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ICE 2154 NETWORK ANALYSIS AND SIGNALS

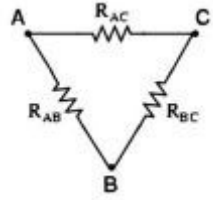
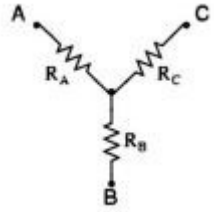
Symbols and Units:

Quantity	Symbols	Unit	Equivalent Unit	Unit Abbreviation
Charge	q	Coulomb	-	C
Current	I , i	Ampere	Coulomb/Second	amp
Flux Linkages	Ψ	Weber-Turn	-	Wb
Energy	W , w	Joul	Newton-Meter	J
Voltage	V , v	Volt	Joul/Coulomb	V
Power	P , p	Watt	Joul/Second	W
Capacitance	C	Farad	Coulomb/Volt	F
Inductance	M , L	Henry	Weber/Ampere	H
Resistance	R	Ohm	Aolt/Ampere	Ω
Conductance	G	Mho	Ampere/Volt	
Time	t	Second	-	sec
Frequency	f	Hertz	cycles/second	Z H
Frequency	ω	Radian/second	-	-

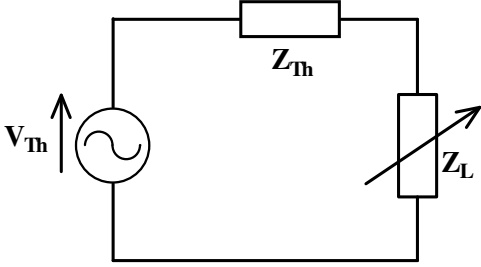
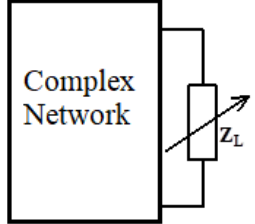
Relationships between the network parameters:

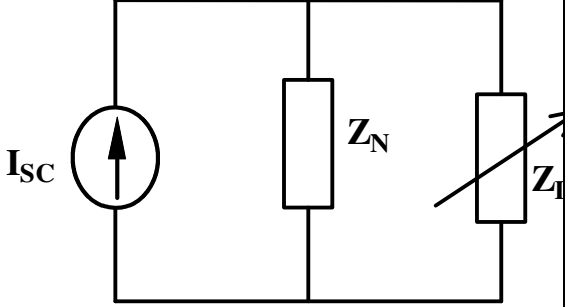
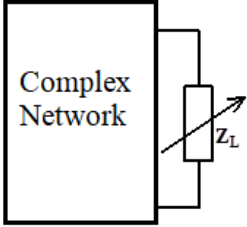
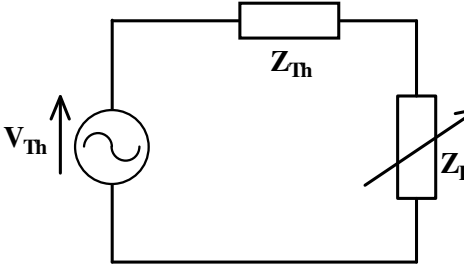
Parameter	Basic Relationship	Voltage-Current Relationship	Energy
R $G = \frac{1}{R}$	$v = Ri$	$v_R = i_R R$ $i_R = G v_R$	$w_R = \int_{-\infty}^t v_R i_R dt$
L (or M)	$\Psi = Li$	$v_L = L \frac{di}{dt}$ $i_L = \frac{1}{L} \int_{-\infty}^t v_L dt$	$w = \frac{1}{2} Li^2$
C $D = \frac{1}{C}$	$Q = Cv$	$v_C = \frac{1}{C} \int_{-\infty}^t i_C dt$ $i_C = C \frac{dv}{dt}$	$w = \frac{1}{2} C v^2$

Star Delta Conversion:

1.	Star - delta (wye-delta) conversion	<p>Star to delta conversion:</p> $R_{AB} = \frac{R_A R_B + R_B R_C + R_A R_C}{R_C}$ $R_{BC} = \frac{R_A R_B + R_B R_C + R_A R_C}{R_A}$ $R_{AC} = \frac{R_A R_B + R_B R_C + R_A R_C}{R_B}$ <p>Delta to star conversion:</p> $R_A = \frac{R_{AB} R_{AC}}{R_{AB} + R_{BC} + R_{AC}}$ $R_B = \frac{R_{AB} R_{BC}}{R_{AB} + R_{BC} + R_{AC}}$ $R_C = \frac{R_{BC} R_{AC}}{R_{AB} + R_{BC} + R_{AC}}$	<p>Delta (Δ) Network</p>  <p>Star (Y) Network</p> 
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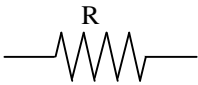
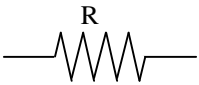
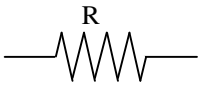
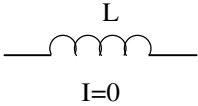
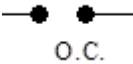
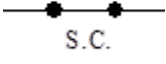
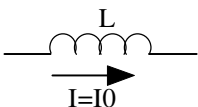
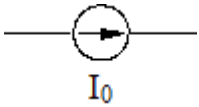
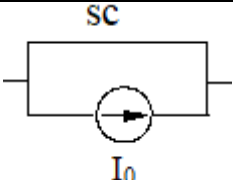
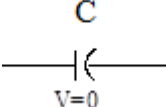
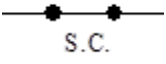
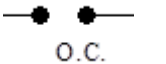
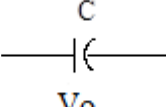
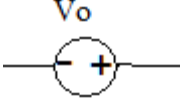
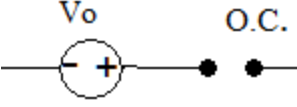
Network Theorems:

1	Thevinin's Theorem	 <p> V_{th} = Open Circuit voltage at the load terminals Z_{th} = Open circuit equivalent impedance at the load terminals after deactivating all the independent sources </p>	
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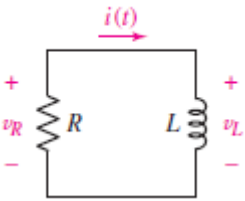
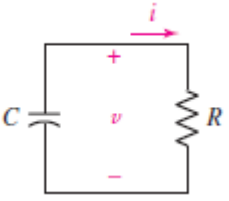
2	Norton's Theorem (Dual of Thevenin's theorem)	 <p> I_{sc} = Short circuit current through the load terminals $Z_N = Z_{th}$ = Open circuit equivalent impedance at the load terminals after deactivating all the independent sources </p>	
3	Maximum Power Transfer theorem	<p>DC Circuit-- $R_L = R_{TH}$</p> $P = \frac{V_{TH}^2}{4R_L}$ <p>AC Circuit</p> <ol style="list-style-type: none"> (1) both load resistance and reactance are variable $Z_L = Z_{TH}^*$ (2) load being purely resistive $R_L = Z_L = Z_{th}$ (3) load being variable resistance and fixed reactance $Z_{th} = Z_{th} \pm jX_L$ $R_L = Z_{th}$ 	<p>Given circuit is to be replaced by Thevenin's equivalent circuit</p> 

TRANSIENT ANALYSIS:

Equivalent form of elements in terms of the initial and final condition of element:

Element	Equivalent circuit at $t=0^+$	Equivalent circuit at $t = \infty$
		
		
		
		
		

First order differential equations:

Source free RL circuit	$\frac{di}{dt} + \frac{R}{L}i = 0$ $i(t) = I_0 e^{-\frac{Rt}{L}} \text{ where,}$ $I_0 \text{ is the initial current at time } t = 0$	
Source free RC circuit	$\frac{dv}{dt} + \frac{v}{RC} = 0$ $v(t) = v(0) e^{-\frac{t}{RC}}$ $v_0 \text{ is the initial voltage across capacitor at time } t = 0$	
Solution of standard first order differential equation	$\frac{di}{dt} + Pi = Q$ $i = e^{-Pt} \int Q e^{Pt} dt + Ae^{-Pt}$	Total response = Forced response + Natural response

Solution of second order differential equation:

Second order differential equation representing **source free** RLC circuit is of the form

$$\frac{d^2x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_2 x(t) = 0 \text{ and characteristic equation } s^2 + a_1 s + a_2 = 0$$

Roots of the characteristic equation are

$$s_1, s_2 = \frac{-a_1}{2} \pm \sqrt{\left(\frac{a_1}{2}\right)^2 - a_2}$$

Response in terms of coefficient conditions:

case	Coefficient Condition	Nature of Roots	Descriptive Name	Form of Solution
1	$a_1^2 > 4a_2$	Negative real and unequal	Overdamped	$x(t) = K_1 e^{s_1 t} + K_2 e^{s_2 t}$
2	$a_1^2 = 4a_2$	Negative real and equal	Critically damped	$x(t) = K_1 e^{s_1 t} + K_2 t e^{s_2 t}$
3	$a_1^2 < 4a_2$	Conjugate Complex	Underdamped	$x(t) = e^{\sigma t} (K_1 \cos \omega t + K_2 \sin \omega t)$ $s_1, s_2 = \sigma \pm j\omega$
4	$a_1 = 0 \text{ and } a_2 \neq 0$	Conjugate imaginary	Oscillatory	$x(t) = K_1 \cos \omega t + K_2 \sin \omega t$ $s_1, s_2 = \pm j\omega$

Second order differential equation representing RLC circuit **with excitation** is of the form

$$\frac{d^2 x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_2 x(t) = v(t)$$

Has a solution (total) $x(t) = x_c(t) + x_p(t)$: $x_c(t)$ is complementary function and $x_p(t)$ is particular integral

Case	Factor in $v(t)$ { excitation }	Necessary choice for the particular integral
1	$V (a \text{ Constant})$	A
2	$a_1 t^n$	$B_0 t^n + B_1 t^{n-1} + B_2 t^{n-2} + \dots + B_{n-1} t + B_n$
3	$a_2 e^{rt}$	$C e^{rt}$
4	$a_3 \cos \omega t$ $a_4 \sin \omega t$	$D \cos \omega t + E \sin \omega t$
5	$a_5 t^n e^{rt} \cos \omega t$ $a_6 t^n e^{rt} \sin \omega t$	$(F_1 t^n + \dots + F_{n-1} t + F_n) e^{rt} \cos \omega t + (G_1 t^n + \dots + G_{n-1} t + G_n) e^{rt} \sin \omega t$

Note: The initial condition must always to be applied to the total solution – never to the complementary function alone unless $x_p(t) = 0$.

LAPLACE TRANSFORMS;

Laplace Transform: $L\{f(t)\} = F(s) = \int_0^{+\infty} f(t) e^{-st} dt$

Inverse Laplace Transform: $f(t) = \frac{1}{2\pi j} \int_{\sigma_0 - j\infty}^{\sigma_0 + j\infty} e^{st} F(s) ds$

Standard Laplace Transforms:

$f(t)$	$F(s) = \int_0^{\infty} f(t)e^{-st} dt$
$u(t)$	$\frac{1}{s}$
t	$\frac{1}{s^2}$
$\frac{t^{n-1}}{(n-1)!}$ n is a integer	$\frac{1}{s^n}$
e^{at}	$\frac{1}{s-a}$
e^{-at}	$\frac{1}{s+a}$
te^{at}	$\frac{1}{(s-a)^2}$
te^{-at}	$\frac{1}{(s+a)^2}$
$\frac{1}{(n-1)!} t^{n-1} e^{at}$	$\frac{1}{(s-a)^n}$
$\frac{1}{(n-1)!} t^{n-1} e^{-at}$	$\frac{1}{(s+a)^n}$
$1 - e^{at}$	$\frac{-a}{s(s-a)}$
$\frac{1}{\omega} \sin \omega t$	$\frac{1}{s^2 + \omega^2}$
$\cos \omega t$	$\frac{s}{s^2 + \omega^2}$
$1 - \cos \omega t$	$\frac{\omega^2}{s(s^2 + \omega^2)}$
$\sin(\omega t + \theta)$	$\frac{s \sin \theta + \omega \cos \theta}{s^2 + \omega^2}$
$\cos(\omega t + \theta)$	$\frac{s \cos \theta - \omega \sin \theta}{s^2 + \omega^2}$
$e^{-at} \sin \omega t$	$\frac{\omega}{(s+a)^2 + \omega^2}$
$e^{at} \sin \omega t$	$\frac{\omega}{(s-a)^2 + \omega^2}$
$e^{-at} \cos \omega t$	$\frac{s+a}{(s+a)^2 + \omega^2}$

$e^{at} \cos \omega t$	$\frac{s-a}{(s-a)^2 + \omega^2}$
$\sinh at$	$\frac{a}{s^2 - a^2}$
$\cosh at$	$\frac{s}{s^2 - a^2}$

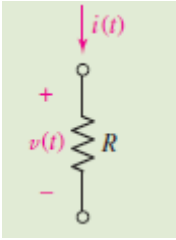
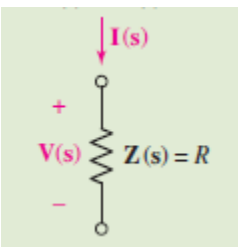
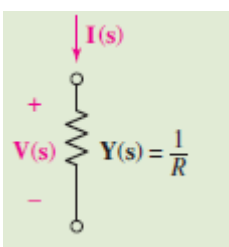
Laplace Transform Operations:

Nature of operation	$f(t)$	$F(s)$
Definition	$f(t)$	$F(s) = \int_0^\infty f(t)e^{-st} dt$
Linear Operation	$af_1(t) \pm bf_2(t)$	$aF_1(s) \pm bF_2(s)$
Differentiation	$\frac{d}{dt} f(t)$	$sF(s) - f(0-)$
	$\frac{d^2}{dt^2} f(t)$	$s^2 F(s) - sf(0-) - \frac{d}{dt} f(0-)$
	$\frac{d^3}{dt^3} f(t)$	$s^3 F(s) - s^2 f(0-) - s \frac{d}{dt} f(0-) - \frac{d^2}{dt^2} f(0-)$
Integration	$\int_0^t f(t) dt$	$\frac{F(s)}{s}$
	$\int_{-\infty}^t f(t) dt$	$\frac{F(s)}{s} + \frac{f(0)}{s}$
Shifting in time domain	$f(t-a)u(t-a)$	$e^{-as}F(s)$
Multiplication by exponential	$e^{-at}f(t)$	$F(s-a)$
Multiplication by t	$t f(t)$	$-\frac{d}{ds} F(s)$
	$t^n f(t)$	$(-1)^n \frac{d^n}{ds^n} F(s)$
Time scaling	$f(at)$	$\frac{1}{a} F\left(\frac{s}{a}\right)$
Magnitude scaling	$af(t)$	$aF(s)$
Periodic function	$f(t) = f(t+nT)$ n is an integer	$F(s) = \frac{1}{1-e^{-sT}} F_1(s),$ Where $F_1(s) = \int_0^\infty f(t)e^{-st} dt$: Laplace transform of one cycle of the periodic function

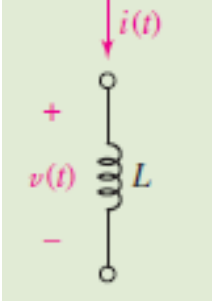
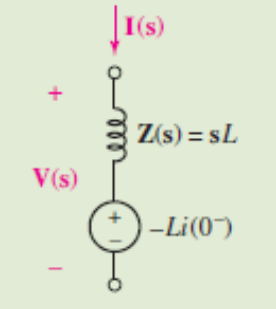
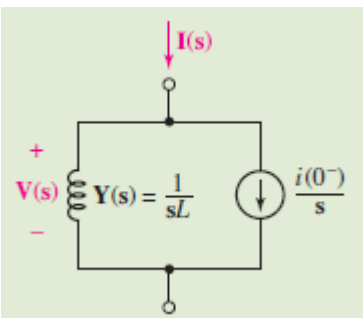
Initial value $f(0^+)$	$\lim_{t \rightarrow 0} f(t) =$	$= \lim_{s \rightarrow \infty} sF(s)$
Final value $f(\infty)$	$\lim_{t \rightarrow \infty} f(t) =$	$= \lim_{s \rightarrow 0} sF(s)$

Transformed Network representation for Basic Elements R, L and C:

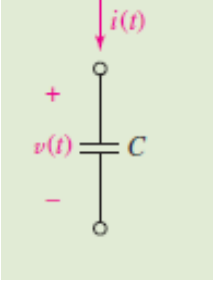
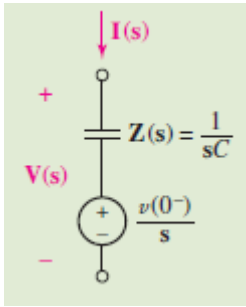
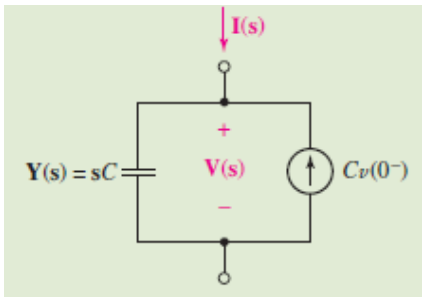
(a) Resistor (R)

 <p>$v(t) = Ri(t)$</p>	 <p>$V(s) = RI(s)$</p>	 <p>$I(s) = \frac{1}{R}V(s)$</p>
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(b) Inductor (L)

 <p>$v(t) = L \frac{di}{dt}$</p>	 <p>$V(s) = sLI(s) - Li(0^-)$</p>	 <p>$I(s) = \frac{V(s)}{sL} + \frac{i(0^-)}{s}$</p>
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(c) Capacitor

 $i(t) = C \frac{dv}{dt}$	 $V(s) = \frac{I(s)}{sC} + \frac{v(0^-)}{s}$	 $I(s) = sCV(s) - Cv(0^-)$
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TWO PORT PARAMETERS:

Name	Equations
Z parameters(Open-circuit Impedances)	$V_1 = Z_{11}I_1 + Z_{12}I_2$ $V_2 = Z_{21}I_1 + Z_{22}I_2$
Y parameters(Short-circuit admittances)	$I_1 = Y_{11}V_1 + Y_{12}V_2$ $I_2 = Y_{21}V_1 + Y_{22}V_2$
h(Hybrid) parameters	$V_1 = h_{11}I_1 + h_{12}V_2$ $I_2 = h_{21}I_1 + h_{22}V_2$
T (Transmission) parameters (ABCD)	$V_1 = AV_2 - BI_2$ $I_1 = CV_2 - DI_2$

Relationship between parameter sets:

	$[z]$	$[y]$	$[T]$	$[h]$
$[z]$	$\begin{matrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{matrix}$	$\begin{matrix} \frac{y_{22}}{\Delta_y} & -\frac{y_{12}}{\Delta_y} \\ -\frac{y_{21}}{\Delta_y} & \frac{y_{11}}{\Delta_y} \end{matrix}$	$\begin{matrix} \frac{A}{C} & \frac{\Delta_T}{C} \\ \frac{1}{C} & \frac{D}{C} \end{matrix}$	$\begin{matrix} \frac{\Delta_h}{h_{22}} & \frac{h_{12}}{h_{22}} \\ -\frac{h_{21}}{h_{22}} & \frac{1}{h_{22}} \end{matrix}$
$[y]$				

	$\begin{array}{cc} \frac{z_{22}}{\Delta_z} & -\frac{z_{12}}{\Delta_z} \\ -\frac{z_{21}}{\Delta_z} & \frac{z_{11}}{\Delta_z} \end{array}$	$\begin{array}{cc} y_{11} & y_{12} \\ y_{21} & zy_{22} \end{array}$	$\begin{array}{cc} \frac{D}{B} & \frac{\Delta_T}{C} \\ -\frac{1}{B} & \frac{A}{B} \end{array}$	$\begin{array}{cc} \frac{1}{h_{11}} & -\frac{h_{12}}{h_{11}} \\ \frac{h_{21}}{h_{11}} & \frac{\Delta_h}{h_{11}} \end{array}$
[T]	$\begin{array}{cc} \frac{z_{11}}{z_{21}} & \frac{\Delta_z}{z_{21}} \\ \frac{\Delta_z}{z_{21}} & \frac{z_{11}}{z_{21}} \end{array}$	$\begin{array}{cc} -\frac{y_{11}}{y_{12}} & -\frac{1}{y_{12}} \\ -\frac{\Delta_y}{y_{12}} & -\frac{y_{11}}{y_{12}} \end{array}$	$\begin{array}{cc} A & B \\ C & D \end{array}$	$\begin{array}{cc} -\frac{\Delta_h}{h_{21}} & -\frac{h_{11}}{h_{21}} \\ -\frac{h_{22}}{h_{21}} & -\frac{1}{h_{21}} \end{array}$
[h]	$\begin{array}{cc} \frac{\Delta_z}{z_{22}} & \frac{z_{12}}{z_{22}} \\ -\frac{z_{21}}{z_{22}} & \frac{1}{z_{22}} \end{array}$	$\begin{array}{cc} \frac{1}{y_{11}} & -\frac{y_{12}}{y_{11}} \\ \frac{y_{21}}{y_{11}} & \frac{\Delta_y}{y_{11}} \end{array}$	$\begin{array}{cc} \frac{B}{D} & \frac{\Delta_T}{D} \\ -\frac{1}{D} & \frac{C}{D} \end{array}$	$\begin{array}{cc} h_{11} & h_{12} \\ h_{21} & h_{22} \end{array}$

Some Parameter Simplification for Passive, Reciprocal Networks:

<i>Parameter</i>	<i>Condition for Passive networks</i>	<i>Condition for Electrical symmetry</i>
z	$z_{12} = z_{21}$	$z_{11} = z_{22}$
y	$y_{12} = y_{21}$	$y_{11} = y_{22}$
$ABCD$	$AD - BC = 1$	$A = D$
h	$h_{12} = -h_{21}$	$\Delta_h = 1$

SIGNALS AND SYSTEMS

Elementary signals:

Name	Continuous time	Discrete time
Impulse function	$\delta(t) = 0, t \neq 0$	$\delta[n] = \begin{cases} 1, n = 0 \\ 0, n \neq 0 \end{cases}$
Unit step function	$u(t) = \begin{cases} 1, t \geq 0 \\ 0, t < 0 \end{cases}$	$u[n] = \begin{cases} 1, n \geq 0 \\ 0, n < 0 \end{cases}$
Unit Ramp	$r(t) = \begin{cases} t, t \geq 0 \\ 0, t < 0 \end{cases}$	$r[n] = \begin{cases} n, n \geq 0 \\ 0, n < 0 \end{cases}$
Exponential	$x(t) = e^{at}$	$x[n] = a^n$
Sinusoid	$x(t) = \sin(\omega t + \phi)$	$x[n] = \sin(\Omega n + \theta)$
Sinc function	$\text{sinc}(\omega_0 t) = \frac{\sin(\pi \omega_0 t)}{\pi \omega_0 t}$	$\text{sinc}[\Omega_0 n] = \frac{\sin(\pi \Omega_0 n)}{\pi \Omega_0 n}$
Rectangular pulse	$x(t) = \begin{cases} 1, t \leq T_0 \\ 0, t > T_0 \end{cases}$	$x[n] = \begin{cases} 1, n \leq M \\ 0, \text{otherwise} \end{cases}$
Triangular pulse	$\Lambda\left(\frac{t}{\tau}\right) = \begin{cases} 1 - \left \frac{t}{\tau}\right , t \leq \tau \\ 0, t > \tau \end{cases}$	$\Lambda\left[\frac{n}{N}\right] = \begin{cases} 1 - \frac{ n }{N}, n \leq N \\ 0, \text{otherwise} \end{cases}$

Important properties of signals:

Name	Properties	
	Continuous time	Discrete time
Impulse properties	$\int_{t=-\infty}^{\infty} \delta(t) dt = 1$ $\int_{t=-\infty}^{\infty} x(t) \delta(t - t_0) dt = x(t_0)$ $x(t) \delta(t - t_0) = x(t_0) \delta(t - t_0)$ $\delta(at) = \frac{1}{ a } \delta(t)$	$x[n] \delta[n - n_0] = x[n_0] \delta[n - n_0]$

Even and Odd symmetry	$x_e(t) = x_e(-t)$ $x_o(t) = -x_o(-t)$ $x_e(t) = \frac{x(t) + x(-t)}{2}$ $x_o(t) = \frac{x(t) - x(-t)}{2}$	$x_e[n] = x_e[-n]$ $x_o[n] = -x_o[-n]$ $x_e[n] = \frac{x[n] + x[-n]}{2}$ $x_o[n] = \frac{x[n] - x[-n]}{2}$
Periodicity	<p>For</p> $x(t) = x(t + T), \text{ fundamental period } T = \frac{2\pi}{\omega}$	$x(n) = x(n + N),$ $\text{fundamental period } N = \frac{2\pi}{\Omega} m,$
Common Periodicity	$T = \frac{T_1}{T_2} = \frac{n}{m}$ <p>T_1 & T_2 are periods of functions, n & m are the integers</p>	$T = \frac{N_1}{N_2} = \frac{n}{m}$ <p>N_1 & N_2 are periods of functions, n & m are the integers</p>
Energy of a signal	$E = \lim_{T \rightarrow \infty} \int_{-\frac{T}{2}}^{\frac{T}{2}} x^2(t) dt$ <p>For non-periodic signal</p> $E = \int_{t=-\infty}^{\infty} x(t) ^2 dt$	$E = \sum_{n=-\infty}^{\infty} x[n] ^2$
Power of a signal	$P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x^2(t) dt$ <p>For periodic signal</p> $P = \frac{1}{T} \int_{t=-T/2}^{T/2} x(t) ^2 dt$	$P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{n=N} x[n] ^2$ <p>For periodic sequence</p> $P = \frac{1}{N} \sum_{n=0}^{N-1} x[n] ^2$
Linear combination of N signals	$\sum_{i=1}^N a_i x_i(t)$	$\sum_{i=1}^N a_i x_i[n]$

Convolution between two non-periodic signals	$x_1(t) * x_2(t) = \int_{\tau=-\infty}^{\infty} x_1(\tau)x_2(t - \tau)d\tau$	$x_1[n] * x_2[n] = \sum_{k=-\infty}^{\infty} x_1[k]x_2[n - k]$
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LTI system analysis:

	Continuous time system	Discrete time system
Name	$x(t) : \text{input}$ $y(t) : \text{output}$ $h(t) : \text{impulse response}$	$x[n] : \text{input}$ $y[n] : \text{output}$ $h[n] : \text{impulse response}$
Causality and stability in-terms of Impulse response	<i>Causality:</i> $h(t) = 0, t < 0$ <i>stability:</i> $\int_{t=-\infty}^t h(t) d\tau < \infty$ <i>memoryless:</i> $h(t) = c\delta(t)$	<i>Causality:</i> $h[n] = 0, n < 0$ <i>stability:</i> $\sum_{n=-\infty}^n h[n] < \infty$ <i>memoryless:</i> $h[n] = c\delta[n]$
Response to any input	$y(t) = x(t) * h(t)$	$y[n] = x[n] * h[n]$
Step response	$s(t) = \int_{\tau=-\infty}^t h(\tau)d\tau$	$s[n] = \sum_{m=-\infty}^n h[m]$
Differential/Difference equation description	$\sum_{k=0}^N a_k \frac{d^k}{dt^k} y(t) = \sum_{k=0}^M b_k \frac{d^k}{dt^k} x(t) ; a_0 \neq 0$	$\sum_{k=0}^N a_k y[n - k] = \sum_{k=0}^M b_k x[n - k] ; a_0 \neq 0$

Geometric Series Formulas:

1	$\sum_{n=0}^M a^n = \frac{1 - a^{M+1}}{1 - a}$
2	$\sum_{n=0}^{\infty} a^n = \frac{1}{1 - a}, \quad a < 1$

3	$\sum_{n=M_1}^{M_2} a^n = \frac{a^{M_1} - a^{M_2+1}}{1 - a}$
4	$\sum_{n=1}^M n = \frac{M(M+1)}{2}$

FOURIER ANALYSIS

Fourier representation of continuous time signals:

Time domain representation		Fourier representation		
$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$	<ul style="list-style-type: none"> • Continuous • Periodic • Period=T, Fundamental frequency $\omega_0=2\pi/T$ rad/sec 	$a_k = \frac{1}{T} \int_{t=-T/2}^{T/2} x(t) e^{-jk\omega_0 t} dt$	<ul style="list-style-type: none"> • Discrete • Non periodic 	FS
$x(t) = \frac{1}{2\pi} \int_{\omega=-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$	<ul style="list-style-type: none"> • Continuous • Non-Periodic 	$X(\omega) = \int_{t=-\infty}^{\infty} x(t) e^{-j\omega t} dt$	<ul style="list-style-type: none"> • Continuous • Non periodic 	FT

Properties of Fourier Transform:

Property	Continuous time signals	
	Time domain	Frequency domain (FT)
Notation	$x(t)$ $x_i(t)$	$X(\omega)$ $X_i(\omega)$
Linearity	$\sum_{i=1}^N a_i x_i(t)$	$\sum_{i=1}^N a_i X_i(\omega)$
Time shifting	$x(t - t_0)$	$e^{-j\omega t_0} X(\omega)$
Frequency shift	$e^{j\gamma t} x(t)$	$X((\omega - \gamma))$

Time reversal	$x(-t)$	$X(-\omega)$
Correlation	$r_{x_1 x_2}(\tau)$ $= x_1(\tau) * x_2(-\tau)$	$X_1(\omega)X_2(-\omega)$
Differentiation in time	$\frac{d}{dt}x(t)$	$j\omega X(\omega)$
Differentiation in frequency	$-jtx(t)$	$\frac{d}{d\omega}X(\omega)$
Integration /summation	$\int_{\tau=-\infty}^t x(\tau)d\tau$	$\frac{X(j\omega)}{j\omega} + \pi X(j0)\delta(\omega)$
Convolution	$x_1(t) * x_2(t)$	$X_1(\omega)X_2(\omega)$
Multiplication	$x_1(t)x_2(t)$	$\frac{1}{2\pi} \int_{\vartheta=-\infty}^{\infty} X_1(\vartheta)X_2(\omega - \vartheta)d\vartheta$
Symmetry	$x(t)$ real	$X^*(\omega) = X(-\omega)$
	$x(t)$ imaginary	$X^*(\omega) = -X(-\omega)$
	$x(t)$ real & even	$Im\{X(\omega)\} = 0$
	$x(t)$ real & odd	$Re\{X(\omega)\} = 0$
Parseval's Theorem	$\int_{t=-\infty}^{\infty} x(t) ^2 dt = \frac{1}{2\pi} \int_{\Omega=-\infty}^{\infty} X(\omega) ^2 d\Omega$	
Duality	$X(t) \xleftrightarrow{FT} 2\pi x(-\omega)$	

Properties of Fourier Series:

Continuous time signal: Periodic, Period=T, Fundamental frequency $\omega_0 = \frac{2\pi}{T}$ radian/sec

Property	Continuous time signals	
	Time domain	Frequency domain (FS)
Notation	$x(t)$ $y(t)$	a_k b_k
Linearity	$Ax(t) + By(t)$	$Aa_k + Bb_k$
Time shifting	$x(t - t_0)$	$e^{-jk\omega_0 t_0} a_k$
Frequency shift	$e^{jk_0\omega_0 t} x(t)$	a_{k-k_0}
Differentiation in time	$\frac{d}{dt}x(t)$	$jk\omega_0 a_k$
Convolution	$x_1(t) * x_2(t)$	$Ta_{k1}a_{k2}$
Multiplication	$x_1(t)x_2(t)$	$\sum_{l=-\infty}^{\infty} a_l b_{k-l}$
Symmetry	$x(t)$ real	$a_k^* = a_{-k}$
	$x(t)$ imaginary	$a_k^* = -a_{-k}$
	$x(t)$ real & even	$Im\{a_k\} = 0$
	$x(t)$ real & odd	$Re\{a_k\} = 0$

Parseval's Theorem	$\frac{1}{T} \int_{t=0}^T x(t) ^2 dt = \sum_{k=-\infty}^{\infty} a_k ^2$
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FT representation for a continuous-time periodic signal $g(t)$:

$$g(t) \xleftrightarrow{FT} G(\omega) = 2\pi \sum_{k=-\infty}^{\infty} g_k \delta(\omega - k\omega_0)$$

Where g_k are the FS coefficients and ω_0 is the fundamental frequency.

Sampling:

Continuous time signal $x(t)$ with FT $X(j\omega)$ is sampled at sampling interval T_s to get $x_\delta(t)$

$$x_\delta(t) = \sum_{n=-\infty}^{\infty} x[nT_s] \delta(t - nT_s) \xleftrightarrow{FT} X_\delta(j\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X\left(j\left(\omega - k\frac{2\pi}{T_s}\right)\right)$$

Basic Fourier Series pairs:

Time domain	Frequency domain
$x(t) = \sum_{k=-\infty}^{\infty} X(k) e^{jk\omega_0 t}$ <p><i>Period = T</i></p>	$a_k = \frac{1}{T} \int_{t=-\frac{T}{2}}^{\frac{T}{2}} x(t) e^{-jk\omega_0 t} dt$ $\omega_0 = \frac{2\pi}{T}$
$x(t) = \begin{cases} 1, t \leq T_0 \\ 0, T_0 < t \leq \frac{T}{2} \end{cases}$	$a_k = \frac{\sin(k\omega_0 T_0)}{k\pi}$
$x(t) = e^{jp\omega_0 t}$	$a_k = \delta[k - p]$
$x(t) = \cos(p\omega_0 t)$	$a_k = \frac{1}{2} \delta[k - p] + \frac{1}{2} \delta[k + p]$
$x(t) = \sin(p\omega_0 t)$	$a_k = \frac{1}{2j} \delta[k - p] - \frac{1}{2j} \delta[k + p]$
$x(t) = \sum_{p=-\infty}^{\infty} \delta(t - pT)$	$a_k = \frac{1}{T}$

Basic Fourier Transform pairs:

Time domain	Frequency domain
$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$	$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$
$x(t) = \begin{cases} 1, & t \leq T_0 \\ 0, & t > T_0 \end{cases}$	$X(\omega) = \frac{2\sin(\omega T_0)}{\omega}$
$x(t) = \frac{1}{\pi t} \sin(Wt)$	$X(\omega) = \begin{cases} 1, & \omega \leq W \\ 0, & \text{otherwise} \end{cases}$
$x(t) = \delta(t)$	$X(\omega) = 1$
$x(t) = 1$	$X(\omega) = 2\pi\delta(\omega)$
$x(t) = u(t)$	$X(\omega) = \frac{1}{j\omega} \pi\delta(\omega)$
$x(t) = e^{-at}u(t) \quad \text{Re}\{a\} > 0$	$X(\omega) = \frac{1}{a + j\omega}$
$x(t) = te^{-at}u(t), \quad \text{Re}\{a\} > 0$	$X(\omega) = \frac{1}{(a + j\omega)^2}$
$x(t) = e^{-a t }, \quad a > 0$	$X(\omega) = \frac{2a}{a^2 + \omega^2}$
$x(t) = \frac{1}{\sqrt{2\pi}} e^{-t^2/2}$	$X(\omega) = e^{-\omega^2/2}$
$x(t) = \cos(\omega_0 t)$	$X(\omega) = \pi\delta(\omega - \omega_0) + \pi\delta(\omega + \omega_0)$
$x(t) = \sin(\omega_0 t)$	$X(\omega) = \frac{\pi}{j}\delta(\omega - \omega_0) - \frac{\pi}{j}\delta(\omega + \omega_0)$
$x(t) = e^{j\omega_0 t}$	$X(j\omega) = 2\pi\delta(\omega - \omega_0)$
$x(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$	$X(\omega) = \frac{2\pi}{T_s} \sum_{k=-\infty}^{\infty} \delta\left(\omega - k\frac{2\pi}{T_s}\right)$