

Functional analysis

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PART 1

PRELIMINARIES

1.1 RELATIONSHIPS BETWEEN STRUCTURES

Let X be a set.

Definition 1.1

1. A basis of a topology is a collection \mathcal{B} of subsets of X satisfying the following properties:
 - i. (cover) The base elements cover X .
 - ii. (intersection) For every $B_1, B_2 \in \mathcal{B}$, if $x \in B_1 \cap B_2$, then there is a $B_x \in \mathcal{B}$ such that $x \in B_x \subseteq B_1 \cap B_2$.
2. A metric is a function $d(\cdot, \cdot) : X \times X \rightarrow [0, \infty)$ such that for all vectors $x, y, z \in X$, we have
 - i. (identity of indiscernibles) $d(x, y) = 0$ iff $x = y$.
 - ii. (symmetry) $d(x, y) = d(y, x)$.
 - iii. (triangle inequality) $d(x, z) \leq d(x, y) + d(y, z)$.
3. A norm is a function $\|\cdot\| : X \rightarrow [0, \infty)$ such that for all vectors $x, y \in X$ and scalar $\alpha \in \mathbb{C}$, we have
 - i. (identity of indiscernibles) $\|x\| = 0$ iff $x = 0$.
 - ii. (scaling) $\|\alpha x\| = |\alpha| \|x\|$.
 - iii. (triangle inequality) $\|x + y\| \leq \|x\| + \|y\|$.
4. An inner product is a function $\langle \cdot, \cdot \rangle : X \times X \rightarrow \mathbb{C}$ such that for all vectors $x, y, z \in X$ and scalar $\alpha \in \mathbb{C}$, and we have
 - i. (positive-definiteness) $\langle x, x \rangle \geq 0$ and $\langle x, x \rangle = 0$ iff $x = 0$.
 - ii. (conjugate symmetry a.k.a. Hermitian) $\langle x, y \rangle = \overline{\langle y, x \rangle}$.
 - iii. (sesquilinearity) $\langle \alpha x + y, z \rangle = \alpha \langle x, z \rangle + \langle y, z \rangle$.

Proposition 1.2 Inner product \implies norm \implies metric \implies topology.

Proof.

A. inner product \implies norm. Define the norm as $\|\cdot\| = \sqrt{\langle \cdot, \cdot \rangle}$.

- i. $\|x\| = 0 \iff \|x\|^2 = 0 \iff \langle x, x \rangle = 0 \iff x = 0$ using 4.i.
- ii. $\|\alpha x\|^2 = \langle \alpha x, \alpha x \rangle = \langle \bar{\alpha} \alpha x, x \rangle = \bar{\alpha} \alpha \langle x, x \rangle = |\alpha|^2 \|x\|^2$ using 4.ii and 4.iii.
- iii.

$$\begin{aligned}
\|x + y\|^2 &= \langle x + y, x + y \rangle \\
&= \langle x, x \rangle + \langle x, y \rangle + \langle y, x \rangle + \langle y, y \rangle && [4.iii] \\
&= \|x\|^2 + \langle x, y \rangle + \overline{\langle x, y \rangle} + \|y\|^2 && [4.ii] \\
&= \|x\|^2 + 2\Re \langle x, y \rangle + \|y\|^2 \\
&\leq \|x\|^2 + 2|\langle x, y \rangle| + \|y\|^2 \\
&\leq \|x\|^2 + 2\|x\|\|y\| + \|y\|^2 && [1.2] \\
&= (\|x\| + \|y\|)^2.
\end{aligned}$$

B. *norm* \Rightarrow *metric*. Define the metric as $d(x, y) = \|x - y\|$.

- i. $d(x, y) = 0 \iff \|x - y\| = 0 \iff x - y = 0 \iff x = y$ using 3.i.
- ii. $d(x, y) = \|x - y\| = \|-(y - x)\| = |-1|\|y - x\| = d(y, x)$ using 3.ii.
- iii. $d(x, z) = \|x - z\| = \|(x - y) + (y - z)\| \leq \|x - y\| + \|y - z\| = d(x, y) + d(y, z)$ using 3.iii.

C. *metric* \Rightarrow *topology*. Define the basis of the topology as open balls of the form

$$D_r(x_0) = \{x \in X \mid d(x, x_0) < r\}, \quad x_0 \in X, r > 0.$$

That is, $\mathcal{T} = \tau(\mathcal{B})$, where $\mathcal{B} = \{D_r(x_0) \mid x_0 \in X, r > 0\}$.

All we have to do is show that \mathcal{B} is a basis. The cover is obvious. Note that for any $B_1, B_2 \in \mathcal{B}$, we can write $B_1 = D_{r_1}(x_1), B_2 = D_{r_2}(x_2)$. Suppose $x \in B_1 \cap B_2$. Then $x \in D_r(x) \subseteq D_{r_1}(x_1) \cap D_{r_2}(x_2)$ if $r \leq \min\{r_1 - d(x, x_1), r_2 - d(x, x_2)\}$, and we are done.

The topology induced by the metric is called the *metric topology*.

□

1.2 STRONG, WEAK AND WEAK* CONVERGENCE

Disclaimer: This section is shamelessly copied from [Christopher Heil's notes](#).

Definition 2.1 Let X be a normed vector space, and $x_n, x \in X$. We define the following convergences as $n \rightarrow \infty$.

$$(\text{strong}) \quad x_n \rightarrow x \iff \|x_n - x\| \rightarrow 0$$

$$(\text{weak}) \quad x_n \xrightarrow{w} x \iff \forall \phi \in X^*, \quad (x_n - x, \phi) \rightarrow 0$$

Definition 2.2 Let X be a normed vector space, and $\phi_n, \phi \in X^*$. We define the following convergences as $n \rightarrow \infty$.

$$(\text{strong}) \quad \phi_n \rightarrow \phi \iff \|\phi_n - \phi\| \rightarrow 0$$

$$(\text{weak}) \quad \phi_n \xrightarrow{w} \phi \iff \forall \zeta \in X^{**}, \quad (\phi_n - \phi, \zeta) \rightarrow 0$$

$$(\text{weak}^*) \quad \phi_n \xrightarrow{w^*} \phi \iff \forall x \in X, \quad (x, \phi_n - \phi) \rightarrow 0$$

Remark 2.3 Weak* convergence is simply pointwise convergence for the functionals ϕ_n .

Proposition 2.4 (strong \Rightarrow weak \Rightarrow weak* for convergence) Suppose $\phi_n, \phi \in X^*$.

Then $\phi_n \rightarrow \phi \Rightarrow \phi_n \xrightarrow{w} \phi \Rightarrow \phi_n \xrightarrow{w^*} \phi$.

The second implication reverses if X is reflexive.

Proof. strong \Rightarrow weak: $(x_n - x, \phi) \leq \|x_n - x\| \|\phi\| \rightarrow 0$.

weak \Rightarrow weak*: $(x, \phi_n - \phi) = (\phi_n - \phi, x^{**}) \rightarrow 0$.

The claim about the reverse implication is now obvious.

Counterexample for converse of the first implication: Suppose $X = \ell^2(\mathbb{N})$. Then $e_n \xrightarrow{w} 0$, but $\|e_n - 0\| = 1 \not\rightarrow 0$. \square

Proposition 2.5 In Hilbert spaces, weak convergence plus convergence of norms ($\|x_n\| \rightarrow \|x\|$) is equivalent to strong convergence.

Proof. $\|x_n - x\|^2 = \langle x_n - x, x_n - x \rangle = \langle x_n - x, x_n \rangle - \langle x_n - x, x \rangle \rightarrow 0$. \square

Proposition 2.6 Let H and K be Hilbert spaces, and let $T \in B(H, K)$ be a compact operator.

Show that $x_n \xrightarrow{w} x \Rightarrow Tx_n \rightarrow Tx$.

Thus, a compact operator maps weakly convergent sequences to strongly convergent sequences.

Proof. *Disclaimer:* Stolen from [MSx1142451](#).

$Tx_n \xrightarrow{w} Tx$ by continuity. Thus if any subsequence has a strong limit, it certainly is Tx . But compactness guarantees every subsequence has a subsequence that converges to something: that something is Tx by uniqueness, and so by our above equivalence with convergence, we have $Tx_n \rightarrow Tx$. \square

PART 2

HILBERT SPACES

2.1 BASICS

In what follows, $(H, \langle \cdot, \cdot \rangle)$ is a Hilbert space, and we write $x \perp y$ iff $\langle x, y \rangle = 0$.

Theorem 1.1 (Pythagorean) If $x, y \in H$ and $x \perp y$, then $\|x + y\|^2 = \|x\|^2 + \|y\|^2$.

Proof.

$$\begin{aligned}\|x + y\|^2 &= \langle x + y, x + y \rangle \\ &= \langle x, x \rangle + \langle x, y \rangle + \langle y, x \rangle + \langle y, y \rangle \\ &= \|x\|^2 + \|y\|^2.\end{aligned}$$

□

Theorem 1.2 (Cauchy–Schwarz inequality) If $x, y \in H$, then $|\langle x, y \rangle| \leq \|x\| \|y\|$.

Proof. (norm expansion) Note that $0 \leq \|x - \lambda y\|^2 = \|x\|^2 - 2\Re(\bar{\lambda} \langle x, y \rangle) + |\lambda|^2 \|y\|^2$, so if we take $\lambda = \frac{\langle x, y \rangle}{\|y\|^2}$, we get $0 \leq \|x\|^2 - \frac{|\langle x, y \rangle|^2}{\|y\|^2}$, which gives us the required result. □

Proof. (projection) Note that we can write $x = x_{\parallel} + x_{\perp}$, where x_{\parallel} is the component of x in the direction of y and x_{\perp} is the component of x in the direction perpendicular to y . Explicitly, $x_{\parallel} = \langle x, \hat{y} \rangle \hat{y} = \langle x, y \rangle \frac{y}{\|y\|^2}$. Using the Pythagorean theorem (1.1), we get

$$\|x\|^2 = \|x_{\parallel}\|^2 + \|x_{\perp}\|^2 \geq \|x_{\parallel}\|^2 = \frac{|\langle x, y \rangle|^2}{\|y\|^2}.$$

□

Theorem 1.3 (Riesz–Fischer) $L^p(X, \mu)$ is complete for $p \in [0, \infty]$.

Proof. Let (f_n) be a Cauchy sequence in L^p . We have to show that there exists $f \in L^p$ such that $f_n \rightarrow f$ in L^p .

Since (f_n) is Cauchy, for every $\varepsilon > 0$, there exists $N \in \mathbb{N}$ such that for every $n, m > N$, we have $\|f_n - f_m\|_p < \varepsilon$. Therefore, there exists a subsequence (f_{n_k}) such that $\|f_{n_{k+1}} - f_{n_k}\|_p < 2^{-(k+1)}$ for every $k \in \mathbb{N}_0$, where we adopt the convention that $f_{n_0} \equiv 0$.

Note that $f_{n_k} = \sum_{j=0}^{k-1} (f_{n_{j+1}} - f_{n_j})$ for each $k \in \mathbb{N}$.

Define $f = \sum_{j=0}^{\infty} (f_{n_{j+1}} - f_{n_j})$. Clearly, $f_{n_k} \rightarrow f$ pointwise. Moreover, if $g = \sum_{j=0}^{\infty} |f_{n_{j+1}} - f_{n_j}|$, then $|f_{n_k}| \leq g$ and $\|g\|_p \leq \sum_{j=0}^{\infty} \|f_{n_{j+1}} - f_{n_j}\|_p \leq 1$ using the triangle inequality. Therefore, by Lebesgue's dominated convergence theorem, $f_{n_k} \rightarrow f$ in L^p . Similar to g , we get $\|f\|_p \leq 1$, showing $f \in L^p$. All that is left to show is that $f_n \rightarrow f$ in L^p . Using the fact that the sequence is Cauchy, we get

$$\|f_n - f\|_p \leq \|f_n - f_{n_k}\|_p + \|f_{n_k} - f\|_p \rightarrow 0 \text{ as } n \rightarrow \infty.$$

□

PART 3

OPERATOR THEORY

3.1 ELEMENTARY IDEAS

A great source is [Trace class operators and Hilbert-Schmidt operators by Jordan Bell](#).

3.1.1 Intuition

On a separable Hilbert space, we have

▷ $T \in \mathcal{B}^\infty \iff \lambda \in \ell^\infty$ (bounded)

Example $I : \ell^2 \rightarrow \ell^2 : e_n \mapsto e_n$.

▷ $T \in \mathcal{B}_0 \iff \lambda \in c_0$ (compact)

Example $T : \ell^2 \rightarrow \ell^2 : e_n \mapsto \frac{1}{\sqrt{n}} e_n$.

▷ $T \in \mathcal{B}^2 \iff \lambda \in \ell^2$ (Hilbert-Schmidt)

Example $T : \ell^2 \rightarrow \ell^2 : e_n \mapsto \frac{1}{n} e_n$.

▷ $T \in \mathcal{B}^1 \iff \lambda \in \ell^1$ (trace-class)

Example $T : \ell^2 \rightarrow \ell^2 : e_n \mapsto \frac{1}{n^2} e_n$.

▷ $T \in \mathcal{B}_{00} \iff \lambda \in c_{00}$ (degenerate or finite rank)

Example $T : \ell^2 \rightarrow \ell^2 : e_n \mapsto \alpha_n e_n \mathbb{1}_{[N]}(n)$ for $\alpha_n \in \mathbb{C}$ and $N \in \mathbb{N}$.

Remark 1.1 Since the dual of c_0 is ℓ^1 and the dual of ℓ^1 is ℓ^∞ , we have $\mathcal{B}_0^* = \mathcal{B}^1$ and $(\mathcal{B}^1)^* = \mathcal{B}^\infty$. Similarly, $(\mathcal{B}^2)^* = \mathcal{B}^2$.

Theorem 1.2 (Operator inclusions) $\mathcal{B}_{00} \subset \mathcal{B}^1 \subset \mathcal{B}^2 \subset \mathcal{B}_0 \subset \mathcal{B}^\infty$

Proof.

▷ $\mathcal{B}_{00} \subset \mathcal{B}^1$ Trivial

▷ $\mathcal{B}^1 \subset \mathcal{B}^2$

▷ $\mathcal{B}^2 \subset \mathcal{B}_0$

▷ $\mathcal{B}_0 \subset \mathcal{B}^\infty$ ((<BMC2009>), Proposition 4.6) If T is unbounded, we can find a sequence of unit vectors (e_n) such that $\|Te_n\| \nearrow \infty$. So Te_n cannot have a convergent subsequence, for if $Te_n \rightarrow x$, then $\|Te_n\| \rightarrow \|x\|$.

□

Proposition 1.3 For $T \in \mathcal{B}^\infty$, $\|T\|_\infty = \sup \{|\langle Tx, y \rangle| : \|x\| = 1, \|y\| = 1\}$.

Proof.

(≤) Since $\|Tx\| = \frac{\|Tx\|^2}{\|Tx\|} = \frac{\langle Tx, Tx \rangle}{\|Tx\|} = \left\langle Tx, \frac{Tx}{\|Tx\|} \right\rangle$, we have

$$\|T\|_\infty = \sup \{\|Tx\| : \|x\| = 1\} \leq \sup \{|\langle Tx, y \rangle| : \|x\| = 1, \|y\| = 1\}.$$

(\geq) Since $\langle Tx, y \rangle \leq \|Tx\| \|y\| \leq \|T\|_\infty \|x\| \|y\|$, we have

$$\sup \{ |\langle Tx, y \rangle| : \|x\| = 1, \|y\| = 1 \} \leq \|T\|_\infty .$$

□

3.1.2 Projection operators

Proposition 1.4 $\|P\|_\infty \leq 1$.

Proof. Since $\|Px\|^2 = \langle Px, Px \rangle = \langle P^*Px, x \rangle = \langle PPx, x \rangle = \langle Px, x \rangle \leq \|Px\| \|x\|$, we have $\|P\|_\infty \leq 1$. □

Proposition 1.5 *A projection operator is compact iff its image is finite dimensional.*

Proof.

(\Rightarrow) Let $P : H \rightarrow H$ be a projection operator, so that $P^2 = P$, or $P(P - I) = 0$.

(\Leftarrow) Since the image is finite dimensional, fix an orthonormal basis e_1, \dots, e_n of $\text{im } T$.

□

3.2 OPTIMIZATION

3.2.1 Duality in optimization is the same as duality in functional analysis

For an various intuitions of duality in optimization, see [MSx223235](#).

Let X and Y be Banach spaces, and X^* and Y^* be their (algebraic?) duals. Consider the two problems, with ϕ_0, y_0 fixed. Here (\cdot, \cdot) denotes the canonical duality pairing.

$$\begin{array}{llll}
 \max & (\phi_0, x) & \min & (\psi, y_0) \\
 \text{(Primal)} & \text{s.t.} & \text{(Dual)} & \text{s.t.} \\
 & Tx \leq y_0 & & T^*\psi \geq \phi_0 \\
 & x \geq 0 & & \psi \geq 0
 \end{array}$$

See the following diagram for more details.

$$\begin{array}{ccccc}
 & x & \xrightarrow{T} & Tx & \\
 x \in & X & \xrightarrow{T} & y_0 & \ni Tx, y_0 \\
 & \downarrow & & \downarrow & \\
 \phi_0, T^*\psi \in & X^* & \xleftarrow{T^*} & y_0^* & \ni \psi \\
 & T^*\psi & \xleftarrow{T^*} & \psi &
 \end{array}$$

BIBLIOGRAPHY