SUDHANSH PEDDABOMMA

노 +1 (858)-518-9808 | @ speddabomma@ucsd.edu | 🦠 sudhansh6.github.io | **in** sudhansh-peddabomma | 🖸 sudhansh6

EDUCATION

University of California San Diego

Sep 2023 - Jun 2025

Master of Science in Computer Science and Engineering

GPA 4.00/4.00

• Key Courses - Robotics, Recommender Systems, Quantum Cryptography, Convex Optimization

Indian Institute of Technology Bombay

Jul 2019 - Jul 2023

Bachelor of Technology with **Honors** in Computer Science and Engineering, Minor in **Entrepreneurship**

CPI 9.66/10

Key Courses - Computer Vision, Reinforcement Learning, Image Processing, Machine Learning and Deep Learning

EXPERIENCE

Data and Applied Scientist Intern | Microsoft India

May 2022 - Jul 2022

- Developed a decision-tree ranker for Outlook to suggest emails to users based on their past interactions
- Engineered a dataset by extracting user-dependent email attributes from context logs in a large-scale data pipeline
- Demonstrated an optimized ranking model using hierarchical feature sets, resulting in higher recall and click rate

Software Engineering Intern | FinIQ Consulting

Nov 2021 - Apr 2022

- Enhanced the firm's trading platform by integrating **pricing models for options** and target redemption forwards
- Designed a parser using Python to verify the format in email transactions, lowering the trade-discard rate up to 15%
- Deployed pricing strategies such as Black-Scholes and Heston models with Monte Carlo simulations on the platform

PUBLICATIONS

- 1. **S. Peddabomma**, S. Banerjee, R. Srivastava, A. Rajwade, **A likelihood based method for compressive signal recovery under Gaussian and saturation noise** in Signal Processing 2024 DOI: 10.1016/j.sigpro.2023.109349
- 2. **S. Peddabomma**, M. Betcke, A. Hauptmann, W. Hong, E. Macneil, K. Rullan, **Learned Stochastic Primal Dual for large scale and fully 3D tomographic reconstruction**Special Issue IOP 2023 (preprint)

KEY PROJECTS

3D Perception for Home Robots

Sep 2023 - Present

Graduate Student Researcher, Supervisor: Prof. Henrik Christensen

- Implemented dense SLAM algorithms with **NeRFs** and **Gaussian Splatting** for real-time 3D scene reconstruction
- Developed real-time **object segmentation** and point cloud mapping methods for precise grasp pose estimation

Image Reconstruction in Saturated Compressed Sensing | [REPORT]

Jul 2022 - Jun 2023

Bachelor's Thesis, Supervisor: Prof. Ajit Rajwade, IIT Bombay

Bachelor Thesis Project

- Proposed a novel likelihood maximization technique to recover signals, images, and audio from compressed measurements and obtained 20% lower RMSE over the state of the art methods even with high saturation effects
- Established robust performance guarantees with statistical methods and published a journal paper on this work

3D Tomography with Primal-Dual Neural Networks

May 2021 - Jul 2023

UCL Research Internship, Supervisor: Prof. Marta Betcke, University College London

- Developed a stochastic neural-network architecture of primal-dual algorithm for online reconstruction of 3D volumes
 from tomographic projections and obtained 99.6 % structural similarity in challenging low-dosage conditions
- Built a Python library with custom network layers in Tensorflow for reconstruction using cone-vector tomography

OTHER PROJECTS

- Image Colorization GAN. Deployed a web-app to color grayscale images using pix2pix U-Net architecture GAN
- Sudoku Solver. Created an Augmented Reality app to solve Sudoku from live feed, with robust real-time performance
- Autonomous Robot. Developed a Roomba-like robot with visual-SLAM using EKF and A* path planning on ROS

SKILLS

Programming

C++, C, Python, MATLAB, Java, Bash, VHDL, SQL, HTML, Javascript

Tools & Software Expertise in

PyTorch, ROS, TensorFlow, Jax, OpenCV, CUDA, Angular, Matplotlib, Arduino, Raspberry Pi Computer Vision, Artificial Intelligence, Image Processing, Algorithms, Statistical Modeling

AWARDS AND LEADERSHIP

■ Teaching Assistant, UC San Diego | Quantum Cryptography

Jan 2024 - Present

■ Team Leader at Exofly | Tech Team IITB

Mar 2022 - Apr 2023

- Led a 40-member team and secured funding to design a safe and compact manned eVTOL aerial vehicle
- o Designed a controller on Simulink, performing sensor fusion for localization with an Extended Kalman Filter
- Secured the prestigious KC Mahindra scholarship of INR 500,000 for post-graduate studies

(2023)

Secured 3rd rank in Statistics Olympiad conducted by C.R. Rao AIMSCS across India and Sri Lanka

(2019)