$$

Added Context! (a vector)

# How to Pass Context

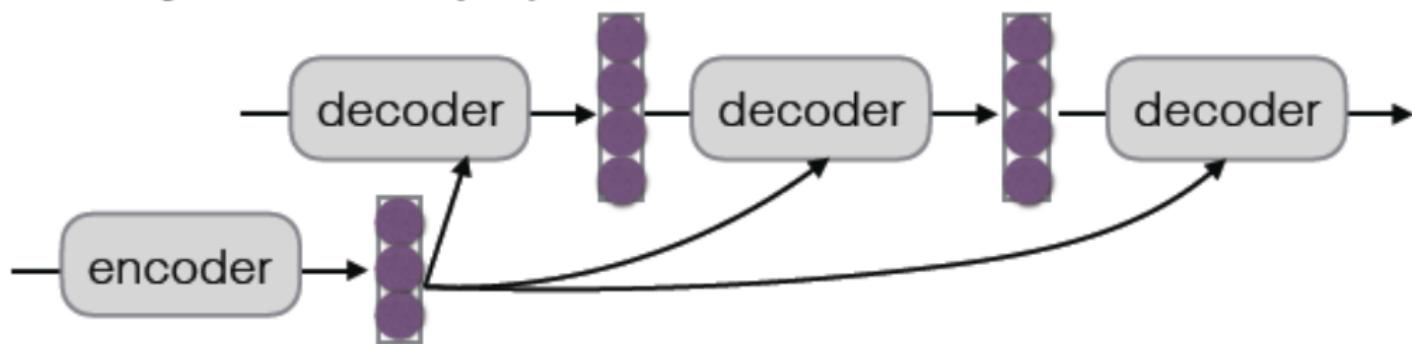
- Initialize decoder w/ encoder (Sutskever et al. 2014)



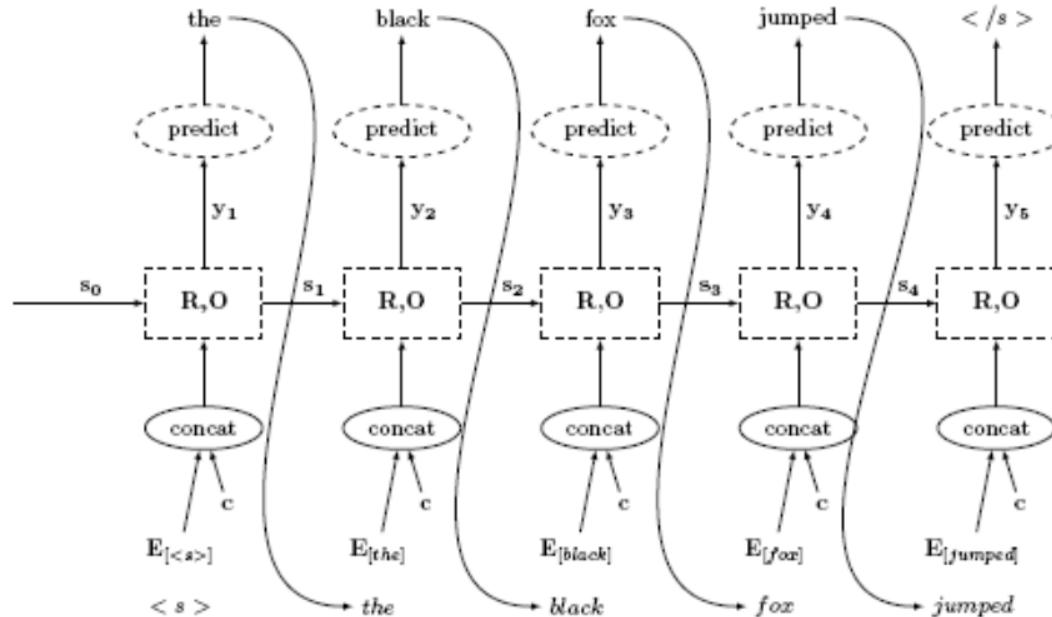
- Transform (can be different dimensions)



- Input at every time step (Kalchbrenner & Blunsom 2013)



# RNN Language Model for Conditioned generation



$$p(t_{j+1} = k \mid \hat{t}_{1:j}, c) = f(O(s_{j+1}))$$

$$s_{j+1} = R(s_j, [\hat{t}_j; c])$$

$$\hat{t}_j \sim p(t_i \mid \hat{t}_{1:j-1}, c)$$

# RNN Language Model for Conditioned generation

what if we want to condition on an entire sentence?

just encode it as a vector...

$$\mathbf{c} = \text{RNN}^{\text{enc}}(\mathbf{x}_{1:n})$$

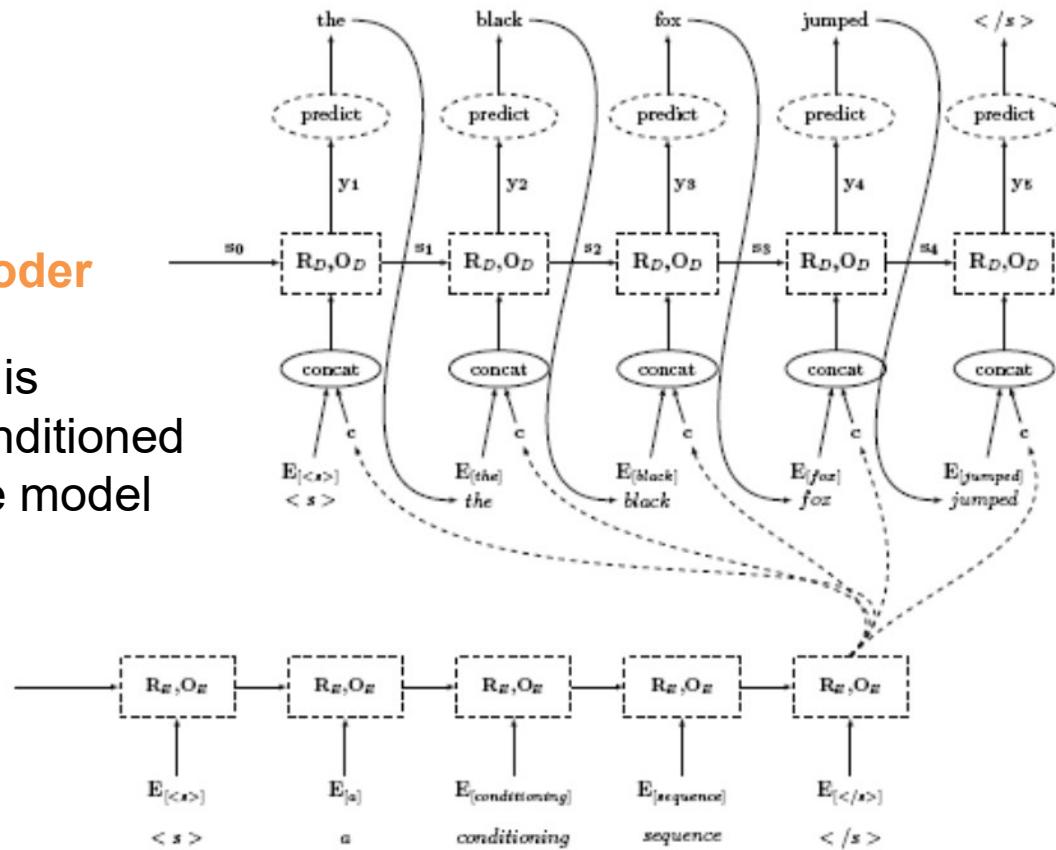
# Sequence to Sequence conditioned generation

This is also called  
"Encoder Decoder"  
architecture.

## Decoder

Decoder is  
just a conditioned  
language model

## Encoder



# The Generation Problem

We have a probability model, how do we use it to generate a sentence?

Two methods:

- **Sampling:** Try to generate a *random* sentence according to the probability distribution.
- **Argmax:** Try to generate the sentence with the *highest* probability.

# Ancestral Sampling

**Randomly generate** words one-by-one.

```
while  $y_{j-1} \neq "$ </s>" $":$   
 $y_j \sim P(y_j | X, y_1, \dots, y_{j-1})$ 
```

An **exact method** for sampling from  $P(X)$ , no further work needed.

# Greedy Search

One by one, pick the single highest-probability word

```
while  $y_{j-1} \neq "$ </s>" :
```

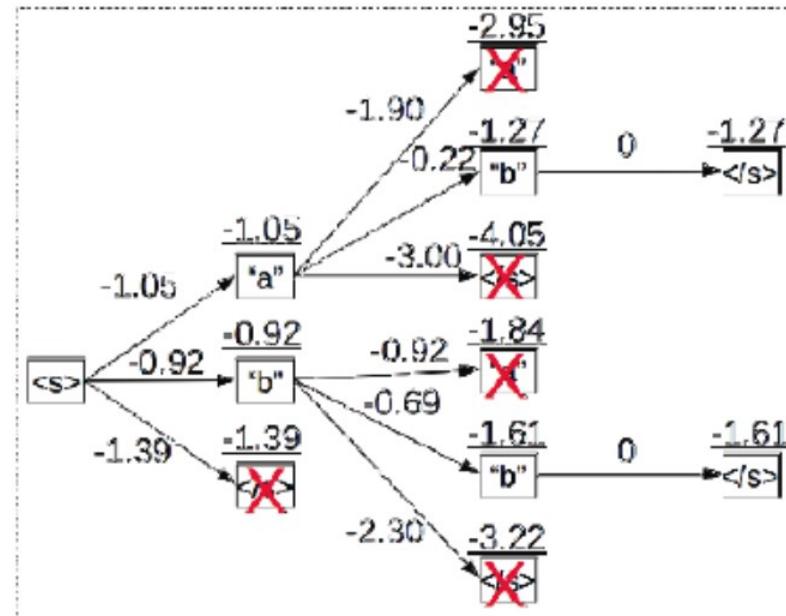
```
     $y_j = \operatorname{argmax} P(y_j | X, y_1, \dots, y_{j-1})$ 
```

## Not exact, real problems:

- Will often generate the “easy” words first
- Will prefer multiple common words to one rare word

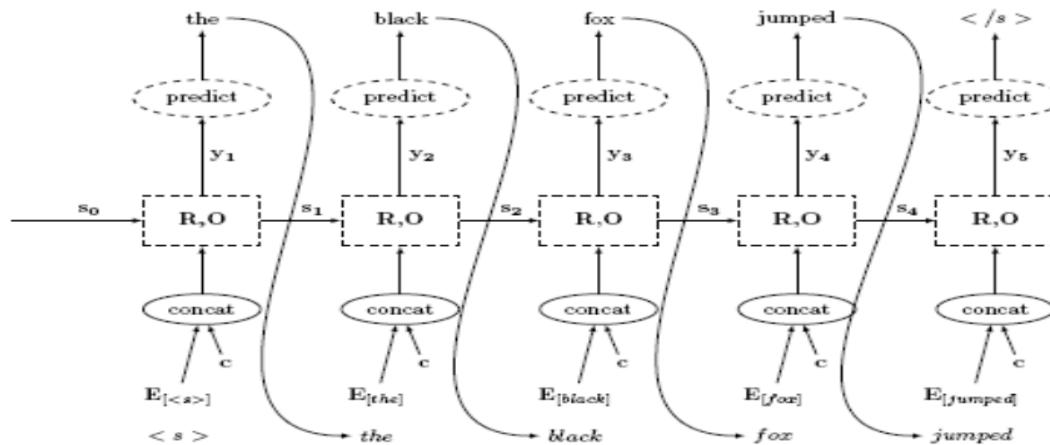
# Beam Search

Instead of picking one high-probability word,  
maintain several paths



# How to Train this Model?

- Issues with vanilla training
  - Slow convergence. Model instability. Poor skill.
- Simple idea: **Teacher Forcing**
  - Just feed in the *correct* previous word during training
- Drawback: **Exposure bias**
  - Not exposed to mistakes during training



# Solutions to Exposure Bias

- Start with no mistakes, and then
  - gradually introduce them using annealing
- Dropout inputs
  - Helps ensure that the model doesn't rely too heavily on predictions, while still using them
- Corrupt training data

# Evaluation Idea 1

- Steps
  - Use parallel test set
  - Use system to generate translations
  - Compare target translations w/ reference
- We train parameters of our model on a **training set**.
- We test the model's performance on data we haven't seen.
  - A **test set** is an unseen dataset that is different from our training set, totally unused.
  - An **evaluation metric** tells us how well our model does on the test set.

# Metric: Human Evaluation

太郎が花子を訪れた

Taro visited Hanako   the Taro visited the Hanako   Hanako visited Taro

Adequate?	Yes	Yes	No
Fluent?	Yes	No	Yes
Better?	1	2	3

- Final goal, but slow, expensive, and sometimes inconsistent

# Metric: BLEU

- Works by comparing n-gram overlap w/ reference

Reference: Taro visited Hanako

System: the Taro visited the Hanako

1-gram: 3/5

2-gram: 1/4

Brevity:  $\min(1, |\text{System}|/|\text{Reference}|) = \min(1, 5/3)$  brevity penalty = 1.0

$$\text{BLEU-2} = (3/5 * 1/4)^{1/2} * 1.0 \\ = 0.387$$

- **Pros:** Easy to use, good for measuring system improvement
- **Cons:** Often doesn't match human eval, bad for comparing very different systems

# Metric: METEOR

- Like BLEU in overall principle, with many other tricks: consider paraphrases, reordering, and function word/content word difference
- **Pros:** Generally significantly better than BLEU, esp. for high-resource languages
- **Cons:** Requires extra resources for new languages (although these can be made automatically), and more complicated

# Evaluation Idea 2

- Don't generate a translation. Instead ask:
- Does our language model prefer good sentences to bad ones?
  - Assign a high probability to “real” sentence

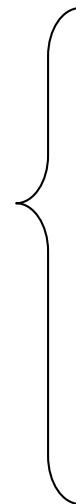
# Intuition of Perplexity

- The Shannon Game:
  - How well can we predict the next word?

I always order pizza with cheese and \_\_\_\_\_

The 33<sup>rd</sup> President of the US was \_\_\_\_\_

I saw a \_\_\_\_\_



mushrooms 0.1  
pepperoni 0.1  
anchovies 0.01  
...  
fried rice 0.0001  
...  
and 1e-100

- Unigrams are terrible at this game. (Why?)
- A better model of a text
  - is one which assigns a higher probability to the word that actually occurs

# Perplexity

The best language model is one that best predicts an unseen test set

- Gives the highest  $P(\text{sentence})$

Perplexity is the inverse probability of the test set, normalized by the number of words:

Chain rule:

$$PP(W) = P(w_1 w_2 \dots w_N)^{-\frac{1}{N}}$$

$$= \sqrt[N]{\frac{1}{P(w_1 w_2 \dots w_N)}}$$

$$PP(W) = \sqrt[N]{\prod_{i=1}^N \frac{1}{P(w_i | w_1 \dots w_{i-1})}}$$

**Minimizing perplexity is the same as maximizing probability**

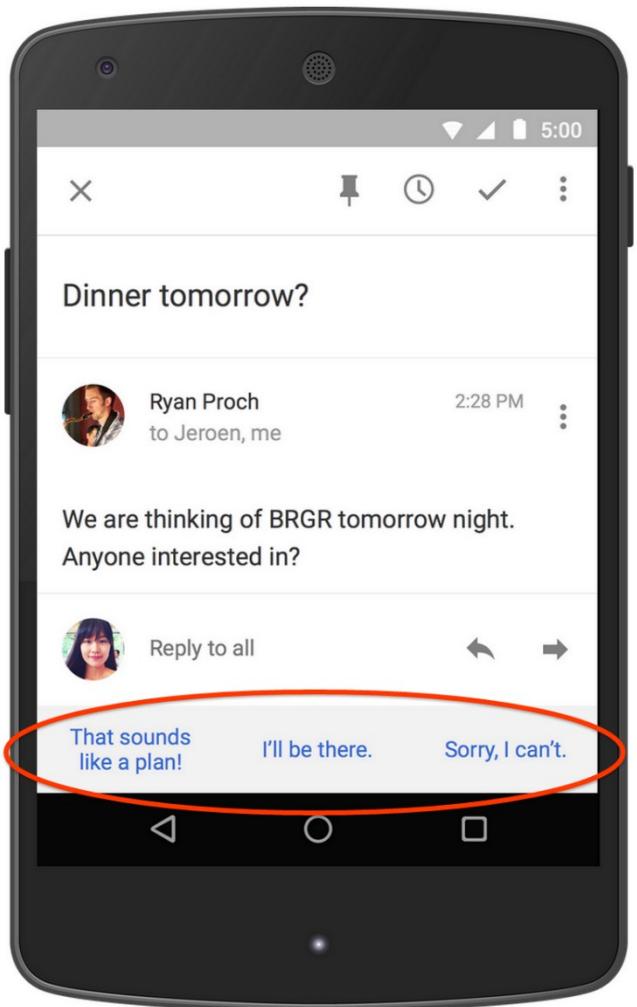
# The Shannon Game intuition for perplexity

- How hard is the task of recognizing digits '0,1,2,3,4,5,6,7,8,9'
  - Perplexity 10
- How hard is recognizing (30,000) names at Microsoft.
  - Perplexity = 30,000
- If a system has to recognize
  - Operator (1 in 4)
  - Sales (1 in 4)
  - Technical Support (1 in 4)
  - 30,000 names (1 in 120,000 each)
  - Perplexity is 53
- Perplexity is weighted equivalent branching factor

# Metric: Perplexity

- Calculate the perplexity of the words in the held-out set *without* doing generation
- **Pros:** Naturally solves multiple-reference problem!
- **Cons:** Doesn't consider decoding or actually generating output.

# Case Study



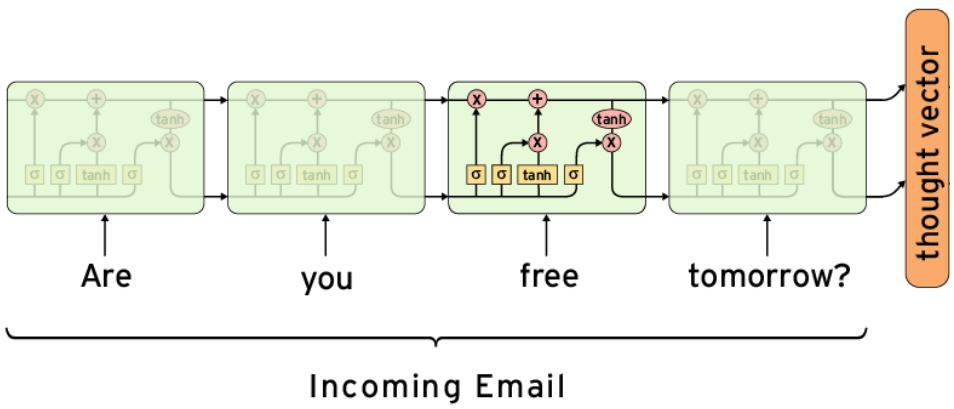
# Case Study: Smart Reply in Gmail



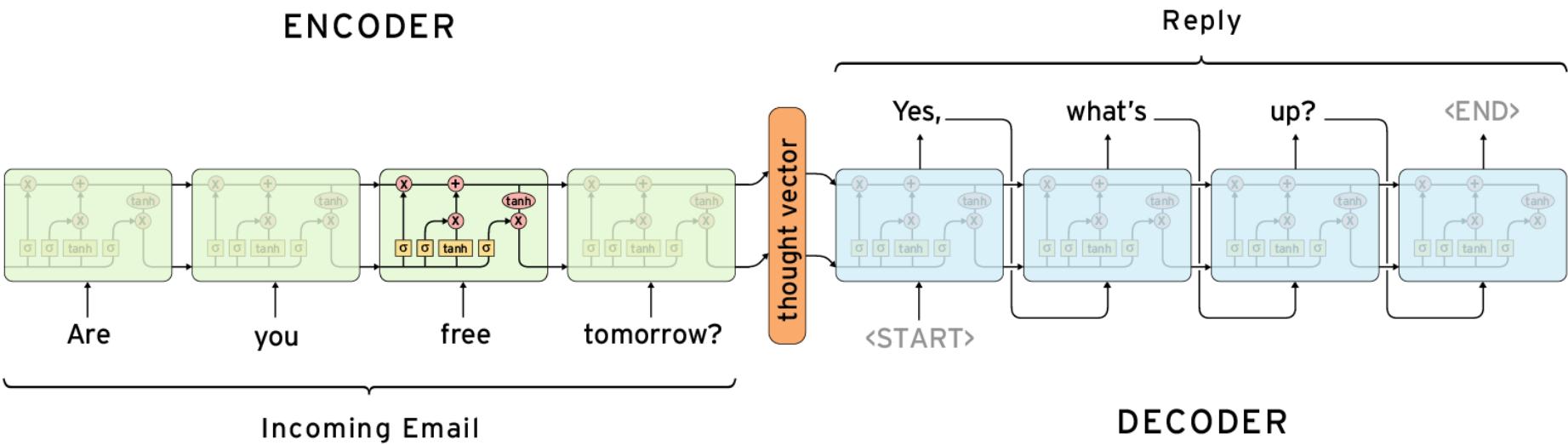
# Preprocessing an incoming email

- Language detection
  - Currently handle English, Portuguese, Spanish ... a few more languages are in preparation
- Tokenization of subject and message body
- Sentence segmentation
- Normalization of infrequent words and entities – replaced by special tokens
- Removal of quoted and forward email portions
- Removal of greeting and closing phrases (“Hi John”,... “Regards, Mary”)

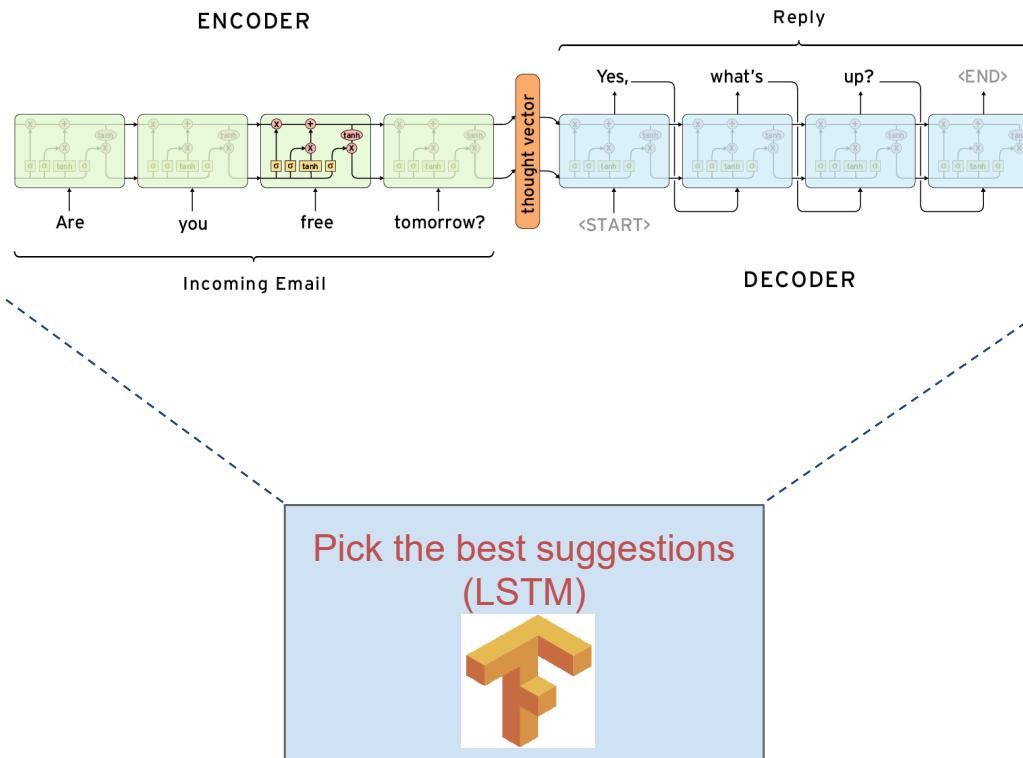
## ENCODER



# LSTM translation



Vinyals & Le, 2015



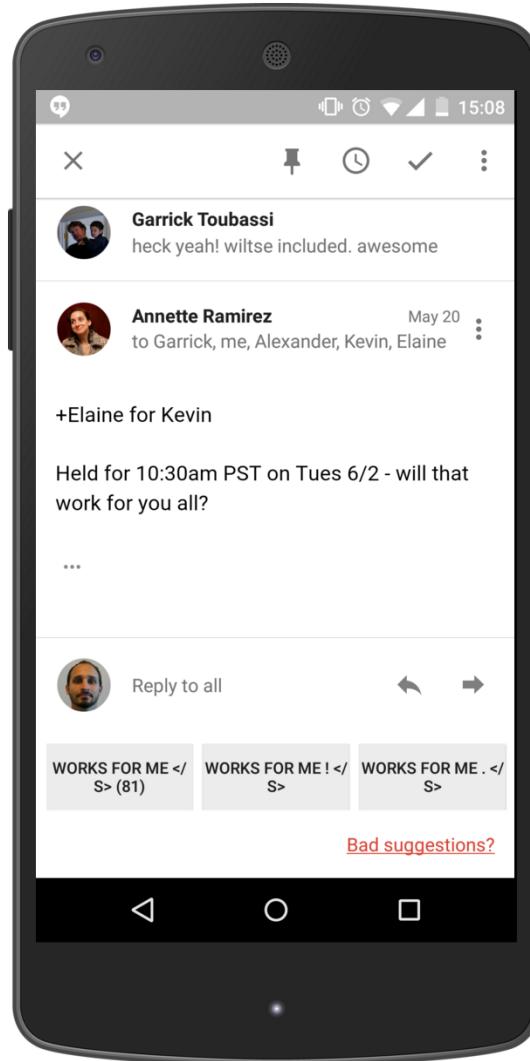
# Is it worth it?

- Precision/accuracy - how well can we guess good replies?
- Coverage - do most emails have simple, predictable responses?

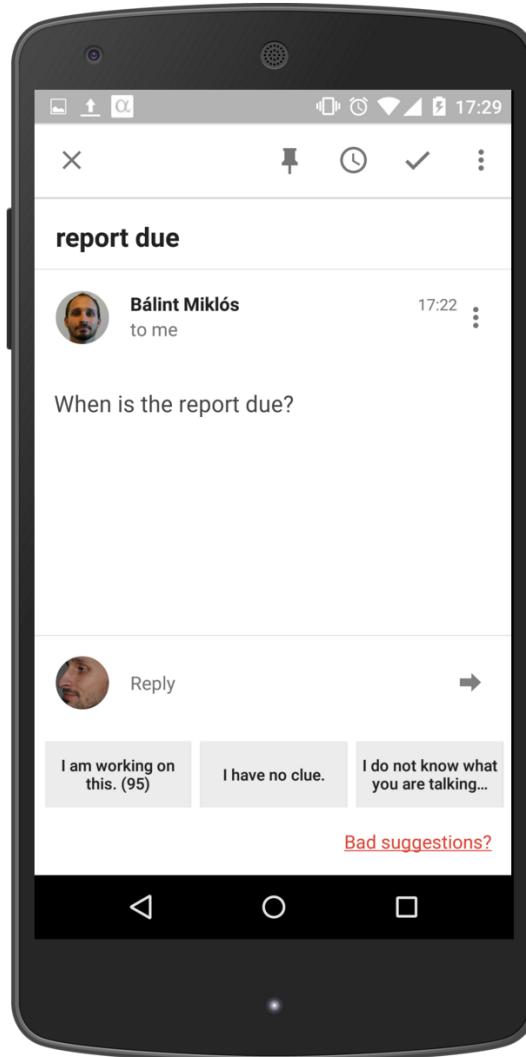
# Metric

- What fraction of the time do users select a suggested reply?
  - How many replies do we suggest? 3
  - Constraint based on user interface, but also users' ability to quickly process choices
- We get a boost from allowing users to edit responses before sending
  - In early studies, users were nervous that choosing a response would instantly send
  - Careful tuning of this UI gave us bigger gains than a lot of ML tuning

# Some early observations



# Some early observations



# A scoring algorithm != product

- Semantic variation: all 3 suggestions say the same thing ...
  - Can't simply take the 3 highest scoring suggestions
- The “I love you” problem
  - A human can say them, but not a computer ...\*
  - A lot of responses in the training corpus have “I love you”
  - In many cases this isn’t appropriate
  - “Family friendliness”
- Sensitivity
  - There are many incoming emails where you don’t want the computer to guess replies - Bad news, etc
- \* our expectations of “working” AI are higher than of humans



**Michael Gadberry** @michaelgadberry · 13h

Google Inbox's automated suggested replies are mind-blowingly awesome and accurate. #CheckOutDatStuff #GoogleInbox @inboxbygmail



**Simon Dingle** @SimonDingle · Nov 12

It's like @inboxbygmail has telepathy with its automated responses.

--



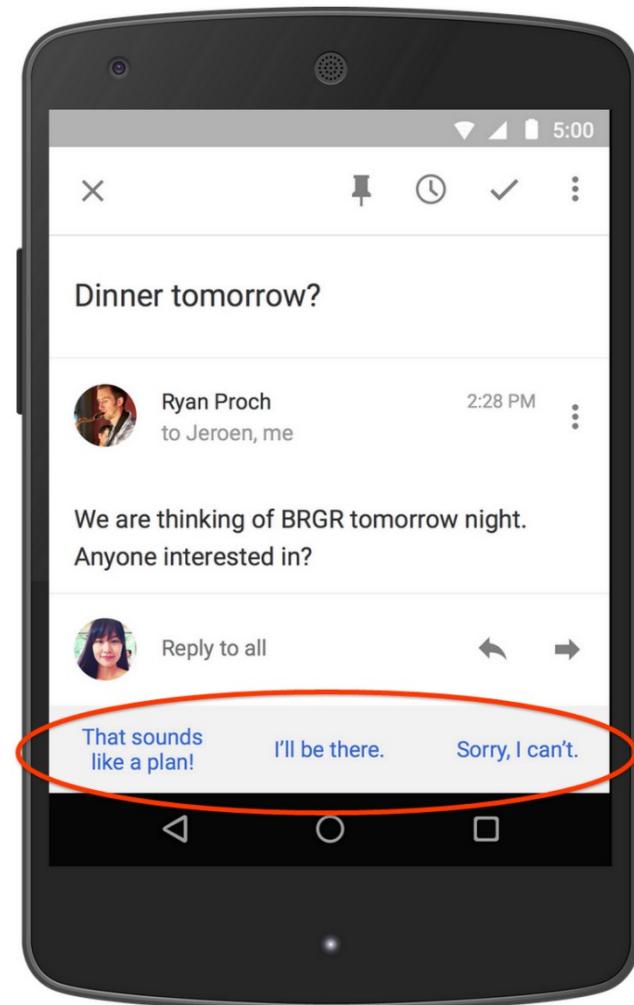
**Tatiana King Jones** @TatianaKing · Nov 12

The new @inboxbygmail auto response choices have been pretty good so far. Have been using them maybe 50% of the time.

# >10%

of Gmail responses are Smart Replies.

(Users accept computer-generated replies.)



# Encoder-Decoder with different modalities

The encoded conditioning context need not be text, or even a sequence.

# Encoder-Decoder with different modalities

Show and Tell: A Neural Image Caption Generator

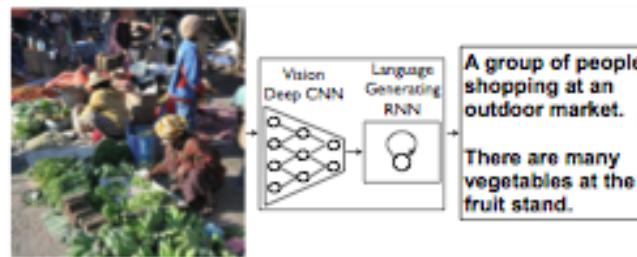
Oriol Vinyals  
Google  
[vinyals@google.com](mailto:vinyals@google.com)

Alexander Toshev  
Google  
[toshev@google.com](mailto:toshev@google.com)

Samy Bengio  
Google  
[bengio@google.com](mailto:bengio@google.com)

Dmitri Erhan  
Google  
[dumitru@google.com](mailto:dumitru@google.com)

- Encode: **image** to vector.  
Decode: a sentence describing the image.



This sort-of works.

In my opinion, looks more impressive than really is.

I think it's a man in a business suit  
standing on a bench.



I am not really confident, but I think it's a man standing on a beach near the water.



I think it's a group of people sitting in front of a crowd.



I am not really confident, but I think it's  
a close up of a sheep.

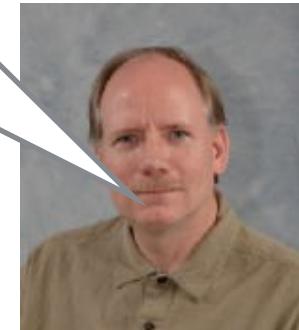


# Sequence 2 Sequence

## Part II: with attention

# Sentence Representation

You can't cram the meaning of a whole %&!\$# sentence into a single \$&!#\* vector!

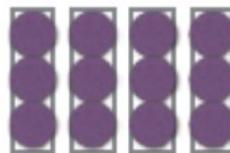


But what if we could use multiple vectors, based on the length of the sentence.

this is an example →

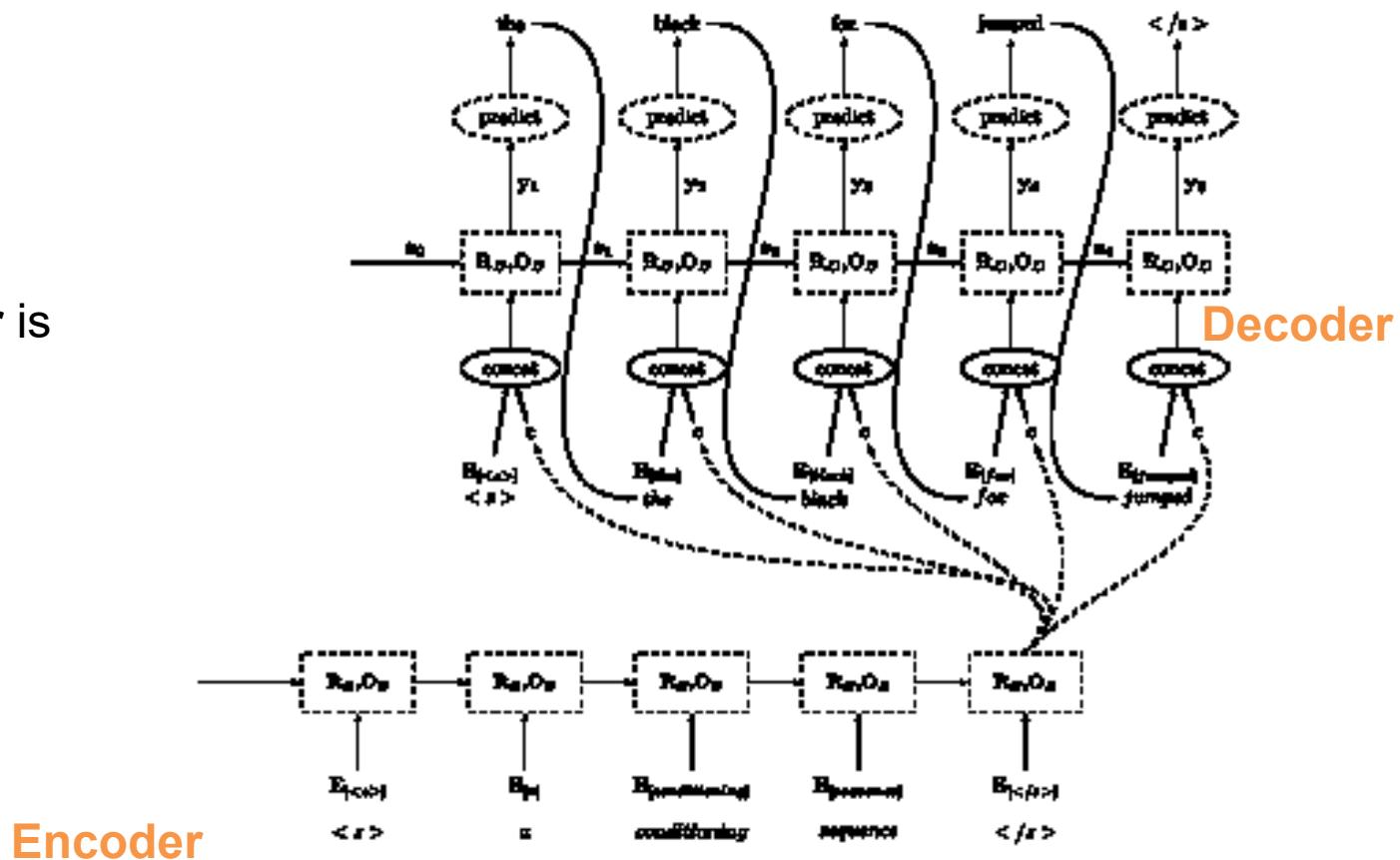


this is an example →



# Sequence to Sequence conditioned generation

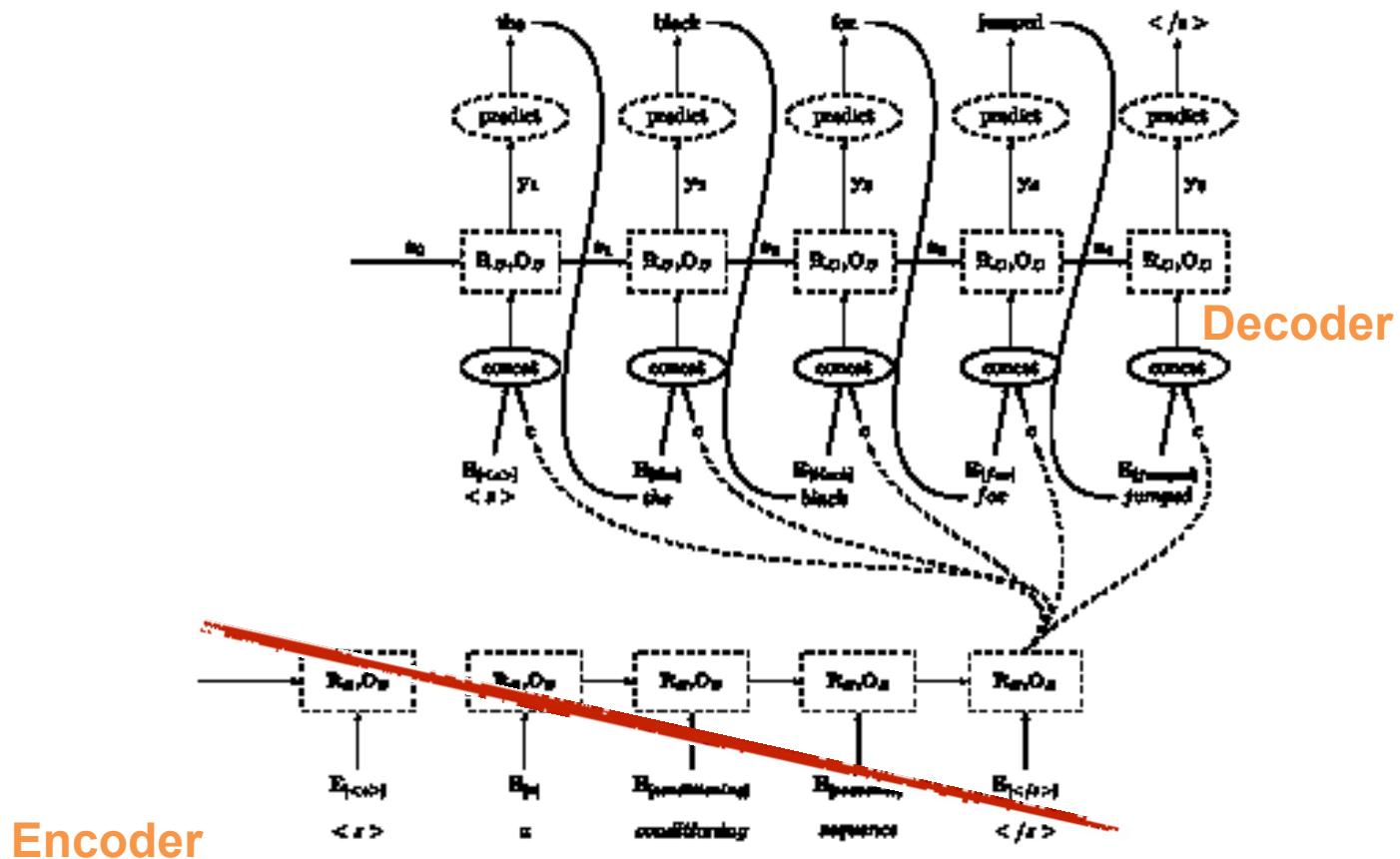
main idea:  
**encoding**  
**a single vector** is  
**too restrictive.**



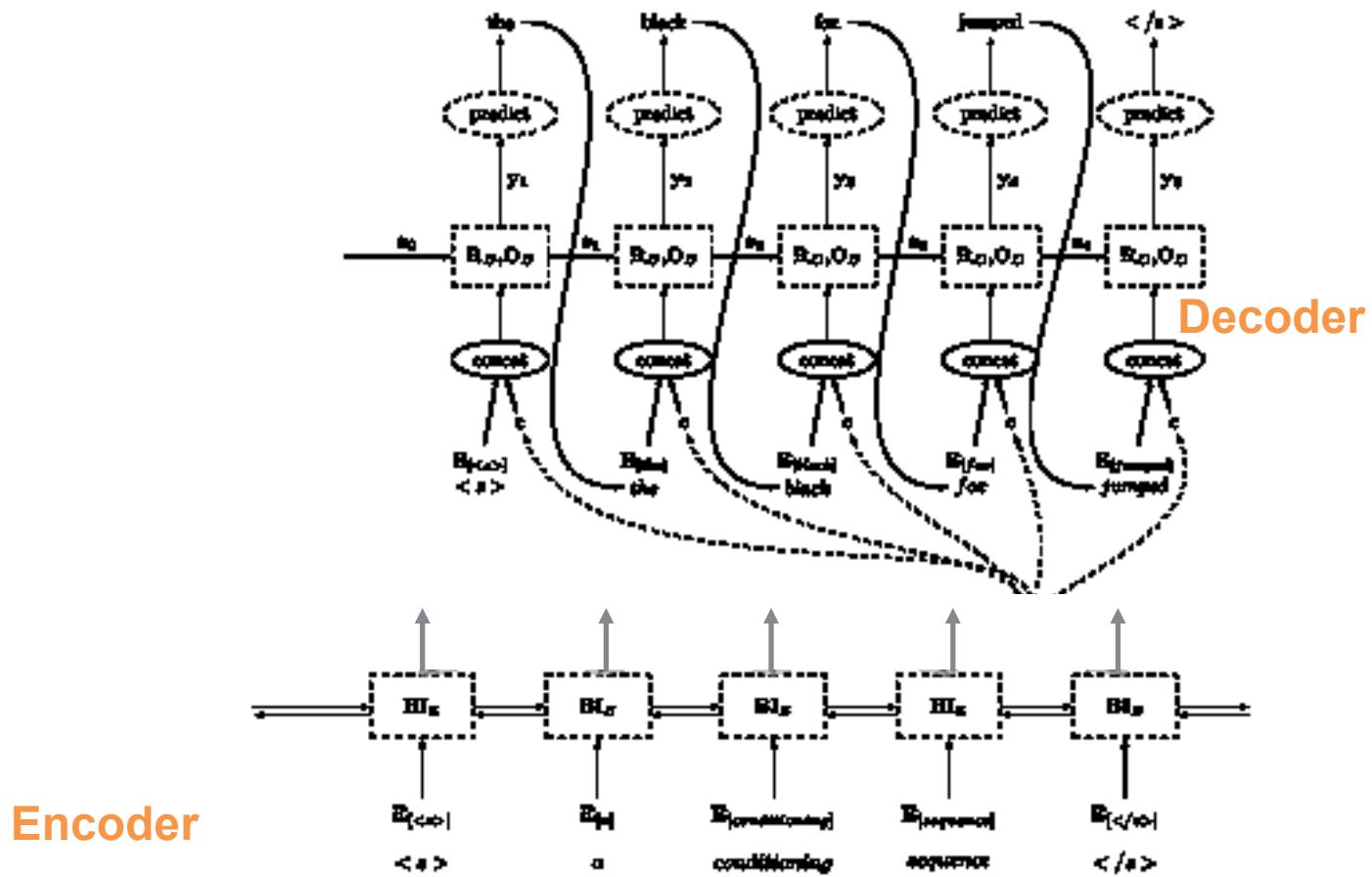
# Attention

- Instead of the encoder producing a single vector for the sentence, it will produce a one vector **for each word**.

# Sequence to Sequence conditioned generation

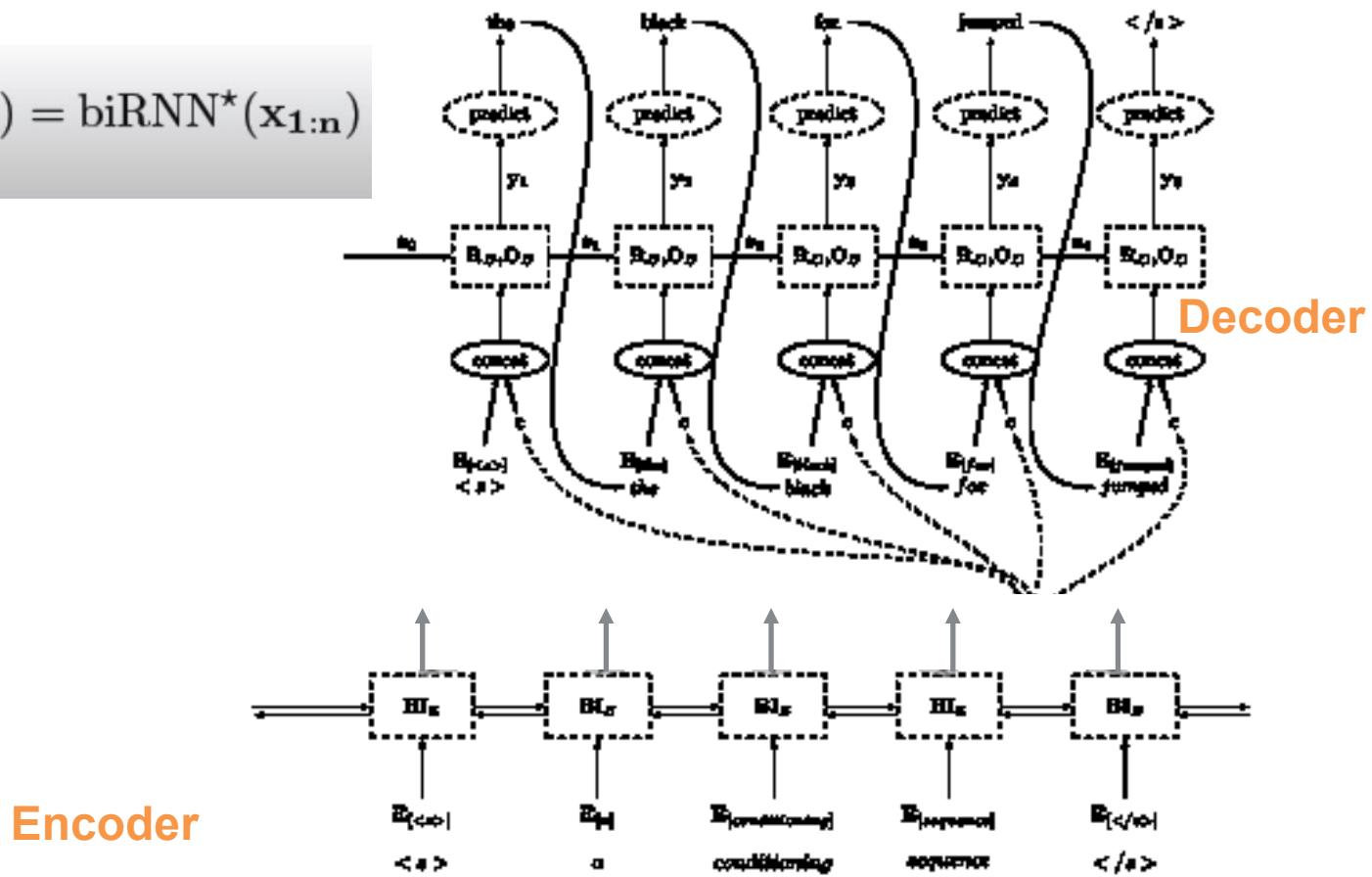


# Sequence to Sequence conditioned generation



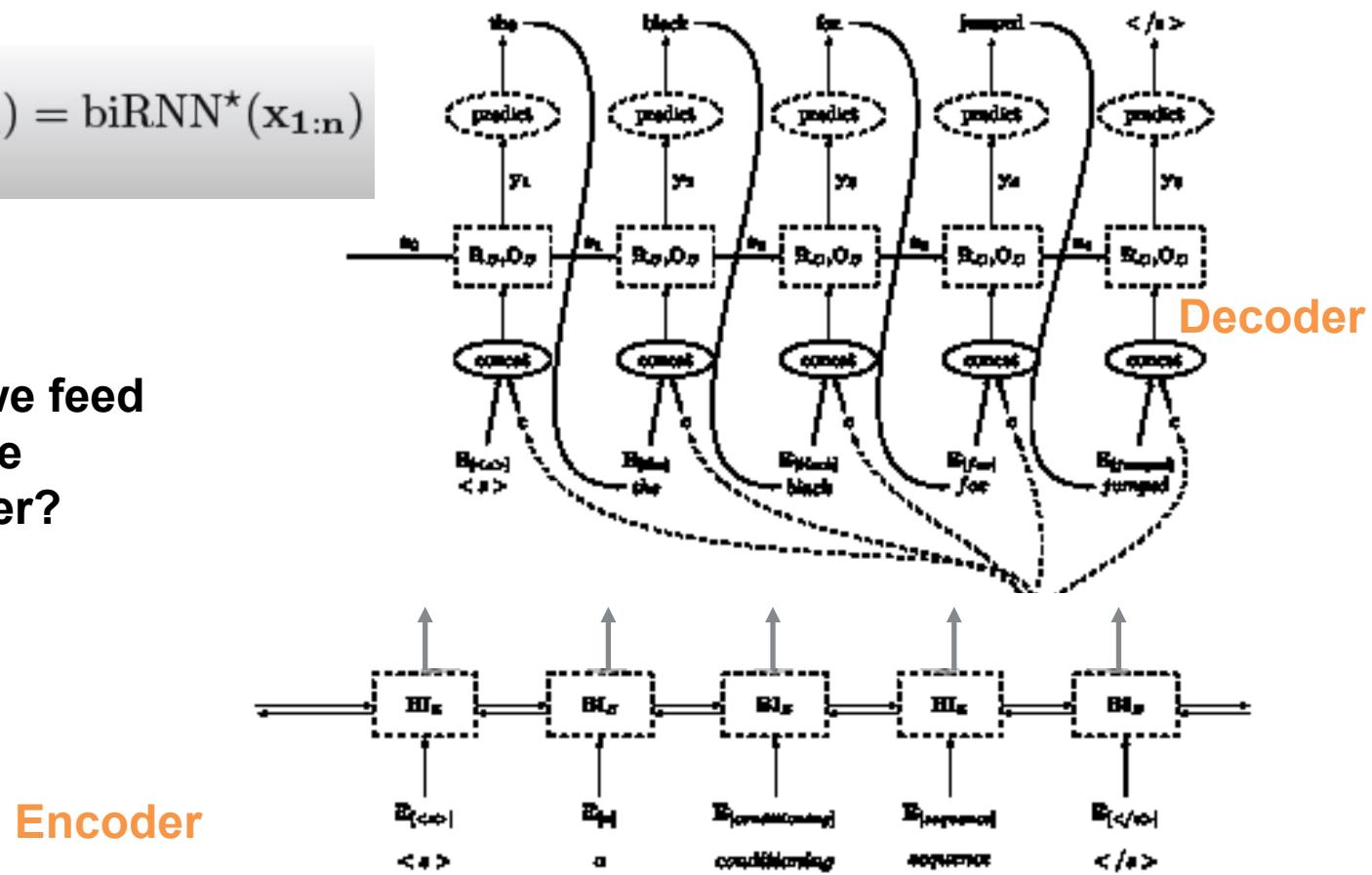
# Sequence to Sequence conditioned generation

$$\mathbf{c}_{1:n} = \text{ENC}(\mathbf{x}_{1:n}) = \text{biRNN}^*(\mathbf{x}_{1:n})$$



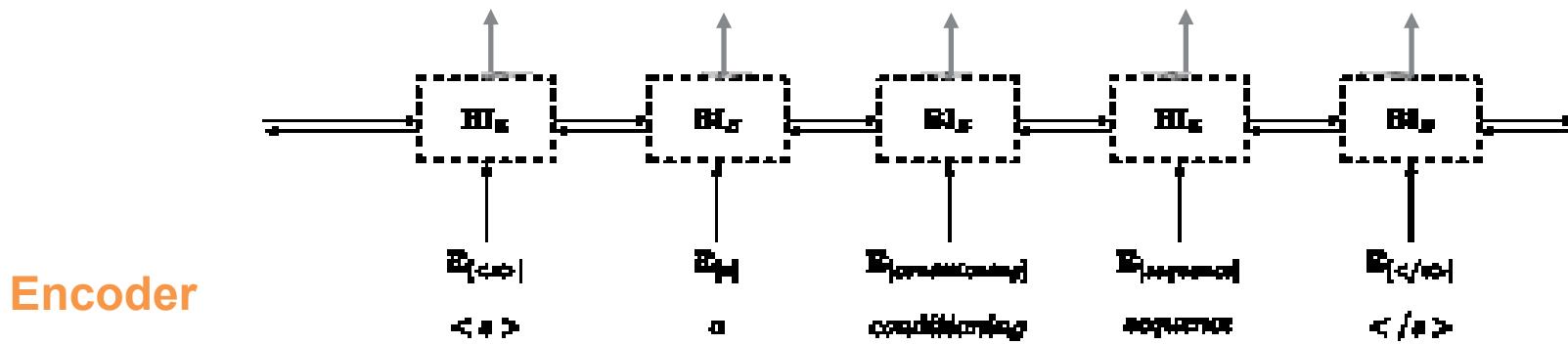
# Sequence to Sequence conditioned generation

$$c_{1:n} = \text{ENC}(x_{1:n}) = \text{biRNN}^*(x_{1:n})$$



# Sequence to Sequence conditioned generation

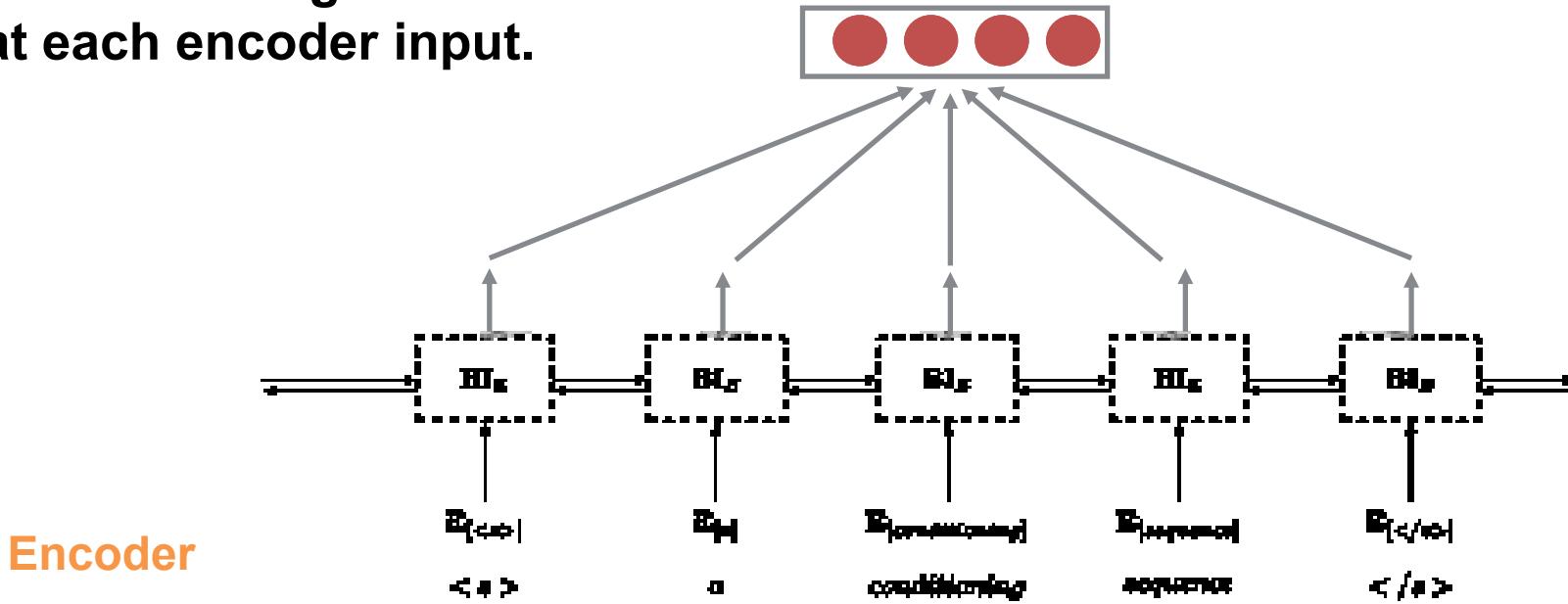
we can combine the different outputs  
into a single vector (attended summary)



# Sequence to Sequence conditioned generation

we can combine the different outputs  
into a single vector (attended summary)

a different single vector  
at each encoder input.



$$p(t_{j+1} = k \mid \hat{t}_{1:j}, \mathbf{x_{1:n}}) = f(O(\mathbf{s_{j+1}}))$$

$$\mathbf{s_{j+1}} = R(\mathbf{s_j}, [\hat{\mathbf{t_j}} \textcolor{blue}{\bigcirc}])$$

$$\textcolor{blue}{\bigcirc} = \mathrm{attend}(\mathbf{c_{1:n}}, \hat{t}_{1:j})$$

$$\hat{t}_j \sim p(t_j \mid \hat{t}_{1:j-1}, \mathbf{x_{1:n}})$$

$$p(t_{j+1} = k \mid \hat{t}_{1:j}, \mathbf{x_{1:n}}) = f(O(\mathbf{s_{j+1}}))$$

$$\mathbf{s_{j+1}} = R(\mathbf{s_j}, [\hat{\mathbf{t}_j}; \mathbf{c^j}])$$



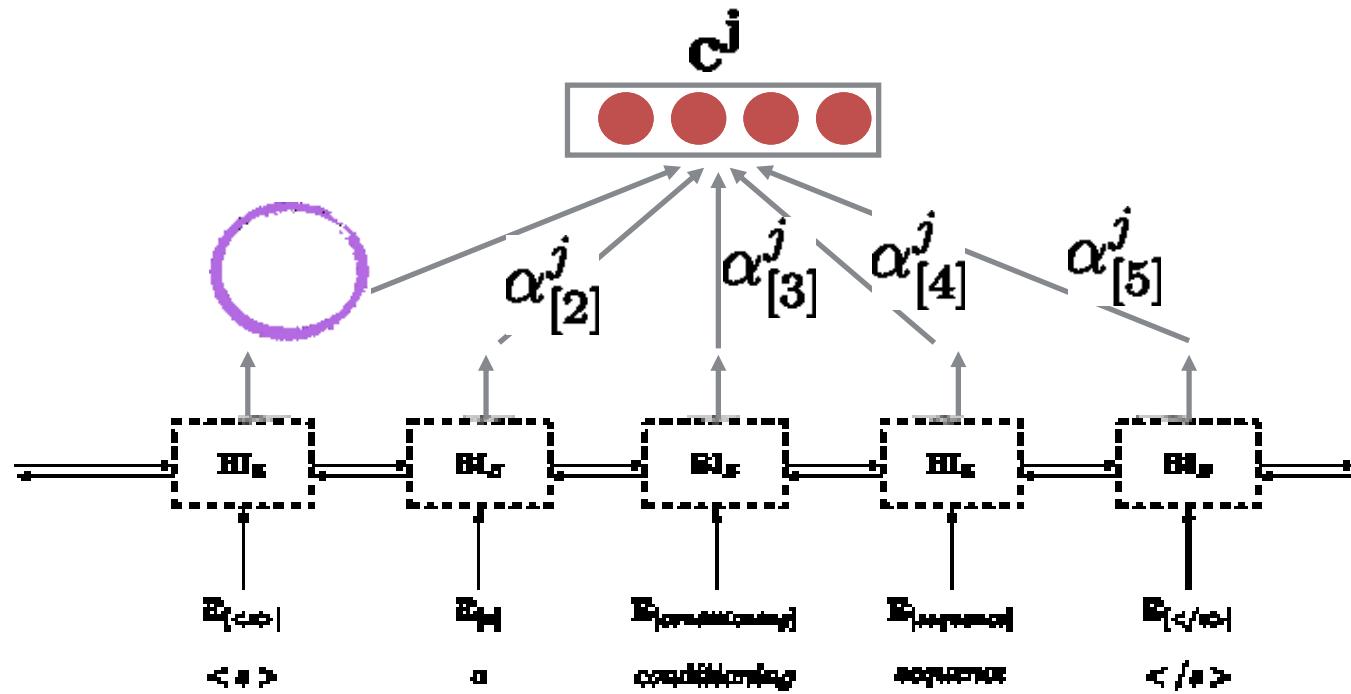
$$\hat{t}_j \sim p(t \mid \hat{t}_{1:j-1}, \mathbf{x_{1:n}})$$

$$\mathbf{c^j} = \sum_{i=1}^n \alpha_{[i]}^j \cdot \mathbf{c_i}$$

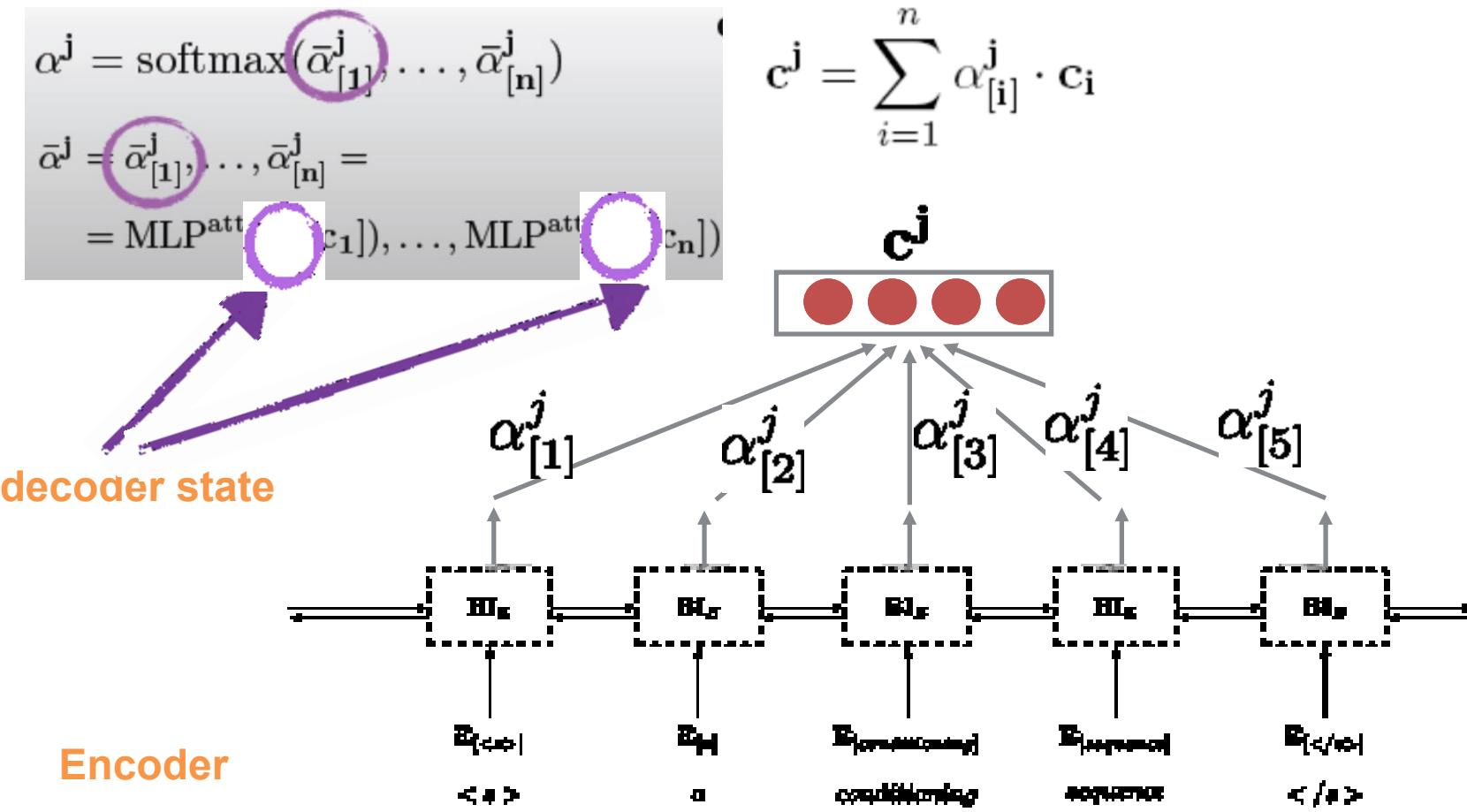
# Sequence to Sequence conditioned generation

$$\alpha^j = \text{softmax}(\bar{\alpha}_{[1]}^j, \dots, \bar{\alpha}_{[n]}^j)$$

$$c^j = \sum_{i=1}^n c_i$$



# Sequence to Sequence conditioned generation



# encoder-decoder with attention

$$p(t_{j+1} = k \mid \hat{t}_{1:j}, \mathbf{x}_{1:n}) = f(O_{\text{dec}}(\mathbf{s}_{j+1}))$$

$$\mathbf{s}_{j+1} = R_{\text{dec}}(\mathbf{s}_j, [\hat{\mathbf{t}}_j; \mathbf{c}^j])$$

$$\mathbf{c}^j = \sum_{i=1}^n \alpha_{[i]}^j \cdot \mathbf{c}_i$$

$$\mathbf{c}_{1:n} = \text{biRNN}_{\text{enc}}^\star(\mathbf{x}_{1:n})$$

$$\alpha^j = \text{softmax}(\bar{\alpha}_{[1]}^j, \dots, \bar{\alpha}_{[n]}^j)$$

$$\bar{\alpha}_{[i]}^j = \text{MLP}^{\text{att}}([\mathbf{s}_j; \mathbf{c}_i])$$

$$\hat{t}_j \sim p(t_j \mid \hat{t}_{1:j-1}, \mathbf{x}_{1:n})$$

$$f(\mathbf{z}) = \text{softmax}(\text{MLP}^{\text{out}}(\mathbf{z}))$$

$$\text{MLP}^{\text{att}}([\mathbf{s}_j; \mathbf{c}_i]) =$$

# encoder-decoder with attention

$$p(t_{j+1} = k \mid \hat{t}_{1:j}, \mathbf{x}_{1:n}) = f(O_{\text{dec}}(\mathbf{s}_{j+1}))$$

$$\mathbf{s}_{j+1} = R_{\text{dec}}(\mathbf{s}_j, [\hat{\mathbf{t}}_j; \mathbf{c}^j])$$

$$\mathbf{c}^j = \sum_{i=1}^n \alpha_{[i]}^j \cdot \mathbf{c}_i$$

$$\mathbf{c}_{1:n} = \text{biRNN}_{\text{enc}}^{\star}(\mathbf{x}_{1:n})$$

$$\alpha^j = \text{softmax}(\bar{\alpha}_{[1]}^j, \dots, \bar{\alpha}_{[n]}^j)$$

$$\bar{\alpha}_{[i]}^j = \text{MLP}^{\text{att}}([\mathbf{s}_j; \mathbf{c}_i])$$

$$\hat{t}_j \sim p(t_j \mid \hat{t}_{1:j-1}, \mathbf{x}_{1:n})$$

$$f(\mathbf{z}) = \text{softmax}(\text{MLP}^{\text{out}}(\mathbf{z}))$$

$$\text{MLP}^{\text{att}}([\mathbf{s}_j; \mathbf{c}_i]) =$$

# encoder-decoder with attention

$$p(t_{j+1} = k \mid \hat{t}_{1:j}, \mathbf{x}_{1:n}) = f(O_{\text{dec}}(\mathbf{s}_{j+1}))$$

$$\mathbf{s}_{j+1} = R_{\text{dec}}(\mathbf{s}_j, [\hat{\mathbf{t}}_j; \mathbf{c}^j])$$

$$\mathbf{c}^j = \sum_{i=1}^n \alpha_{[i]}^j \cdot \mathbf{c}_i$$

$$\mathbf{c}_{1:n} = \text{biRNN}_{\text{enc}}^*(\mathbf{x}_{1:n})$$

$$\alpha^j = \text{softmax}(\bar{\alpha}_{[1]}^j, \dots, \bar{\alpha}_{[n]}^j)$$

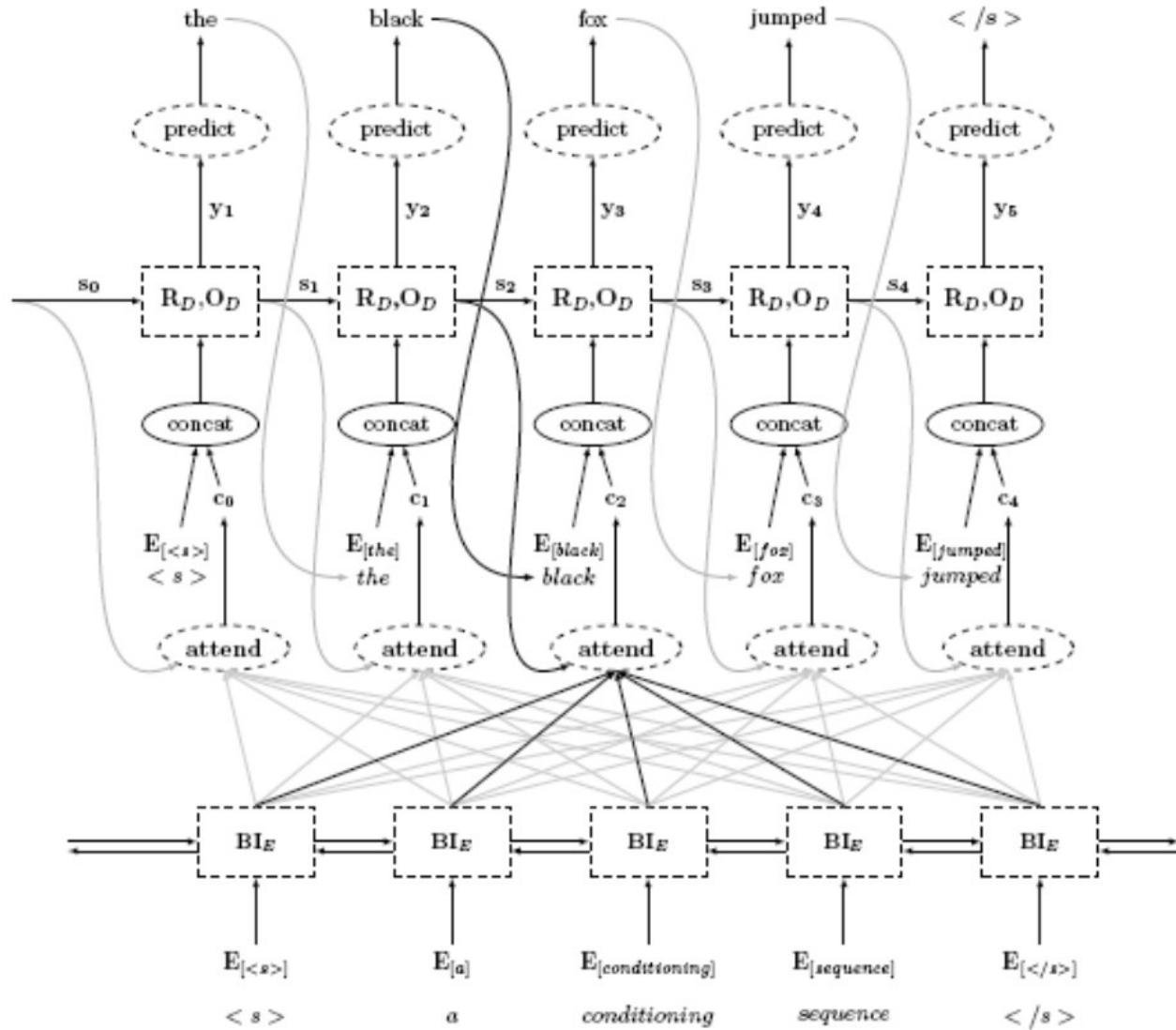
$$\bar{\alpha}_{[i]}^j = \text{MLP}^{\text{att}}([\mathbf{s}_j; \mathbf{c}_i])$$

$$\hat{t}_j \sim p(t_j \mid \hat{t}_{1:j-1}, \mathbf{x}_{1:n})$$

$$f(\mathbf{z}) = \text{softmax}(\text{MLP}^{\text{out}}(\mathbf{z}))$$

$$\text{MLP}^{\text{att}}([\mathbf{s}_j; \mathbf{c}_i]) =$$

# encoder-decoder with attention



# encoder-decoder with attention

- Encoder encodes a sequence of vectors,  $c_1, \dots, c_n$
- At each decoding stage, an MLP assigns a relevance score to each Encoder vector.
- The relevance score is based on  $c_i$  and the state  $s_j$
- Weighted-sum (based on relevance) is used to produce the conditioning context for decoder step  $j$ .

# encoder-decoder with attention

- Decoder "pays attention" to different parts of the encoded sequence at each stage.
- The attention mechanism is "soft" -- it is a mixture of encoder states.
- The encoder acts as a read-only memory for the decoder
- The decoder chooses what to read at each stage

# Attention

- Attention is very effective for sequence-to-sequence tasks.
- Current state-of-the-art systems all use attention.  
(this is basically how Machine Translation works)
- Attention makes models somewhat more ~interpretable.
- (we can see where the model is "looking" at each stage of the prediction process)

# Attention

The agreement  
on the European Economic  
Area was signed in August 1992 . <end>

L'accord sur la zone économique européenne a été signé en août 1992 . <end>

# Attention

in the evening until 21:00, there was a further 5mm rain on the town, after 6:00 am already dropped to Sunday during the night!  
am Abend bis 21 Uhr fielen weitere 5mm Regen auf die Stadt, nach 6:00 mm, die bereits in der Nacht zum Sonntag niedergegangen waren.

since then, the island authorities have tried to put an end to the illegal behaviour of non-alcoholic tourists in Magaluf by minimizing the number of participants in the notorious alcohol-free bar!  
die Inselbehörden haben seither versucht, das widrige Verhalten alkoholischer Urlauber in Magaluf zu stoppen, indem die Anzahl der Teilnehmer an den berüchtigten alkoholfreien getrankten Kneipen minimiert wurde.

## Attention is not Explanation

**Sarthak Jain**  
Northeastern University  
jain.sar@husky.neu.edu

**Byron C. Wallace**  
Northeastern University  
b.wallace@northeastern.edu

# Complexity

- Encoder decoder:
- Encoder-decoder with attention:

# Complexity

- Encoder decoder:  $O(n+m)$
- Encoder-decoder with attention:  $O(nm)$

# Beyond Seq2Seq

- Can think of a general design pattern in neural nets:
  - **Input**: sequence, query
    - **Encode** the input into a sequence of vectors
    - **Attend** to the encoded vectors, based on query  
(weighted sum, determined by query)
    - **Predict** based on the attended vector

# Attention Functions

$v$ : attended vec,  $q$ : query vec

$\text{MLP}^{\text{att}}(q;v) =$

- Additive Attention:  $ug(\mathbf{W}^1v + \mathbf{W}^2q)$
- Dot Product:  $v \cdot q$
- Bilinear attention:  $v^\top \mathbf{W} q$

# Additive vs Multiplicative

While the two are similar in theoretical complexity, dot-product attention is much faster and more space-efficient in practice, since it can be implemented using highly optimized matrix multiplication code.

While for small values of  $d_k$  the two mechanisms perform similarly, additive attention outperforms dot product attention without scaling for larger values of  $d_k$  [3]. We suspect that for large values of  $d_k$ , the dot products grow large in magnitude, pushing the softmax function into regions where it has extremely small gradients<sup>4</sup>. To counteract this effect, we scale the dot products by  $\frac{1}{\sqrt{d_k}}$ .

$$\frac{\mathbf{v} \cdot \mathbf{q}}{\sqrt{d_k}}$$

---

Attention Is All You Need

---

$d_k$  is the dimensionality of  $\mathbf{q}$  and  $\mathbf{v}$

Ashish Vaswani\*  
Google Brain  
avaswani@google.com

Noam Shazeer\*  
Google Brain  
noam@google.com

Niki Parmar\*  
Google Research  
nikip@google.com

Jakob Uszkoreit\*  
Google Research  
usz@google.com

Llion Jones\*  
Google Research  
llion@google.com

Aidan N. Gomez\* †  
University of Toronto  
aidan@cs.toronto.edu

Lukasz Kaiser\*  
Google Brain  
lukaszkaiser@google.com

Illia Polosukhin\* †  
illia.polosukhin@gmail.com

# Key-Value Attention

- Split  $v$  into two vectors  $v = [v_k; v_v]$ 
  - $v_k$ : key vector
  - $v_v$ : value vector
- Use key vector for computing attention  
$$\text{MLP}^{\text{att}}(q; v) = u g(\mathbf{W}^1 v_k + \mathbf{W}^2 q) \quad // \text{additive}$$
- Use value vector for computing attended summary

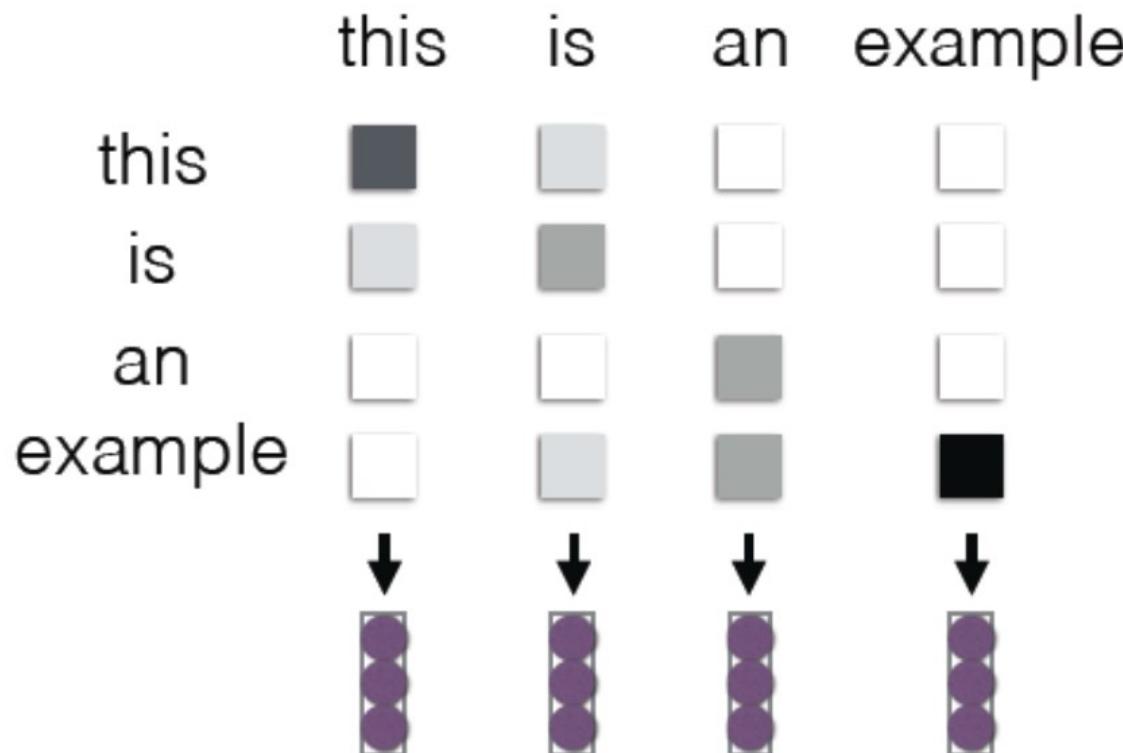
$$v^j = \sum_{i=1}^n \alpha_{[i]}^j \cdot (v_v)_i$$

# Multi-head Key-Value Attention

- For each head
  - Learn different projection matrices  $\mathbf{W}_q$ ,  $\mathbf{W}_k$ ,  $\mathbf{W}_v$
- $\text{MLP}^{\text{att}}(\mathbf{q}; \mathbf{v}) = [(\mathbf{v}_k \mathbf{W}_k) \cdot (\mathbf{q} \mathbf{W}_q)] / \sqrt{d_k}$
- For summary use  $\mathbf{v}_v \mathbf{W}_v$  (instead of  $\mathbf{v}_v$ )
- Train many such heads and
  - use  $\text{aggr}(\text{all such attended summaries})$

# Self-attention/Intra-attention

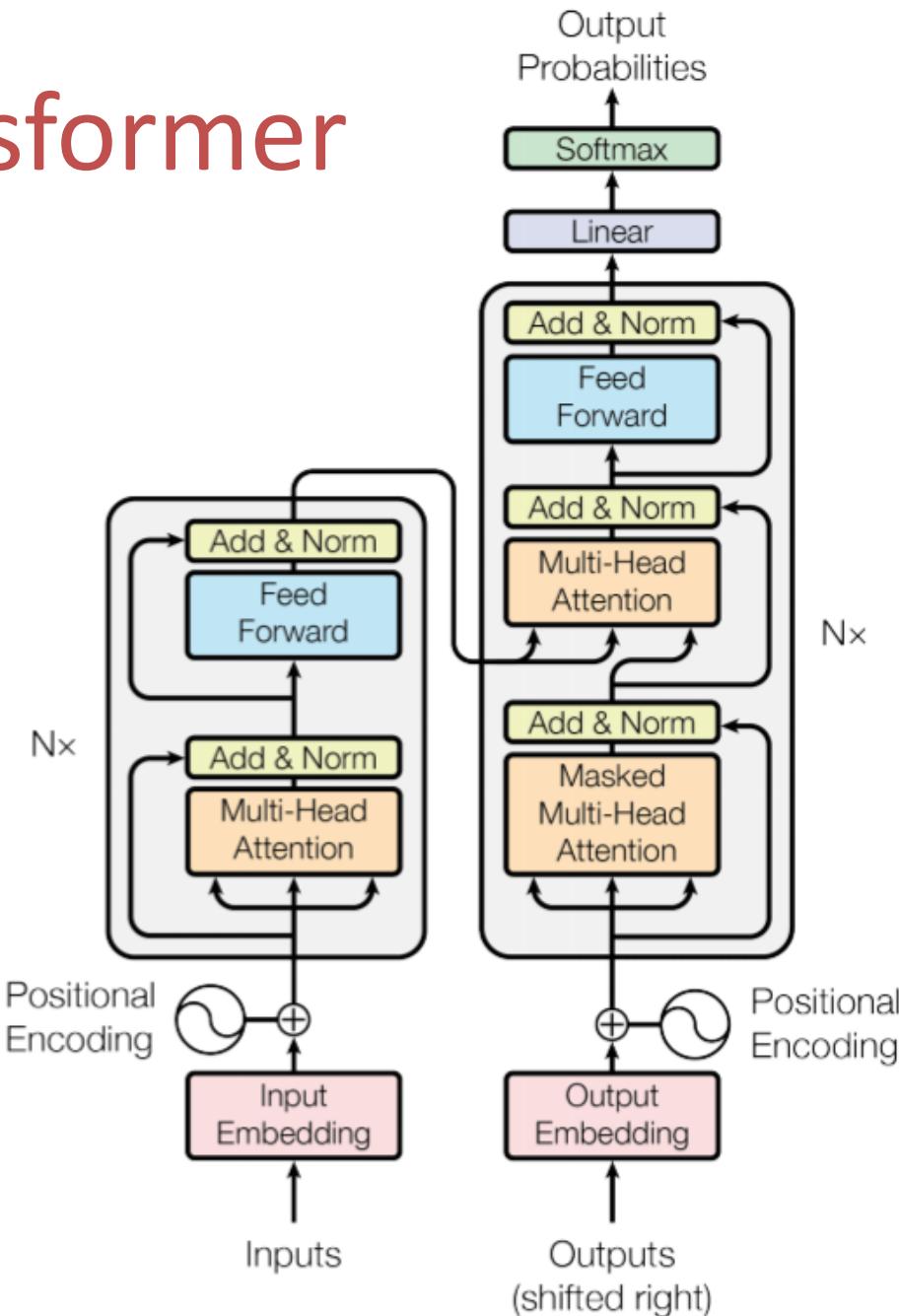
Each element in the sentence attends to other elements → context sensitive encodings!



# Do we “need” an LSTM?

- **They are slow**
  - Sequential nature of computation makes it tough to optimize operations on GPUs
  - Contrast to CNNs: convolutions completely parallelizable
- **They are not deep**
  - Vanishing gradient: aggravated for deeper networks
  - Less depth → low compositionality power of the network
  - Deepest LSTM networks are 8 layered
    - in-contrast to 50-layered Resnets
- **They don’t transfer well**
  - Networks trained on one task, do not generalize well to even other datasets in the same task, not to speak about other tasks
  - ImageNet-trained ResNet fine-tuned on many other datasets

# Transformer



# BERT: Transformer + PreTraining

- In NLP, we are interested in solving a variety of end tasks - Question Answering, Search, etc.
- One approach - train neural models from scratch
- Issue - this involves two things
  - Modelling of Syntax and Semantics of the language
  - Modelling of the end-task
- Pretraining - Learns the modelling of syntax and semantics - through another task
- So the current model can focus exclusively on modelling of end-task

# Pretraining - Masked Language Modelling

- How to pretrain?
- Which base task to choose:
  - Must have abundant data available
  - Must require learning of syntax and semantics
- Language Modelling (Self-supervision)
  - Does not require human annotated labels - abundance of sentences
  - Requires understanding of both syntax and semantics to predict the next word in sentence

# Summary

- RNNs are very capable learners of sequential data.
  - $n \rightarrow 1$ : (bi)RNN acceptor
  - $n \rightarrow n$  : biRNN (transducer)
  - $1 \rightarrow m$  : conditioned generation (conditioned LM)
  - $n \rightarrow m$  : conditioned generation (encoder-decoder)
  - $n \rightarrow m$  : encoder-decoder with attention
- Transformer
  - More scalable than RNN
  - May slowly replace RNNs