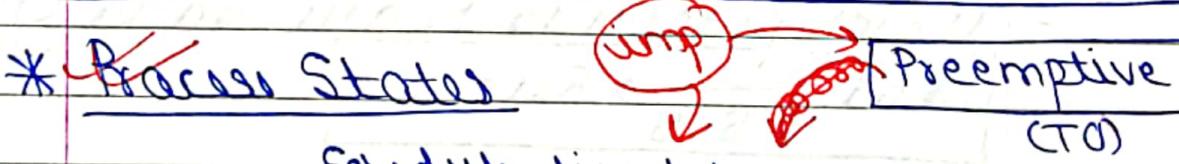
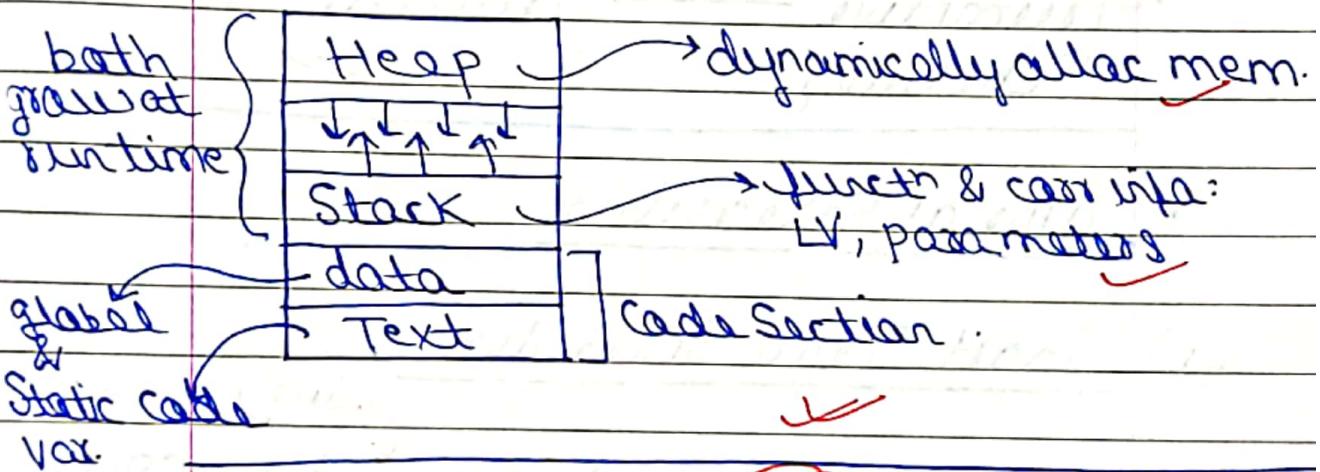


# OPERATING SYSTEMS

[Avg: 7M - Imp] ✓

## 1 PROCESS

- OS acts as interface b/w h/w & s/w,
- Process: Program under execution.  
(loaded in MM from SM). [Hard Disk]



- ✓ **Ready:** loaded in MM (in Partition).
- ✓ **Running:** CPU executes from MM.
- ✓ When P hits i/o event  $\Rightarrow$  WS.

\* Timeout: max amt of time, it can spend with CPU.  
 ⇒ Ready & Waiting, both are implemented as queue, with linkedlist. (PCBs)

Non-Premptive Scheduling → P1 terminates  
 Premptive Scheduling → P1 waits for I/O went.

### \* Type of Schedulers

#### (i) Short Term Scheduler

- Which process to be assigned to CPU.
- Ready → Running

(ii) Long Term Scheduler → doesn't do any [context switch of multi prog]  
 New → Ready (MM)  
 (already in HD) → Ready Suspended (in HD)

#### (iii) Medium term Scheduler

- Involves in Swapping from SM to MM & vice-versa, when Process hits I/O wait.  
 - which Process must be sent or brought from SM, at the time of Swapping.

[eq] → Pg 11 ✓

### \* Process Control Block (PCB)

Process ID	
Process State	
CPU Registers	
PC	
CPU scheduling info	→ WT, AT, TAT, BT
Memory manag info	→ PT
Accounting info	→ Amt of real time.
Device info & OpenFiles	→ List of resources.

### \* Process Switching

P1 → (starts PCB1)

P2 → (leads PCB2)

- Saving current contexts (PCB) & loading the contexts of new Process: Context Switch

### \* Dispatcher

main control of CPU to that Process  
 [This interrupt]

### Scheduler

to take decision that which process to be exec next  
 [This doesn't interrupt]

\* Dispatcher latency: time taken to switch from 1 process to another

### \* Operations on Process

#### ① Process Creation

- fork(): returns -1 : failure  
returns 0 : child process  
returns Pid child : Parent

[eg] → Pg 19 [order of execn] (VA)

[eg] → Pg 21 [if n fork() → no. of P =  $2^n$ ]

[eg] → Pg 22 (10 times) ✓

if fork(), executed n times:

$$\text{No. of Child Process} = 2^n - 1 \quad \checkmark$$

#### ② Process Termination

- Normal / exit() / Simult. termination of Parent & child / segment

### \* Scheduling Criteria

- 1 CPU utilization : % of time CPU used
- 2 throughput : no. of processes exec per unit time

imp

- 3 turn Around time : entire time Gap b/w Process Arrival & completion
- 4 Waiting time : amt of time in Ready Q
- 5 Response time : time taken to produce first response from CPU

### ② CPU Scheduling Algorithms

#### 1) FCFS (First Come First Serve)

- Non-preemptive algo.

- suffers from Conway effect: larger jobs executed b4 shorter jobs, leads to delay in shorter jobs execution.

[eg] → Pg 38 [WT = 4.5, TAT = 9]. ✓

[eg] → Pg 40 [% CPU utilin] ✓

[eg] → Pg 43 [X = 28.6] ✓

#### 2) SJF (Shortest Job First)

- non-preemptive

- No Conway effect here

#### 3) SRTF (Shortest remaining time first)

- preemptive

late coming Shorter jobs will take control from longer time, current job

eg → Pg 47 [SJF & SRTF] ✓ drawback

Process can suffer from Starvation  
[Large Jobs Starve]

\* Predicting next CPU Burst

$$T_{n+1} = \alpha t_n + (1-\alpha) T_n$$

(CBT)

- exponential avg.

$T_{n+1}$ : pred. value of next CPU B.

$t_n$ : actual CPU Burst at nth item

$T_n$ : predicted CPU B at nth item

#### 4) Priority Scheduling

if Priority on BT : SJF/SRTF

if Priority on AT : FCFS ✗

eg → Pg 53 (Preempt & Non-Preempt. Priority) ✓

- b/w Prior. Process can suffer from Starv.  
Solution: Aging (improve priority  
of process) as waiting time increases

eg → Pg 60 {3, 2, 1} ✓

imp

Page No.: 6  
Date: youva

Page No.: 7  
Date: youva

→ Pg 62 & 63 [SRTF & Priority] ✓

#### 5) Round Robin Scheduling Algorithm

- CPU time equally divided among Process

- used in time sharing

✓ Preemptive FCFS : RR

come back:  $t < (n-1)q$

After

- RRA produces excellent response time.

- TQ & Avg TAT varies irregularly

eg → Pg 68 (Response Time b/w FCFS & RR) ✓

- When TQ ↑, it behaves like FCFS.

- if CS ↑, RT ↓ [better resp.]

Niraj

Frost

eg → Pg 17 (Rev Copy) [RR] ✗

- Throughput is poor in RR.

- RT best in RR.

- SRTF is optimal (throughput, Avg WT)

Gate

### 6) LRTF [Largest remain time first] Preemptive

- largest job given max priority.

eg → Pg 18 [Rev copy] ✓

### 7) Multilevel Queue Preemptive

System Process

Interactive Process

Inter-editing Process

Batch Process

User Process

Imp

foreground

(Served using RR)

background

(Served using FCFS)

[Priority]

### 8) Multilevel Feedback Queue

H

Q1

TQ = 8 ms

Imp

Q2

TQ = 16 ms

Each queue

→ Process inside Q3 will be randomly when Q1, Q2 empty.

- excellent response time. [like RR]

### 9) HRRN (Highest response Ratio next)

- Non-Preemptive

- give priority to shorter jobs, but due to the cost of longer jobs in queue.

$$R = W + S$$

S

eg → Pg 78 P1 P4 P3 P2 ✓

eg → Pg 20 (LRTF - trick) ✓

GATE

eg → Pg 84 (RR) ✓

Imp

eg → Pg 87 (CPU & I/O B) ✓

Imp

## INTER PROCESS COMMUNICATION

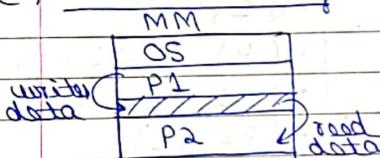
- Process → independent

→ cooperative

→ 2 techniques

Imp

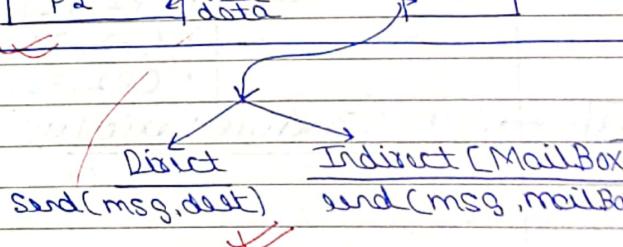
### (i) Shared Memory



### (ii) Message Passing

MM

Snd( )  
rcv( )



\* Blocking Send / rcv: sender/receiver gets blocked (can't perform any comp) until send/rcv opn completed.  
 Overall  $\rightarrow$  communication time + computation time

\* Non-Blocking Send / rcv:

Overall exec time  $\rightarrow$  max (communication time, computation time)

#### (4) Concurrency

- (i) Serial exec: coffee m/c made by one
- (ii) Parallel exec: 10 coffee m/c, parallelly, many served.
- (iii) Concurrent exec: 1 coffee m/c, 2 people, 1M, 1F will be served concurrently.

P1	P2	• (P1, P2)
S1	S2	• (P1, P2, P1, P2)
S3	S4	• (P1, P2, P1) • (P2, P1) • (P2, P1, P2, P1) • (P2, P1, P2)

[eg]  $\rightarrow$  Pg 95 [Concurrent exec]

Page No: 10  
Date: Youva

lock of mutual exclusion

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Date: Youva

\* Due to improper synchronization: it leads to incorrect result - race condition  
 eg  $\rightarrow$  Pg 98 [register Value]

#### (5) Process Synchronization

- CS : Place where commonly Shared V. are kept: Gate

\* Solutions to CS Problem

do { entry section }  $\rightarrow$  Lock = 1;  
 // CS

exit section } while (true);  $\rightarrow$  do code not dependent on CS  
 done lock = 0; RS

\* Soln to CS Problem must Satisfy: VIMP

- (i) Mutual exclusion
- (ii) Progress
- (iii) Bounded unit

. ME: only 1 process can be in CS, at a given time.

. Progress: CS should not be empty.

Progress ✓, Strict Alternation X

. Bounded Wait: If P2 try to enter CS, P1 can enter again [Not so waiting]

[eg]  $\rightarrow$  Pg 103 [Strict Alternation]

✓ (imp)

### complete solution

#### Peterson's Soln to CS Problem (S/W)

- (Code) → Pg 29 (Rev Copy) ✓ imp
- ✓ ME - (P1 in CS, P2 cont enters) ✓
  - ✓ Propri : P1 can enter again & again, & if P1 leaves, P2 can also enter
  - ✓ Bounded Wait : If P2 in Spinlock, P1 leaves CS, enters again, P2 enters.

#### H/W Solution to CS Problem (H/W)

##### (i) ME using Test & Set(C)

(Code) init Value of lock = false;  
→ Pg 31 (Rev Copy) ✓ imp

- For 1 Process, test and Set() returns F,
- For 2 or more outside CS, returns True ..

##### (ii) ME using Swap()

Whenever gets inside CS, makes lock → true  
↳ Key → false,  
while leaving, make lock → false  
[available]  
→ Pg 32 (Rev Copy) ✓ imp

#### Complete H/W Solution

(Code) → Pg 33 & 34 [Read carefully] ✓ imp

(eg) → Q4 (Pg 118) ✓ GATE Q

(eg) → Q5 (Pg 120) ✓ GATE Q

### \* SEMAPHORE

- Used for synchronization purpose.
- Variable upon which we perform wait & signal.

wait (Semaphore S) {  
    while ( $S \leq 0$ );  
     $S++$ ;  
     $S--$ ;  
}

signal (Semaphore S)  
{  
     $S--$ ;  
}

• Semaphores → Counting S (Resource Alloc.)  
→ Binary S (0, 1)

(eg) → Pg 126 (min no of Semaphores) ✓

\* Drawback of BS : Traditional When 1 process in CS, other can in SL, simply waiting CPU cycles. imp

## \* Modern implementation of BS

```
wait(Semaphore S) {  
    S--;  
    if(S<0)  
        Place Process in Queue;  
    Block();  
}  
  
Signal(Semaphore S) {  
    S++;  
    if(S>=0)  
        wakeup();  
}
```

## \* Deadlock

- When none of the processes can enter CS.
- If any 1 ref shows DL = DL
- If no refence shows DL = DL free

[eg] → Pg 128 [Deadlock Sol] ✓

[eg] → Pg 131 [DL] ( $P_3 \rightarrow P_2$ ) ✓

## \* POPULAR PROBLEMS (Semaphore)

### ① Producer-Consumer Problem

[Code] → Pg 40 [Rev Copy] ✓

[mutex, full, empty]

Page No.: 14 Date: Youva

### ② Readers-Writers Problem

- Only 1 writer is allowed to perform write opem at a time. (No reader/writer)
- Any no. of readers are allowed.  
[At that time, writer not allowed]

[Code] → Pg 41 [Rev Copy] ✓

### ③ Dining Philosophers Problem

- 5 Philosophers, 5 chopsticks  
Satn: [Deadlock Problem]

1. allow only 4 P to enter.
2. Perform taking of CS, when 2 is avail.
3. even takes right CS first & then left;  
odd takes left CS first & then right CS.

[eg] → Pg 139 (Q1) ✓

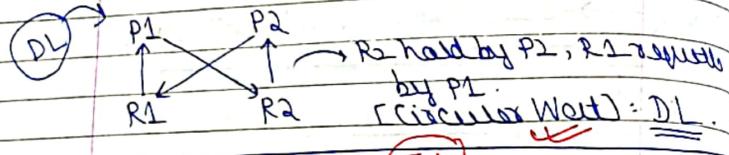
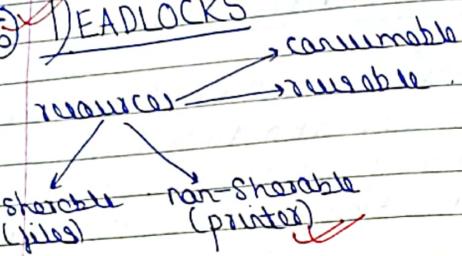
[eg] → Pg 143 ✓

[eg] → Pg 145 ✓

[eg] → Pg 149 ✓

Gate QS

## ⑥ DEADLOCKS



\* Conditions for occurrence of Deadlock:

(i) MF : (Non-Sharable resource)

(ii) Hold & Wait :

(iii) No-Premption (cont Snatch)

(iv) Circular Wait: (Pn holding Rn, req R1)

Necessary

\* Resource Allocation Graph (RAG)

$G = (V, E)$  → rep/assign/claim.  
↳ Process & Resources

multi  
tree

If cycle: Possibility of DL

If no cycle: No DL

in RAG

ans

## \* Deadlock Handling Methods

(i) DL Prevention

(ii) DL Avoidance

(iii) DL Recovery/Retention

(iv) DL Recovery.

(PAD-R)

(i) DL Prevention

- avoid any one condition

(ii) MF: use Sharable resource than

(iii) Hold & Wait :

- alloc all resources to P1 at start  
- P1 can request another, only when it is holding none

(iv) No-Premption:

- if P1 req R2, R2 not allocated; P1 needs to release all its resources

(v) Circular Wait:

- never allow, issues no resource to be requested: (enumerates in inc order)

P1 → R2

P2 → R3

Pn → Rn+1] not,  $< n$  (not)

## (ii) DL Avoidance

(1) Safe State Method

(2) RAG

(3) Banker's algo.

Test  
Knowledge of  
resources is req.  
a priority

### (i) Safe State Method

$$\text{MAX-Allocation} = \text{need}$$

$$\text{Avail} = \text{Total} - \text{Alloc}$$

eg → Pg 48 (Rev Copy) ✓

eg → Pg 161 [X=5] ✓

### (ii) Banker's Algorithm

- multiple resource types

$$\text{MAX}[i][j] : P_i \text{ req max of } k \text{ nos. of resour.} \\ = K.$$

of type  $R_j$

$$\text{MAX}[i][j]$$

$$\text{ALLOC}[i][j]$$

$$\text{need}[i][j] = \text{MAX} - \text{ALLOC}$$

Matrix.

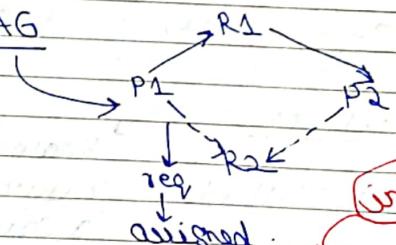
$$\text{Available}[j]$$

$$\text{Total}[j]$$

$$\text{work} = \text{Avail}; \text{work} = \text{work} + \text{Alloc}$$

eg → Pg 51 (Rev Copy) ✓

### (iii) RAG



- b4 allocating  $R_2$  to  $P_1$ , checks possibility of DL in future. ✓

Single resource type

Imp

### (i) DL Detection

(ii) Single instance: Construct WFG

(iii) Multi instance: Use Banker's Algo

### (ii) DL Recovery

#### (i) Process Termination

all Process in DL

Process by  $P_i$ , based on Priority

Ter

[Wait-die, wait-wound]

#### (ii) Resource Preemption

- Select the victim process & switch all its resources. (call Back)

DL Prevention > DL Avoidance  
more restrictive

DL Avoidance

Gate

eg → Pg 171 (Q 2) ✓

eg → Pg 54 (Rev Copy) [Imp]

eg → Pg 175 ✓

→ no preemption allowed

## 7. THREADS

- light weight processes
- Thread contains:
  - thread id
  - PC
  - Register Set
  - Stack
- Thread shares code, data, files but has their individual register/Stack. **Goal**
- Appln Process is heavier & slower than thread.

Threads → Kernel level threads  
Threads → User level threads

diff

Main advantage of threads: Multi Process Archit.

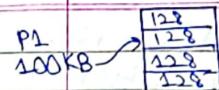
ULT → implemented by user & cont.  
be split to diff CPUS.  
KLT → Yes

## 8. MEMORY MANAGEMENT

- ### (i) Partitioning technique
- static
  - dynamic
- ### (ii) Static
- Partition already created in MM (init).
  - Process brought here for execution.

Page No: 20 Date: youvt

Page No: 21 Date: youvt



Internal fragmentation

### (iii) Dynamic

- init. partitions not present, created due to placement of process.
- Holes created here. **External fragmentation**
- Compaction technique used: big hole mode

eg

→ Pg 58 (Rev Copy)

jmp

## ② Placement Algorithm

P1 = 100KB

MM	
64KB	PAR1
512KB	PAR2
250KB	PAR3
128KB	PAR4

- Best Fit: PAR4
- Worst Fit: PAR2
- First Fit: PAR2

✓

## ③ PAGING

- MM divided into frames & process into pages.  
[Page Size = Frame Size]

- pages must be loaded into MM for execution.

F# MM

0	A.0
1	A.1
2	A.2
3	B.0
4	B.1
5	B.2
6	B.3

Page Table of A

Pg#	F#
0	0
1	1
2	2

Page Table of B

Pg#	F#
0	3
1	4
2	5
3	6

~~jmp~~

Page Table: page carries frame info.  
Contents: F# & V/I bits  
Pg# acts as index.

### \* Address translation

Logical Address to Physical Add.

MMU does it.  
(CPU generated add.)

eg → Pg 190 (Add. Transl.)

4 offset = 13, Pg Size = fr. Size =  $2^{13}$   
No. of entries in PT  $\Rightarrow$  Pg# bits

~~jmp~~  
Size of PT  $\Rightarrow$  size of each entry \* total entries.

$\Rightarrow$  V/I bit: If V. Page is avail in MM.

eg → Pg 62 [Rew Copy - 32 bit LA]

### \* TRANSLATION LOOKASIDE BUFFER

- New working cache [PT defined for every Process]

PT  $\rightarrow$  all Pages of that Process

TLB  $\rightarrow$  Page car. frame info of recently accessed Page from var. Process

drag → Pg 193 [TLB]

~~jmp~~

Page No: 23 Date: ~~youuu~~

Hierarchical.

Effective Mem Access time:

$$(LA \rightarrow PA) + (\text{Mem Access using PA})$$

$$t + (1-h)m + m$$

TLB Access Time

TLB HR page Table [in MM].

$$EMA = t + m(2-h)$$

$h \times 1 / EMA$

### \* Shared Page

eg → Pg 196 (cd1, id2)

## ④ PAGE TABLE STRUCTURES

### 4. Multilevel PT / Hierarchical PT

- In Simple PT, allocating large amt of Space contiguously in MM difficult.

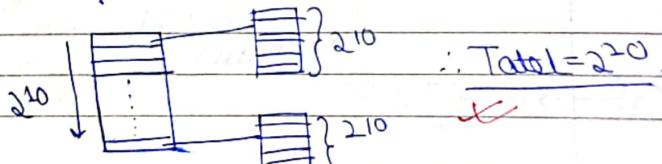
Multilevel PT

~~jmp~~

$[P_1 | P_2 | \dots | P_d]$ , Pg Size =  $2^{12}$  B.

No of entries in outer PT =  $2^{10}$ .

No of entries in inner PT =  $2^{10}$ .



~~contiguous memory locations not resp. memory efficient.~~

### 2. Hash Structured PT

- Page no. hashed into index using HF.
- Chaining technique is used to avoid collision.

→ Pg 199 ✓

### 3. Inverted PT

~~No. of entries in IPT = No. of Frames in which Mem is divided~~

→ Pg 200 ✓

Content of IPT: Pid & Pg#

Index of IPT: F#

→ Pgs of diff Process can be placed inside IPT unlike PT.

→ Pg 201 [Q2] ✓

Gate Q

→ Pg 203 [Q4] ✓ [Forward OT]

Size of MM: 512 MB.

Address:  $2^9 \times 2^{20}$  bits = 29 bits.

$2^{29}$  bytes.  
Byte Addressable

→ Pg 207 ✓

### 5. Segmentation

- Memory divided into variable size parts: Segments which can be allocated to Process.



→ Pg 209 [Segmentation Unit?] ✓

### 6. Virtual Memory Management

[Max size]

size of MM < size of VM < size of SM.

- VM: unshared form of memory

- Alocating VM: increases degree of multiprogramming ✓

### 7. Demand Paging

- Degree of Multiprogramming ↑

- (if 100F in MM, 10 Process, each Proc. (= 100 pgf))

→ load 10 pgf of each Process.  
(instead of 100 pgf of 1 process)

### \* Strict demand Paging

- Never load a page into MM, unless it's required/needed.

### \* Handling Page Faults

When pgs corresponding frames info, will have invalid bit in Page Table, that means the page is not in MM = Page Fault

e.g. Pg 212 (Handling PF)

(i) no Free Frame = Page Replacement Algo  
[Swap page out of disk]

## ③ \* Page Replacement Algorithm

(i) Optimal Algorithm [work on future requests]

(ii) LRU (Least Recently Used)

e.g. Pg 70 (Rew Copy)

(iii) FIFO (First in first out)

Bellady's Anomaly: happens in FIFO,  
[no. of PF  $\propto$  no. of PF Size]  
[Page Fault] [Page Frame]

Generally, inverse occurs

### (iv) LIFO

e.g. Pg 71 (FIFO & LIFO) X (Not so imp/com in options)  
(v) MRU } Tricky.  
(vi) MFU } X.

### ④ THRASHING

- Due to demand Paging, degree of MP, slowly leads to thrashing.
- CPU spends more time in Swapping (∴ prob. of not finding the page incr.)

Thrashing leads to excessive Page Faults

- depending on func., diff. pgf are referred

### \* Locality of reference

Spatial

[current mem. loc. referenced again & again]

Temporal

[same mem. loc. referred again & again]

- array

[look ahead]

- init in for loop

[look aside]

## 10) Frame Allocation

- done by instruction set architecture.
- (i) Round robin allocation

(i) 100F, 5 Process:  
Each Process  $\rightarrow$  20 frames.

(ii) Proportional allocation [100F]

$$P_1: 160 \text{ pg} \quad P_2: 40 \text{ pg} \\ \Rightarrow 80F \quad \Rightarrow 20F$$

(iii) Priority allocation imp  
Process with higher P, more frames.

## 11) Placement

- Local Placement: Process can't access frames allocated to other Process.
- Global Placement: If any frame of Process is free, it can be used by Process with excess Pg.

cgt  $\rightarrow$  Pg 4 [Rev Copy 2] X

cgt  $\rightarrow$  Pg 225 [Demand Paging] X

cgt  $\rightarrow$  Pg 227 (Q7) X

done by working set strategy.

imp

## 12) FILE SYSTEM

### (i) Allocation methods

- allocate the blocks in disk to file Blocks.

### (ii) contiguous Allocation

File	Start	Len
F1	5	3

Adv: read performance is excellent  
disadv: external fragmentation imp

### (iii) linked list allocation

cgt  $\rightarrow$  Pg 2 (Notes - FS) X

imp  
- busy file contains start Physical Block.

Adv: - external fragmentation avoided.

Disadv: - Random access is very slow  
- Pointer takes up few bytes X.

### (iv) File Allocation Table [for every file → FAT]

- for every disk block in HD, make entry.

Adv: random access is easier imp

Disadv: FAT size can be too huge, to be stored in MM.

cgt  $\rightarrow$  Pg 3 (FAT) X

(iv) Indexed allocation

~~primary file, maintain 1 special block called index Block / I-node~~

File / Inode  
File A | 10 | [go inside 10, 10 shows all block no.s: 3, 4, 5, 8].

Adv: need not bring FAT in MM (memory efficient). [just one node] (Index Node)

• [if very less no. of blocks] size ↓.

• [if too many blocks, entries] → many index blocks in index block ↑.

[eg] → Pg 5 [Notes] → Pg 8 [Imp]

(v) Extended indexed allocation

disk → cell ✗ if too many blocks.

[eg] → Pg 6 (2004 & 2012) [Vimp] ✗

(vi) DISK SCHEDULING ALGORITHMS

- OS main purpose is that HD serves every I/O request in an optimum way.

Seek time: moving disk Head to the appropriate cylinder/track.

When process gets suspended / blocked ifo, it is swapped onto HD, hence of processes get piled up and by one, they get served [for I/O event]

(i) FCFS Scheduling

- No Starvation.

[eg] → Pg 8 ✗

(ii) SSTF Scheduling

- least movement of the disk arm.  
- reduces total seek time.

- Starvation is possible → Pg 9 [Best Throughput]

→ like SRTF.

(iii) SCAN [Elevator]

outside → inside (0)  
inside (0) → destination

[eg] → Pg 10 (dirn will be mentioned)

(iv) C-SCAN

outside → inside (0).  
inside (0) → outside (199)  
outside (199) → destn.

[disk] → cell ✗

#### (iv) LOOK

- Like Scan, but don't move till innermost cylinder.

eg → Pg 11 ✓

#### (v) C-LOOK

- Like C-SCAN, go till lowest & then highest [Not innermost/outermost]

eg → Pg 12 [Gate 2016 Q] ✗ imp

### 3) FREE SPACE MANAGEMENT.

- How to show which blocks in disk are free. [Super block keeps count].
- bit notation.
- linked notation (list of free blocks).
- counting technique.
- indexed. [i block having list of fB].

### 4) DIRECTORY STRUCTURE

eg → Pg 9 [Rev Copy - 2] ✗

### \* POINTS from Prev Years.

- Timer interrupt will involve the scheduler & scheduler just affects the next process to be scheduled.
- It doesn't cause interrupt.
- Dispatcher causes interrupt.

\* Transparent: means functioning without being aware. [like VLT]

\* Synchronous I/O : Process is blocked S, ISR after I/O, place process back to ready.

\* Asynchronous I/O : process not blocked, process continues executing in that time. ISR after I/O notifies the process, that I/O is done.

\* T → Time Quantum  
Scheduler regulates the process priorities every Time units. [Round robin].

\* Semaphore operations implemented within OS Kernel. [Gate - 1990]

\* Disk has Swap Space, since all the swapping of processes (carried by MTS) b/w MM & Disk occurs. [expanded I/O].

- \* ~~Harris Monitor uses wait/Signal operations.~~
- \* ~~Locality is commonly used to determine the no. of assigned pages. The no. of pages that meet the requirement of locality is called working set.~~ (imp)

- \* ~~Amt of VM available is limited by the availability of secondary storage.~~
- \* ~~LRU can cause thrashing obviously.~~

- \* ~~Buddy System: Buddy memory allocation technique divides memory into partitions to try to satisfy a memory request. [Runtime environment → CD]~~ (imp)
- \* ~~Garbage collector depends on free pointer.~~

→ ~~Look Ahead Buffer → Spatial Locality~~  
~~Look Aside Buffer → Temporal Locality~~

#### \* Locality of reference

↳ ~~page reference being made by the process is likely to be one of the pages used in the last few page references.~~ (imp)

- \* ~~Object Module → Object code~~
- \* ~~Object Module → relocation bits.~~
- \* ~~Names & locations of all external symbols.~~
- \* ~~In a resident OS computer, loader must reside in MM (in all situations)~~
- \* ~~A Page replacement Algorithm suffers from Belady's anomaly, when it is not Stack algorithm.~~
  - FIFO → Not Stack
  - LRU → Stack. : Belady's
  - Random → Not Stack.

- \* ~~Dirty bit: write-back; if page is modified, & not written back to mem, DB set to 1.~~
- \* ~~R/W bit: true if page is read only / r/w used as Page Protection.~~
- \* ~~Reference bit: used in page replacement algo; to avoid replacement of heavily used Page.~~
- \* ~~Valid: for page indirection. (in mem/not)~~
  - [Working Set Strategy]
- \* ~~OS Selects a process to suspend, if the sum of the size of the working sets exceeds the total no. of available frames. & also: aim of working Set Strategy: initiate other Process, if extra frames available.~~
  - [global allocation]

\* Instruction takes  $i$  usec.  
Page fault takes additional  $j$  usec.  
Page fault occurs every  $K$  instructions.

Q4.24)

$$\text{Effective wait time} = i + \frac{j}{K}$$

$$\text{EMA} = \% \text{ of Page misses} * \text{PF Service time} \\ + \% \text{ of Page hit} * \text{Memory Access time}$$

$$\text{jmp} \Rightarrow \frac{1-i}{K} * (i+j) + \frac{(1-i)}{K} * i$$

Page Fault Service Time

$$\Rightarrow \frac{i+j}{K} + \frac{i-i}{K}$$

$$\therefore \frac{i+j}{K}$$

$$Q4.35 \quad \text{TLB HR} = 96\%, \text{ Cache HR} = 90\% \\ m = 10 \text{ ns}, C_L = 1 \text{ ns}, \text{TLB}_f = 1 \text{ ns}$$

Vjmp

Process  $\rightarrow [LA \rightarrow PA] + [\text{Access PA}]$

$$\text{jmp} \Rightarrow (\text{TLB}_f) + (1-H_f)(2m)$$

$$\Rightarrow 1 + 0.04 \times 20$$

$$\Rightarrow 1.8 \text{ ns}$$

$$(C_L) + (1-H_C) \times m$$

$$\Rightarrow 1 + 0.1 \times 10$$

$$\Rightarrow 2 \text{ ns}$$

$$\therefore 3.8 \text{ ns}$$

Q4.47.

Dirty Page + Page Fault Service

$$3 = (1-p)1 + p[p \cdot 300 + (1-p)100]$$

Q4.39

TLB & Page Fault

$$\text{EAIT} = \text{CPU} + 2 * \text{EMAT}$$

$$\text{EMAT} = (\text{VA} \rightarrow \text{PA}) + \text{Access byte from PA} \\ [\text{Extra Notes}] \quad \text{jmp} \quad [\& \text{next pg of exto-N}]$$

$$*\text{ MM access time} = 30 \text{ ns}$$

$$\text{Page fault rate} = 15\%$$

$$\text{Page fault Service time} = 10 \text{ ns}$$

$$\text{EMA?}$$

Soln:

$$\text{EMA} = p(10) + (1-p)(30) \\ \Rightarrow 0.15 \times 10 + 0.85 \times 30$$

Page Fault Service

jmp

\* If head changes its direction after servicing every request;  
Pattern comes out to be:

$$\text{new min} = (\text{old dist} \times 2) + 1$$

✓

above  
the  
pattern  
[ROMQ]

~~jmp~~ \* MMU (Special h/w Support), needed only for VM. If VM is removed, this h/w is also removed. TESTS - 1

\* Scheduling algorithms (like FCFS, SJF...) are used by STS, LTS uses none.



KLT. Every task uses 1 KLT, therefore can use multi processor facility.

→ If VLT is blocked, whole Process gets blocked; Kernel can do CS to run another VLT (unblocked).

→ Multiprogramming: increases CPU utilization  
Time Sharing: increases CPU responsiveness

\* If all jobs have identical Run lengths, RR Scheduler → horrible TAT.  
[All jobs complete at same time]

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\* In bit Map Approach:

[No. Every disk block mapped to one bit]

$$\text{if no. of disk blocks} = 40M \quad \text{size of Bit Map} \\ 40M \cdot \frac{1}{8} B = 5MB$$

\* LTS controls deg of multiprogramming.

[No. of Process present in MM at any time]

\* MTS can only decrease deg of MP by suspending some Process.

[Q8]

\* Page Size = 8 KB, offset = 13 bit.

← 64 bit VA

↓ Pg # | offset

← 5 | ← 13 bit →

↓ Tag (45 bit) ↓ 6 bit (No. of sets)

→ Min Size of TLB Tag [Q9] ✓

\* Indexed allocation can support both sequential + direct access. Clinked → seq.

\* PA = 30 bit, PA space =  $2^{30}$ .

PA Space = No. of frames  
Page Size

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**Q9** → Trade (Present in Memory) (Imp)

Q15 [No. of disk access required to access a byte Position] ✓

\* If Virtual address Space = 4 GB  
 Virtual Address = 32 bit (Imp)

If MM has 32K physical Pages,  
 No. of frames =  $2^{15} \Rightarrow$  frame# = 15 bit ✓

Content of PT = 16 bit = 2 B (1 VB) ✓

\* Demand Paging taken care by OS, nothing to do with Programmer.

Shared Pages can be swapped out to disk  
 OS automatically loads pages from disk, when necessary (Imp)

\* Purpose of dynamic loading: optimal utilization of memory (Imp)

Routine not loaded until called: dynamic  
 All routines are part of code, & are loaded at the same time, regardless of called or not: Static ✓

\* CPU utilization increase as the deg. of multiprogramming increases up to threshold after that utilization starts decreasing.  
\* Due to thrashing?

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**NOTE:** If there is deadlock, progress not satisfied  
 if progress satisfied, no deadlock ✓

**Q27** [Level of PT required, Page Table Size] (Imp)

→ Q27 [Level of PT required, Page Table Size] are calculated at each level]

**Q31** [Page faults, like Prev Year Q] (Imp)

\* Not just circular wait (Imp)

\* For System to be in deadlock, all 4 conditions must be satisfied.

\* If each resource type has single instance then cycle in RAG implies deadlock.

**Q33** [Tough Q on Scheduling & lock → concept clearing (Imp)]

**TEST-2 (2020)**

\* 30 instances of resource 'R'  
 Each Process — 4 instances (Mistake)

Max possible no. of processes for System to be in safe state?

9 ✓  $(3 \times 8) = 24$ , 1 will get 6. ✓

10 X  $(3 \times 10) = 30$ ; None will get 4. ✓

\* External fragmentation: When there is enough total memory space to satisfy req., but avail. space is not contiguous. (Dynamic Partitioning)

\* System is well utilized when:  
CPU utilization ↑, disk utilization ↓

\* A Thread running in User Mode in critical Section may get context switched  
Process can get preempted, while exec. Critical Section code.

\* Process Id is a part of PCB.  
Process creation is done in Kernel Mode.

There is a bit in PSW (Prog State Word) that indicates mode: User / Kernel.

### Approximations in Page Table Size

- No. of PT entries =  $2^{23}$ .
- Frame# = 16 bit.

Given (@ valid bit, 2 MB, 2<sup>21</sup> bit).

$$\therefore 16 + 2 + 2 + 2 = 22 \text{ bit.}$$

$\therefore 22 \text{ bit} \approx 3B$ . *(Jump)* (Approx)

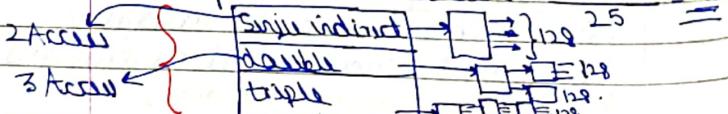
$$\therefore \text{PT Size} = 2^{23} * 3.$$

$$= 2^{20} * 2^3 * 3 = 24 \text{ MB}$$

\* Disk block size = 512B

Pointer = 32 bits.

$$\therefore \text{No. of pointers in 1 block} = 2^9 * 2^3 = 128.$$



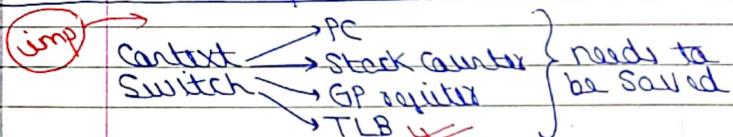
1 double indirect pointer = 128 × 128 blocks  
1 triple indirect = (128 × 128 × 128) blocks  
1 simple indirect = 128 blocks *(Jump)*

\* **Dynamic Linking** → on demand linking  
- dynamic linking optimizes (decreases) memory space utilization.  
- Increases program execution time.  
(Dynamic linking, dynamic loading, dynamic address binding), practically used in majority of OS.

\* SRTF can't be implemented in a time sharing OS. (It's round Robin).

\* TLB needs to be saved in runtime on a context switch between processes.  
PC must also be saved during CS.

\* System calls invoked using S/W interrupt *(Jump)*



legt  $\rightarrow Q28$

[Similar Q in Prev year]

\* Page Size = 1K Words. [1024 words].

4 Frames, 8 pages

Given: List of Virtual Address.

Pg	Address
0	0 - 1023
1	1024 - 2047
2	2048 - 3071

*(Jump)*  
Approach

\* CO Q → Magnetic Disk

12380 bytes per track

Rotation time = 20 msec

Seek time = 45 msec

Time to read a 1024 B block?

$$\Rightarrow \text{Time} = \text{ST} + \text{Rot. L} + \text{Transfer Time}$$

$$\Rightarrow 45 + \frac{20}{2} + \underline{\underline{\text{TT}}} = \underline{\underline{56.65}}$$

Rotation covers 1 track

$$12380 \longrightarrow 20$$

$$1024 \longrightarrow \pi$$

$$\therefore \pi = \frac{1024 \times 20}{12380} = 1.65$$

imp

\* Page Size = 1 KB = 1024 B

Info to be stored = 4000 B

∴ 4 pages are required

Max. 4 TLB miss will occur