3. z-Transform

Aim: To determine the z-Transform of given sequences using MATLAB.

1. Let $X_1(Z) = 1 + 2Z^{-1} + 3Z^{-2}$ and $X_2(Z) = 1 + 3Z^{-1} + 4Z^{-2}$. Determine the following using MATLAB. $X_3(Z) = X_1(Z)X_2(Z)$ 2. Write a MATLAB program to find Z-transform of the following causal signals. a) 0.5^n b) n c) na^n clear all; syms n a real; %Let n be real variable % a) $x1=0.5^n$; disp('z-transform of "0.5^n" is'); X1 = ztrans(x1)% b) x2=n; disp('z-transform of "n" is'); X2 = ztrans(x2)% c) $x3=n*(a^n);$ disp('z-transform of "n*(a^n)" is'); X3 = ztrans(x3)3. Given a causal system, y(n) = 0.9y(n-1) + x(n). Determine the following using MATLAB H(z) and sketch its pole-zero plot. i) The impulse response h(n). ii) clear all; syms n real; syms z complex;

b = [1, 0]; a = [1, -0.9]; zplane(b,a);

 $H=1/(1-0.9*(z^{(-1)}));$

disp('Impulse response h(n) is'); h=iztrans(H) %compute impulse response

4.

Write a MATLAB program to find inverse Z-transform of the following z-domain signal.

$$X(Z) = \frac{1}{1 - 1.5z^{-1} + 0.5z^{-2}}$$

5.

Write a MATLAB program to perform convolution of signals, $x_1(n) = (0.3)^n u(n)$ and $x_2(n) = (0.9)^n u(n)$ using Z-transform, and extract $x_1(n)$ and $x_2(n)$ using deconvolution.
