

Searching and Sorting: Part 1

DSA

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Objectives

- What you will learn today
 - Linear & Binary Search
 - Binary Search on Answers
 - Bubble, Selection, Insertion Sort

common goal

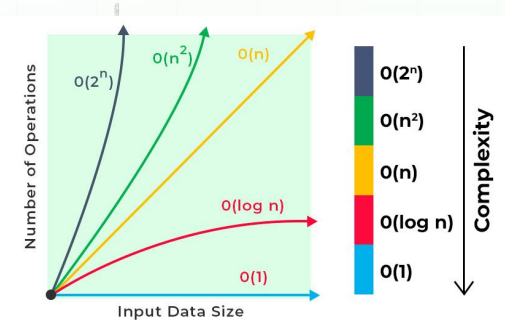




Introduction to Searching

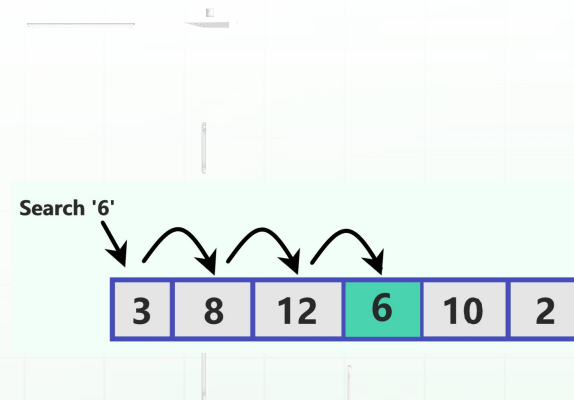
Why Search?

- Searching is the single most common operation a computer does
- Use Cases
 - Google: How does Google find the most relevant sites out of billions?
 - E-commerce: How does Amazon make it easy to explore ALL their products?
 - Your IDE: When you Ctrl/Cmd+Click on a method call, how does the IDE immediately allow you to visit the method definition?
 - Netflix: How do they find and suggest content to you from a library of tens of thousands?
- In such scenarios, search and optimal performance matters.
- Why does optimal matter? Consider a problem: Searching 1,000,000,000 (1 Billion) items
 - $O(n)$: 1,000,000,000 operations (take several seconds)
 - $O(\log n)$: 30 operations (instant)



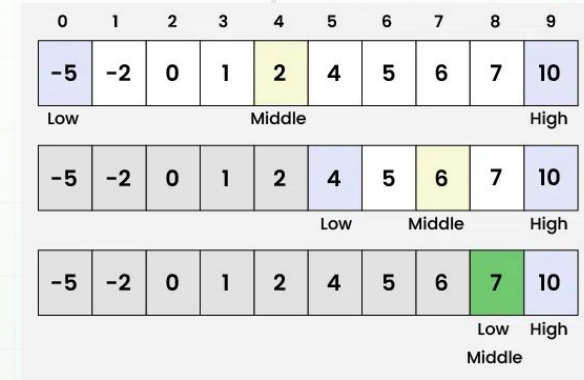
Linear Search

- Concept
 - The most basic, common-sense search
 - It sequentially checks every element in a collection, one by one, until the target is found
- Approach
 - Use a for loop to iterate from $i = 0$ to $\text{array.length} - 1$.
 - Inside the loop, check if $\text{array}[i] == \text{target}$.
 - If a match is found, return i (the index).
 - If the loop finishes without a match, return -1 .
- Key Trait
 - Works on any collection, sorted or unsorted. This is its main advantage
- Time Complexity: $O(n)$. In the worst case, we must check every single element
- Time Complexity: $O(1)$. We only use a few variables for the loop; no extra memory is allocated



Binary Search

- The Requirement: The array MUST be sorted first
- Concept
 - A highly efficient "divide and conquer" algorithm.
 - Check the middle element (not the first).
 - If our target is smaller, we throw away the entire right half of the array.
 - If our target is larger, we throw away the entire left half.
- Approach
 - Set two pointers: low = 0 and high = array.length - 1.
 - Loop while (low <= high).
 - Find the middle: $mid = low + (high - low) / 2$.
 - If `array[mid] == target`: We found it! return mid.
 - If `target < array[mid]`: Throw away the right. `high = mid - 1`.
 - If `target > array[mid]`: Throw away the left. `low = mid + 1`.
- Time Complexity: $O(\log n)$. We cut the search space in half with every single guess
- Space Complexity: $O(1)$. We only store three variables: low, high, and mid



Binary Search on Answers

- Concept
 - This is a problem-solving pattern, not a direct array search.
 - We use the idea of binary search to find a specific answer that exists within a large, continuous range of possibilities
- Example Problem: "What is the square root of 2100?"
- Approach
 - We know the answer must be in a range, e.g., $[0 \dots 2100]$. This is our "search space."
 - Let's binary search this answer range:
 - $low = 0$, $high = 2100$.
 - Guess $mid = 1050$. Is $1050 * 1050 > 2100$? Yes. The answer must be smaller. New range: $[0 \dots 1049]$.
 - ...this continues until low and high converge on the answer
- You can use binary search for any answer where you need to quickly check if your "guess" is too high or too low



Introduction to Sorting

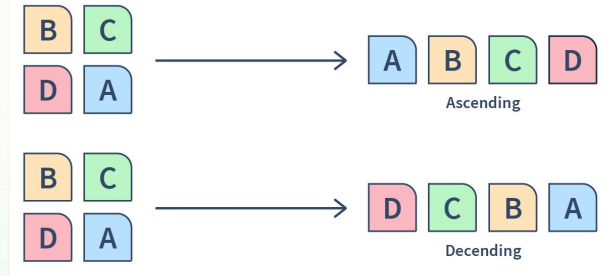
Why Sort?

- Concept:

- The process of arranging items in a specific order (e.g., ascending).
- We will start with three fundamental (but slow) sorts.

- Key Terminology

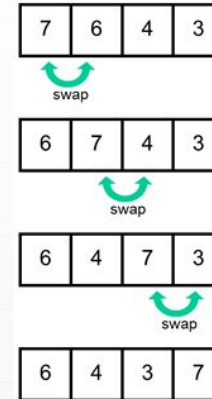
- **In-Place**: The algorithm sorts within the original array, without creating a new one. (Uses $O(1)$ space).
- **Stable**: A sort is "stable" if elements with identical values (e.g., two 5s) are guaranteed to remain in their original relative order after the sort is complete



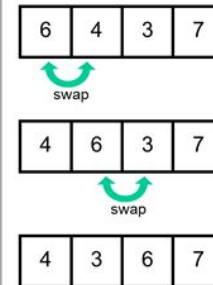
Bubble Sort

- Concept
 - Compares adjacent pairs, swapping them if they are in the wrong order.
 - This "bubbles" the largest element to the end of the array on each pass
- Approach
 - Use a nested for loop.
 - The outer loop (i) controls how many passes we do (or how many elements are "locked in" at the end).
 - The inner loop (j) does the comparisons and swaps, from 0 up to $n-i-1$.
 - if $(\text{nums}[j] > \text{nums}[j+1])$, we swap
- Time Complexity: $O(n^2)$. A nested loop structure where we compare n elements n times
- Time Complexity: $O(1)$. It's fully in-place; we only need a temp variable for swapping

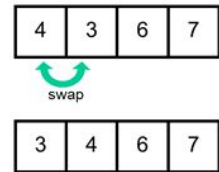
First pass



Second pass

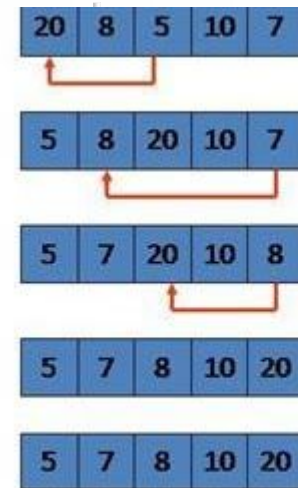


Third pass



Selection Sort

- Concept
 - "Selects" the minimum element from the unsorted part of the list.
 - Swaps that minimum element with the first element of the unsorted part.
- Approach
 - The outer loop (i) iterates from 0 to n-1, tracking the start of the "unsorted" section.
 - In the inner loop (j), we don't swap. We just find the index of the minimum element (min_index).
 - After the inner loop finishes, we perform one swap: `swap(nums[i], nums[min_index])`
- Time Complexity: $O(n^2)$. The "find min" operation ($O(n)$) is inside the main loop ($O(n)$)
- Time Complexity: $O(1)$. It's fully in-place



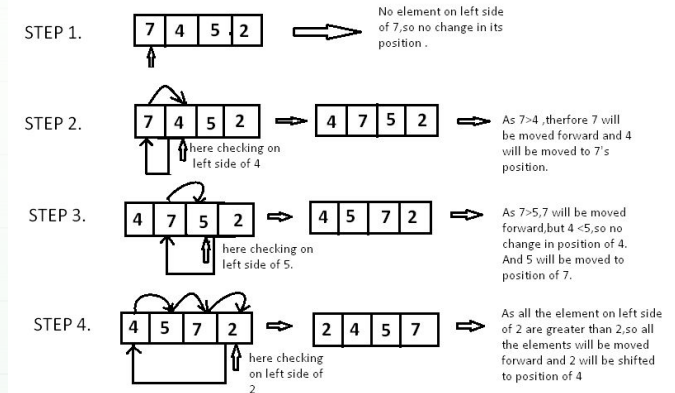
Insertion Sort

• Concept

- Builds the final sorted array one item at a time.
- It takes the next unsorted element (the key) and "inserts" it into its correct position within the already sorted part on the left.

• Approach

- The outer loop (i) starts at 1 (the first "unsorted" element).
 - Store `nums[i]` as our key.
 - Use a while loop (or inner for loop) to "shift" all elements in the sorted part that are greater than our key one position to the right.
 - When the shifting is done, insert the key into the open slot.
- Time Complexity: $O(n^2)$
 - Best Case: If the array is already sorted, it's $O(n)$ because the inner while loop never runs.
 - Time Complexity: $O(1)$. It's fully in-place





That's for today!
Any questions?